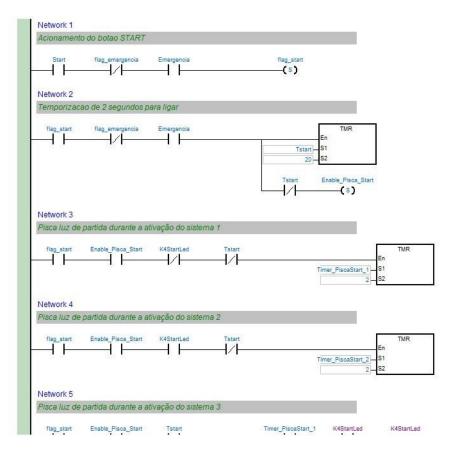
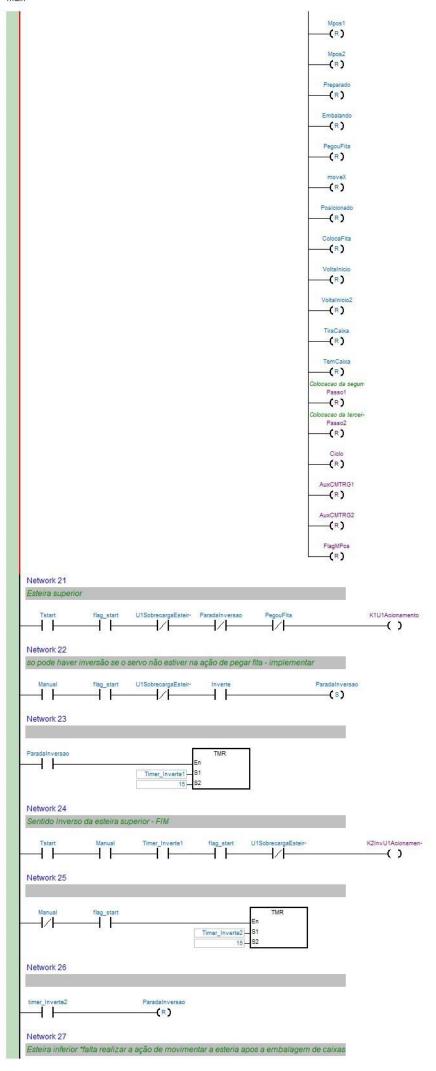
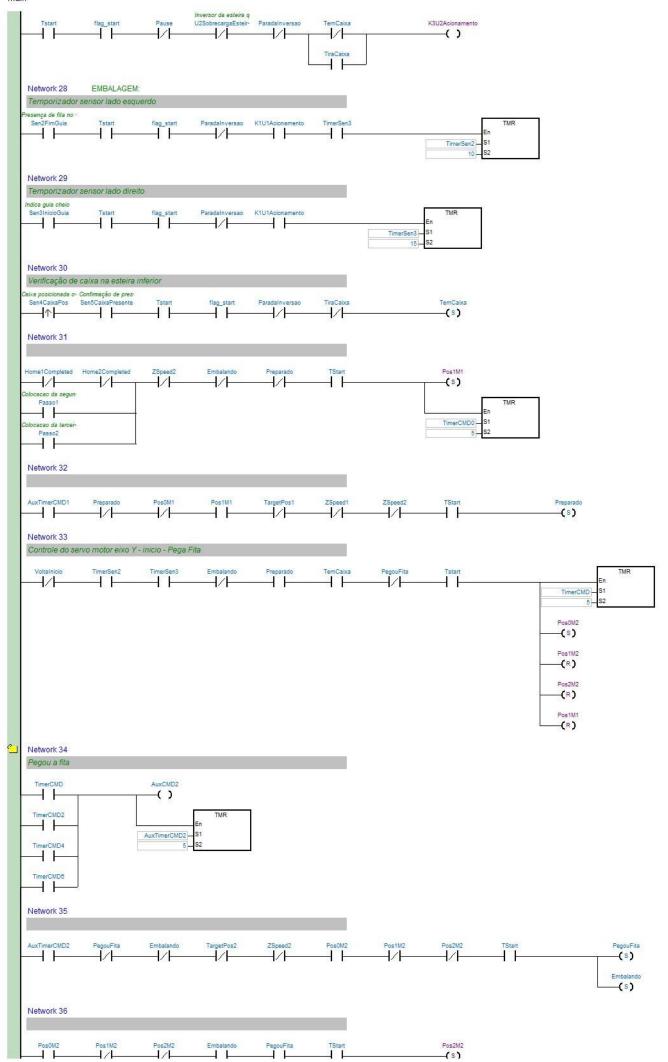
Declaration Type	Identifiers	Address	Type	Initial Value	Identifier Comment
/AR	MStart	M0	BOOL	FALSE	
AR	flag_stop	M1	BOOL	N/A	
/AR	BtnEmergencia	M12	BOOL	N/A	
VAR	Parada_Manual	M15	BOOL	N/A	5
VAR	TiraCaixa	M16	BOOL	N/A	5
VAR	TirandoCaixa	M17	BOOL	N/A	5
VAR	VoltaInicio2	M18	BOOL	N/A	5
VAR	flag sobrecarga	M2	BOOL	N/A	5
VAR	ParadaInversao	M25	BOOL	N/A	5
VAR	TemCaixa	M26	BOOL	N/A	5
VAR	PegouFita	M27	BOOL	N/A	5
VAR	EmRepouso	M28	BOOL	N/A	5
VAR	Posicionado	M29	BOOL	N/A	5
VAR	Preparado	M3	BOOL	N/A	
/AR	Embalando	M32	BOOL	N/A	5
VAR.	MoveX	M33	BOOL	N/A	
VAR.	Mpos0	M34	BOOL	N/A	
VAR.	Mpos1	M35	BOOL	N/A	
VAR	Mpos2	M36	BOOL	N/A	
VAR.	ColocaFita	M37	BOOL	N/A	
VAR	VoltaInicio	M38	BOOL	N/A	
VAR	AuxTiraCaixa	M39	BOOL	N/A	
VAR	flag sensor	M4	BOOL	N/A	
/AR	flag emergencia	M40	BOOL	N/A	
VAR	flag start	M41	BOOL	N/A	
VAR	Enable Pisca Start	M42	BOOL	N/A	
VAR	AuxCMD2	M5	BOOL	N/A	
VAR	AuxStart	M6	BOOL	N/A	
VAR	AuxCMD1	M7	BOOL	N/A	*
VAR	TimerCM2	M8	BOOL	N/A	*
VAR	Timer Start	TO	TIMER	0	
VAR	Timer Inverte1	T1	TIMER	N/A	*
VAR	TimerCMD3	T10	TIMER	N/A	*
VAR	TimerCMD4	T11	TIMER	N/A	
VAR	TimerPosicionado	T12	TIMER	N/A	5
VAR	TimerColocaFita	T13	TIMER	N/A	*
VAR	TimerTiraCaixa	T14	TIMER	N/A	5
VAR	TimerColocaFita2	T15	TIMER	N/A	5
VAR	Tstart	T16	TIMER	N/A	5
/AR	Timer PiscaStart 1	T17	TIMER	N/A	5
VAR	Timer PiscaStart 2	T18	TIMER	N/A	5
VAR	TimerCMD0	T19	TIMER	N/A	5
VAR.	Timer Inverte2	T2	TIMER	N/A	5
VAR	TimerHome	T20	TIMER	N/A	5
VAR	AuxTimerCMD2	T21	TIMER	N/A	5
VAR	AuxTimerCMD1	T22	TIMER	N/A	5
VAR	TimerCMD5	T23	TIMER	N/A	5
/AR	TimerCMD6	T24	TIMER	N/A	5
/AR	TimerHome2	T25	TIMER	N/A	5
/AR	debug	T26	TIMER	N/A	5
/AR	Timer trocal	T3	TIMER	N/A	5
AR.	Timer troca2	T4	TIMER	N/A	5
/AR	TimerSen2	T5	TIMER	N/A	5
/AR	TimerSen3	T6	TIMER	N/A	
/AR	Timer servol	T7	TIMER	N/A	
/AR	TimerCMD	T8	TIMER	N/A	
VAR	TimerCMD2	T9	TIMER	N/A N/A	5
(AL)	I HIELOMINE	117	THVIER	µv/A	



```
AuxCMD1
                Voltalnicio
Network 16
Acionamento do boao de emergencia
 Emergencia
                             flag_emergencia
                               flag_start
—(R)
                                AuxStart
                                (R)
                               EmGS1
                               EMGS2
                                (s)
                              K4StartLed
Network 17
Acionamento do botao de STOP
  Parada
                                           flag_emergencia
                                                           Emergencia
                                                                                          flag_stop
                 flag_start
                                Start
  flag_stop
                                                                                          flag_start
