

Fundamentals of MIMO Wireless Communication

Tutorial

Rubeena Aafreen

Prime Minister Research fellow
IIT Hyderabad

Week 4
March 3, 2023

Prev. Week:

Re Signal correlation:-

$$\begin{aligned}\phi_{rr}(\Delta t) &= E[r(t)r(t+\Delta t)] \\ &= \phi_{h_r h_r}(\Delta t) \cos \omega_c \Delta t - \phi_{h_r h_o}(\Delta t) \sin \omega_c \Delta t\end{aligned}$$

$$r(t) = \text{Re}\{h(t)e^{j2\pi f_c t}\}$$

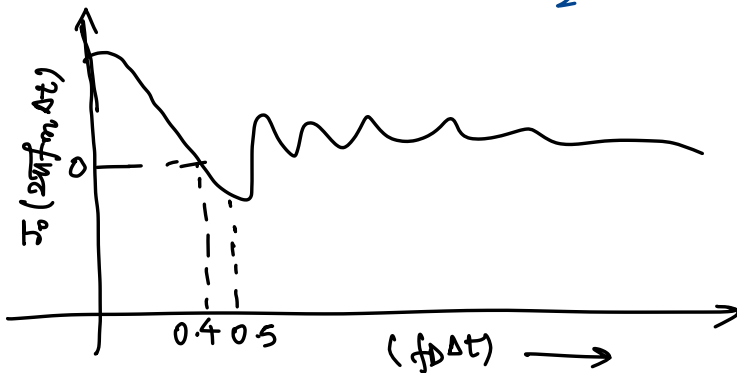
$$\phi_{rr}(\Delta t) = \text{Re}\{\phi_{hh}(\Delta t)e^{j2\pi f_c \Delta t}\}$$

$$\phi_{hh}(\Delta t) = \phi_{h_r h_r}(\Delta t) + \phi_{h_r h_o}(\Delta t)$$

$$\phi_{h_r h_o}(\Delta t) = 0$$

$$\phi_{h_1 h_1}(\Delta t) = \frac{\sqrt{2P}}{2} J_0(2\pi f_{\max} \Delta t)$$

$$\phi_{h_1 h_2}(\Delta t) = \phi_{h_2 h_1}(\Delta t) = \frac{\sqrt{2P}}{2} J_0(2\pi f_{\max} \Delta t)$$



We had considered 'isotropic scattering',

$$p(\theta) = \text{Uniform} = \frac{1}{2\pi}$$

$$\Phi_{h_f h_f}(\Delta t) = \frac{\eta_p}{2} J_0(2\pi f_m \Delta t).$$

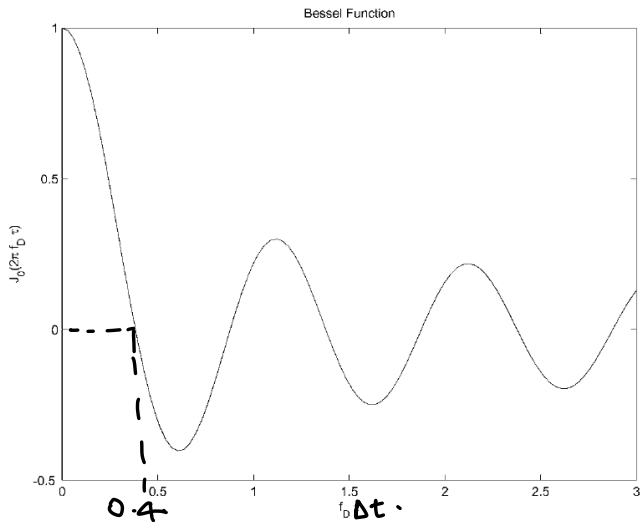
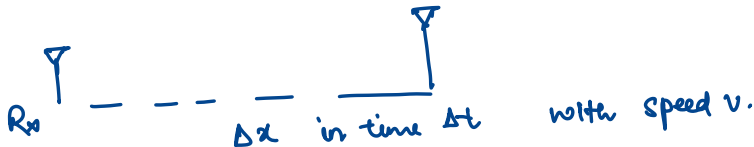


Figure 3.5: Bessel function versus $f_D \tau$.

