

PROB. 11.1.* Consider an LTI filter with impulse response $h[n] = \sqrt{2}\delta[n] + 0.5\delta[n-3]$.

- Find the system function $H(z)$ for this system.
- Sketch the pole-zero plot for $H(z)$.
- With the help of MATLAB, sketch its magnitude response $|H(e^{j\omega})|$ versus ω . Make a connection between the locations of the zeros in the pole-zero plot and the frequencies for which $|H(e^{j\omega})|$ is small.

a) $h[n] = [\sqrt{2}, 0, 0, 0.5]$

$$\sqrt{2} + \frac{1}{2}z^{-3} = H(z)$$

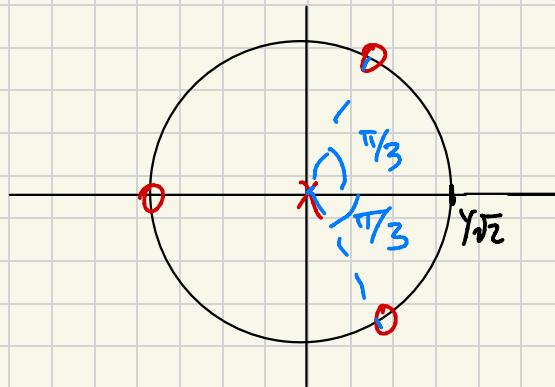
b) $H(z) \left(\frac{z^3}{z^3} \right) = \frac{\sqrt{2}z^3 + \frac{1}{2}}{z^3} \Rightarrow \frac{\sqrt{2}(z^3 + \frac{1}{2\sqrt{2}})}{z^3} \Rightarrow \frac{\sqrt{2}(z^3 + \frac{\sqrt{2}}{4})}{z^3}$

$$z = \left(re^{j\theta} \right)^3 = -\frac{\sqrt{2}}{4} \Rightarrow r^3 e^{j3\theta} = -\left(\frac{1}{2}\right) \left(\frac{\sqrt{2}}{2}\right) \Rightarrow re^{j\theta} = \left(\frac{-1}{2}\right)^{1/3} \left(\frac{\sqrt{2}}{2}\right)^{1/3}$$

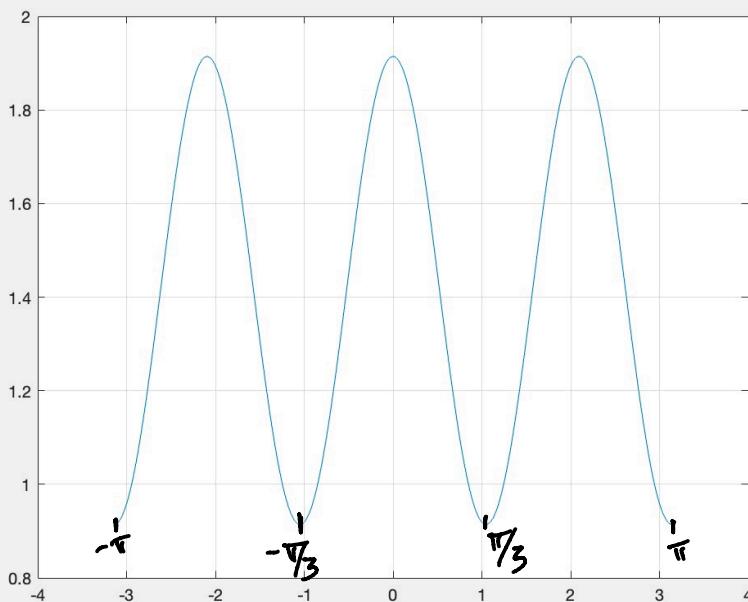
$$z = -\frac{1}{\sqrt[3]{2}} + \frac{1}{\sqrt[3]{2}}(i) + \frac{\sqrt{3}}{2\sqrt[3]{2}}i$$

$$\frac{1}{\sqrt[3]{2}} \left(\frac{1}{2} \pm \frac{\sqrt{3}}{2}i \right)$$

$\theta = \frac{\pi}{3}$



c)



Not zero @
locations But close since
zeros occur @ $f=1$
But $\frac{1}{\sqrt[3]{2}} = f < 1 \Rightarrow$
close to zero

PROB. 11.2.* Consider an FIR system whose system function is $H(z) = 1 - z^{-2}$.

