

11/08

Tuesday, November 7, 2023 16:52

1. We have established that if A is not invertible then $\det(A) = 0$. Can you show the converse? In the future, you can add this result to the ever-growing list of invertibility theorem.
2. Find the determinant of the following matrices with the proposed methods.
 - a. $\begin{pmatrix} 1 & 9 & 8 & 7 \\ 0 & 2 & 9 & 6 \\ 0 & 0 & 3 & 5 \\ 0 & 0 & 0 & 4 \end{pmatrix}$. Use Gauss elimination and cofactor expansion. Generalize the result.
 - b. $\begin{pmatrix} 1 & 1 & 1 \\ 1 & 3 & 3 \\ 2 & 2 & 5 \end{pmatrix}$. Use Gauss elimination, Sarrus's Rule and cofactor expansion.
 - c. Discuss the computational cost of finding the determinant with Laplace/Cofactor expansion vs row reduction. If you are asked to make a program to find determinant, which algorithm would you use? What if the matrix is large?
3. Let $A \in M_n(\mathbb{R})$. What is $\det(-A)$?
4. If Q is an orthogonal matrix, what can you say about $\det(Q)$?
5. Let $T \in \mathcal{L}(V)$ where V is finite-dimensional. We define the determinant of T to be equal to $\det[T]_{\mathcal{B}}$ for some basis \mathcal{B} .
 - a. Note that in this definition we call it the determinant instead of a determinant. This suggests that \det of T is the same regardless what \mathcal{B} one chooses. Show this fact.
 - b. Determine the determinant of T where $T: \mathbb{R}_2[x] \rightarrow \mathbb{R}_2[x]$ given by $f \mapsto 2f + 3f'$.
6. Determinant as an expansion factor.
 - a. Consider the parallelogram, call it R , determined by vector $\begin{pmatrix} 3 \\ 4 \end{pmatrix}, \begin{pmatrix} 2 \\ 2 \end{pmatrix}$. Under the map $T_A: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $x \mapsto Ax$, where $A = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$. What is the area of the image of R under T_A ?
 - b. Given that linear map $Tx = Ax$ from $\mathbb{R}^n \rightarrow \mathbb{R}^n$, where $A \in M_n(\mathbb{R})$. Show that $\det(A)$ gives the expansion factor of T for n -parallelepiped determined by $v_1, \dots, v_n \in \mathbb{R}^n$, i.e.

$$\text{Vol}(Av_1, \dots, Av_n) = |\det(A)| \text{Vol}(v_1, \dots, v_n).$$
 Where $\text{Vol}(\dots)$ gives the "volume" of n -parallelepipids.

This can be shown in multiple ways. I suggest row reduction class.

Please stress the general rule for triangular(upper/lower) an

I believe it is $n!$ vs n^3 . Please tell them just because we have necessarily the best when matrix size is big. Row reduction is

Please stress polarity of n is very important.

Please also relate 4 with 6, since Q does not change area but n

We have covered $\det(A^{-1}) = 1/\det(A)$. The result follows from $[T]_{\mathcal{B}} = [id]_{C \rightarrow B} [T]_{\mathcal{B}} [id]_{\mathcal{B} \rightarrow C}$

This is useful for their multi-variable calc. Please also draw a unit square and show them how the expands

Please also bring their attention to $|\det A|$ since it can be a negative consideration.

