



# **Common functional principal component models for mortality forecasting**

**Rob J Hyndman and Farah Yasmeen**

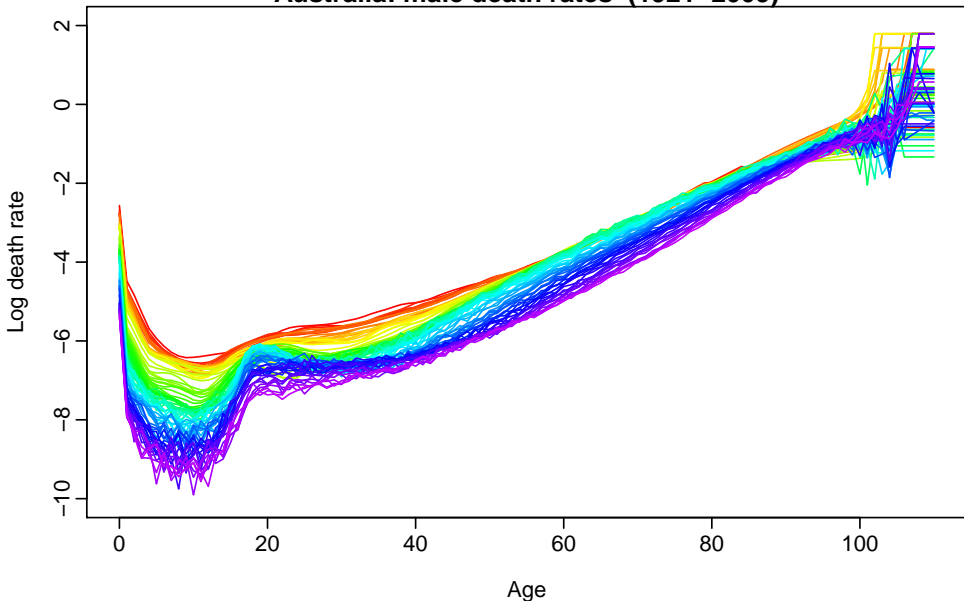
# Outline

- 1 Functional time series**
- 2 Functional time series models
- 3 Common functional principal components
- 4 Australian mortality
- 5 References

# Functional time series

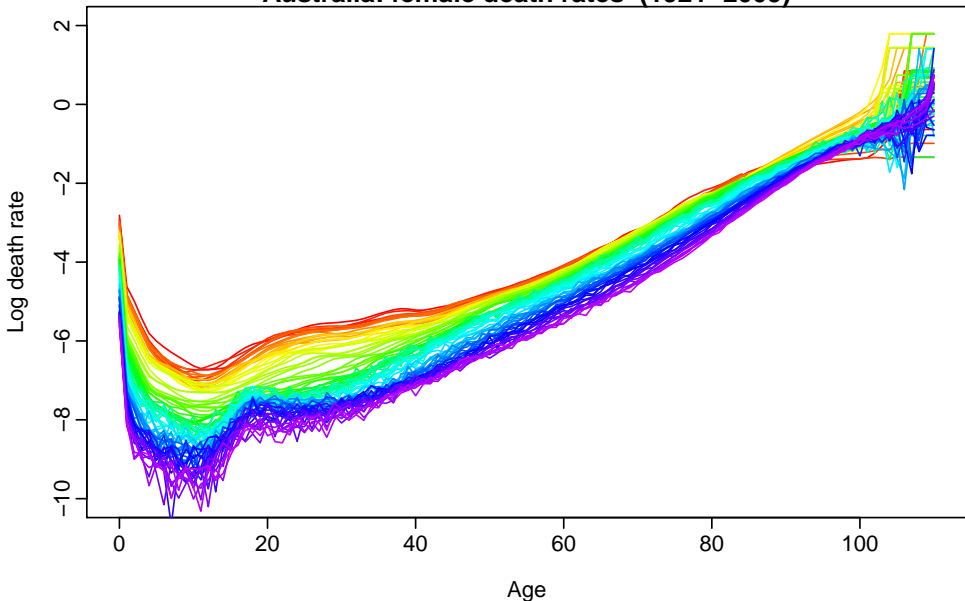
# Functional time series

Australia: male death rates (1921–2009)



