Agriculture and Agrifoods - PlotCam Lite

Ruaa Abdulmajeed

April 2021

Contents

| 1 | Introduction | | | | |
|---|----------------------------------|---|----|--|--|
| | 1.1 | Key Features: | 3 | | |
| 2 | In t | In the Box | | | |
| 3 | Technical Specifications | | | | |
| 4 | Requirements | | | | |
| 5 | Getting Started | | | | |
| | 5.1 | Hardware | 5 | | |
| | 5.2 | Software | 6 | | |
| 6 | Getting Started - For Developers | | | | |
| | 6.1 | Set Up Repository | 8 | | |
| | 6.2 | Install Dependencies | 9 | | |
| | 6.3 | Access CMD Options | 9 | | |
| | 6.4 | Edit UI of Main Window and 'About' Window | 10 | | |
| | 6.5 | Edit 'Take Picture' Shutter Sound | 10 | | |
| Δ | crony | vms | 11 | | |

1 Introduction

Monitoring growth is an essential facet of managing crops. It allows farmers to make changes to the crops when needed and harvest the crops at the correct time to ensure optimal yield. The Plot Cam Lite (PCL) is an affordable solution to human-operated plant monitoring experiments. The design of this device is based on the original Plot Cam developed by Marc Lefebvre. The PCL uses a depth camera and a high resolution accelerometer to take Red Green Blue (RGB) and depth images of plants plots.

1.1 Key Features:

- User friendly
- Developed using PyQt5 and pyrealsense libraries
- Compatible with Intel Realsense D415 and PhidgetSpatial Precision 3/3/3 Accelerometer
- Easy camera configuration of FPS and resolution

2 In the Box

The items included in the PCL are listed below:

- Intel Realsense D415
- PhidgetSpatial Precision 3/3/3 High Resolution
- VR Head Set
- 1x USB C Cable
- 2x USB B Cables

3 Technical Specifications

| Part | Component | Rating |
|---------------|--|---|
| | Model | Intel RealSense D415 |
| | Ideal Range | 0.5m to 3m |
| | Use Environment | Indoor/Outdoor |
| | Image Sensor Technology | Rolling Shutter |
| | Depth Technology | Active IR Stereo |
| Depth Camera | Depth Accuracy | 2% at 2 m |
| Depui Camera | Depth Frame Rate | 30, 60, 90 FPS |
| | Depth Output Resolution | $640x480, 1280 \times 720$ |
| | RGB Sensor Technology | Rolling Shutter |
| | RGB Frame Resolution | 1920×1080 |
| | RGB Frame Rate | 15, 30 FPS |
| | Connector | USB-C 3.1 |
| | Dimensions | $99 \text{ mm} \times 20 \text{ mm} \times 23 \text{ mm}$ |
| | Model | PhidgetSpatial 3/3/3 High Resolution |
| | Acceleration Measurement Max | $\pm 2g$ |
| | Acceleration Measurement Resolution | 76.3 μg |
| Accelerometer | Acceleration Bandwidth | 497 Hz |
| | Accelerometer White Noise | 280 µg |
| | Accelerometer Minimum Drift | 40.6 µg |
| | Accelerometer Optimal Averaging Period | 398s |

Table 1: Technical Specifications of the Hardware Components of the PCL

4 Requirements

The minimum requirements for running the software required to operate the Plot Cam Lite are listed below:

- Microsoft Windows 10 or above
- Python 3.9 or above
- 2x USB A 3.0 ports
- $\bullet~1x~USB~C~3.0~port$

5 Getting Started

5.1 Hardware

Follow the steps below to set up the hardware of the Plot Cam Lite.

- 1. Connect the VR Headset through HDMI to your PC.
- 2. Connect the Phidget accelerometer through USB A to PC
- 3. Connect a wireless air mouse through USB to the PC
- 4. Connect the Intel camera through USB C to the PC

The hardware connections of the components of the PCL are shown in Figure 1.

