Documentation

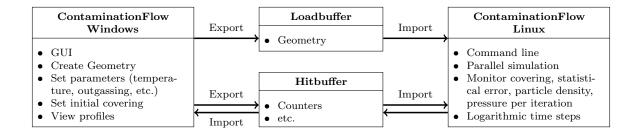
ContaminationFlow on Linux and Windows

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1. General Structure



General structure for ContaminationFlow simulation

- Code adapted from Molflow
- ContaminationFlow Windows primary used to create Geometry and to view simulation results through the GUI
- ContaminationFlow Linux primary used for simulation and calculation of counters, profiles, etc.
- Loadbuffer contains information of geometry
- Hitbuffer contains information such as hit counters, profiles, etc.
- Import and export of buffer files for communication between ContaminationFlow Windows and ContaminationFlow Linux
- Export of simulationHistory for ContaminationFlow Linux

2. ContaminationFlow Linux

- Parallel simulation on several sub processes
- Processing and control of data in main process
- Update and accumulation of hit counters and other information such as profiles
- SimulationHistory, simulation parameters, console output exported to results folder

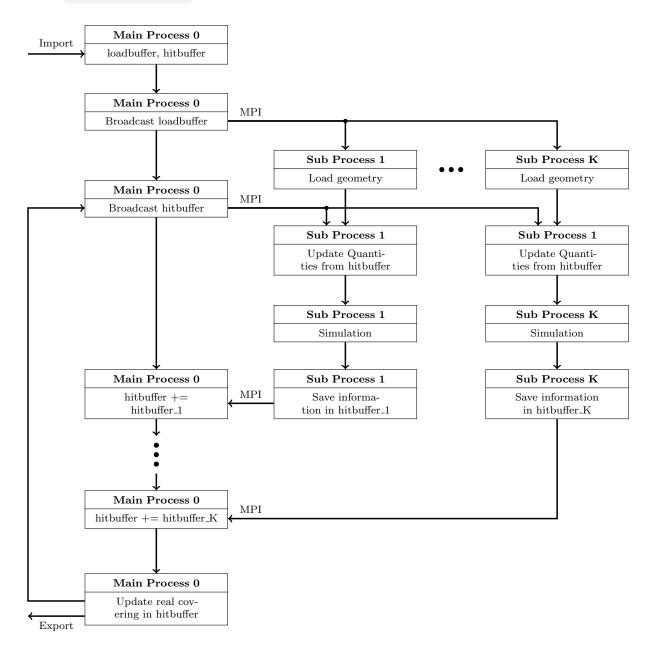


Figure 2.1.: Processing of data in main and sub processes

2.1. Call of Application from Command line

New class ProblemDef

- Defines parameters used for simulation
- Possible adaptation of default parameters through input file
- Creates result folder for simulation if desired:
 - Final covering, error, pressure, particle density as text files
 - Input file and console output as text files

Application with custom parameters using input file

Requirements: Input and buffer files readable, $N \geq 2$, zero moments in loadbuffer Call of ContaminationFlow Linux application in the command line:

```
$ module load mpi
$ mpirun -n N MolflowLinux inputfile save
```

with the following command line parameters:

- N: desired number of worker processes; simulation on K=N-1 worker processes
- MolflowLinux: path to application, e.g. ~/MolflowLinux/Debug/MolflowLinux
- inputfile: path to file that defines simulation parameters
- save: determines whether result directory is created (1: true, 0:false); default: 1

and the input file defining the following parameters:

- loadbufferPath: path to loadbuffer file, contains geometry, e.g. ~/loadbuffer
- hitbufferPath: path to hitbuffer file, contains counters, etc., e.g. ~/hitbuffer
- simulationTime: simulation time per iteration step; default: 10.0
- unit: simulation time unit; default: s
- maxTime: max. simulated time; default: 10.0
- maxUnit: max. simulated time unit; default: y
- iterationNumber: number of iterations; default: 43200
- particleDia: diameter of particles; default: 2.76E-10
- E_{de} : binding energy of a particle on pure substrate; default: 1.6E-19
- H_{vap} : vaporization enthalpy of a particle if multilayer contamination; default: 0.8E-19
- sticking: constant sticking coefficient for all facets; default: 0
- errorMode: Type of error monitored, "covering" or "event"; default: covering
- targetPaticles: min. number of desorbed particles per iteration; default: 1000
- targetError: avg. statistical uncertainty (error) to be achieved for each iteration, calculated as the avg. (weighted with the facets area) of the normalized standard deviation of events per facet; default: 0.001
- hitRatioLimit: Ratio (facet/all), e.g., number events or covering change, at which facet is ignored for error calculation; default: 0
- t_min: min. time for step size; default: 1E-4
- t_max: max. time for step size; default: max
- maxTimePerIt: max. simulation time [s] per iteration; default: max
- coveringMinThresh: min. covering (through multiplication); default: 1000000
- histsize: Size of history lists; default: max