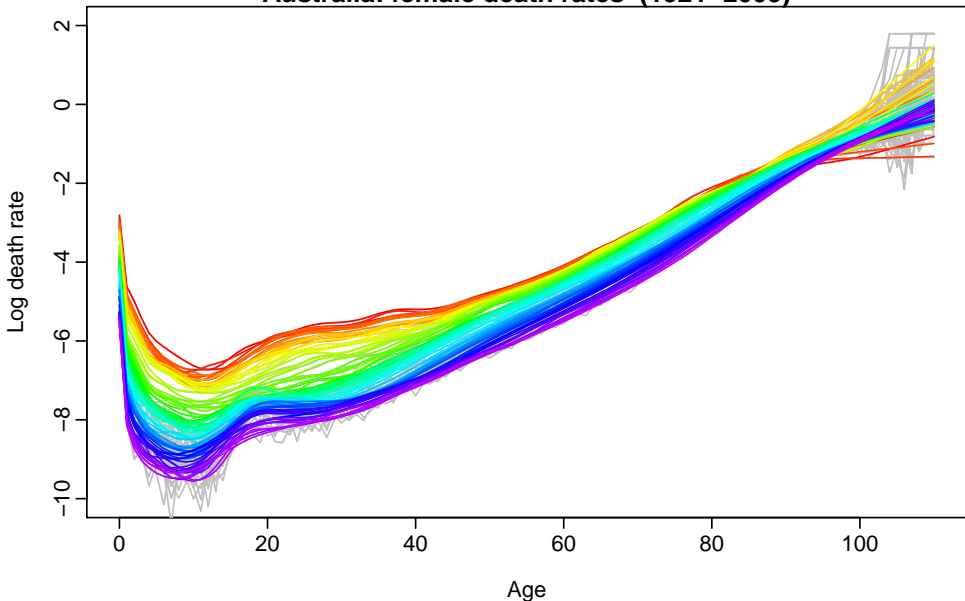
# Functional time series

Australia: female death rates (1921–2009)



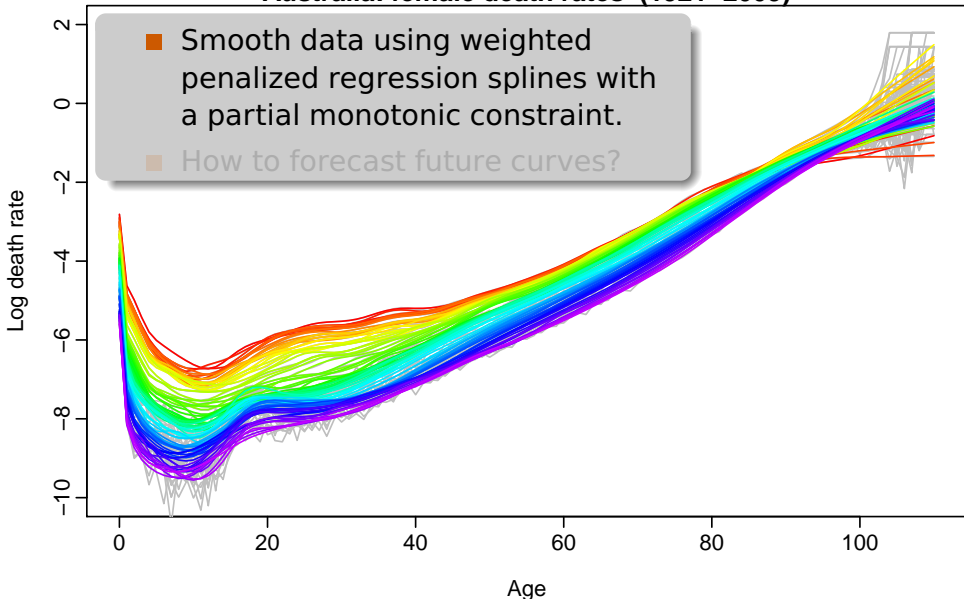
# Functional time series

Australia: female death rates (1921–2009)



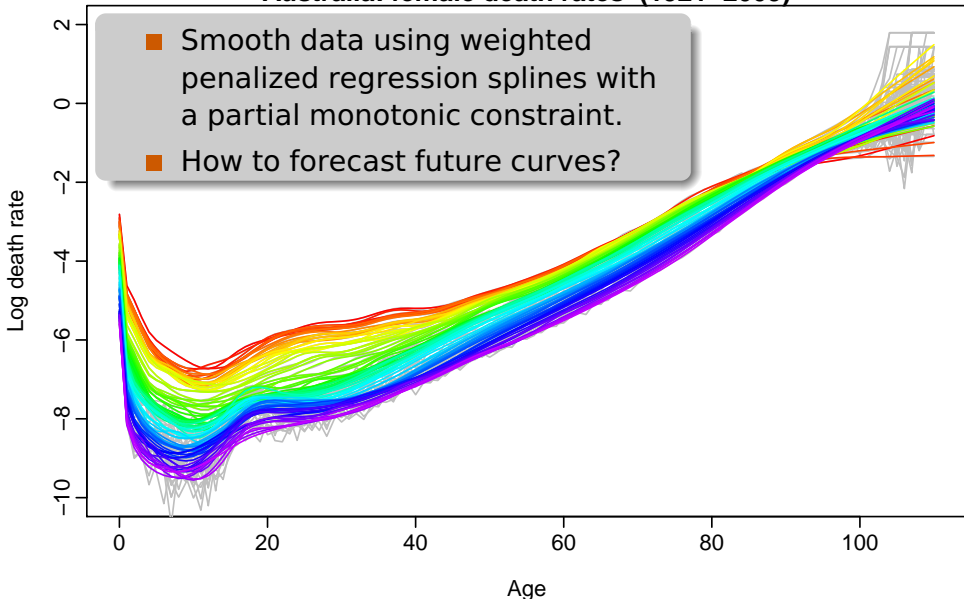
# Functional time series

Australia: female death rates (1921–2009)



