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Other slides: https://goo.gl/jPtWNt



With TF 1.0!



maps feature maps feature maps feature maps

Lab II-I

CNN Basics

Sung Kim < hunkim+ml@gmail.com>

Code: https://github.com/hunkim/DeepLearningZeroToAll/

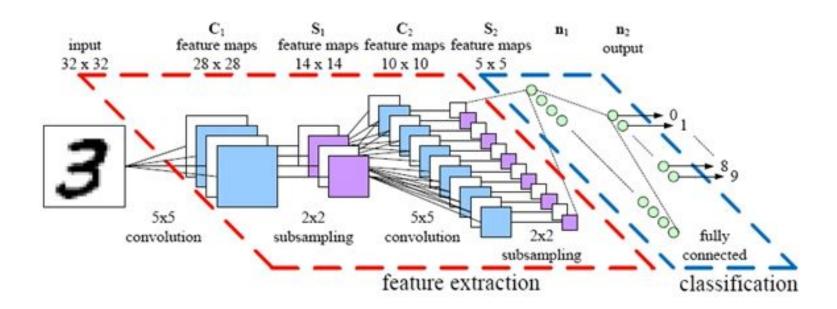
feature extraction



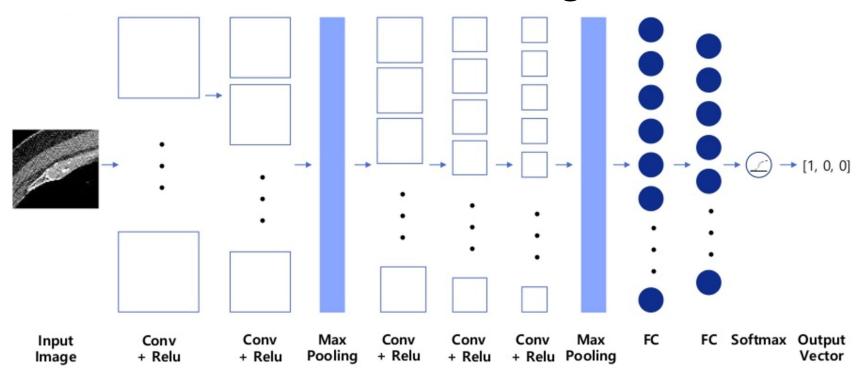
https://github.com/hunkim/DeepLearningZeroToAll/



CNN

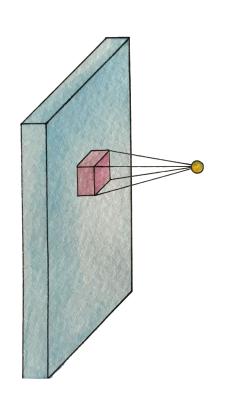


CNN for CT images



Asan Medical Center & Microsoft Medical Bigdata Contest Winner by GeunYoung Lee and Alex Kim https://www.slideshare.net/GYLee3/ss-72966495

Convolution layer and max pooling



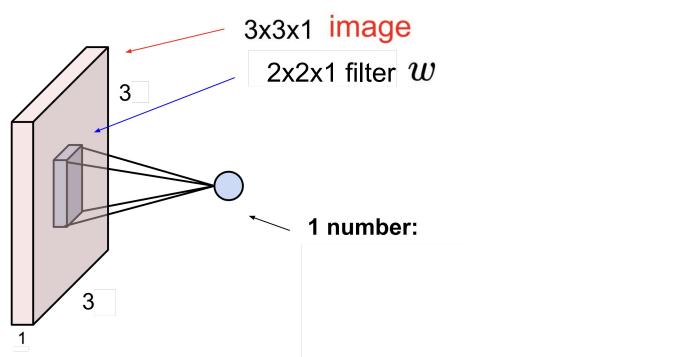
Singl	e (dep	oth	sli	се

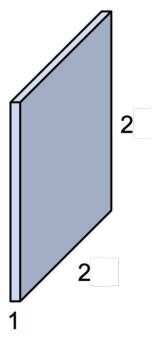
1	1	2	4
5	6	7	8
3	2	1	0
1	2	3	4

max pool with 2x2 filters and stride 2

6	8
3	4

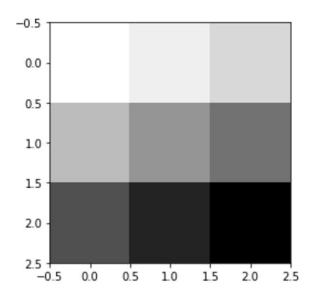
Simple convolution layer Stride: 1x1





(1, 3, 3, 1)