Suppose moving mobile.



$$\Delta x = v \Delta t \quad \text{--- (1)}$$

$$\frac{v}{c} f_c = f_m$$

$$\Rightarrow v = \frac{f_m}{f_c} \cdot c \quad \text{--- (2)}$$

$$\Delta x = \frac{f_m}{f_c} \cdot c \cdot \Delta t = \frac{f_m \Delta t}{f_c} \cdot c$$

$$f_m \Delta t = \frac{\Delta x \cdot f_c}{c}$$

$$c = f_c \cdot \lambda$$

$$\Rightarrow f_m \Delta t = \frac{\Delta x}{\lambda}$$

$$\Phi_{h_I h_I}(\Delta t) = \frac{\Omega_p}{2} J_0(2\pi f_m \Delta t)$$

$$\Phi_{h_I h_I}(\Delta x) = \frac{\Omega_p}{2} J_0\left(2\pi \frac{\Delta x}{\lambda}\right)$$

$$\alpha = |h(t)|$$

$$S_{\alpha\alpha}(\Delta x) = \frac{\pi}{16} \Omega_p J_0^2\left(\frac{2\pi}{\lambda} \Delta x\right)$$

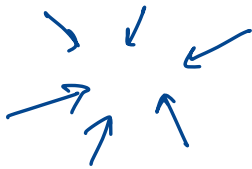
$\int_0 \Delta t = 0.4$ for uncorrelated sig.

$$\frac{\Delta x}{\lambda} \approx 0.4$$

$$\Rightarrow \Delta x \approx 0.4\lambda \approx \frac{\lambda}{2}$$

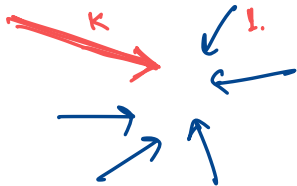
→ for uncorrelated sig, antennas should be spaced at min $\frac{\lambda}{2}$ distance.

Note: if $p(\theta)$ is different, results will change.



$$p(\theta) = \frac{1}{2\pi}$$

LOS component present:-



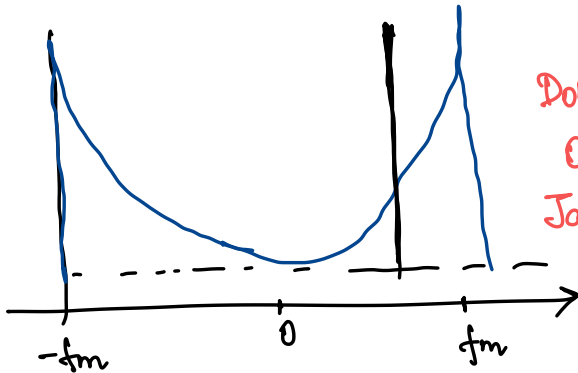
$$p(\theta) = \underbrace{\left(\frac{1}{K+1}\right) \hat{p}(\theta)}_{\text{scattering}} + \underbrace{\left(\frac{K}{K+1}\right) \delta(\theta - \theta_0)}_{\text{LOS.}}$$

Uniform

$\theta_0 \rightarrow$ AoA of specular component.

$$S_{h_f h_f}(\Delta t) = \frac{\Omega_p}{2\pi f_m} \cdot \frac{1}{\sqrt{1 - \left|\frac{f}{f_m}\right|^2}}, \quad \left|\frac{f}{f_m}\right| \leq 1$$

