

Page No.	O1
Date	23/04/24

FEA: Finite Element Analysis is approximate mathematical method to solve simple as well as complex engg problems.

③ Advantages of FEA:

- 1) It can handle complex structures & loading.
- 2) saves time.
- 3) Reduce cost.

④ Disadvantage:

- 1) Approximate answer
- 2) Cost of software & hardware is high.
- 3) Need skilled workers.

- 26/04/2024.

● Types of Analysis:

- 1) Linear Analysis
- 2) Non-Linear Analysis.
- 3) Dynamic Analysis
- 4) Linear Buckling Analysis
- 5) Thermal Analysis
- 6) Fatigue Analysis
- 7) Crush Analysis

- Linearity:

elastic material \rightarrow linear \rightarrow meted.

Static: $\&$ same with time doesn't change.

SHRENESS - resistant to change shape.
Toughness - to absorb max load / energy

Plasticity - continuous load causes removal of material.
Strength - capacity to carry load.
hardness - resist deformation

Plain strain \rightarrow considering obj to be 2D for our convinience.

Step -
1) preprocessing

\Rightarrow soln

2) Post

④ Type of Forces / Load:-

- ① point load
- ② Body force
- ③ Traction

⑤ Types of Element:

- 1) 1D Beam truss
- 2) 2D Δ , \square
- 3) 3D tetrahedral.

⑥ Engineering Applicat' of FEA:

1) Nuclear Engg :-

Analysis of nuclear pressure vessels and containment structure, steady state temp distribution in reactor components.

2) Bio-Medical Engg:

Stress Analysis of bones, teeth, load bearing capacity of implant and prosthetic sys.

3) Mechanical Design:-

4) Electrical Machine and Electromagnetics:
Steady state analysis of induction machines eddy curvy and core losses in electric machines.

No.	Element	DOF per node	no. of nodes	Used for
1.	Beam Element	1	2	beam analysis.

2. St. Truss Element 1 2 Truss & rods 5) Civil Engg Structures - Static Analysis of trusses, frames, shell roofs, shear walls, bridges, concrete structures.

3. Triangle Element 2 3 plain stress & plain-strain condition.

4. Quadrilateral 2 4 plain stress & plain strain condition.

3D	6. Hexahedral	6	20	3D Analysis
----	---------------	---	----	-------------

#) Heat Conductn:

Steady state temp distribution in solids or
dig.

8) Geomechanics:

Analysis of underground openings, soil structure
stress analysis of Dams and machine
foundatn.

9) Hydraulic and Water Resources Engg:-

Analysis of potential flows, free surface
flows, boundary layer flow, viscous flow
Analysis of hydraulic structure and dams

General steps of FEA:-

- 1) Discretization of Structure
- 2) Selection of Proper Interpolation or
displacement Model
- 3) Deviation of Element Stiffness Matrix
ces and Load Vector.
- 4) Assembly of Element eqn stiffness matrix
to obtain overall Equilibrium.
- 5) SOR for unknown Nodal displacement
- 6)* Computation of Element Strain &
stresses.

Boundary Conditions :-
Boundary condtn are in which surrounding
structure is applied by force and supported
by different types of constraints.

Types of Boundary Condtn:-

- 1) Geometric / Essential B.C.
- 2) Force or Natural B.C.

Geometric:

In geometric B.C. prescribed displacement
and slopes are included.

Force / Natural B.C.:

In these BC, prescribed forces and
moments in structural mechanic problems
are included.

Consistent Unit System:-

Most of softw used consistent unit sys
w/o any conversion of unit inside the
program.
It is therefore users responsibility to
input data and interpretate o/p in
appropriate units.

1D Element Analysis.

- Beam, Truss.
- Triangle,

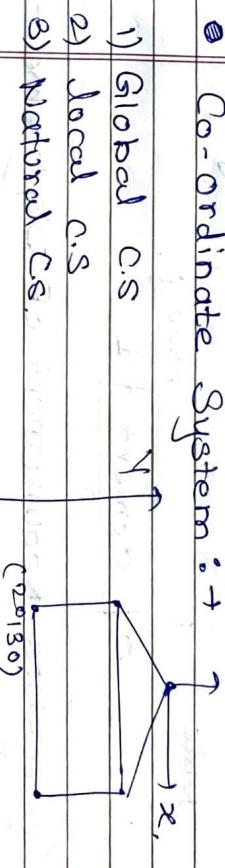
④ Symmetric Conditions:-

- The shapes, sizes, numbers, configuration of elements have to be chosen carefully such that; the original body or domain is simulated as closely as possible to \uparrow computational efforts needed for soln. Mostly the choice of type of elements is dictated by geometry of Body and no. of independent co-ordinates necessary to describe the sys.
- keep the geometry