Out[2]: <matplotlib.image.AxesImage at 0x10db67dd8>



Toy image

Simple convolution layer

Image: 1,3,3,1 image, Filter: 2,2,1,1, Stride: 1x1, Padding: VALID

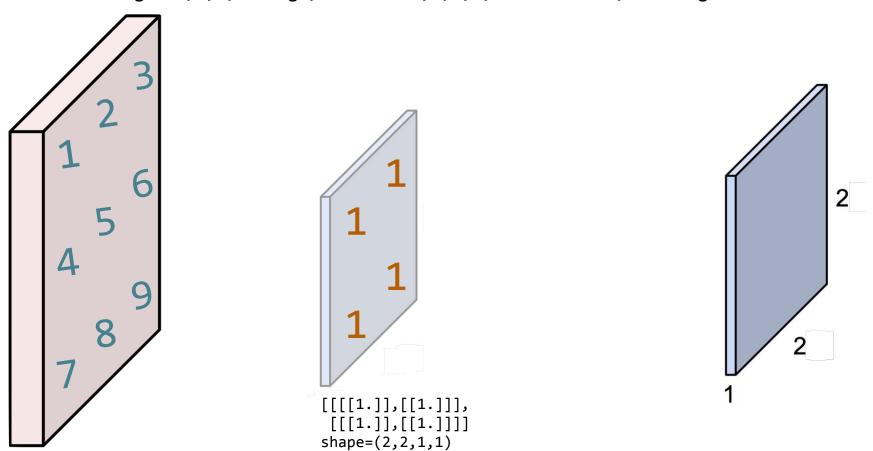


Image: 1,3,3,1 image, Filter: 2,2,1,1, Stride: 1x1, Padding: VALID

print("imag:\n", image)

print("image.shape", image.shape)

weight = tf.constant([[[[1.]],[[1.]]],

```
[[[1.]],[[1.]]])
print("weight.shape", weight.shape)
conv2d = tf.nn.conv2d(image, weight, strides=[1, 1, 1, 1], padding='VALID')
conv2d img = conv2d.eval()
print("conv2d img.shape", conv2d img.shape)
conv2d img = np.swapaxes(conv2d img, 0, 3)
for i, one_img in enumerate(conv2d_img):
    print(one img.reshape(2,2))
    plt.subplot(1,2,i+1), plt.imshow(one img.reshape(2,2), cmap='gray')
image.shape (1, 3, 3, 1)
weight.shape (2, 2, 1, 1)
conv2d img.shape (1, 2, 2, 1)
[[ 12. 16.]
 [ 24. 28.]]
 -0.5
  0.0
  0.5
  1.0
  15 -
        0.0
             0.5
   -0.5
                  1.0
```

Simple convolution layer

Image: 1,3,3,1 image, Filter: 2,2,1,1, Stride: 1x1, Padding: SAME

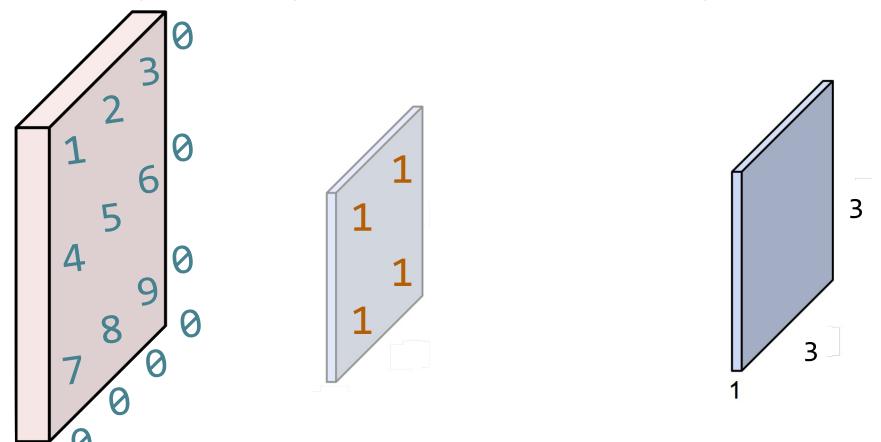
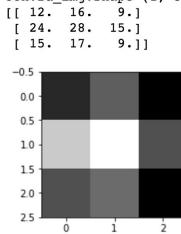
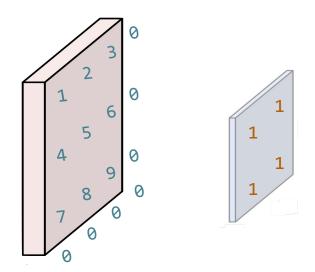


Image: 1,3,3,1 image, Filter: 2,2,1,1, Stride: 1x1, Padding: SAME

```
# print("imag:\n", image)
print("image.shape", image.shape)
weight = tf.constant([[[[1.]],[[1.]]],
                      [[[1.]],[[1.]]])
print("weight.shape", weight.shape)
conv2d = tf.nn.conv2d(image, weight, strides=[1, 1, 1, 1], padding='SAME')
conv2d img = conv2d.eval()
print("conv2d img.shape", conv2d img.shape)
conv2d img = np.swapaxes(conv2d img, 0, 3)
for i, one img in enumerate(conv2d img):
    print(one img.reshape(3,3))
    plt.subplot(1,2,i+1), plt.imshow(one img.reshape(3,3), cmap='gray')
image.shape (1, 3, 3, 1)
weight.shape (2, 2, 1, 1)
conv2d img.shape (1, 3, 3, 1)
```

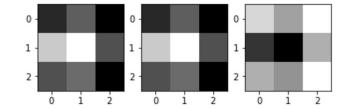




3 filters (2,2,1,3)