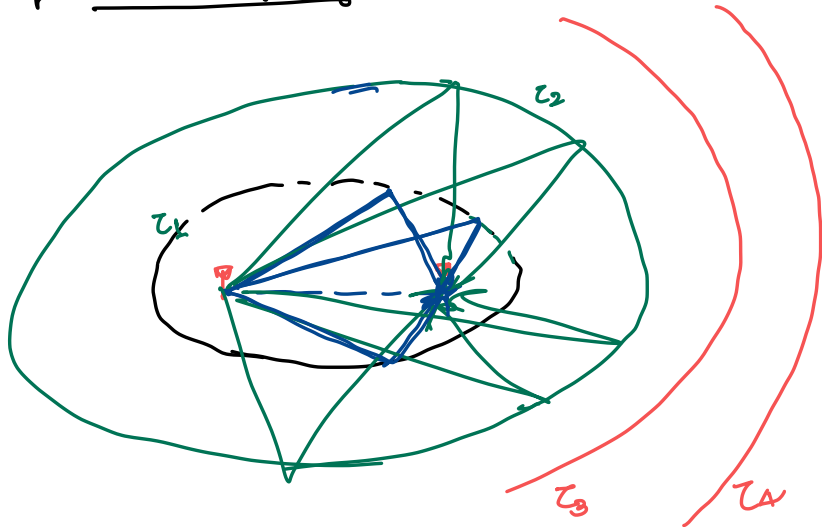
$$f \leq f_m.$$

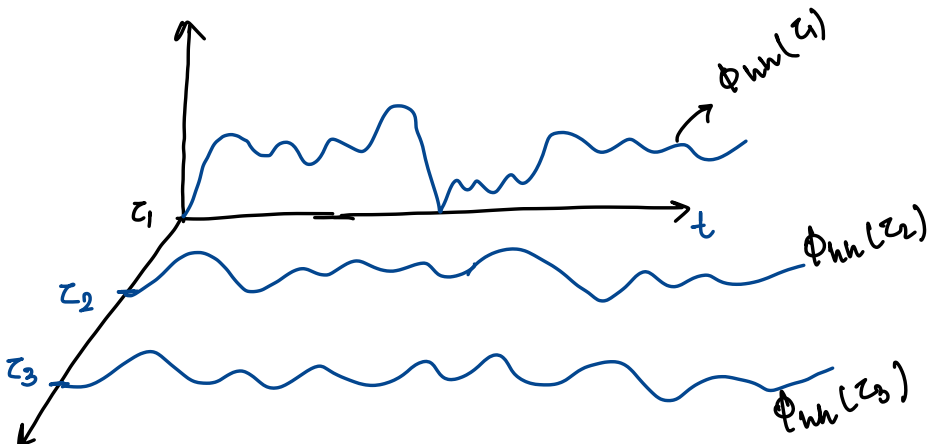


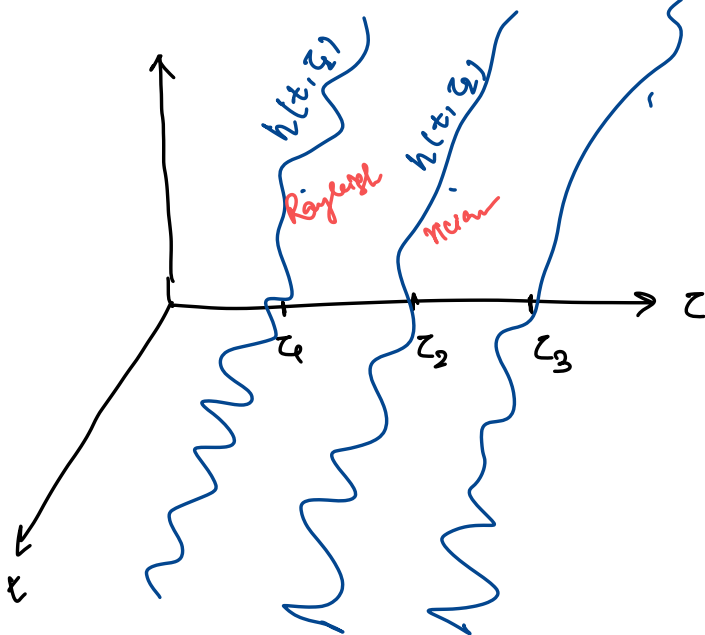
Doppler spectrum
Or,
Jakes spectrum

$$P(\theta) = \frac{1}{2\pi}$$

freq. Selective fading:







freq. selective fading:-

$$h(t, \tau) = \sum_{n=1}^N C_n e^{-j\phi_n(t)} \delta(\tau - \tau_n).$$

$$\phi_n(t) = 2\pi \{ (f_c + f_{D,n}) \tau_n - f_{D,n} t \}$$

$$\phi_{n_0}(t) = 2\pi \{ (f_c + f_{\max} \cos(\theta_{n_0})) \tau_{n_0} - f_{\max} \cos(\theta_{n_0}) t \}$$

$$h(t, \tau) = \sum_{n_0=1}^N C_{n_0,1} e^{-j\phi_{n_0}(t, \tau_1)} \delta(\tau - \tau_1) + \sum_{n_0=1}^N C_{n_0,2} e^{-j\phi_{n_0}(t, \tau_2)} \delta(\tau - \tau_2) + \dots$$

f.T :

$$H(t, k) = \sum_{n_z=1}^{N_{zmax}} h(t, z) e^{-j2\pi k/N_f \cdot n_z}$$

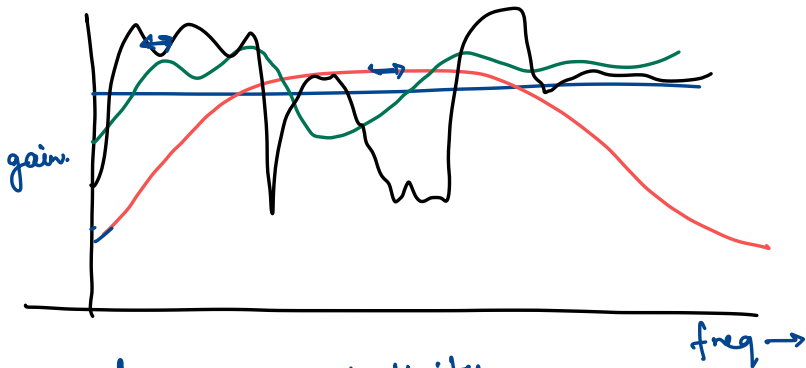
$$H(t, k) = h(t, z_1) e^{-j2\pi k/N_f \cdot 1} + h(t, z_2) e^{-j2\pi k/N_f \cdot 2}$$

+ - - -

$$H(t, k) = \mathcal{F}(h(t, z_1)) + \mathcal{F}(h(t, z_2)) + \dots$$

$$+ \mathcal{F}(h(t, z_{max}))$$

$$H(t, k) = H(t, k_{z_1}) + H(t, k_{z_2}) + \dots + H(t, k_{z_{max}}).$$



→ frequency selectivity.

