

# *Computer Graphics*

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**ICL/ITRI**



# *Wrap up from last week*

## ◆ Anti-alias Techniques

- Super sampling
- Multi sampling
- Post processing
- Temporal AA



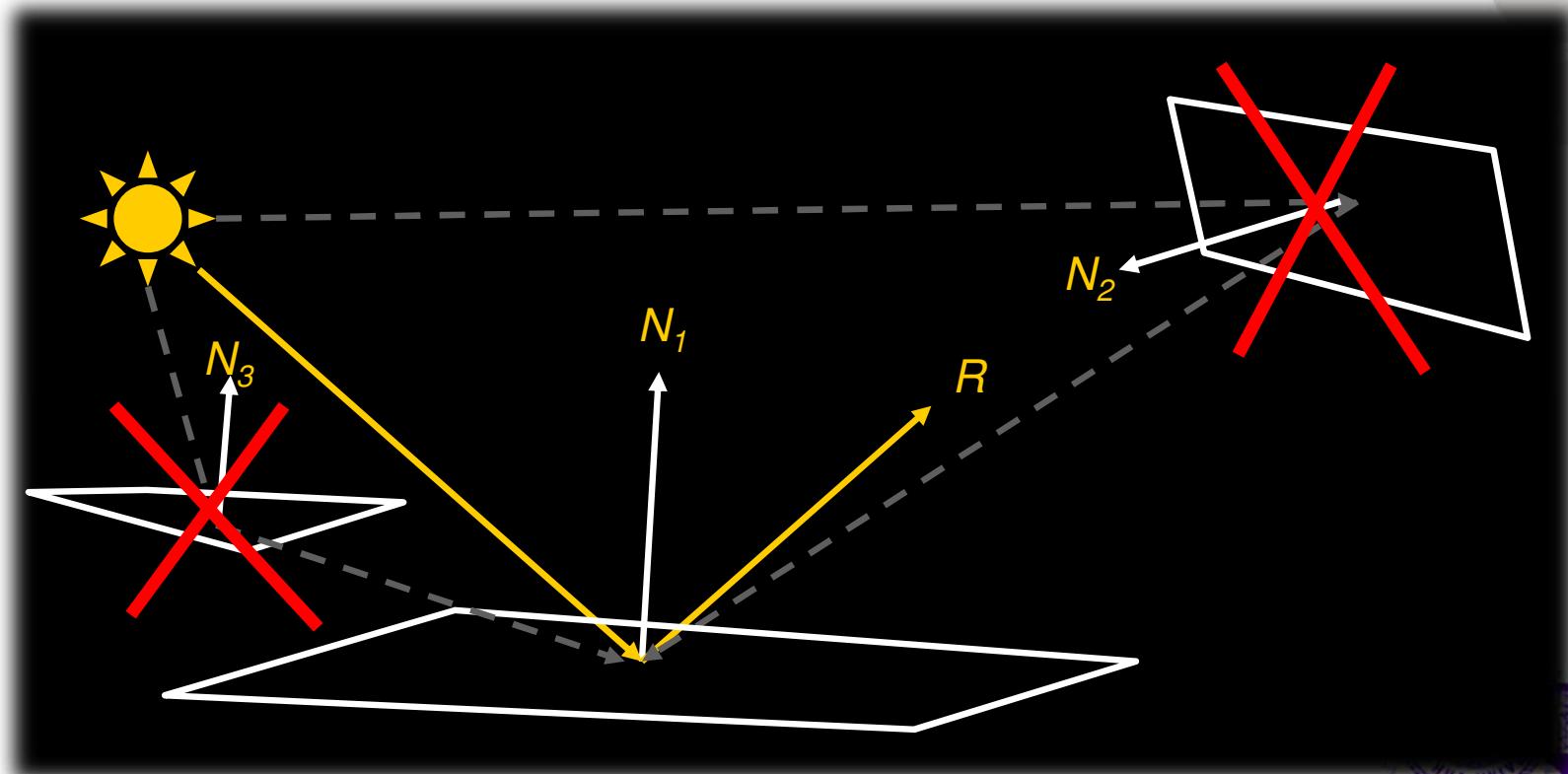
# *Global Illumination*

*Radiosity*  
*Ray Tracing*



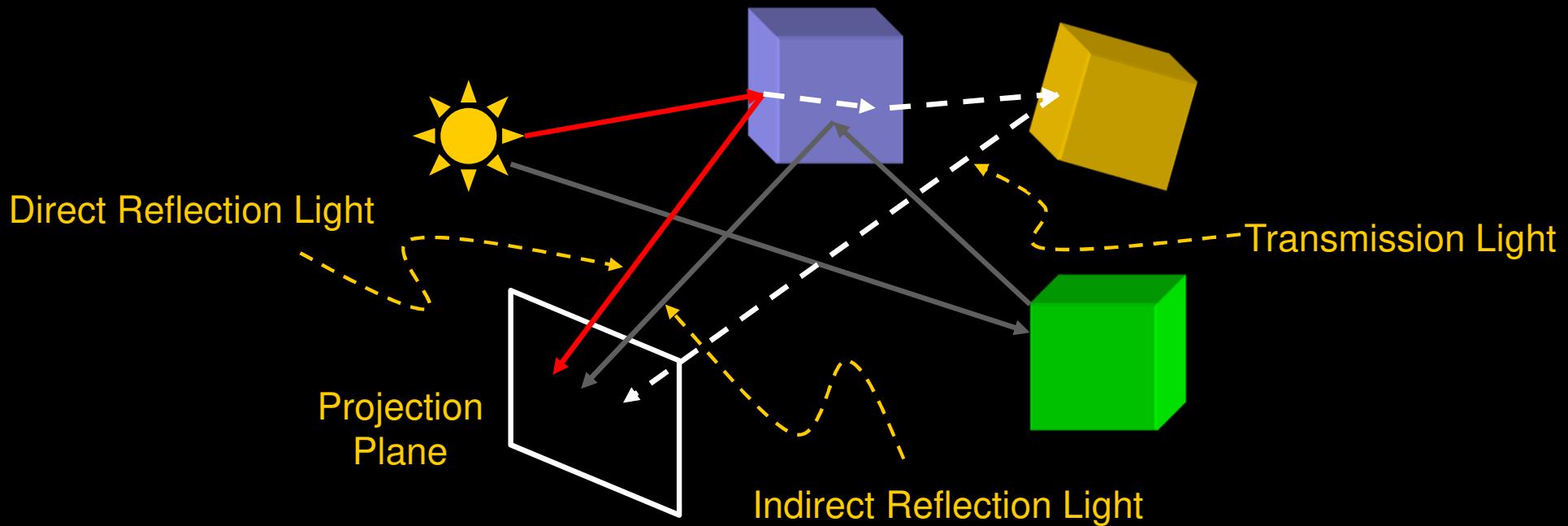
# *Local Illumination*

- ◆ Local illumination counts only light sources directly on the shaded points
- ◆ No inter-reflection, no refraction, no realistic shadow



# *Global Illumination*

- ◆ **Global illumination counts not only the direct light sources, but also the indirect lights. Such as reflection or transmission lights from other objects**



# *Global Illumination*

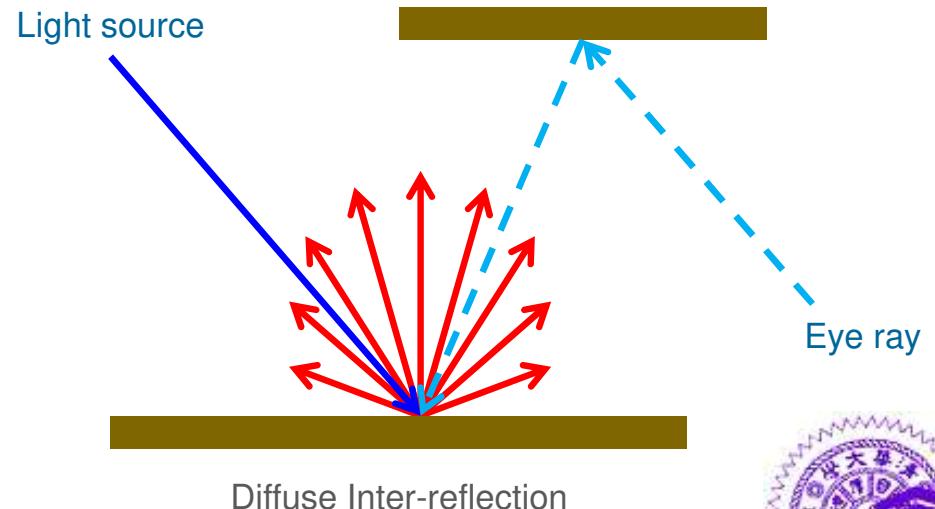
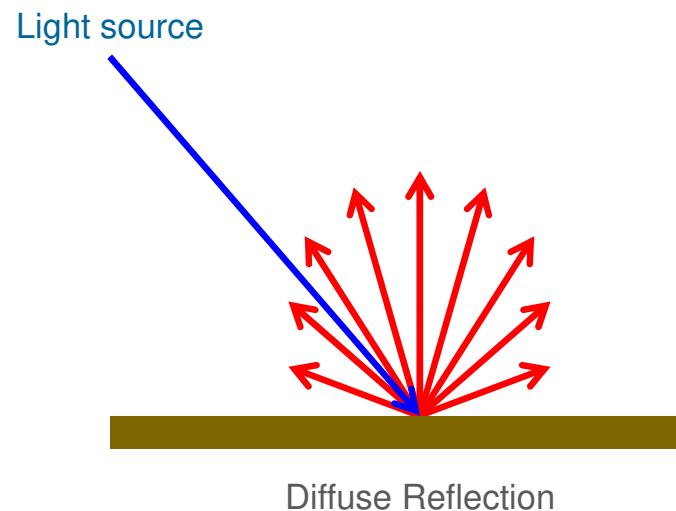
- ◆ **Theoretically, reflections, refractions, and shadows are all examples of global illumination.**
  - One object affects the rendering of another object (as opposed to an object being affected only by a direct light).
- ◆ **In practice, however, only the simulation of diffuse inter-reflection or caustics is called global illumination.**



# *Global Illumination*

## ◆ Diffuse inter-reflection

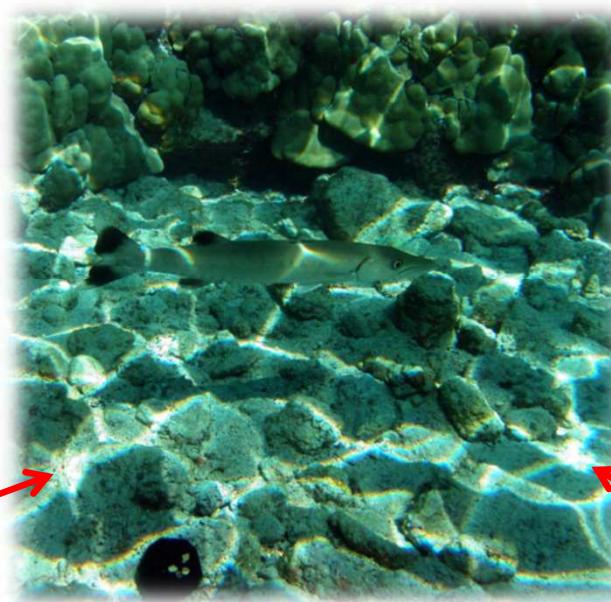
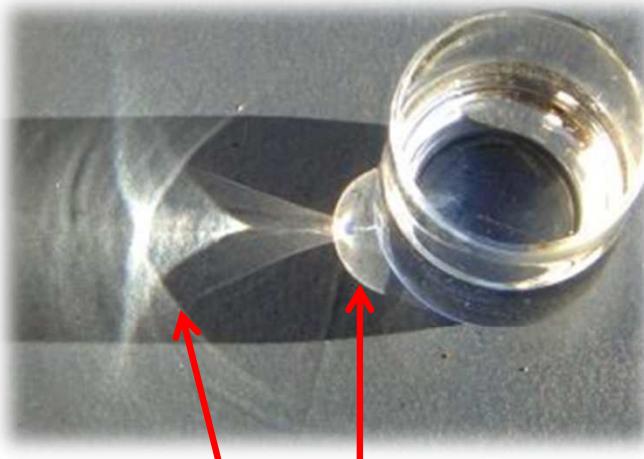
- A process whereby light reflected from an object strikes other objects in the surrounding area and illuminating them
- If the diffuse surface is colored, the reflected light is also colored



# *Global Illumination*

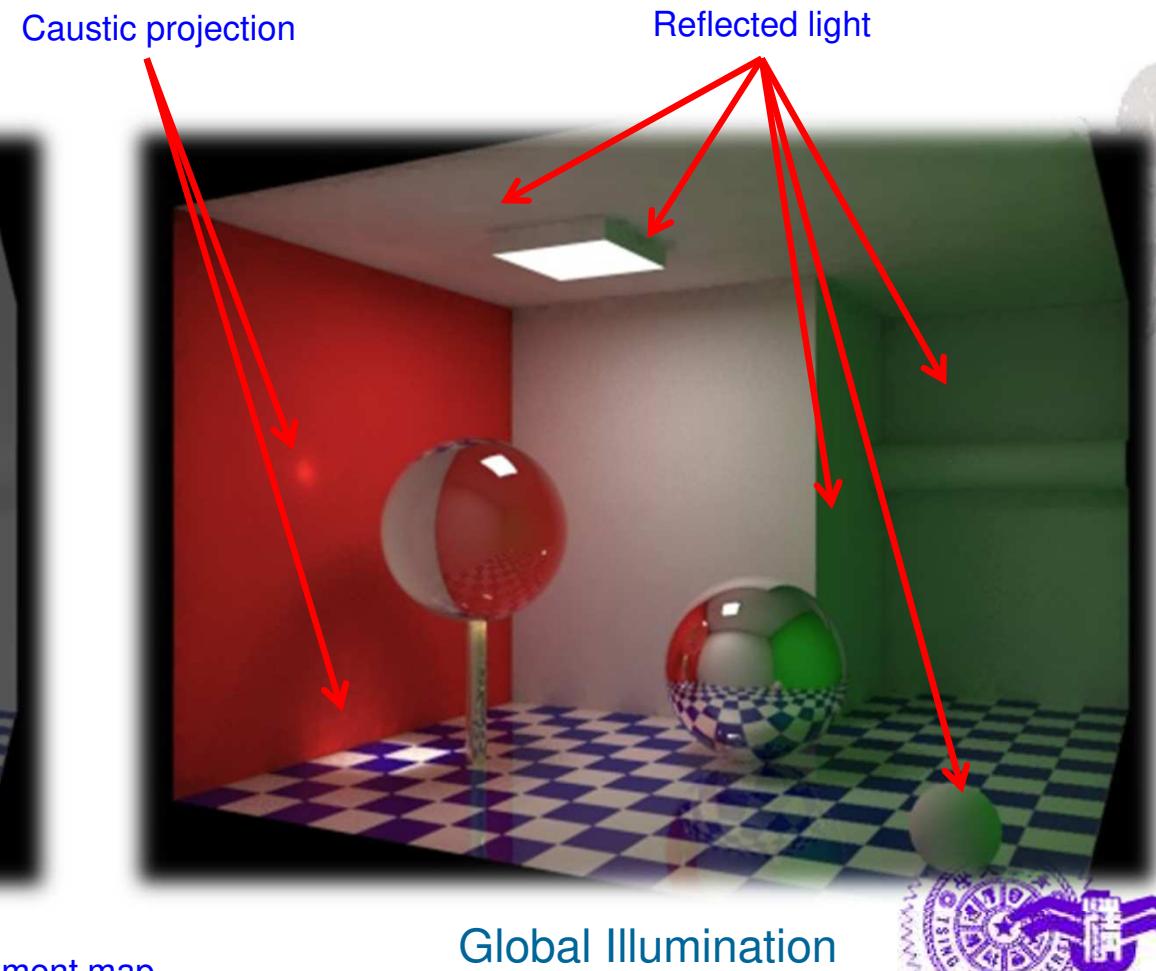
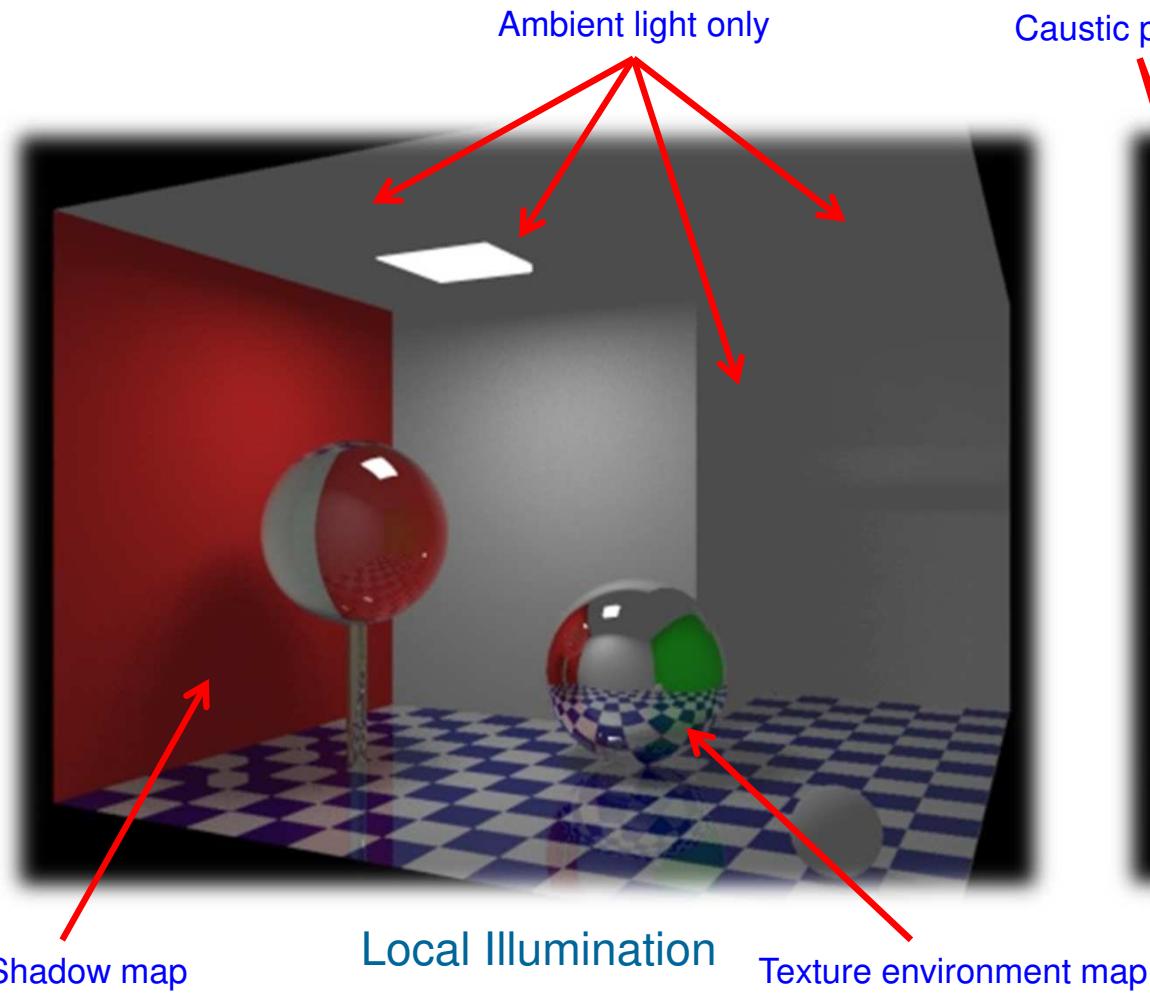
## ◆ Caustic

