

5/5/21 Lec 21

From last time

$$= (\sigma^2)^{-\frac{n+n_0}{2}-1} e^{-\frac{1}{2\sigma^2}(n-1)s^2 + n\sigma_0^2 + n\bar{x}^2} \cdot \sqrt{\frac{\pi}{b}} e^{-\frac{a^2}{4b}}$$

$$\uparrow N\left(\frac{\frac{n\bar{x}}{\sigma^2} + \frac{\mu_0}{\tau^2}}{\frac{n}{\sigma^2} + \frac{1}{\tau^2}}, \frac{1}{\frac{n}{\sigma^2} + \frac{1}{\tau^2}}\right)$$

$$N\left(\frac{a}{2b}, \frac{1}{2b}\right) = \sqrt{\frac{b}{\pi}} e^{-\frac{a^2}{4b}} e^{-a\theta - b\theta^2}$$

$$\propto P(\theta|x, \sigma^2) (\sigma^2)^{-\frac{n+n_0}{2}-1} e^{-\frac{1}{2\sigma^2}(n-1)s^2 + n\sigma_0^2 + n\bar{x}^2} \left(\frac{n}{\sigma^2} + \frac{1}{\tau^2}\right)^{-\frac{1}{2}} \cdot \left(\frac{n\bar{x} + \frac{\mu_0}{\tau^2}}{\frac{n}{\sigma^2} + \frac{1}{\tau^2}}\right)^2 / \left(\frac{2n}{\sigma^2} + \frac{2}{\tau^2}\right)$$

$$\propto P(\theta|x, \sigma^2) (\sigma^2)^{-\frac{n+n_0}{2}-1} e^{-\frac{1}{2\sigma^2}(n-1)s^2 + n\sigma_0^2 + n\bar{x}^2} \left(\frac{n}{\sigma^2} + \frac{1}{\tau^2}\right)^{-\frac{1}{2}} e^{\frac{(n\bar{x} + \frac{\mu_0}{\tau^2})^2}{(\frac{2n}{\sigma^2} + \frac{2}{\tau^2})}}$$

$$K(\sigma^2|x) = (\sigma^2)^{-\alpha-1} e^{-\frac{\beta}{\sigma^2}} \left(\frac{\gamma}{\sigma^2} + \delta\right)^{-\frac{1}{2}} e^{\frac{(\frac{\gamma}{\sigma^2} + \delta)^2}{(\frac{\gamma}{\sigma^2} + \delta)}}$$

Is this kernel $K(\sigma^2|x)$ Proportional to any distribution we know? NO!! This means we can't sample from it using the table you've seen. Get a bigger table? No! This isn't a known distribution. So, we're in trouble... because we can't sample from $P(\sigma^2|x)$ thus we can't sample from the Posterior.

We need a general way to sample from kernels of unknown variables.

Grid Sampling Algorithm:

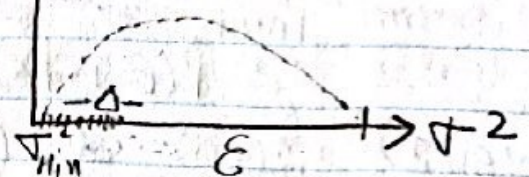
- 1 Create a grid by first picking $\sigma_{\min}^2, \sigma_{\max}^2, \Delta$

$$\mathcal{E} = \{\sigma_{\min}^2, \sigma_{\min}^2 + \Delta, \sigma_{\min}^2 + 2\Delta, \dots, \sigma_{\max}^2 - \Delta, \sigma_{\max}^2\}$$

