

Use pretrained model for Car

Run

```
python eval_rcnn.py --cfg_file cfgs/default.yaml --ckpt PointRCNN.pth
--batch_size 1 --eval_mode rcnn --set RPN.LOC_XZ_FINE False
```

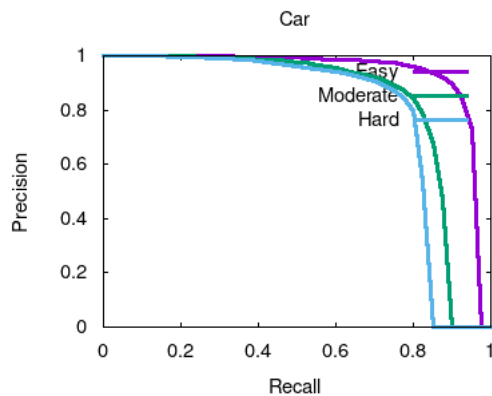
and get results in `output/rcnn/default/eval/epoch_no_number/val/final_result`

Then run the following command

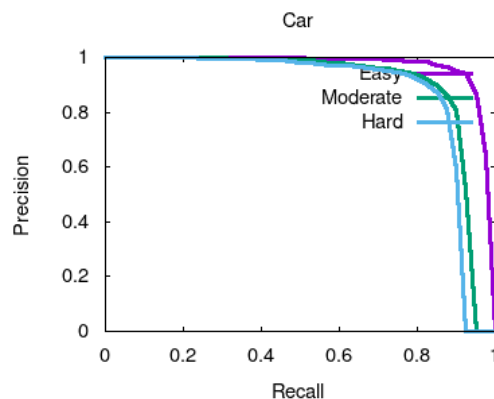
```
./evaluate_object_3d_offline
/local-scratch/projects/PointRCNN/data/KITTI/object/training/label_2
/local-scratch/projects/PointRCNN/output/rcnn/default/eval/epoch_no_number/val/final_result
```

Get plot under `final_result`

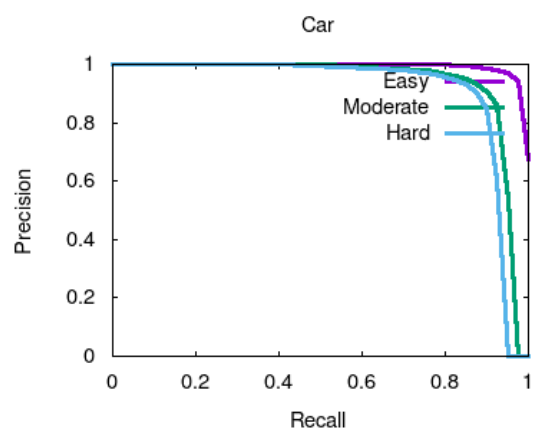
1. car detection 3d:



2. car detection ground:



3. car detection:



4. car orientation:

