

CS 354 - Machine Organization & Programming

Tuesday Nov 28, and Thursday Nov 30 , 2023

CS Annual Climate Survey Reminder: Data Buddies “slides”

Homework hw7: DUE on or before Monday Nov 27

Homework hw8: DUE on or before Monday Dec 5

Project p6: Available and due on last day of classes.

Learning Objectives

- ♦ Describe and explain how computers transfer control to other processes
- ♦ Diagram and describe Exception Table and its use.
- ♦ Identify by name, number, and use several common exception types.
- ♦ Identify by name, number, and use several common system call operations.
- ♦ Describe and trace assembly for system calls.
- ♦ Describe and explain a process's context.
- ♦ Diagram and describe interleaved processes and parallel processes
- ♦ Describe and explain the role of the Kernel's scheduler.
- ♦ Compare and contrast kernel mode vs user mode.
- ♦ Identify and describe the steps and state changes in a context switch.

This Week

Kinds of Exceptions (from Week 12) Transferring Control via Exception Table Exceptions/System Calls in IA-32 & Linux Processes and Context User/Kernel Modes Context Switch Context Switch Example	Meet Signals Three Phases of Signaling Processes IDs and Groups Sending Signals Receiving Signals
This Week and Next Week: Signals, and multithreading, Linking and Symbols B&O 8.5 Signals Intro, 8.5.1 Signal Terminology 8.5.2 Sending Signals 8.5.3 Receiving Signals 8.5.4 Signal Handling Issues, p.745	

Transferring Control via Exception Table

* *Exceptions transfer control to the kernel*

Transferring Control to an Exception Handler

1. push *ret addr (I_{curr}/I_{next})*
2. push *interrupted proc state*

→ What stack is used for the push steps above? *kernel's stack*

3. do indirect function call

indirect function call $EHA = m[R[ETBR] + ENUM]$

ETBR is for exception table base reg

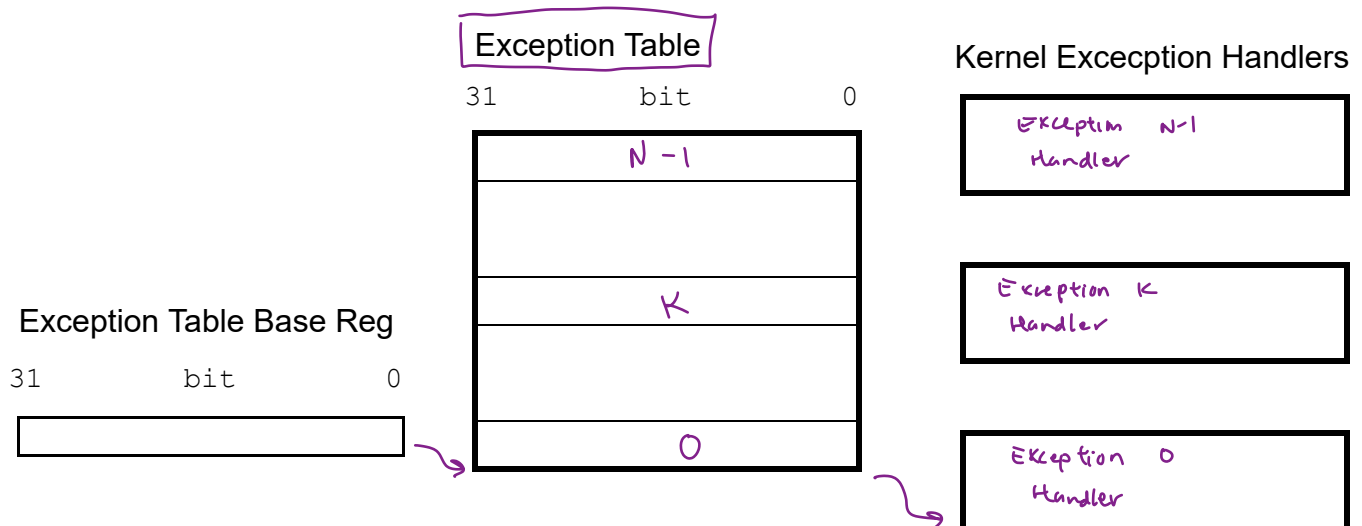
ENUM is for exception number

EHA is for exception handler's address

} *jump table*

Exception Table - *unique non neg ints associated w/ each exception type*

exception number



Exceptions/System Calls in IA-32 & Linux

Exception Numbers and Types

0 - 31 are defined by processor



0 div by 0

13 general prot fault - SEG fault!