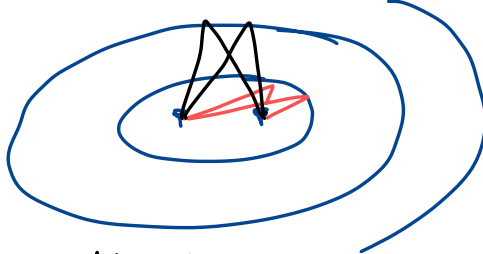
Coherence BW:

$$B_c \propto \frac{1}{T_{\text{rms}}}$$

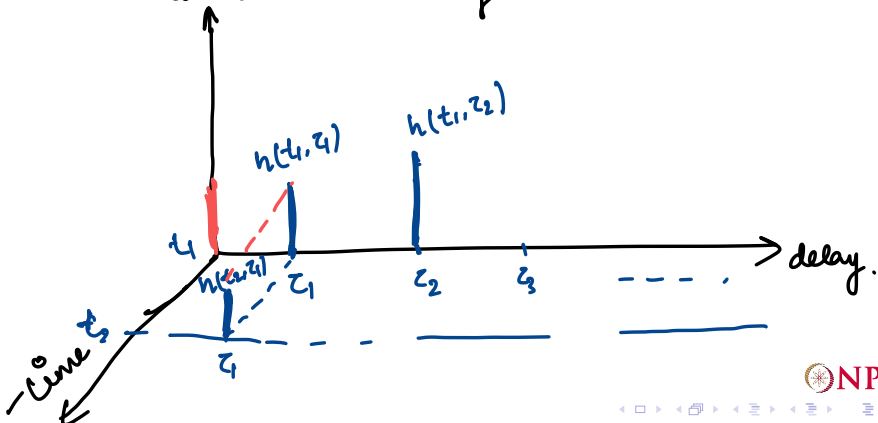
$T_{\text{rms}} \rightarrow$ Rms delay spread.

$$B_c(0.5) = \frac{1}{5 T_{\text{rms}}} \rightarrow 50\% \text{ coherence BW}$$

$$B_c(0.9) = \frac{1}{50 T_{\text{rms}}} \rightarrow 90\% \text{ coherence BW.}$$



→ all resolvable delay.

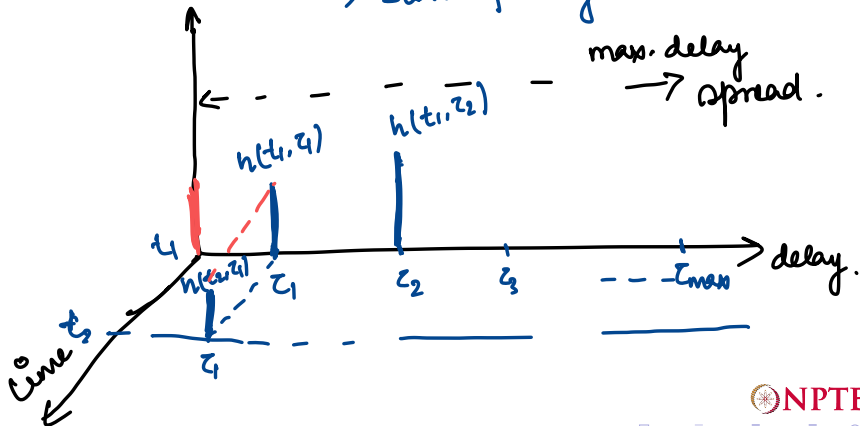


$$h(t_1, \tau_1) \text{ \& \; } h(t_2, \tau_1) \rightarrow$$

$$\dot{\gamma}(t_2 - t_1) \ll T_c$$

$$\rightarrow h(t_1, \tau_n) \approx h(t_2, \tau_n)$$

\rightarrow Slow fading



delay spread: difference b/w time of arrival of earliest multipath component & last component.

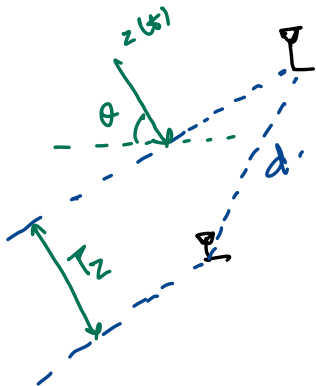
Average delay / mean delay : $\tau_m = \frac{\int_0^{\infty} \tau E|h(\tau)|^2 d\tau}{\int_0^{\infty} E|h(\tau)|^2 d\tau}$

rms delay: $\tau_{rms} = \sqrt{\overline{\tau^2} - \tau_m^2}$

$$\bar{z}^2 = \frac{\int_0^{\infty} z^2 E[|h(z)|^2] dz}{\int_0^{\infty} E[|h(z)|^2] dz}$$

$$z_{rms} = \sqrt{\bar{z}^2 - z_m^2}$$

Narrowband antenna array:-



$T_2 \rightarrow$ time diff b/w reaching 1st & 2nd antenna.

