

Computer Graphics

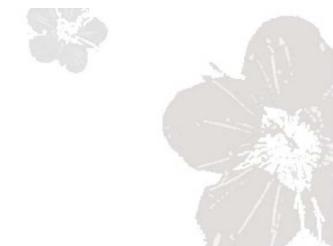


by Ruen-Rone Lee ICL/ITRI





- Color Model
- Lighting Equation
 - Illumination Model
 - Ambient
 - Diffuse
 - Specular







Part I: Conventional 3D Graphics Pipeline

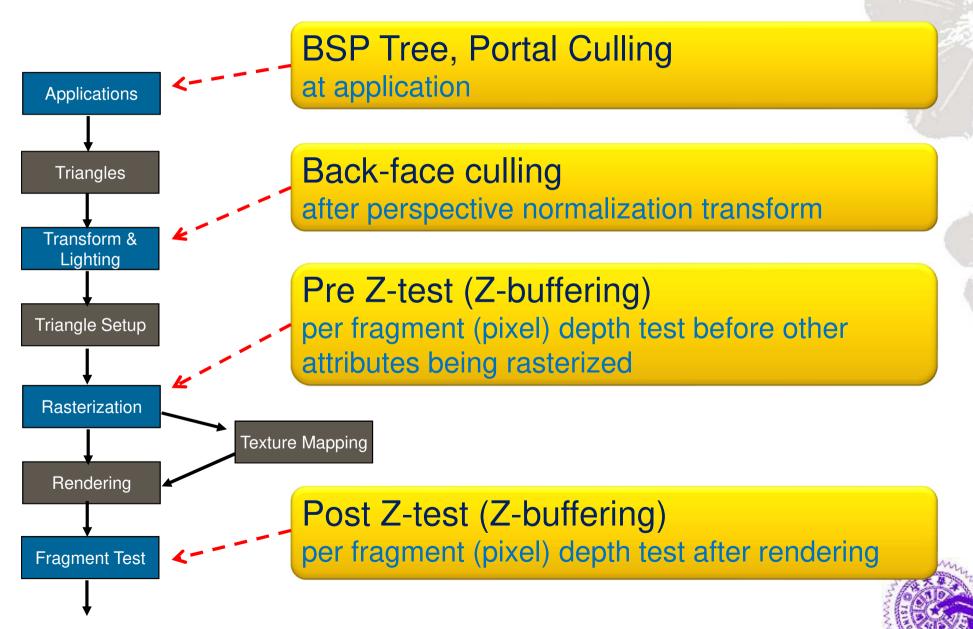


Remove hidden pixels / primitives





HSR at Different Stages



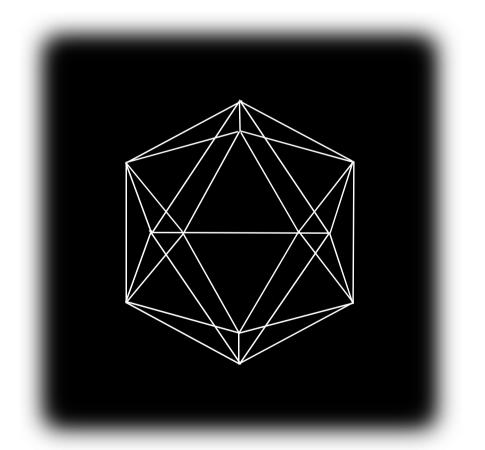
Objectives of HSR

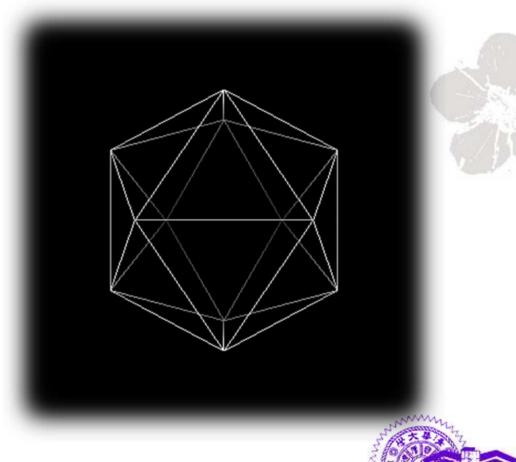
- Remove objects, surfaces, or pixels that are not visible
 - Clipping remove objects/surfaces that are outside the view volume
 - HSR applies on spatial relationship, especially the hidden relationship, between objects with respect to the viewing direction
- Improve performance by reducing the computation of invisible surfaces / pixels
- Perception of spatial occlusion

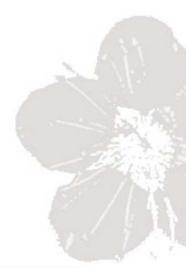


Depth Cue

Wireframe Display

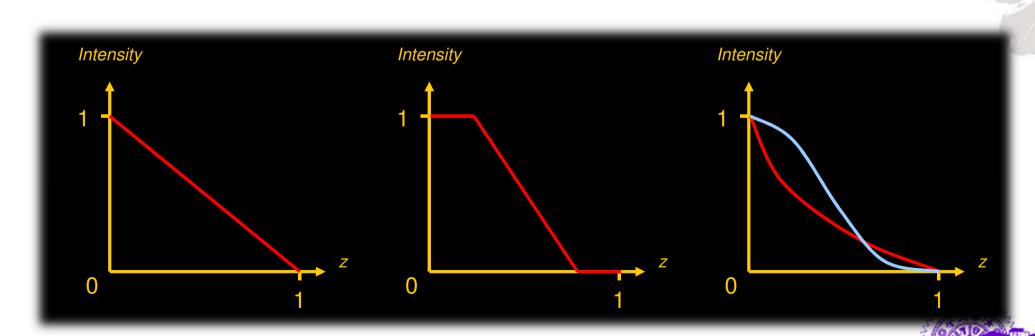






Depth Cue

- Implementation
 - e.g., $Intensity = f(z) = 1/z, 0 \le z \le 1$
 - Map the intensity values within the range of [0, 255]