- A caustic is the envelope of light rays reflected or refracted by a curved surface or object, or the projection of that envelope of rays on another surface.



# *Global vs. Local Illumination*

## ◆ Comparison



# *Examples of Global Illumination*

- ◆ **Radiosity**
- ◆ **Ray tracing**
- ◆ **Beam tracing**
- ◆ **Cone tracing**
- ◆ **Path tracing**
- ◆ **Metropolis light transport**
- ◆ **Ambient occlusion**
- ◆ **Photon mapping**
- ◆ **Image-based lighting**



# *Radiosity*



# *Radiosity*

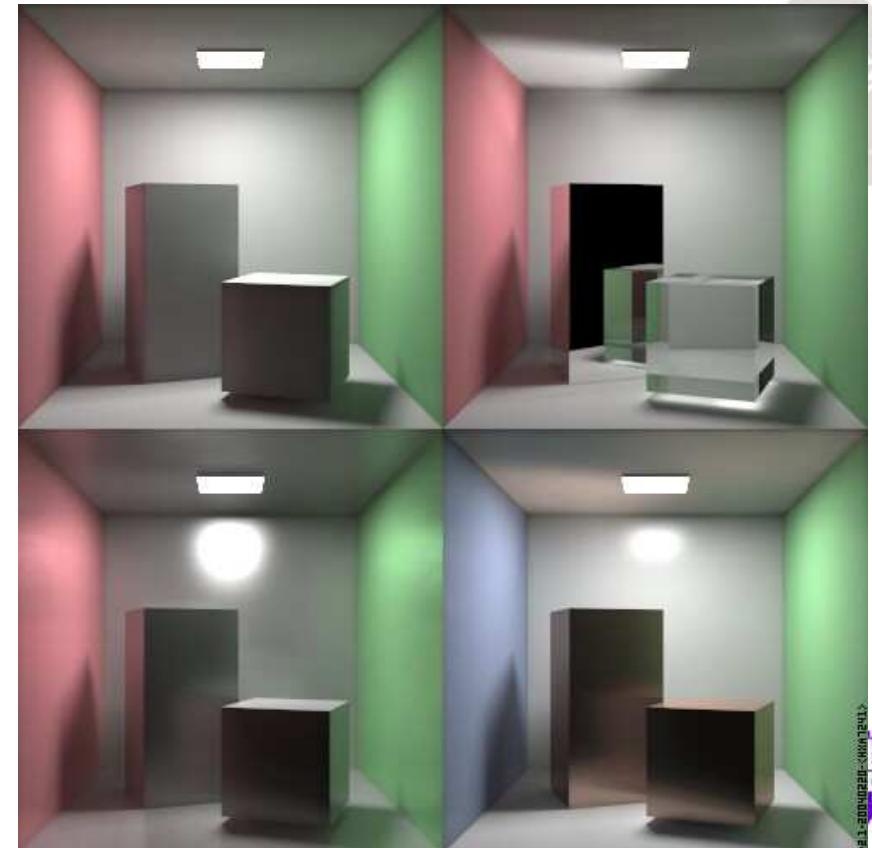
- ◆ The illumination arriving at the eye comes not just from the light sources, but all the scene surfaces interacting with each other as well.



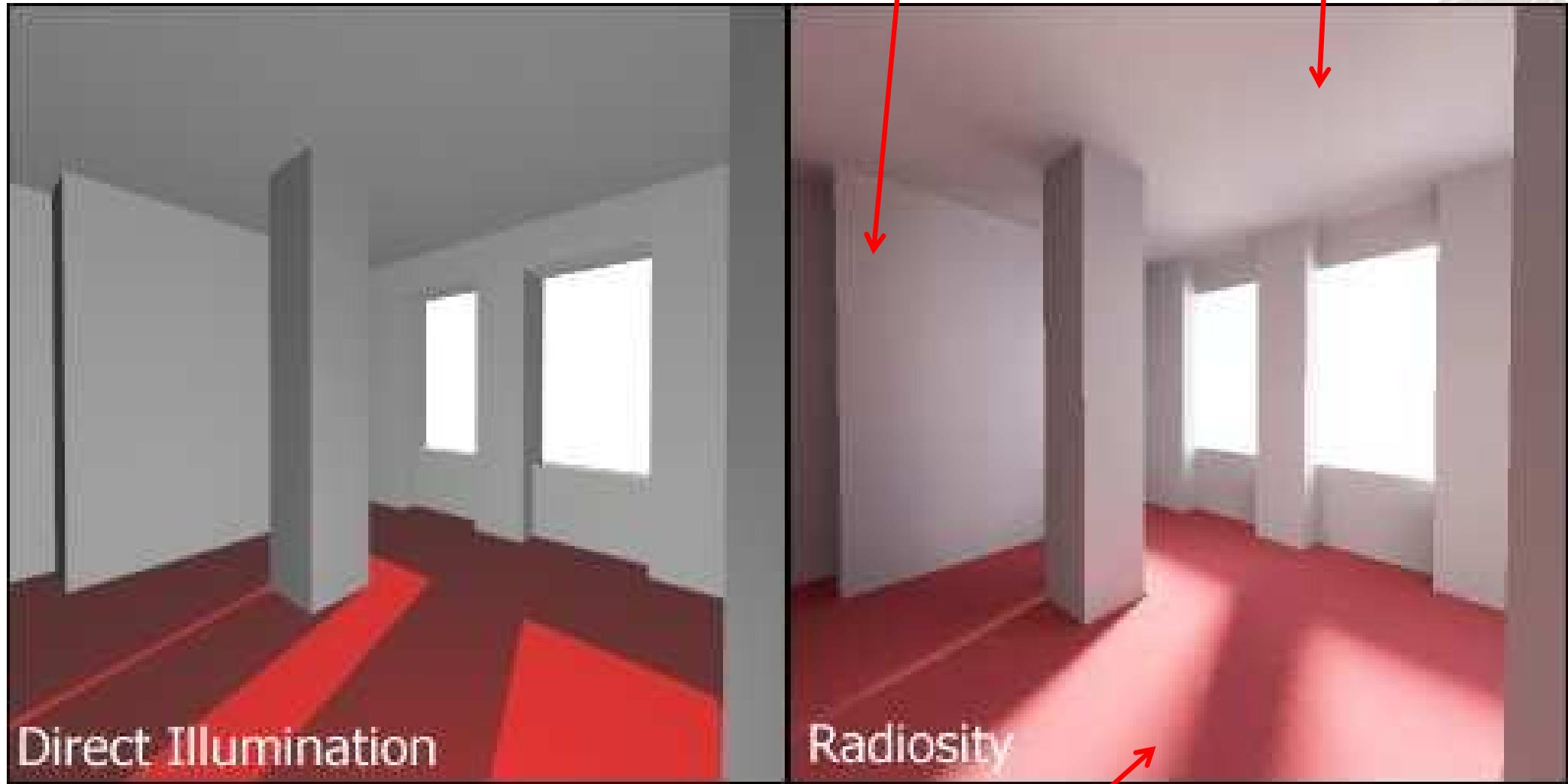
Variation



The Cornell Box



# Radiosity



# *Radiosity*

- ◆ The radiosity of a surface is the rate at which energy leaves that surface
- ◆ It includes the energy emitted by a surface as well as the energy reflected from other surfaces
- ◆ Radiosity methods allow the intensity of radiant energy arriving at a surface to be computed. These intensities can then be used to determine the shading of the surface.



# Form Factor (View Factor)

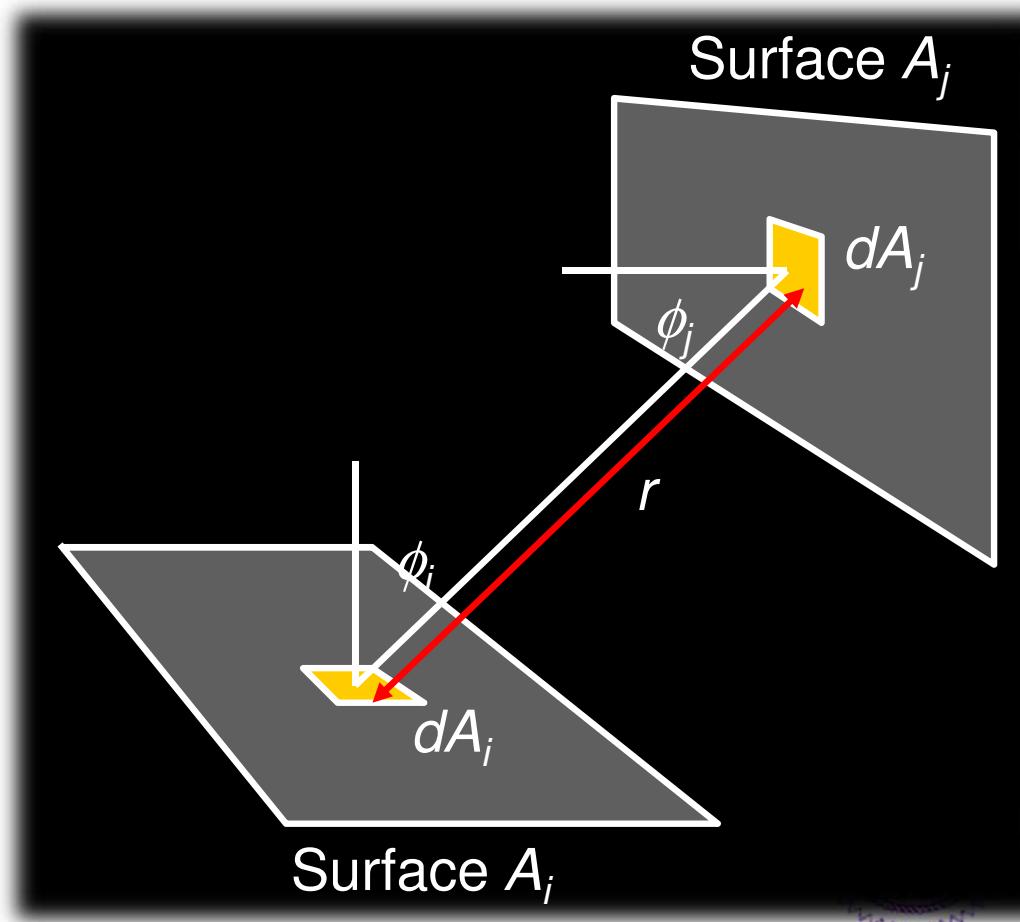
- The form factor is defined as the fraction of energy leaving one surface that reaches another surface

Form factor:  $dA_j \rightarrow dA_i$

$$F_{ij} = \frac{\cos \phi_i \cos \phi_j}{\pi |r|^2} dA_j$$

Form factor:  $A_j \rightarrow A_i$

$$F_{ij} = \frac{1}{A_i} \int_{A_i} \int_{A_j} \frac{\cos \phi_i \cos \phi_j}{\pi |r|^2} dA_j dA_i$$



