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Tuesday, October 10, 2023 15:15

- 1. For each of the following matrices, interpret geometrically what ${\cal T}_A$ does.

 - For each of the following matrices, $A = \begin{pmatrix} 0.5 & 0 \\ 0 & 0.5 \end{pmatrix}$ $b. \quad A = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$ $c. \quad A = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$ $d. \quad A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & cos\theta & -sin\theta \\ 0 & sin\theta & cos\theta \end{pmatrix}$
- 2. Determine the matrix for each of the following transformations on \mathbb{R}^2
 - a. Projection onto the line spanned by $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$
 - b. Reflection along y=x followed by refelction along x-axis.
- 3. Consider linear map $T:M_2\ (\mathbb{R})\ o \ M_2\ (\mathbb{R})$

$$A \mapsto \begin{pmatrix} 2 & -4 \\ -1 & 2 \end{pmatrix} A$$

Consider linear map $T:M_2$ $(\mathbb{R})\to M_2$ (\mathbb{R}) $A\mapsto \begin{pmatrix} 2&-4\\-1&2\end{pmatrix}A$ Let $E=<\begin{pmatrix} 1&0\\0&0\end{pmatrix},\begin{pmatrix} 0&1\\0&0\end{pmatrix},\begin{pmatrix} 0&0\\1&0\end{pmatrix},\begin{pmatrix} 0&0\\0&1\end{pmatrix}>$ be an ordered basis for M_2 (\mathbb{R}) and let $B=<\begin{pmatrix} 1&0\\0&-1\end{pmatrix},\begin{pmatrix} 1&0\\0&1\end{pmatrix},\begin{pmatrix} 1&1\\0&1\end{pmatrix},\begin{pmatrix} 1&0\\1&1\end{pmatrix}>$

$$M_2$$
 (\mathbb{R}) and let $B=$ $<$ $\begin{pmatrix}1&0\\0&-1\end{pmatrix}$, $\begin{pmatrix}1&0\\0&1\end{pmatrix}$, $\begin{pmatrix}1&1\\0&1\end{pmatrix}$, $\begin{pmatrix}1&0\\1&1\end{pmatrix}$

- a. Show B is basis for M_2 (\mathbb{R})
- b. Find $[T]_{E \to E}, \ [T]_{E \to B}, \ [T]_{B \to E}, \ [T]_{B \to B}$
- c. Use $[T]_{E o E}$ to determine a basis and dimension of ImT and KerT. What results did you use here that guarantee your algorithm is correct? Explain.

Aran, the main result we covered in class is that for T:V $B=\ \ < b_1, \ldots,\ b_n>$ be an ordered basis for V and Cmatrix representation of T is

$$[T]_{B o C} = \left(egin{array}{ccc} \mid & & \mid & & \mid \\ [T\left(b_{1}
ight)]_{C} & \dots & [T\left(b_{n}
ight)]_{C} \\ \mid & & \mid & \end{array}
ight)$$

where $\left[T\left(b_{i}\right)\right]_{C}$ is basis vector b _ i 's image under T w

We can basically use the Nul[T] and Col[T] to find KerT and II previously in studio. That is surjective maps preserve spanni independence. And since the coordinate map $\left[\cdot\right]_{\mathscr{B}}$ is a biject matrix and the map very easily.