- Find the difference equation relating the filter output $y[n]$ to the input $x[n]$.
- Find the filter impulse response $h[n]$.
- Find the filter frequency response $H(e^{j\omega})$.
- Find the dc gain of the filter.
- Sketch the magnitude response $|H(e^{j\omega})|$. (Hint: It should look like a rectified sinusoid.)
- Sketch the pole-zero plot.

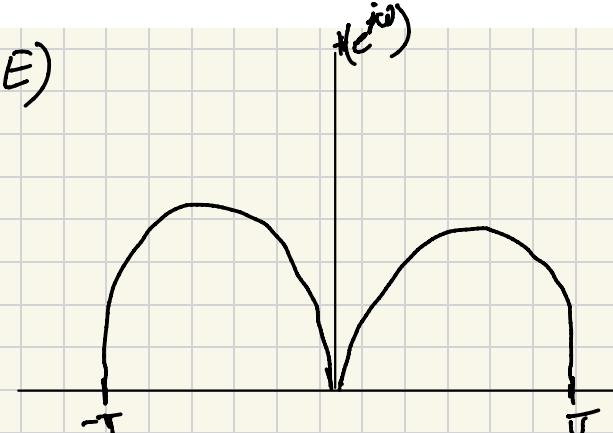
a) $H(z) = 1 - z^{-2} \Rightarrow h[n] = [1 \ 0 \ -1] \ E$

$y[n] = x[n] - x[n-2]$

b) $h[n] = \delta[n] - \delta[n-2]$

c) $H(e^{j\omega}) = 1 - e^{-2j\omega}$

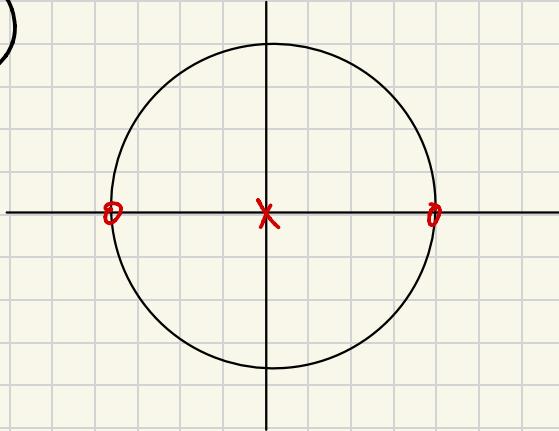
d) $H(e^{j\omega}) \Big|_{\omega=0} = 0$



$$H(e^{j\omega}) = e^{-j\omega} (e^{j\omega} - e^{-j\omega})$$

$$\begin{aligned} & e^{j\omega} (2i \sin(\omega)) \\ & -e^{j\omega} (2i \sin(\omega)) \end{aligned}$$

$$H(z) = \frac{z^2 - 1}{z^2}$$



PROB. 11.3.* A first-order LTI system whose system function is of the form $H(z) = 1 - e^{j\hat{\omega}_0 z^{-1}}$ completely nulls out a complex exponential input signal of the form $e^{j\hat{\omega}_0 n}$. The concept of *cascading* systems can be used to null out multiple complex exponential signals. For example, the system function $(1 - e^{j0.3\pi}z^{-1})(1 - e^{-j0.3\pi}z^{-1})$ nulls both $e^{j0.3\pi n}$ and $e^{-j0.3\pi n}$, and because of the Euler relation, it also nulls the real sinusoid of the form $A \cos(0.3\pi n + \phi)$, regardless of the sinusoid amplitude or phase.

- (a) Design the coefficients $\{b_k\}$ of an FIR filter of minimal order that nulls out the signal:

$$x_a[n] = \sqrt{2} \cos(0.2\pi n + 0.3\pi).$$

- (b) Design the coefficients $\{b_k\}$ of an FIR filter of minimal order that nulls out the signal:

$$x_b[n] = \sqrt{2} \sum_{k=0}^4 \cos(0.2\pi k) \cos(0.2\pi kn + 0.3\pi).$$

- (c) Sketch the pole-zero plot of the system function for the filter of part (b).