# Functional time series

Australia: female death rates (1921–2009)





# Outline

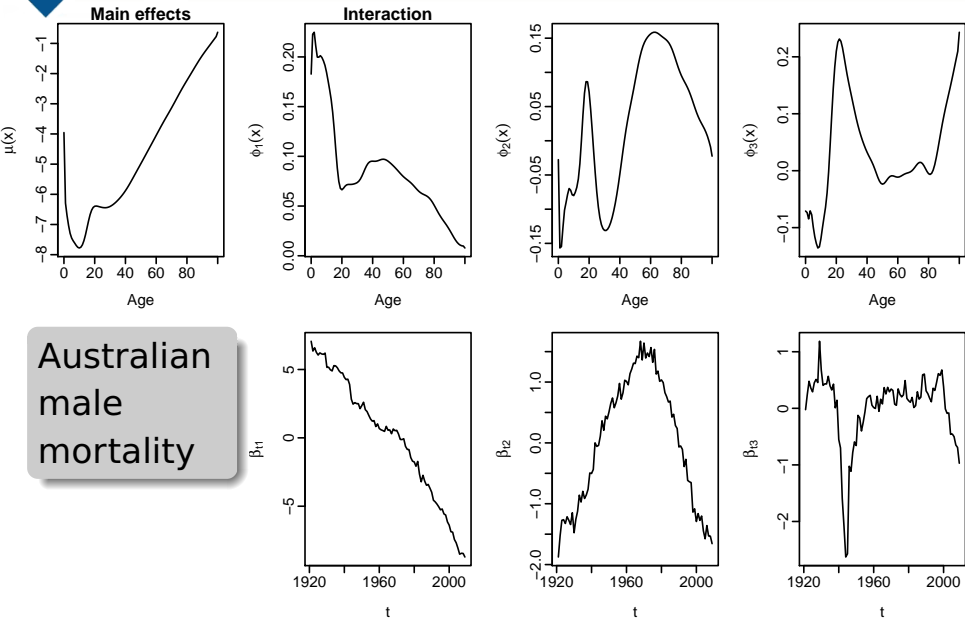
- 1 Functional time series
- 2 Functional time series models**
- 3 Common functional principal components
- 4 Australian mortality
- 5 References

# Functional time series model

$$f_{t,j}(x) = \mu_j(x) + \sum_{k=1}^K \beta_{t,j,k} \phi_{j,k}(x) + r_{t,j}(x)$$

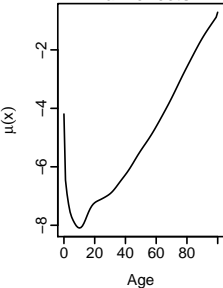
- 1  $f_{t,j}(x)$  = smoothed log mortality rate for age  $x$  in group  $j$  in year  $t$ .
- 2 Compute  $\mu_j(x)$  as  $\bar{f}_j(x)$  across years.
- 3 Compute  $\beta_{t,j,k}$  and  $\phi_{j,k}(x)$  using functional principal components.
- 4 Forecast  $\{\beta_{t,j,k}\}$  using univariate time series models (e.g., ETS, ARIMA, ARFIMA, ...)

# Functional time series model

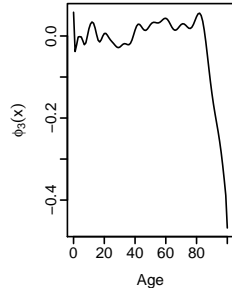
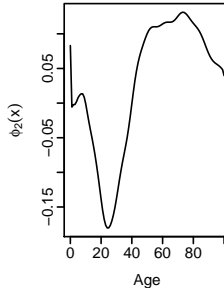
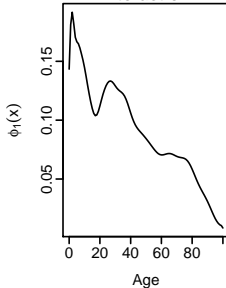


# Functional time series model

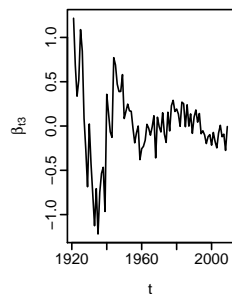
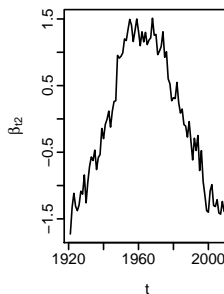
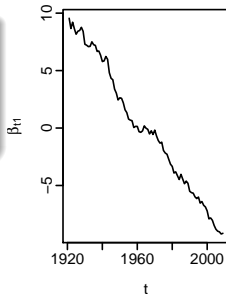
Main effects