[-15. -17. -9.]

```
# print("imag:\n", image)
print("image.shape", image.shape)
weight = tf.constant([[[[1.,10.,-1.]],[[1.,10.,-1.]]],
                      [[[1.,10.,-1.]],[[1.,10.,-1.]]]]
print("weight.shape", weight.shape)
conv2d = tf.nn.conv2d(image, weight, strides=[1, 1, 1, 1], padding='SAME')
conv2d img = conv2d.eval()
print("conv2d img.shape", conv2d img.shape)
conv2d img = np.swapaxes(conv2d img, 0, 3)
for i, one img in enumerate(conv2d img):
    print(one img.reshape(3,3))
    plt.subplot(1,3,i+1), plt.imshow(one_img.reshape(3,3), cmap='gray')
image.shape (1, 3, 3, 1)
weight.shape (2, 2, 1, 3)
conv2d img.shape (1, 3, 3, 3)
[[ 12. 16. 9.]
[ 24. 28. 15.]
 [ 15. 17. 9.]]
[[ 120. 160. 90.]
 [ 240. 280. 150.]
 [ 150. 170. 90.]]
[[-12. -16. -9.]
 [-24. -28. -15.]
```



4 3 2 1

Max Pooling

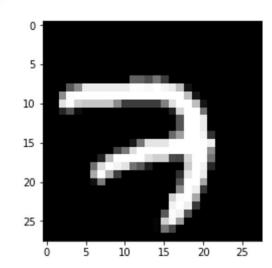
```
In [19]:
         image = np.array([[[[4],[3]],
                              [[2],[1]]], dtype=np.float32)
         pool = tf.nn.max_pool(image, ksize=[1, 2, 2, 1],
                              strides=[1, 1, 1, 1], padding='SAME')
         print(pool.shape)
         print(pool.eval())
         (1, 2, 2, 1)
         [[[ 4.]
                           SAME: Zero paddings
            [ 3.]]
           [[ 2.]
                                         3
                                              0
                                                       4
                                                             3
                                                                           4
                                                                                3
                                                                                     0
                                                                                              4
                                                                                                   3
                                                                                                        0
                                    4
                                                                  0
            [ 1.]]]]
                                    2
                                                             1
                                                                           2
                                                                                1
                                                                                                   1
                                              0
                                                                  0
                                                                                     0
                                                                                                        0
```

```
In [6]: from tensorflow.examples.tutorials.mnist import input_data
mnist = input_data.read_data_sets("MNIST_data/", one_hot=True)
# Check out https://www.tensorflow.org/get_started/mnist/beginners for
# more information about the mnist dataset
```

Extracting MNIST_data/train-images-idx3-ubyte.gz Extracting MNIST_data/train-labels-idx1-ubyte.gz Extracting MNIST_data/t10k-images-idx3-ubyte.gz Extracting MNIST_data/t10k-labels-idx1-ubyte.gz

```
In [7]: img = mnist.train.images[0].reshape(28,28)
plt.imshow(img, cmap='gray')
```

Out[7]: <matplotlib.image.AxesImage at 0x115029ac8>



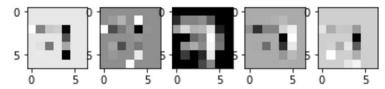
MNIST image loading

https://github.com/hunkim/DeepLearningZeroToAll/blob/master/lab-11-0-cnn_basics.ipynb

MNIST Convolution layer

```
In [8]: sess = tf.InteractiveSession()
        img = imq.reshape(-1,28,28,1)
        W1 = tf.Variable(tf.random normal([3, 3, 1, 5], stddev=0.01))
        conv2d = tf.nn.conv2d(img, W1, strides=[1, 2, 2, 1], padding='SAME')
        print(conv2d)
        sess.run(tf.global variables initializer())
        conv2d img = conv2d.eval()
        conv2d img = np.swapaxes(conv2d img, 0, 3)
        for i, one img in enumerate(conv2d img):
            plt.subplot(1,5,i+1), plt.imshow(one img.reshape(14,14), cmap='gray')
        Tensor("Conv2D 1:0", shape=(1, 14, 14, 5), dtype=float32)
```

MNIST Max pooling



With TF 1.0!



Lab II-2

CNN MNIST: 99%!

Sung Kim < hunkim+ml@gmail.com>

Code: https://github.com/hunkim/DeepLearningZeroToAll/

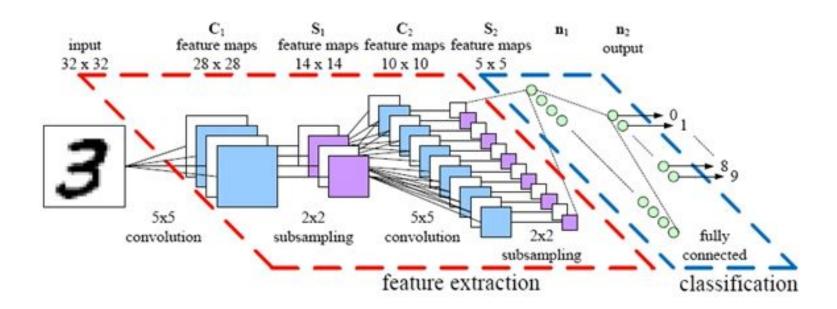
feature extraction



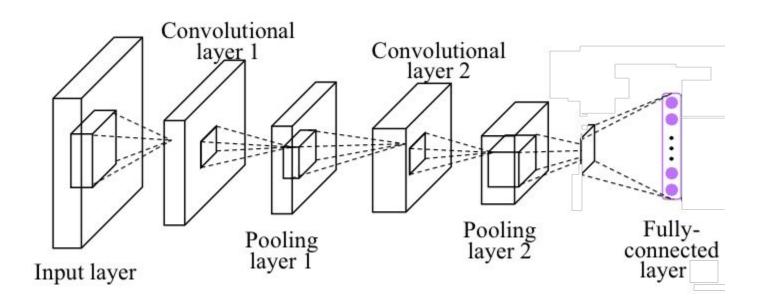
https://github.com/hunkim/DeepLearningZeroToAll/



