Documentation

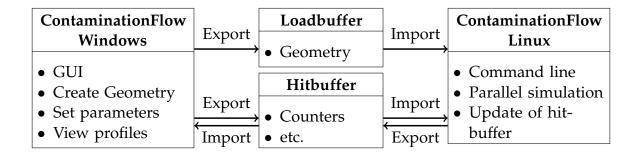
ContaminationFlow on Linux and Windows

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1. General Structure



General structure for ContaminationFlow simulation

- Code adapted from Molflow
- ContaminationFlow Windows primary used to create Geometry and to view simulation results through the GUI
- ContaminationFlow Linux primary used for simulation and calculation of counters, profiles, etc.
- Loadbuffer contains information of geometry
- Hitbuffer contains information such as hit counters, profiles, etc.
- Import and export of buffer files for communication between ContaminationFlow Windows and ContaminationFlow Linux
- Export of simulationHistory for ContaminationFlow Linux

2. ContaminationFlow Linux

- Parallel simulation on several sub processes
- Processing and control of data in main process
- Update and accumulation of hit counters and other information such as profiles
- SimulationHistory, final hitbuffer and used parameters exported to results folder

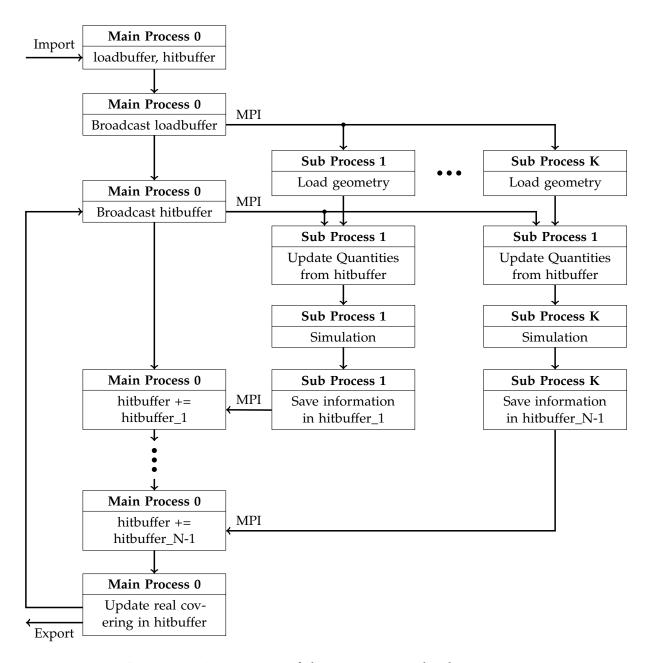


Figure 2.1.: Processing of data in main and sub processes

2.1. Call of Application from Command line

New class ProblemDef

- Defines parameters used for simulation
- Possible adaptation of default paramaters through input file
- Conducts some intern conversions
- Creates result folder for simulation if desired
 - Final resultbuffer
 - Final covering, input file and console output as text files

Application with custom parameters using input file

Call of ContaminationFlow Linux application in the command line:

```
$ module load mpi
$ mpirun -n N MolflowLinux inputfile save
```

with the following command line parameters:

- N: desired number of worker processes; simulation on K=N-1 worker processes
- MolflowLinux: path to application, e.g. ~/MolflowLinux/Debug/MolflowLinux
- inputfile: path to file that defines simulation parameters
- save: determines whether result directory is created (1: true, 0:false); default: 1

and the input file defining the following parameters:

- loadbufferPath: path to loadbuffer file, contains geometry, e.g. ~/loadbuffer
- *hitbufferPath*: path to hitbuffer file, contains counters, etc., e.g. ~/hitbuffer
- *simulationTime*: simulation time per iteration step; default: 10.0
- *unit* : simulation time unit; default: s
- *maxTime* : maximum simulation time; default: 10.0
- maxUnit: maximum simulation time unit; default: y
- *iterationNumber* : number of iterations; default: 43200
- *d* : power for base of coverage used for calculation of desorption; default: 1
- E_{de} : maximum energy used for calculation of desorption; default: 1E-21
- H_{vap} : minimum energy used for calculation of desorption; default: 1E-21
- W_{tr} : window width used for calculation of desorption; default: 1E-21
- sticking: constant sticking coefficient for all facets; default: 0.8E-19
- *coveringLimit* : threshold for zero desoprtion; default: 0
- *targetPaticles*: Minimum number of desorbed particles per iteration; default: 1000
- *targetError* : Maximum error per iteration; default: 0.001
- *hitRatioLimit*: Ratio at which hits are ignored, default: 1E-5
- *Tmin*: minimum time for step size; default: 1E-4

