

1 Ontology Languages

- Elements of an ontology language
- Intensional and extensional level of an ontology language
- Ontologies vs. other formalisms

2 UML class diagrams as FOL ontologies

- Approaches to conceptual modelling
- Formalising UML class diagram in FOL
- Reasoning on UML class diagrams

3 Brief introduction to computational complexity

- Basic Definitions
- Hardness and Completeness
- Most Important complexity classes

4 Introduction to Description Logics

- Ingredients of Description Logics
- Description Logics ontologies
- Reasoning in Description Logics

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- **Syntax**
 - Alphabet
 - Languages constructs
 - Sentences to assert knowledge
- **Semantics**
 - Formal meaning
- **Pragmatics**
 - Intended meaning
 - Usage

The aspects of the domain of interest that can be modeled by an ontology language can be classified into:

- **Static aspects**
 - Are related to the structuring of the domain of interest.
 - Supported by virtually all languages.
- **Dynamic aspects**
 - Are related to how the elements of the domain of interest evolve over time.
 - Supported only by some languages, and only partially (cf. services).

Before delving into the dynamic aspects, we need a good understanding of the static ones. In this course we concentrate essentially on the static aspects.

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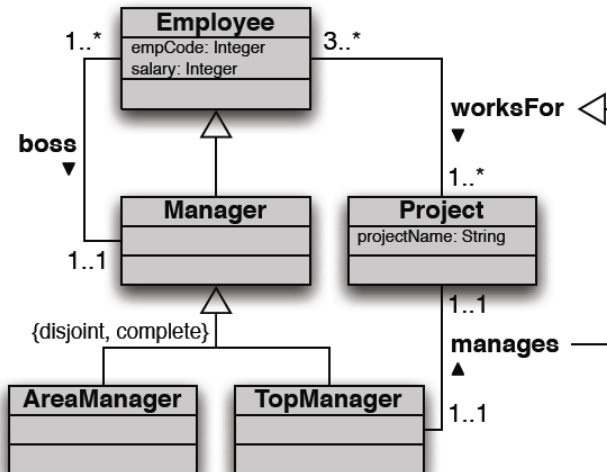
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An ontology language for expressing the intensional level usually includes:

- Concepts
- Properties of concepts
- Relationships between concepts, and their properties
- Axioms
- Queries

Ontologies are typically **rendered as diagrams** (e.g., Semantic Networks, Entity-Relationship schemas, UML Class Diagrams).

Example: ontology rendered as UML Class Diagram



Definition (Concept)

A **concept** is an element of an ontology that denotes a collection of instances (e.g., the set of “employees”).

We distinguish between:

- **Intensional definition:**
 - specification of **name, properties, relations**,...
- **Extensional definition:**
 - specification of the **instances**

Concepts are also called **classes, entity types, frames**.

Definition (Property)

A **property** is an element of an ontology that qualifies another element (e.g., a concept or a relationship).

Property definition (intensional and extensional):

- Name
- Type: may be either
 - atomic (integer, real, string, enumerated,...), or
e.g., **eye-color** → { **blu**, **brown**, **green**, **grey** }
 - structured (date, set, list,...)
e.g., **date** → **day/month/year**
- The definition may also specify a default value.

Properties are also called **attributes**, **features**, **slots**, **data properties**

Definition (Relationship)

A **relationship** is an element of an ontology that expresses an association among concepts.

We distinguish between:

- **Intensional definition:**
specification of involved **concepts**
e.g., **worksFor** is defined on **Employee** and **Project**
- **Extensional definition:**
specification of the instances of the relationship, called **facts**
e.g., **worksFor(domenico, tones)**

Relationships are also called **associations**, **relationship types**, **roles**, **object properties**.

Definition (Axiom)

An **axiom** is a logical formula that expresses at the intensional level a condition that must be satisfied by the elements at the extensional level.

Different kinds of axioms/conditions:

- subclass relationships, e.g., $\text{Manager} \sqsubseteq \text{Employee}$
- equivalences, e.g., $\text{Manager} \equiv \text{AreaManager} \sqcup \text{TopManager}$
- disjointness, e.g., $\text{AreaManager} \sqcap \text{TopManager} \equiv \perp$
- (cardinality) restrictions, e.g., each Employee worksFor at least 1 Project
- ...

Axioms are also called **assertions**.

A special kind of axioms are **definitions**

At the extensional level we have individuals and facts:

- An **instance** represents an individual (or object) in the extension of a concept.
e.g., **domenico** is an instance of **Employee**
- A **fact** represents a relationship holding between instances.
e.g., **worksFor(domenico, tones)**

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- Ontology languages vs. knowledge representation languages:
 - Ontologies **are** knowledge representation schemas.
- Ontology vs. logic:
 - Logic is **the** tool for assigning semantics to ontology languages.
- Ontology languages vs. conceptual data models:
 - Conceptual schemas **are** special ontologies, suited for conceptualizing a **single** logical model (database).
- Ontology languages vs. programming languages:
 - Class definitions **are** special ontologies, suited for conceptualizing a **single** structure for computation.

- Graph-based
 - Semantic networks
 - Conceptual graphs
 - **UML class diagrams**, Entity-Relationship diagrams
- Frame based
 - Frame Systems
 - OKBC, XOL
- Logic based
 - **Description Logics** (e.g., *SHOIQ*, *DLR*, **DL-Lite** , OWL,...)
 - Rules (e.g., RuleML, LP/Prolog, F-Logic)
 - First Order Logic (e.g., KIF)
 - Non-classical logics (e.g., non-monotonic, probabilistic)

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Exercise

Requirements: We are interested in building a software application to manage filmed scenes for realizing a movie, by following the so-called “Hollywood Approach”.

Every **scene** is identified by a code (a string) and is described by a text in natural language.

Every scene is filmed from different positions (at least one), each of this is called a **setup**. Every setup is characterized by a code (a string) and a text in natural language where the photographic parameters are noted (e.g., aperture, exposure, focal length, filters, etc.).

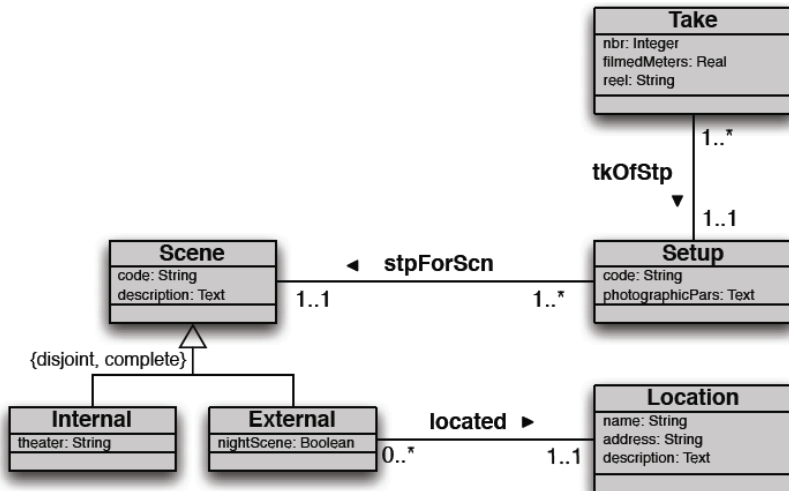
Note that a setup is related to a single scene.

For every setup, several **takes** may be filmed (at least one). Every take is characterized by a (positive) natural number, a real number representing the number of meters of film that have been used for shooting the take, and the code (a string) of the reel where the film is stored. Note that a take is associated to a single setup.

Scenes are divided into **internals** that are filmed in a theater, and **externals** that are filmed in a **location** and can either be “day scene” or “night scene”. Locations are characterized by a code (a string) and the address of the location, and a text describing them in natural language.

Write a precise specification of this domain using any formalism you like!

Solution 1: Use conceptual modeling diagrams (UML)!



Good points:

- Easy to generate (it's the standard in software design).
- Easy to understand for humans.
- Well disciplined, well-established methodologies available.

Bad points:

- No precise semantics (people that use it wave hands about it).
- Verification (or better validation) done informally by humans.
- Machine incomprehensible (because of lack of formal semantics).
- Automated reasoning and query answering out of question.
- Limited expressiveness.^a

^aNot really a bad point, in fact.

Use logic!!!

Alphabet

Scene(x), Setup(x), Take(x), Internal(x), External(x), Location(x), stpForScn(x, y), tkOfStp(x, y), located(x, y),...

Axioms

$$\begin{aligned}\forall x, y. \text{code}_{Scene}(x, y) &\rightarrow Scene(x) \wedge String(y) \\ \forall x, y. \text{description}(x, y) &\rightarrow Scene(x) \wedge Text(y) \\ \forall x, y. \text{code}_{Setup}(x, y) &\rightarrow Setup(x) \wedge String(y) \\ \forall x, y. \text{photographicPars}(x, y) &\rightarrow Setup(x) \wedge Text(y) \\ \forall x, y. \text{nbr}(x, y) &\rightarrow Take(x) \wedge Integer(y) \\ \forall x, y. \text{filmedMeters}(x, y) &\rightarrow Take(x) \wedge Real(y) \\ \forall x, y. \text{reel}(x, y) &\rightarrow Take(x) \wedge String(y) \\ \forall x, y. \text{theater}(x, y) &\rightarrow Internal(x) \wedge String(y) \\ \forall x, y. \text{nightScene}(x, y) &\rightarrow External(x) \wedge Boolean(y) \\ \forall x, y. \text{name}(x, y) &\rightarrow Location(x) \wedge String(y) \\ \forall x, y. \text{address}(x, y) &\rightarrow Location(x) \wedge String(y) \\ \forall x, y. \text{description}(x, y) &\rightarrow Location(x) \wedge Text(y) \\ \forall x. Scene(x) &\rightarrow (1 \leq \#\{y | \text{code}_{Scene}(x, y)\} \leq 1) \\ \forall x. Internal(x) &\rightarrow Scene(x) \\ \forall x. External(x) &\rightarrow Scene(x) \\ \forall x. Internal(x) &\rightarrow \neg External(x) \\ \forall x. Scene(x) &\rightarrow Internal(x) \vee External(x)\end{aligned}$$
$$\begin{aligned}\forall x, y. \text{stpForScn}(x, y) &\rightarrow \\ \forall Setup(x) \wedge Scene(y) & \\ \forall x, y. \text{tkOfStp}(x, y) &\rightarrow \\ \forall Take(x) \wedge Setup(y) & \\ \forall x, y. \text{located}(x, y) &\rightarrow \\ \forall External(x) \wedge Location(y) & \\ \forall x. Setup(x) &\rightarrow \\ \forall (1 \leq \#\{y | \text{stpForScn}(x, y)\} \leq 1) & \\ \forall y. Scene(y) &\rightarrow \\ \forall (1 \leq \#\{x | \text{stpForScn}(x, y)\} & \\ \forall x. Take(x) &\rightarrow \\ \forall (1 \leq \#\{y | \text{tkOfStp}(x, y)\} \leq 1) & \\ \forall x. Setup(y) &\rightarrow \\ \forall (1 \leq \#\{x | \text{stpForScn}(x, y)\} & \\ \forall x. External(x) &\rightarrow \\ \forall (1 \leq \#\{y | \text{located}(x, y)\} \leq 1) & \\ \dots &\end{aligned}$$

Good points:

- Precise semantics.
- Formal verification.
- Allows for query answering.
- Machine comprehensible.
- Virtually unlimited expressiveness ^a.