CNN



Simple CNN



Conv layer I

```
Convolutional layer 1

Convolutional layer 2

Pooling layer 2

Fully-connected layer 2

R/White)
```

```
# input placeholders
X = tf.placeholder(tf.float32, [None, 784])
X \text{ img} = \text{tf.reshape}(X, [-1, 28, 28, 1])  # img 28x28x1 (black/white)
Y = tf.placeholder(tf.float32, [None, 10])
# L1 ImgIn shape=(?, 28, 28, 1)
W1 = tf.Variable(tf.random normal([3, 3, 1, 32], stddev=0.01))
     Conv \rightarrow (?, 28, 28, 32)
# Pool -> (?, 14, 14, 32)
L1 = tf.nn.conv2d(X img, W1, strides=[1, 1, 1, 1], padding='SAME')
L1 = tf.nn.relu(L1)
L1 = tf.nn.max pool(L1, ksize=[1, 2, 2, 1],
         strides=[1, 2, 2, 1], padding='SAME')
1 1 1
Tensor("Conv2D:0", shape=(?, 28, 28, 32), dtype=float32)
Tensor("Relu:0", shape=(?, 28, 28, 32), dtype=float32)
Tensor("MaxPool:0", shape=(?, 14, 14, 32), dtype=float32)
1 1 1
```

https://github.com/hunkim/DeepLearningZeroToAll/blob/master/lab-11-1-mnist_cnn.py

Conv layer 2

```
Tensor("Conv2D:0", shape=(?, 28, 28, 32), dtype=float32)
Tensor("Relu:0", shape=(?, 28, 28, 32), dtype=float32)
Tensor("MaxPool:0", shape=(?, 14, 14, 32), dtype=float32)
```

W2 = tf.Variable(tf.random normal([3, 3, 32, 64], stddev=0.01))

L2 = tf.nn.conv2d(L1, W2, strides=[1, 1, 1, 1], padding='SAME')

L2 ImgIn shape=(?, 14, 14, 32)

Pool ->(?. 7. 7. 64)

L2 = tf.nn.relu(L2)

Conv \rightarrow (?. 14. 14. 64)

1.1.1

```
Convolutional layer I

Pooling layer I

Input layer I

Pooling layer 2

Pooling layer 2

Pooling layer 2
```

```
L2 = tf.nn.max_pool(L2, ksize=[1, 2, 2, 1], strides=[1, 2, 2, 1], padding='SAME')
L2 = tf.reshape(L2, [-1, 7 * 7 * 64])

Tensor("Conv2D_1:0", shape=(?, 14, 14, 64), dtype=float32)
Tensor("Relu_1:0", shape=(?, 14, 14, 64), dtype=float32)
Tensor("MaxPool_1:0", shape=(?, 7, 7, 64), dtype=float32)
Tensor("Reshape_1:0", shape=(?, 3136), dtype=float32)
```

Fully Connected (FC, Dense) layer

```
1 1 1
Tensor("Conv2D 1:0", shape=(?, 14, 14, 64), dtype=float32)
Tensor("Relu 1:0", shape=(?, 14, 14, 64), dtype=float32)
                                                                       Convolutional
                                                                                 Convolutional
                                                                                   laver 2
Tensor("MaxPool 1:0", shape=(?, 7, 7, 64), dtype=float32)
Tensor("Reshape 1:0", shape=(?, 3136), dtype=float32)
L2 = tf.reshape(L2, [-1, 7 * 7 * 64])
                                                                           Pooling
                                                                                      layer 2
                                                                           laver I
                                                                 Input laver
# Final FC 7x7x64 inputs -> 10 outputs
W3 = tf.get variable("W3", shape=[7 * 7 * 64, 10],
initializer=tf.contrib.layers.xavier initializer())
b = tf.Variable(tf.random normal([10]))
hypothesis = tf.matmul(L2, W3) + b
# define cost/loss & optimizer
cost = tf.reduce mean(tf.nn.softmax_cross_entropy_with_logits(logits=hypothesis, labels=Y))
optimizer = tf.train.AdamOptimizer(learning rate=learning rate).minimize(cost)
```

https://github.com/hunkim/DeepLearningZeroToAll/blob/master/lab-11-1-mnist_cnn.py

```
sess = tf.Session()
sess.run(tf.global variables initializer())
# train my model
print('Learning stared. It takes sometime.')
for epoch in range(training epochs):
   avg cost = 0
   total batch = int(mnist.train.num examples / batch size)
   for i in range(total batch):
       batch_xs, batch_ys = mnist.train.next_batch(batch_size)
       feed dict = {X: batch xs, Y: batch ys}
       c, _, = sess.run([cost, optimizer], feed_dict=feed dict)
       avg cost += c / total batch
   print('Epoch:', '%04d' % (epoch + 1), 'cost =', '{:.9f}'.format(avg cost))
print('Learning Finished!')
# Test model and check accuracy
correct_prediction = tf.equal(tf.argmax(hypothesis, 1), tf.argmax(Y, 1))
accuracy = tf.reduce mean(tf.cast(correct prediction, tf.float32))
print('Accuracy:', sess.run(accuracy, feed_dict={X: mnist.test.images, Y: mnist.test.labels}))
                                     https://github.com/hunkim/DeepLearningZeroToAll/blob/master/lab-11-1-mnist cnn.py
```