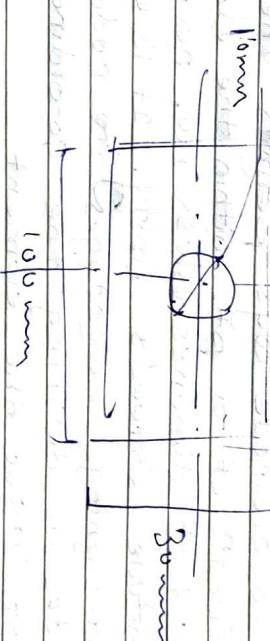
- Size of element influences conversions of soln directly and hence has to be chosen with care.
- If size of element is small, finel soln is expected to be more accurate But computational time for soln is high.

⑤ Location of Nodes:-

element node
Node 1 2 element 2
Nodes 3 4

Co-ordinate System :-

TF configuration of body, as well as exterior cond's are symmetric, we may consider only half of body for finite element problems.



uniform.

- If the Body has no abrupt changes in geometry, material properties and external condition like load & temp. Body can be divided into equal subdivisions and hence spacing of nodes can be

- 1) Global Co-ordinate System:- Co-ordinate system used to define points in entire structure is called as Global Co-ordinate System.
- 2) Local Co-ordinate System:- for each element or component a separate coordinate system is used to deriving element properties. it is called local co-ordi-

- however, final opn are to be formed in global co-ordinate System.

3) Natural Co-ordinate System:

This co-ordinate sys permits the specification of a pt within the element by a set of dimensionless no, never use magnitude exceeds unity. It is obtained by assigning weightages to nodal co-ordinates in defining the coordinate of any pt inside the element.

- The use of natural co-ordinate sys is advantageous in assembling element properties. Since closed form integratn formulae are available when expression are in natural co-ordinate system.



④ Conversions Requirement of Displacement funct'n

1) Displacement funct'n must be continuous & compatible within the element

- continuous means 2nd element should start by taking one edge common of 1st

- compatible means when it deforms, there should not be any discontinuity betw' elements, means element must not

Separate or overlap and there should not be any sudden change in slope across the inter element boundaries,

2) Displacement funct'n must be capable of representing constant strain stage within the element.

3) Displacement funct'n must be capable of representing rigid body displacement.

* Displacement funct'n for 1D element:

2) Bar Element:

$$u = \alpha_1 + \alpha_2 x$$



$$\text{at node } 1, u_1 = \alpha_1 + \alpha_2 x_1$$

$$\text{at node } 2, u_2 = \alpha_1 + \alpha_2 x_2$$

⑤ Beam Element



$$u = \alpha_1 + \alpha_2 x + \alpha_3 x^2 + \alpha_4 x^3$$

Natural C.S for 1D

$$L_1 + L_2 = 1$$

$$\alpha_1 \quad x_1 \quad x_2$$

in matrix form

$$0 \begin{bmatrix} x_1 - x_2 \\ x_2 - x_1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \alpha_1 & \alpha_2 \end{bmatrix} \begin{bmatrix} \alpha_1 & \alpha_2 \end{bmatrix}$$

nodes at x_1, x_2, x_3

$$N_1(x) = (x - x_2)(x - x_3)$$

$$(x_1 - x_2)(x_1 - x_3)$$

$$N_2(x) = (x - x_1)(x - x_3)$$

$$(x_2 - x_1)(x_2 - x_3)$$

$$= \frac{1}{\Delta} \begin{bmatrix} x_2 & -1 \\ -x_1 & 1 \end{bmatrix} \begin{Bmatrix} 1 \\ 2 \end{Bmatrix}$$

$$l_1 = \frac{x_2 - x}{\Delta} + l_2 \frac{x - x_2}{\Delta}$$

(3) Cubic Interpolation function:-

- Polynomial form of Interpolation function:-

Interpolation function also known as shape function are used in numerical methods like FEA to approximate solution per element