^aNot necessarily a good point, in fact.

Bad points:

- Difficult to generate.
- Difficult to understand for humans.
- Too unstructured (making reasoning difficult), no well-established methodologies available.
- Automated reasoning may be impossible.

Solution 3: Use both!!!

Note these two approaches seem to be orthogonal, but in fact they can be used together cooperatively!!!

Basic idea

- Assign formal semantics to constructs of the conceptual design diagrams.
- Use conceptual design diagrams as usual, taking advantage of methodologies developed for them in Software Engineering.
- Read diagrams as logical theories when needed, i.e., for formal understanding, verification, automated reasoning, etc.

Added value

- Inherited from conceptual modeling diagrams: ease-to-use for humans
- inherit from logic: formal semantics and reasoning tasks, which are needed for formal verification and machine manipulation.

Important

The logical theories that are obtained from conceptual modeling diagrams are of a specific form.

- Their expressiveness is limited (or better, well-disciplined).
- One can exploit the particular form of the logical theory to simplify reasoning.
- The aim is getting:
 - decidability, and
 - reasoning procedures that match the intrinsic computational complexity of reasoning over the conceptual modeling diagrams.

We illustrate now what we get from interpreting conceptual modeling diagrams in logic. We will use:

- as conceptual modeling diagrams: **UML Class Diagrams**. Note: we could equivalently use Entity-Relationship Diagrams instead of UML.
- as logic: **First-Order Logic** to formally capture **semantics** and **reasoning**.

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The Unified Modeling Language (UML)

The **Unified Modeling Language (UML)** was developed in 1994 by unifying and integrating the most prominent object-oriented modeling approaches:

- Booch
- Rumbaugh: Object Modeling Technique (OMT)
- Jacobson: Object-Oriented Software Engineering (OOSE)

History:

- 1995, version 0.8, Booch, Rumbaugh; 1996, version 0.9, Booch, Rumbaugh, Jacobson; version 1.0 BRJ + Digital, IBM, HP,...
- UML 1.4.2 is industrial standard ISO/IEC 15901.
- Current version: 2.3 (May 2010): <http://www.omg.org/spec/UML/>
- 1999-today: **de facto standard object-oriented modeling language**.

References:

- Grady Booch, James Rumbaugh, Ivar Jacobson, "The unified modeling language user guide", Addison Wesley, 1999 (2nd ed., 2005)
- <http://www.omg.org/> → UML
- <http://www.uml.org/>

In this course we deal only with one of the most prominent components of UML: UML Class Diagrams.

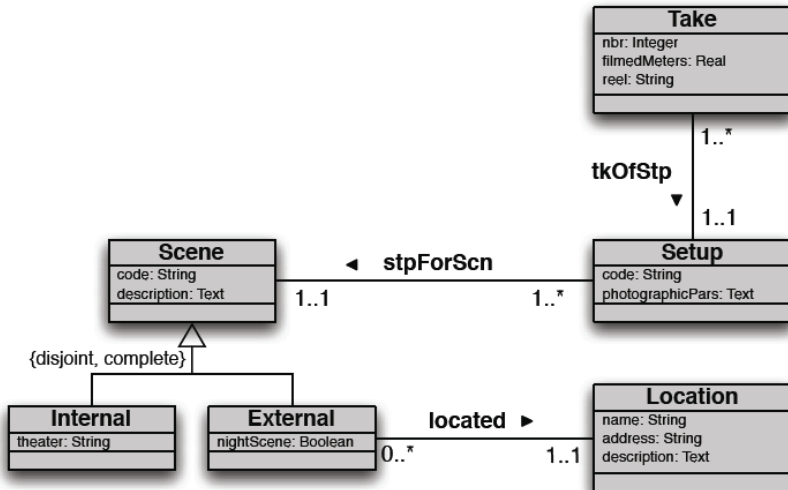
A UML Class Diagram is used to represent explicitly the information on a domain of interest (typically the application domain of software).

Note: This is exactly the goal of all conceptual modeling formalism, such as Entity-Relationship Diagrams (standard in Database design) or Ontologies.

The UML class diagram models the domain of interest in terms of:

- objects grouped into **classes**;
- **associations**, representing relationships between classes;
- **attributes**, representing simple properties of the instances of classes;
Note: here we do not deal with “operations”.
- **sub-classing**, i.e., ISA and generalization relationships.

Example of a UML Class Diagram



UML Class Diagrams are used in various phases of a software design:

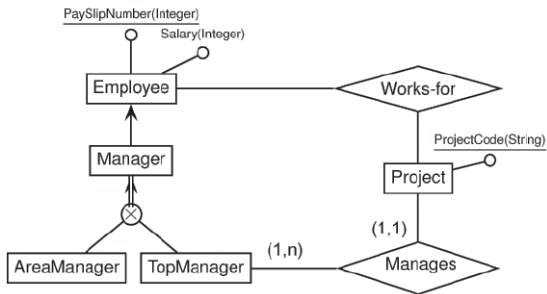
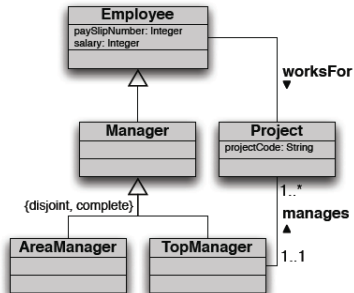
- ① During the so-called **analysis**, where an abstract precise view of the domain of interest needs to be developed.
~> the so-called “**conceptual perspective**”.
- ② During **software development**, to maintain an abstract view of the software to be developed.
~> the so-called “**implementation perspective**”.

In this course we focus on 1!

UML Class Diagrams and ER Schemas

UML class diagrams (when used for the conceptual perspective) closely resemble Entity-Relationship (ER) Diagrams.

Example of UML vs. ER:



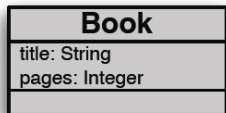
Definition (Class)

A **class** in UML models a **set of objects** (its “instances”) that share certain common properties, such as **attributes**, **operations**, etc.

Each class is characterized by:

- a **name** (which must be unique in the whole class diagram),
- a **set of (local) properties**, namely **attributes** and **operations** (see later).

Example



- the name of the class is 'Book'
- the class has two properties (attributes)

Definition (Instances)

The objects that belong to a class are called **instances** of the class. They form a so-called **instantiation** (or **extension**) of the class.

Example

Here are some possible instantiations of our class Book:

$$\{book_a, book_b, book_c, book_d, book_e\}$$
$$\{book_\alpha, book_\beta\}$$
$$\{book_1, book_2, book_3, \dots, book_{500}, \dots\}$$

Which is the actual instantiation?

We will know it only at run-time!!! - We are now at design time!

A class represents a set of objects. ... But which set? We don't actually know. So, how can we assign a semantics to such a class?

Definition (Class representation)

We represent a **class** as a **FOL unary predicate**!

Example

For our class *Book*, we introduce a predicate $Book(x)$.

Definition (Association)

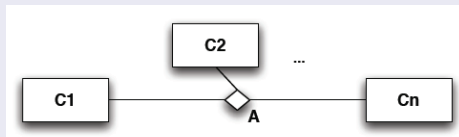
An **association** in UML models a **relationship** between two or more classes.

- At the instance level, an association is a relation between the instances of two or more classes.
- Associations model properties of classes that are **non-local**, in the sense that they involve other classes.
- An association between n classes is a property of each of these classes.

Example



Definition (Association representation)



We can represent an n -ary association A among classes C_1, \dots, C_n as an n -ary predicate A in FOL.

We assert that the components of the predicate must belong to the classes participating to the association:

$$\forall x_1, \dots, x_n. A(x_1, \dots, x_n) \rightarrow C_1(x_1) \wedge \dots \wedge C_n(x_n)$$

Example

$$\forall x_1, x_2. \text{writtenBy}(x_1, x_2) \rightarrow \text{Book}(x_1) \wedge \text{Author}(x_2)$$

Definition (Multiplicity Constraints)

On binary associations, we can place **multiplicity constraints**, i.e., a minimal and maximal number of tuples in which every object participates as first (second) component.

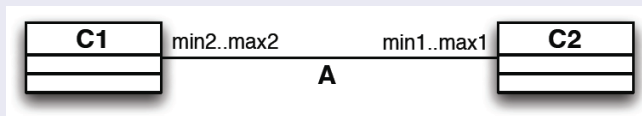
Example



Note: UML multiplicities for associations are **look-across** and are not easy to use in an intuitive way for n -ary associations. So typically they are not used at all.

In contrast, in ER Schemas, multiplicities are not look-across and are easy to use, and widely used.