- *vipFacets*: very important facets: facets with own target error. Alternating sequence of facet numbers and respective target errors separated via blanks; default: []
- outgassingTimeWindow: Duration [s] of outgassing impulse; default: 0.0
- counterWindowPercent: Percentage of step size (posterior) at which velocity counters are increased; default: 0.1
- desWindowPercent: Percentage of step size (anterior) at which desorption occurs; default: 1.0
- rollingWindowSize: Number of iterations for avg. statistics; default: 10
- convergenceTarget: Target for avg. statistics to indicate convergence; default: 1
- stopConverged: Stop simulation if avg. statistics indicate convergence; default: 1
- convergenceTime: Min. simulated time to stop simulation if converged; default: 0

Terminology

- Simulation time: desired computation time until check if target is reached for iteration
- Simulated time: physical time in the simulated system, e.g. flight time of particle
- Maximum simulated time: desired total simulated time
- Step size: desired simulated time per particle for iteration

2.2. Communication

Import and export of buffer files

New Databuff struct that replaces Dataport struct from MolFlow Windows

```
typedef unsigned char BYTE;
typedef struct {
   signed int size;
   BYTE *buff;
} Databuff;
```

- New functions importBuff(·) / exportBuff(·) to import buffer/export Databuff struct
- New functions checkReadable() / checkWriteable() to check if file is readable/writeable

Communication between worker processes via MPI

- Main process 0 sends Databuff structs containing loadbuffer/hitbuffer and required simulationHistory values to sub processes using MPI_Bcast(·)
- Sub processes send updated Databuff struct containing hitbuffer and required simulationHistory values to main process 0 using MPI_Send(·) and MPI_Recv(·)

2.3. Usage of *boost* Library

Multiprecision

- Increase precision for variables if required (float128, uint_128t)
- Avoid overflow for integer and underflow for floating point numbers

2.4. New Quantities

New counter covering

- Number of carbon equivalent particles on facet
- Increases with adsorption, decreases with desorption
- Extracted from new FacetHitBuffer counter in getCovering(·) (Simulationcalc.cpp)

Coverage

- Number of monolayers of adsorbed particles
- Calculated from covering, particle diameter (previously gas mass) and facet area
- Coverage computed in calcCoverage(·) (Simulationcalc.cpp)

Sticking factor

- Ratio adsorbed particles to impinging particles
- Set to value specified in input file in calcStickingnew(.) (Simulationcalc.cpp)

Binding energy

- Either E_{de} or H_{vap} , depending on the how many layers of particles are adsorbed.
- If coverage is smaller than a monolayer, it will be decided at random.
- Used in StartFromSource(·) & PerformBounce(·) (SimulationMC.cpp) and calcDesorption(·) & calcStartTime(·) (SimulationCalc.cpp)

Desorption

- Number of particles desorbing
- Calculated from binding energy, covering, temperature and step size
- Desorption computed in calcDesorption(·) (Simulationcalc.cpp)

Outgassing

- Number of particles from outgassing
- Calculated from facet outgassing, temperature, and outgassing time
- Outgassing computed in CalcTotalOutgassingWorker() (Worker.cpp)

$K_{\mathsf{real/virtual}}$

- Number of real particles represented by test particles
- Calculated from desorption & outgassing and number of desorbed molecules
- $K_{\text{real/virtual}}$ computed in GetMoleculesPerTP(·) (Simulationcalc.cpp)

Statistical error

- Event error: calculated from hits and desorbed particles (of facet and total)
- Covering error: calculated from adsorbed and desorbed particles (of facet and total)
- Used to determine significance of simulation results of iteration
- Error calculated in UpdateErrorList(·) for facet error & UpdateErrorAll(·) for average error weighted with area (UpdateSubProcess.cpp)

Step size

- Minimum time between adsorption and desorption
- Step size computed in getStepSize() (UpdateMainProcess.cpp)

Particle density

- Calculated from sum over reciprocal of orthogonal velocity, facet area and $K_{\rm real/virtual}$
- Particle density computed in calcParticleDensity(·) (Simulationcalc.cpp)

Pressure

- Calculated from sum over orthogonal velocity, facet area, gas mass and $K_{\rm real/virtual}$
- Pressure computed in calcPressure(·) (Simulationcalc.cpp)