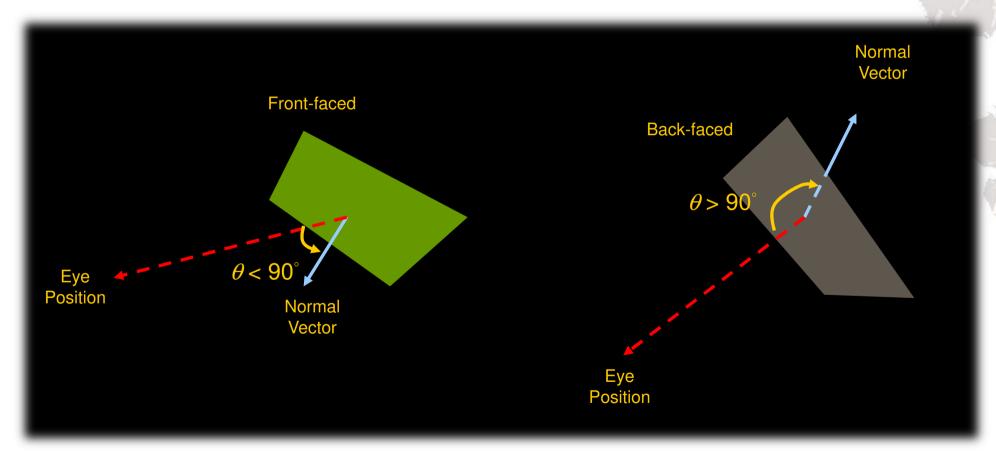






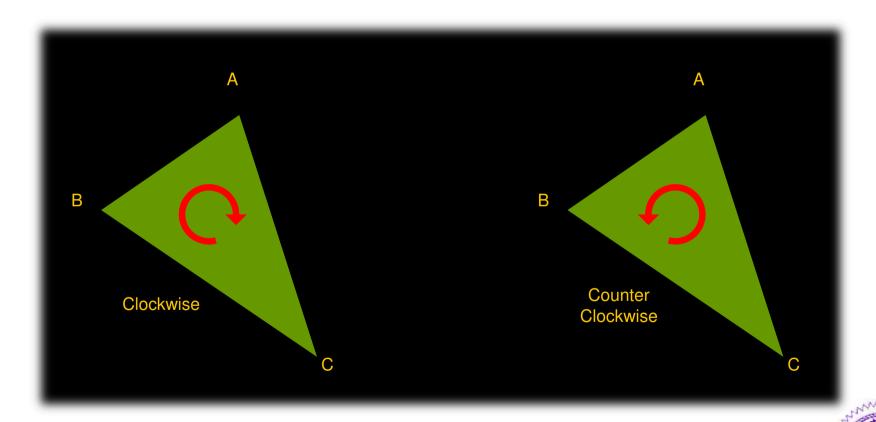
HSR at Primitive Stage

Back-face determination

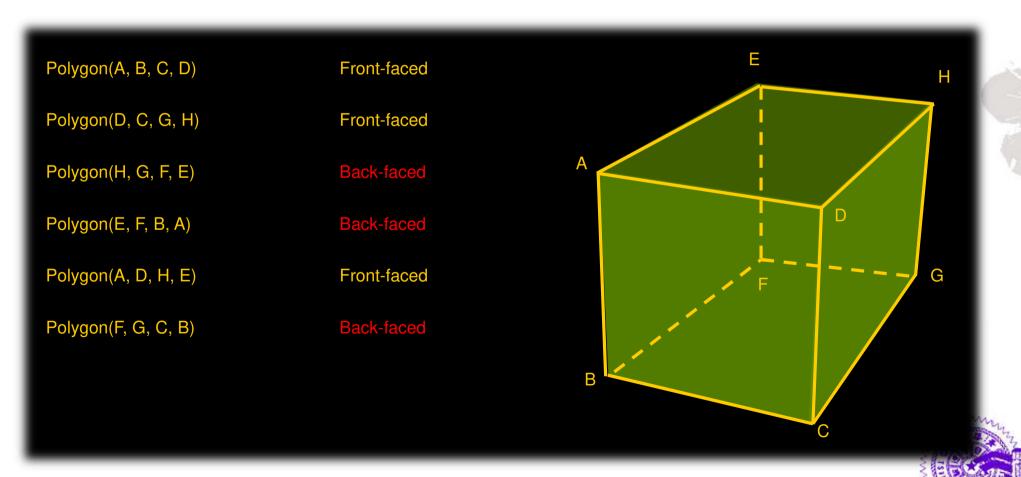




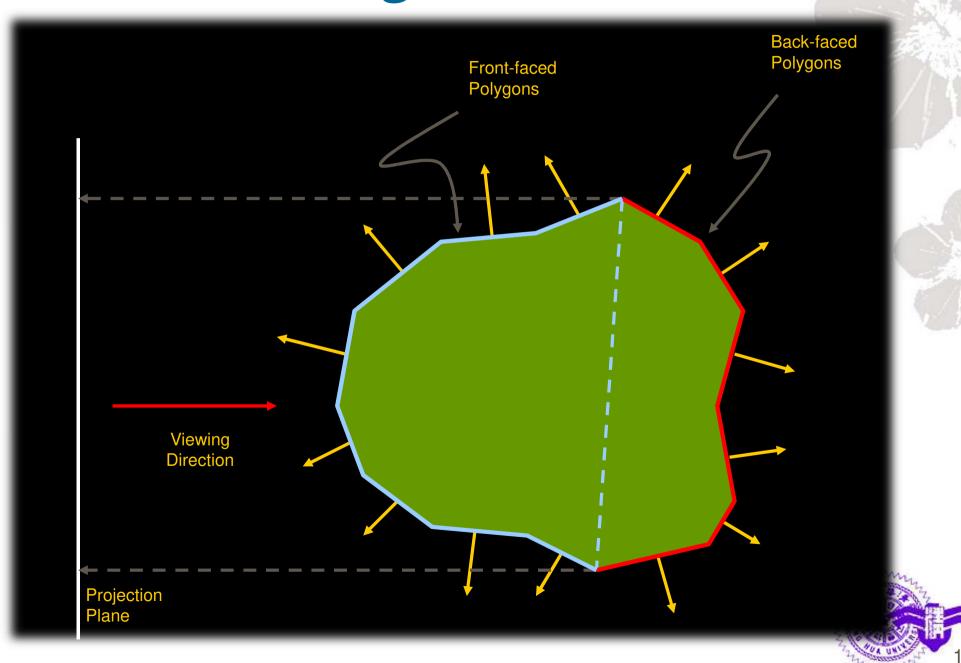
 Define clockwise or counter clockwise for front-faced polygon



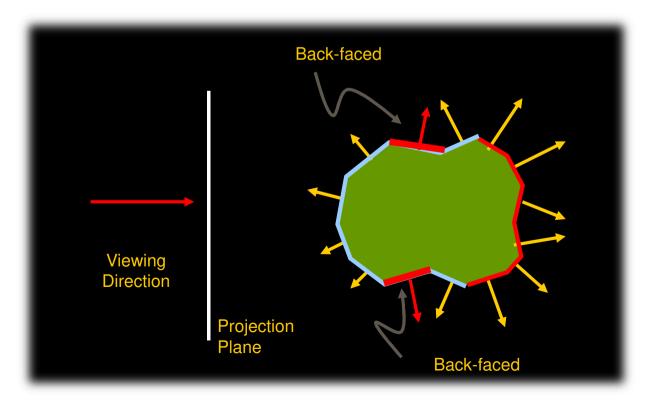
 Assume the counter clockwise polygon is the front-faced polygon



- Apply cross product to determine the normal vector of a polygon
- ◆ A dot product of the eye vector and the normal vector determines the facing attribute (assuming counter-clockwise is the vertex order of a front-faced polygon)
 - *N E* > 0 implies front-facing
 - *N E* < 0 implies back-facing
- ps. if clockwise is defined to be the front-faced then N = -N before applying dot product

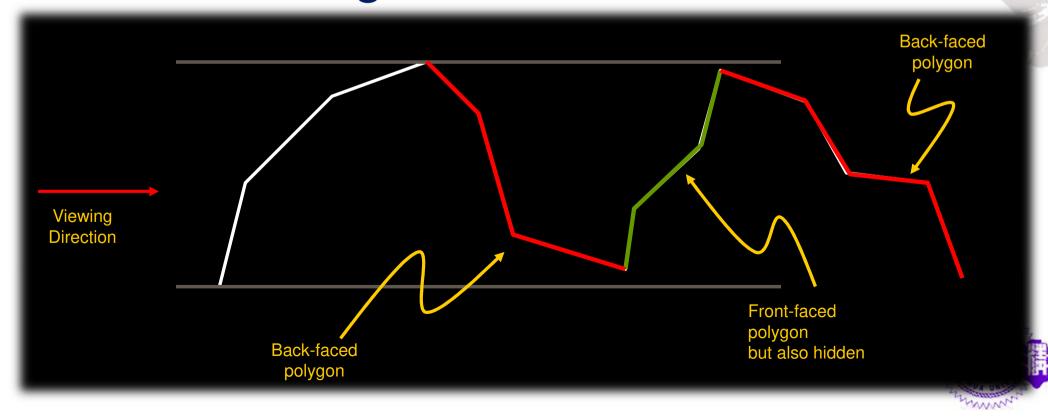


- Why consider parallel projection only?
 - After perspective normalization, the polygon normals will toward the right directions to distinguish front-faced or back-faced polygons



