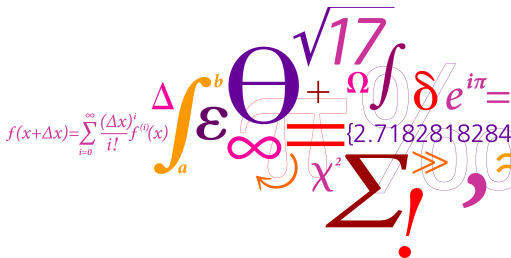


## 02224 Real-Time Systems

# An Introduction to Timed Automata using Uppaal

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## Timed Automata:

AlurDill 1994

- A *system* is a network of communication *timed automata*, put in parallel
- A *timed automaton* is a finite state machine with *clocks*
- A *clock* is a real-valued variable that is used to measure the progress of time.

## Uppaal

[www.uppaal.org](http://www.uppaal.org)

- Uppaal is a tool box for *modelling* real-time systems and for *validation* and *verification* of such systems.
- *Modelling* is timed-automata based
- *Validation* is based on simulation
- *Verification* is based on *model checking*

# A simple example (1)

Consider an **untimed** system consisting of a **Lamp** and a **User**:

- A user can switch the light **on** and **off**
- The lamp reacts appropriately on input from the user

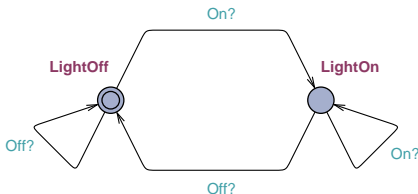


Figure: Lamp

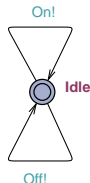
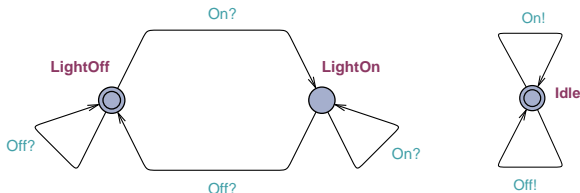


Figure:  
User

- **LightOff**, **LightOn** and **Idle** are **locations**
- **Off** and **On** are **channels**
- **Off?** and **On?** are input events
- **Off!** and **On!** are output events
- An input event **e?** may **synchronize** with an output event **e!**

## A simple example (2)



A **path** in the un-timed system is a sequence of states altered by events:

$$(LightOff, Idle) \xrightarrow{on} (LightOn, Idle) \xrightarrow{off} (LightOff, Idle) \xrightarrow{on} \dots$$

where, for example,

- $(LightOff, Idle) \xrightarrow{on} (LightOn, Idle)$  is a **transition of the system**

because

- $LightOff \xrightarrow{on?} LightOn$  is a **transition of the lamp** and
- $Idle \xrightarrow{on!} Idle$  is a **transition of the user**

## A Uppaal model comprising two lamps

- Global declarations of two channel arrays:

```
chan On[2];  
chan Off[2];
```

- The **Lamp template** contains two formal parameters:

```
chan &On, chan &Off
```

Notice that Channels and clocks must be reference parameters

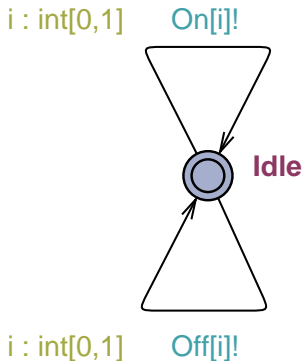
- The system declaration part contains two process assignments:

```
Lamp0 = Lamp(On[0],Off[0]);  
Lamp1 = Lamp(On[1],Off[1]);  
system Lamp0, Lamp1, User;
```

The Lamp automaton is as before.

# A user template with a selection

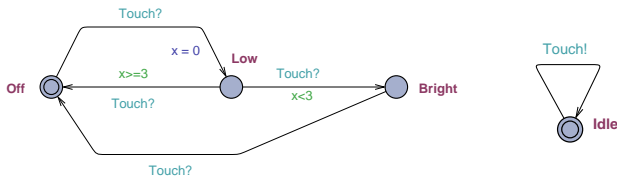
The new user automaton is:



- Both transitions contain a **selection**:  $i : \text{int}[0,1]$
- $\text{int}[0,1]$  is a type with two elements 0 and 1
- A selection denotes a family of transitions by binding  $i$  to the elements of the type

# A simple timed system (1)

- With a single **touch** on the lamp, it will give a dimmed light,
- if it is touched twice quickly, it will give a bright light; otherwise it will switch off the light

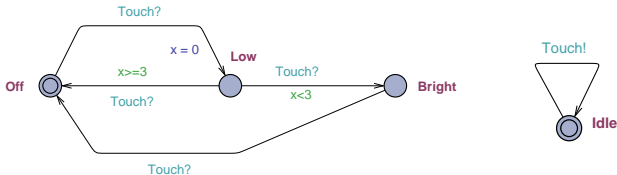


- $x$  is a real-valued **clock**
- The value of a clock can be tested in **guards**  $x < 3$  and  $x \leq 3$
- A clock can be **reset**  $x = 0$