Interaction



Australian  
female  
mortality



# The problem

$$f_{t,j}(x) = \mu_j(x) + \sum_{k=1}^K \beta_{t,j,k} \phi_{j,k}(x) + r_{t,j}(x)$$

- Groups may be males and females, or states within a country.
- Expected that groups will behave similarly.
- Fitting separate models to the groups leads to divergent forecasts when the coefficients are non-stationary.
- We require “coherent” forecasts:

# The problem

$$f_{t,j}(x) = \mu_j(x) + \sum_{k=1}^K \beta_{t,j,k} \phi_{j,k}(x) + r_{t,j}(x)$$

- Groups may be males and females, or states within a country.
- Expected that groups will behave similarly.
- Fitting separate models to the groups leads to divergent forecasts when the coefficients are non-stationary.
- We require “coherent” forecasts:

# The problem

$$f_{t,j}(x) = \mu_j(x) + \sum_{k=1}^K \beta_{t,j,k} \phi_{j,k}(x) + r_{t,j}(x)$$

- Groups may be males and females, or states within a country.
- Expected that groups will behave similarly.
- Fitting separate models to the groups leads to divergent forecasts when the coefficients are non-stationary.
- We require “coherent” forecasts:

$$\lim_{t \rightarrow \infty} E \|f_{t,j} - f_{t,j'}\| < \infty \text{ for all } j \text{ and } j'$$

# The problem

$$f_{t,j}(x) = \mu_j(x) + \sum_{k=1}^K \beta_{t,j,k} \phi_{j,k}(x) + r_{t,j}(x)$$

- Groups may be males and females, or states within a country.
- Expected that groups will behave similarly.
- Fitting separate models to the groups leads to divergent forecasts when the coefficients are non-stationary.
- We require “coherent” forecasts:

$$\lim_{t \rightarrow \infty} E \|f_{t,i} - f_{t,j}\| < \infty \text{ for all } i \text{ and } j$$



# The problem

$$f_{t,j}(x) = \mu_j(x) + \sum_{k=1}^K \beta_{t,j,k} \phi_{j,k}(x) + r_{t,j}(x)$$

- Groups may be males and females, or states within a country.
- Expected that groups will behave similarly.
- Fitting separate models to the groups leads to divergent forecasts when the coefficients are non-stationary.
- We require “coherent” forecasts:

$$\lim_{t \rightarrow \infty} E \|f_{t,j} - f_{t,i}\| < \infty \text{ for all } i \text{ and } j$$

# Outline

- 1 Functional time series
- 2 Functional time series models
- 3 Common functional principal components**
- 4 Australian mortality
- 5 References

# Partial Common Functional Principal Components

## PCFPC( $K, L$ ) model

$$f_{t,j}(x) = \mu_j(x) + \sum_{k=1}^K \beta_{t,k} \phi_k(x) + \sum_{\ell=1}^L \gamma_{t,j,\ell} \psi_{j,\ell}(x) + \varepsilon_{t,j}(x)$$

- Coherence when  $\{\gamma_{t,j,\ell} - \gamma_{t,i,\ell}\}$  is stationary for each combination of  $i, j$  and  $\ell$  so that

$$\lim_{t \rightarrow \infty} E \|f_{t,j} - f_{t,i}\| < \infty \quad \text{for all } i \text{ and } j.$$

- Can impose coherence by requiring either cointegrated scores, or stationary scores.

## PCFPC( $K, L$ ) model

$$f_{t,j}(x) = \mu_j(x) + \sum_{k=1}^K \beta_{t,k} \phi_k(x) + \sum_{\ell=1}^L \gamma_{t,j,\ell} \psi_{j,\ell}(x) + \varepsilon_{t,j}(x)$$

- Coherence when  $\{\gamma_{t,j,\ell} - \gamma_{t,i,\ell}\}$  is stationary for each combination of  $i, j$  and  $\ell$  so that

$$\lim_{t \rightarrow \infty} E \|f_{t,j} - f_{t,i}\| < \infty \quad \text{for all } i \text{ and } j.$$

- Can impose coherence by requiring either cointegrated scores, or stationary scores.

## PCFPC( $K, L$ ) model

$$f_{t,j}(x) = \mu_j(x) + \sum_{k=1}^K \beta_{t,k} \phi_k(x) + \sum_{\ell=1}^L \gamma_{t,j,\ell} \psi_{j,\ell}(x) + \varepsilon_{t,j}(x)$$

- Coherence when  $\{\gamma_{t,j,\ell} - \gamma_{t,i,\ell}\}$  is stationary for each combination of  $i, j$  and  $\ell$  so that

$$\lim_{t \rightarrow \infty} E \|f_{t,j} - f_{t,i}\| < \infty \quad \text{for all } i \text{ and } j.$$

- Can impose coherence by requiring either cointegrated scores, or stationary scores.