14 page fault - handled by OS

18 mach check - hardware error

32 - 255 are defined by OS

128 (\$0x80) ← trap to system call

System Calls and Service Numbers

1 exit

2 fork

3 read file

4 write file

5 open file

6 close file

file I/O

11 execve

Making System Calls

1.) put svc num in %eax

2.) put sys call args in registers: %ebx, %ecx, %edx, %esi, %edi

3.) int \$0x80 trap or system call

System Call Example

```
#include <stdlib.h>
int main(void) {
    → write(1, "hello world\n", 12);
    exit(0);
}
```

Assembly Code:

```
.section .data
string:
    .ascii "hello world\n"
string_end:
    .equ len, string_end - string
.section .text
.global main
main:
```

svc num - movl \$4, %eax

args [movl \$1, %ebx

movl \$string, %ecx

movl \$len, %edx

sys call - int \$0x80

svc num - movl \$1, %eax

arg - movl \$0, %ebx

sys call - int \$0x80

put 4 in eax "write file"

} args to write

} write to std out

"exit"

arg = 0

exit(0)

Processes & Context

Recall, a process

- ♦ an instance of an exec program (running)
- ♦ has "context" info needed to restart process

Why?

easier to treat process as a single entity

running by itself
Key illusions - OS

1. CPU
2. memory
3. devices

→ Who is the illusionist? OS

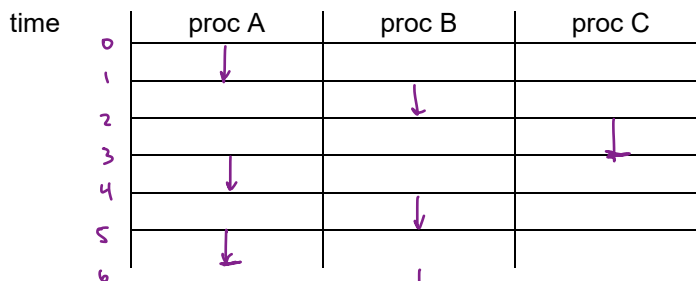
Concurrency

combined execution of 2 or more proc.

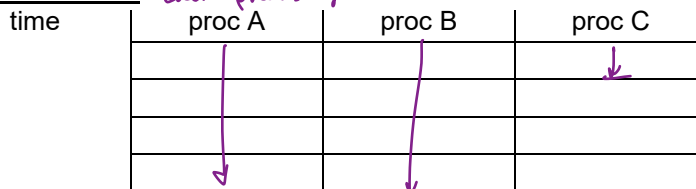
scheduler kernel code that switches btw proc