Start time

- Determines time of desorption/outgassing for particle based on the distribution
- Desorption rate: exponential distribution for whole iteration
- Outgassing: uniform distribution of limited time for whole simulation
- Start time computed in calcStartTime(·) (Simulationcalc.cpp)

2.5. Iterative Algorithm

2.5.1. Initialization of simulation

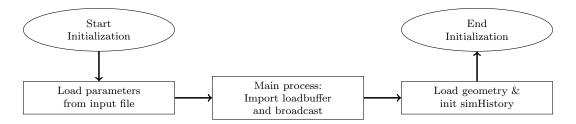


Figure 2.2.: Overview: Initialize simulation

New class to store Simulation History

• HistoryList and SimulationHistory class

```
template <typename T> class HistoryList {
public:
    HistoryList();
    pair<vector<double>,vector<vector<T>>> historyList;//(vec(time), vec(facets))
    vector<pair<float128,float128>> statisticsList;//vec(mean, std)
    vector<T> currentList;//facets
};
```

```
class SimulationHistory {
public:
   SimulationHistory();
   SimulationHistory(Databuff *hitbuffer);

HistoryList<uint_128t> coveringList;//covering
HistoryList<1long> desorbedList;//Number desorbed paticles
HistoryList<double> hitList;//MC hits
HistoryList<double> errorList_event;//error event: hits & desorbed particles
HistoryList<double> errorList_covering;//error covering: desorbed & adsorbed
HistoryList<double> particleDensityList;
HistoryList<double> pressureList;

double lastTime;
int currentStep;
};
```

- In SimulationLinux.h and SimulationLinux.cpp file
- Updated after each iteration in UpdateParticleDensityAndPressure(·), UpdateCovering(·), UpdateErrorMain(·) (UpdateMainProcess.cpp)
- Recorded quantities: covering, error (event and covering), particle density and pressure for each facet and iteration, total hits and desorbed particles for each facet
- lastTime: simulated time (accumulated time steps) instead of computation time

2.5.2. Simulation on subprocesses

Calculate step size

• Calculation from simHistory -> currentStep in getStepSize() (UpdateMainProcess.cpp)

Calculate covering threshold

- Set lower threshold for covering for each facet to prevent covering getting negative
- Stop simulation once threshold is reached
- Threshold set in setCoveringThreshold(·) (Iteration.cpp)

Multiply small covering

- Multiply covering so that smallest covering > ProblemDef::coveringThreshMin
- Multiply covering threshold with same factor
- Calculation in checkSmallCovering(·) (SimulationLinux.cpp)

Calculate desorption and outgassing

- Desorption from covering in UpdateDesorption(·) (UpdateSubProcess.cpp)
- Outgassing in CalcTotalOutgassingWorker() (Worker.cpp)

Create particle and calculate start time

- Facet randomly selected based on total desorption and outgassing
- Desorption or outgassing randomly selected based on ratio on facet
- Start time randomly generated based on distribution of desorption or outgassing
- Calculation in StartFromSource(·) (SimulationMC.cpp)

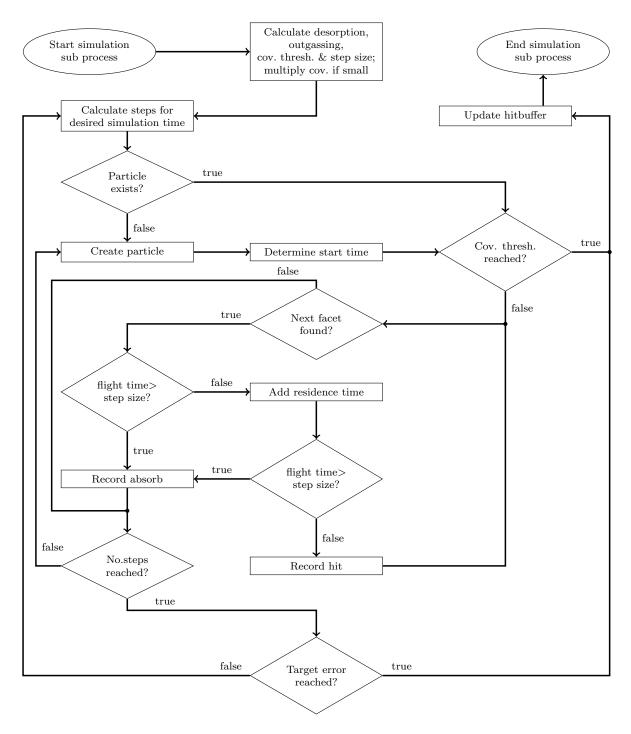


Figure 2.3.: Overview: simulation on sub processes

Calculate residence time

• Sojourn time randomly calculated from binding energy, facet temperature and sojourn frequency in PerformBounce(·) (SimulationMC.cpp)

Increase facet counters in case of desorb, absorb or hit

- Increase hit, desorb or absorb counter according to event
- ullet Increase velocity counters only if event within $\mathtt{p} { o} \mathtt{counterWindowPercent}$
- Facet counters increased in IncreaseFacetCounter(·) (SimulationMC.cpp)

Target error reached?