# Partial Common Functional Principal Components

## PCFPC( $K, L$ ) model

$$f_{t,j}(x) = \mu_j(x) + \sum_{k=1}^K \beta_{t,k} \phi_k(x) + \sum_{\ell=1}^L \gamma_{t,j,\ell} \psi_{j,\ell}(x) + \varepsilon_{t,j}(x)$$

- **Model 1:** PCFPC( $K, 0$ ). No idiosyncratic principal components in the model.
  - **Model 2:** PCFPC( $K, L$ ) with a coherence constraint. For each  $\ell$ ,  $\{\gamma_{t,j,\ell} - \gamma_{t,i,\ell}\}$  is stationary for all  $i, j$ .
  - **Model 3:** PCFPC( $K, L$ ) with a coherence constraint. For each  $\ell$  and  $j$ ,  $\{\gamma_{t,j,\ell}\}$  is stationary.
- These are special cases of the general principal component model with idiosyncratic components.

# Partial Common Functional Principal Components

## PCFPC( $K, L$ ) model

$$f_{t,j}(x) = \mu_j(x) + \sum_{k=1}^K \beta_{t,k} \phi_k(x) + \sum_{\ell=1}^L \gamma_{t,j,\ell} \psi_{j,\ell}(x) + \varepsilon_{t,j}(x)$$

- **Model 1: PCFPC( $K, 0$ ).** No idiosyncratic principal components in the model.
- **Model 2: PCFPC( $K, L$ )** with a coherence constraint. For each  $\ell$ ,  $\{\gamma_{t,i,\ell} - \gamma_{t,j,\ell}\}$  is stationary for all  $i, j$ .
- **Model 3: PCFPC( $K, L$ )** with a coherence constraint. For each  $\ell$  and  $j$ ,  $\{\gamma_{t,\ell,j}\}$  is stationary.
- **Model 4: PCFPC( $0, L$ ).** All principal components and scores are idiosyncratic.

# Partial Common Functional Principal Components

## PCFPC( $K, L$ ) model

$$f_{t,j}(x) = \mu_j(x) + \sum_{k=1}^K \beta_{t,k} \phi_k(x) + \sum_{\ell=1}^L \gamma_{t,j,\ell} \psi_{j,\ell}(x) + \varepsilon_{t,j}(x)$$

- **Model 1: PCFPC( $K, 0$ ).** No idiosyncratic principal components in the model.
- **Model 2: PCFPC( $K, L$ ) with a coherence constraint.** For each  $\ell$ ,  $\{\gamma_{t,i,\ell} - \gamma_{t,j,\ell}\}$  is stationary for all  $i, j$ .
- **Model 3: PCFPC( $K, L$ ) with a coherence constraint.** For each  $\ell$  and  $j$ ,  $\{\gamma_{t,\ell,j}\}$  is stationary.
- **Model 4: PCFPC( $0, L$ ).** All principal components and scores are idiosyncratic.



# Partial Common Functional Principal Components

## PCFPC( $K, L$ ) model

$$f_{t,j}(x) = \mu_j(x) + \sum_{k=1}^K \beta_{t,k} \phi_k(x) + \sum_{\ell=1}^L \gamma_{t,j,\ell} \psi_{j,\ell}(x) + \varepsilon_{t,j}(x)$$

- **Model 1: PCFPC( $K, 0$ ).** No idiosyncratic principal components in the model.
- **Model 2: PCFPC( $K, L$ )** with a coherence constraint. For each  $\ell$ ,  $\{\gamma_{t,i,\ell} - \gamma_{t,j,\ell}\}$  is stationary for all  $i, j$ .
- **Model 3: PCFPC( $K, L$ )** with a coherence constraint. For each  $\ell$  and  $j$ ,  $\{\gamma_{t,\ell,j}\}$  is stationary.
- **Model 4: PCFPC( $0, L$ ).** All principal components and scores are idiosyncratic.

# Partial Common Functional Principal Components

## PCFPC( $K, L$ ) model

$$f_{t,j}(x) = \mu_j(x) + \sum_{k=1}^K \beta_{t,k} \phi_k(x) + \sum_{\ell=1}^L \gamma_{t,j,\ell} \psi_{j,\ell}(x) + \varepsilon_{t,j}(x)$$

- **Model 1: PCFPC( $K, 0$ ).** No idiosyncratic principal components in the model.
- **Model 2: PCFPC( $K, L$ )** with a coherence constraint. For each  $\ell$ ,  $\{\gamma_{t,i,\ell} - \gamma_{t,j,\ell}\}$  is stationary for all  $i, j$ .
- **Model 3: PCFPC( $K, L$ )** with a coherence constraint. For each  $\ell$  and  $j$ ,  $\{\gamma_{t,\ell,j}\}$  is stationary.
- **Model 4: PCFPC( $0, L$ ).** All principal components and scores are idiosyncratic.

# Outline

- 1 Functional time series
- 2 Functional time series models
- 3 Common functional principal components
- 4 Australian mortality**
- 5 References

# Australian mortality

- Data obtained from Human Mortality Database.
- All data smoothed (independently for each year) using penalized regression splines with monotonicity constraint above age 65.
- $K = L = 6$ .
- ARIMA models for common PC scores.
- ARFIMA models for stationary PC scores with  $0 < d < 0.5$ .
- VECM using the Johansen procedure for cointegrated PC scores.