interleaved execution one CPU that is shared w/ all proc that take turns exec

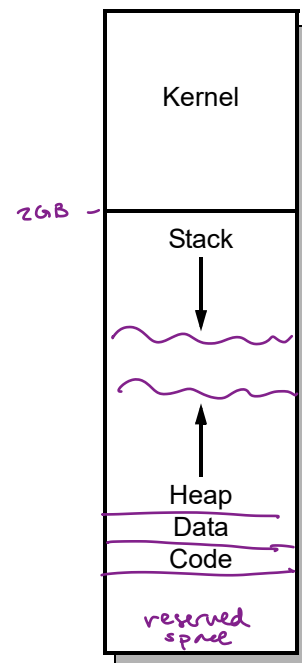
time slice interval that a proc runs in



parallel execution each process gets a core



Process VAS



User/Kernel Modes

What? Processor modes are diff privilege level that a process can run on

mode bit indicate curr mode 1 = kernel 0 = user

kernel mode - can exec any inst
- " access any mem location
- " " any device

user mode - can exec some inst
- " access some mem
- " " some devices

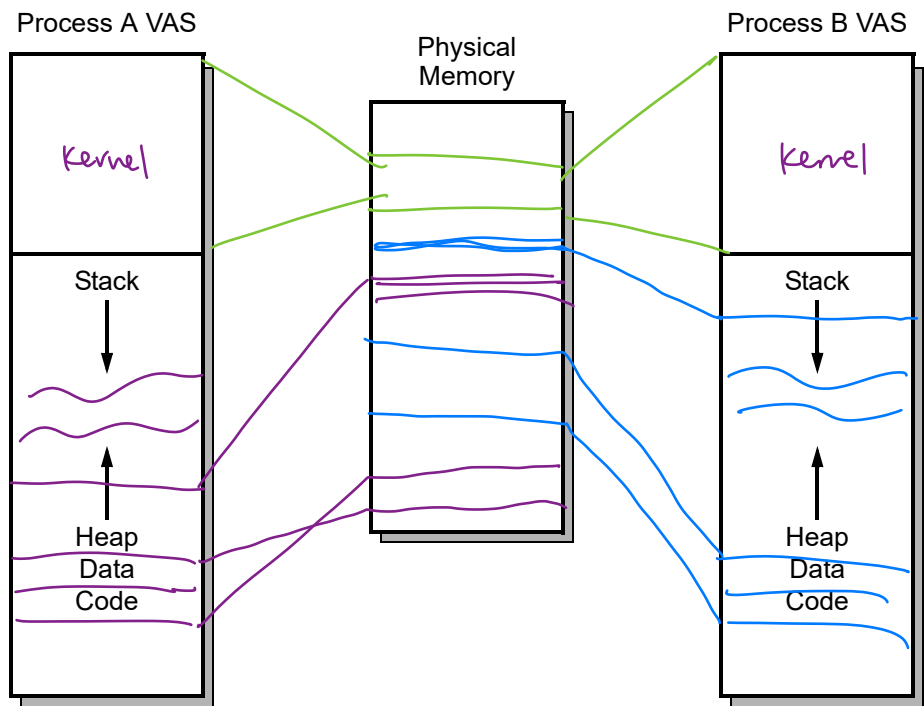
flipping modes

- ♦ start in user mode
- ♦ only exception switch to kernel
- ♦ Kernel's E.H. can switch to user

Sharing the Kernel

key parts of OS:
+ shared by all proc
+ mem resident

pages of -
mem 4K



Context Switch

stepping through a read call() system call

What? A context switch

- ♦ when OS switches from one process to another
- ♦ req. preservation of proc context so it can restart
 1. CPU state
 2. user's stack esp ebp
 3. kernel's stack esp ebp
 4. kernel's data structure
 - a. page table
 - b. process table
 - c. file table

When? happens as result of exception when kernel execute another process
ex) scheduler runs after timer interrupts to swap proc

Why? enables exceptions to be process

How?