$$N_1(x) = (x - x_2)(x - x_3)(x - x_4)$$

$$(x - x_2)(x_1 - x_3)(x_1 - x_4)$$

Linear interpolation function for element with node x_1 & x_2 can be written as

$$N_1(x) = \frac{x_2 - x}{x_2 - x_1}; \quad N_2 = \frac{x - x_1}{x_2 - x_1}$$

2) Quadratic Interpolation for 1D problem:-

Quadratic interpolation function are 2nd degree polynomial, for 2D element with

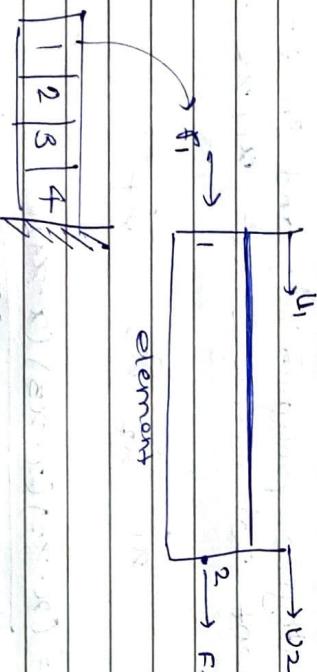
• Properties of Shape funtn:-

- It possesses several imp properties that ensure their utility in FEA.

- 1) Compatibility
- 2) Completeness

- 3) Interpolation property.
- 4) Partition of unit
- 5) Non-negativity

⑥ Stiffness matrix :-



For element;

$$f_1 = K(u_2 - u_1) = -k(u_2 - u_1)$$

$$f_2 = K(u_2 - u_1) = k(u_2 - u_1)$$

$$K = \frac{AE}{L}$$

$$\begin{bmatrix} f_1 \\ f_2 \end{bmatrix} = \begin{bmatrix} -k & K \\ K & -k \end{bmatrix} \begin{bmatrix} u_2 \\ u_1 \end{bmatrix}$$

$$\begin{bmatrix} f_1 \\ f_2 \end{bmatrix} = \begin{bmatrix} k & -k \\ -k & k \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

$$= k \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

L = Length of Element

A = o/s area of 1

E = modulus of elasticity of material

f_1 = force acting on node 1

$$f_2 = -f_1$$

u_1 = displacement of node 1

$$u_2 = -u_1$$

$$\left\{ \begin{array}{l} f_1 \\ f_2 \end{array} \right\} = \frac{AE}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \left\{ \begin{array}{l} u_1 \\ u_2 \end{array} \right\}$$

Element force vector = Element stiffness matrix \times displacement vector

Total degree of freedom = DOF per node \times No. of nodes.

* Assembly of Stiffness Matrix:-

$$f_1 \rightarrow \begin{bmatrix} u_1 \\ 1 \\ 2 \\ 3 \end{bmatrix} \xrightarrow{\text{①}} \begin{bmatrix} u_2 \\ -1 \\ 1 \end{bmatrix} \xrightarrow{\text{②}} \begin{bmatrix} u_3 \\ 1 \end{bmatrix} \rightarrow F_3$$

K_1

for element 1

$$\begin{cases} f_1 \\ f_2 \end{cases} = K_1 \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{cases} u_1 \\ u_2 \end{cases}$$

for element 2;

$$\begin{cases} f_2 \\ f_3 \end{cases} = K_2 \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{cases} u_2 \\ u_3 \end{cases}$$

for element 3;

$$\begin{cases} f_3 \\ f_1 \end{cases} = K_3 \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{cases} u_3 \\ u_1 \end{cases}$$

displacement

$$\begin{cases} u_1 \\ u_2 \\ u_3 \end{cases}$$

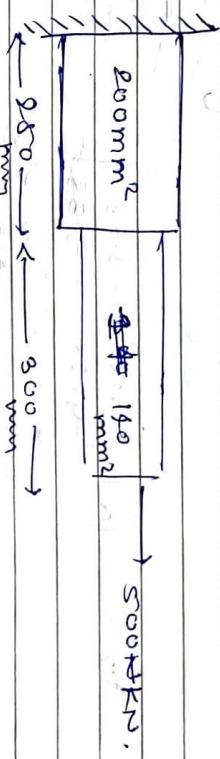
Stiffness

$$\text{Total D.o.F.} = 1 \times 3 = 3$$

$$= \begin{bmatrix} 1 & -1 & 0 \\ -1 & 1+1 & 0-1 \\ 0-1 & 0+1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix} \dots \dots$$

Global Stiffness Matrix.