for ex, in our case Let

$$\sigma_{\min}^2 = 0, \sigma_{\max}^2 = 100, \Delta = 0.1$$

$$\mathcal{E} = \{0, 0.1, 0.2, \dots, 99.9, 100\}$$



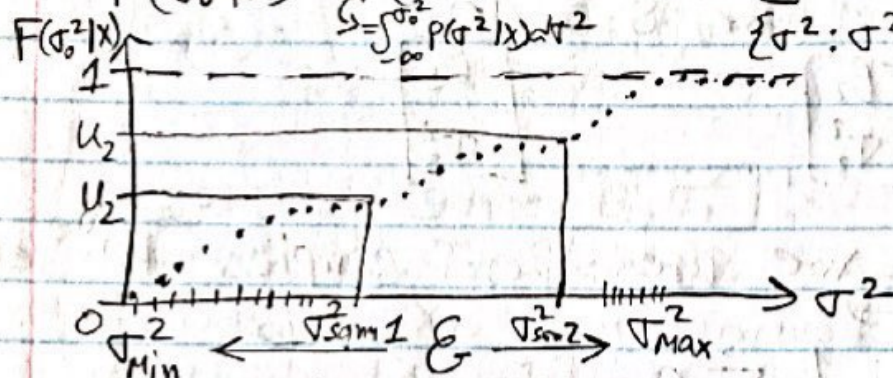
- ② Approximate the value of C , the normalization constant via Riemann Sum (if continuous)

$$C = \frac{1}{\int k(\sigma^2|x) d\sigma^2} \approx \frac{1}{\sum_{\sigma^2 \in \mathcal{E}} k(\sigma^2|x)}$$

- ③ Compute the "Sampling CDF" for all grid points:

$$F(\sigma_0^2|x) := P(\sigma^2 \leq \sigma_0^2|x) \approx \sum_{\{\sigma^2: \sigma^2 \in \mathcal{E}, \sigma^2 \leq \sigma_0^2\}} c k(\sigma^2|x)$$

$c = \frac{1}{\sum_{\sigma^2 \in \mathcal{E}} k(\sigma^2|x)}$



- ④ Draw u from $U(0,1)$ and locate

$$\sigma_{\text{sample}}^2 = \min_{\sigma^2 \in \mathcal{E}} \{F(\sigma^2|x) \geq u\}$$

If you want to draw many samples, repeat step 4. You only need to do step 1-3 once.

Returning to our Problem, how do we sample from the posterior $P(\theta, \sigma^2|x)$?

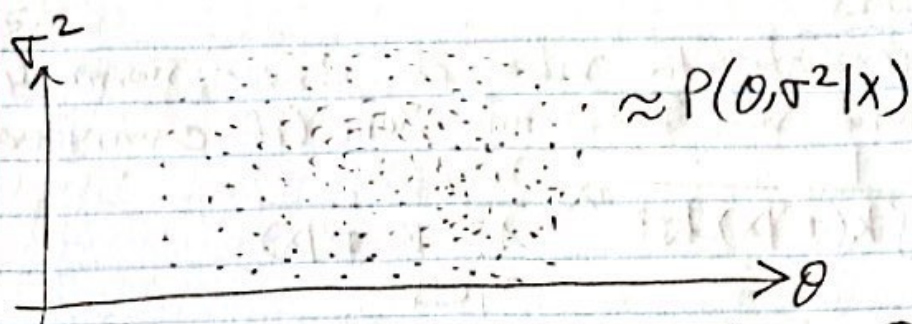
- ① Sample σ_{sample}^2 from $P(\sigma^2|x)$ using the grid sampler

- ② Sample θ_{sample} from $P(\theta|\sigma_{\text{sample}}^2, x)$ via `rnorm`.

Return $[\theta_{\text{sample}}, \sigma_{\text{sample}}^2]$

At this point, we're not limited to distributions we know about nor limited to using conjugate priors. We're liberated!

We agree we can sample now any arbitrary posterior. But how do we get point estimates?