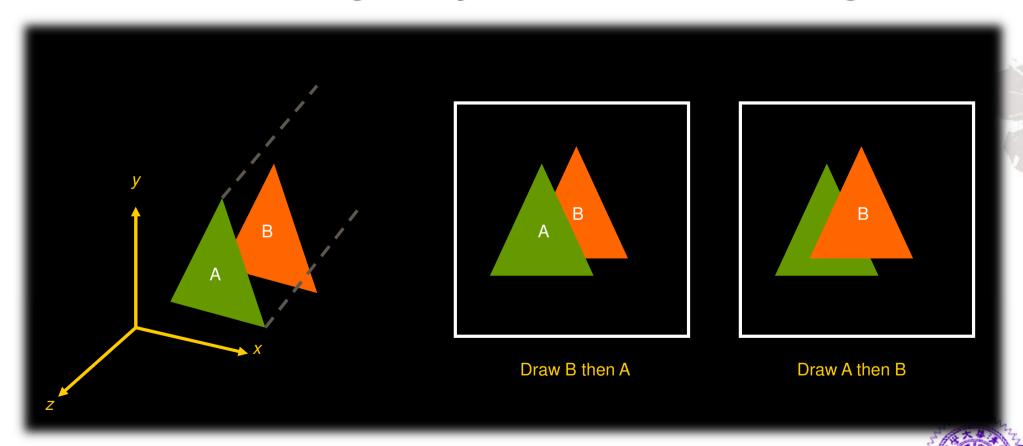


 Despite the back-face culling is simple and fast to remove hidden surfaces at primitive stage, but it cannot guarantee to remove all surfaces being hidden.



Display Order

 The display order might derive in different results if using only back-face culling







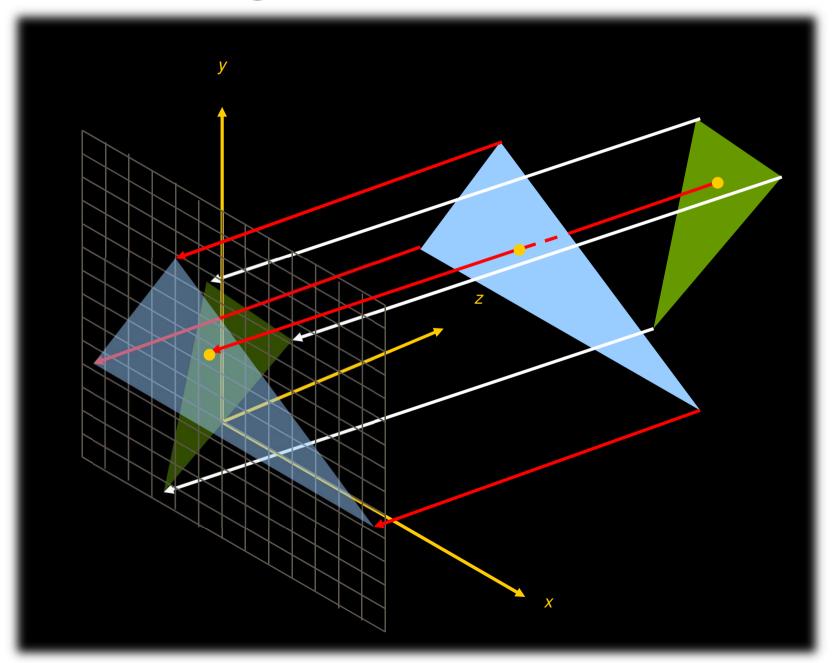




- Eliminate the limitation of display order
- Require a memory space, equal to the size of display buffer, to store the depth / Z values
- Comparison is required to determine which pixel is closer to the viewer

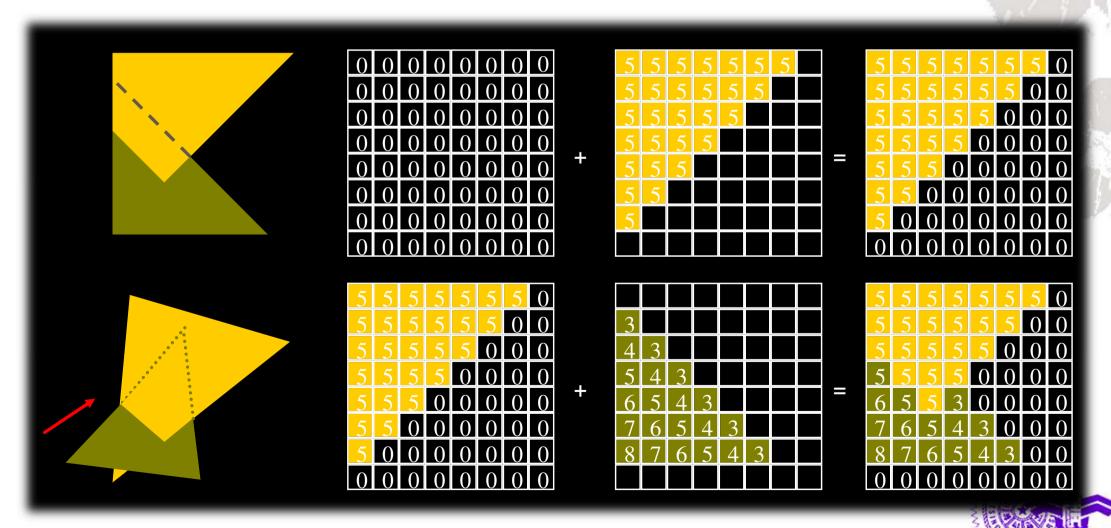


- Basic concept
 - Store the depth value of the closest object at each pixel found so far
- Render each polygon, pixel by pixel
- Compare the depth of each pixel of a polygon with the depth of the corresponding depth value in Z-buffer
- If the comparison pass, then render the color to color buffer and replace the depth value by current pixel depth





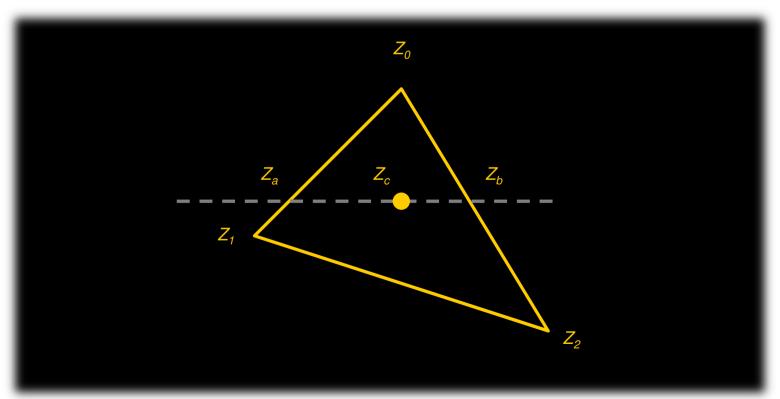
Example: (larger z value is closer to viewer)



Choose of Depth Values

When Interpolation Z in screen space, which Z values should be used?

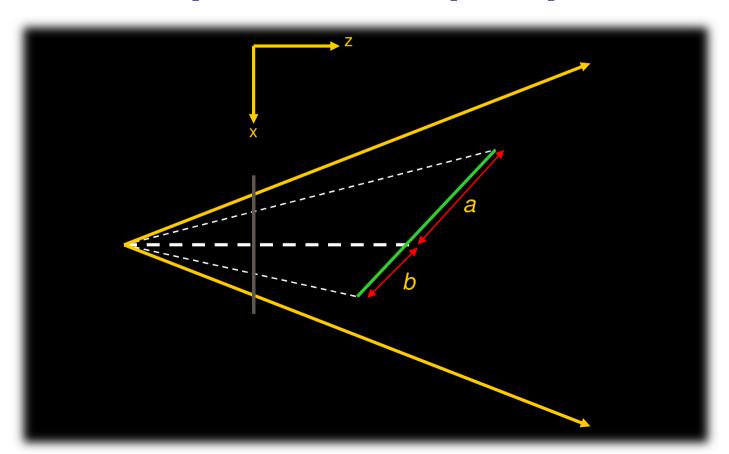
World space Z or clip space Z?