# The Radiosity Equation

$$B_i = E_i + \rho_i \sum B_j F_{ij}$$

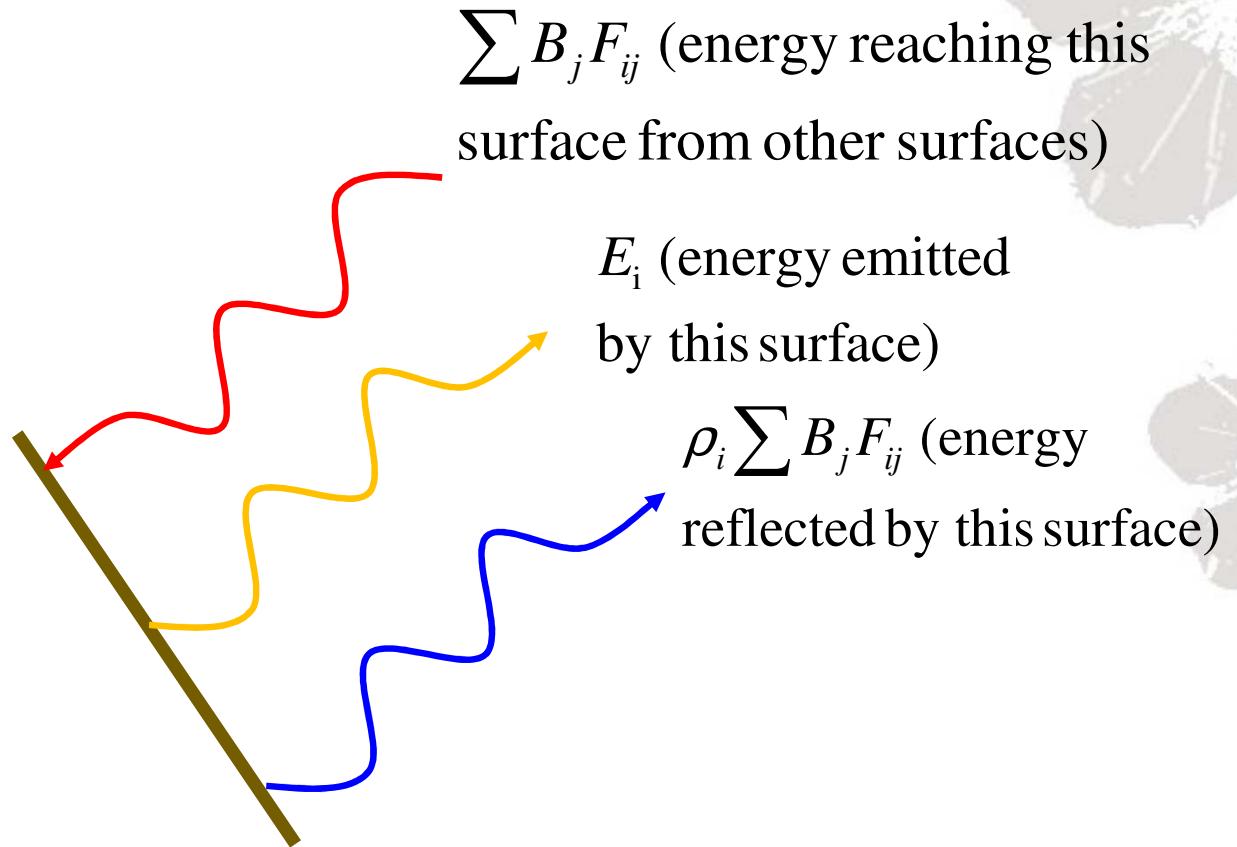
$B_i$  = Radiosity of surface  $i$

$E_i$  = Emissivity of surface  $i$

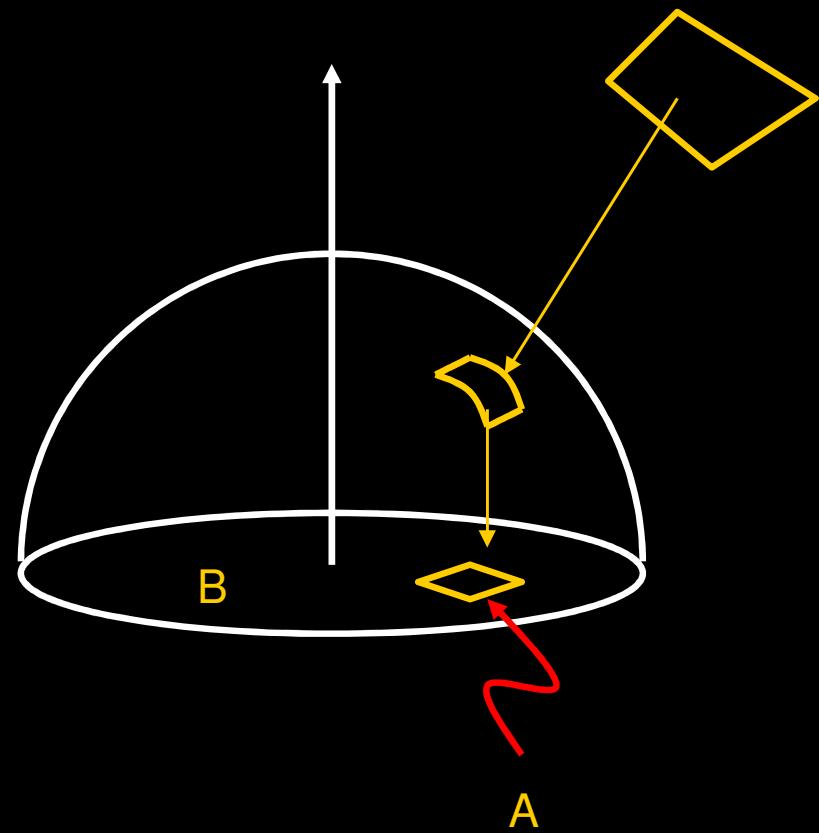
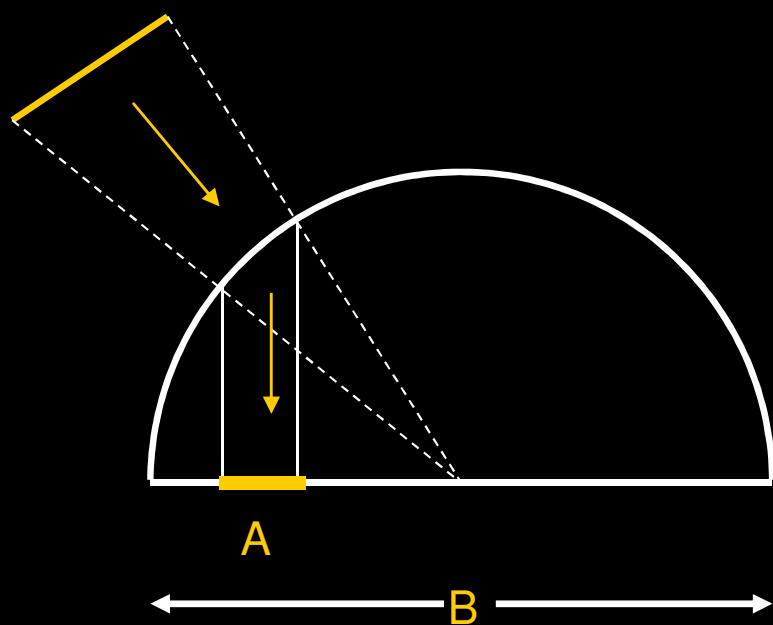
$\rho_i$  = Reflectivity of surface  $i$

$B_j$  = Radiosity of surface  $j$

$F_{ij}$  = Form Factor for the radiation leaving surface  $j$  and hitting surface  $i$

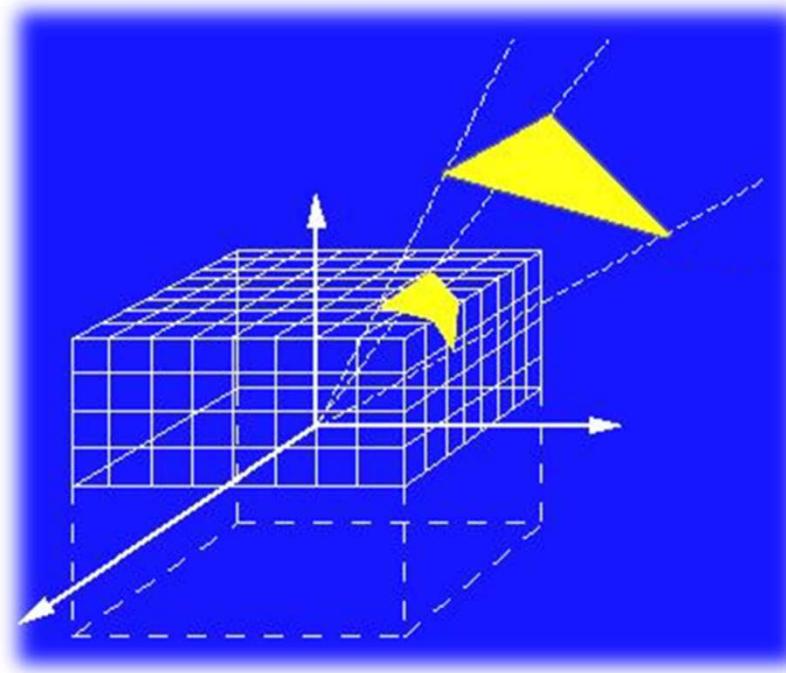


# Hemisphere

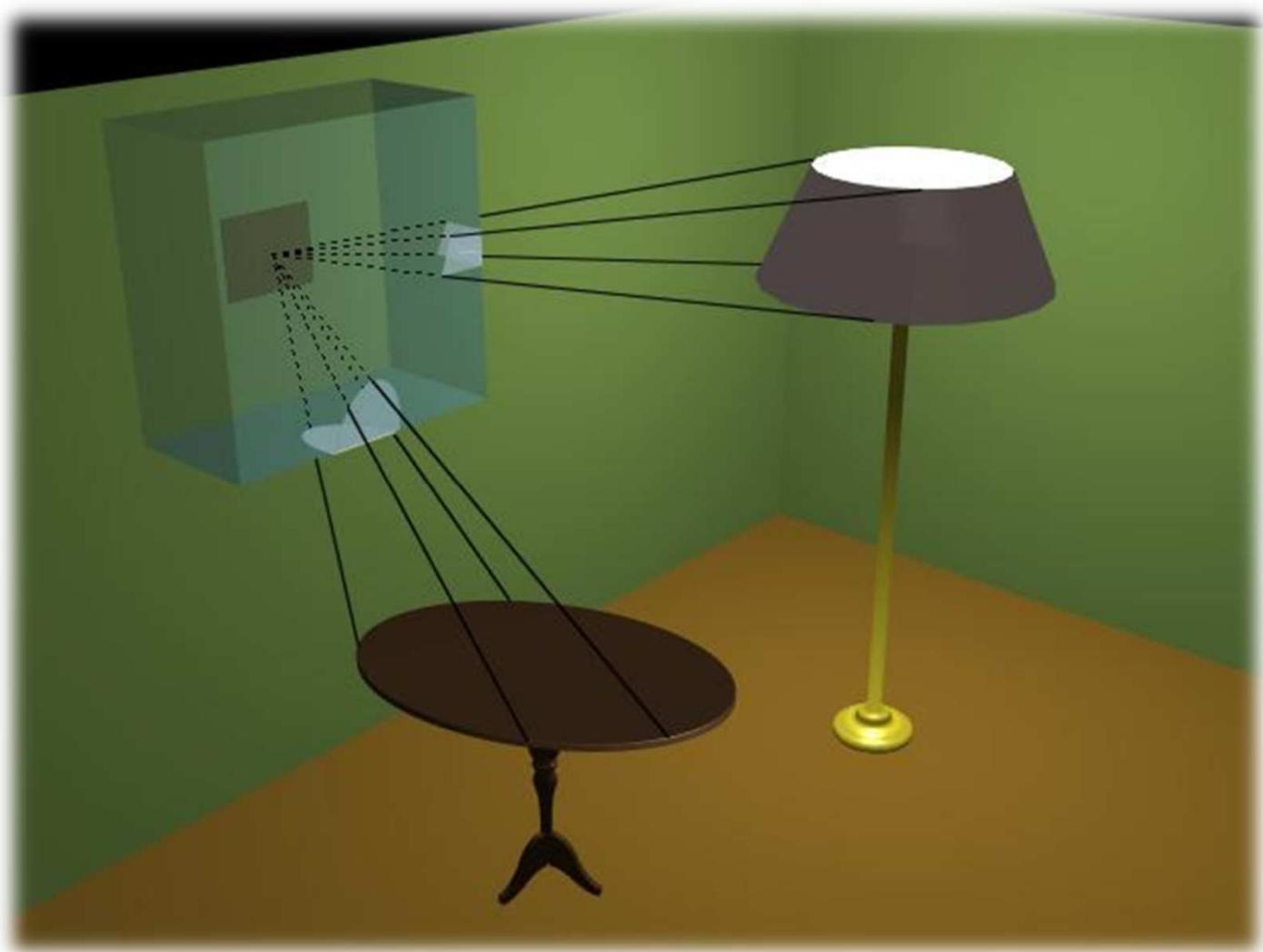


# *Hemicube Approximation*

- ◆ Project each patches onto the hemicube
- ◆ Each pixel has pre-computed form factor
- ◆ The form factor is the sum of the pixels it overlaps



# *Hemicube Approximation*



# *Resolving Radiosity Equation*

## ◆ Solving Full Matrix

$$\begin{bmatrix} 1 - \rho_1 F_{11} & -\rho_1 F_{12} & \cdots & -\rho_1 F_{1n} \\ -\rho_2 F_{21} & 1 - \rho_2 F_{22} & \cdots & -\rho_2 F_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ -\rho_n F_{n1} & -\rho_n F_{n2} & \cdots & 1 - \rho_n F_{nn} \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \\ \vdots \\ B_n \end{bmatrix} = \begin{bmatrix} E_1 \\ E_2 \\ \vdots \\ E_n \end{bmatrix}$$

$\rho_i$  is the reflectivity of surface  $i$

$F_{ij}$  is the form factor from surface  $j$  to surface  $i$

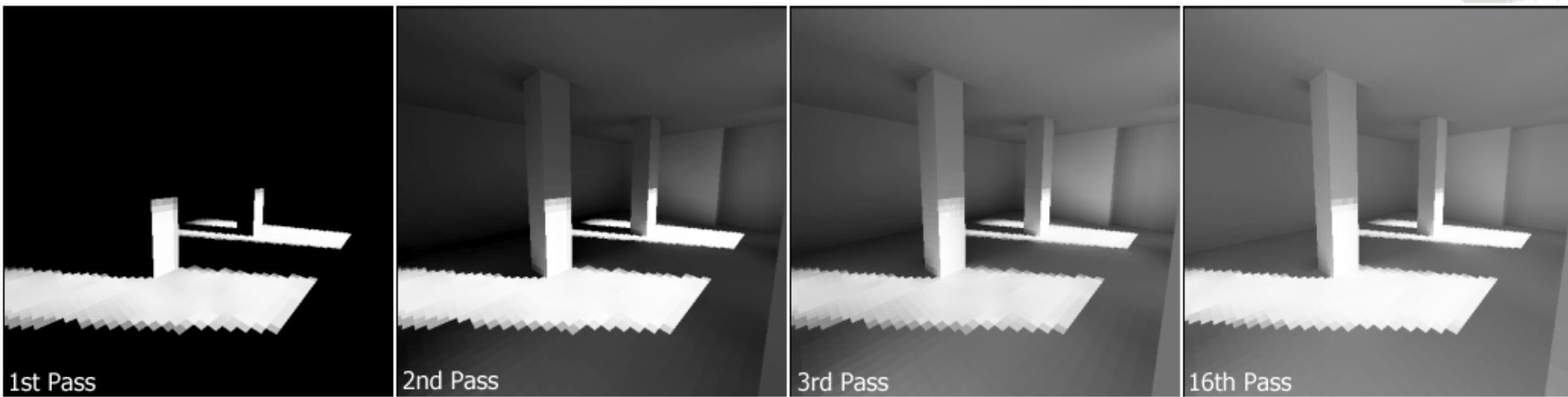
$B_i$  is the radiosity of surface  $i$

$E_i$  is the emission of surface  $i$



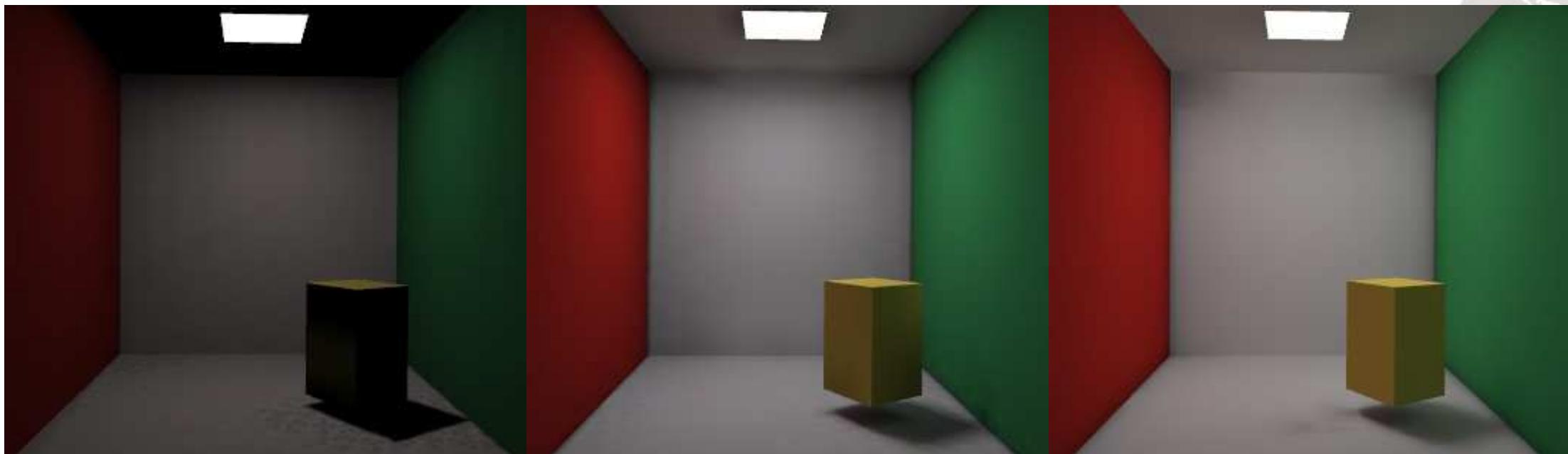
# *Iterations of Radiosity Algorithm*

- ◆ Iteratively solves the radiosity equation by "shooting" light from the patch with the most error at each step



# *Iterations of Radiosity Algorithm*

- ◆ Iteratively solves the radiosity equation by "shooting" light from the patch with the most error at each step



1 iteration

32 iterations

320 iterations



# *Progressive Solution*



## **PROGRESSIVE SOLUTION**

The above images show increasing levels of global diffuse illumination. From left to right: 0 bounces, 1 bounce, 3 bounces.