Definition (Multiplicity constraint representation)



Multiplicities of binary associations are easily expressible in FOL:

$$\forall x_1 \cdot C_1(x_1) \rightarrow (\min_1 \leq \#\{x_2 | A(x_1, x_2)\} \leq \max_1)$$

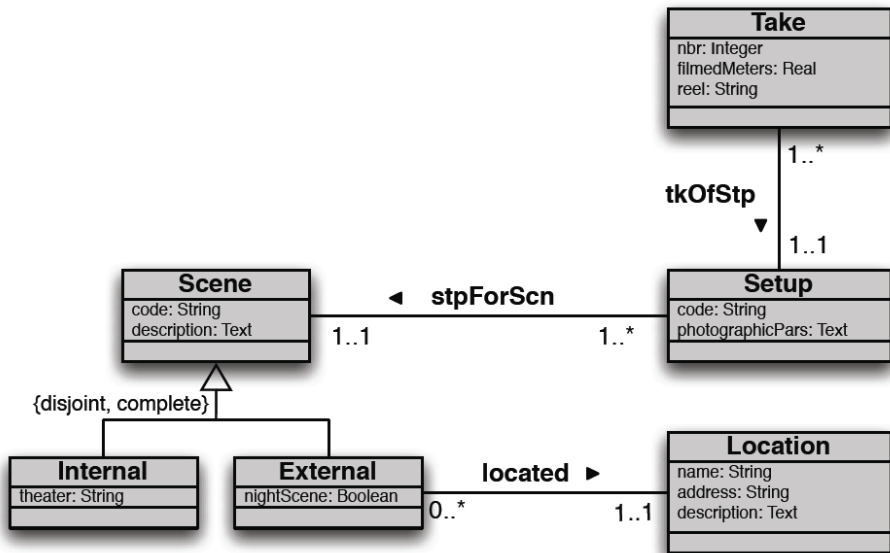
$$\forall x_2 \cdot C_2(x_2) \rightarrow (\min_2 \leq \#\{x_1 | A(x_1, x_2)\} \leq \max_2)$$

Example

$$\forall x \cdot Book(x) \rightarrow (1 \leq \#\{y | written_{by}(x, y)\})$$

Note: this is a shorthand for a FOL formula expressing the cardinality of the set of possible values for y .

In our example...



In our example...

Alphabet

$Scene(x)$, $Setup(x)$, $Take(x)$, $Internal(x)$, $External(x)$, $Location(x)$, $stpForScn(x, y)$,
 $tkOfStp(x, y)$, $located(x, y)$,...

Axioms

$\forall x, y. code_{Scene}(x, y) \rightarrow Scene(x) \wedge String(y)$
 $\forall x, y. description(x, y) \rightarrow Scene(x) \wedge Text(y)$
 $\forall x, y. code_{Setup}(x, y) \rightarrow Setup(x) \wedge String(y)$
 $\forall x, y. photographicPars(x, y) \rightarrow Setup(x) \wedge Text(y)$
 $\forall x, y. nbr(x, y) \rightarrow Take(x) \wedge Integer(y)$
 $\forall x, y. filmedMeters(x, y) \rightarrow Take(x) \wedge Real(y)$
 $\forall x, y. reel(x, y) \rightarrow Take(x) \wedge String(y)$
 $\forall x, y. theater(x, y) \rightarrow Internal(x) \wedge String(y)$
 $\forall x, y. nightScene(x, y) \rightarrow External(x) \wedge Boolean(y)$
 $\forall x, y. name(x, y) \rightarrow Location(x) \wedge String(y)$
 $\forall x, y. address(x, y) \rightarrow Location(x) \wedge String(y)$
 $\forall x, y. description(x, y) \rightarrow Location(x) \wedge Text(y)$
 $\forall x. Scene(x) \rightarrow (1 \leq \#\{y | code_{Scene}(x, y)\} \leq 1)$
 $\forall x. Internal(x) \rightarrow Scene(x)$
 $\forall x. External(x) \rightarrow Scene(x)$
 $\forall x. Internal(x) \rightarrow \neg External(x)$
 $\forall x. Scene(x) \rightarrow Internal(x) \vee External(x)$

$\forall x, y. stpForScn(x, y) \rightarrow$
 $\forall Setup(x) \wedge Scene(y)$
 $\forall x, y. tkOfStp(x, y) \rightarrow$
 $\forall Take(x) \wedge Setup(y)$
 $\forall x, y. located(x, y) \rightarrow$
 $\forall External(x) \wedge Location(y)$
 $\forall x. Setup(x) \rightarrow$
 $\forall (1 \leq \#\{y | stpForScn(x, y)\} \leq 1)$
 $\forall y. Scene(y) \rightarrow$
 $\forall (1 \leq \#\{x | stpForScn(x, y)\})$
 $\forall x. Take(x) \rightarrow$
 $\forall (1 \leq \#\{y | tkOfStp(x, y)\} \leq 1)$
 $\forall x. Setup(y) \rightarrow$
 $\forall (1 \leq \#\{x | stpForScn(x, y)\})$
 $\forall x. External(x) \rightarrow$
 $\forall (1 \leq \#\{y | located(x, y)\} \leq 1)$
...

The most interesting multiplicities are:

- 0..* : unconstrained
- 1..* : mandatory participation
- 0..1 : functional participation (the association is a partial function)
- 1..1 : mandatory and functional participation (the association is a total function)

Definition (In FOL)

- 0..* : no constraint
- 1..* : $\forall x \cdot C_1(x) \rightarrow \exists y \cdot A(x,y)$
- 0..1 : $\forall x \cdot C_1(x) \rightarrow \forall y, y' \cdot A(x,y) \wedge A(x,y') \rightarrow y = y'$
(or simply $\forall x, y, y' \cdot A(x,y) \wedge A(x,y') \rightarrow y = y'$)
- 1..1 : $(\forall x \cdot C_1(x) \rightarrow \exists y \cdot A(x,y)) \wedge (\forall x, y, y' \cdot A(x,y) \wedge A(x,y') \rightarrow y = y')$

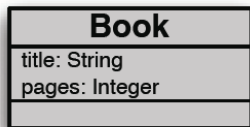
Definition (Attribute)

An **attribute** models a local property of a class.

It is characterized by:

- a **name** (which is unique only in the class it belongs to),
- a **type** (a collection of possible values),
- and possibly a **multiplicity**.

Example



- The name of one of the attributes is 'title'.
- Its type is 'String'.

Attributes (without explicit multiplicity) are:

- **mandatory** (must have at least a value), and
- **single-valued** (can have at most one value).

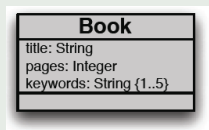
That is, they are **total functions** from the instances of the class to the values of the type they have.

Example

*book*₃ has as value for the attribute 'title' the String: "The little digital video book".

More generally attributes may have an explicit **multiplicity** (similar to that of associations).

Example



- The attribute 'title' has an implicit multiplicity of 1..1.
- The attribute 'keywords' has an explicit multiplicity of 1..5.

Note: When the multiplicity is not specified, then it is assumed to be 1..1

Since **attributes** may have a multiplicity different from 1..1, they are better formalized as **binary predicates**, with suitable **assertions** representing types and multiplicity.

Definition (Attribute representation)

Given an **attribute** att of a class C with type T and multiplicity $i..j$, we capture it in FOL as a **binary predicate** $att_C(x, y)$ with the following assertions:

- An assertion for the attribute **type**:

$$\forall x, y \cdot att_C(x, y) \rightarrow C(x) \wedge T(y)$$

- An assertion for the **multiplicity**:

$$\forall x \cdot C(x) \rightarrow (i \leq \#\{y | att_C(x, y)\} \leq j)$$

Example

| Book |
|-------------------------|
| title: String |
| pages: Integer |
| keywords: String {1..5} |
| |

$$\forall x, y \cdot title_B(x, y) \rightarrow Book(x) \wedge String(y)$$

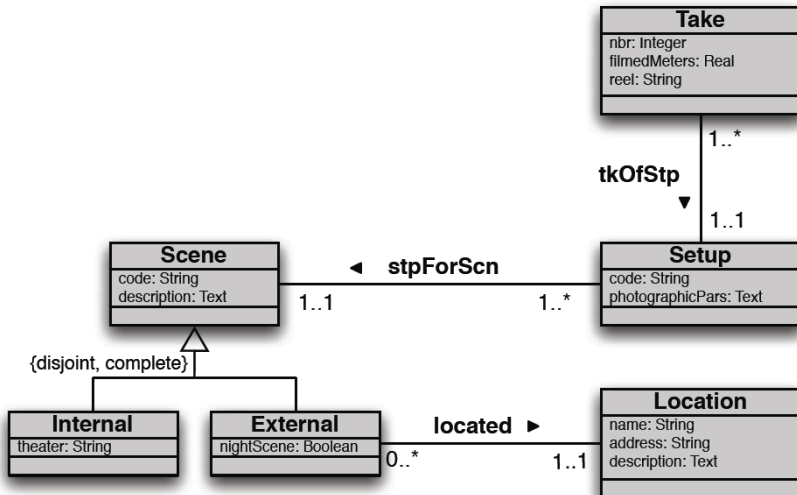
$$\forall Book(x) \rightarrow (1 \leq \#\{y | title_B(x, y)\} \leq 1)$$

$$\forall x, y \cdot pages_B(x, y) \rightarrow Book(x) \wedge Integer(y)$$

$$\forall Book(x) \rightarrow (1 \leq \#\{y | pages_B(x, y)\} \leq 1)$$

$$\forall x, y \cdot keywords_B(x, y) \rightarrow Book(x) \wedge String(y)$$

$$\forall Book(x) \rightarrow (1 \leq \#\{y | keywords_B(x, y)\} \leq 5)$$



In our Example

Alphabet

Scene(x), Setup(x), Take(x), Internal(x), External(x), Location(x), stpForScn(x, y), tkOfStp(x, y), located(x, y),...