Terminology

- Simulation time: desired computation time until check if target is reached for iteration
- Maximum simulation time: desired total simulated time
- Step size: desired simulated time per particle for iteration

2.2. Communication

Import and export of buffer files

• New Databuff struct that replaces Dataport struct from MolFlow Windows

```
typedef unsigned char BYTE;
typedef struct {
  signed int size;
  BYTE *buff;
} Databuff;
```

- New functions importBuff(·) and exportBuff(·) for import of buffer files and export of Databuff struct
- New functions checkReadable(·) and checkWriteable(·) to check if file is readable or writeable

Communication between worker processes via MPI

- Main process 0 sends Databuff struct containing loadbuffer and Databuff struct containing hitbuffer and required simulationHistory values to sub processes using MPI_Bcast(·)
- Sub processes send updated Databuff struct containing hitbuffer and required simulationHistory values to main process 0 using MPI_Send(·) and MPI_Recv(·)

2.3. Usage of boost Library

Multiprecision

- Increase precision for variables if required
- Avoid underflow for integer and underflow for floating point numbers

2.4. New Quantities

New counter covering

- Number of carbon equivalent particles on facet
- Added covering counter to hitbuffer
- Extracted from hitbuffer from Simulationcalc.cpp file in getCovering(·)
- Covering increases with adsorption, decreases with desorption

Coverage

- Number of carbon equivalent particles per monolayer on facet
- Calculated from covering, gas mass and facet area
- Coverage computed from Simulationcalc.cpp file in calcCoverage(·)

Sticking factor

- Ratio adsorbed particles to impinging particles
- Set to 0, can be adapted for all facets through input file

Binding energy

- Calculated from E_{de} , H_{vap} and W_{tr}
- Desorption computed from Simulationcalc.cpp file in calcEnergy(⋅)

Desorption [1/s]

- Calculated from binding energy, covering and temperature
- Desorption computed from Simulationcalc.cpp file in calcDesorption(·)

Desorption Rate [Pa m³/s]

- Calculated from desorption, gas mass and facet area
- Desorption rate computed from Simulationcalc.cpp file in calcDesorptionRate(·)
- Used to determine starting point for new particle
- Updated and fixed before each interation

Outgassing Rate

- Calculated from facet outgassing and temerature defined in sHandle
- Outgassing rate computed from Worker.cpp file in CalcTotalOutgassingWorker()

K_{real/virtual}

- Number of real particles represented by test particles
- Calculated from desorption rate, outgassing rate and number of desorbed molecules
- $K_{real/virtual}$ computed from Simulationcalc.cpp file in GetMoleculesPerTP(·)

2.5. Iterative Algorithm

2.5.1. Initialization of simulation

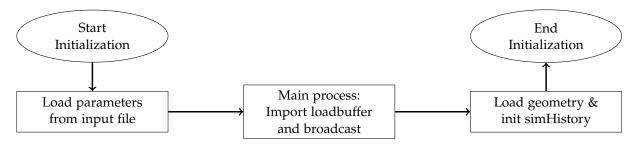


Figure 2.2.: Overview: Initialize simulation

New class to store Simulation History

• SimulationHistory class

```
class SimulationHistory {
public:
   SimulationHistory();
   SimulationHistory(Databuff *hitbuffer);

HistoryList<llong> coveringList;
HistoryList<llong> desorbedList;
HistoryList<double> hitList;
HistoryList<double> errorList;

double lastTime;
int currentStep;
};
```

```
template <typename T> class HistoryList {
public:
    HistoryList();
    std::vector<std::pair<double,std::vector<T>>> pointInTimeList;
    std::vector<T> currentList;
};
```

- In SimulationLinux.h and SimulationLinux.cpp file
- SimulationHistory updated after each iteration in UpdateCovering(·) from UpdateMainProcess.cpp file
- Currently recorded quantities: covering and error for each facet for each iteration, total hits and desorbed particles for each facet
- Time: simulated time (accumulated time steps) instead of computation time