# *Characteristic of Radiosity*

- ◆ An object space algorithm
- ◆ View independent (can be pre-computed)
- ◆ Render perfect diffuse scenes
- ◆ Area light sources (polygonal patches)
- ◆ Ideas came from the conservation of energy



# Ray Tracing



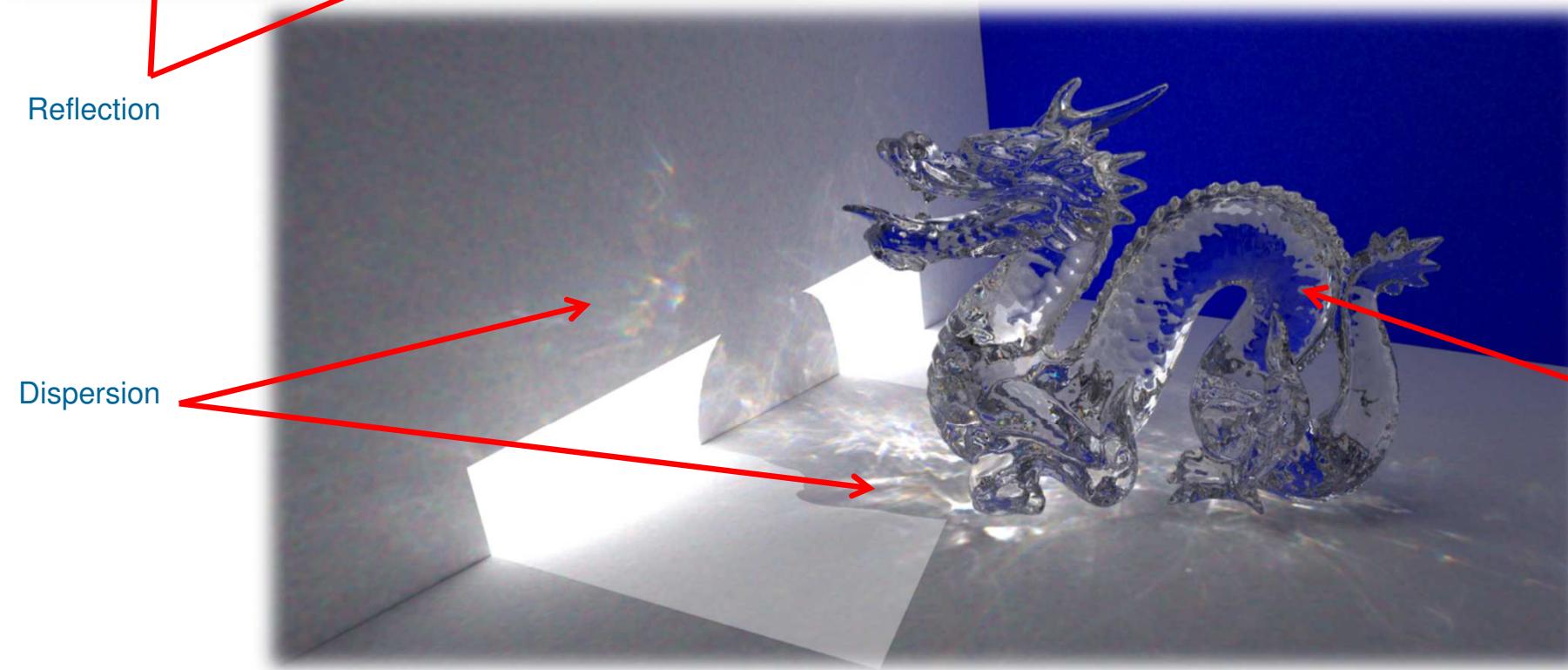
Reflection



MARBLE

JADE

WAX



Dispersion

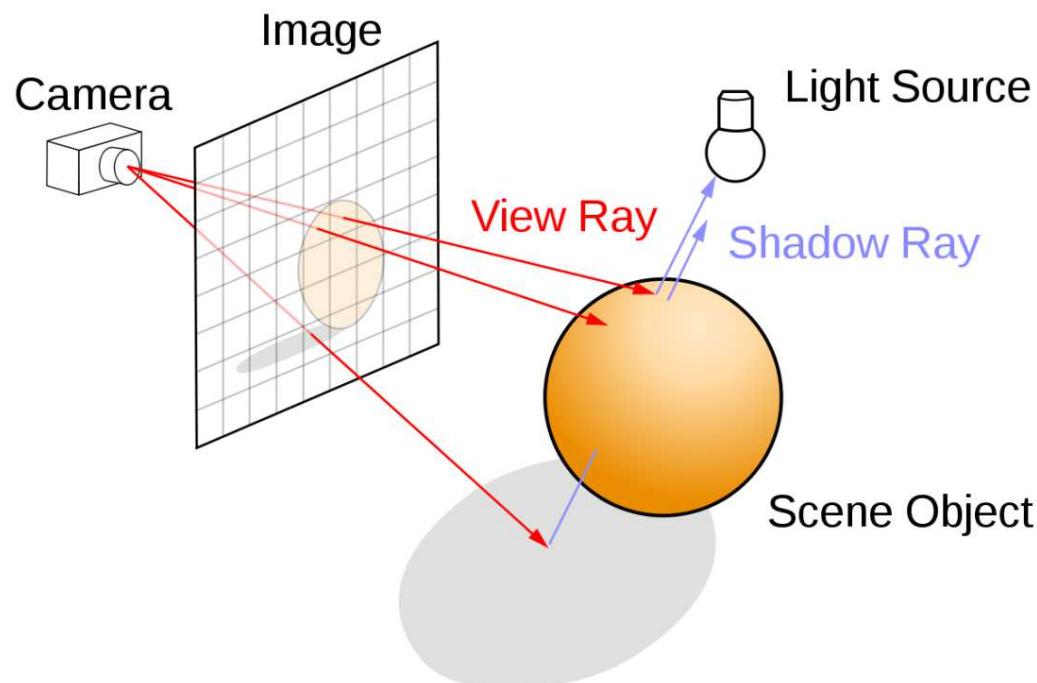
Refraction

Scattering



# Ray Tracing

- ◆ A technique for generating an image by tracing the path of light through pixels in an image plane and simulating the effects of its encounters with virtual objects.



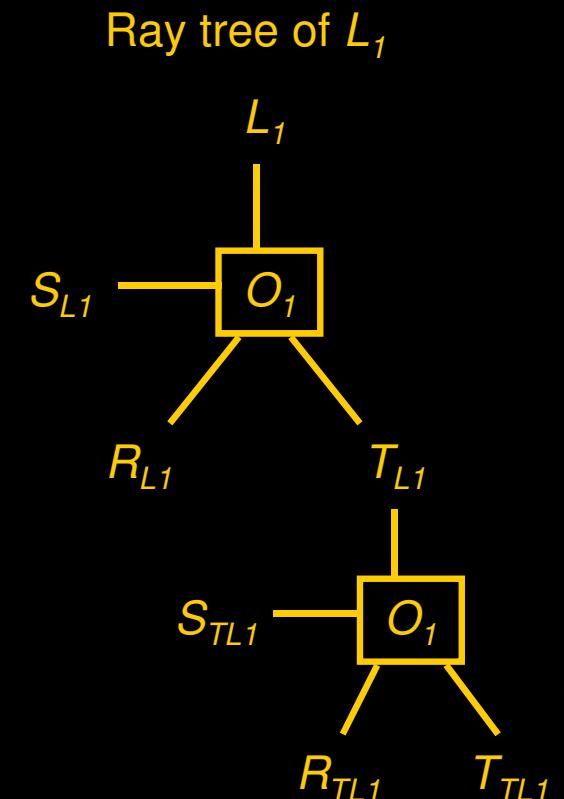
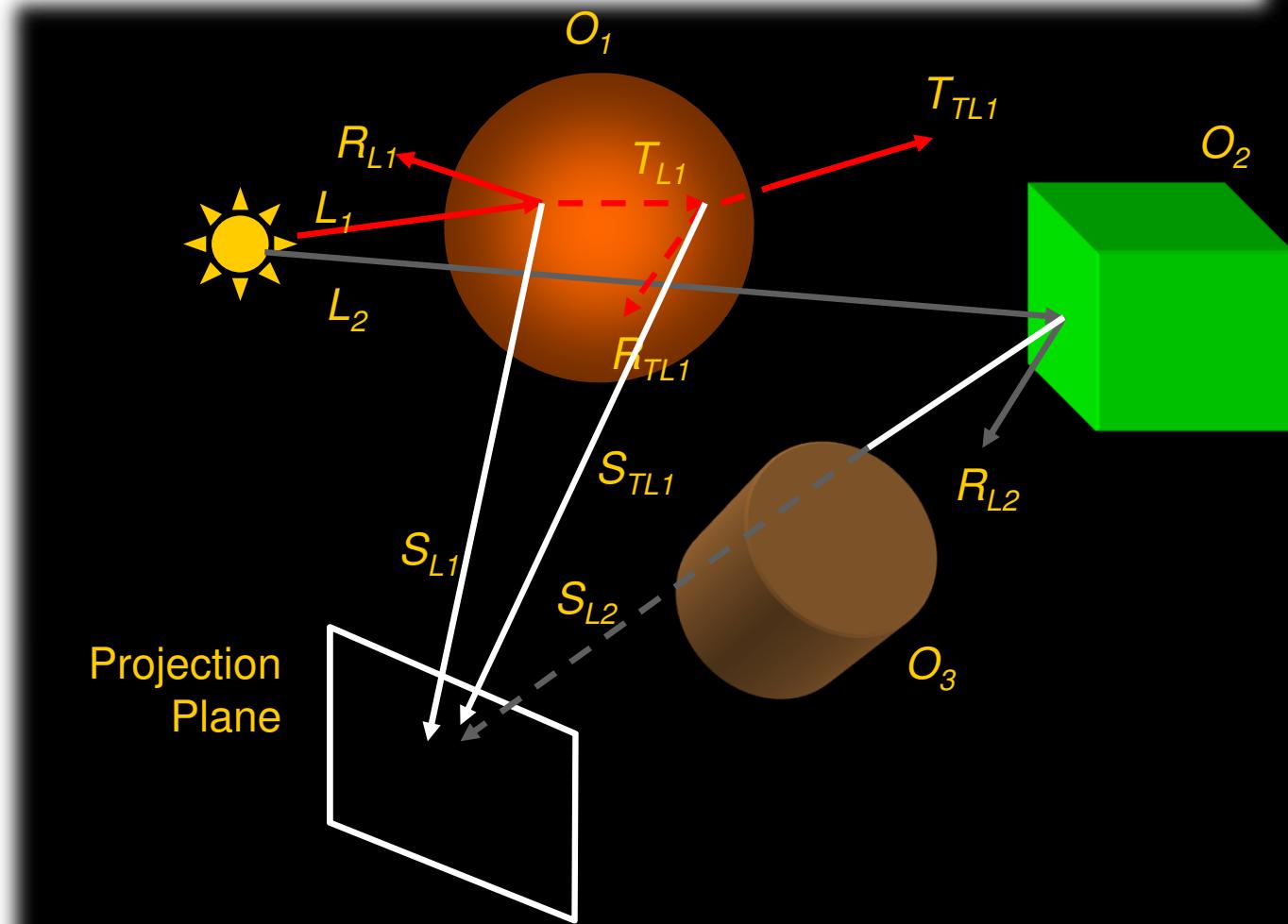
# *Forward Ray Tracing*

- ◆ Light rays (primary rays) emitted from light sources
- ◆ Secondary rays including a shadow ray, a reflection ray, and a refraction ray (if translucent object) are generated for each light-object intersection
- ◆ Shadow ray is used to check whether the intersection point is illuminated or in shadow
- ◆ Reflection and refraction rays are traced recursively as if they are new light rays



# Forward Ray Tracing

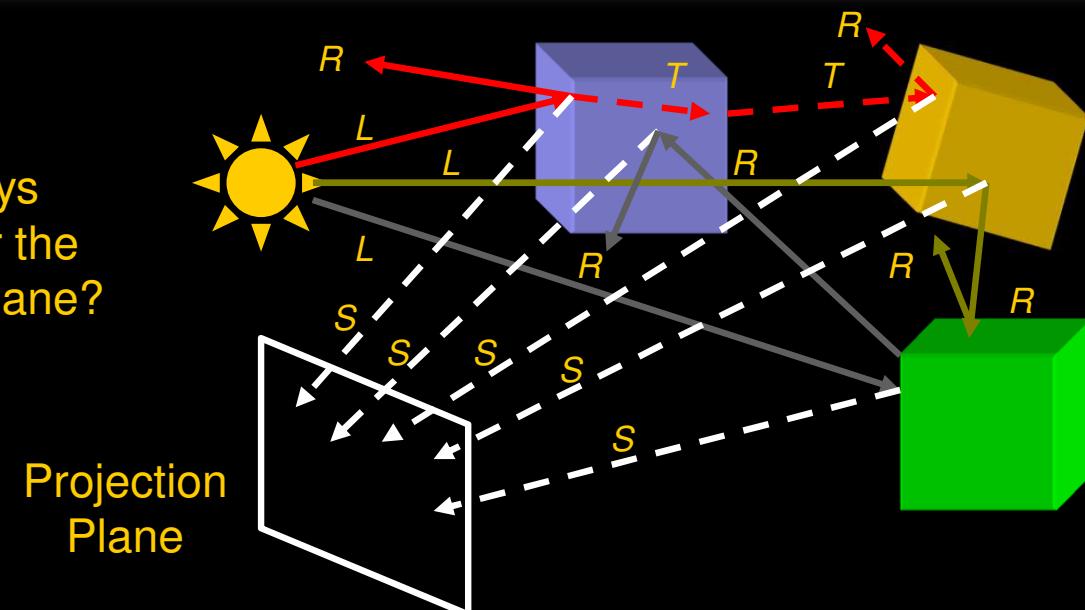
## ◆ Ray classification



# Forward Ray Tracing

- ◆ Trace light rays emitted from light sources
- ◆ Light rays bounced between objects in scene
- ◆ Accumulate the contribution of each light rays if they hit the projection plane

How many light rays  
is enough to cover the  
entire projection plane?