a) to null out freq $\omega_0 \approx 0.2\pi n$

We design the system function as:

$$\begin{aligned} H(z) &= (1 - e^{-j(0.2\pi)} z^{-1}) (1 - e^{-j(-0.2\pi)} z^{-1}) \\ &= 1 - e^{-j0.2\pi} z^{-1} - e^{+j0.2\pi} z^{-1} + e^{j(0.2\pi - 0.2\pi)} z^{-2} \\ &= 1 - (e^{-j0.2\pi} + e^{j0.2\pi}) z^{-1} + z^{-2} \\ &= 1 - 2 \cos(0.2\pi) z^{-1} + z^{-2} \\ b_k &= \{1, -2 \cos(0.2\pi), 1\} \end{aligned}$$

b) $\omega = 0, 0.2\pi, 0.4\pi, 0.6\pi, 0.8\pi$ to null

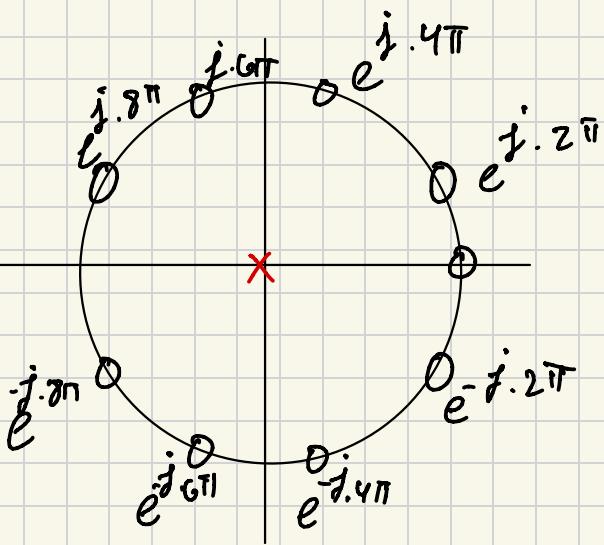
$$(1 - 2 \cos(\pi) z^{-1} + z^{-2}) (1 - 2 \cos(0.2\pi) z^{-1} + z^{-2}) (1 - z^{-1})$$

Or convolve each individual filter

$$\Rightarrow b_n = \{1, -1, 1, -1, 1, -1, 1, -1, 1, -1\}$$

$b_0 \quad b_1 \quad b_2 \quad b_3 \quad b_4 \quad b_5 \quad b_6 \quad b_7 \quad b_8 \quad b_9$

c)



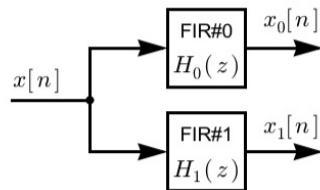
PROB. 11.4.*

Let $x[n]$ be an unspecified periodic sequence with fundamental period $N_0 = 3$. Applying the Euler relation to its DFS representation, such a signal can be written as a constant plus a sinusoid at the fundamental frequency $\frac{2\pi}{N_0} = \frac{2\pi}{3}$, according to:

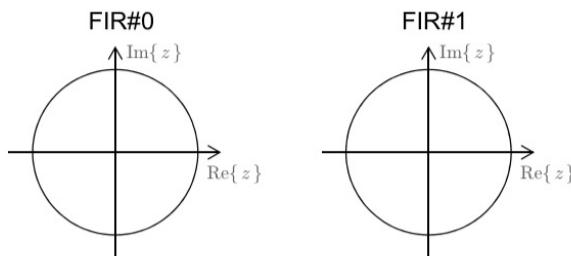
$$x[n] = \underbrace{x_0[n]}_{B} + \underbrace{\text{Acos}(2\pi n/3 + \varphi)}_{x_1[n]},$$

where $x_0[n]$ is the constant component, and $x_1[n]$ is the sinusoidal component.