Axioms

$\forall x, y. \text{code}_{Scene}(x, y) \rightarrow Scene(x) \wedge String(y)$
 $\forall x, y. \text{description}(x, y) \rightarrow Scene(x) \wedge Text(y)$
 $\forall x, y. \text{code}_{Setup}(x, y) \rightarrow Setup(x) \wedge String(y)$
 $\forall x, y. \text{photographicPars}(x, y) \rightarrow Setup(x) \wedge Text(y)$
 $\forall x, y. \text{nbr}(x, y) \rightarrow Take(x) \wedge Integer(y)$
 $\forall x, y. \text{filmedMeters}(x, y) \rightarrow Take(x) \wedge Real(y)$
 $\forall x, y. \text{reel}(x, y) \rightarrow Take(x) \wedge String(y)$
 $\forall x, y. \text{theater}(x, y) \rightarrow Internal(x) \wedge String(y)$
 $\forall x, y. \text{nightScene}(x, y) \rightarrow External(x) \wedge Boolean(y)$
 $\forall x, y. \text{name}(x, y) \rightarrow Location(x) \wedge String(y)$
 $\forall x, y. \text{address}(x, y) \rightarrow Location(x) \wedge String(y)$
 $\forall x, y. \text{description}(x, y) \rightarrow Location(x) \wedge Text(y)$
 $\forall x. Scene(x) \rightarrow (1 \leq \#\{y | \text{code}_{Scene}(x, y)\} \leq 1)$
 $\forall x. Internal(x) \rightarrow Scene(x)$
 $\forall x. External(x) \rightarrow Scene(x)$
 $\forall x. Internal(x) \rightarrow \neg External(x)$
 $\forall x. Scene(x) \rightarrow Internal(x) \vee External(x)$

$\forall x, y. \text{stpForScn}(x, y) \rightarrow$
 $\forall Setup(x) \wedge Scene(y)$
 $\forall x, y. \text{tkOfStp}(x, y) \rightarrow$
 $\forall Take(x) \wedge Setup(y)$
 $\forall x, y. \text{located}(x, y) \rightarrow$
 $\forall External(x) \wedge Location(y)$
 $\forall x. Setup(x) \rightarrow$
 $\forall (1 \leq \#\{y | \text{stpForScn}(x, y)\} \leq 1)$
 $\forall y. Scene(y) \rightarrow$
 $\forall (1 \leq \#\{x | \text{stpForScn}(x, y)\})$
 $\forall x. Take(x) \rightarrow$
 $\forall (1 \leq \#\{y | \text{tkOfStp}(x, y)\} \leq 1)$
 $\forall x. Setup(y) \rightarrow$
 $\forall (1 \leq \#\{x | \text{stpForScn}(x, y)\})$
 $\forall x. External(x) \rightarrow$
 $\forall (1 \leq \#\{y | \text{located}(x, y)\} \leq 1)$
...

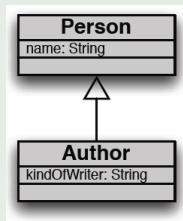
ISA and generalizations

The ISA relationship is of particular importance in conceptual modeling: a class C ISA a class C' if every instance of C is also an instance of C' .

Generalization

In UML, the **ISA relationship** is modeled through the notion of **generalization**.

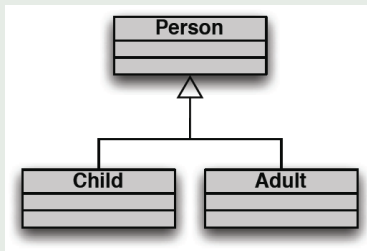
Example



The attribute 'name' is inherited by 'Author'.

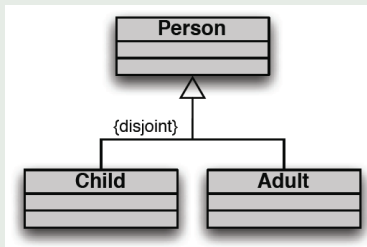
A **generalization** involves a **superclass** (base class) and one or more subclasses: every instance of each **subclass** is also an instance of the superclass.

Example



The ability of having more subclasses in the same generalization, allows for placing suitable **constraints** on the classes involved in the generalization.

Example

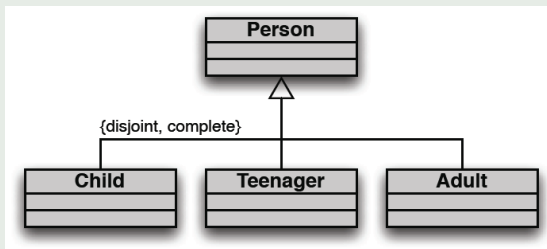


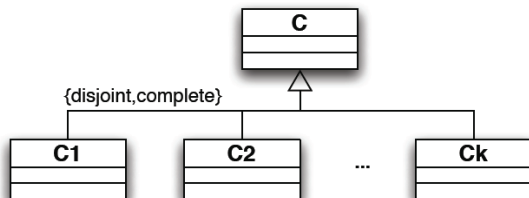
Generalizations with constraints (cont'd)

Most notable and used constraints:

- **Disjointness**, which asserts that different subclasses cannot have common instances (i.e., an object cannot be at the same time instance of two disjoint subclasses).
- **Completeness** (aka “covering”), which asserts that every instance of the superclass is also an instance of at least one of the subclasses.

Example

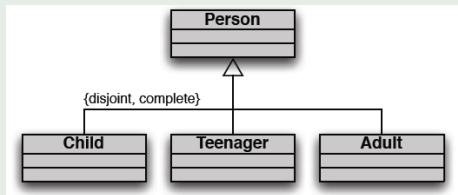




Definition (Generalization representation)

ISA: $\forall x. C_i(x) \rightarrow C(x),$ for $1 \leq i \leq k$
Disjointness: $\forall x. C_i(x) \rightarrow \neg C_j(x),$ for $1 \leq i < j \leq k$
Completeness: $\forall x. C(x) \rightarrow \bigvee_{i=1}^k C_i(x)$

Example



$$\forall x. \text{Child}(x) \rightarrow \text{Person}(x)$$

$$\forall x. \text{Teenager}(x) \rightarrow \text{Person}(x)$$

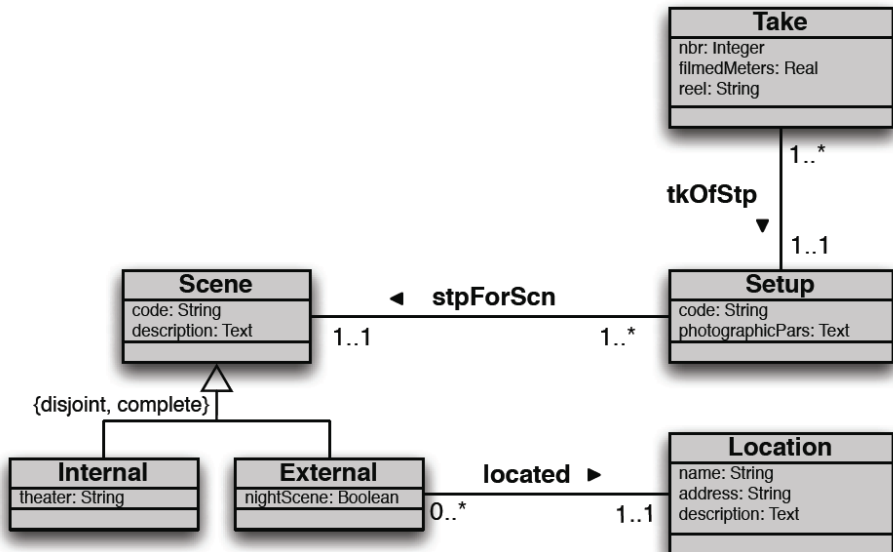
$$\forall x. \text{Adult}(x) \rightarrow \text{Person}(x)$$

$$\forall x. \text{Child}(x) \rightarrow \neg \text{Teenager}(x)$$

$$\forall x. \text{Child}(x) \rightarrow \neg \text{Adult}(x)$$

$$\forall x. \text{Teenager}(x) \rightarrow \neg \text{Adult}(x)$$

$$\forall x. \text{Person}(x) \rightarrow (\text{Child}(x) \vee \text{Teenager}(x) \vee \text{Adult}(x))$$



In our Example

Alphabet

$Scene(x)$, $Setup(x)$, $Take(x)$, $Internal(x)$, $External(x)$, $Location(x)$, $stpForScn(x, y)$, $tkOfStp(x, y)$, $located(x, y)$, ...

Axioms

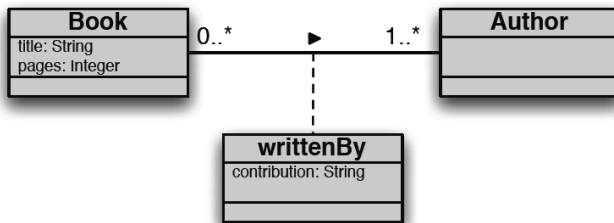
$\forall x, y. code_{Scene}(x, y) \rightarrow Scene(x) \wedge String(y)$
 $\forall x, y. description(x, y) \rightarrow Scene(x) \wedge Text(y)$
 $\forall x, y. code_{Setup}(x, y) \rightarrow Setup(x) \wedge String(y)$
 $\forall x, y. photographicPars(x, y) \rightarrow Setup(x) \wedge Text(y)$
 $\forall x, y. nbr(x, y) \rightarrow Take(x) \wedge Integer(y)$
 $\forall x, y. filmedMeters(x, y) \rightarrow Take(x) \wedge Real(y)$
 $\forall x, y. reel(x, y) \rightarrow Take(x) \wedge String(y)$
 $\forall x, y. theater(x, y) \rightarrow Internal(x) \wedge String(y)$
 $\forall x, y. nightScene(x, y) \rightarrow External(x) \wedge Boolean(y)$
 $\forall x, y. name(x, y) \rightarrow Location(x) \wedge String(y)$
 $\forall x, y. address(x, y) \rightarrow Location(x) \wedge String(y)$
 $\forall x, y. description(x, y) \rightarrow Location(x) \wedge Text(y)$
 $\forall x. Scene(x) \rightarrow (1 \leq \#\{y | code_{Scene}(x, y)\} \leq 1)$
 $\forall x. Internal(x) \rightarrow Scene(x)$
 $\forall x. External(x) \rightarrow Scene(x)$
 $\forall x. Internal(x) \rightarrow \neg External(x)$
 $\forall x. Scene(x) \rightarrow Internal(x) \vee External(x)$

$\forall x, y. stpForScn(x, y) \rightarrow$
 $\forall Setup(x) \wedge Scene(y)$
 $\forall x, y. tkOfStp(x, y) \rightarrow$
 $\forall Take(x) \wedge Setup(y)$
 $\forall x, y. located(x, y) \rightarrow$
 $\forall External(x) \wedge Location(y)$
 $\forall x. Setup(x) \rightarrow$
 $\forall (1 \leq \#\{y | stpForScn(x, y)\} \leq 1)$
 $\forall y. Scene(y) \rightarrow$
 $\forall (1 \leq \#\{x | stpForScn(x, y)\})$
 $\forall x. Take(x) \rightarrow$
 $\forall (1 \leq \#\{y | tkOfStp(x, y)\} \leq 1)$
 $\forall x. Setup(y) \rightarrow$
 $\forall (1 \leq \#\{x | stpForScn(x, y)\})$
 $\forall x. External(x) \rightarrow$
 $\forall (1 \leq \#\{y | located(x, y)\} \leq 1)$
...