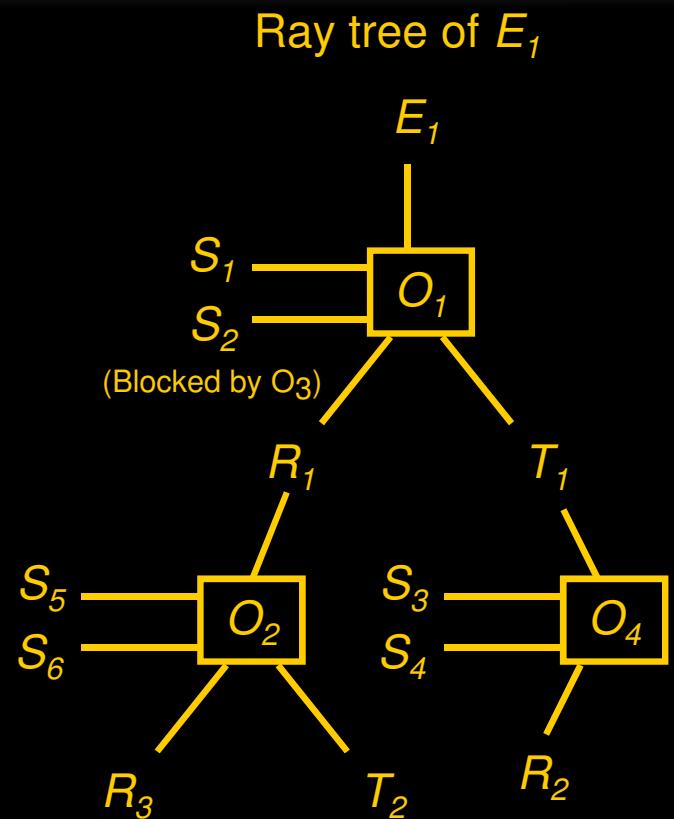
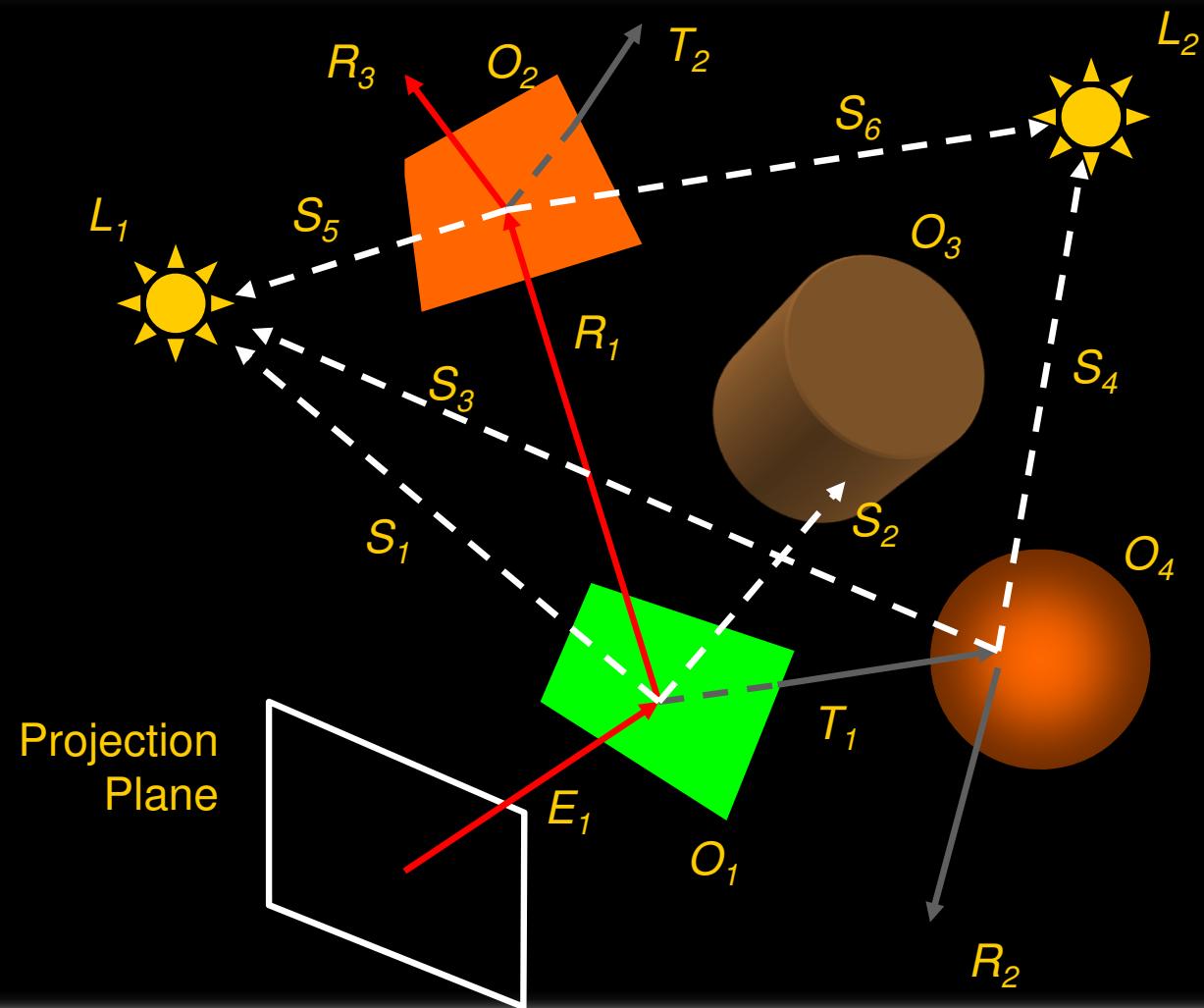
# *Backward Ray Tracing*

- ◆ Eye rays (primary rays) emitted from each pixel of projection plane
- ◆ Secondary rays including a shadow ray, a reflection ray, and a refraction ray (if translucent object) are generated for each ray-object intersection
- ◆ Shadow ray is used to check whether the intersection point is illuminated or in shadow
- ◆ Reflection and refraction rays are traced recursively as if they are new eye rays



# Backward Ray Tracing

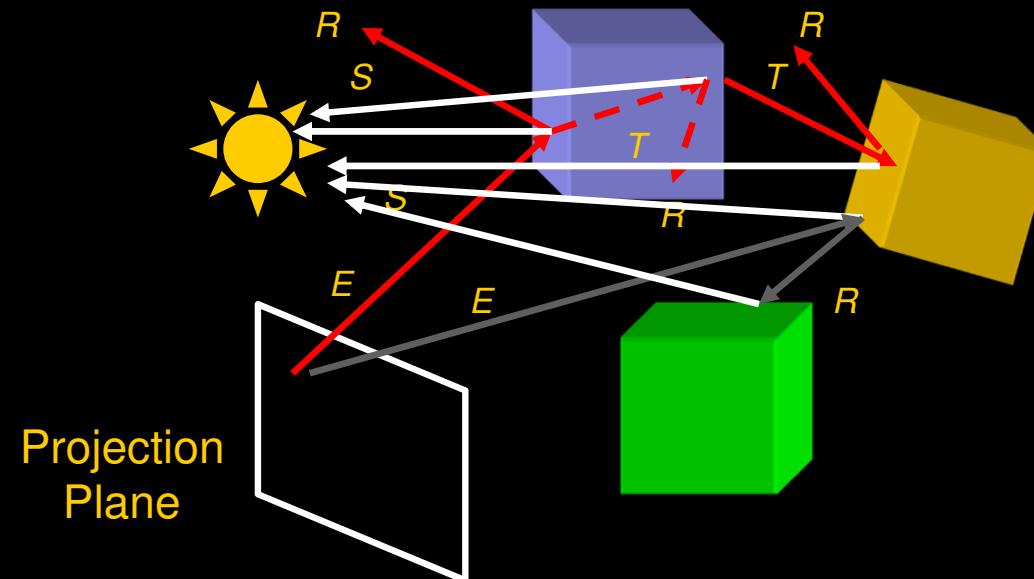
## ◆ Ray classification



# *Backward Ray Tracing*

- ◆ Trace eye rays emitted from projection plane
- ◆ Eye rays bounced between objects in scene
- ◆ Accumulate the contributions of each shadow rays if they can reach the light sources

If the level of secondary rays is limited, then the algorithm can be terminated in finite time



# *Efficiency of Ray Tracing*

- ◆ Reduce the number of ray-object intersections
  - Bounding Box
  - Space Partition
- ◆ Parallel Processing



# *Characteristic of Ray Tracing*

- ◆ An image space algorithm
- ◆ View dependent
- ◆ Render scenes with perfect specular reflection and refraction
- ◆ Point light sources
- ◆ Ideas came from the path of light flow



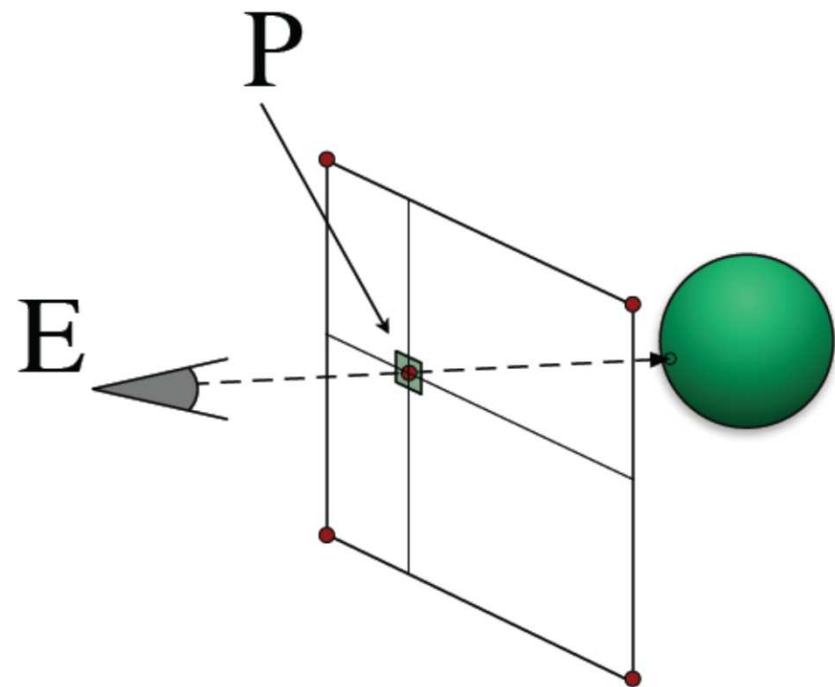
# *Building Eye Rays*

## ◆ Ray equation

$$\mathbf{R}(t) = \mathbf{E} + t (\mathbf{P} - \mathbf{E})$$

$$t \in [1. . . +\infty]$$

- Through eye at  $t = 0$
- Through pixel center at  $t = 1$



# Shadow Rays

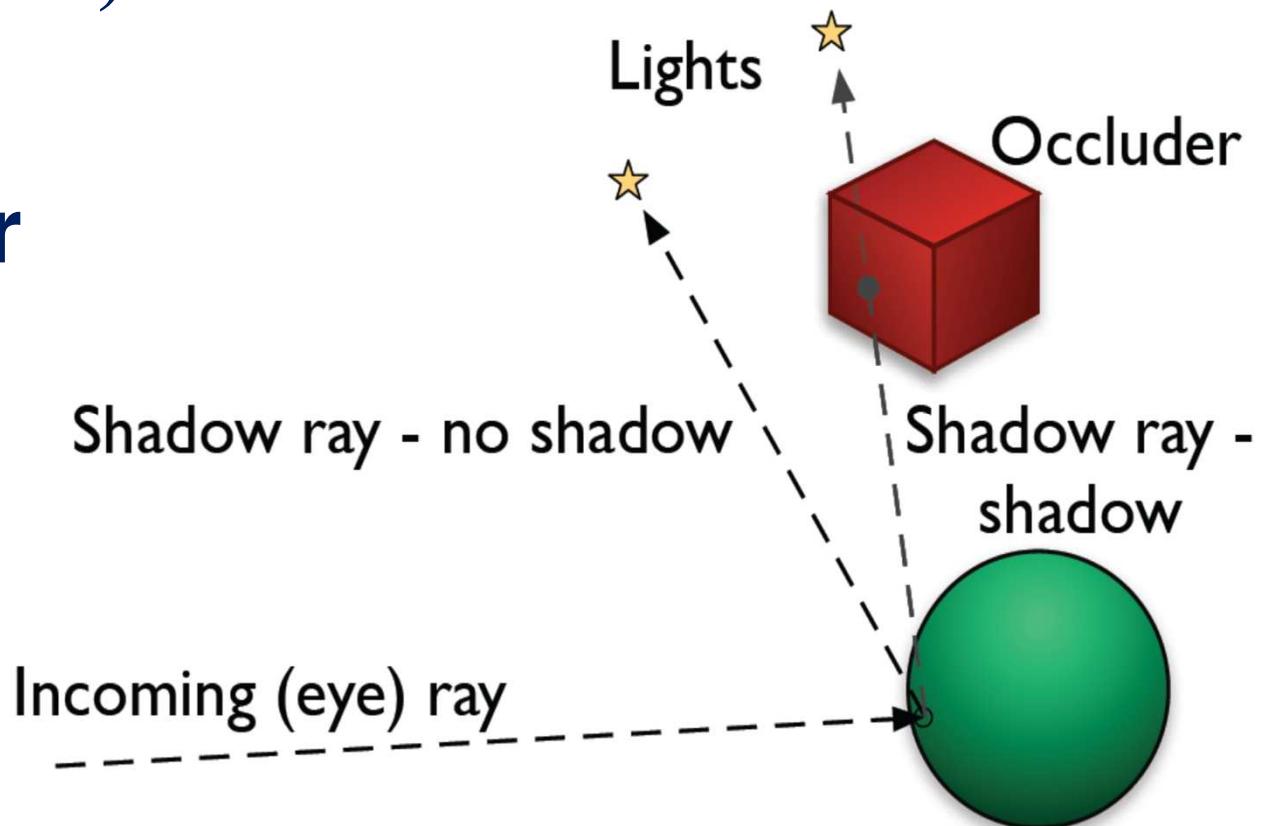
- ◆ Detect shadow by rays to light sources

$$\mathbf{R}(t) = \mathbf{S} + t (\mathbf{L} - \mathbf{S})$$

$$t \in [\varepsilon \dots 1)$$

- ◆ Test for occluder

- Shade normally if no occluder



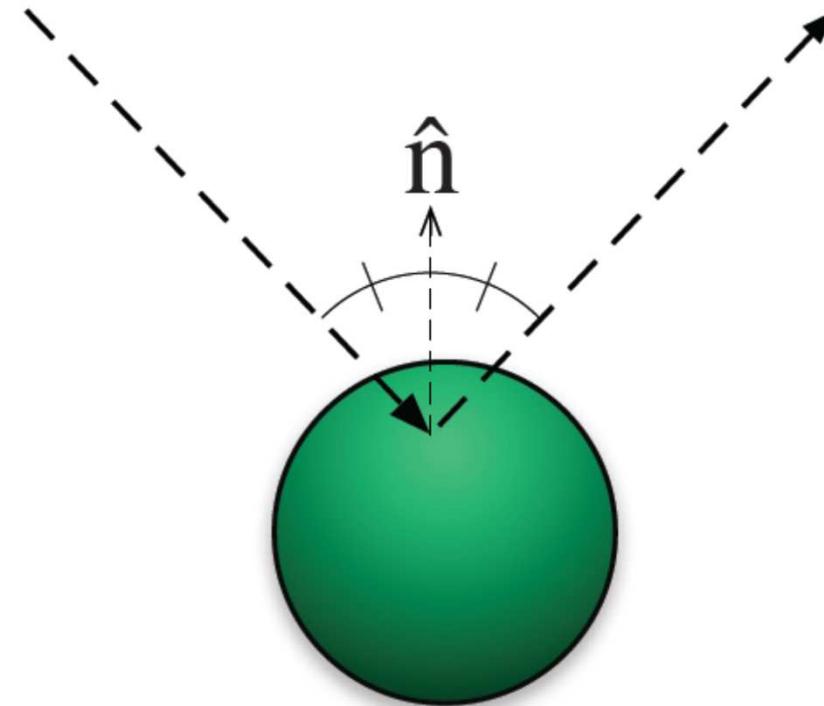
# *Reflection Rays*

## ◆ Recursive shading

$$\mathbf{R}(t) = \mathbf{S} + t \mathbf{B}$$

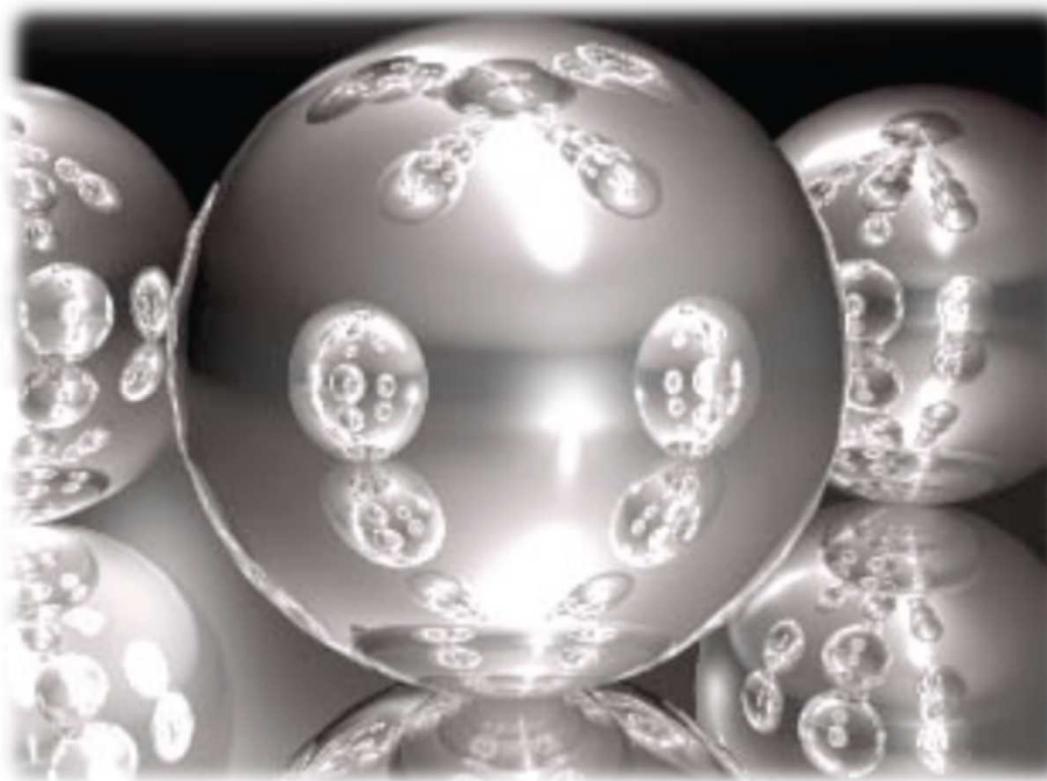
$$t \in [\varepsilon \dots +\infty)$$

- Ray bounces off object
- Treat bounce rays (mostly) like eye rays
- Shade bounce ray and return color
- Add color to shading at original point