Basic Steps in FEA:-

- 1) Discretization of Body
- 2) Formation of element stiffness matrix
- 3) Formation of Global stiffness matrix
- 4) Formation of Global load vector.
- 5) Assembly of Global displacement vector
- 6) Incorporation of specified B.C.

Ex - A stepped metallic bar with circular cross sect'n consists of 2 segments, 1st seg is of length 250 mm & cross sect'n Area 200 mm². 2nd segment is of length 300 mm & cross sect'n area 140 mm². Modulus of elasticity of bar material is 200 GPa. If bar is fixed at 1 end of bigger cross sect'n & subjected to tensile force of 500 kN at opposite end of smallest sect'n. Determine:

- 1) Nodal displacement
- 2) Element Stress
- 3) Support reaction

→
↓)



$$J_1 = 0.50 \quad R = 3.00 \rightarrow$$

2) format of Element Stiffness Matrix:-

$$K_1 = \frac{A_1 E_1}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = \frac{200 \times 200 \times 10^3}{250} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

4) Global Load Vector:-

$$\begin{bmatrix} R \\ 0 \\ 0 \\ F_{P3} \end{bmatrix} = \begin{bmatrix} R \\ 0 \\ 0 \\ -2500 \times 10^3 \end{bmatrix} \xrightarrow{\text{Reaction}}$$

5) Nodal displacement

$$\begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}$$

for E_2 :

$$K_2 = \frac{A_2 E_2}{L_2} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = \frac{140 \times 200 \times 10^3}{300} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

6) Assembly of Global Stiffness Matrix:-

$$\{K\} \{u\} = \{F\}$$

$$10^4 \begin{bmatrix} 16 & -16 & 0 \\ -16 & 16+9.33 & 0-9.33 \\ 0 & 0-9.33 & 0+9.33 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} R \\ 0 \\ 0 \end{bmatrix} = 500 \times 10^3$$

3) Global Stiff matrix:

E)

At Node I; Rigid support is there
 $\therefore u_1 = 0$

By using row elimination,

$$10^4 \begin{bmatrix} 25.33 & -9.33 \\ -9.33 & 5.33 \end{bmatrix} \begin{Bmatrix} u_2 \\ u_3 \end{Bmatrix} = \begin{Bmatrix} 10^3 \\ 0 \end{Bmatrix} \quad \left\{ \begin{array}{l} 10^3 \\ 0 \end{array} \right\} = \left\{ \begin{array}{l} 500 \times 10^3 \\ 0 \end{array} \right\}$$

$$10^4 [25.33 \times u_2 - 9.33 \times u_3] = 0$$

$$10^4 [-9.33 u_2 + 9.33 u_3] = 500 \times 10^3.$$

8) By adding $(\frac{9.33}{25.33})$ Row I to Row II.

$$= 10^4 \begin{bmatrix} 25.33 & -9.33 \\ 0 & 5.33 \end{bmatrix} \begin{Bmatrix} u_2 \\ u_3 \end{Bmatrix} = 10^3 \begin{Bmatrix} 0 \\ 500 \end{Bmatrix}$$

$$10^4 [0 \times u_2 + 5.33 \times u_3] = 10^3 \times 500$$

$$10^4 [5.33 u_3] = 10^3 \times 500$$

$$\therefore u_3 = 50$$

$$10^4 [5.33 u_3] = 10^3 \times 500$$

$$25.33 u_2 = 79.1463$$

$$\therefore u_2 = 3.124$$

$u_1 \rightarrow 0$; $b_{12} = d_{13} = 0$; b_{22} is fixed (Node I)

$$\left\{ \begin{array}{l} u_x \\ u_y \end{array} \right\} = \left\{ \begin{array}{l} 3.125 \\ 8.482 \end{array} \right\}$$

Stress:-

$$\sigma_x = \frac{E_x}{J_1} \begin{bmatrix} -1 & 1 \\ 1 & 1 \end{bmatrix} \left\{ \begin{array}{l} u_1 \\ u_2 \end{array} \right\}$$

$$\sigma_x = \frac{E_x}{J_1} \begin{bmatrix} -1 & 1 \\ 1 & 1 \end{bmatrix} \left\{ \begin{array}{l} u_1 \\ u_2 \end{array} \right\}$$

$$= \frac{200 \times 10^3}{250} [-1 \times 0 + 1 \times 3.125]$$

$$\sigma_x = 2500 \text{ N/mm}^2$$

$$\sigma_2 = \frac{E_2}{J_2} \begin{bmatrix} -1 & 1 \\ 1 & 1 \end{bmatrix} \left\{ \begin{array}{l} u_1 \\ u_2 \end{array} \right\}$$