Narrowband antennas
assumption:

$B \rightarrow$ BW of signal.

$$B < \frac{1}{T_2}$$

$$T_z = 5 \text{ ns}$$

a. 100 MHz

b. 200 MHz

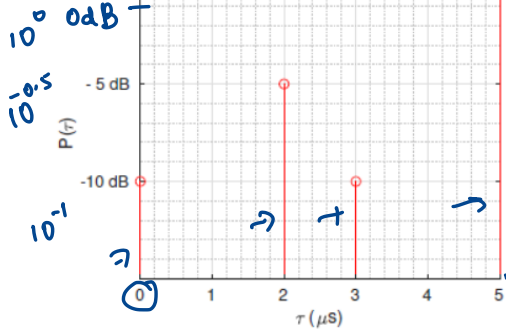
☒ c. 10 MHz

d. 1 GHz

$$\frac{1}{T_z} = \frac{1}{5 \times 10^{-9}} = 200 \text{ MHz}$$

For narrowband assumption,

$$B \ll \frac{1}{T_z}$$



$$\tau_{\max} = 5 \mu\text{s}$$

$$\tau_m = \frac{5 \times 10^0 + 3 \times 10^{-1} + 2 \times 10^{-0.5}}{10^0 + 10^{-0.5} + 10^{-1} + 10^{-1}} \approx 3.9 \mu\text{s}.$$

The maximum delay spread and average delay spread are respectively.

a. $5 \mu\text{s}$ and $3.9 \mu\text{s}$.

b. $5 \mu\text{s}$ and $2.9 \mu\text{s}$.

c. ∞ , and $0.9 \mu\text{s}$.

d. None of the above.

$$\tau_m = 3.9 \mu s.$$

$$\bar{\tau}^2 = \frac{\tau_1^2 P(\tau_1) + \tau_2^2 P(\tau_2) + \tau_3^2 P(\tau_3) + \tau_4^2 P(\tau_4)}{P(\tau_1) + P(\tau_2) + P(\tau_3) + P(\tau_4)}$$

$$= \frac{0 \times 10^{-1} + 4 \times 10^{-0.5} + 9 \times 10^{-1} + 28 \times 10^{-0}}{0.1 + 0.316 + 0.1 + 1}$$

$$= 17.918 \mu s.$$

$$\tau_{me} = \sqrt{\bar{\tau}^2 - \tau_m^2} = \sqrt{17.918 - (3.9)^2}$$

$$= 1.6 \mu s.$$

The RMS delay spread in the previous problem is obtained as,

a. $4.6\mu s$

b. $3.6\mu s$

c. $2.6\mu s$

☒ d. $1.6\mu s$

Let $h(t_1, \tau)$ and $h(t_2, \tau)$ are impulse responses of a channel at time instants t_1 and t_2 . If $|t_1 - t_2| \ll T_c$, where, T_c is the channel coherence time, then the impulses received at a delay of τ_1 at time instants t_1 and t_2 would be

- a. Totally unrelated
- ☒ b. Almost same in magnitude and phase angle
- c. Almost same in magnitude but would have totally unrelated phase angles
- d. Almost same in phase angle but would have totally unrelated magnitudes

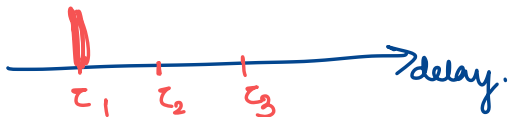
$$|t_1 - t_2| \ll T_c$$
$$h(t_1, \tau) \approx h(t_2, \tau)$$

↑

rms delay spread : τ_{rms} .

$\tau_{\text{rms}} \rightarrow$

for any impulse sent, how much is the spread of envelope.



$$\tau_{\text{max}} \approx (5-10) \tau_{\text{rms}}$$

The rms delay spread of a wireless channel experiencing frequency selective fading is $1 \mu\text{s}$. The maximum excess delay is likely to be