initialize

Training and **Evaluation**

```
# initialize
sess = tf.Session()
sess.run(tf.global variables initializer())
# train my model
print('Learning stared. It takes sometime.')
for epoch in range(training epochs):
   avg cost = 0
   total batch = int(mnist.train.num examples / batch size)
   for i in range(total batch):
       batch_xs, batch_ys = mnist.train.next_batch(batch_size)
       feed dict = {X: batch xs, Y: batch ys}
       c, _, = sess.run([cost, optimizer], feed_dict=feed dict)
       avg cost += c / total batch
   print('Epoch:', '%04d' % (epoch + 1), 'cost =', '{:.9f}'.format(avg_cost))
print('Learning Finished!')
# Test model and check accuracy
correct_prediction = tf.equal(tf.argmax(hypothesis, 1), tf.argmax(Y, 1))
```

print('Accuracy:', sess.run(accuracy, feed_dict={X: mnist.test.images, Y: mnist.test.labels}))

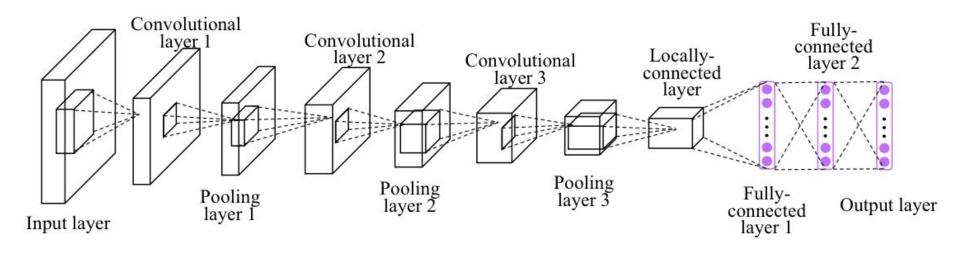
accuracy = tf.reduce mean(tf.cast(correct prediction, tf.float32))

Training and Evaluation

```
Epoch: 0001 \cos t = 0.340291267
Epoch: 0002 \cos t = 0.090731326
Epoch: 0003 \cos = 0.064477619
Epoch: 0004 \cos t = 0.050683064
Epoch: 0011 cost = 0.017758641
Epoch: 0012 cost = 0.014156652
Epoch: 0013 \cos = 0.012397016
Epoch: 0014 \cos t = 0.010693789
Epoch: 0015 \cos t = 0.009469977
Learning Finished!
Accuracy: 0.9885
```

https://github.com/hunkim/DeepLearningZeroToAll/blob/master/lab-11-1-mnist_cnn.py

Deep CNN



```
L1 = tf.nn.conv2d(X img, W1, strides=[1, 1, 1, 1], padding='SAME')
                                                                        L3 = tf.nn.relu(L3)
L1 = tf.nn.relu(L1)
                                                                        L3 = tf.nn.max pool(L3, ksize=[1, 2, 2, 1], strides=[1, 2, 2, 1],
L1 = tf.nn.max pool(L1, ksize=[1, 2, 2, 1],
                                                                        padding='SAME')
                   strides=[1, 2, 2, 1], padding='SAME')
                                                                        L3 = tf.nn.dropout(L3, keep_prob=keep_prob)
L1 = tf.nn.dropout(L1, keep prob=keep prob)
                                                                        L3 = tf.reshape(L3, [-1, 128 * 4 * 4])
'''Tensor("Conv2D:0", shape=(?, 28, 28, 32), dtype=float32)
                                                                        '''Tensor("Conv2D_2:0", shape=(?, 7, 7, 128), dtype=float32)
   Tensor("Relu:0", shape=(?, 28, 28, 32), dtype=float32)
                                                                           Tensor("Relu_2:0", shape=(?, 7, 7, 128), dtype=float32)
  Tensor("MaxPool:0", shape=(?, 14, 14, 32), dtype=float32)
                                                                           Tensor("MaxPool 2:0", shape=(?, 4, 4, 128), dtype=float32)
  Tensor("dropout/mul:0", shape=(?, 14, 14, 32), dtype=float32)'''
                                                                           Tensor("dropout_2/mul:0", shape=(?, 4, 4, 128), dtype=float32)
                                                                           Tensor("Reshape_1:0", shape=(?, 2048), dtype=float32)'''
# L2 ImgIn shape=(?, 14, 14, 32)
                                                                        # L4 FC 4x4x128 inputs -> 625 outputs
W2 = tf.Variable(tf.random normal([3, 3, 32, 64], stddev=0.01))
                                                                        W4 = tf.get variable("W4", shape=[128 * 4 * 4, 625],
    Conv \rightarrow (?, 14, 14, 64)
                                                                        initializer=tf.contrib.layers.xavier initializer())
  Pool ->(?, 7, 7, 64)
                                                                        b4 = tf.Variable(tf.random normal([625]))
L2 = tf.nn.conv2d(L1, W2, strides=[1, 1, 1, 1], padding='SAME')
                                                                        L4 = tf.nn.relu(tf.matmul(L3, W4) + b4)
L2 = tf.nn.relu(L2)
                                                                        L4 = tf.nn.dropout(L4, keep prob=keep prob)
L2 = tf.nn.max pool(L2, ksize=[1, 2, 2, 1],
                                                                        '''Tensor("Relu 3:0", shape=(?, 625), dtype=float32)
                   strides=[1, 2, 2, 1], padding='SAME')
                                                                           Tensor("dropout_3/mul:0", shape=(?, 625), dtype=float32)'''
L2 = tf.nn.dropout(L2, keep prob=keep prob)
                                                                        # L5 Final FC 625 inputs -> 10 outputs
'''Tensor("Conv2D_1:0", shape=(?, 14, 14, 64), dtype=float32)
                                                                        W5 = tf.get variable("W5", shape=[625, 10],
   Tensor("Relu_1:0", shape=(?, 14, 14, 64), dtype=float32)
                                                                        initializer=tf.contrib.layers.xavier_initializer())
  Tensor("MaxPool_1:0", shape=(?, 7, 7, 64), dtype=float32)
                                                                        b5 = tf.Variable(tf.random normal([10]))
  Tensor("dropout_1/mul:0", shape=(?, 7, 7, 64), dtype=float32)'''
                                                                        hypothesis = tf.matmul(L4, W5) + b5
                                                                        '''Tensor("add 1:0", shape=(?, 10), dtype=float32)'''
                                           https://github.com/hunkim/DeepLearningZeroToAll/blob/master/lab-11-2-mnist_deep_cnn.pv
```

