$$\begin{split} \frac{\partial N_1}{\partial t} &= k_1 N_1 \left(1 - \frac{N_1}{\theta_1 - \alpha_1 M} - \frac{N_2}{\theta_2 - \alpha_2 M} \right) + \nabla \cdot \left(D_{N_1} \left(1 - \frac{N_1}{\theta_1 - \alpha_1 M} - \frac{N_2}{\theta_2 - \alpha_2 M} \right) \nabla N_1 \right) - f_1(H) N_1 \\ &\qquad \qquad \underline{\text{set arbitrary variable}} \ \mathbf{a} = \left(1 - \frac{N_1}{\theta_1 - \alpha_1 M} - \frac{N_2}{\theta_2 - \alpha_2 M} \right) \end{split}$$

$$\frac{\partial N_1}{\partial t} = k_1 N_1 a + \nabla \cdot \left(D_{N_1} a \nabla N_1 \right) - f_1(H) N_1$$

$$\begin{split} \frac{\partial N_1}{\partial t} &= k_1 N_1 a \\ + D_{N_1} \frac{\partial}{\partial x} \left(a \frac{\partial N_1}{\partial x} + a \frac{\partial N_1}{\partial y} \right) + D_{N_1} \frac{\partial}{\partial y} \left(a \frac{\partial N_1}{\partial x} + a \frac{\partial N_1}{\partial y} \right) \\ &- f_1(H) N_1 \end{split}$$

$$\frac{\frac{\text{Product rule}:}{\partial N_1}}{\frac{\partial N_1}{\partial t}} = k_1 N_1 a$$

$$+ D_{N_1} \left(\frac{\partial a}{\partial x} \frac{\partial N_1}{\partial x} + a \frac{\partial^2 N_1}{\partial x^2} + \frac{\partial a}{\partial x} \frac{\partial N_1}{\partial y} + a \frac{\partial^2 N_1}{\partial x \partial y} + \frac{\partial a}{\partial y} \frac{\partial N_1}{\partial x} + a \frac{\partial^2 N_1}{\partial x \partial y} + \frac{\partial a}{\partial y} \frac{\partial N_1}{\partial x} + a \frac{\partial^2 N_1}{\partial x \partial y} + a \frac{\partial^2 N_1}{\partial y^2} \right)$$

$$- f_1(H) N_1$$

$$\begin{split} \frac{\partial N_1}{\partial t} &= k_1 N_1 a \\ + D_{N_1} \left(a \left(\frac{\partial^2 N_1}{\partial x^2} + 2 \frac{\partial^2 N_1}{\partial x \partial y} + \frac{\partial^2 N_1}{\partial y^2} \right) + \frac{\partial a}{\partial x} \left(\frac{\partial N_1}{\partial x} + \frac{\partial N_1}{\partial y} \right) + \frac{\partial a}{\partial y} \left(\frac{\partial N_1}{\partial x} + \frac{\partial N_1}{\partial y} \right) \right) \\ &- f_1(H) N_1 \end{split}$$

$$\frac{N_1(t) - N_1(t-1)}{\Delta t} = k_1 N_1(t-1) a(t-1)$$

$$+ D_{N_1} \left(a(t-1) \left(\frac{N_1(x-1,t-1) - 2N_1(x,t-1) + N_1(x+1,t-1)}{\Delta x^2} \right) + \frac{1}{\Delta x} \left(\frac{N_1(x+1,y+1,t-1) - N_1(x+1,y-1,t-1)}{2\Delta y} - \frac{N_1(x-1,y+1,t-1) - N_1(x-1,y-1,t-1)}{2\Delta y} \right) + \frac{N_1(y-1,t-1) - 2N_1(y,t-1) + N_1(y+1,t-1)}{\Delta x} + \frac{N_1(y+1,t-1) - a(x-1,t-1)}{\Delta x} \left(\frac{N_1(x+1,t-1) - N_1(x-1,t-1)}{\Delta x} + \frac{N_1(y+1,t-1) - N_1(y-1,t-1)}{\Delta y} \right) + \frac{a(y+1,t-1) - a(y-1,t-1)}{\Delta y} \left(\frac{N_1(x+1,t-1) - N_1(x-1,t-1)}{\Delta x} + \frac{N_1(y+1,t-1) - N_1(y-1,t-1)}{\Delta y} \right) - f_1(H)N_1(t-1)$$