We can separate $x[n]$ into these components using a bank of FIR filters, as shown below:



- (a) Design the coefficients $\{b_0, b_1, b_2\}$ of FIR#0 so that its output is $x_0[n]$.
- (b) Design the coefficients $\{b_0, b_1, b_2\}$ of FIR#1 so that its output is $x_1[n]$.
- (c) Let $H_i(z)$ be the system function of the i -th FIR filter. Sketch the pole-zero plot for both of the system functions $H_0(z)$ and $H_1(z)$. Align them side-by-side like this:



- (d) Find a simplified expression for the sum of the component system functions:

$$H(z) = H_0(z) + H_1(z),$$

where $H_i(z)$ is the system function of the i -th FIR filter. (Simplify the answer as much as possible.)

a) must have frequencies $\omega = \frac{2\pi}{3}$ and DC gain must be 1

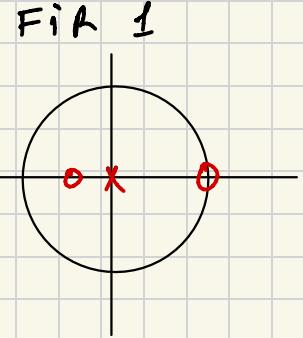
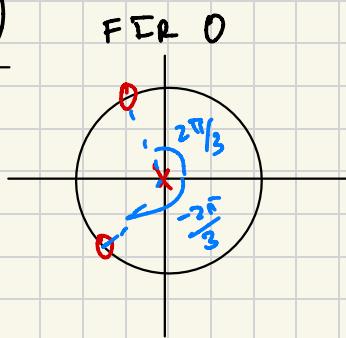
$$\Rightarrow (1 - z^{-1}(e^{j2\pi/3})) (1 - z^{-1}(e^{-j2\pi/3}))$$

$$\Rightarrow \{ 1 - 2 \cos(\frac{2\pi}{3}) \} + j \{ 0 \} \Rightarrow b_E = \{ \frac{1}{3}, \frac{1}{3}, \frac{1}{3} \}$$

$$b) x_1[n] = x[n] - x_0[n] \Rightarrow H(z) = 1 - \frac{1}{3}(1 + z^{-1} + z^{-2}) \Rightarrow \frac{2}{3} - \frac{z^{-1}}{3} - \frac{z^{-2}}{3} \Rightarrow b_E = \{ \frac{2}{3}, -\frac{1}{3}, -\frac{1}{3} \}$$

$$c) H_0(z) = \frac{(1)(z - e^{j2\pi/3})(z - e^{-j2\pi/3})}{z^2}$$

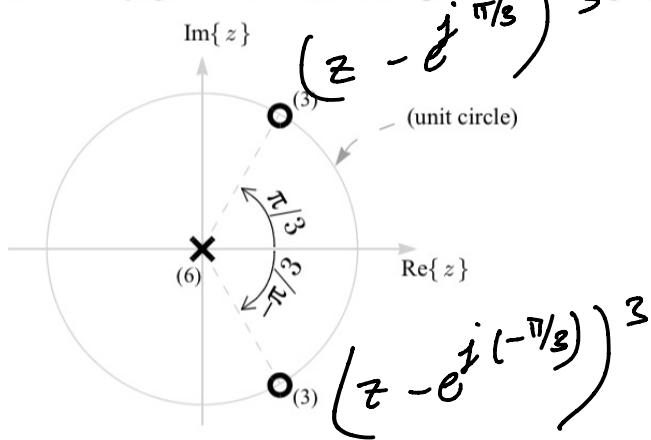
$$H_1(z) = \frac{zz^2 + z + 1}{z^2} = \frac{(2z+1)(z-1)}{3z^2}$$



$$D) \frac{z^2 + z + 1}{3z^2} \quad \cancel{(z+1)(z-1)}_{2z^2}$$

$$\frac{\cancel{z^2 + z + 1}_{3z^2} + 2z^2 - z - 1}{\cancel{3z^2}} \quad \frac{3z^2}{3z^2} = \boxed{1}$$

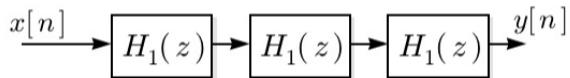
PROBLEM 11.5.* Consider an LTI filter whose system function $H(z)$ has the pole-zero plot shown below, with three zeros (multiplicity 3) on the unit circle with angle $\pi/3$, and similarly three zeros at the conjugate location, and six poles at the origin:



Assume further that evaluating $H(z)$ at $z = 1$ yields $H(1) = 1$.

(A pole-zero plot is invariant to an arbitrary scaling constant, some extra constraint like this is needed to uniquely define a filter.)