                                                                                          K4StartLed
                                                                                           —(R)
Network 18
Aciona luz de parada
                              K5ParadaLed
  flag_stop
flag_emergencia
 flag_sensor
Network 19
Aciona luz de sobrecarga de motor e ativa flag indicador de sobrecarga
                                           K6SobrecargaLed
1SobrecargaEsteir-
                                             ()
                                            flag_sobrecarga
  SRDY1
                 TStart
  SRDY2
Network 20
Reset
                Emergencia flag_start flag_stop
                                                                            (R)
                                                                            (R)
                                                                            ???
-(`)
                                                                            EmGS2
                                                                            (R)
                                                                            Pos0M1
                                                                            (R)
                                                                            Pos1M1
                                                                            (R)
                                                                            (R)
                                                                            Pos1M2
                                                                            (R)
                                                                            Pos2M2
                                                                            (R)
                                                                            Mpos0
—(R)
```





Network 46

Network 37 Pos2M2 Embalando 1/1-1/1-Network 38 Pevou as fitas e reseta os contadores G112 (R) TimerCMD2 11 **-**|↑|-C113 Network 39 PegouFita AuxCMTRG2 1/1-+ $\dashv \vdash$ (s) Network 40 Recua para a posição inicial AuxCMTRG2 Pos0M2 Pos1M2 Pos2M2 Embalando PegouFita ZSpeed2 Pos0M1 (R) Pos1M1 (R) MoveX (s) AuxCMTRG2 (R) Network 41 Controle do servo motor eixo X - Inicio - posição para embalagem flag_start Paradalnversao TargetPos2 Tstart Embalando Pos0M1 TStart (s) Network 42 Controle do servo motor eixo X - Inicio - posição para embalagem flag_start Embalando 1/1 -1/ \vdash TimerCMD3 __ S1 Network 43 TimerCMD3 +(R) TimerCMD0 Pos1M2 (R) Pos2M2 (R) (R) AuxCMD1 () TMR S1 AuxTimerCMD1 Network 44 AuxCMTRG1 TimerCMD3 $-\Gamma$ (s) Network 45 Posicionado ZSpeed1 TargetPos1 Posicionado (s) (R) AuxCMTRG1 —(R)