- Calculate statistical error in UpdateError() from UpdateSubProcess.cpp file
- Avg. error calculated from summing facet error weighted with facet area
- Error to check can be either covering or event error (currently covering)
 - Check if vip facets reached their own target error
 - Check if avg. error reached target error
- Facets with error=inf are not considered
 - Facets that reached ProblemDef::hitRatioLimit
 - Facets with no events or covering change
 - If vip facet: own target error automatically reached
 - If normal facet: facet error and area not used for calculation
- Check in checkErrorSub(·) (UpdateSubProcess.cpp)

2.6. Update main buffer

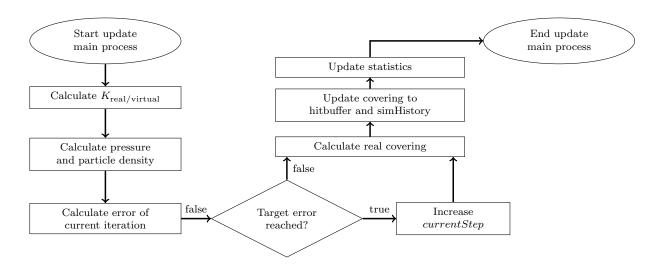


Figure 2.4.: Overview: update of covering in hitbuffer

Before summation of subprocesses

- Calculate step size in getStepSize() (UpdateMainProcess.cpp)
- Multiply covering in hitbuffer of main process analogous to sub processes in checkSmallCovering(·) (SimulationLinux.cpp)

Calculate pressure and particle density

- Calculation in UpdateParticleDensityAndPressure(·) (UpdateMainProcess.cpp)
- Values per facet saved in simHistory—pressureList / simHistory—particleDensityList

Calculate error

- Calculation analogous to sub processes in UpdateErrorMain(·) (UpdateMainProcess.cpp)
- Save error per facet in simHistory—errorList_event / simHistory—errorList_covering ⇒ Increase simHistory—currentStep if target errors reached

Calculate & update covering

- $K_{\mathrm{real/virtual}}$ computed in GetMoleculesPerTP(·) (Simulationcalc.cpp)
- Divide covering in hitbuffer if previously multiplied
- Use $K_{\text{real/virtual}}$ to calculate new covering
- Save new covering in simHistory—coveringList and hitbuffer
- Calculation in UpdateCovering(·) from UpdateMainProcess.cpp file
- Update buffers in UpdateCoveringPhys(·) (UpdateMainProcess.cpp)

Calculate & update statistics

- Calculate mean and std of covering over last p→rollingWindowSize iterations
- Update statistics in HistoryList::updateStatistics(·) (SimulationLinux.h)
- End simulation if p→convergenceTarget is reached by avg. statistics weighted with area which is calculated in HistoryList::getAverageStatistics(·) (SimulationLinux.h)