# Australian mortality

- Data obtained from Human Mortality Database.
- All data smoothed (independently for each year) using penalized regression splines with monotonicity constraint above age 65.
- $K = L = 6$ .
- ARIMA models for common PC scores.
- ARFIMA models for stationary PC scores with  $0 < d < 0.5$ .
- VECM using the johansen procedure for cointegrated PC scores.

# Australian mortality

- Data obtained from Human Mortality Database.
- All data smoothed (independently for each year) using penalized regression splines with monotonicity constraint above age 65.
- $K = L = 6$ .
- ARIMA models for common PC scores.
- ARFIMA models for stationary PC scores with  $0 < d < 0.5$ .
- VECM using the Johansen procedure for cointegrated PC scores.

# Australian mortality

- Data obtained from Human Mortality Database.
- All data smoothed (independently for each year) using penalized regression splines with monotonicity constraint above age 65.
- $K = L = 6$ .
- ARIMA models for common PC scores.
- ARFIMA models for stationary PC scores with  $0 < d < 0.5$ .
- VECM using the Johansen procedure for cointegrated PC scores.

# Australian mortality

- Data obtained from Human Mortality Database.
- All data smoothed (independently for each year) using penalized regression splines with monotonicity constraint above age 65.
- $K = L = 6$ .
- ARIMA models for common PC scores.
- ARFIMA models for stationary PC scores with  $0 < d < 0.5$ .
- VECM using the Johansen procedure for cointegrated PC scores.

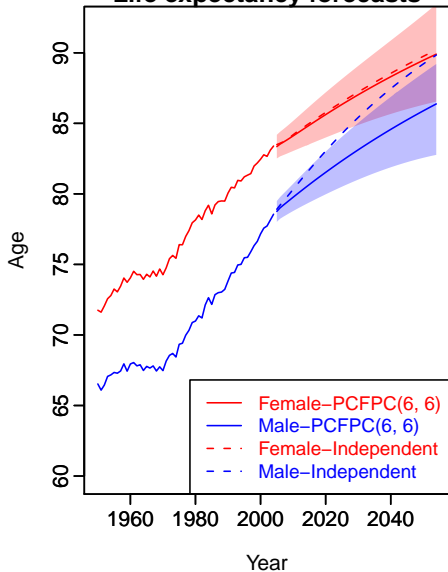


# Australian mortality

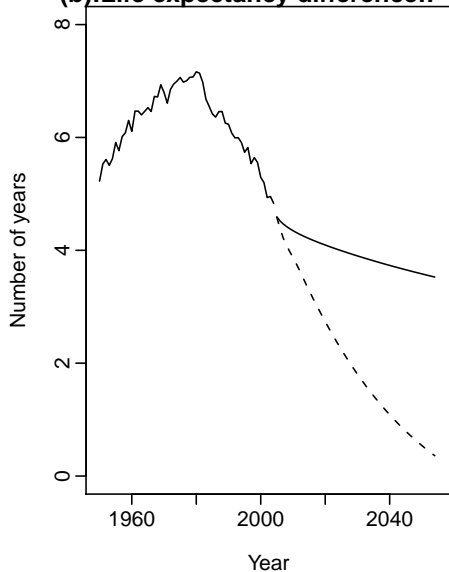
- Data obtained from Human Mortality Database.
- All data smoothed (independently for each year) using penalized regression splines with monotonicity constraint above age 65.
- $K = L = 6$ .
- ARIMA models for common PC scores.
- ARFIMA models for stationary PC scores with  $0 < d < 0.5$ .
- VECM using the Johansen procedure for cointegrated PC scores.