- (a) Find the dc gain of the filter.
- (b) Write the difference equation relating the filter output $y[n]$ to its input $x[n]$.
- (c) Let $H_1(z) = 1 + b_1z^{-1} + b_2z^{-2}$ be the system function of an order-two FIR filter. Find real values for the coefficients b_1 and b_2 so that the filter with system function $H(z)$ — having the above pole-zero plot — can be constructed by cascading three copies of the $H_1(z)$ filter in series, as illustrated below:



- (d) Use MATLAB to generate a plot of the magnitude response $|H(e^{j\hat{\omega}})|$ versus $\hat{\omega}$.

- (e) Looking at the plot from part (d), how are nulling frequencies of the frequency response (the values of $\hat{\omega}$ where the magnitude response is zero) related to the locations of the zeros in the given pole-zero plot?

a) Given that $H(z)|_{z=1} = 1$

we know $z = e^{j\omega} \Rightarrow 1 \Rightarrow \omega = 0$ making

DC gain is 1

b) $H(z) = \frac{(z - e^{j\pi/3})^3 (z - e^{-j\pi/3})^3}{z^6} \Rightarrow \left[\frac{(z - e^{j\pi/3})(z - e^{-j\pi/3})}{z^2} \right]^3$

$b_K = \begin{bmatrix} 1 & -2 \cos(\pi/3) & 1 \\ 1 & -1 & 1 \end{bmatrix} * \begin{bmatrix} 1 & -2 \cos(\pi/3) & 1 \\ 1 & -1 & 1 \end{bmatrix} * \dots = \begin{bmatrix} 1 & -3 & 6 & -7 & 6 & -3 \end{bmatrix}$ 3 cascaded filters

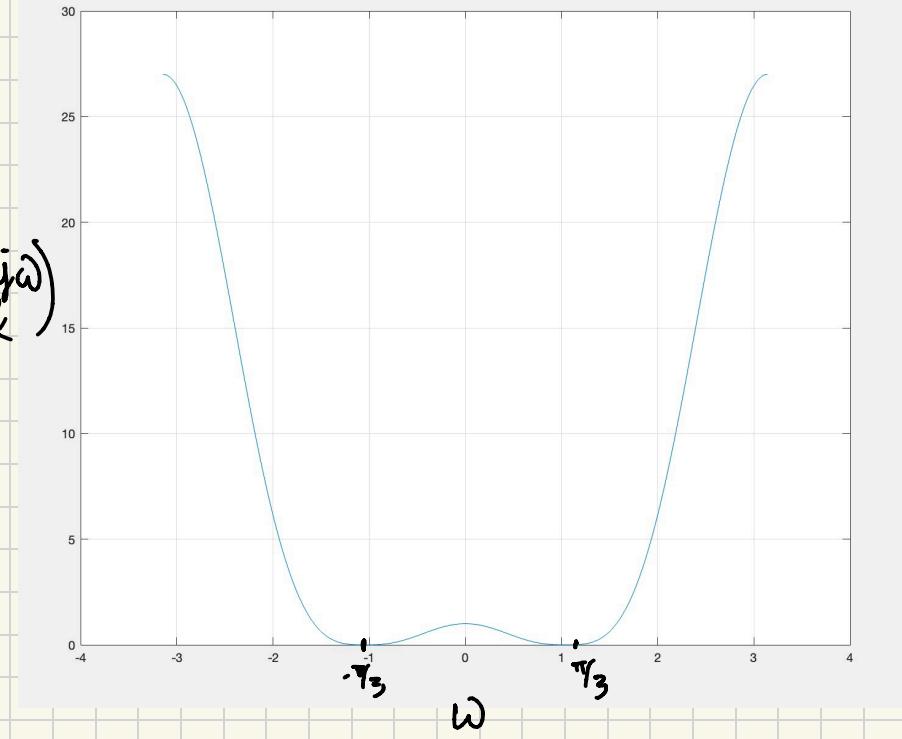
$y[n] = x[n] - 3x[n-1] + 6x[n-2] - 7x[n-3] + 6x[n-4] - 3x[n-5] + 1x[n-6]$

C) solved in Part B

$$b_1 = -1$$

$$b_2 = 1$$

D)



E) The zeros of the pole-zero plot

are $\pm \sqrt{3}$ which is what $(H(e^{j\omega}))$ shows. Furthermore, the degree of each zero

being 3 makes the figuring in the region near vicinity affected.