Choose of Depth Values

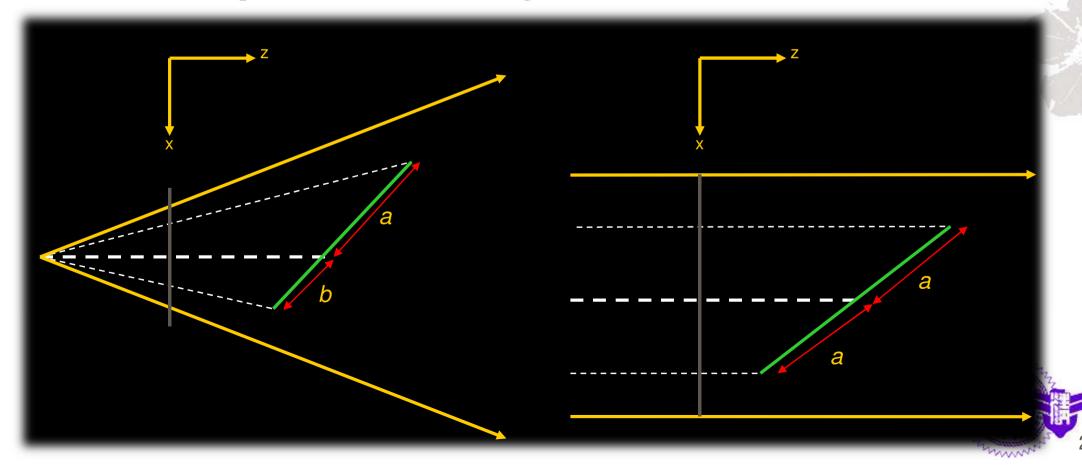
 Linear interpolation for depth in screen space does not hold for depth interpolation in world space under perspective view





Choose of Depth Values

 After perspective transform and normalized into clip space, the depth value can be used to interpolate linearly







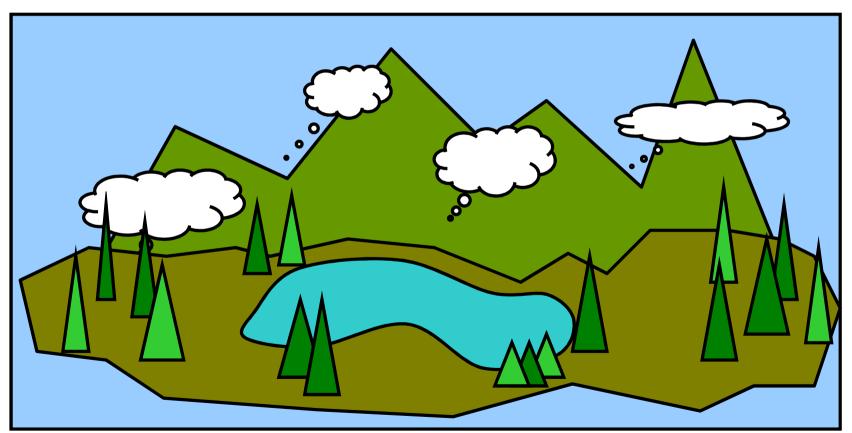


Painter's Algorithm
Binary Space Partition (BSP) Tree
Portal Culling



Painter's Algorithm

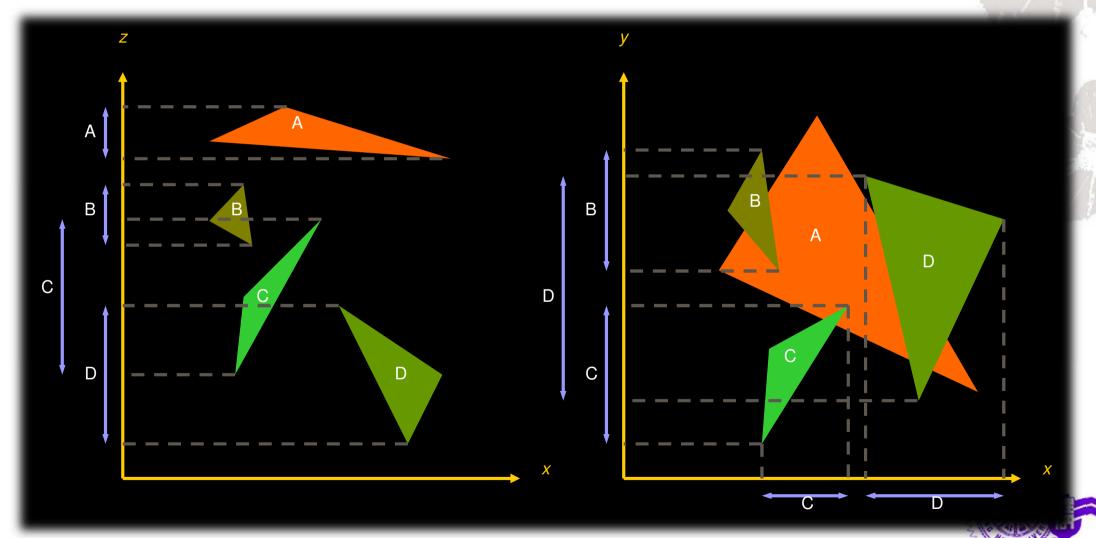
Back-to-Front Rendering





Depth Sort

Sort the polygons in depth order



Difficult Cases

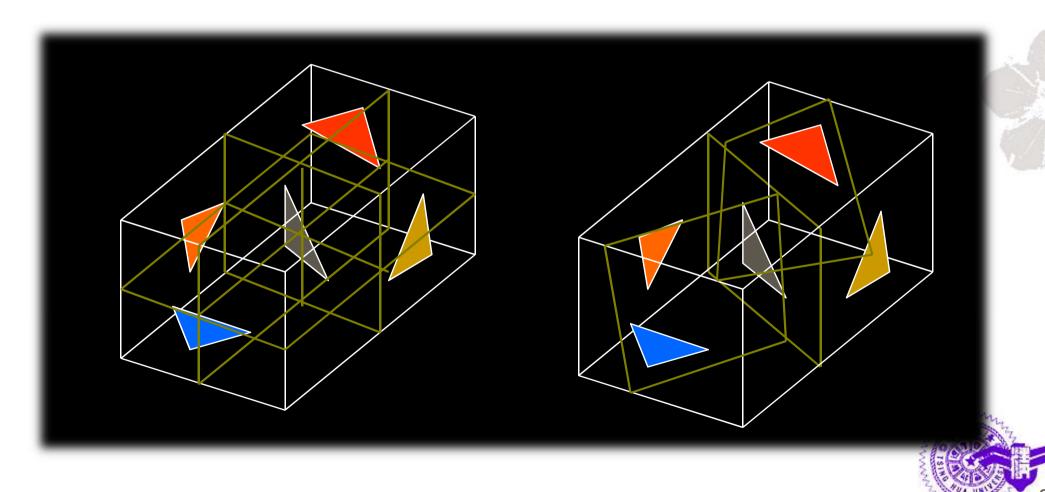
 Might need further subdivision to make it easy to identify the hidden surface