# Australian mortality

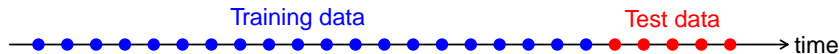
Life expectancy forecasts



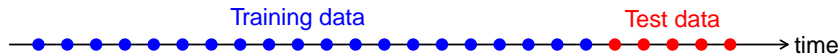
(b):Life expectancy difference:F-M



# Experimental set up

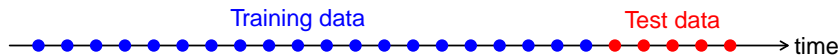


# Experimental set up

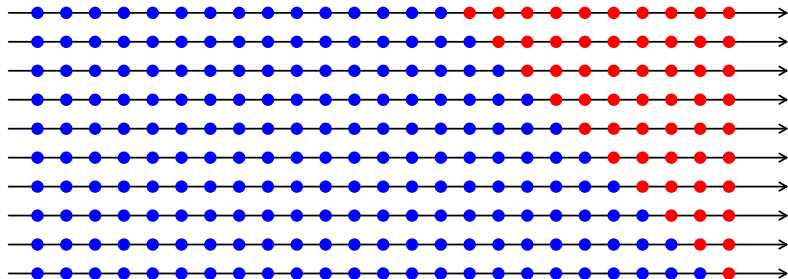


**Rolling forecast origin: 1969–2008,  
forecasting up to 20 years ahead**

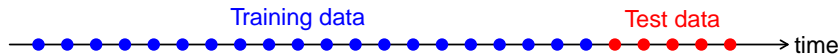
# Experimental set up



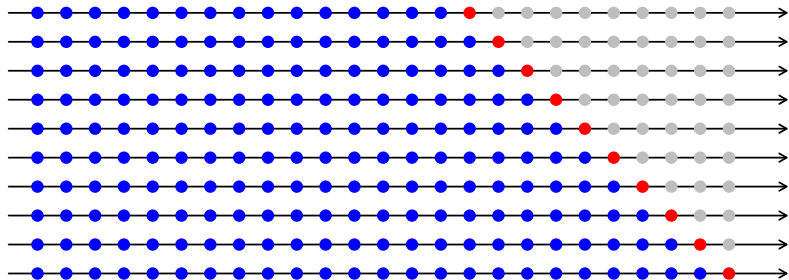
**Rolling forecast origin: 1969–2008,  
forecasting up to 20 years ahead**



# Experimental set up

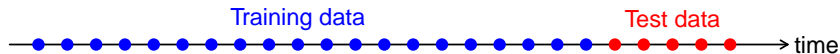


**Rolling forecast origin: 1969–2008,  
forecasting up to 20 years ahead**

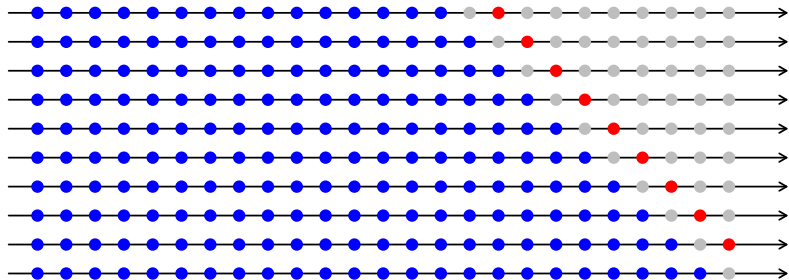


$h = 1$

# Experimental set up

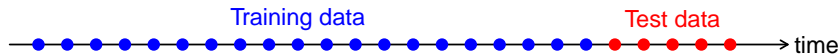


**Rolling forecast origin: 1969–2008,  
forecasting up to 20 years ahead**

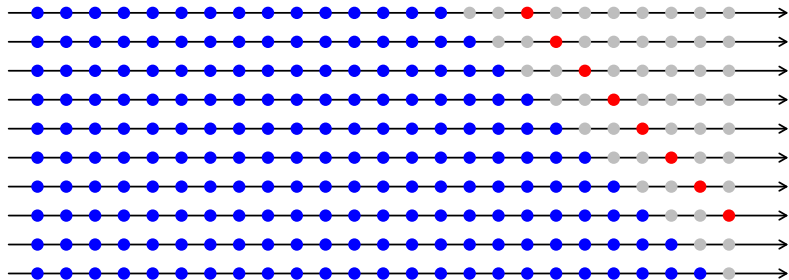


$$h = 2$$

# Experimental set up



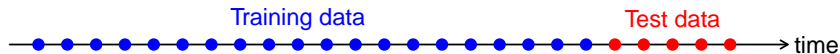
**Rolling forecast origin: 1969–2008,  
forecasting up to 20 years ahead**