$$\sigma_2 = \frac{200 \times 10^3}{300} [-1 \times 3.125 + 1 \times 8.483]$$

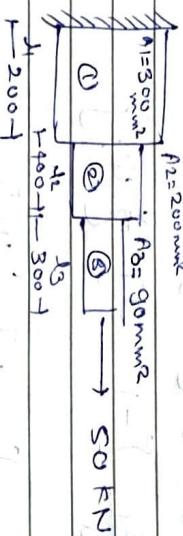
$$\sigma_2 = 3571.3 \text{ N/mm}^2.$$

$$10^4 \begin{bmatrix} 16 & -16 \\ -16 & 16 \end{bmatrix} \begin{Bmatrix} u_1 \\ u_2 \end{Bmatrix} = \begin{Bmatrix} R_1 \\ 0 \end{Bmatrix}$$

$$10^4 [16 \times u_1 - 16 \times u_2] = R_1$$

$$u_1 \rightarrow 0$$

Ex - Axial step bar shown in fig. is subjected to an axial pull of 50 KN. If modulus of elasticity is uniform and as modulus of elasticity 200 GPa, find: (i) Nodal displacement. (ii) Stress in each element. (iii) Reaction at support.



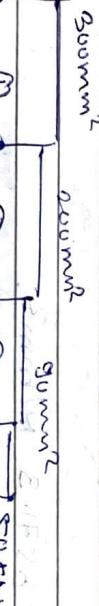
$$E_1 = E_2 = E_3 = 200 \text{ GPa}$$

→

i) Discretization



Give nodes:



Area node 1: 3000 mm², node 2: 2000 mm², node 3: 96 mm², node 4: 50 KN.

200 400 300

ii) Total DOF :- DOF at each node × no. of element

1 4

a) Formulation of Element Stiffness Matrix

For element 1;

$$K_1 = \frac{A_1 E}{J_1} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = \frac{300 \times 200 \times 10^3}{200} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 300 \times 10^4$$

$$K_1 = 10^4 \begin{bmatrix} 30 & -30 \\ -30 & 30 \end{bmatrix}$$

$$K_2 = 10^4 \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$K_2 = \frac{A_2 E_2}{J_2} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = \frac{200 \times 200 \times 10^3}{480} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$\therefore K_2 = 10 \times 10^4 \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 10^4 \begin{bmatrix} 10 & -10 \\ -10 & 10 \end{bmatrix}$$

$$K_3 = \frac{A_3 E_3}{J_3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = \frac{96 \times 200 \times 10^3}{300} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$\therefore K_3 = 60 \times 10^3 \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 10^4 \begin{bmatrix} 6 & -6 \\ -6 & 6 \end{bmatrix}$$

$$K = K_1 + K_2 + K_3 = 10^4 \begin{bmatrix} 30 & -30 & 0 & 0 \\ -30 & 30+10 & -10 & 0 \\ 0 & -10 & 10+6 & -6 \\ 0 & 0 & -6 & 6 \end{bmatrix}$$

4) Incorporation of Specified BC:

at node 2: $u_1 = 0$
using row elimination:

$$2 \times 10^4 \begin{bmatrix} 20 & -5 & 0 \\ -5 & 8 & -3 \\ 0 & -3 & 3 \end{bmatrix} \begin{Bmatrix} u_2 \\ u_3 \\ u_4 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \\ 50 \times 10^3 \end{Bmatrix}$$

$$2 \times 10^4 [-5 u_2 + 8 u_3 - 3 u_4] = 0$$

Step 4) Global Load Vector:-

$$\begin{Bmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \end{Bmatrix} = 2 \times 10^4 \begin{Bmatrix} R \\ 0 \\ 0 \\ 0 \end{Bmatrix} = 50 \times 10^3$$

↓
load acting at 1, 2, 3, 4.
R → for support (जिसे फिर्माना होगा R)