An edge in a Uppaal template can be equipped with

- a select
- a synchronization
- a guard
- an update

# A simple timed system (2)



A **state**  $(l, v)$  of a timed automaton consist of

- a **location**  $l$ , and
- a **valuation**  $v$  giving values for the clocks

A **transition** from one state  $(l, v)$  to another  $(l', v')$  can either be

- a discrete transition  $(l, v) \xrightarrow{e} (l', v')$ , where  $e$  is an event
- a time-progress  $(l, v) \xrightarrow{d} (l, v')$ , where  $d > 0$

A **path** (ignoring the state of the user):

$e$  is Touch

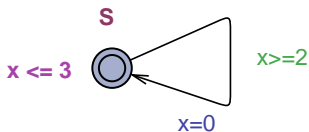
$$\begin{aligned}
 & (Off, 0) \xrightarrow{2} (Off, 2) \xrightarrow{3.44} (Off, 5.44) \xrightarrow{e} (Low, 0) \xrightarrow{2.5} (Low, 2.5) \\
 & \xrightarrow{e} (Bright, 2.5) \xrightarrow{3.1} (Bright, 5.6) \xrightarrow{e} (Off, 5.6) \xrightarrow{1.2} (Off, 6.8) \\
 & \xrightarrow{e} (low, 0) \xrightarrow{3} (Low, 3) \xrightarrow{e} (Off, 3) \xrightarrow{3} \dots
 \end{aligned}$$



# A simple timed system with an invariant

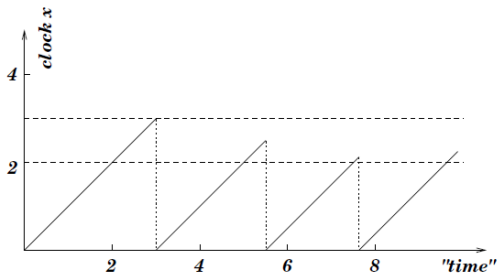
An **invariant** in a location is used to ensure progress

- $x$  cannot progress beyond 3 in location  $S$ :



Possible values of  $x$

from Uppaal Tutorial [BDL2016]



- A **clock constraint** is a conjunction of formulas of the form:

$$x \bowtie n \quad \text{or} \quad x - y \bowtie n$$

where  $x, y \in C$  are clocks,  $\bowtie \in \{<, \leq, >, \geq\}$  and  $n$  in an integer.

- $B(C)$  denotes the set of all clock constraints that can be formed from the set of clocks  $C$
- $2^C$  denotes the set of all subsets of  $C$
- $R_{\geq 0}^C$  denotes the set of functions from the set of clocks to the non-negative real numbers.
- An element  $v \in R_{\geq 0}^C$  is called a clock evaluation.
- $[r \mapsto 0]v$  denotes the clock evaluation obtained from  $v$  by mapping each clock in  $r$  to 0.

A **timed automaton** is a tuple  $(L, l_0, C, A, E, I)$ , where

- $L$  is a finite set of **locations**,
- $l_0 \in L$  is the **initial location**,
- $C$  is a finite set of **clocks**,
- $A$  is a finite set of *actions*,
- $E \subseteq L \times A \times B(C) \times 2^C \times L$  is a set of **edges**, and
- $I : L \rightarrow B(C)$  assigns **invariants** to locations.

where an edge  $(l, a, g, r, l')$  from location  $l$  to  $l'$  is decorated with

- an action  $a$  – can be input, output or internal
- a guard  $g$ ,
- a set of clocks  $r$  that is reset

The semantics of a timed automaton  $(L, l_0, C, A, E, I)$  is a labelled transition system  $(S, s_0, \longrightarrow)$ , where

- $S = \{(l, v) \in L \times \mathbb{R}_{\geq 0}^C \mid v \text{ satisfies the invariant } I(l)\}$   
is the set of **states**,
- $s_0 = (l_0, v_0)$  is the **initial state**, and
- the **transition relations**  $\longrightarrow \subseteq S \times (A \cup \mathbb{R}_{\geq 0}) \times S$  is such that
  - $(l, v) \xrightarrow{d} (l, v + d)$ , for  $d > 0$   
if  $v + d'$  satisfies the invariant  $I(l)$  for every  $d' : 0 \leq d' \leq d$ , and
  - $(l, v) \xrightarrow{a} (l', v')$   
if there is an edge  $(l, a, g, r, l') \in E$  such that
    - $v$  satisfies the guard  $g$ ,
    - $v' = [r \mapsto 0]v$ , and
    - $v'$  satisfies the invariant  $I(l')$  of the target location.

A path is **time divergent** when time grows towards infinity;  
otherwise it is **time convergent**

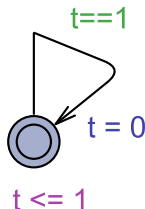
A path is **Zeno** if it is time-convergent and it performs infinitely many  
discrete actions

A state is a **deadlock** state if there are no outgoing action transitions  
neither from the state itself or any of its delay successors

A state contains a **timelock** if there is no time-divergent path starting  
from it.

Timelocks and Zeno paths represent typical modelling flaws:

- They should be avoided in the models.
- Add a test automaton to the system:



where  $t$  is a new clock

- Verify the liveness property:  $t == 0 \rightarrow t == 1$

Uppaal has some special features to control timing:

- A **channel** may be declared as **urgent**: There will be no delay if an edge with a synchronization over an urgent channel can be taken
- A **location** may be declared as **urgent**: There will be no delay in an urgent location
- A **location** may be declared as **committed**: There will be no delay in a committed location, and the next transition must involve an automaton in a committed location.

We will consider these features later in the course