2.5.2. Simulation on subprocesses

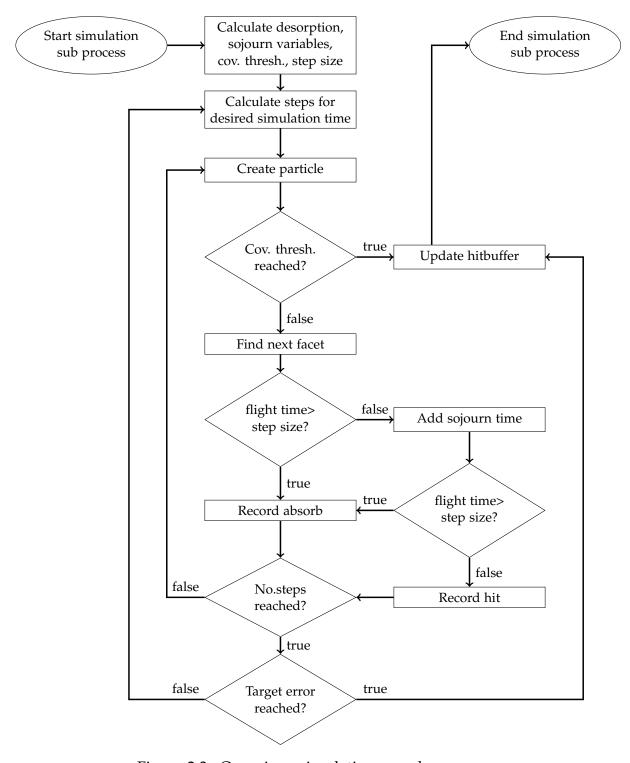


Figure 2.3.: Overview: simulation on sub processes

Set Covering Threshold

- Set lower threshold for covering for each facet to prevent covering getting negative
- Stop simulation once threshold is reached
- Threshold set in setCoveringThreshold(·) from Iteration.cpp file

Sojourn

- Sojourn time of bounce calculated from energy and frequency
- Sojourn energy equal to binding energy
- Sojourn frequency calculated from temperature

2.6. Update main buffer

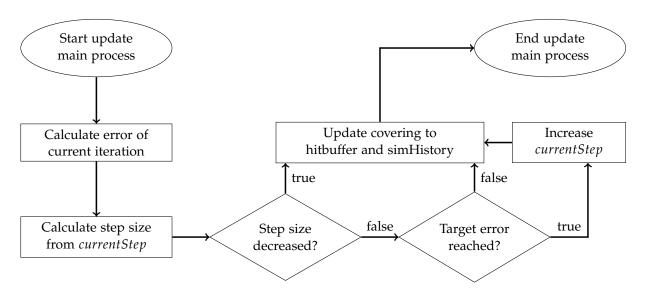


Figure 2.4.: Overview: update of covering in hitbuffer

Error Calculation

- Calculate statistical error
- Facet error calculated from hits of facet and total hits, hits weighted with opacity of facet
- Total error calculated from summing facet error weighted with facet area

Calculate Step Size

- Use SimulationHistory::currentStep to calculate logarithmic step size
- Duration between outgassing/desorption and adsorption

Management of Step Size

- Check whether current step size would cause desorption to be larger than covering
- Adapt step size if required
- Increment SimulationHistory::currentStep if step size not decreased and ProblemDef::targetError reached
- Management in UpdateMainProcess.cpp file in manageStepSize(·)