2.7. Summary

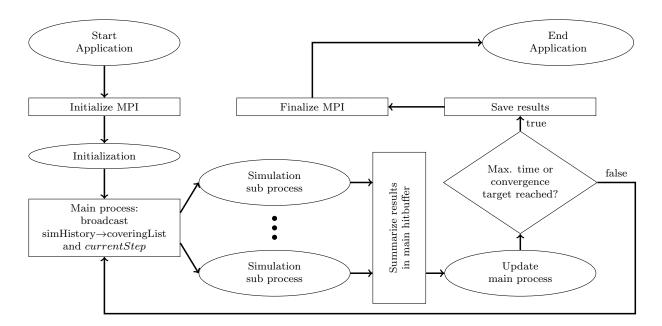


Figure 2.5.: Overview: ContaminationFlow application

General Pipeline

- Initialize MPI, ProblemDef p and SimulationHistory simHistory
- Load geometry into Simulation sHandle using LoadSimulation()
- Iteration until $p\rightarrow maxTimeS$ or $p\rightarrow convergenceTarget$ is reached:
 - Reset hitbuffer counters using initbufftotero(·)
 - Broadcast simHistory→coveringList using MPI_Bcast(·)
 - Set covering threshold covthresh using setCoveringThreshold()
 - Update relevant simulation values using simHistory→updateStepSize(·),
 UpdateSticking(·), CalcTotalOutgassingWorker(·), UpdateDesorption(·)
 - Multiply covering and covthresh with simHistory—smallCoveringFactor if covering is small
 - Simulation in sub processes
 - Simulate until targetParticles and targetError or covthresh reached
 - Update hitbuffers of sub processes from sHandle using UpdateSubHits(·) (UpdateSubProcess.cpp)
 - Update Main process:
 - Send hitbuffer to main process using MPI_Send(·) and MPI_Recv(·)
 - Update of hitbuffer in UpdateMainHits(·) (UpdateMainProcess.cpp)
 - Update pressure and particle density using UpdateParticleDensityAndPressure(·) (UpdateMainProcess.cpp), save in simHistory
 - Update error of iteration using UpdateErrorMain(·) (UpdateMainProcess.cpp), save in simHistory
 - Calculate real covering in main process using $K_{\text{real/virtual}}$ in UpdateCovering(·) (UpdateMainProcess.cpp), save in simHistory
 - Update real covering in hitbuffer of main process in UpdateCoveringphys(·) (UpdateMainProcess.cpp)
 - Update statistics using simHistory→coveringList.updateStatistics(·)
- Export final results (simHistory lists) to results folder
- Close MPI

3. ContaminationFlow Windows

• Create Geometry and set parameters such as initial coverage and temperature

3.1. Graphical User Interface

Add screenshot of GUI

New GUI elements

- "Particles out" renamed to Contamination level
 - Text field for covering
 - Text field for coverage
- New facet properties
 - Effective surface factor
 - Facet depth and facet volume
 - Diffusion coefficient
 - Concentration and gas mass
- Window for CoveringHistory (reworked to SimulationHistory in ContaminationFlow Linux)
- PressureEvolution window expanded
 - Added list that contains information of graph
 - Option to show only selected facets or all
 - List exportable

3.2. Communication

Import and export of buffer files via GUI

• New Databuff struct

```
typedef unsigned char BYTE;
typedef struct
  signed int size;
  BYTE *buff;
Databuff;
```

- New functions importBuff(·) and exportBuff(·) for import and export of buffer files/Databuff struct
- New options in file menu: Export buffer and Import buffer

3.3. New Quantities

New counter covering

• Covering computed in SimulationMC.cpp file in updatecovering(.)

- Added covering counter to hitbuffer
- Added covering to GUI, can be defined through textfield

New facet property effetiveSurfaceFactor

• Defines increase of facet area due to texture

New facet property facetDepth

• Defines depth of facet

New facet property diffusionCoefficient

• Defines diffusion coefficient

New facet property concentration

• Defines concentration = mass of particles in volume

Removal of irrelevant quantities

- Sticking factor and pumping speed removed from GUI
- calcSticking() and calcFlow() in Molflow.cpp file not used anymore
- Flow not needed for iterative Algorithm

3.4. Iterative algorithm

New class to store covering for all facets at any time

- In HistoryWin.cpp and HistoryWin.h file
- std::vector<std::pair<double,std::vector<double>>> pointintime_list to store points in time and respective covering for all facets
- New GUI option to add and remove entries for pointintime_list
- New GUI option to export or import a complete list

A. Formulas for new Quantities

Constants

$$k_b = 1.38 \, 10^{-23}$$

 $h = 6.626 \, 10^{-34}$ (A.1)
 $N_A = 6 \, 10^{23}$

Variables

$$T = \text{Facet temperature}$$
 (A.2)

Number of carbon equivalent particles of one monolayer

$$N_{mono} = \frac{\text{Area of Facet } [\text{m}^2]}{\text{ProblemDef::particleDia}^2 [\text{m}^2]}$$
(A.3)

Carbon equivalent relative mass factor

$$\Delta N_{surf} = \frac{\text{carbon equivalent gas mass}}{12.011} \tag{A.4}$$

Covering θ^*

$$\theta^* = N_{\text{particles on facet}}$$
 (A.5)

Coverage θ

$$\theta = \frac{\theta^*}{N_{mono}/\Delta N_{surf}} \tag{A.6}$$

Binding energy E

$$E = \begin{cases} E_{de}, & \text{if particle binds with substrate} \\ H_{vap}, & \text{if particle binds with adsorbate} \end{cases}$$
 (A.7)

Residence time τ

$$A = \exp\left(-E/(k_b T)\right), \ \tau_0 = \frac{k_b T}{h}$$

$$\tau = \frac{-\ln(rnd) \cdot \tau_0}{A}$$
(A.8)

