

Assignment 17

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Download the latex-tikz codes from

<https://github.com/rubeenaafreen20/EE5609/tree/master/Assignment17>

1 PROBLEM

Let \mathbf{T} be the diagonalizable linear operator on \mathbb{R}^3 which we discussed in example 3 of section 6.2. Use the Lagrange polynomials to write the representing matrix \mathbf{A} in the form

$$\mathbf{A} = \mathbf{E}_1 + 2\mathbf{E}_2, \quad \mathbf{E}_1 + \mathbf{E}_2 = \mathbf{I}, \mathbf{E}_1\mathbf{E}_2 = \mathbf{0} \quad (1.0.1)$$

2 OUTLINE

Diagonalizable Operator	<p>For a linear operator $\mathbf{T}: \mathbf{V} \longrightarrow \mathbf{V}$, \mathbf{T} is a diagonalizable operator if \exists some basis for \mathbf{V} such that the matrix representing \mathbf{T} is a diagonal matrix i.e.</p> $\mathbf{T}(\mathbf{X}) = \mathbf{A}\mathbf{X},$ $\implies \mathbf{A} \text{ is a diagonalizable matrix}$
Characteristic Polynomial	<p>For an $n \times n$ matrix \mathbf{A}, characteristic polynomial is defined by,</p> $p(x) = x\mathbf{I} - \mathbf{A} $
Minimal Polynomial	<p>Minimal polynomial $m(x)$ is the smallest factor of characteristic polynomial $p(x)$ such that,</p> $m(\mathbf{A}) = \mathbf{0}$ <p>Every root of characteristic polynomial should be the root of minimal polynomial</p>
Lagrange Polynomials	<p>For a set of scalars $c_0, c_1, \dots, c_n \in \mathbb{F}$, Lagrange Polynomial is defined as:</p> $p_j = \prod_{i \neq j} \frac{(x - c_i)}{(c_j - c_i)}$
Theorem	<p>If \mathbf{T} is a diagonalizable linear operator on a finite dimensional space \mathbf{V}, and if c_1, c_2, \dots, c_k are distinct characteristic values of \mathbf{T}, then there exist</p>

	<p>linear operators $\mathbf{E}_1, \mathbf{E}_2, \dots, \mathbf{E}_k$ such that:</p> <ol style="list-style-type: none"> (1) $\mathbf{T} = c_1 \mathbf{E}_1 + \dots + c_k \mathbf{E}_k$ (2) $\mathbf{E}_1 + \dots + \mathbf{E}_k = \mathbf{I}$ (3) $\mathbf{E}_i \mathbf{E}_j = \mathbf{0}, \quad i \neq j$ (4) $\mathbf{E}_i = \mathbf{E}_i^2, \quad (\mathbf{E}_i \text{ is a projection})$ (5) $\alpha = \mathbf{E}_i \alpha, \forall \alpha \in \mathbf{V}$
Relation between Lagrange Polynomials and Projection	<p>We have:</p> $\mathbf{T} = c_1 \mathbf{E}_1 + \dots + c_k \mathbf{E}_k$ <p>If g is any polynomial over field \mathbb{F},</p> $g(\mathbf{T}) = g(c_1) \mathbf{E}_1 + \dots + g(c_k) \mathbf{E}_k \quad \dots (1)$ <p>Now,</p> $p_j = \prod_{i \neq j} \frac{(x - c_i)}{(c_j - c_i)}$ $\Rightarrow p_j(c_i) = \delta_{ij} \text{ (Kronecker Delta)} \quad \dots (2)$ <p>From (1) and (2),</p> $\Rightarrow p_j(\mathbf{T}) = \sum_{i=1}^k \delta_{ij} \mathbf{E}_i = \mathbf{E}_j$ $\Rightarrow \boxed{p_j(\mathbf{T}) = \mathbf{E}_j}$ <p>\Rightarrow Projections \mathbf{E}_j are polynomials in \mathbf{T}</p>