Step 5: Nodal Displacement:

$$\begin{Bmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \end{Bmatrix}$$

Step 6: Assembly of Stiffness Matrix

$$[K] \{u\} = \{f\}$$

$$2 \times 10^4 \begin{bmatrix} 20 & -5 & 0 \\ -5 & 8 & -3 \\ 0 & -3 & 3 \end{bmatrix} \begin{Bmatrix} u_2 \\ u_3 \\ u_4 \end{Bmatrix} = \frac{3}{8} \times (-3) + R_3$$

$$2 \times 10^4 \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{Bmatrix} u_2 \\ u_3 \\ u_4 \end{Bmatrix} = \frac{-9}{8} + \frac{3 \times 8}{8} = -15$$

$$2 \times 10^4 \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{Bmatrix} u_2 \\ u_3 \\ u_4 \end{Bmatrix} = 50 \times 10^3$$

$$-15 u_4 =$$

$$2 \times 10^4 \begin{bmatrix} 15 & -15 & 0 & 0 \\ -15 & 20 & -5 & 0 \\ 0 & -5 & 8 & -3 \\ 0 & 0 & -3 & 3 \end{bmatrix} \begin{Bmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \end{Bmatrix} = 50 \times 10^3$$

Multiplying: $\sum_{20} \times \text{Row 5} + \text{Row } \sum$

$$2 \times 10^4 \begin{bmatrix} 20 & -5 & 0 \\ -5 & 8 & -3 \\ 0 & -3 & 13 \end{bmatrix}$$

We need zero here.

That's why we need zero here, so that row below won't change.

\therefore Multiply \sum_{20} to Row 5 and add to Row 2.

$\therefore \sum_{20} \text{Row 1} + \text{Row 2} \Rightarrow$

$$1) 20 \times 5 + -5 \Rightarrow 0$$

$$2) -5 \times \frac{5}{20} + 8 \Rightarrow 9$$

$$\frac{5}{20} \times (-5) + 8 = \frac{-5}{4} + \frac{8}{4} \times 4 = 32 - 5 = 27.5$$

$$2 \times 10^4 \begin{bmatrix} 20 & -5 & 0 \\ 0 & 6.75 & -3 \\ 0 & -3 & 13 \end{bmatrix} \left\{ \begin{array}{l} U_2 \\ U_3 \\ U_4 \end{array} \right\} = \left\{ \begin{array}{l} 0 \\ 0 \\ 50 \times 10^3 \end{array} \right\}$$

zero

$$R_3 \Rightarrow \frac{3}{6.75} \times R_2 + R_3 \Rightarrow$$

$$\frac{3}{6.75} \times R_2 + R_3 \Rightarrow$$

$$3) \frac{3}{6.75} \times (6.75 + (-3)) = 0$$

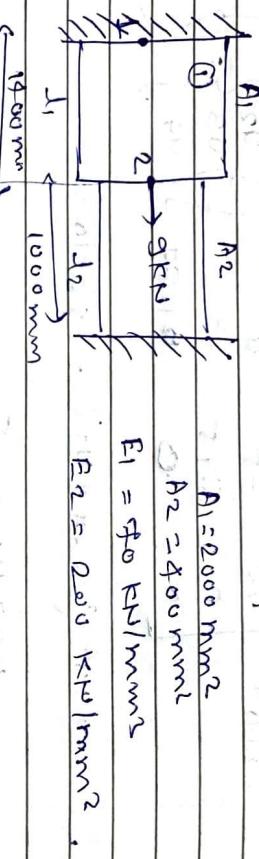
$$2) \frac{3}{6.75} \times (-3) + 3 = -1.33 + 3 = 1.67.$$

$$2 \times 10^4 \begin{bmatrix} 20 & -5 & 0 \\ 0 & 6.75 & -3 \\ 0 & -3 & 13 \end{bmatrix} \left\{ \begin{array}{l} U_2 \\ U_3 \\ U_4 \end{array} \right\} = \left\{ \begin{array}{l} 0 \\ 0 \\ 50 \times 10^3 \end{array} \right\}$$

$$1.67 \cdot 6.74 = \frac{5}{2}$$

$$\therefore U_4 = 1.49700$$

que. 2 bar 1 of Aluminium & other of steel joined together; & subjected to load as shown in fig. Determine displacement at common joint and member forces.