a. $0.5 \mu\text{s}$

b. $1 \mu\text{s}$

~~c. $5 \mu\text{s}$~~

d. 1 ms

$$\tau_{\text{rms}} = 1 \mu\text{s}.$$

$$\tau_{\text{max}} \approx (5-10) \tau_{\text{rms}}$$

$$\approx 5 \mu\text{s} - 10 \mu\text{s}.$$

Coherence distance is inversely proportional to

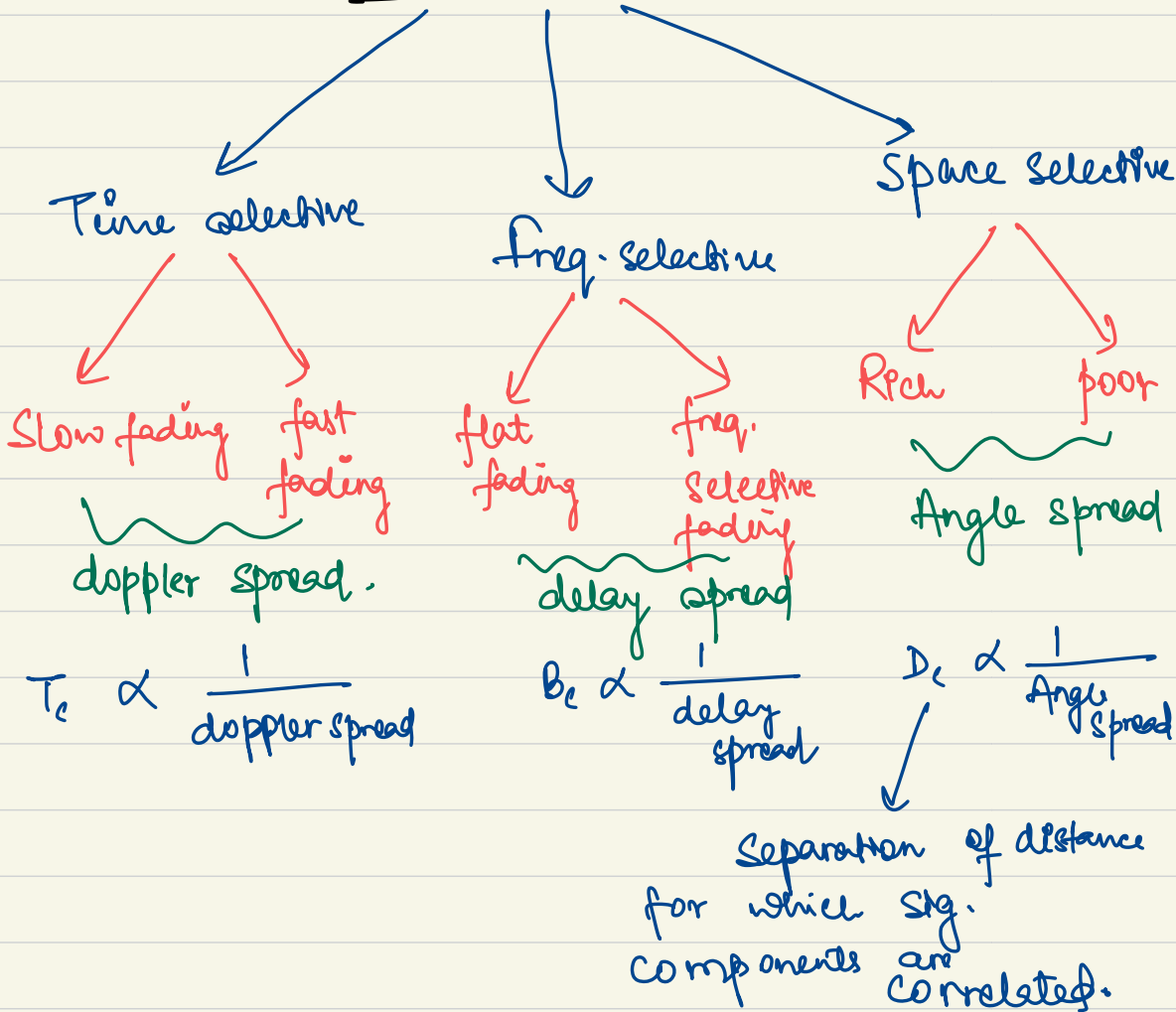
a. delay spread $B_c \propto \frac{1}{\text{delay spread}}$

b. doppler spread $(T_c \propto \frac{1}{f},)$

☒ c. angle spread

d. all the above

Wireless channel



multipath delay $< T_s/10$

→ delay $\ll T_s \rightarrow$ flat fading

→ not time resolvable

→ components not distinguishable

→ No ISI

multipath delay $> T_s/10$.

- frequency selective fading

→ Time resolvable.

→ Components are distinguishable.

→ ISI

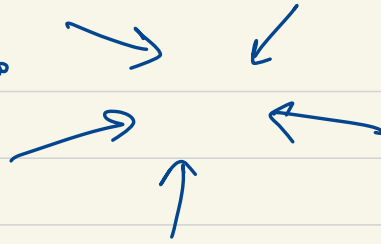


$T_c > T_s \rightarrow$ flat

$T_c < T_s \rightarrow$

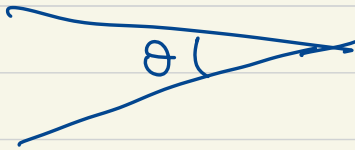
Rich Scattering:

(lots of reflection)



→ coherence distance → low
angle spread → more.