Step size t_{step}

 $t_{min} = \text{ProblemDef::t_min}$

$$t_i = t_{min} \cdot \exp\left(i \cdot \ln(\text{ProblemDef::maxTimeS}/T_{min})/\text{ProblemDef::iterationNumber}\right)$$

$$t_{step} = \min(t_{currentStep+1} - t_{currentStep}, \text{ProblemDef::t_max})$$
(A.9)

Desorption des

$$\tau_0 = \frac{h}{k_b T}, \ \tau_{subst} = \tau_0 \cdot \exp\left(\frac{E_{de}}{k_b T}\right), \ \tau_{ads} = \tau_0 \cdot \exp\left(\frac{H_{vap}}{k_b T}\right), \ t_{ads} = \tau_{ads} \cdot (\theta - 1)$$

$$des = \begin{cases} 0, & \text{if } \theta = 0 \text{ or } T = 0 \\ \theta \cdot (1 - \exp(-t_{step}/\tau)), & \text{else if } \theta \le 1 \\ t_{step}/\tau_{ads}, & \text{else if } \theta - 1 \ge t_{step}/\tau_{ads} \\ \theta - 1 + (1 - \exp(-(t_{step} - t_{ads}/\tau))), & \text{else if } \theta - 1 < t_{step}/\tau_{ads} \end{cases}$$
(A.10)

Outgassing out

$$out = \frac{\text{Facet outgassing}}{k_b T} \tag{A.11}$$

Particle density

$$density = \frac{\text{sum over reciprocal of orthogonal velocity}}{\text{Area of Facet } [\text{m}^2] \cdot t_{step}} \cdot K_{\text{real/virtual}}$$
(A.12)

Pressure [mbar]

$$density = \frac{\text{sum over orthogonal velocity}}{\text{Area of Facet } [\text{m}^2] \cdot t_{step}} \cdot \frac{\text{carbon equivalent gas mass}}{1000/N_A} \cdot 0.01 \cdot K_{\text{real/virtual}}$$
(A.13)

Small covering factor

mincov = Smallest covering on a single facet that desorbs

 $small\ covering\ factor = \begin{cases} 1, & \text{if}\ mincov \geq ProblemDef::coveringMinThresh} \\ 1 + 1.1 \cdot (ProblemDef::coveringMinThresh/mincov), & \text{otherwise} \end{cases}$ (A.14)

 $K_{\text{real/virtual}}$

$$K_{\text{real/virtual}} = \frac{\sum_{\text{facets}} \left(out + des \right)}{\text{number of total desorbed molecules/small covering factor}}$$
(A.15)

Statistical error

$$\operatorname{error}(counter) = \begin{cases} inf & \text{if } (counter) \text{ on facet } = 0 \\ \left(\frac{1}{(counter) \text{ on facet}} \cdot \frac{1 - (counter) \text{ on facet}}{\operatorname{total}(counter)}\right)^{0.5} & \text{, else} \end{cases}$$
(A.16)

error_covering = error(adsorbed particles + desorbed particles)
error_event = error(hits + desorbed particles)

B. Datatypes

B.1. Boost

Datatype	Alias
boost::multiprecision::uint_128t	$uint_{-}128t$
boost::multiprecision::float128	float128

B.2. Class Members

Name	Datatype	Note
SimulationHistory::coveringList	uint_128t	
FacetHitBuffer::covering	llong	hitbuffer & tmpcounter
FacetProperties::desorption	float128	
Simulation::coveringThreshold	llong	

B.3. Functions

Function	Output Datatype	Relevant Input
getCovering()	float128	SimulationHistory::coveringList
getCovering()	llong	FacetHitBuffer::covering
calcCoverage()	float128	getCovering()
calcDesorption()	float128	calcCoverage()
calctotalDesorption()	float128	FacetProperties::desorption
GetMoleculesPerTP()	float128	FacetProperties::desorption

C. Overview of new Classes and Functions

C.1. New Classes

HistoryList		
historyList	list containing history respective facet values	
currentList	list containing facet values at current step	
statisticsList	list containing facet statistics over last iterations	
currIt	current iteration number	
reset()	Reset lists	
initCurrent()	Initialize size of currentList	
initStatistics()	Initialize size of statisticsList	
initList()	Initialize size of historyList	
appendCurrent()	Append currentList to historyList	
appendList()	Append input list to historyList	
updateStatistics()	Calculate statistics per facet (mean, std), save to statisticsList	
getAverageStatistics()	Calculate average ratio (std/mean) weighted with area	
convertTime()	Convert time for better clarity	
print()	Print historyList to terminal, optinal message	
printCurrent()	Print currentList as table to terminal, optional message	
printStatistics()	Print statisticsList as table to terminal, optional message	
write()	Write historyList to file	
erase()	delete desired point in historyList	
empty()	Check if historyList is empty	
setCurrent()	Set value of desired facet in currentList	
getCurrent()	Get value of desired facet in currentList	
setLast()	Set value of desired facet from historyList	
getLast()	Get value of desired facet from historyList	