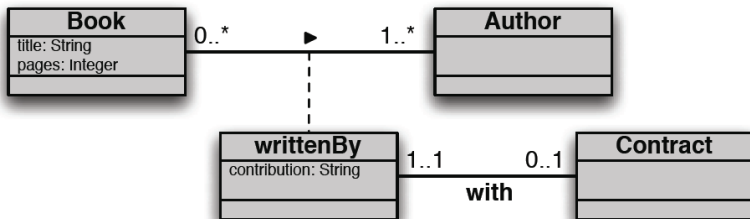
Sometimes we may want to assert properties of associations. In UML to do so we resort to **association classes**:

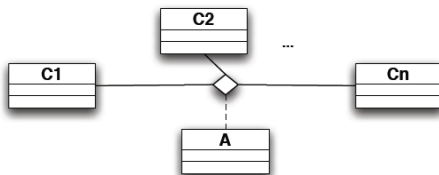
- That is, we associate to an association a class whose instances are in **bijection** with the tuples of the association.
- Then we use the association class exactly as a UML class (modeling local and non-local properties).

Association class - Example



Association class - Example (cont'd)





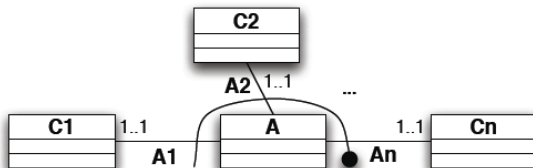
Definition (Reification)

The process of putting in correspondence objects of a class (the association class) with tuples in an association is formally described as **reification**.

That is:

- We introduce a unary predicate A for the association class A .
- We introduce n new binary predicates A_1, \dots, A_n , one for each of the components of the association.
- We introduce suitable assertions so that objects in the extension of the unary-predicate A are in bijection with tuples in the n -ary association A .

Association classes: formalization (cont'd)



Definition

Association Class Representation FOL Assertions are needed for stating a bijection between instances of the association class and instances of the association:

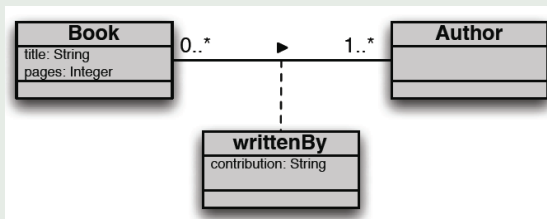
$$\forall x, y. A_i(x, y) \rightarrow A(x) \wedge C_i(y), \quad \text{for } i \in \{1, \dots, n\}$$

$$\forall x. A(x) \rightarrow \exists y. A_i(x, y), \quad \text{for } i \in \{1, \dots, n\}$$

$$\forall x, y, y'. A_i(x, y) \wedge A_i(x, y') \rightarrow y = y', \quad \text{for } i \in \{1, \dots, n\}$$

$$\forall x, x', y_1, \dots, y_n. \bigwedge_{i=1}^n (A_i(x, y_i) \wedge A_i(x', y_i)) \rightarrow x = x'$$

Example



$$\forall x, y. wb_1(x, y) \rightarrow writtenBy(x) \wedge Book(y)$$

$$\forall x, y. wb_2(x, y) \rightarrow writtenBy(x) \wedge Author(y)$$

$$\forall x. writtenBy(x) \rightarrow \exists y. wb_1(x, y)$$

$$\forall x. writtenBy(x) \rightarrow \exists y. wb_2(x, y)$$

$$\forall x, y, y'. wb_1(x, y) \wedge wb_1(x, y') \rightarrow y = y'$$

$$\forall x, y, y'. wb_2(x, y) \wedge wb_2(x, y') \rightarrow y = y'$$

$$\forall x, x', y_1, y_2. wb_1(x, y_1) \wedge wb_1(x', y_1) \wedge wb_2(x, y_2) \wedge wb_2(x', y_2) \rightarrow x = x'$$

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Definition (Class Consistency)

A class is **consistent**, if the class diagram admits an instantiation in which the class has a non-empty set of instances.

Theorem

Let Γ be the set of FOL assertions corresponding to the UML Class Diagram, and $C(x)$ the predicate corresponding to a class C of the diagram.

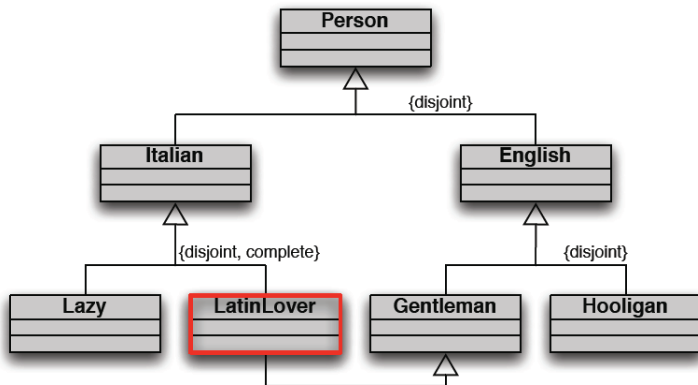
Then C is **consistent** iff

$$\Gamma \not\models \forall x.C(x) \rightarrow false$$

i.e., there exists a model of Γ in which the extension of $C(x)$ is not the empty set.

Note: Corresponding FOL reasoning task: **satisfiability**.

Class consistency: example (by E. Franconi)



$$\Gamma \models \forall x. \text{LatinLover}(x) \rightarrow \text{false}$$

Definition (Class Diagram Consistency)

A class diagram is **consistent**, if it admits an instantiation, i.e., if its classes can be populated without violating any of the conditions imposed by the diagram.

Theorem

Let Γ be the set of FOL assertions corresponding to the UML Class Diagram.
Then, **the diagram is consistent** iff

Γ is satisfiable

i.e., Γ admits at least one model. (Remember that FOL models cannot be empty.)

Note: Corresponding FOL reasoning task: **satisfiability**.

Definition (Class Subsumption)

A class C_1 **is subsumed by** a class C_2 (or C_2 subsumes C_1), if the class diagram implies that C_2 is a generalization of C_1 .

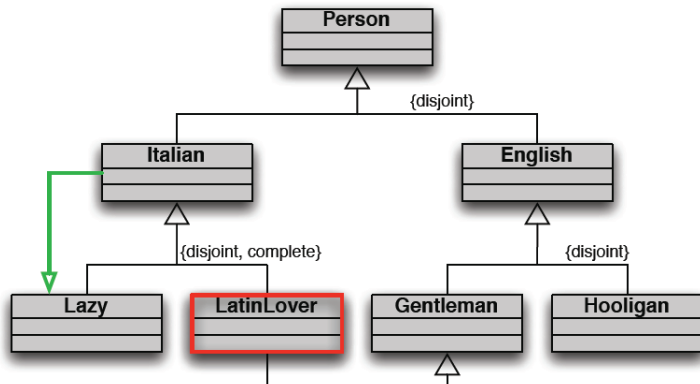
Theorem

Let Γ be the set of FOL assertions corresponding to the UML Class Diagram, and $C_1(x)$, $C_2(x)$ the predicates corresponding to the classes C_1 , and C_2 of the diagram.
Then C_1 **is subsumed by** C_2 iff

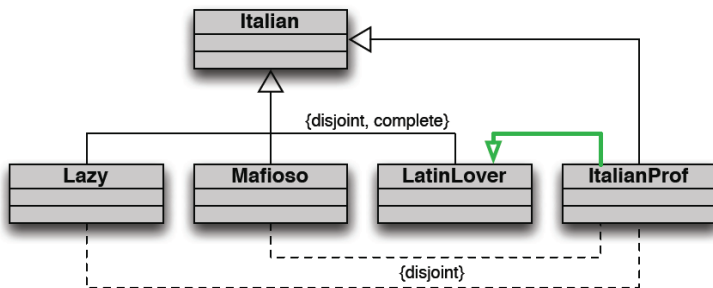
$$\Gamma \models \forall x. C_1(x) \rightarrow C_2(x)$$

Note: Corresponding FOL reasoning task: **logical implication**.

Class subsumption: example


$$\Gamma \models \forall x. \text{Latin Lover}(x) \rightarrow \text{false}$$
$$\Gamma \models \forall x. \text{Italian}(x) \rightarrow \text{Lazy}(x)$$

Class subsumption: another example (by E. Franconi)



$$\Gamma \models \forall x. \text{ItalianProf}(x) \rightarrow \text{LatinLover}(x)$$

Note: this is an example of reasoning by cases.

Definition (Class Equivalence)

Two classes C_1 and C_2 are **equivalent**, if C_1 and C_2 denote the same set of instances in all instantiations of the class diagram.

Theorem

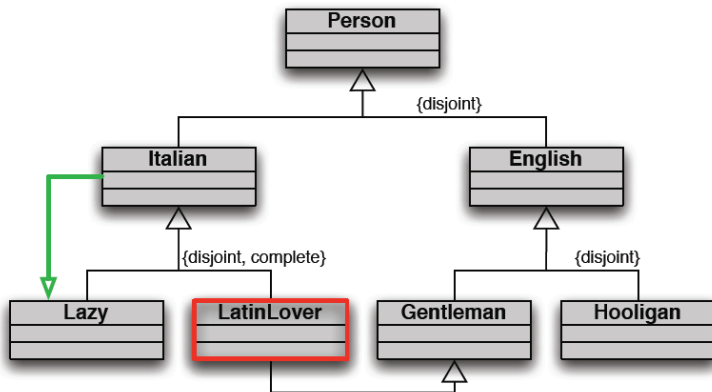
Let Γ be the set of FOL assertions corresponding to the UML Class Diagram, and $C_1(x), C_2(x)$ the predicates corresponding to the classes C_1 , and C_2 of the diagram. Then **C_1 and C_2 are equivalent** iff

$$\Gamma \models \forall x. C_1(x) \leftrightarrow C_2(x)$$

Note:

- If two classes are equivalent then one of them is redundant.
- Determining equivalence of two classes allows for their merging, thus reducing the complexity of the diagram.

Class equivalence: example



$\Gamma \models \forall x. ItalianLover(x) \rightarrow false$

$\Gamma \models \forall x. Italian(x) \rightarrow Lazy(x)$

$\Gamma \models \forall x. Lazy(x) \equiv Italian(x)$

Forms of reasoning: implicit consequence

The properties of various classes and associations may interact to yield stricter multiplicities or typing than those explicitly specified in the diagram.

More generally...

Definition (Implicit Consequence)

A property \mathcal{P} is an **(implicit) consequence** of a class diagram if \mathcal{P} holds whenever all conditions imposed by the diagram are satisfied.