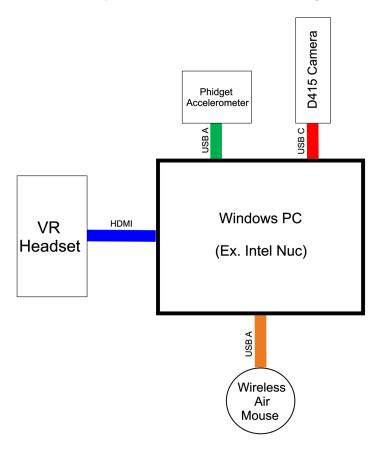
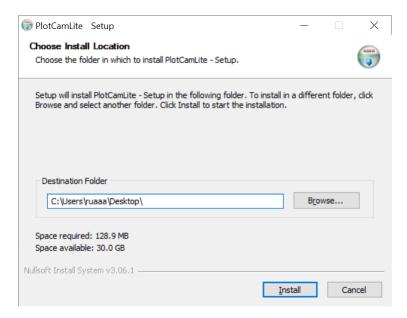


Figure 1: PCL Hardware Connections

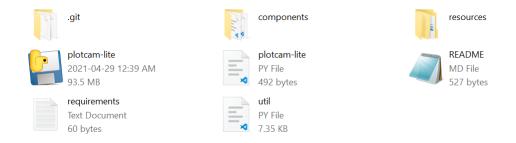
5.2 Software

Follow these steps to install and set up the Plot Cam Lite program on your machine.

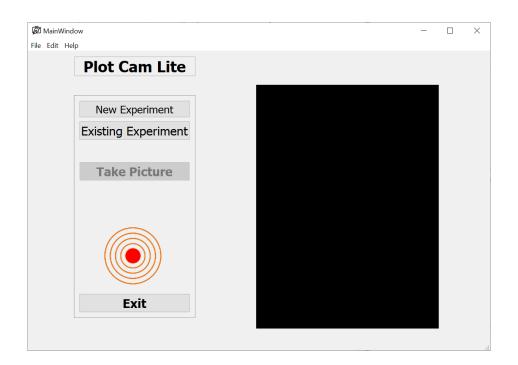
- 1. Follow this link and download PlotCamLite.exe
- 2. Open the file, note that an error about an unknown publisher might pop up, click 'More Info' and "Run Anyway".
- 3. Choose a destination folder for the program, such as Desktop, and click 'Install'. This directory will be used to launch the program as well as access camera data. Ensure that the chosen directory does not contain a folder with the same name as the program.



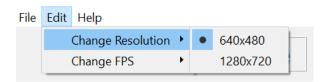
4. Once the install is complete, close the setup pop up and head over to the directory the program was just saved in. The folder will contain the following files.



5. To start the program, open the 'plotcam-lite.exe' file. A new folder will be created within the directory titled 'Experiments'. This folder will be used to store the camera data of each experiment.



6. The resolution and Frames per Second (FPS) can be configured using the edit menu in the top-left options bar. The default (and optimal) stream is set at 1280x720 and running at 30 FPS.





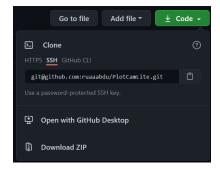
7. To access documentation for the PCL, go to Help \rightarrow Documentation.

6 Getting Started - For Developers

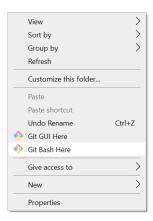
6.1 Set Up Repository

Follow theses steps to set up a respository of the Plot Cam Lite on your computer.

- 1. Install the GitBash on your PC from here.
- 2. Set up SSH by following the steps on this page.
- 3. On the GitHub repository, there is a green button marked 'Code'. Once its clicked, select the SSH link as shown below.