1. Save context of curr process
2. restore context of some other process
3. transfer control to restored process

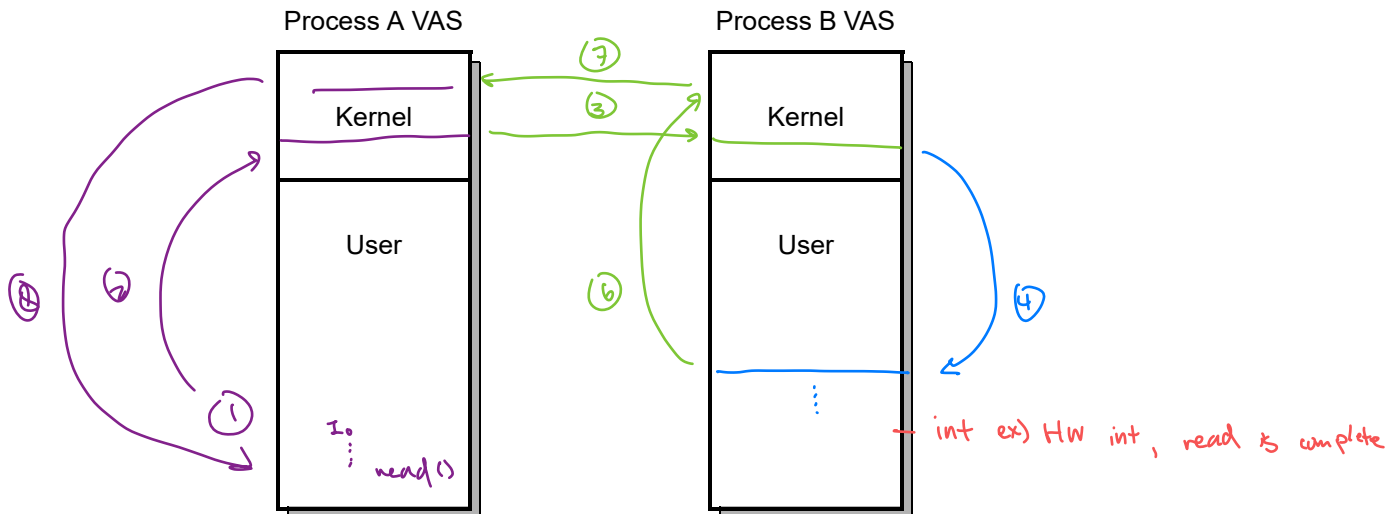
* Context switches are very expensive'

→ What is the impact of a context switch on the cache? negative

- "cache pollution"

Context Switch Example

Stepping through a read() System Call



1. process A is running in user mode ... get to read(i)
2. switch to kernel mode, run E4 for sys call svc num (3)
3. In kernel mode do context switch
 - save context
 - restore B context
 - transfer control to B
4. switch to user mode
5. In user mode in proc B - int occurs
 - finish I curr
6. switch to kernel mode
7. In ker mode do context switch -
 - save B
 - restore A
 - transfer to A
8. switch user control - cont. A

Meet Signals

* The Kernel uses signals to notify user proc. of exceptional events

What? A signal is small msg sent to proc via kernel

Linux: has 30 std sig. types, each w/ unique non-neg ID

\$kill -l lists signal names and numbers

signal(7) man 7 signal

Why?

- ♦ so kernel can notify processes
 1. low-level Hw exceptions
 2. high-level sw events (kernel) or from user processes
- ♦ to enable user proc to comm. w/ each other
- ♦ to implement a higher-level software form of Exceptional control flow

Examples

1. divide by zero

exception 0 interrupts to kernel handler

- kernel signals user proc with SIGFPE #8

2. illegal memory reference

exception 13 interrupts to kernel handler

- kernel signals user proc with SIGSEGV #11

3. keyboard interrupt irq #1

- ctrl-c interrupts to kernel handler which signal SIGINT #2

terminate foreground process by default

- ctrl-z interrupts to kernel handler which signal SIGTSTP #20

suspends foreground process by default

Three Phases of Signaling

Sending

- ♦ when the kernel's E.H. runs in response to Exception Event
- ♦ is directed to destination (proc)

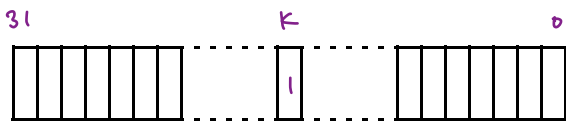
Delivering

when the kernel records a sent signal for its destination proc

pending signal delivered but not received

- ♦ each process has a bit vector to record pending signals

bit vectors



- ♦ bit K is set to 1 when signal K is delivered

Receiving

when the kernel wakes dest proc to react to pending signal

- ♦ happens when kernel transfers control back to process
- ♦ multiple pending signals are received in order low to high signal