L1 ImgIn shape=(?, 28, 28, 1)

Conv -> (?, 28, 28, 32)

Pool -> (?, 14, 14, 32)

W1 = tf.Variable(tf.random normal([3, 3, 1, 32], stddev=0.01))

L3 ImaIn shape=(?, 7, 7, 64)

Conv

Pool

->(?, 7, 7, 128)

->(?, 4, 4, 128)

W3 = tf.Variable(tf.random normal([3, 3, 64, 128], stddev=0.01))

Reshape ->(?, 4 * 4 * 128) # Flatten them for FC

L3 = tf.nn.conv2d(L2, W3, strides=[1, 1, 1, 1], padding='SAME')

```
W1 = tf.Variable(tf.random_normal([3, 3, 1, 32], stddev=0.01))
    Conv -> (?, 28, 28, 32)
    Pool -> (?, 14, 14, 32)
L1 = tf.nn.conv2d(X img, W1, strides=[1, 1, 1, 1], padding='SAME')
L1 = tf.nn.relu(L1)
L1 = tf.nn.max pool(L1, ksize=[1, 2, 2, 1],
                   strides=[1, 2, 2, 1], padding='SAME')
L1 = tf.nn.dropout(L1, keep prob=keep prob)
'''Tensor("Conv2D:0", shape=(?, 28, 28, 32), dtype=float32)
   Tensor("Relu:0", shape=(?, 28, 28, 32), dtype=float32)
  Tensor("MaxPool:0", shape=(?, 14, 14, 32), dtype=float32)
   Tensor("dropout/mul:0", shape=(?, 14, 14, 32), dtype=float32)'''
# L4 FC 4x4x128 inputs -> 625 outputs
W4 = tf.get variable("W4", shape=[128 * 4 * 4, 625],
initializer=tf.contrib.layers.xavier initializer())
b4 = tf.Variable(tf.random normal([625]))
L4 = tf.nn.relu(tf.matmul(L3, W4) + b4)
L4 = tf.nn.dropout(L4, keep prob=keep prob)
'''Tensor("Relu 3:0", shape=(?, 625), dtype=float32)
   Tensor("dropout 3/mul:0", shape=(?, 625), dtype=float32)'''
# L5 Final FC 625 inputs -> 10 outputs
W5 = tf.get variable("W5", shape=[625, 10],
initializer=tf.contrib.layers.xavier initializer())
b5 = tf.Variable(tf.random normal([10]))
hypothesis = tf.matmul(L4, W5) + b5
'''Tensor("add 1:0", shape=(?, 10), dtype=float32)'''
```

L1 ImgIn shape=(?, 28, 28, 1)

Deep CNN

```
Epoch: 0013 cost = 0.027188021
Epoch: 0014 cost = 0.023604777
Epoch: 0015 cost = 0.024607201
Learning Finished!
```

Accuracy: 0.9938

With TF 1.0!