Theorem

Let Γ be the set of FOL assertion corresponding to the UML Class Diagram, and \mathcal{P} (the formalization in FOL of) the property of interest

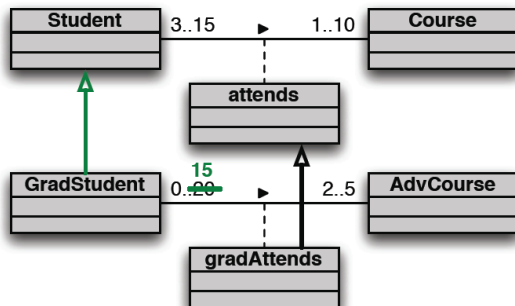
Then **\mathcal{P} is an implicit consequence** iff

$$\Gamma \models \mathcal{P}$$

i.e., the property \mathcal{P} holds in every model of Γ .

Note: Corresponding FOL reasoning task: **logical implication**.

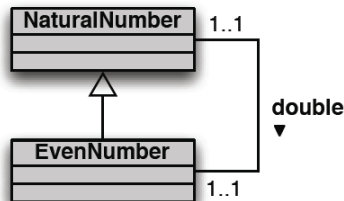
Implicit consequences: example



$\Gamma \models \forall x. AdvCourse(x_2) \rightarrow \#\{x_1 | gradAttends(x_1, x_2)\} \leq 15$

$\Gamma \models \forall x. GradStudent(x) \rightarrow Student(x)$

$\Gamma \not\models \forall x. AdvCourse(x) \rightarrow Course(x)$



- Due to the multiplicities, the classes *NaturalNumber* and *EvenNumber* are in bijection.
As a consequence, in every instantiation of the diagram, “the classes *NaturalNumber* and *EvenNumber* contain the same number of objects”.
- Due to the ISA relationship, every instance of *EvenNumber* is also an instance of *NaturalNumber*, i.e., we have that

$$\Gamma \models \forall x. \text{EvenNumber}(x) \rightarrow \text{NaturalNumber}(x)$$

Question: Does also the reverse implication hold, i.e.,

$$\Gamma \models \forall x. \text{NaturalNumber}(x) \rightarrow \text{EvenNumber}(x) \quad ?$$

- if the domain is **infinite**, the implication **does not hold**.
- If the domain is **finite**, the implication **does hold**.

Finite model reasoning: means reasoning only with respect to models with a finite domain.

- Finite model reasoning is interesting for standard databases.
- The previous example shows that in UML Class Diagrams, finite model reasoning is **different** from unrestricted model reasoning.

In the above examples reasoning could be easily carried out on intuitive grounds. However, two questions come up.

1. Can we develop sound, complete, and terminating procedures for reasoning on UML Class Diagrams?

- We cannot do so by directly relying on FOL!
- But we can use specialized logics with better computational properties. A form of such specialized logics are **Description Logics**.

2. How hard is it to reason on UML Class Diagrams in general?

- What is the worst-case situation?
- Can we single out **interesting fragments** on which to reason efficiently?

Note: all what we have said holds for Entity-Relationship Diagrams as well

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[J.E. Hopcroft, 2007; Papadimitriou, 1994]

Computational complexity theory aims at understanding how difficult it is to solve specific problems.

- A **problem** is considered as an (in general infinite) set of instances of the problem, each encoded in some meaningful (i.e., compact) way.
- Standard complexity theory deals with **decision problems**: i.e., problems that admit a yes/no answer.
- **Algorithm** that solves a decision problem:
 - input: an instance of the problem
 - output: yes or no
- The difficulty (complexity) is measured in terms of the amount of **resources** (time, space) that the algorithm needs to solve the problem.
~> complexity of the algorithm, or **upper bound**
- To measure the complexity of the problem, we consider the best possible algorithm that solves it.
~> **lower bound**

- **Worst-case** complexity analysis: the complexity is measured in terms of a (complexity) function f :
 - argument: the size n of an instance of the problem (i.e., the length of its encoding)
 - result: the amount $f(n)$ of time/space needed in the worst-case to solve an instance of size n
- The **asymptotic behaviour** of the complexity function when n grows is considered.
- To abstract away from contingent issues (e.g., programming language, processor speed, etc.), we refer to an abstract computing model: **Turing Machines** (TMs).

To achieve robustness wrt encoding issues, usually one does not consider specific complexity functions f , but rather families \mathcal{C} of complexity functions, giving rise to complexity classes.

Definition (Time/space complexity class \mathcal{C})

A time/space complexity class \mathcal{C} is the set of all problems P such that an instance of P of size n can be solved in time/space at most $C(n)$.

Note: Consider a (decision) problem P , and an encoding of the instances of P into strings over some alphabet Σ .

Once we fix such an encoding, the problem actually corresponds to a language L_P , namely the set of strings encoding those instances of the problem for which the answer is yes.

Hence, in the technical sense, a complexity class is actually a set of languages.

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To establish lower bounds on the complexity of problems, we make use of the notion of reduction:

Definition (Reduction)

A **reduction** from a problem P_1 to a problem P_2 is a function R (the reduction) from instance of P_1 to instances of P_2 such that:

- 1 R is efficiently computable (i.e., in logarithmic space), and
- 2 An instance I of P_1 has answer yes iff $R(I)$ has answer yes.

P_1 **reduces** to P_2 if there is a reduction R from P_1 to P_2 .

Intuition: If P_1 reduces to P_2 , then P_2 is at least as difficult as P_1 , since we can solve an instance I of P_1 by reducing it to the instance $R(I)$ of P_2 and then solve $R(I)$.

Definition (Hardness)

A problem P is **hard** for a complexity class \mathcal{C} if every problem in \mathcal{C} can be reduced to P .

Definition (Completeness)

A problem P is **complete** for a complexity class \mathcal{C} if

- 1 it is hard for \mathcal{C} , and
- 2 it belongs to \mathcal{C}

Intuitively, a problem that is complete for \mathcal{C} is among the hardest problems in \mathcal{C} .

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Tractability and intractability: PTime and NP

Definition (PTime)

Set of problems solvable in polynomial time by a deterministic TM.

- These problems are considered **tractable**, i.e., solvable for large inputs.
- Is a robust class (PTime computations compose).

Definition (NP)

Set of problems solvable in polynomial time by a non-deterministic TM.

- These problems are believed **intractable**, i.e., unsolvable for large inputs.
- The best known algorithms actually require exponential time.
- Corresponds to a large class of practical problems, for which the following type of algorithm can be used:
 - 1 Non-deterministically guess a possible solution of polynomial size.
 - 2 Check in polynomial time that the guessed solutions is good.

Complexity classes above NP

Definition (PSpace)

Set of problems solvable in **polynomial space** by a deterministic TM.

- Polynomial space is “not really good”, since these problems may require exponential time.
- These problems are considered to be more difficult than NP problems.
- Practical algorithms and heuristics work less well than for NP problems.

Definition (ExpTime)

Set of problems solvable in **exponential time by a deterministic TM**.

- This is the first provably intractable complexity class.
- These problems are considered to be very difficult.

Definition (NExpTime)

Set of problems solvable in **exponential time by a non-deterministic TM**.

Definition (LogSpace and NLogSpace)

Set of problems solvable in **logarithmic space by a (non-)deterministic TM.**

- Note: when measuring the space complexity, the size of the input does not count, and only the working memory (TM tape) is considered.
- Note 2: logarithmic space computations compose (this is not trivial).
- Correspond to reachability in undirected and directed graphs, respectively.

Definition (AC^0)

Set of problems solvable in **constant time using a polynomial number of processors.**

- These problems are solvable efficiently even for very large inputs.
- Corresponds to the complexity of model checking a fixed FO formula when the input is the model only.

The following relationships are known:

$$\begin{aligned} AC^0 \subsetneq LogSpace \subseteq NLogSpace \subseteq PTime \subseteq \\ \subseteq NP \subseteq PSpace \subseteq \\ \subseteq ExpTime \subseteq NExpTime \end{aligned}$$

Moreover, we know that:

$$PTime \subsetneq ExpTime$$

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What are Description Logics?

Description Logics (DLs) [Baader et al., 2003] are **logics** specifically designed to represent and reason on structured knowledge.

The domain of interest is composed of **objects** and is structured into:

- **concepts**, which correspond to classes, and denote sets of objects
- **roles**, which correspond to (binary) relationships, and denote binary relations on objects

The knowledge is asserted through so-called **assertions**, i.e., logical axioms.

Description Logics stem from early days knowledge representation formalisms (late '70s, early '80s):

- Semantic Networks: graph-based formalism, used to represent the meaning of sentences.
- Frame Systems: frames used to represent prototypical situations, antecedents of object-oriented formalisms.

Problems: **no clear semantics**, reasoning not well understood.

Description Logics (a.k.a. Concept Languages, Terminological Languages) developed starting in the mid '80s, with the aim of providing semantics and inference techniques to knowledge representation systems.

What are Description Logics about?

Abstractly, DLs allow one to predicate about **labeled directed graphs**:

- Vertexes represents real world objects.
- Vertexes's labels represents qualities of objects.
- Edges represents relations between (pairs of) objects.
- Edges' labels represents the types of relations between objects.

Every fragment of the world that can be abstractly represented in terms of a labeled directed graph is a good candidate for being represented by DLs.

What are Description Logics about? - Example 1



Exercise

Represent Metro lines in Milan in a labelled directed graph.

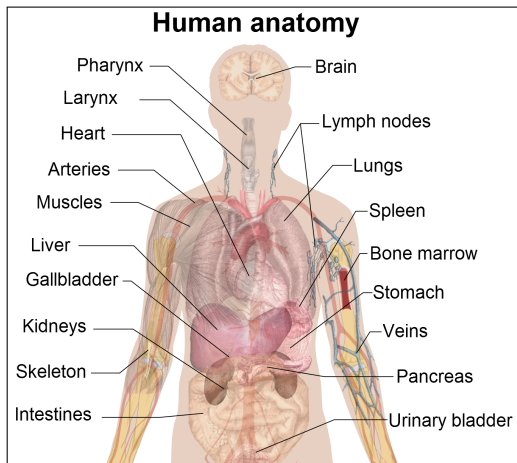
What are Description Logics about? - Example 2



Exercise

Represent some aspects of Facebook as a labelled directed graph.

What are Description Logics about? - Example 3



Exercise

Represent some aspects of human anatomy as a labelled directed graph.