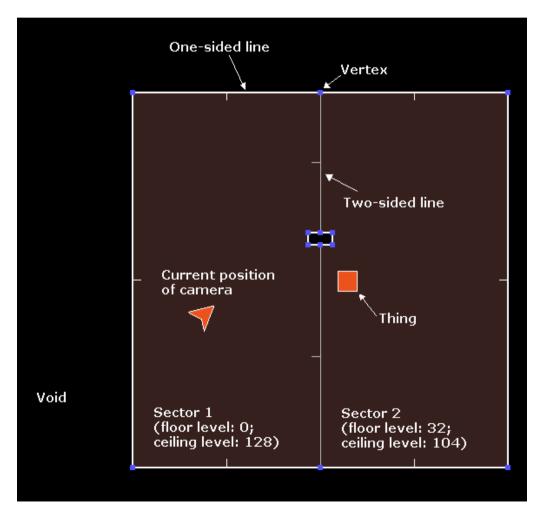
Binary Space Partition Tree

 Axis Aligned Partition vs. Arbitrary Plane Partition



Games using BSP Tree

Doom-like or Quake-like Games

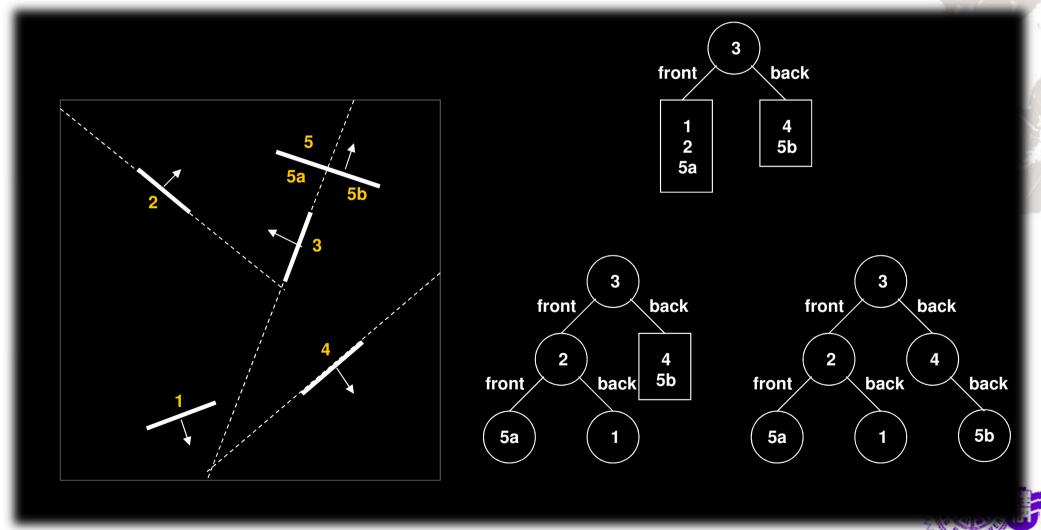






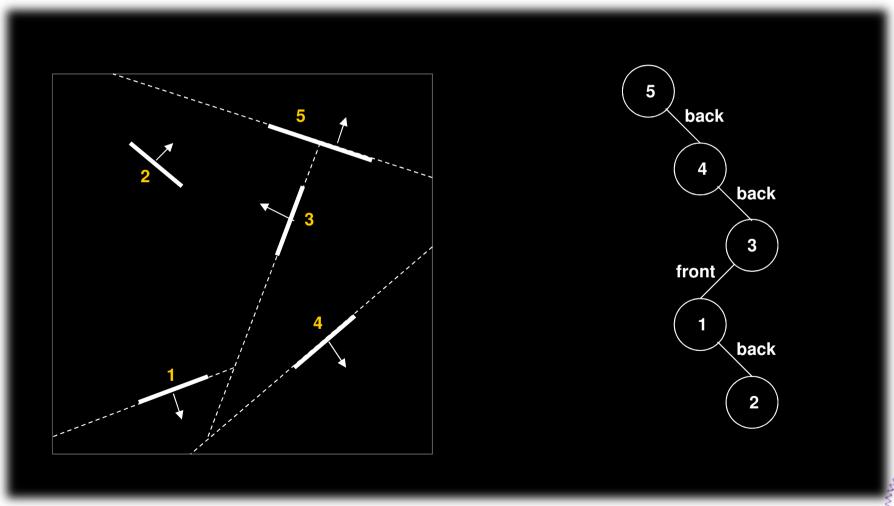
Building a BSP Tree

Balanced Tree



Building a BSP Tree

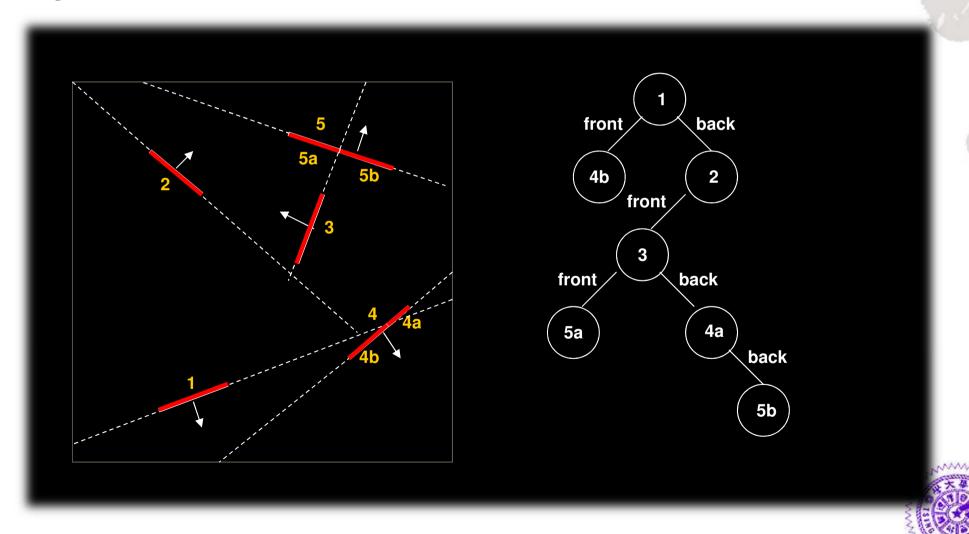
Minimize Splitting





Building a BSP Tree

Dynamic BSP Tree Construction



Back-to-Front Display

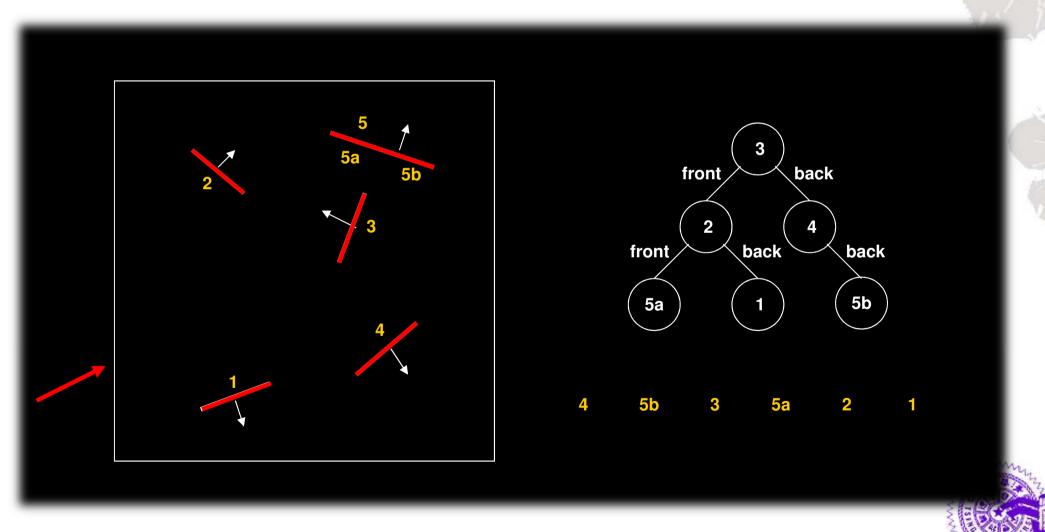
BSP Tree Traversal for Back-to-Front Display

```
BSP Back to Front(Node)
   if (Node == Leaf node)
     Draw(Node)
  else
      if (Viewpoint is in front of the Node)
        BSP Back to Front(Back(Node))
        Draw(Node)
        BSP Back to Front(Front(Node))
     else if (Viewpoint is in back of the Node)
        BSP Back to Front(Front(Node))
        Draw(Node)
        BSP Back to Front(Back(Node))
```