→ 1) Discretization:

$$u_1 = u_3 = 0$$

$$\begin{matrix} \text{①} \\ \text{②} \\ \text{③} \end{matrix} \rightarrow \text{rotated Dof}$$

$$= 1 \times 3 = 3$$

$$F_1$$

$$F_2$$

2) Format of Element Stiffness Matrix:

$$k_1 = \frac{A_1 E_1}{L_1} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = \frac{2000 \times 70 \times 10^3}{1400} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$k_1 = \frac{15 \times 10^3}{1400} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 10^4 \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$k_2 = \frac{A_2 E_2}{L_2} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = \frac{400 \times 200 \times 10^3}{1000} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$= 8 \times 10^4 \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 10^4 \begin{bmatrix} 8 & -8 \\ -8 & 8 \end{bmatrix}$$

b) Global Stiffness matrix:

$$K = k_1 + k_2 = \begin{bmatrix} 10 & -10 & 0 \\ -10 & 10+8 & -8 \\ 0 & -8 & 8 \end{bmatrix}$$

4) Global Load Vector:

$$\begin{cases} R_1 \\ R_2 \\ R_3 \end{cases} = \begin{cases} 0 \\ 0 \\ 0 \end{cases}$$

Global displacement: $\begin{cases} u_1 \\ u_2 \\ u_3 \end{cases} = \begin{cases} 0 \\ 0 \\ 0 \end{cases}$

c) Assembly of Global Stiffness Matrix:

$$[K] \{u\} = \{f\}$$

$$\begin{bmatrix} 10 & -10 & 0 \\ -10 & 18 & -8 \\ 0 & -8 & 8 \end{bmatrix} \begin{cases} u_1 \\ u_2 \\ u_3 \end{cases} = \begin{cases} R_1 \\ R_2 \\ R_3 \end{cases}$$

d) Incorporation of Specified B.C.: at node 2: $u_1 = 0$, Using row elimination (Support removed now)

$$\begin{bmatrix} 18 & -8 \\ -8 & 8 \end{bmatrix}$$

$$10^4 (18 u_2) = 9 \times 10^3$$

$$\therefore u_2 = 0.5 \times 10^{-3} = \frac{500}{10^4} = 0.05$$

Beam - Transient load acts.

$$10^4 \times \left[10 \times u_1 + 10 \times u_2 \right] = R_1$$

$$10^4 \times \left[10 \times 0 - 10 \times 0.05 \right] = R_2$$

$$R_1 = 10^4 \times (-0.5)$$

$$R_1 = -5 \times 10^3 \text{ N.}$$

For R_3 ,

$$10^4 \begin{bmatrix} 8 & -8 \\ -8 & 8 \end{bmatrix} \begin{bmatrix} u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$10^4 \begin{bmatrix} (-8 \times u_2) + (8 \times u_3) \\ 0 \end{bmatrix} = R_3$$

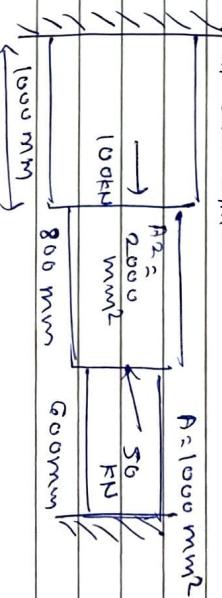
$$R_3 = 10^4 \begin{bmatrix} (-8 \times 0.05) + (8 \times 0) \\ 0 \end{bmatrix}$$

$$R_3 = -4 \times 10^3 \text{ N.}$$

Ques:-

$$A_1 = 3000 \text{ mm}^2$$

$$A_2 = 1000 \text{ mm}^2$$



$$\sigma_2 = \frac{P_2 \times 10^3}{A_2} \begin{bmatrix} -1 & 1 \end{bmatrix} \begin{bmatrix} u_2 \\ u_3 \end{bmatrix}$$

$$= 200 \begin{bmatrix} -1 & 1 \end{bmatrix} \begin{bmatrix} 0.05 \\ 0 \end{bmatrix}$$

$$= 200 \begin{bmatrix} -0.05 & 0 \end{bmatrix}$$

$$\sigma_2 = -10$$

(b) Computation of strain & stress:-

For R_1

$$10^4 \begin{bmatrix} 10 & -10 \\ -10 & 10 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} f_1 \\ f_2 \end{bmatrix}$$

Global Stiffness Matrix for Truss Element:



In fig., 4 nodal bar element for analysis of truss is selected. ∴ The members are subjected to only axial forces, displacement are only axial direction of members. Therefore, nodal displacement vector for bar element is :-

$$\{x'\}_e = \begin{Bmatrix} \delta_1' \\ \delta_2' \\ \delta_3' \\ \delta_4' \end{Bmatrix}$$

where δ_1' and δ_2' are displacement in axial direction of element

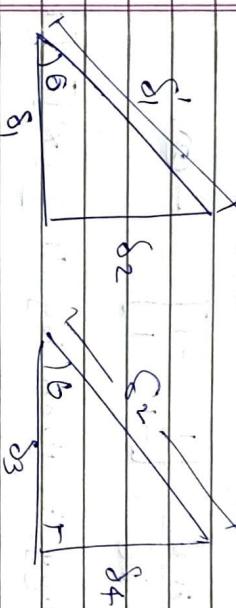
$\delta_1' \neq \delta_2'$ = Axial displacement in local c.s

$\delta_1' \neq \delta_2' = -1$ Global c.s.