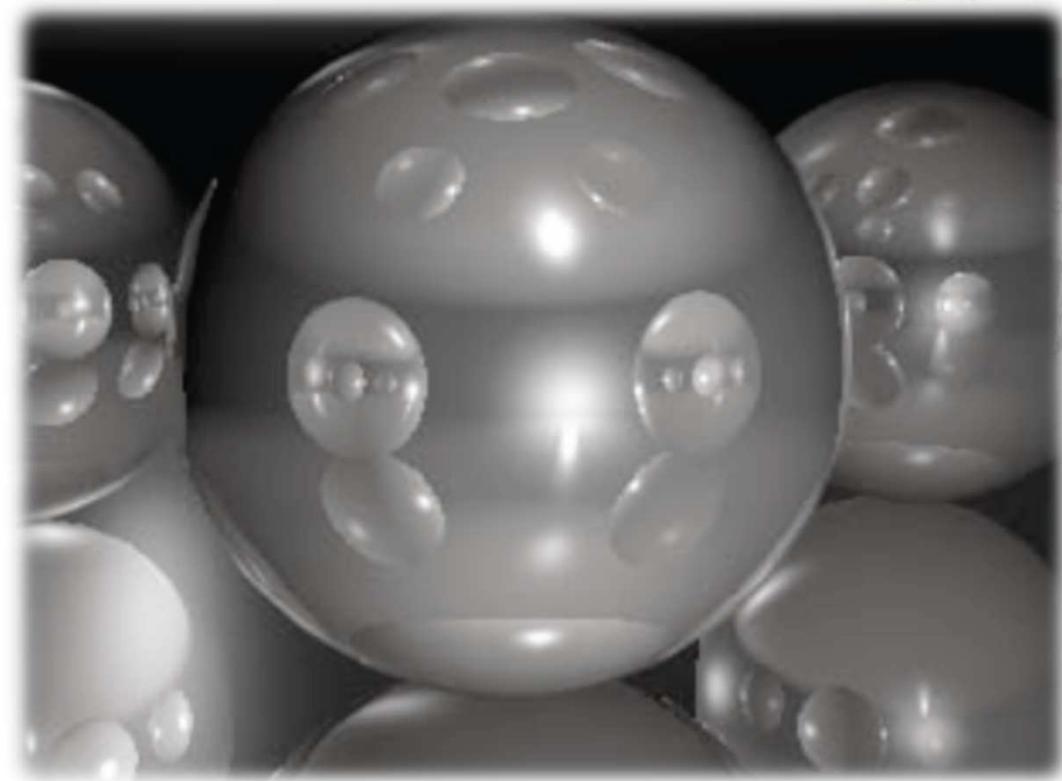


# *Reflection Rays*

## ◆ Recursion Depth

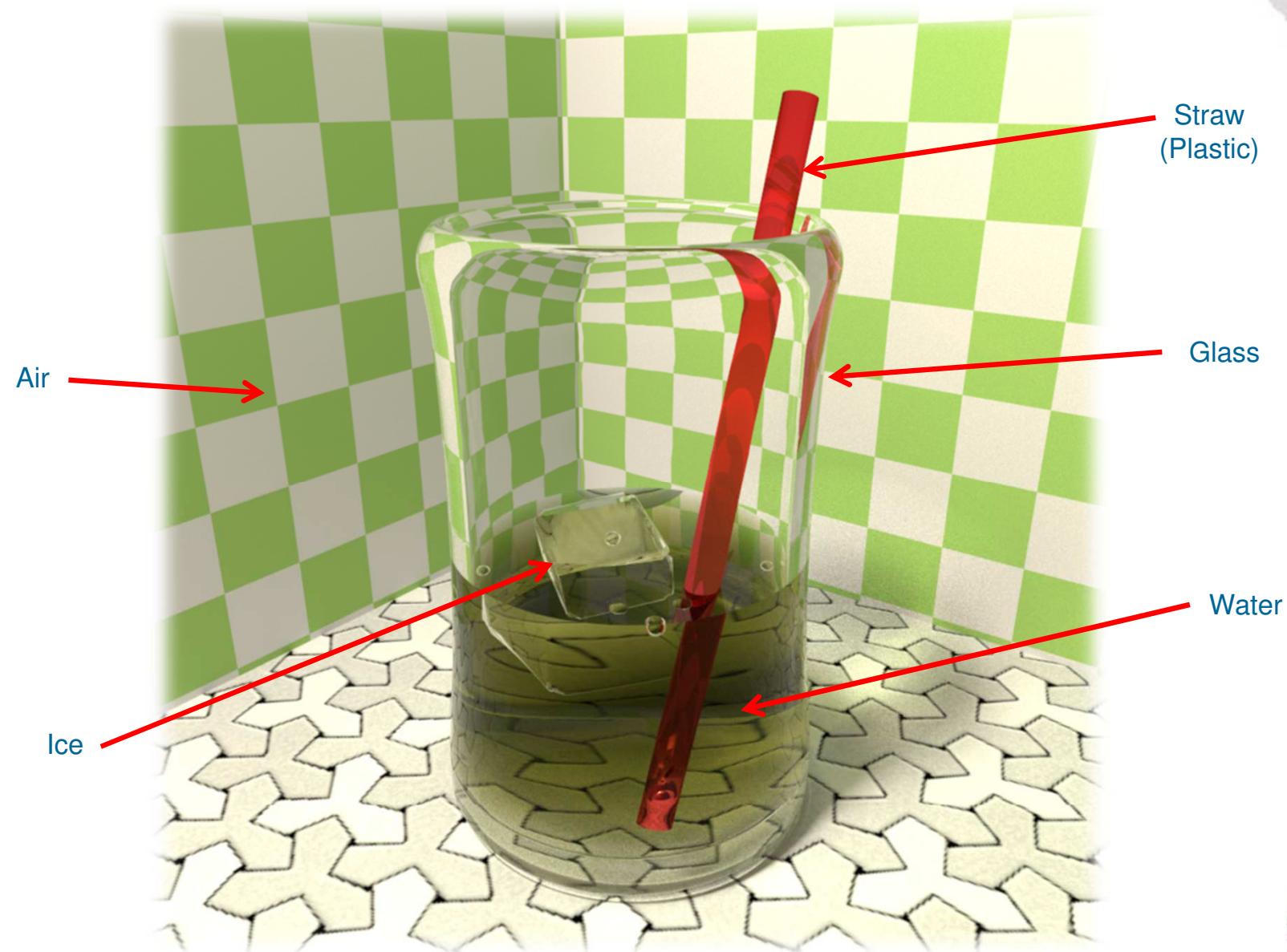


High recursion depth



Low recursion depth

# Refraction Rays



# Refraction Rays

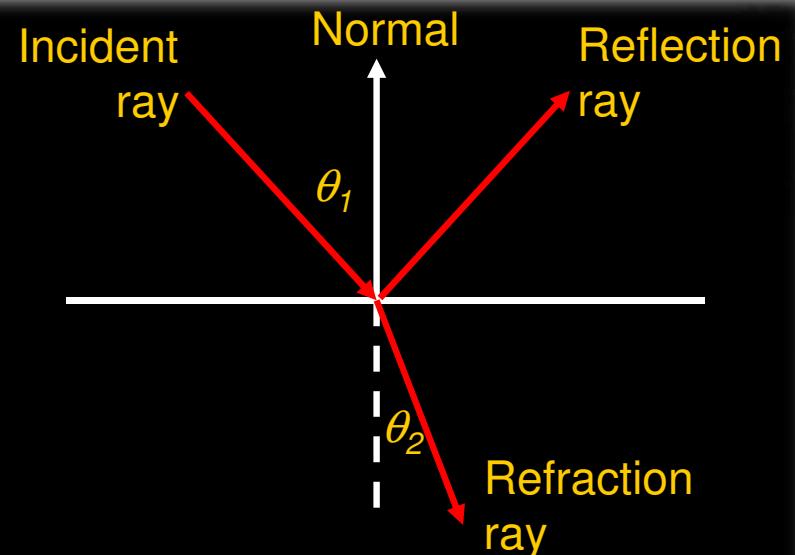
- ◆ Transparent materials bend light
  - Snell's Law

$$\frac{\sin \theta_1}{\sin \theta_2} = \eta_{21} = \frac{\eta_2}{\eta_1}$$

where  $\eta$  is the indices of refraction

Refraction indices of some common materials

Vacuum	1.0
Water	1.333
Ice	1.309
Glass	1.5~1.6



# Refraction Rays

- ◆ Behavior of light when moving between different refractive media
  - Fresnel Equation
  - Schlick's approximation to Fresnel equation

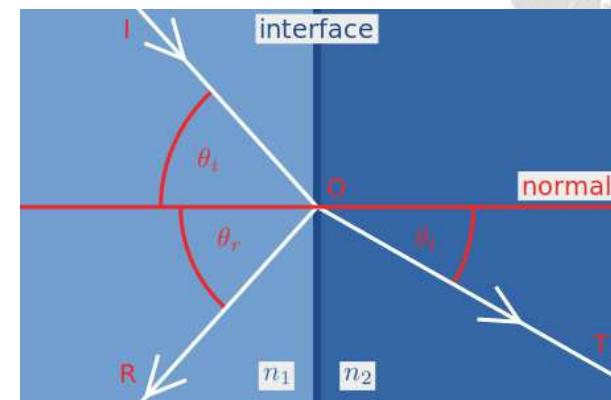
Reflection coefficient  $R$

$$R(\theta) = R_0 + (1 - R_0)(1 - \cos \theta)^5$$

$$R_0 = \left( \frac{\eta_1 - \eta_2}{\eta_1 + \eta_2} \right)^2$$

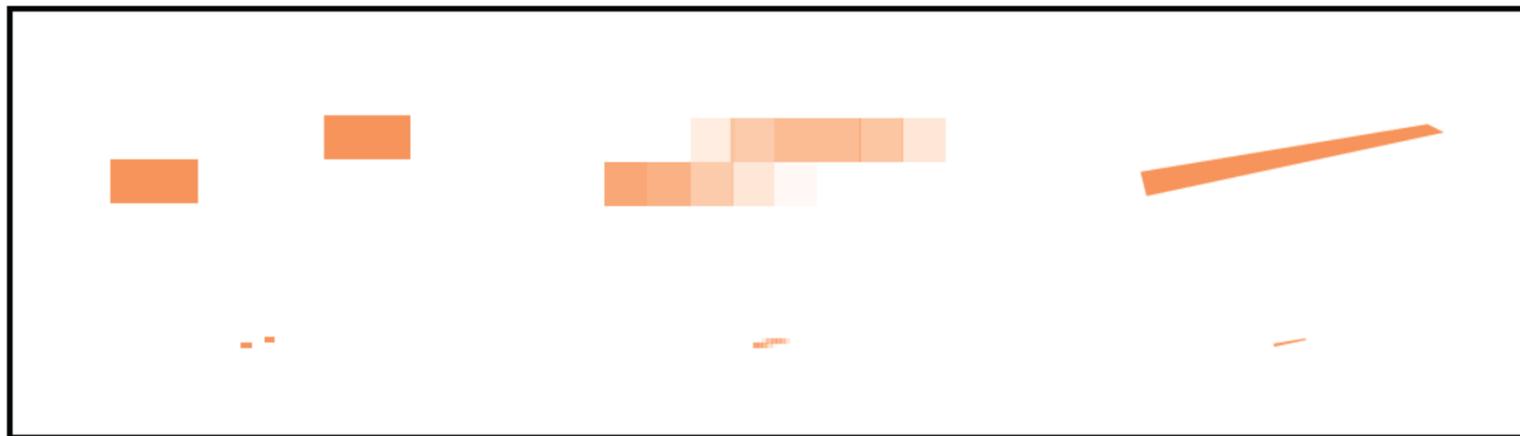
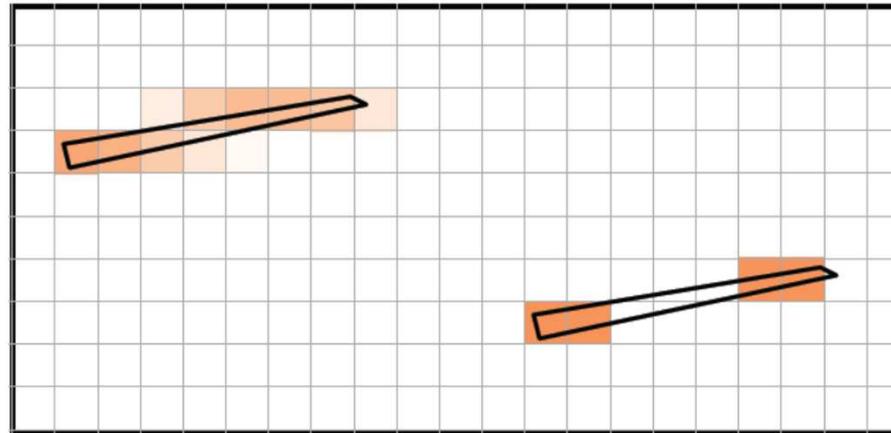
Transmission coefficient  $T$

$$T(\theta) = 1 - R(\theta)$$



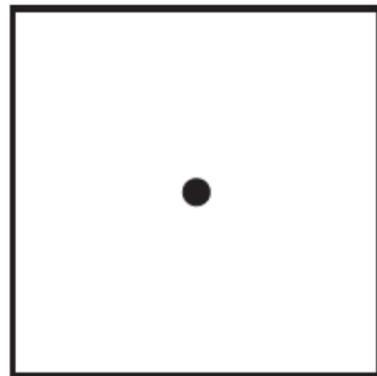
# *Aliasing Issue*

- ◆ Use only rays through pixel centers
- ◆ Need a solution of an integral over pixel