TABLE 1: Definitions and results used

3 SOLUTION

Given	<p>Matrix of \mathbf{T} in the standard basis of \mathbb{R}^3 :</p> $\mathbf{A} = \begin{pmatrix} 5 & -6 & -6 \\ -1 & 4 & 2 \\ 3 & -6 & -4 \end{pmatrix}$
Characteristic polynomial	$p(x) = x\mathbf{I} - \mathbf{A} $ $= \begin{vmatrix} x & -1 & 0 \\ -2 & x+2 & -2 \\ -2 & 3 & x-2 \end{vmatrix}$ $= x^3 - 5x^2 + 8x - 4$ $= (x-1)(x-2)^2$ $\Rightarrow \lambda = 1, 2$

Minimal Polynomial	$p(x) = (x - 1)(x - 2)^b, \quad b \leq 2$ $(\mathbf{A} - \mathbf{I})(\mathbf{A} - 2\mathbf{I}) = \begin{pmatrix} 4 & -6 & -6 \\ -1 & 3 & 2 \\ 3 & -6 & -5 \end{pmatrix} \begin{pmatrix} 3 & -6 & -6 \\ -1 & 2 & 2 \\ 3 & -6 & -6 \end{pmatrix} = \mathbf{0}$ <p>Therefore, $(x - 1)(x - 2)$ is the minimal polynomial.</p>
Lagrange Polynomial	$p_j = \prod_{i \neq j} \frac{(x - c_i)}{(c_j - c_i)}$ <p>For characteristic values $c_1 = 1, \quad c_2 = 2,$</p> $\Rightarrow p_1 = \frac{(x-1)}{2-1}, \quad p_2 = \frac{(x-2)}{1-2}$ $\Rightarrow p_1 = (x - 1), \text{ and}$ $p_2 = (2 - x)$
Projection Maps	<p>We know that,</p> $\mathbf{E}_j = p_j(\mathbf{T})$ $\Rightarrow \mathbf{E}_1 = \mathbf{A} - \mathbf{I} \text{ and } \mathbf{E}_2 = 2\mathbf{I} - \mathbf{A}$ $\Rightarrow \mathbf{E}_1 = \begin{pmatrix} 4 & -6 & -6 \\ -1 & 3 & 2 \\ 3 & -6 & -5 \end{pmatrix}, \text{ and}$ $\mathbf{E}_2 = \begin{pmatrix} -3 & 6 & 6 \\ 1 & -2 & -2 \\ -3 & 6 & 6 \end{pmatrix}$
Verification	<p>We have,</p> $\mathbf{E}_1 = \mathbf{A} - \mathbf{I}$ $\Rightarrow \mathbf{A} - \mathbf{E}_1 = \mathbf{I} \quad \dots (1)$ $\mathbf{E}_2 = 2\mathbf{I} - \mathbf{A}$ <p>From (1),</p> $\Rightarrow \mathbf{E}_2 = 2(\mathbf{A} - \mathbf{E}_1) - \mathbf{A}$ $\Rightarrow \boxed{\mathbf{A} = 2\mathbf{E}_1 + \mathbf{E}_2}$ <p>Also,</p> $\mathbf{E}_1 = \begin{pmatrix} 4 & -6 & -6 \\ -1 & 3 & 2 \\ 3 & -6 & -5 \end{pmatrix}, \quad \mathbf{E}_2 = \begin{pmatrix} -3 & 6 & 6 \\ 1 & -2 & -2 \\ -3 & 6 & 6 \end{pmatrix}$

	$\Rightarrow \mathbf{E}_1 + \mathbf{E}_2 = \begin{pmatrix} 4 & -6 & -6 \\ -1 & 3 & 2 \\ 3 & -6 & -5 \end{pmatrix} + \begin{pmatrix} -3 & 6 & 6 \\ 1 & -2 & -2 \\ -3 & 6 & 6 \end{pmatrix}$ $= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$ $\Rightarrow \boxed{\mathbf{E}_1 + \mathbf{E}_2 = \mathbf{I}}$ $\mathbf{E}_1 \mathbf{E}_2 = \begin{pmatrix} 4 & -6 & -6 \\ -1 & 3 & 2 \\ 3 & -6 & -5 \end{pmatrix} \begin{pmatrix} -3 & 6 & 6 \\ 1 & -2 & -2 \\ -3 & 6 & 6 \end{pmatrix}$ $= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ $\Rightarrow \boxed{\mathbf{E}_1 \mathbf{E}_2 = \mathbf{0}}$
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TABLE 2: Using Lagrange Polynomials to represent A