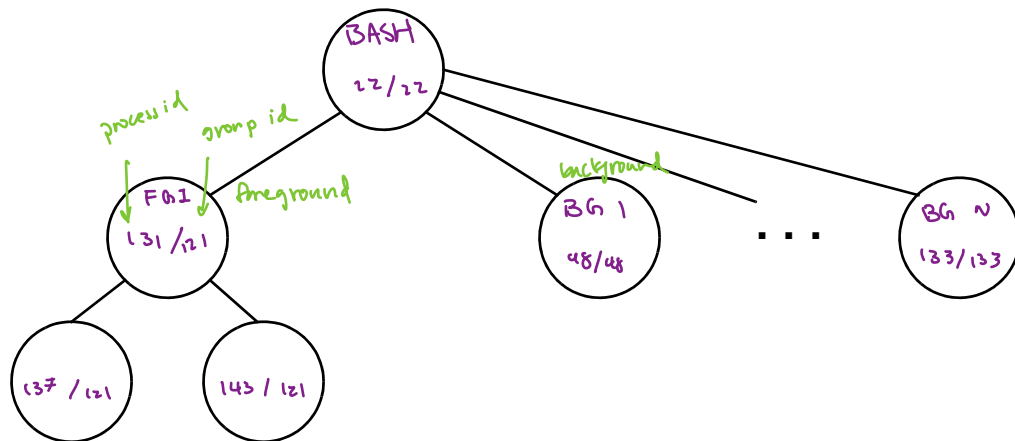
blocking prevents a signal from being rec'd

- ♦ enables a process to control which signal it pays attention to
- ♦ each process has a second bit vector for blocking signal

Process IDs and Groups

What? Each process

- ♦ is identified by a process id
- ♦ belongs to exactly one process group



Why?

#s are easier to manage than names

How?

Recall: `ps` list process `ps -u` your processes
 `ps -al` all in long forms

jobs list process using simple #s

getpid(2)getpgrp(2) man 2 get pid

#include <unistd.h>

pid_t getpid(void) returns process pid

pid_t getpgrp(void) " " gpid

Sending Signals

What? A signal is sent by the kernel or a user process via the kernel or from cmd line

or in program using sys calls

How? Linux Command

`kill(1)` `man 1 kill` - send signal from cmd line to a specific proc

`kill -9 <pid>` 9 `SIGKILL` 2 `SIGINT` 20 `SIGTSTP`
↑ terminate all proc. `ctrl-C` `ctrl-Z`

→ What happens if you kill your shell?

How? System Calls

`kill(2)` `man 2 kill` - send from calling proc to callee proc

`killpg(2)` - send signal to all members of pgid

```
#include <sys/types.h>
#include <signal.h>
int kill (pid_t pid, int sig)
```

proc that is target of signal
the signal being sent

returns 0 on success

`alarm(2)` `man 2 alarm`

sets alarm that will deliver `SIGALRM` after specified # of seconds

```
#include <unistd.h>
unsigned int alarm(unsigned int seconds)
```

↑
returns # secs. # secs until `SIGALRM` is sent to you

returning 0 prev let alarm is running

otherwise, return 0

Receiving Signals

What? A signal is received by its destination process *by doing default action*
or by executing code specified by sig handler

How? Default Actions

- ◆ Terminate the process *SIGINT #2 ctrl-C*
- ◆ Terminate the process and dump core *coredump ctrl-C segfault*
- ◆ Stop the process *SIGTSTP #20 ctrl-Z suspend*
- ◆ Continue the process if it's currently stopped *SIGCONT #18 resume*
- ◆ Ignore the signal *SIGWINCH #28*

How? Signal Handler

1. code a signal handler (func)

- ◆ looks like a regular func but it's called by the kernel
- ◆ should not make unsafe system calls like printf (file I/O) *(except in pb)*

2. Register the signal handler

- ◆ catch 1 or more signals

~~signal(2)~~

sigaction(2) *POSIX examining and changing a signal's default behavior*

Code Example

```
#include <signal.h>
#include ...
#include <string.h>

void handler_SIGALRM() { ... }

int main(...) {
```

code to handle sig

// 2. Register sig alarm handler

struct sigaction sa;

memset (&sa, 0, sizeof (sa));

*sa.sa_handler = handler_SIGALRM; *no parentheses!*

if (sigaction (SIGALRM, &sa, NULL) != 0) {

printf ("Error binding SIGALRM handler\n");
exit(1);

}

*for each
sig
handler*

different

sa gets null