I now have as many sample as I wish from my Posterior (you want more? Let the computer churn more). You have S samples:

$$\begin{bmatrix} \theta_1 \\ \sigma_1^2 \end{bmatrix}, \begin{bmatrix} \theta_2 \\ \sigma_2^2 \end{bmatrix}, \dots, \begin{bmatrix} \theta_S \\ \sigma_S^2 \end{bmatrix}$$

How do we use these samples to get point estimates?

$$\hat{\theta}_{MISE} \approx \frac{1}{S} \sum_{k=1}^S \theta_k$$

$$\hat{\theta}_{MMAE} \approx \text{SampleMedian}[\theta_1, \dots, \theta_S] \quad \text{i.e. you order all the samples and return the mid value.}$$

$\hat{\theta}_{MAP}$ is complicated... you need to use smoothing. forget it!

$$\hat{\sigma}_{MMSE}^2 = \frac{1}{S} \sum_{k=1}^S \sigma_k^2$$

$$\hat{\sigma}_{MMAE}^2 = \text{SampleMedian}[\sigma_1^2, \dots, \sigma_S^2]$$

How do we get CR's?

$$CR_{\theta, 1-\alpha_0} = [Q[\theta|x, \frac{\alpha_0}{2}], Q[\theta|x, 1-\frac{\alpha_0}{2}]]$$

$$\approx [\text{SampleQuantile}[\theta_1, \dots, \theta_S, \frac{\alpha_0}{2}], \text{SampleQuantile}[\theta_1, \dots, \theta_S, 1-\frac{\alpha_0}{2}]]$$

How do we get P-val's for hypothesis tests?

$$H_0: \theta \in \Theta_0, \text{ P-val} := P(\theta \in \Theta_0 | x) = \int_{\Theta_0} P(\theta | x) d\theta$$

$$\approx \frac{1}{S} \sum_{k=1}^S \mathbb{1}_{\theta_k \in \Theta_0}$$

e.g. $H_0: \theta \leq 5.89$, $P\text{-val} = \frac{\#\theta_k \leq 5.89}{S} = \text{Proportion} \leq 5.89$

How do we get the marginal distribution $P(\theta|X)$? Sample.

$$P(\theta|X) = \int_{\text{supp}[\sigma^2]} P(\theta, \sigma^2|X) d\sigma^2 \approx U(\{\theta_1, \dots, \theta_S\})$$

uniform discrete distribution

How do we get the Posterior Predictive distribution $P(X_*|X)$?

$$P(X_*|X) = \int \int \underbrace{P(X_*|\theta, \sigma^2)}_{N(\theta, \sigma^2)} \underbrace{P(\theta, \sigma^2|X)}_{??} d\theta d\sigma^2 = \int \int P(X_*, \theta, \sigma^2|X) d\theta d\sigma^2$$

You use the sample $[\theta_1, \sigma_1^2]$ and then draw X_{*1} from $\text{rnorm}(\theta_1, \sigma_1^2)$. Then use the sample $[\theta_2, \sigma_2^2]$ and then draw X_{*2} from $\text{rnorm}(\theta_2, \sigma_2^2)$ Then use the sample $[\theta_S, \sigma_S^2]$ and then draw X_{*S} from $\text{rnorm}(\theta_S, \sigma_S^2)$:

$$U(\{X_{*1}, X_{*2}, \dots, X_{*S}\}) \approx P(X_*|X)$$

$$E[X_*|X] \approx \frac{1}{S} \sum_{k=1}^S X_{*k}$$

Disadvantages of the Grid Sampling Algorithm

① In many dimensions, how do you pick min, max? For parameters in multiparameter models, it's not so simple!

② Computers have numerical underflow and overflow.

③ "Curse of dimensionality". Let's say you want to sample 10,000 grid points per dimension. But you have 10 different θ s. $10,000^{10} = 10^{50}$ which is Impossible for the computer. As another ex. Let's say I want 1 billion points in 10 dimensions. That is only $\sqrt[10]{10^9} \approx 8$ points per dimensions.

That's not good resolution at all!

We need another solution to this problem!!