2.7. Summary

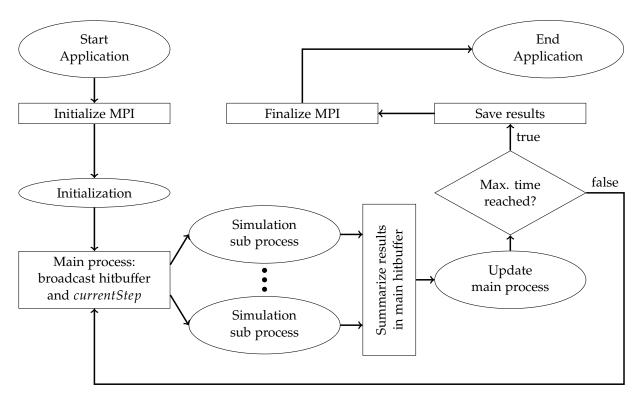


Figure 2.5.: Overview: ContaminationFlow application

General Pipeline

- Initialize MPI, ProblemDef p and SimulationHistory simHistory
- Load geometry into Simulation sHandle using LoadSimulation()
- Iteration until desired maximum simulation time is reached:
 - Reset hitbuffer counters using initbufftotero(·), broadcast using MPI_Bcast(·)
 - Simulation in sub processes
 - Simulate until targetParticles and targetError or covthresh reached
 - Update hitbuffer of sub processes from sHandle using UpdateSubHits(·)
 from UpdateSubProcess.cpp
 - Update Main process:
 - Send hitbuffer to main process using MPI_Send(·) and MPI_Recv(·)
 - Update of hitbuffer in UpdateMainHits(·) from UpdateMainProcess.cpp
 - Update error of iteration using UpdateErrorMain(·) from UpdateMainProcess.cpp
 - ullet Calculate real covering in main process using $K_{real/virtual}$ and simulated step size in UpdateCovering(\cdot) from UpdateMainProcess.cpp, save in simHistory
 - Update real covering in hitbuffer of main process in UpdateCoveringphys(·) from UpdateMainProcess.cpp
- Export final results (hitbuffer and simulationHistory) to results folder
- Close MPI

3. ContaminationFlow Windows

- Create Geometry and set parameters such as pumping speed or sticking
- Evaluate profiles such as pressure profile
- Simulation also possible for testing, but mostly done on Linux

3.1. Graphical User Interface

Add screenshot of GUI

New GUI elements

- "Particles out" renamed to Contamination level
 - Text field for covering
 - Text field for coverage
- New facet properties
 - Effective surface factor
 - Facet depth and facet volume
 - Diffusion coefficient
 - Concentration and gas mass
- Window for CoveringHistory (reworked to SimulationHistory in Contamination-Flow Linux)
- PressureEvolution window expanded
 - Added list that contains information of graph
 - Option to show only selected facets or all
 - List exportable

3.2. Communication

Import and export of buffer files via GUI

• New Databuff struct

```
typedef unsigned char BYTE;
typedef struct
  signed int size;
  BYTE *buff;
Databuff;
```

- New functions importBuff(·) and exportBuff(·) for import and export of buffer files/Databuff struct
- New options in file menu: Export buffer and Import buffer

3.3. New Quantities

New counter covering

- Covering computed in SimulationMC.cpp file in updatecovering(·)
- Added covering counter to hitbuffer
- Added covering to GUI, can be defined through textfield

New facet property effetiveSurfaceFactor

Defines increase of facet area due to texture

New facet property facetDepth

• Defines depth of facet

New facet property diffusionCoefficient

• Defines diffusion coefficient

New facet property concentration

• Defines concentration = mass of particles in volume

Removal of irrelevant quantities

- Sticking factor and pumping speed removed from GUI
- calcSticking() and calcFlow() in Molflow.cpp file not used anymore
- Flow not needed for iterative Algorithm

3.4. Iterative algorithm

New class to store covering for all facets at any time

- In HistoryWin.cpp and HistoryWin.h file
- std::vector<std::pair<double,std::vector<double>>> pointintime_list to store points in time and respective covering for all facets
- New GUI option to add and remove entries for pointintime_list
- New GUI option to export or import a complete list

A. Formulas for new Quantities

Constants

carbondiameter =
$$2 \cdot 76E - 12$$

 $K_b = 1.38E - 23$ (A.1)
 $h = 6.626E - 34$

Number of carbon equivalent particles of one monolayer

$$N_{mono} = \frac{\text{Area of Facet [m^2]}}{carbondiameter^2}$$
 (A.2)

Carbon equivalent relative mass factor

$$\Delta N_{surf} = \frac{\text{carbon equivalent gas mass}}{12.011} \tag{A.3}$$

Covering θ^*

$$\theta^* = N_{\text{particles on facet}}$$
 (A.4)

Coverage θ

$$\theta = \frac{\theta^*}{N_{mono}/\Delta N_{surf}} \tag{A.5}$$

Energy *E*

$$E = \frac{E_{de} - H_{vap}}{2} \cdot \tanh\left(\left(1 - coverage\right) \cdot \frac{5.4}{W_{tr}}\right) + \frac{E_{de} + H_{vap}}{2} \tag{A.6}$$