4. Go to the directory you want to have the repository in, right click and select 'Git Bash Here'



5. In the terminal window that comes up, type **git clone** followed by the SSH link from the last step and press enter.

```
ruaaa@RuesSurface MINGW64 /c/Users/ruaaa/Desktop/Working Directory
$ git clone git@github.com:ruaaabdu/PlotCamLite.git
Cloning into 'PlotCamLite'...
remote: Enumerating objects: 405, done.
remote: Counting objects: 100% (222/222), done.
remote: Compressing objects: 100% (166/166), done.
remote: Total 405 (delta 125), reused 104 (delta 52), pack-reused 183
Receiving objects: 100% (405/405), 34.23 MiB | 3.65 MiB/s, done.
Resolving deltas: 100% (212/212), done.
```

- 6. Type **cd PlotCamLite**/ to go into the repository folder.
- 7. It is not good practice to work directly off master. Choose a branch or create one to work within. Once you are sure of your changes, push them to master. To see a list of available remote and local branches, type **git branch -a**.

```
ruaaa@RuesSurface MINGW64 /c/Users/ruaaa/Desktop/Working Directory
$ cd PlotCamLite/

ruaaa@RuesSurface MINGW64 /c/Users/ruaaa/Desktop/Working Directory/PlotCamLite (master)
$ |

ruaaa@RuesSurface MINGW64 /c/Users/ruaaa/Desktop/Working Directory/PlotCamLite (master)
$ git branch -a

* master

remotes/origin/HEAD -> origin/master

remotes/origin/camera-feed-shared-memory

remotes/origin/caire

remotes/origin/executables

remotes/origin/master

remotes/origin/nuc-pcl

remotes/origin/ruaaabdu-patch-1-windows

remotes/origin/windows-patch
```

8. To get into one of the branches, type **git checkout origin/"branch-name"**, as below. This copies the contents of the branch repository onto your local repository, but it creates a new pointer. In order to push your changes to the remote branch, the name of your local branch must match the name of the remote branch, type **git checkout -b "branch-name"**

```
ruaaa@RuesSurface MINGW64 /c/Users/ruaaa/Desktop/Working Directory/PlotCamLite (master)
$ git checkout origin/"nuc-pcl"
Note: checking out 'origin/nuc-pcl'.

You are in 'detached HEAD' state. You can look around, make experimental changes and commit them, and you can discard any commits you make in this state without impacting any branches by performing another checkout.

If you want to create a new branch to retain commits you create, you may do so (now or later) by using -b with the checkout command again. Example:

git checkout -b <new-branch-name>

HEAD is now at 86848a3 Minor Fixes

ruaaa@RuesSurface MINGW64 /c/Users/ruaaa/Desktop/Working Directory/PlotCamLite ((86848a3)))
$ git checkout -b "nuc-pcl"
Switched to a new branch 'nuc-pcl'

ruaaa@RuesSurface MINGW64 /c/Users/ruaaa/Desktop/Working Directory/PlotCamLite (nuc-pcl)
$ |
```

Your local repository is now up to date with the latest version of the chosen branch. If using an IDE which supports Git source control, such as VSCode, there are simple ways to pull changes from the remote branch and push changes from your local branch straight from the IDE. For VSCode, more information on Git can be found here. A GitHub cheatsheet can be found here.

6.2 Install Dependencies

To install the dependencies required for the program, install all the libraries found in requirements.txt by using **pip install** *library-name*

6.3 Access CMD Options

This version supports options which can be accessed through the command terminal. To access these options, navigate to the folder containing the repository and type cmd in the box with the file path to open the terminal at that location. These options allow you to format properly on a monitor, configure resolution and FPS, and see logs as they happen for debugging.

• Type **python plotcam-lite.py -h** to see all the available options.

6.4 Edit UI of Main Window and 'About' Window

In order to make UI changes to the main window or the Help \rightarrow About window, install Qt Designer and edit the .ui files found in resources/UI.

6.5 Edit 'Take Picture' Shutter Sound

Save the .wav file of the sound to the resources/audio file. In util.py, edit the **ALERT_AUDIO_PATH** variable to specify the new .wav file.

ALERT_AUDIO_PATH = os.path.join(PCL_SRC_PATH, "resources", "audio", "camera-shutter-click.wav")

Acronyms

 $\mathbf{FPS}\,$ Frames per Second. 7, 9

 ${\bf IDE}$ Integrated Development Environment. 9

IR Infrared. 4

 \mathbf{PCL} Plot Cam Lite. 3–8

RGB Red Green Blue. 3

UI User Interface. 10