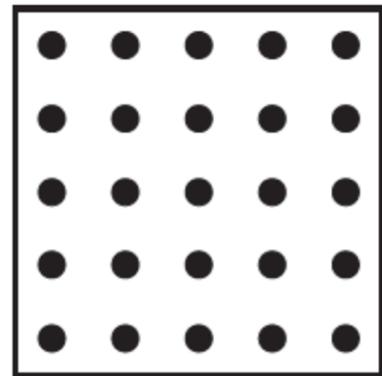


# *Distributed Ray Tracing*

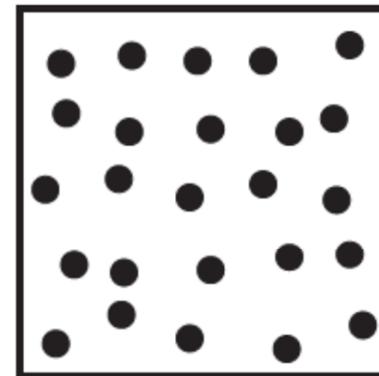
- ◆ Send multiple rays through each pixel



One Sample



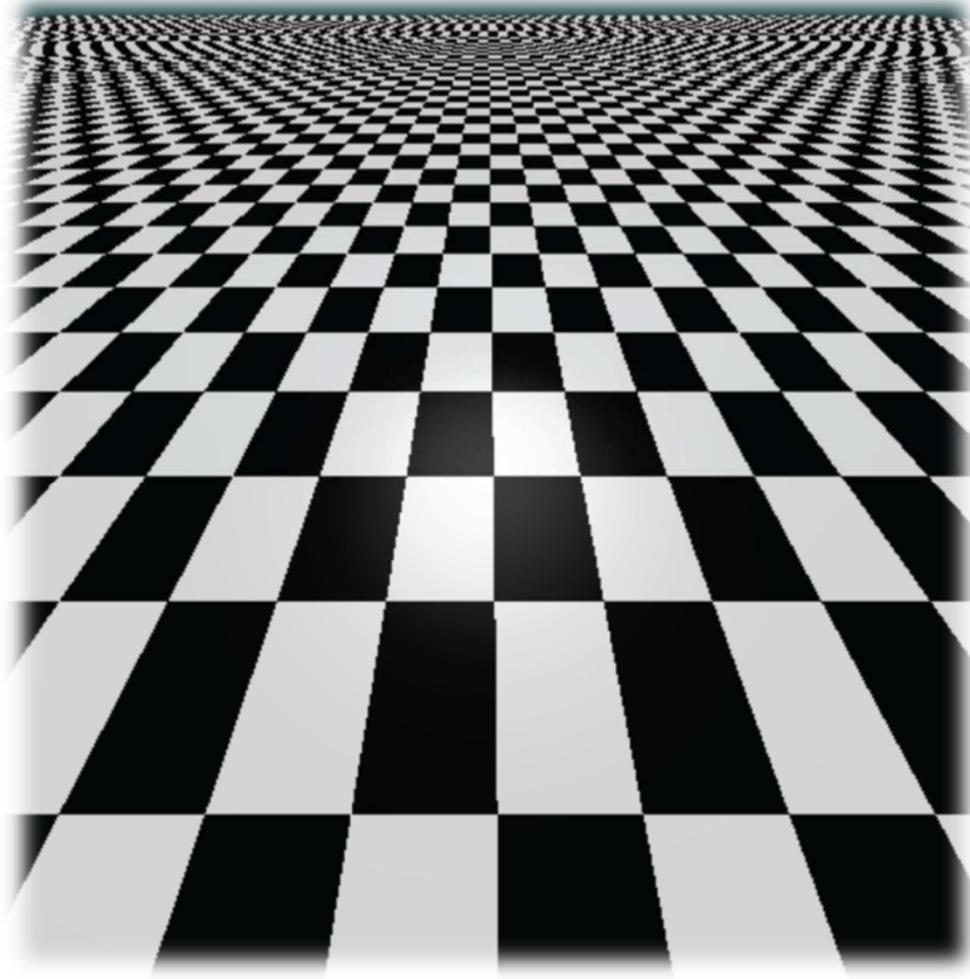
5x5 Grid



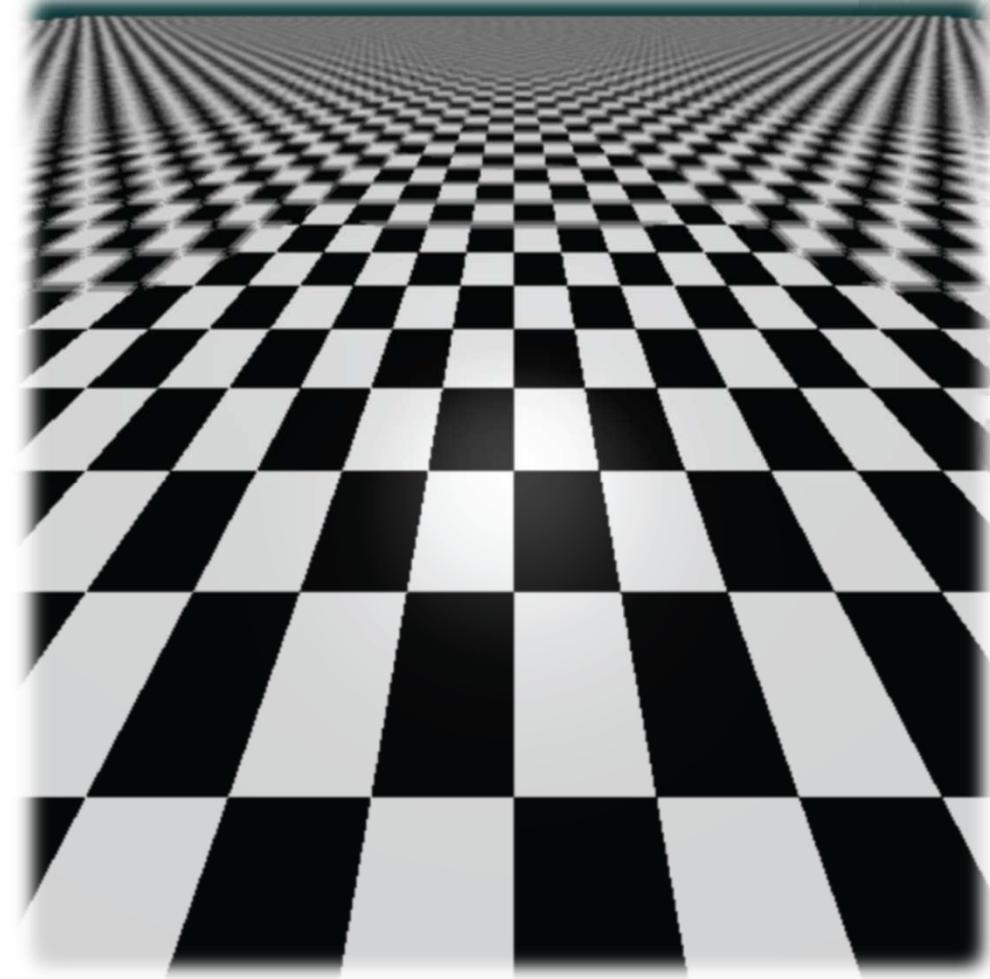
5x5 Jittered Grid

- ◆ Average results together

# *Distributed Ray Tracing*



Without Distributed Ray Tracing

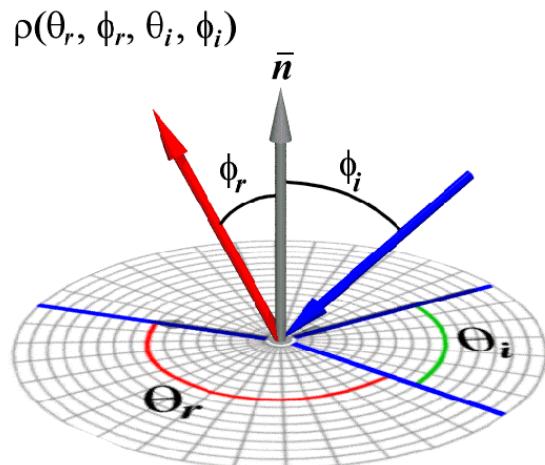


With Distributed Ray Tracing



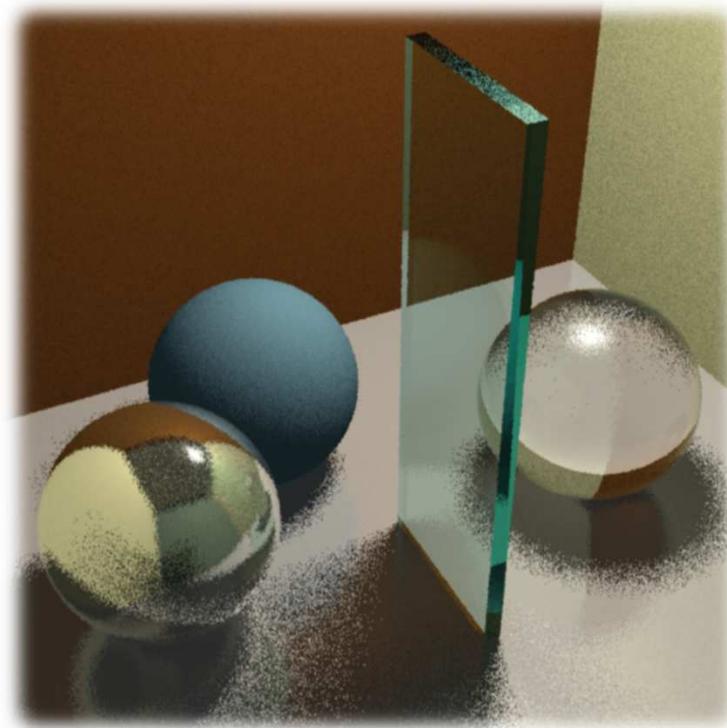
# Distributed Ray Tracing

- ◆ Use multiple rays for reflection and refraction
  - At each bounce send out many extra rays
  - Quasi-random directions
  - Use BRDF (or Phong approximation) for weights

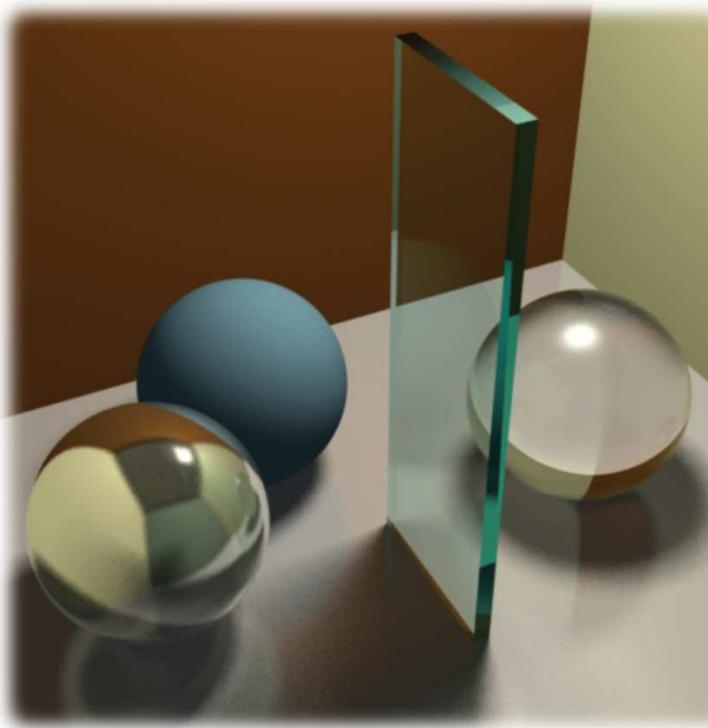


# *Distributed Ray Tracing*

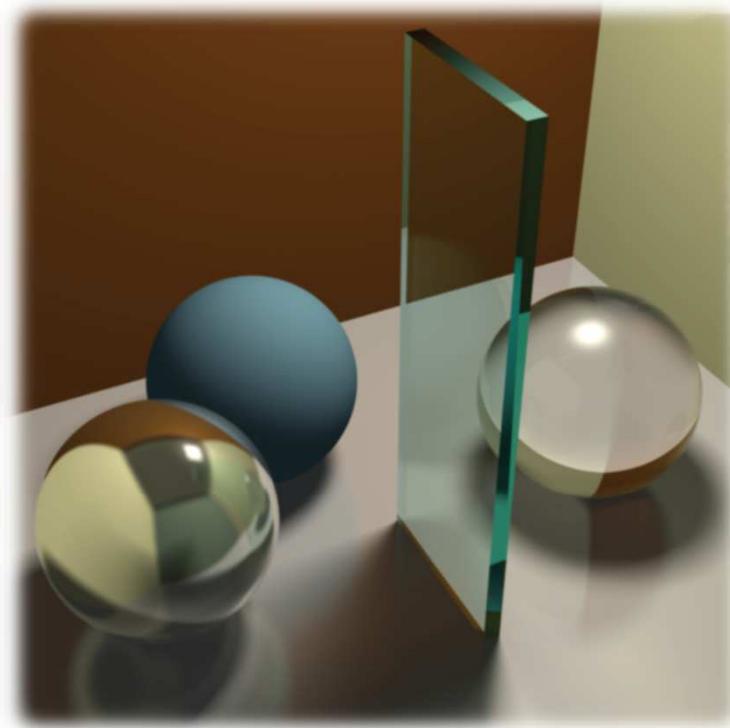
## ◆ How many rays?