Lab II-3

Class, Layers, Ensemble

Sung Kim < hunkim+ml@gmail.com>

Code: https://github.com/hunkim/DeepLearningZeroToAll/

feature extraction



https://github.com/hunkim/DeepLearningZeroToAll/



```
W1 = tf.Variable(tf.random normal([3, 3, 1, 32], stddev=0.01))
    Conv -> (?, 28, 28, 32)
    Pool -> (?, 14, 14, 32)
L1 = tf.nn.conv2d(X img, W1, strides=[1, 1, 1, 1], padding='SAME')
L1 = tf.nn.relu(L1)
L1 = tf.nn.max pool(L1, ksize=[1, 2, 2, 1],
                   strides=[1, 2, 2, 1], padding='SAME')
L1 = tf.nn.dropout(L1, keep prob=keep prob)
'''Tensor("Conv2D:0", shape=(?, 28, 28, 32), dtype=float32)
   Tensor("Relu:0", shape=(?, 28, 28, 32), dtype=float32)
  Tensor("MaxPool:0", shape=(?, 14, 14, 32), dtype=float32)
   Tensor("dropout/mul:0", shape=(?, 14, 14, 32), dtype=float32)'''
# L4 FC 4x4x128 inputs -> 625 outputs
W4 = tf.get variable("W4", shape=[128 * 4 * 4, 625],
initializer=tf.contrib.layers.xavier initializer())
b4 = tf.Variable(tf.random normal([625]))
L4 = tf.nn.relu(tf.matmul(L3, W4) + b4)
L4 = tf.nn.dropout(L4, keep prob=keep prob)
'''Tensor("Relu 3:0", shape=(?, 625), dtype=float32)
   Tensor("dropout 3/mul:0", shape=(?, 625), dtype=float32)'''
# L5 Final FC 625 inputs -> 10 outputs
W5 = tf.get variable("W5", shape=[625, 10],
initializer=tf.contrib.layers.xavier initializer())
b5 = tf.Variable(tf.random normal([10]))
hypothesis = tf.matmul(L4, W5) + b5
'''Tensor("add 1:0", shape=(?, 10), dtype=float32)'''
```

L1 ImgIn shape=(?, 28, 28, 1)

CNN

```
Epoch: 0013 cost = 0.027188021
Epoch: 0014 cost = 0.023604777
Epoch: 0015 cost = 0.024607201
Learning Finished!
```

Accuracy: 0.9938

```
def init (self, sess, name):
       self.sess = sess
       self.name = name
       self. build net()
   def build net(self):
       with tf.variable scope(self.name):
           # input place holders
           self.X = tf.placeholder(tf.float32, [None, 784])
           # img 28x28x1 (black/white)
           X \text{ img} = \text{tf.reshape}(\text{self.X}, [-1, 28, 28, 1])
           self.Y = tf.placeholder(tf.float32, [None, 10])
           # L1 ImgIn shape=(?, 28, 28, 1)
           W1 = tf.Variable(tf.random_normal([3, 3, 1, 32],
                                                   stddev=0.01))
def predict(self, x test, keep prop=1.0):
   return self.sess.run(self.logits,
        feed dict={self.X: x test, self.keep prob: keep prop})
def get accuracy(self, x test, y test, keep prop=1.0):
   return self.sess.run(self.accuracy,
    feed dict={self.X: x test, self.Y: y test, self.keep prob: keep prop})
def train(self, x data, y data, keep prop=0.7):
   return self.sess.run([self.cost, self.optimizer], feed dict={
```

self.X: x data, self.Y: y data, self.keep prob: keep prop})

class Model:

Python Class

```
# initialize
sess = tf.Session()
m1 = Model(sess, "m1")
sess.run(tf.global variables initializer())
print('Learning Started!')
# train my model
for epoch in range(training epochs):
   avg cost = 0
   total batch = int(mnist.train.num examples / batch size)
   for i in range(total batch):
       batch xs, batch ys = mnist.train.next batch(batch size)
       c, = m1.train(batch xs, batch ys)
       avg cost += c / total batc
```

```
conv1d(...): Functional interface for 1D convolution layer (e.g. temporal convolution).
conv2d(...): Functional interface for the 2D convolution layer.
conv2d_transpose(...): Transposed convolution layer (sometimes called Deconvolution).
conv3d(...): Functional interface for the 3D convolution layer.
dense(...): Functional interface for the densely-connected layer.
dropout(...): Applies Dropout to the input.
max_pooling1d(...): Max Pooling layer for 1D inputs.
max_pooling2d(...): Max pooling layer for 2D inputs (e.g. images).
max_pooling3d(...) : Max pooling layer for 3D inputs (e.g. volumes).
separable_conv2d(...): Functional interface for the depthwise separable 2D convolution layer.
```

tf.layers

https://www.tensorflow.org/api_docs/python/tf/layers

average_pooling1d(...) : Average Pooling layer for 1D inputs.

average_pooling2d(...) : Average pooling layer for 2D inputs (e.g. images).

average_pooling3d(...): Average pooling layer for 3D inputs (e.g. volumes).

batch_normalization(...): Functional interface for the batch normalization layer.

```
# L1 ImgIn shape=(?, 28, 28, 1)
W1 = tf.Variable(tf.random_normal([3, 3, 1, 32], stddev=0.01))
# Conv -> (?, 28, 28, 32)
# Pool -> (?, 14, 14, 32)

# Tillayers
```

L1 = tf.nn.conv2d(X img, W1, strides=[1, 1, 1, 1], padding='SAME')

W2 = tf.Variable(tf.random_normal([3, 3, 32, 64], stddev=0.01))

L1 = tf.nn.dropout(L1, keep prob=self.keep prob)

L1 = tf.nn.max_pool(L1, ksize=[1, 2, 2, 1], strides=[1, 2, 2, 1], padding='SAME')

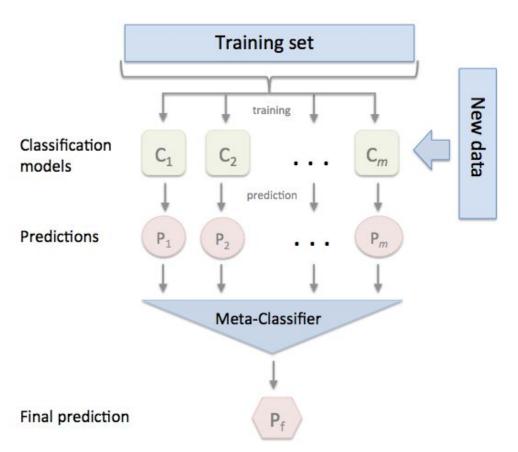
L1 = tf.nn.relu(L1)