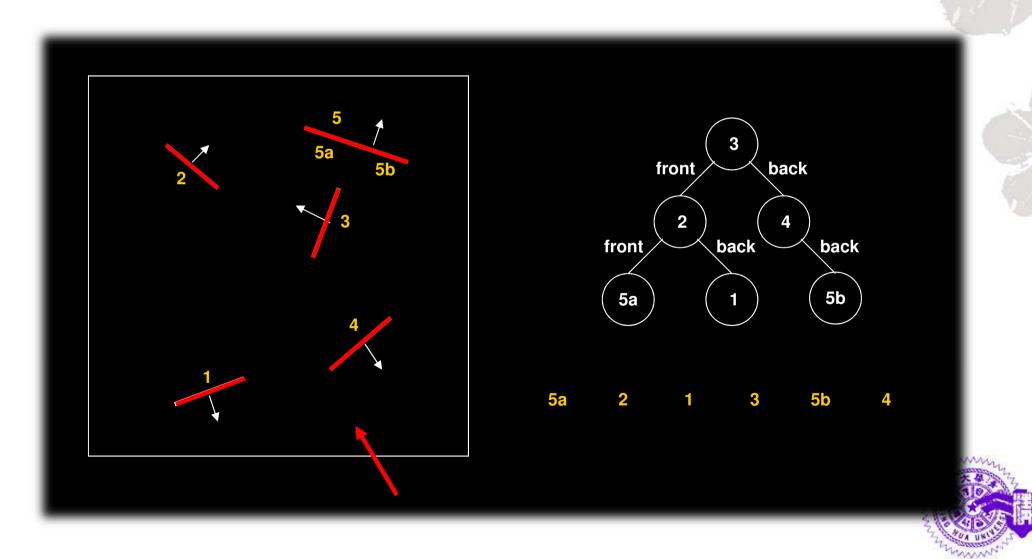
Back-to-Front Display

Painter's Algorithm Approach



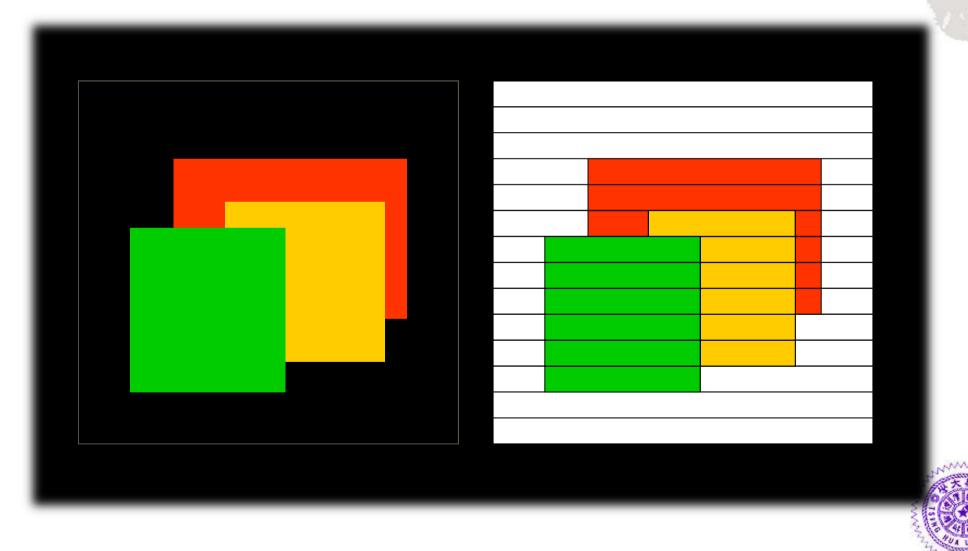
Back-to-Front Display

Painter's Algorithm Approach



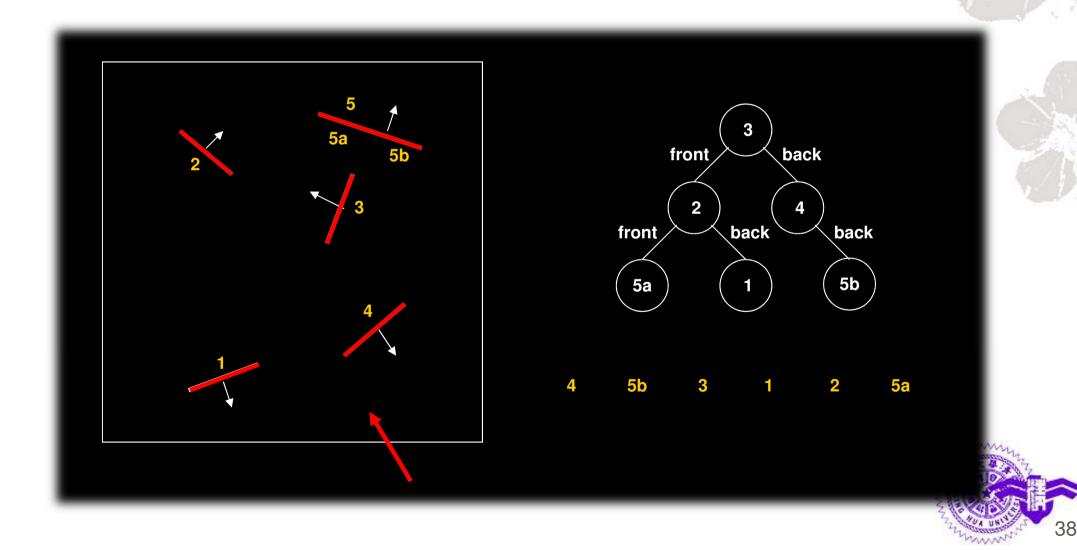
Front-to-Back Display

Scanline Approach



Front-to-Back Display

Scanline Approach



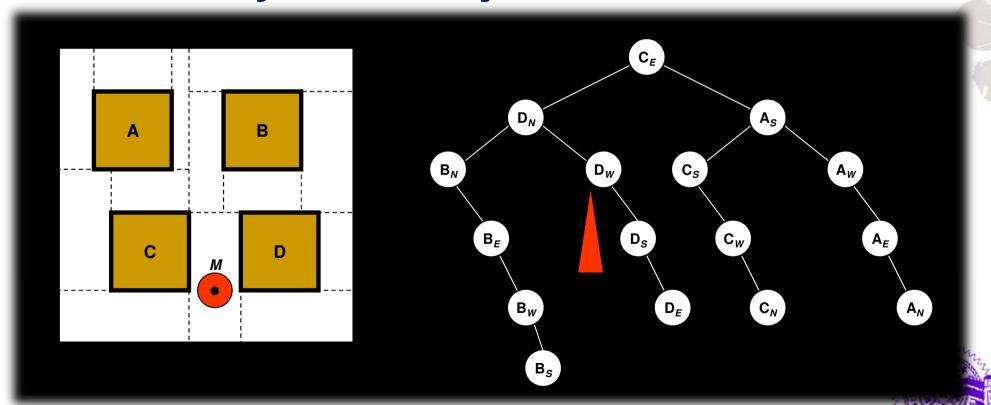
HSR with a BSP Tree

- Back-to-Front Traversal
 - Painter's Algorithm
 - Advantage: No Z buffer is required
 - Disadvantage: Some pixels are over-drawn
- Front-to-Back Traversal
 - Scanline Algorithm
 - Advantage: Only visible pixels are drawn
 - Disadvantage: Need to maintain a dynamic scene data structure to represent pixel masks