Sojourn

$$Frequency = \frac{K_b T}{h}$$

$$Energy = E$$
(A.7)

Desorption rate des

$$\tau = \frac{h}{K_b T}$$

$$des = \begin{cases} \frac{1}{\tau} \theta^d \exp\left(-\frac{E}{K_b T}\right) \cdot \frac{N_{mono}}{\Delta N_{surf}} \cdot K_b T, & \text{if } \theta^* \ge \text{covering limit} \\ 0, & \text{otherwise} \end{cases}$$
(A.8)

Outgassing rate out

$$out = \frac{\text{Facet outgassing}}{K_h T} \tag{A.9}$$

K_{real/virtual}

$$K_{\text{real/virtual}} = \frac{\sum_{\text{facets}} \left(out + \frac{des}{K_b T} \right)}{\text{number of total desorbed molecules}}$$
(A.10)

Step Size T_{step}

$$T_{min} = \text{Tmin}$$

$$T_{i} = T_{min} \cdot \exp\left(i \cdot \ln(\text{max. simulation time}/T_{min})/\text{max. # of steps}\right) \qquad (A.11)$$

$$T_{step} = T_{currentStep+1} - T_{currentStep}$$

Error

$$error = \left(\frac{1}{\text{(hits + desorbed) on facet}} \cdot \frac{1 - \text{(hits + desorbed) on facet}}{\text{total (hits + desorbed)}}\right)^{0.5} \tag{A.12}$$

B. Overview of new Classes and Functions

B.1. New Classes

SimulationHistory		
coveringList	of class HistoryList, stores covering history	
errorList	of class HistoryList, stores error history	
hitList	of class HistoryList, stores hits for each facet	
desorbedList	of class HistoryList, stores desorbed particles for each facet	
numFacet	number of Facets	
numSubProcess	number of sub processes used for simulation	
nbDesorbed_old	number of total desorbed molecules of previous iteration ⇒ To calculate difference between consecutive iterations	
flightTime	number of Facets	
nParticles	Simulated flight time for iteration	
numFacet	Simulated particles for iteration	
lastTime	Total simulated time = last time in Lists	
currentStep	step of logarithmic time step calculation in <pre>getStepSize()</pre>	
updateHistory()	Reset and update from hitbuffer	
appendList()	Updates coveringList from hitbuffer	
print()	Print to terminal	
write()	Write to file	

HistoryList		
pointInTimeList	list containing history respective facet values	
currentList	list containing facet values at current step	
appendCurrent()	Appends currentList to pointInTimeList	
appendList()	Append input list to pointInTimeList	
convertTime()	Converts time for better clarity	
print()	Print pointInTimeList as table to terminal, optional message	
printCurrent()	Print currentList as table to terminal, optional message	
write(), read()	Write to file, read from file	
setCurrentList()	Set value of desired facet in currentList	
getCurrent()	Get value of desired facet from currentList	
setLast()	Set value of desired facet from pointInTimeList	
getLast()	Get value of desired facet from pointInTimeList	

ProblemDef		
resultpath	Path of result folder	
outFile	Path of file that contains terminal output	
loadbufferPath	Path of loadbuffer file	
hitbufferPath	Path of hitbuffer file	
simulationTime, unit ⇒simulationTimeMS	Computation time of each iteration in milliseconds	
maxTime, maxUnit ⇒maxTimeS	Maximal total simulated time in seconds	
iterationNumber	Number of iterations	
d	Parameter to calculate desorption rate, see equation A.8	
E_de, H_vap, W_tr	Parameters to calculate binding energy, see equation A.6	
sticking	Sticking factor for all facets	
coveringLimit	Covering limit for zero desorption	
targetParticles/-Error	Target values for each iteration	
hitRatioLimit	Limit of hitratio to ignore hits	
Tmin	Minimum step size	
readInputfile()	Initialization from input file	
printInputfile()	Print to terminal	

B.2. New Functions

B.2.1. molflowlinux_main.cpp

Preprocessing		
parametercheck()	Checks validity of input parameters from input file Defines values for ProblemDef object p	
importBuff()	Import load- and hitbuffer to main process	
MPI_Bcast()	Send loadbuffer to sub processes	
LoadSimulation()	Load geometry from loadbuffer	
initCoveringThresh()	Initialize covering threshold	
simHistory	Initialize SimulationHistory object	