L2 ImgIn shape=(?, 14, 14, 32)

```
# Convolutional Layer #1
conv1 = tf.layers.conv2d(inputs=X_img,filters=32,kernel_size=[3,3],padding="SAME",activation=tf.nn.relu)
pool1 = tf.layers.max_pooling2d(inputs=conv1, pool_size=[2, 2], padding="SAME", strides=2)
dropout1 = tf.layers.dropout(inputs=pool1,rate=0.7, training=self.training)

# Convolutional Layer #2
conv2 = tf.layers.conv2d(inputs=dropout1,filters=64,kernel_size=[3,3],padding="SAME",activation=tf.nn.relu)
...
flat = tf.reshape(dropout3, [-1, 128 * 4 * 4])
dense4 = tf.layers.dense(inputs=flat, units=625, activation=tf.nn.relu)
dropout4 = tf.layers.dropout(inputs=dense4, rate=0.5, training=self.training)
...
```

Ensemble



Ensemble training

```
class Model:

def __init__(self, sess, name):
    self.sess = sess
    self.name = name
    self._build_net()

def _build_net(self):
    with tf.variable_scope(self.name):
...
```

```
models = []
num models = 7
for m in range(num models):
  models.append(Model(sess, "model" + str(m)))
sess.run(tf.global variables initializer())
print('Learning Started!')
# train my model
for epoch in range(training epochs):
   avg cost list = np.zeros(len(models))
  total batch = int(mnist.train.num examples / batch size)
   for i in range(total batch):
       batch xs, batch ys =mnist.train.next batch(batch size)
      # train each model
       for m idx, m in enumerate(models):
          c, = m.train(batch xs, batch ys)
           avg cost list[m idx] += c / total batch
   print('Epoch:','%04d'%(epoch + 1),'cost =', avg cost list)
```

print('Learning Finished!')

https://github.com/hunkim/DeepLearningZeroToAll/blob/master/lab-11-5-mnist_cnn_ensemble_layers.py

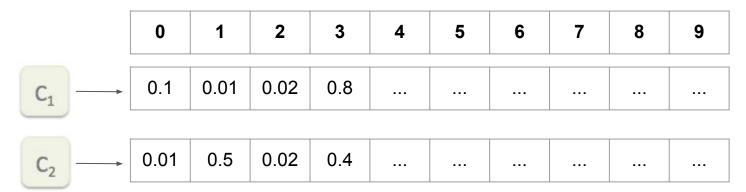
Ensemble prediction

 C_1

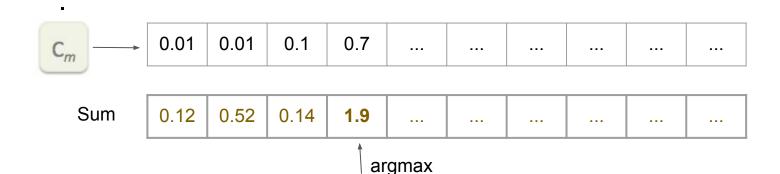
C₂

 C_m

Ensemble prediction







Ensemble prediction

```
for m_idx, m in enumerate(models):
    print(m_idx, 'Accuracy:', m.get_accuracy(mnist.test.images, mnist.test.labels))
    p = m.predict(mnist.test.images)
    predictions += p

ensemble_correct_prediction = tf.equal(
    tf.argmax(predictions, 1), tf.argmax(mnist.test.labels, 1))
ensemble_accuracy = tf.reduce_mean(
    tf.cast(ensemble_correct_prediction, tf.float32))
print('Ensemble accuracy:', sess.run(ensemble_accuracy))
6 Accuracy
```

predictions = np.zeros(test size * 10).reshape(test size, 10)

Test model and check accuracy

test_size = len(mnist.test.labels)

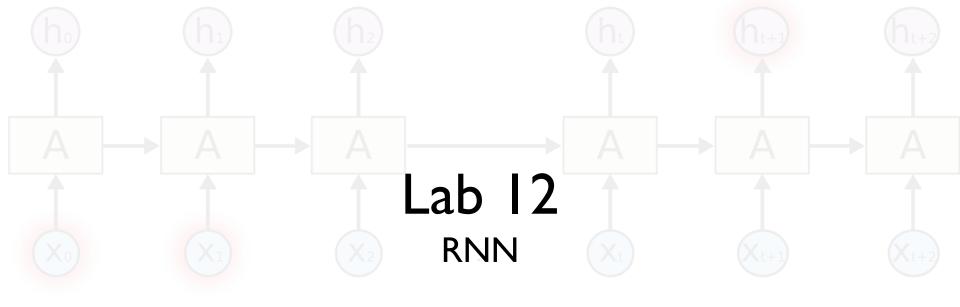
0 Accuracy: 0.9933I Accuracy: 0.99462 Accuracy: 0.99343 Accuracy: 0.99354 Accuracy: 0.99355 Accuracy: 0.99496 Accuracy: 0.9941

Ensemble accuracy: 0.9952

Exercise

- Deep & Wide?
- CIFAR 10
- ImageNet





Sung Kim <hunkim+ml@gmail.com> http://hunkim.github.io/ml/