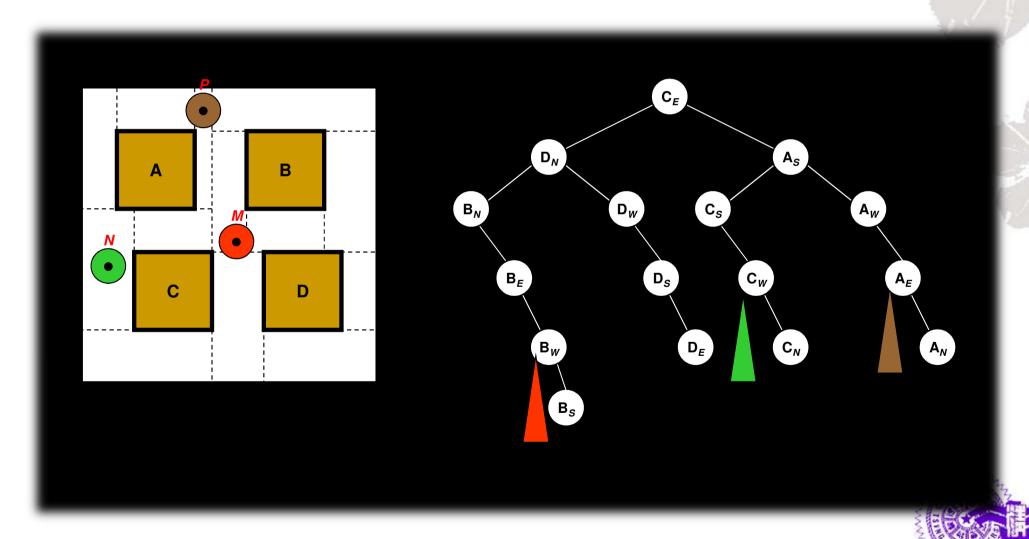
Dynamic Scene with a BSP Tree

- Start with a BSP tree containing all the static objects in the scene
- Insert the dynamic objects into the BSP tree



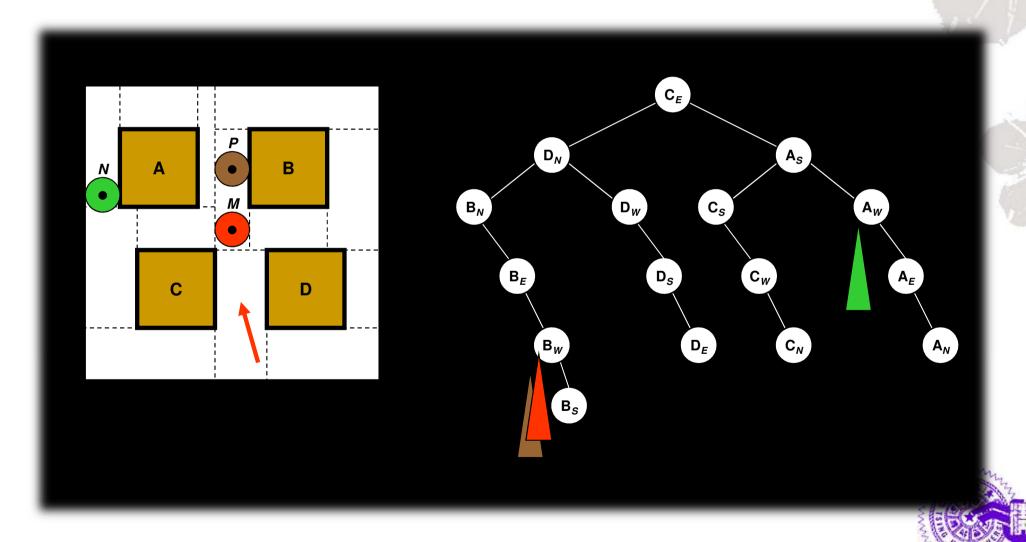
Dynamic Scene with a BSP Tree

Doom/Quake Like Game

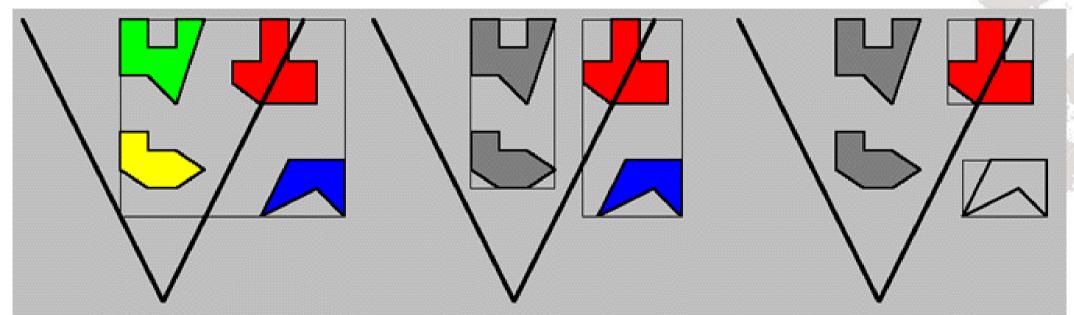


Dynamic Scene with a BSP Tree

Doom/Quake Like Game



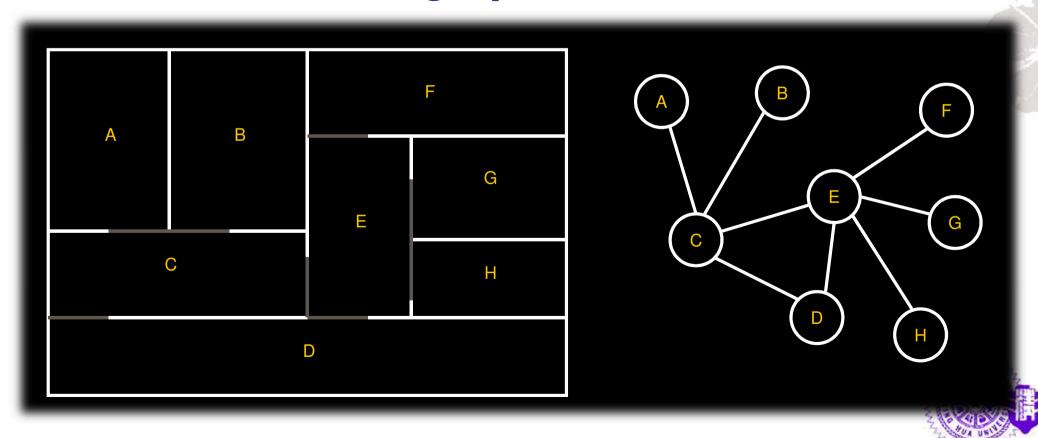
Bounding Volume Hierarchy



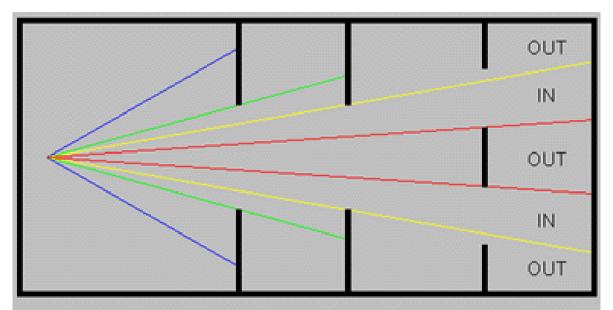
Here we show the progression of overlap tests on a simple three-level bounding-volume hierarchy. The left figure shows the top-level bounding box that encloses the entire scene; it partially overlaps so we must check its children. In the middle figure, the two child boxes are shown; the left box is completely inside so all of the objects it contains are trivially accepted (shown in gray). The right box must be traversed; the process repeats recursively. In the right figure, the lower bounding box is completely outside so its object are trivially rejected (hollowed); the upper box is partially overlapping and does not contain any child boxes, so the individual polygons must be tested for overlap (this step is sometimes omitted and the entire object is just sent to the low-level graphics pipeline).