Poor Scattering



angle spread → less.
coherence distance →
more.

Which of the following is **NOT** true for a Wide Sense Stationary Uncorrelated Scattering (WSSUS) channel?

- a. Impulse response of the channel at two different delays τ_1 and τ_2 are uncorrelated, no matter how small $|\tau_1 - \tau_2|$ is. — — —
- b. Channel scattering functions at two different Doppler frequencies ν_1 and ν_2 are uncorrelated, no matter how small $|\nu_1 - \nu_2|$ is. — —
- c. Impulse response of the channel at two different time instants t_1 and t_2 are uncorrelated, no matter how small $|t_1 - t_2|$ is. —
- d. The channel may be time variant.

WSS US

HO $\rightarrow \Delta d$.

WSS: $\Delta \tau$
 US: Δf

The channel matrix of a single input multiple output (SIMO) channel can be represented as

- a. scalar.
- ☒ b. column vector.
- c. row vector.
- d. square matrix.

$$y = Hx + n.$$

MIMO:
$$\begin{bmatrix} y_{kH} \end{bmatrix}_{M_R \times 1} = \begin{bmatrix} H \end{bmatrix}_{M_R \times M_T} \begin{bmatrix} x_{kH} \end{bmatrix}_{M_T \times 1} + \begin{bmatrix} n_{kH} \end{bmatrix}_{M_R \times 1}$$

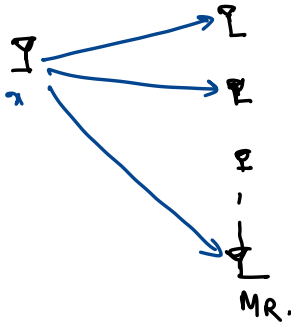
SISO: $M_R = 1, M_T = 1.$

SIMO: $M_T = 1, M_R = M_R.$

MISO: $M_T = M_T, M_R = 1.$

flat fading channel :-

SIMO:



Assuming flat fading

$$h(t, z) \underset{\uparrow}{\approx} h(t).$$

$$h(t) = [h_1(t) \quad h_2(t) \quad \dots \quad h_{M_R}(t)]^T.$$

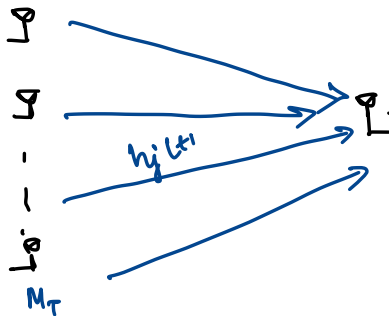
$$= \begin{bmatrix} h_1(t) \\ \vdots \\ h_{M_R}(t) \end{bmatrix}$$

$$\boxed{y = h x + n}$$

$$\begin{bmatrix} y_1(t) \\ y_2(t) \\ \vdots \\ y_{M_R}(t) \end{bmatrix}_{M_R \times 1} = \begin{bmatrix} h_1(t) \\ h_2(t) \\ \vdots \\ h_{M_R}(t) \end{bmatrix} x + \begin{bmatrix} n_1(t) \\ n_2(t) \\ \vdots \\ n_{M_R}(t) \end{bmatrix}$$

$$y(t) = h_1(t)x(t) + h_2(t)x(t) + \dots + \tilde{n}(t)$$

MISO:

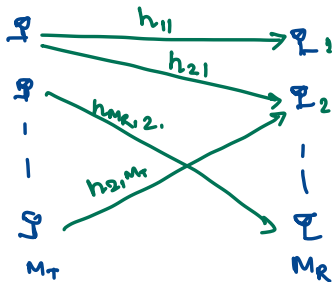


$$y = hx + n.$$

$$y(t) = \begin{bmatrix} x_1(t) \\ x_2(t) \\ \vdots \\ x_{M_T}(t) \end{bmatrix} [h_1(t) \dots h_{M_T}(t)] + n(t)$$

$M_T \times 1$

MIMO:



$$y = hx + n$$

$$\begin{bmatrix} y_1(t) \\ y_2(t) \\ \vdots \\ y_{M_R}(t) \end{bmatrix}_{M_R \times 1} = \begin{bmatrix} h_{11}(t) & \dots & h_{1M_T}(t) \\ \vdots & & \vdots \\ h_{M_R,1}(t) & \dots & h_{M_R,M_T}(t) \end{bmatrix}_{M_R \times M_T} \begin{bmatrix} x_1(t) \\ \vdots \\ x_{M_T}(t) \end{bmatrix}_{M_T \times 1} + \begin{bmatrix} n_1(t) \\ \vdots \\ n_{M_R}(t) \end{bmatrix}_{M_R \times 1}$$

$$Y = HS + n.$$

$$y_i(t) = \sum_{j=1}^{M_T} h_{ij}(t) s_j(t)$$

A mobile station is moving at a speed of 500 kmph. It is using 2.4 GHz carrier frequency. To accomplish channel equalization, it measures the channel coefficients in a regular interval. What should be the maximum measurement interval?