SimulationHistory		
coveringList	of class HistoryList, stores covering history	
errorList_event	of class HistoryList, stores error history for events	
errorList_covering	of class HistoryList, stores error history for covering	
hitList	of class HistoryList, stores hits for each facet	
desorbedList	of class HistoryList, stores desorbed particles for each facet	
particleDensityList	of class HistoryList, stores particle density for each facet	
pressureList	of class HistoryList, stores pressure for each facet	
numFacet	number of Facets	
numSubProcess	number of sub processes used for simulation	
flightTime	Simulated flight time for iteration	
nParticles	Simulated particles for iteration	
lastTime	Total simulated time = last time in historyList	
currentStep	step of logarithmic time step calculation in getStepSize()	
stepSize	current step size	
stepSize_outgassing	current step size of outgassing impulse	
smallCoveringFactor	Factor used to multiply covering to reach a minimal value	
updateHistory()	Reset and update	
updateStepSize()	Calculate stepSize and stepSize_outgassing	
appendList()	Update coveringList	
erase()	Erase desired point in history	
print()	Print to terminal	
write()	Write to file	

ProblemDef		
resultpath	Path of result folder	
outFile	Path of file that contains terminal output	
loadbufferPath	Path of loadbuffer file	
hitbufferPath	Path of hitbuffer file	
saveResults	1: save all results, 0: donot save results	
$\begin{array}{c} \text{simulationTime, unit} \\ \Rightarrow \text{simulationTimeMS} \end{array}$	Computation time of each iteration in milliseconds	
$\begin{array}{c} \text{maxTime, maxUnit} \\ \Rightarrow \text{maxTimeS} \end{array}$	Maximal total simulated time in seconds	
iterationNumber	Number of iterations of simulation	
particleDia	Diameter of particles	
E_de, H_vap	Parameters to calculate binding energy, see eq. A.7	
sticking	Sticking factor for all facets	
targetParticles/-Error	Target values for each iteration	
hitRatioLimit	threshold of hitratio (facet/total) at which hits are ignored	
coveringMinThresh	Minimum covering, multiplication to this if covering low	
$t_{-}min, t_{-}max$	Minimum/ Maximum step size	
maxTimePerIt	Maximun simulation time [s] per iteration	
histSize	Size of historyList objects (most recent values in memory)	
vipFacets	alterning: vip facet and target error, e.g. 1 0.001 3 0.002	
outgassingTimeWindow	Duration of outgassing impulse	
counterWindowPercent	Percentage of step size (posterior) at which velocity counters are increased	
desWindowPercent	Percentage of step size (anterior) for desorption	
rollingWindowSize	Number of iterations over which statistics are calculated	
convergenceTarget	Target for average ratio (std/mean) for convergence	
stopConverged	1: stop simulation at convergence, 0: continue simulation	
createOutput()	Create output directory and file	
readInputfile()	Initialization from input file	
printInputfile()	Print to terminal	
writeInputfile()	Write to terminal	

C.2. New Functions

C.2.1. molflowlinux_main.cpp

	Preprocessing
parametercheck()	Checks validity of input parameters from input file Defines values for ProblemDef object p
importBuff()	Import load- and hitbuffer to main process
MPI_Bcast()	Send loadbuffer to sub processes
LoadSimulation()	Load geometry from loadbuffer
initCoveringThresh()	Initialize covering threshold
UpdateSojourn()	Enable sojourn time for each facet
simHistory	Initialize SimulationHistory object

Simulation Loop		
initbufftozero()	Reset all hitbuffer counters except covering	
MPI_Bcast()	Send simHistory→coveringList and simHistory→currentStep to sub processes	
setCoveringThreshold()	Sets covering threshold for each facet	
updateStepSize()	Calculates step sizes for desorption and outgassing	
CalcTotalOutgassingWorker()	Calculates total outgassing for iteration	
UpdateDesorption()	Sets desorption for each facet, ends simulation if 0	
checkSmallCovering()	multiplies covering to reach threshold if necessary	
simulateSub()	Simulation on sub processes	
MPI_Send(), MPI_Recv()	Send sub hitbuffer to main process	
UpdateMCMainHits()	Add simulation results to main hitbuffer	
${\bf Update Particle Density And Pressure ()}$	Calculate and save particle density and pressure	
UpdateErrorMain()	Calculate and save error of iteration to simHistory	
UpdateCovering()	Calculate and save new covering to simHistory	
UpdateCoveringphys()	Saves current covering to hitbuffer	
$simHistory \rightarrow erase()$	Adapt historyList size of to p→histSize	
updateStatistics(), getAverageStatistics()	Statistics over p-rollingWindowSize iterations	
End simulation if p-maxTimeS or p-convergenceTarget is reached		