Axial direction is not same for all members. Hence, if we select x & y as global co-ordinate sys.

∴ There're 2 displacement component at every node. Hence nodal variable vector for an element is

$$\{x\}_e = \{L\} \{x'\}_e$$



$$\delta_1' = \delta_1 \cos \theta + \delta_2 \sin \theta \quad \text{---(1)}$$

where,

$$[L] = \text{Transformation matrix to R}$$

$$\delta_2' = \delta_3 \cos \theta + \delta_4 \sin \theta \quad \text{---(2)}$$

$$[L] = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \quad \{x'\}_e = \begin{Bmatrix} \delta_1' \\ \delta_2' \end{Bmatrix}$$

$$\therefore \begin{bmatrix} \cos \theta & \sin \theta & 0 & 0 \\ 0 & 0 & \cos \theta & \sin \theta \end{bmatrix} \begin{Bmatrix} \delta_1' \\ \delta_2' \end{Bmatrix} = \begin{Bmatrix} \delta_1 \\ \delta_2 \end{Bmatrix}$$

$$\therefore \cos \theta, \quad m = \sin \theta$$

$$\therefore \{x\}_e = [L] \{x'\}_e$$

• Stiffness Matrix :- (Using Strain Energy)
 The matrix of 2 nodal bar element used for Analysis of Truss is

$$[K] = \frac{A \cdot E}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \quad \text{--- (2)}$$

- Strain Energy is given by $U = \frac{1}{2} [x]^T [k]_e \{x\}_e$

$$U = \frac{1}{2} \{x\}_e^T [k]_e \{x\}_e$$

→ displacement vector

-- for local co-ordinates sys.

$$= \frac{1}{2} \{x\}_e^T \cdot [k]_e \cdot \{x\}_e$$

$$= \frac{1}{2} \{x\}_e^T \cdot [L]^T \cdot [k]_e \cdot [L] \cdot \{x\}_e$$

where,

$$[k] = [L]^T \cdot [k'] \cdot [L] \quad \text{--- (4)}$$

$[k'] \rightarrow$ Stiffness matrix in Local co-ordinate sys.

$[L] \rightarrow$ Transformation matrix in Global c.s.

$[L] \rightarrow$ Transformation matrix, eqn (4) can be written by,

$$[k] = \begin{bmatrix} 1 & 0 \\ m & 0 \end{bmatrix} \cdot A \cdot E \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & m & 0 & 0 \\ 0 & m \end{bmatrix}$$

* Strain-Displacement Matrix for Bar Element.

$$\{e\}_e = \{e_x\} = \frac{\partial u}{\partial x}$$

$$e_x = \frac{\partial}{\partial x} [u] \cdot \{u\}_e$$

$$\text{but, } \nu_1 = x_2 - x_1, \quad \nu_2 = \frac{x_1 - x_2}{2}$$

derivative w.r.t. x ;

$$\frac{\partial \nu_1}{\partial x} = \frac{-1}{2}, \quad \frac{\partial \nu_2}{\partial x} = \frac{1}{2}$$

$$\therefore \{e\}_e = e_x = \begin{bmatrix} -1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

$$\{e\}_e = [B] \cdot \{a\}_e$$

we know,

$$e_1 = x_2 - x_1 = 2 (x_2 - x_1)$$

$$\nu_1 = \frac{1-e}{2}; \quad \nu_2 = \frac{1+e}{2}$$

$$\frac{\partial e}{\partial x} = \frac{2}{L}, \quad \frac{\partial \nu_1}{\partial e} = -\frac{1}{2}, \quad \frac{\partial \nu_2}{\partial e} = \frac{1}{2}$$

$$\{e\}_e = e_x = \frac{2}{L} \begin{bmatrix} -1 & 1 \\ 1 & 1 \end{bmatrix} \cdot \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

$$[k] = \frac{A \cdot E}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & m & -1 & -m \\ -1 & -m & 1 & m \\ 1 & m & 1 & m \\ -m & -m & m & m^2 \end{bmatrix}$$