- a. 120.26 μs .
- b. 161.14 μs .
- c. 180.24 μs .
- d. 200.68 μs .

$$\underline{\underline{R_n}} \text{ --- --- --- --- ---}$$

$$v = 500 \text{ kmph} = 138.8 \text{ m/s.}$$

$$f_c = 2.4 \text{ GHz.}$$

$$f_D = \frac{v}{c} \cdot f_c = \frac{138.8}{3 \times 10^8} \times 2.4 \times 10^9 = 1110.4$$

Z is an element of the channel matrix of a Zero Mean Circularly Symmetric Complex Gaussian (ZMCSG) MIMO channel. Then the expectation of $Ze^{j\phi}$ is

a. always zero.

b. zero only if $\phi = 0$.

c. zero only if $Z = 0$.

d. zero if either $\phi = 0$ or $Z = 0$.

$$E[Z e^{j\phi}] = e^{j\phi} E[Z] = 0.$$

Classic iid channel?

$$\tau_{\text{mme}} \approx 0.$$

→ H can be modelled as

$$Z = X + jY$$

ZMCSG

$X \rightarrow$ Gaussian, with
 $Y \rightarrow$ Zero mean.

Circular symmetry.

$$E[e^{j\phi} Z] = e^{j\phi} E[Z].$$

A is a matrix of the order $m \times n$. Then the order of $\text{vec}(A)$ would be

- a. $m \times n$
- b. $n \times m$
- ☒ c. $mn \times 1$
- d. $1 \times mn$

$$A = \left[\begin{array}{c} \\ \\ \end{array} \right]_{m \times n}$$

$$\text{vec } A = \left[\begin{array}{c} \\ \\ \end{array} \right]_{mn \times 1}$$

The rms delay spread in a channel is found to be $1.5 \mu\text{s}$. The 50% and 90% coherence bandwidth of the channel are respectively:-

- a. 55 kHz, 5 kHz
- b. 25 kHz, 2.5 kHz
- c. 155 kHz, 15.5 kHz
- ☒ d. 133 kHz, 13.3 kHz

$$\tau_{\text{rms}} = 1.5 \mu\text{s}.$$
$$B_c(0.5) = \frac{1}{5 \tau_{\text{rms}}} = \frac{1}{7.5 \times 10^{-6}}$$

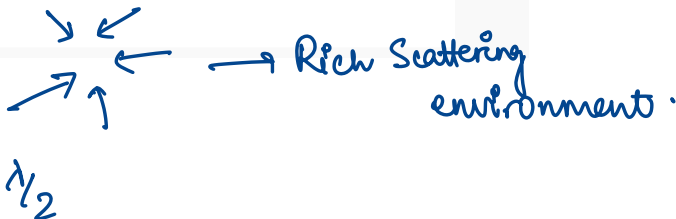
$$= 133 \text{ kHz}.$$

$$B_c(0.9) = \frac{1}{50 \tau_{\text{rms}}} = 13.3 \text{ kHz}.$$

What is the minimum physical separation required between adjacent antennas in a rich scattering environment to have independently faded received signals? (λ denotes wavelength)

- a. λ
- ☒ b. $\frac{\lambda}{2}$
- c. $\frac{\lambda}{3}$
- d. $\frac{\lambda}{4}$

$$p(\theta) = \frac{1}{2\pi}$$



The channel covariance matrix \mathbf{R} is identified as a positive semidefinite hermitian matrix. What are the properties of \mathbf{R} ?

- a. Eigen values are real —
- b. Eigen values are distinct —
- c. Eigen values are non negative —

$$\mathbf{R} = E [\text{vec}(\mathbf{H}) \text{vec}(\mathbf{H})^H]$$

✓ All the above

MIMO:

$$\mathbf{H} \rightarrow M_R \times M_T \rightarrow \text{vec}(\mathbf{H}) \rightarrow M_R M_T \times 1.$$

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 9 & 8 \end{bmatrix}_{3 \times 3} \rightarrow \text{vec}(\mathbf{A}) \rightarrow 9 \times 1 \rightarrow \begin{bmatrix} 1 \\ 4 \\ 7 \\ 2 \\ 5 \\ 6 \\ 9 \\ 3 \\ 8 \end{bmatrix}$$

$$R = E \begin{bmatrix} \text{vec}(H) & \text{vec}(H)^H \end{bmatrix} \\ (M_{RM_T} \times 1) (1 \times M_{RM_T})$$

→ Square matrix.

$R \rightarrow$ +ve semidefinite matrix.

All eigen values are real, distinct and non-negative ≥ 0 .