1 sample per pixel



16 samples per pixel

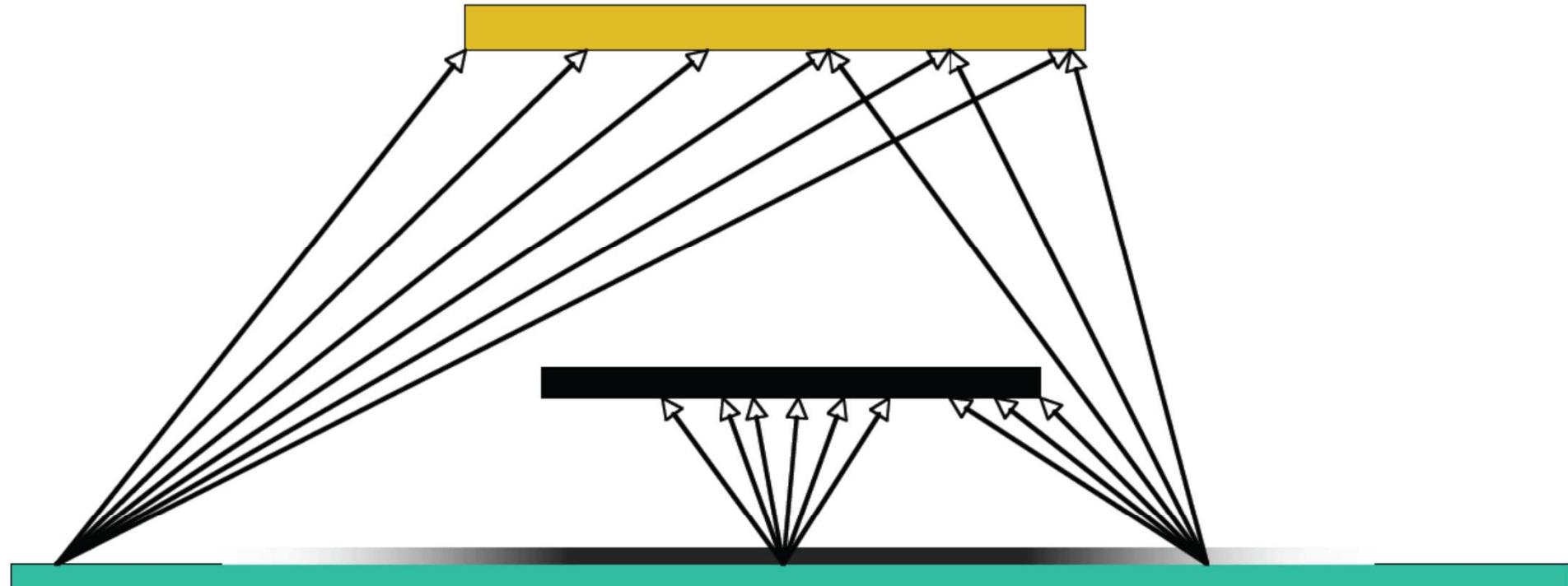


256 samples per pixel



# *Soft Shadow*

- ◆ **Distribute shadow rays over light surface**



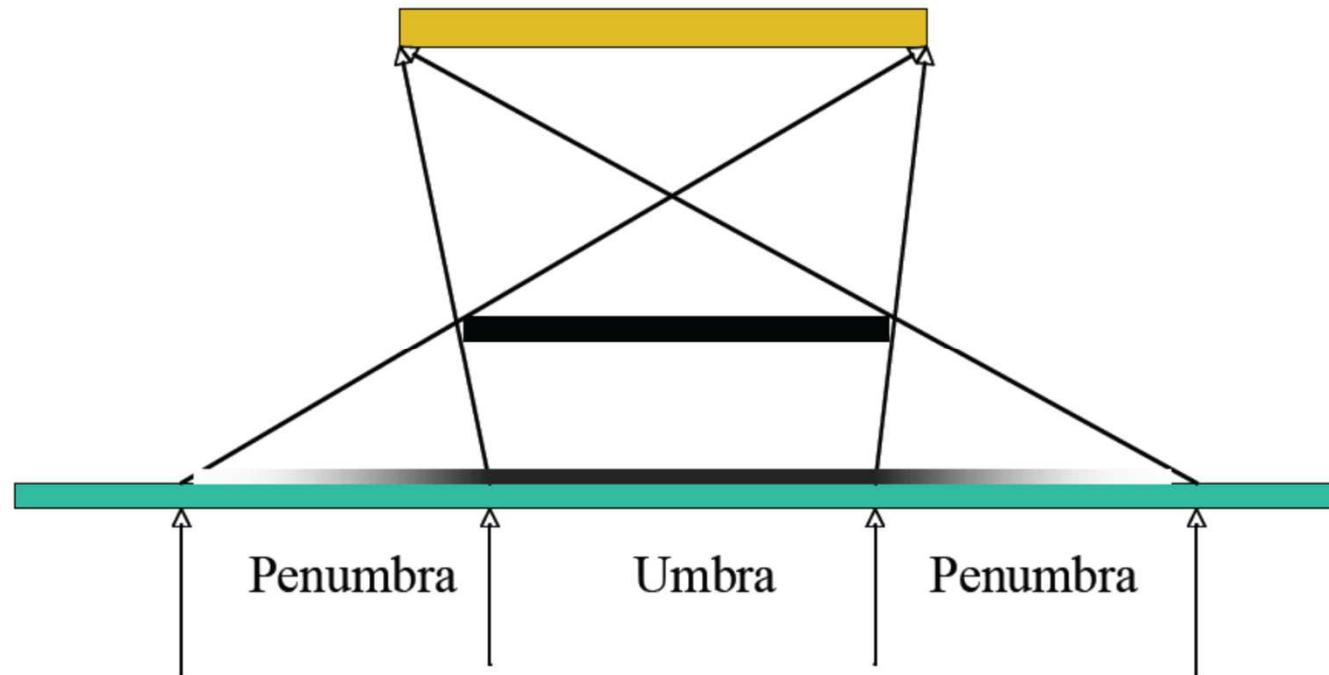
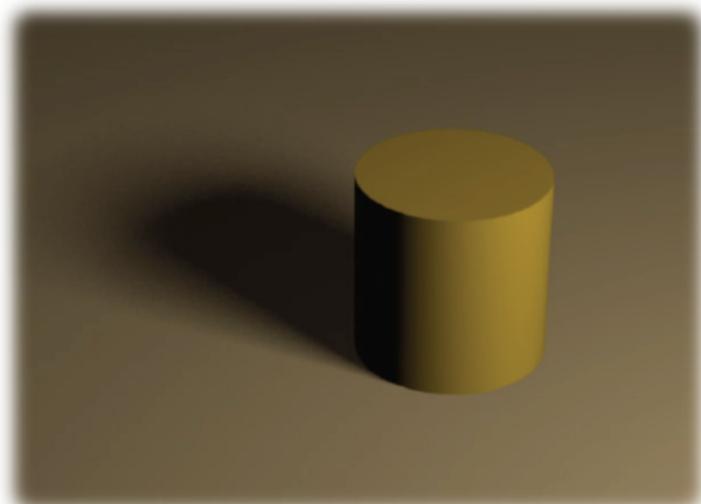
All shadow rays  
go through

No shadow rays  
go through

Some shadow  
rays go through

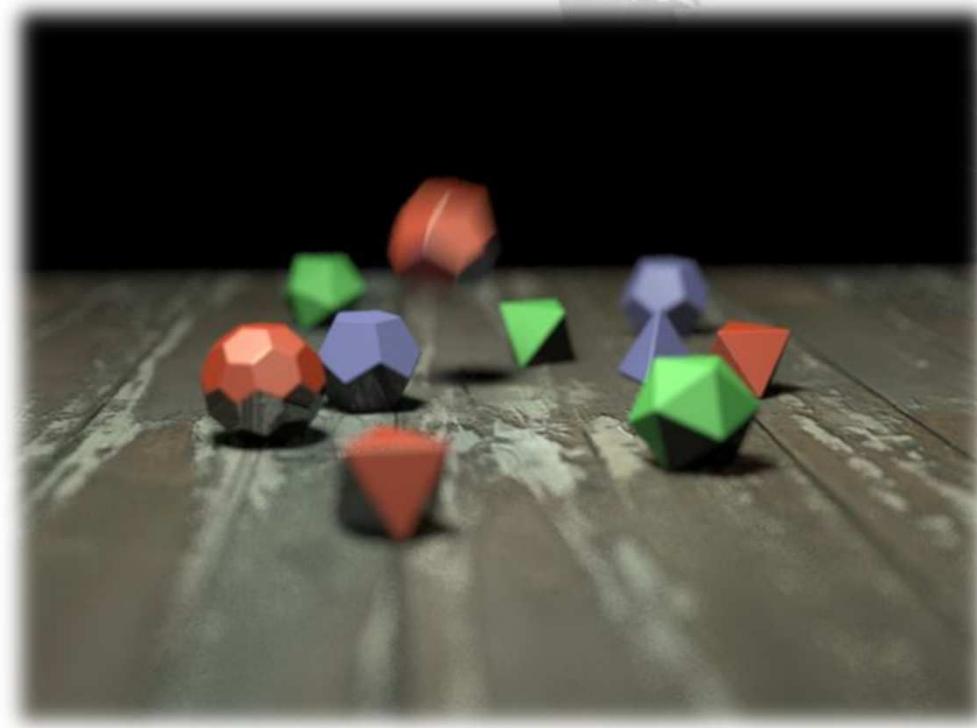
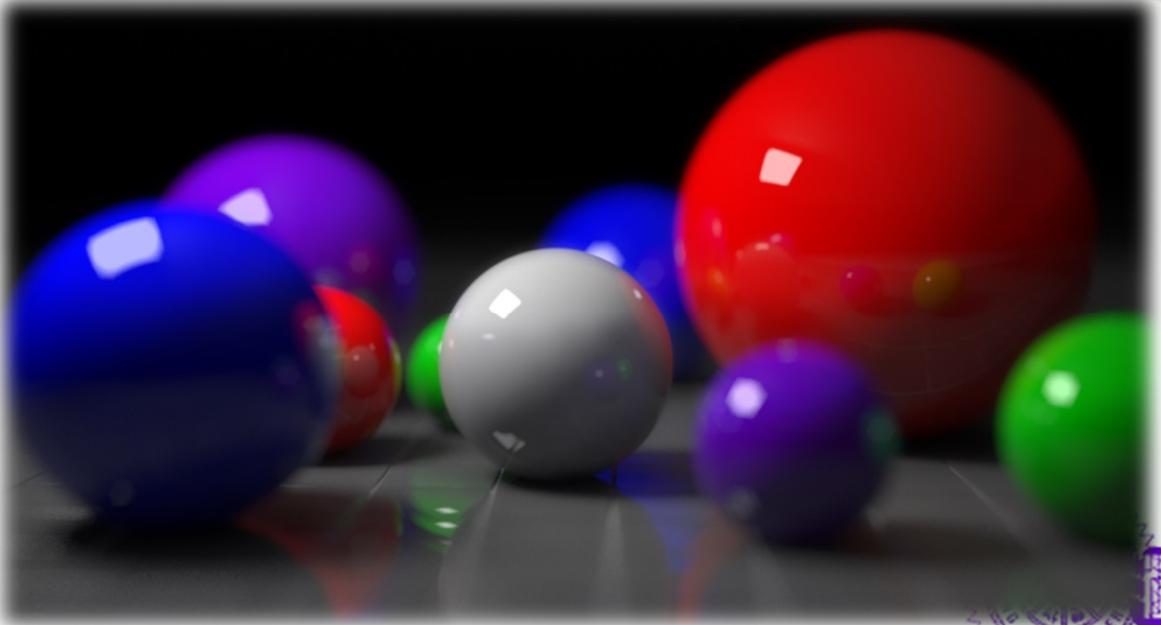
# *Soft Shadow*

- ◆ Soft shadows result from non-point lights



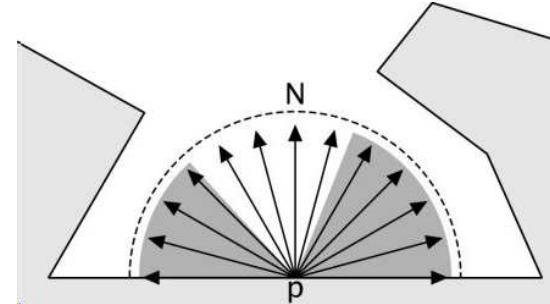
# *Other Effects*

- ◆ Motion Blur
- ◆ Depth of Field



# *Other Effects*

## ◆ Ambient Occlusion



Ambient Occlusion



Diffuse Lighting



Combined

# Intersection Test

## ◆ Ray vs. Sphere

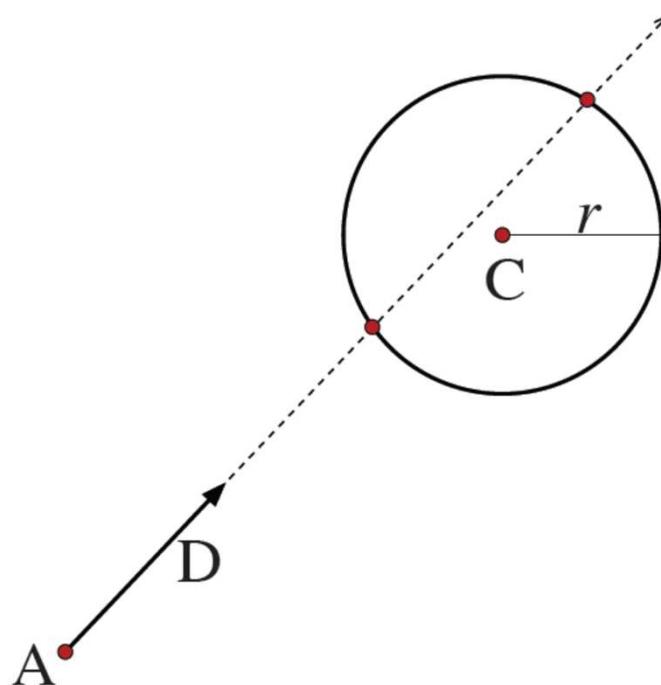
- Ray equation:  $\mathbf{R}(t) = \mathbf{A} + t\mathbf{D}$
- Implicit equation for sphere:  $|\mathbf{X} - \mathbf{C}|^2 - r^2 = 0$

### ■ Combine:

$$|\mathbf{R}(t) - \mathbf{C}|^2 - r^2 = 0$$

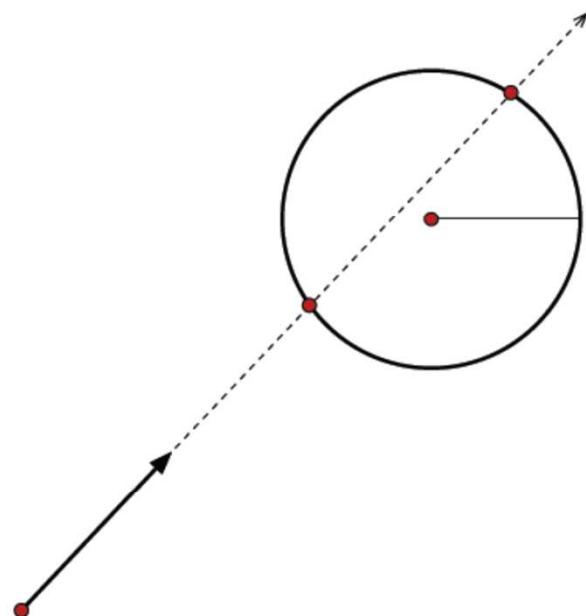
$$|\mathbf{A} + t\mathbf{D} - \mathbf{C}|^2 - r^2 = 0$$

### ■ Quadratic equation in $t$

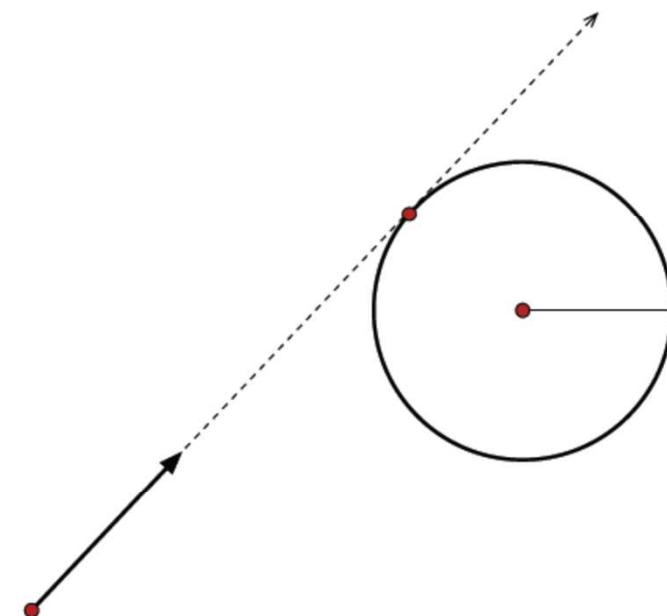


# *Intersection Test*

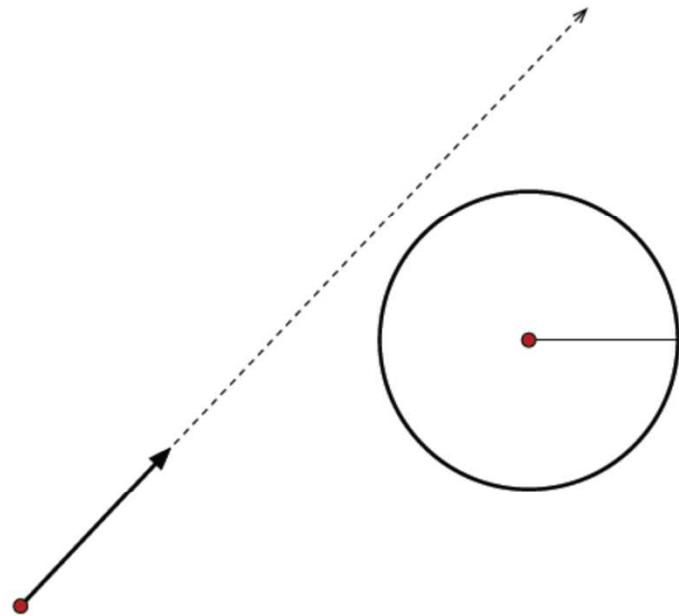
## ◆ Ray vs. Sphere



Two solutions



One solution



Imaginary

# Intersection Test

## ◆ Ray vs. Triangle

- Ray equation:  $\mathbf{R}(t) = \mathbf{A} + t\mathbf{D}$
- Triangle in barycentric coordinates:

$$\mathbf{X}(\beta, \gamma) = \mathbf{V}_1 + \beta(\mathbf{V}_2 - \mathbf{V}_1) + \gamma(\mathbf{V}_3 - \mathbf{V}_1)$$

- Combine:
- $$\mathbf{V}_1 + \beta(\mathbf{V}_2 - \mathbf{V}_1) + \gamma(\mathbf{V}_3 - \mathbf{V}_1) = \mathbf{A} + t\mathbf{D}$$
- Solve for  $\beta, \gamma$ , and  $t$



# Q&A