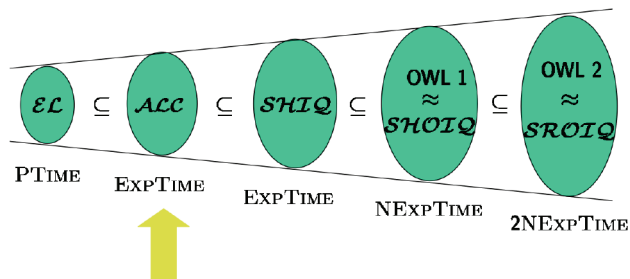
What are Description Logics about? - Example 4



Exercise

Represent some aspects of document classification as a labelled directed graph.

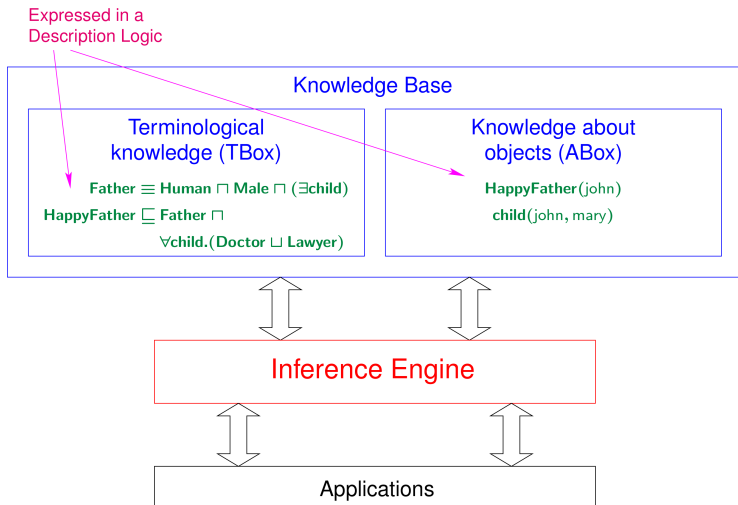
Many description logics



A **DL** is characterized by:

- 1 A **description language**: how to form concepts and roles
 $Human \sqcap Male \sqcap \exists hasChild \sqcap \forall hasChild.(Doctor \sqcup Lawyer)$
- 2 A mechanism to **specify knowledge** about concepts and roles (i.e., a **TBox**)
 $\mathcal{T} = \{Father \equiv Human \sqcap Male \sqcap \exists hasChild, \\ HappyFather \sqsubseteq Father \sqcap \forall hasChild.(Doctor \sqcup Lawyer)\}$
- 3 A mechanism to specify **properties of objects** (i.e., an **ABox**)
 $\mathcal{A} = \{HappyFather(john), hasChild(john, mary)\}$
- 4 A set of **inference services**: how to reason on a given KB
 $\mathcal{T} \models HappyFather \sqsubseteq \exists hasChild.(Doctor \sqcup Lawyer)$
 $\mathcal{T} \cup \mathcal{A} \models (Doctor \sqcup Lawyer)(mary)$

Architecture of a Description Logic system



A description language provides the means for defining:

- **concepts**, corresponding to classes: interpreted as sets of objects;
- **roles**, corresponding to relationships: interpreted as binary relations on objects.

To define concepts and roles:

- We start from a (finite) alphabet of **atomic concepts** and **atomic roles**, i.e., simply names for concept and roles.
- Then, by applying specific constructors, we can build **complex concepts** and **roles**, starting from the atomic ones.

A **description language** is characterized by the set of constructs that are available for that.

The **formal semantics** of DLs is given in terms of interpretations.

Definition (Interpretation)

An **interpretation** $\mathcal{I} = (\Delta^{\mathcal{I}}, \cdot^{\mathcal{I}})$ consists of:

- a nonempty set $\Delta^{\mathcal{I}}$, called the **interpretation domain** (of \mathcal{I})
- an **interpretation function** $\cdot^{\mathcal{I}}$, which maps
 - each atomic concept A to a subset $A^{\mathcal{I}}$ of $\Delta^{\mathcal{I}}$
 - each atomic role P to a subset $P^{\mathcal{I}}$ of $\Delta^{\mathcal{I}} \times \Delta^{\mathcal{I}}$

The interpretation function is extended to complex concepts and roles according to their syntactic structure.

| Construct | Syntax | Example | Semantics |
|-----------------------|---------------|-------------------------|--|
| atomic concept | A | $Doctor$ | $A^I \subseteq \Delta^I$ |
| atomic role | P | $hasChild$ | $P^I \subseteq \Delta^I \times \Delta^I$ |
| atomic negation | $\neg A$ | $\neg Doctor$ | $\Delta^I \setminus A^I$ |
| conjunction | $C \sqcap D$ | $Hum \sqcap Male$ | $C^I \cap D^I$ |
| (unqual.) exist. res. | $\exists R$ | $\exists hasChild$ | $\{o \mid \exists o'. (o.o') \in R^I\}$ |
| value restriction | $\forall R.C$ | $\forall hasChild.Male$ | $\{o \mid \forall o'. (o.o') \in R^I \rightarrow o' \in C^I\}$ |
| bottom | \perp | | \emptyset |

(C , D denote arbitrary concepts and R an arbitrary role)

The above constructs form the basic language \mathcal{AL} of the family of \mathcal{AL} languages.

| Construct | \mathcal{AL} | Syntax | Semantics |
|--------------------------|----------------|---------------|---|
| disjunction | \mathcal{U} | $C \sqcup D$ | $C^{\mathcal{I}} \cup D^{\mathcal{I}}$ |
| top | | \top | $\Delta^{\mathcal{I}}$ |
| qual. exist. res. | \mathcal{E} | $\exists R.C$ | $\{o \mid \exists o'. (o, o') \in R^{\mathcal{I}} \wedge o' \in C^{\mathcal{I}}\}$ |
| (full) negation | \mathcal{C} | $\neg C$ | $\Delta^{\mathcal{I}} \setminus C^{\mathcal{I}}$ |
| number restriction | \mathcal{N} | $(\geq kR)$ | $\{o \mid \#\{o' \mid (o, o') \in R^{\mathcal{I}}\} \geq k\}$ |
| | | $(\leq kR)$ | $\{o \mid \#\{o' \mid (o, o') \in R^{\mathcal{I}}\} \leq k\}$ |
| qual. number restriction | \mathcal{Q} | $(\geq kR.C)$ | $\{o \mid \#\{o' \mid (o, o') \in R^{\mathcal{I}} \wedge o' \in C^{\mathcal{I}}\} \geq k\}$ |
| | | $(\leq kR.C)$ | $\{o \mid \#\{o' \mid (o, o') \in R^{\mathcal{I}} \wedge o' \in C^{\mathcal{I}}\} \leq k\}$ |
| inverse role | \mathcal{I} | R^{-} | $\{(o, o') \mid (o', o) \in R^{\mathcal{I}}\}$ |
| role closure | reg | R^{*} | $(R^{\mathcal{I}})^{*}$ |

Note: Many different DL constructs and their combinations have been investigated.

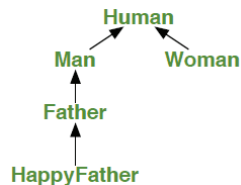
- Disjunction: $\forall hasChild.(Doctor \sqcup Lawyer)$
- Qualified existential restriction: $\exists hasChild.Doctor$
- Full negation: $\neg(Doctor \sqcup Lawyer)$
- Number restrictions: $(\geq 2 hasChild) \sqcup (\leq 1 sibling)$
- Qualified number restrictions: $(\geq 2 hasChild.Doctor)$
- Inverse role: $\forall hasChild^{-}.Doctor$
- Reflexive-transitive role closure: $\exists hasChild^{*}.Doctor$

An interpretation \mathcal{I} is a **model** of a concept C if $C^{\mathcal{I}} \neq \emptyset$.

Basic reasoning tasks

- 1 **Concept satisfiability**: does C admit a model?
- 2 **Concept subsumption** $C \sqsubseteq D$: does $C^{\mathcal{I}} \subseteq D^{\mathcal{I}}$ hold for all interpretations \mathcal{I}

Subsumption is used to build the concept hierarchy:



Exercise

Show that if DL is propositionally closed then (1) and (2) are mutually reducible.

Complexity of concept satisfiability [Donini et al., 1997]

| | |
|--|-----------------|
| $\mathcal{AL}, \mathcal{ALN}$ | PTime |
| $\mathcal{ALU}, \mathcal{ALUN}$ | NP-complete |
| \mathcal{ALE} | coNP-complete |
| $\mathcal{ALC}, \mathcal{ALCN}, \mathcal{ALCI}, \mathcal{ALCQI}$ | PSpace-complete |

- Two sources of complexity:
 - union (\mathcal{U}) of type NP,
 - existential quantification (\mathcal{E}) of type coNP.
- When they are combined, the complexity jumps to PSpace.
- Number restrictions (\mathcal{N}) do not add to the complexity.

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We have seen how to build complex **concept and roles expressions**, which allow one to denote classes with a complex structure.

However, in order to represent real world domains, one needs the ability to **assert properties** of classes and relationships between them (e.g., as done in UML class diagrams).

The assertion of properties is done in DLs by means of an **ontology** (or knowledge base).

Definition (Description Logics ontology (or knowledge base))

A Description Logics ontology (or knowledge base) is a pair $\mathcal{O} = \langle \mathcal{T}, \mathcal{A} \rangle$, where \mathcal{T} is a TBox and \mathcal{A} is an ABox.

Definition (Description Logics TBox)

A Description Logic TBox consists of a set of assertions on concepts and roles:

- Inclusion assertions on concepts: $C_1 \sqsubseteq C_2$
- Inclusion assertions on roles: $R_1 \sqsubseteq R_2$
- Property assertions on (atomic) roles:
 - (transitive P) (symmetric P) (domain P C)
 - (functional P) (reflexive P) (range P C)...

Definition (Description Logics ABox)

A Description Logics ABox consists of a set of assertions on individuals: (we use c_i to denote individuals)

- Membership assertions for concepts: $A(c)$
- Membership assertions for roles: $P(c_1, c_2)$
- Equality and distinctness assertions: $c_1 \approx c_2, \quad c_1 \not\approx c_2$

Note: We use $C_1 \equiv C_2$ as an abbreviation for $C_1 \sqsubseteq C_2$, $C_2 \sqsubseteq C_1$.