Portal Culling

 An adjacency graph is built to represent the connections of cells. The connections are established through portals



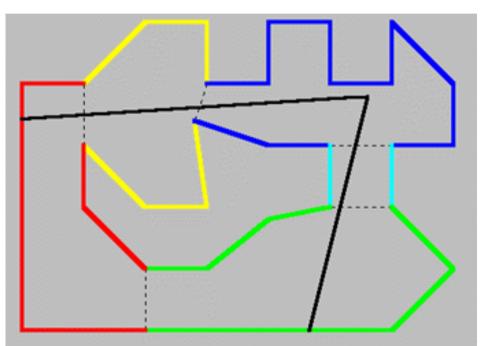
Portal Culling



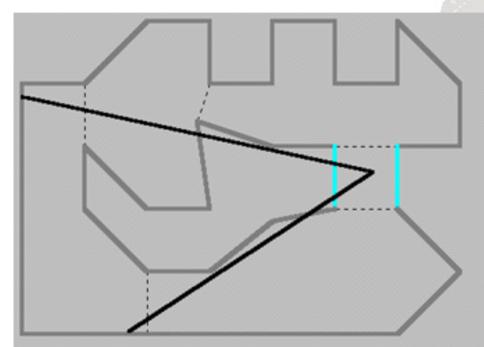
This figures illustrates the recursive nature of cells and portals. Each visible cell has at least one frustum entering it (trivial case is the first cell that contains the viewer). Objects belonging to each cell can be culled against the entering frusta. The viewer's field-of-view is indicated in blue; green lines show the frustum formed through the first portal; yellow lines indicate the second portal frustum; this final frustum is split by the last portal wall into two smaller frusta indicated with the red and yellow lines.



Portal Culling



Here the world is divided into sets of polygons grouped by rooms or cells (different colors) that are separated by doorways or portals (dashed lines). Only cells visible through sequences of portals are drawn. Here there is no advantage since all cells can be seen through the portals; however, if this was used with view-frustum and backface culling we could still reduce the load.

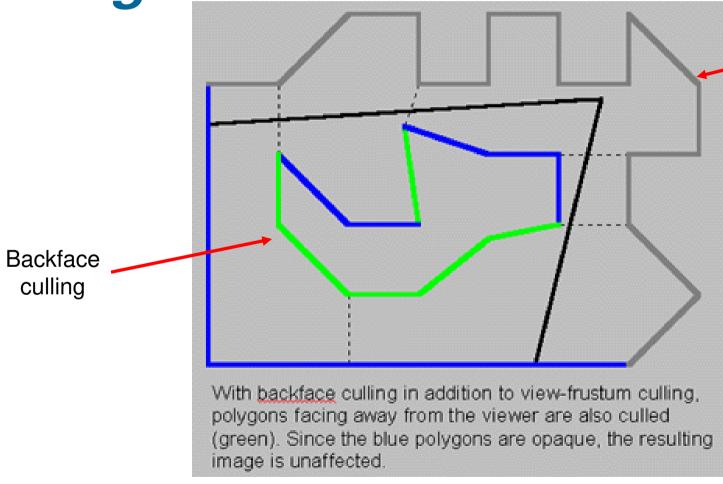


When the viewpoint moves into a cell where long sequences of portals are no longer visible, large portions of the world are culled at a significant fraction of the cost of using other techniques (only two portal overlap tests were required). Clearly, hybrid techniques can cull even more.



View-Frustum Culling with Backface

Culling



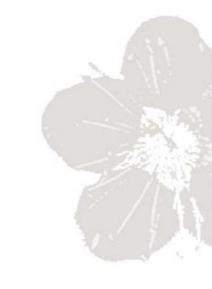
View-frustum culling



Portal Culling Example

◆ Luebke and Georges, I3D 95

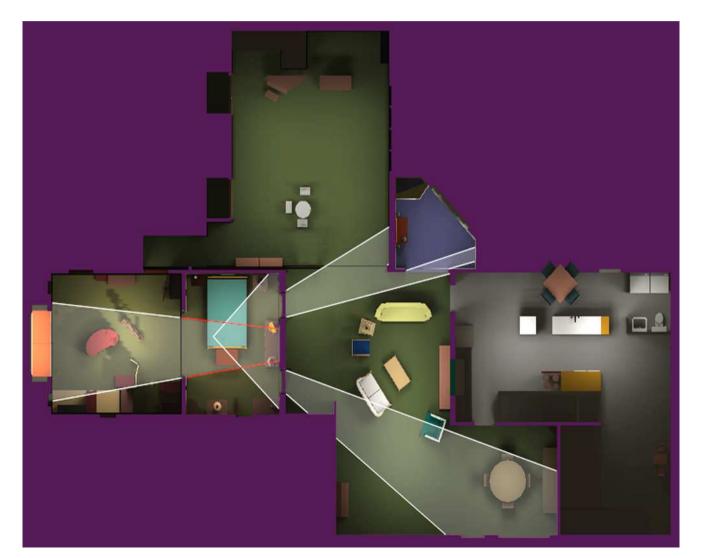


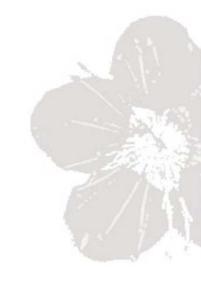






Top view



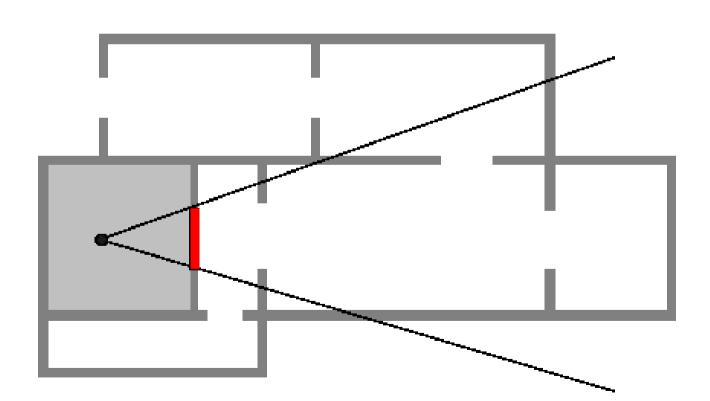




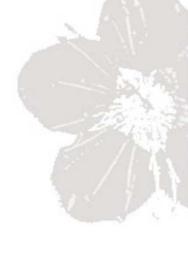


Portal Texture

 Pre-compute portal textures to reduce rendering time during walkthrough



Aliaga and Lastra, IEEE Visualization '97

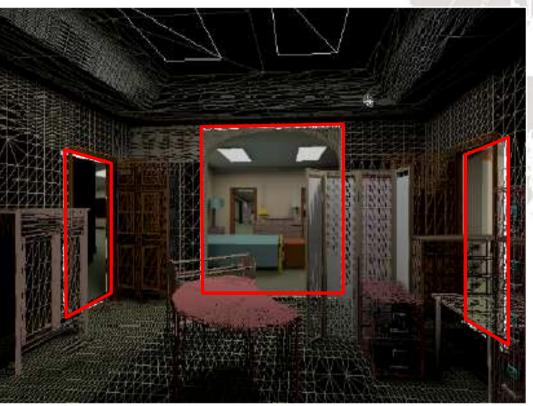






Portal Texture





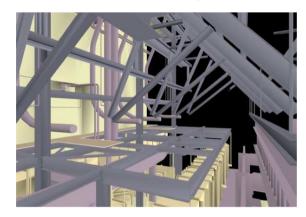
Aliaga and Lastra, *IEEE Visualization '97*



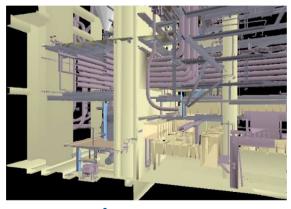
Portal Texture Example



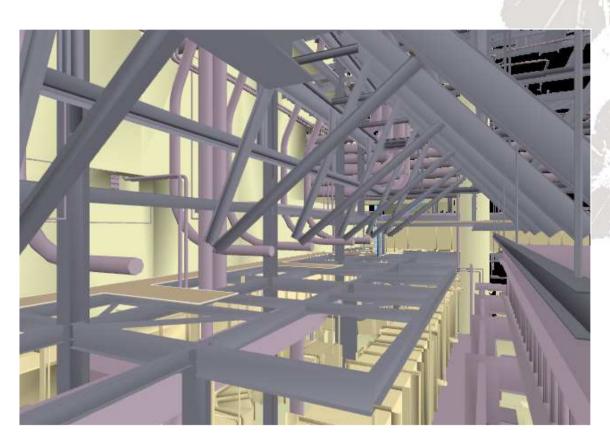
Geometry



+



Image



Final Scene



Q&A