Simulation Loop		
initbufftozero()	Reset all hitbuffer counters except covering	
MPI_Bcast()	Send hitbuffer and simHistory→currentStep to sub processes	
setCoveringThreshold()	Sets covering threshold for each facet	
UpdateDesorptionRate()	Sets desorption for each facet	
UpdateSojourn()	Sets sojourn variables for each facet	
simulateSub()	Simulation on sub processes	
MPI_Send(), MPI_Recv()	Send sub hitbuffer to main process	
UpdateMCMainHits()	Add simulation results from sub hitbuffer to main hitbuffer	
UpdateErrorMain()	Calculate and save error of iteration to simHistory	
UpdateCovering()	Calculate and save new covering to simHistory	
UpdateCoveringphys()	Saves current covering to hitbuffer	
End simulation if maximum simulation time is reached		

Postprocessing	
exportBuff()	Export final hitbuffer
simHistory→write()	Export simulation history

B.2.2. SimulationLinux.cpp

simulateSub()		
targetParticles, targetError	Calculate target values from overall target and number sub processes	
simHistory->updateHistory()	Reset and Update SimulationHistory object from hitbuffer	
SimulationRun()	Simulate for desired simulation time	
UpdateError()	Calculate current error of sub process End simulation if targets or covthresh reached	
UpdateMCSubHits()	Save simulation results to hitbuffer	

B.2.3. Calculations in SimulationCalc.cpp etc.

SimulationCalc.cpp		
getCovering()	Get covering from hitbuffer	
getHits()	Get number of hits from hitbuffer	
getnbDesorbed()	Get number of total desorbed molecules from hitbuffer	
calcNmono()	see equation A.2	
calcdNsurf()	see equation A.3	
calcCoverage()	see equation A.5	
calcEnergy()	see equation A.6	
calcStickingnew()	sets sticking coefficient to p→sticking	
<pre>calcDesorption(), calcDesorptionRate()</pre>	see equation A.8	
GetMoleculesPerTP()	see equation A.10	
calctotalDesorption	calculates desorption for startFromSource()	
calcPressure(), calcParticleDensity()	TODO has to be verified	

worker.cpp	
CalcTotalOutgassingWorker()	see equation A.9, calculates outgassing
Care rotare atgassing (Vorker()	for startFromSource()

SimulationLinux.cpp	
covertunit()	Converts simutime*unit to milliseconds

B.2.4. UpdateSubProcess.cpp

Update sHandle paramters from hitbuffer	
UpdateSticking()	Updates sticking
UpdateDesorptionRate()	Updates desorption rate
UpdateSojourn()	Updates sojourn freqency and energy
UpdateError()	Updates error for current iteration, see equation A.12

Update hitbuffer		
initbufftozero()	Sets hitbuffer except covering to zero	
UpdateMCSubHits()	Saves simulation results from sHandle into hitbuffer	

B.2.5. UpdateMainProcess.cpp

Update main hitbuffer from sub hitbuffer		
UpdateMCMainHits()	Add simulation results from sub hitbuffer to main hitbuffer	

Update real covering in hitbuffer		
getStepSize()	Calculates step size for current step, see equation A.11	
manageStepSize()	Adapts step size if desorption rate \cdot step size $>$ than covering	
UpdateCovering()	Uses step size and Krealvirt to calculate new covering Saved to simHistory→coveringList	
UpdateCoveringphys()	Saves current real covering to hitbuffer	
UpdateErrorMain()	Calculates total error, see equation A.12 Saved to simHistory→errorList	
CalcPerIteration()	Calculates total error and covering over all facets per iteration	

B.2.6. Iteration.cpp

Set Covering Threshold to avoid negative covering		
initCoveringThresh()	Initializes size of covering threshold vector	
setCoveringThreshold()	Sets covering threshold for each facet	

B.2.7. Buffer.cpp

Buffer functions		
Databuff struct()	signed int size BYTE *buff	
checkReadable()	Checks if file can be opened for reading	
checkWriteable()	Checks if file can be openend or created for writing	
importBuff()	Imports buffer file to Databuff struct	
exportBuff()	Exports Databuff struct to buffer file	