Example (TBox assertions)

- Inclusion assertions on concepts:

$$\begin{aligned} \textit{Father} &\equiv \textit{Human} \sqcap \textit{Male} \sqcap \exists \textit{hasChild} \\ \textit{HappyFather} &\sqsubseteq \textit{Father} \sqcap \forall \textit{hasChild}.(\textit{Doctor} \sqcup \textit{Lawyer} \sqcup \textit{HappyPerson}) \\ \textit{HappyAnc} &\sqsubseteq \forall \textit{descendant}.\textit{HappyFather} \\ \textit{Teacher} &\sqsubseteq \neg \textit{Doctor} \sqcap \neg \textit{Lawyer} \end{aligned}$$

- Inclusion assertions on roles:

$$\textit{hasChild} \sqsubseteq \textit{descendant} \qquad \textit{hasFather} \sqsubseteq \textit{hasChild}^{-}$$

- Property assertions on roles:

(**transitive** descendant),(**reflexive** descendant),(**functional** hasFather)

Example (ABox membership assertions)

- $\textit{Teacher}(\textit{mary})$, $\textit{hasFather}(\textit{mary}; \textit{john})$, $\textit{HappyAnc}(\textit{john})$

Semantics of a Description Logics ontology

The semantics is given by specifying when an interpretation \mathcal{I} **satisfies** an assertion α , denoted $\mathcal{I} \models \alpha$

Definition (Satisfiability of TBox Assertions)

- $\mathcal{I} \models C_1 \sqsubseteq C_2$ if $C_1^{\mathcal{I}} \subseteq C_2^{\mathcal{I}}$
- $\mathcal{I} \models R_1 \sqsubseteq R_2$ if $R_1^{\mathcal{I}} \subseteq R_2^{\mathcal{I}}$
- $\mathcal{I} \models (\text{prop } P)$ if $P^{\mathcal{I}}$ is a relation that has the property **prop**.

(Note: domain and range assertions can be expressed by means of concept inclusion assertions.)

Definition (Satisfiability of ABox Assertions)

We need first to extend the interpretation function $\cdot^{\mathcal{I}}$, so that it maps each individual c to an element $c^{\mathcal{I}}$ of $\Delta^{\mathcal{I}}$.

- $\mathcal{I} \models A(c)$ if $c^{\mathcal{I}} \in A^{\mathcal{I}}$.
- $\mathcal{I} \models P(c_1, c_2)$ if $(c_1^{\mathcal{I}}, c_2^{\mathcal{I}}) \in P^{\mathcal{I}}$
- $\mathcal{I} \models c_1 \approx c_2$ if $c_1^{\mathcal{I}} = c_2^{\mathcal{I}}$
- $\mathcal{I} \models c_1 \not\approx c_2$ if $c_1^{\mathcal{I}} \neq c_2^{\mathcal{I}}$

Definition (Model)

An interpretation \mathcal{I} is a **model** of:

- an assertion α , if it satisfies α .
- a TBox \mathcal{T} , if it satisfies all assertions in \mathcal{T} .
- an ABox \mathcal{A} , if it satisfies all assertions in \mathcal{A} .
- an ontology $\mathcal{O} = \langle \mathcal{T}, \mathcal{A} \rangle$ if it is a model of both \mathcal{T} and \mathcal{A} .

Note: We use $\mathcal{I} \models \beta$ to denote that interpretation \mathcal{I} is a **model** of β (where β stands for an assertion, TBox, ABox, or ontology).

We may make some assumptions on how individuals are interpreted.

Definition (Unique name assumption (UNA))

When c_1 and c_2 are two individuals such that $c_1 \neq c_2$, then $c_1^{\mathcal{I}} \neq c_2^{\mathcal{I}}$.

Note: When the UNA holds, equality and distinctness assertions are meaningless.

Definition (Standard name assumption (SNA))

The UNA holds, and moreover individuals are interpreted in the same way in all interpretations.

Hence, we may assume that $\Delta^{\mathcal{I}}$ contains the set of individuals, and that for each interpretation \mathcal{I} , we have that $c^{\mathcal{I}} = c$ (then, c is called a **standard name**).

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The fundamental reasoning service from which all other ones can be easily derived is ...

Definition (Logical implication)

An ontology \mathcal{O} **logically implies** an assertion α , written $\mathcal{O} \models \alpha$ if α is satisfied by all models of \mathcal{O} .

We can provide an analogous definition for a TBox \mathcal{T} instead of an ontology \mathcal{O} .

- **TBox Satisfiability:** \mathcal{T} is satisfiable, if it admits at least one model.
- **Concept Satisfiability:** C is satisfiable wrt \mathcal{T} , if there is a model \mathcal{I} of \mathcal{T} such that $C^{\mathcal{I}}$ is not empty, i.e., $\mathcal{T} \models C \sqsubseteq \perp$
- **Subsumption:** C_1 is subsumed by C_2 wrt \mathcal{T} , if for every model \mathcal{I} of \mathcal{T} we have $C_1^{\mathcal{I}} \subseteq C_2^{\mathcal{I}}$, i.e., $\mathcal{T} \models C_1 \sqsubseteq C_2$
- **Equivalence:** C_1 and C_2 are equivalent wrt \mathcal{T} if for every model \mathcal{I} of \mathcal{T} we have $C_1^{\mathcal{I}} = C_2^{\mathcal{I}}$, i.e., $\mathcal{T} \models C_1 \equiv C_2$
- **Disjointness:** C_1 and C_2 are disjoint wrt \mathcal{T} if for every model \mathcal{I} of \mathcal{T} we have $C_1^{\mathcal{I}} \cap C_2^{\mathcal{I}} = \emptyset$, i.e., $\mathcal{T} \models C_1 \sqcap C_2 \sqsubseteq \perp$
- **Functionality implication:** A functionality assertion (**funct** R) is logically implied by \mathcal{T} if for every model \mathcal{I} of \mathcal{T} , we have that $(o, o_1) \in R^{\mathcal{I}}$ and $(o, o_2) \in R^{\mathcal{I}}$ implies $o_1 = o_2$, i.e., $\mathcal{T} \models (\text{funct } R)$

Note: Analogous definitions hold for role satisfiability, subsumption, equivalence, and disjointness.

- **Ontology Satisfiability:** Verify whether an ontology \mathcal{O} is satisfiable, i.e., whether \mathcal{O} admits at least one model.
- **Concept Instance Checking:** Verify whether an individual c is an instance of a concept C in every model of \mathcal{O} , i.e., whether $\mathcal{O} \models C(c)$.
- **Role Instance Checking:** Verify whether a pair (c_1, c_2) of individuals is an instance of a role R in every model of \mathcal{O} , i.e., whether $\mathcal{O} \models R(c_1, c_2)$.

Example (TBox)

- Inclusion assertions on concepts:

$$\begin{aligned} \textit{Father} &\equiv \textit{Human} \sqcap \textit{Male} \sqcap \exists \textit{hasChild} \\ \textit{HappyFather} &\sqsubseteq \textit{Father} \sqcap \forall \textit{hasChild}.(\textit{Doctor} \sqcup \textit{Lawyer} \sqcup \textit{HappyPerson}) \\ \textit{HappyAnc} &\sqsubseteq \forall \textit{descendant}.\textit{HappyFather} \\ \textit{Teacher} &\sqsubseteq \neg \textit{Doctor} \sqcap \neg \textit{Lawyer} \end{aligned}$$

- Inclusion assertions on roles:

$$\textit{hasChild} \sqsubseteq \textit{descendant} \qquad \textit{hasFather} \sqsubseteq \textit{hasChild}^{-}$$

- Property assertions on roles:

$$(\textbf{transitive} \textit{descendant}), \quad (\textbf{reflexive} \textit{descendant}), \quad (\textbf{functional} \textit{hasFather})$$

The above TBox logically implies: $\textit{HappyAncestor} \sqsubseteq \textit{Father}$.

Example (ABox)

- Membership assertions:

$$\textit{Teacher}(\textit{mary}), \quad \textit{hasFather}(\textit{mary}; \textit{john}), \quad \textit{HappyAnc}(\textit{john})$$

The above TBox and ABox logically imply: $\textit{HappyPerson}(\textit{mary})$

Relationship among TBox reasoning tasks

The TBox reasoning tasks are mutually **reducible** to each other, provided the description language is propositionally closed:

Theorem (TBox satisfiability to concept satisfiability to concept non-subsumption)

$$\mathcal{T} \text{ satisfiable} \quad \text{iff} \quad \mathcal{T} \not\models \top \sqsubseteq \perp \quad \text{iff} \quad \text{not } \mathcal{T} \models \top \sqsubseteq \perp \\ \text{(i.e., } \top \text{ satisfiable w.r.t. } \mathcal{T} \text{)}$$

Theorem (Concept subsumption to concept unsatisfiability)

$$\mathcal{T} \models C_1 \sqsubseteq C_2 \quad \text{iff} \quad \mathcal{T} \models C_1 \sqcap \neg C_2 \equiv \perp \\ \text{(i.e., } \models C_1 \sqcap \neg C_2 \text{ unsatisfiable w.r.t. } \mathcal{T} \text{)}$$

Theorem (Concept satisfiability to TBox satisfiability)

$$\mathcal{T} \not\models C \equiv \perp \quad \text{iff} \quad \mathcal{T} \cup \{ \top \sqsubseteq \exists P_{\text{new}} \sqcap \forall P_{\text{new}}.C \} \text{ satisfiable} \\ \text{(where } P_{\text{new}} \text{ is a new atomic role)}$$

TBox reasoning can be reduced to reasoning over an ontology:

Theorem (Concept satisfiability to ontology satisfiability)

C *satisfiable wrt* \mathcal{T} *iff* $\langle \mathcal{T} \cup \{A_{new} \sqsubseteq C\}, \{A(c_{new})\} \rangle$ *is satisfiable*
(where A_{new} is a new atomic concept and c_{new} is a new individual)

Exercise

Show mutual reductions between the remaining (TBox and ontology) reasoning tasks.

Internalization of the TBox

- In some (very expressive) DLs, it is possible to reduce reasoning wrt a TBox to reasoning over concept expressions only, i.e., the whole TBox can be internalized into a single concept.
- Whether this is possible depends on the available role and concept constructors, and the details differ for each DL.

Reasoning over DL ontologies is much more complex than reasoning over concept expressions:

Bad news:

- without restrictions on the form of TBox assertions, reasoning over DL ontologies is already **ExpTime-hard**, even for very simple DLs (see, e.g., [Donini, 2003]).

Good news:

- We can add a lot of expressivity (i.e., essentially all DL constructs seen so far), while still staying within the ExpTime upper bound.
- There are DL reasoners that perform reasonably well in practice for such DLs (e.g, Racer, Pellet, Fact++, . . .) [Möller and Haarslev, 2003].