Postprocessing	
$simHistory \rightarrow write()$	Export simulation history

C.2.2. SimulationLinux.cpp

simulateSub()		
simHistory->updateHistory()	Update SimulationHistory object from sHandle	
smallCoveringFactor	If covering is small: Covering is multiplied by smallCoveringFactor to be able to have statistics without overflow of the covering variable	
targetParticles, targetError	Calculate target values from overall target and number sub processes	
SimulationRun()	Simulate for desired simulation time	
UpdateError()	Calculate current error of sub process	
CheckErrorSub()	Checks if total error reached targetError and if vip facets reached own target	
UpdateMCSubHits()	Save simulation results to hitbuffer	

Small covering		
CheckSmallCovering()	If covering is small, find smallCoveringFactor to reach p→coveringMinThresh	
Undo multiplication	In UpdateCovering()	

Others	
get_path()	Get path of executable
printStream()	Print input string to terminal and file

C.2.3. Iteration.cpp

Set Covering Threshold to avoid negative covering	
init Covering Thresh()	Initializes size of covering threshold vector
${\it set} Covering Threshold ()$	Sets covering threshold for each facet

C.2.4. Buffer.cpp

Buffer functions	
Databuff struct()	signed int size BYTE *buff
checkReadable()	Checks if file can be opened for reading
checkWriteable()	Checks if file can be openend or created for writing
importBuff()	Imports buffer file to Databuff struct
exportBuff()	Exports Databuff struct to buffer file

C.2.5. Calculations in SimulationCalc.cpp etc.

	SimulationCalc.cpp
getCovering()	Get covering from hitbuffer or simHistory
getHits()	Get number of hits from hitbuffer
getnbDesorbed()	Get number of total desorbed molecules from hitbuffer
getnbAdsorbed()	Get number of total adsorbed molecules from hitbuffer
calcNmono()	see eq. A.3
calcdNsurf()	see eq. A.4
calcCoverage()	see eq. A.6
calcStickingnew()	sets sticking coefficient to p—sticking
calcDesorption()	see eq. A.10
GetMoleculesPerTP()	see eq. A.15
calctotalDesorption	calculates desorption for startFromSource()
calcOutgassingFactor()	Calculate factor to determine outgassing particles
calcPressure()	see eq. A.13
calcParticleDensity()	see eq. A.12
calcStartTime()	Calculate start time of particle depending on desorption/outgassing distribution

worker.cpp	
CalcTotalOutgassingWorker()	see eq. A.11, calculate outgassing distribution
Care rotaro degassing (Vorker()	for startFromSource()

SimulationLinux.cpp	
convertunit()	Converts simutime \cdot unit to milliseconds

C.2.6. UpdateSubProcess.cpp

Update sHandle paramters from hitbuffer	
UpdateSticking()	Update sticking
UpdateDesorption()	Update desorption
UpdateSojourn()	Enable residence time for all facets

Error calculations	
getErrorVariables()	get number hits, adsorbed, desorbed particles
UpdateErrorList()	Calculates error per facet, see eq. A.16 Saves to simHistory
UpdateErrorSub()	UpdateErrorList()
UpdateErrorAll()	Sums up total error of facets & weights by facet area for all possible error quantities
UpdateError()	UpdateErrorAll() for only one error quantity in sub process
CheckErrorSub()	Checks if total error and vip facet error reached target

Update hitbuffer	
initbufftozero()	Sets hitbuffer except covering to zero
UpdateMCSubHits()	Saves simulation results from sHandle into hitbuffer

C.2.7. UpdateMainProcess.cpp

Update main hitbuffer from sub hitbuffer	
UpdateMCMainHits()	Add simulation results from sub hitbuffer to main hitbuffer

Update real covering in hitbuffer	
getStepSize()	Calculates step size for current step, see eq. A.9
UpdateCovering()	Uses Krealvirt to calculate new covering Saved to simHistory—coveringList
UpdateCoveringphys()	Saves current real covering to hitbuffer
UpdateErrorMain()	UpdateErrorList(), adapt time entries
UpdateParticleDensityAndPressure()	Calculate pressure and particle density, see eq. A.12, A.13
CalcPerIteration()	Calculates total error (covering and event) and covering over all facets per iteration