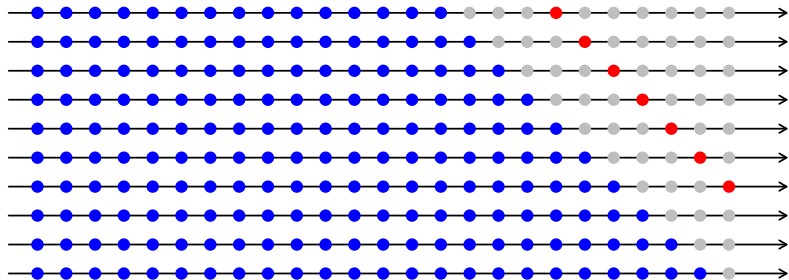
$$h = 3$$



# Experimental set up

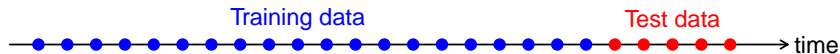


**Rolling forecast origin: 1969–2008,  
forecasting up to 20 years ahead**

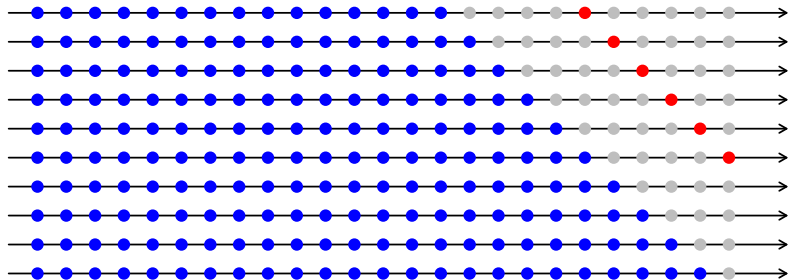


$$h = 4$$

# Experimental set up

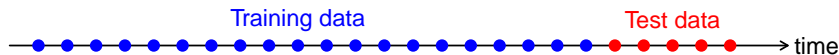


**Rolling forecast origin: 1969–2008,  
forecasting up to 20 years ahead**

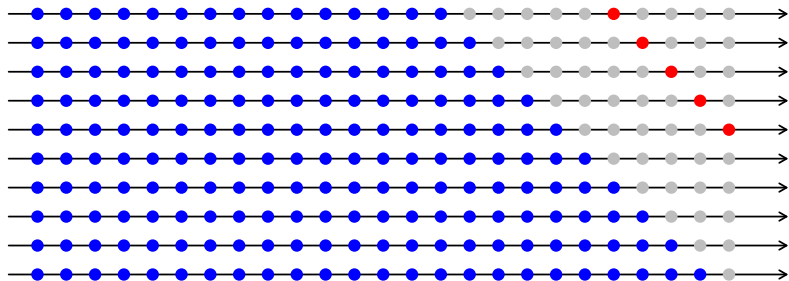


$$h = 5$$

# Experimental set up

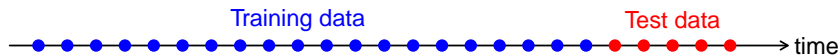


**Rolling forecast origin: 1969–2008,  
forecasting up to 20 years ahead**

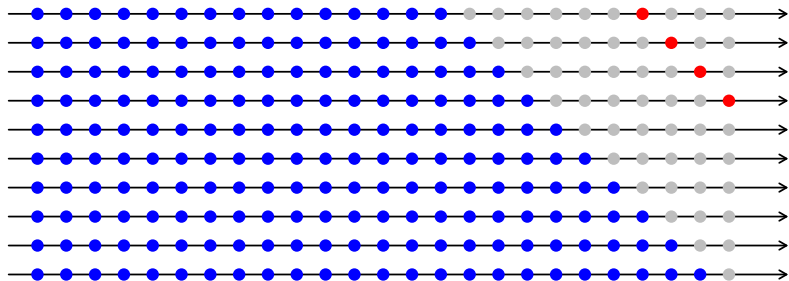


$$h = 6$$

# Experimental set up

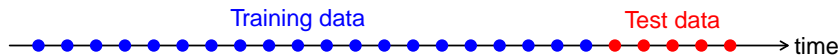


**Rolling forecast origin: 1969–2008,  
forecasting up to 20 years ahead**

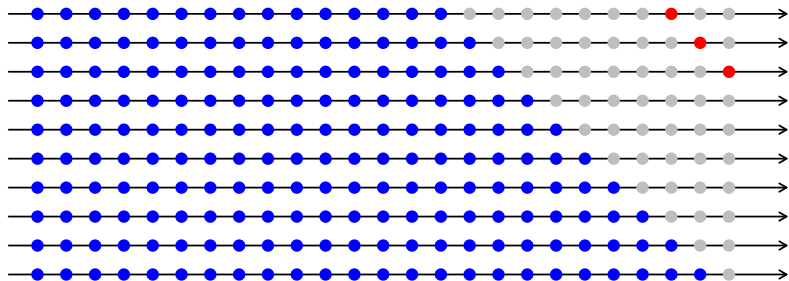


$$h = 7$$

# Experimental set up

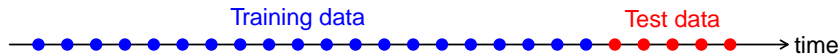


**Rolling forecast origin: 1969–2008,  
forecasting up to 20 years ahead**

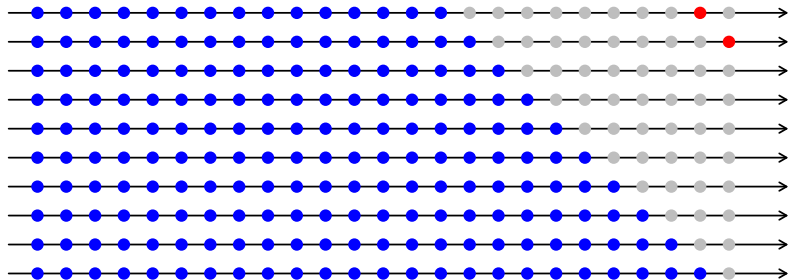


$$h = 8$$

# Experimental set up

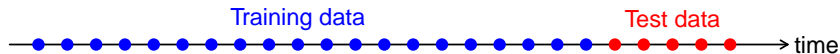


**Rolling forecast origin: 1969–2008,  
forecasting up to 20 years ahead**

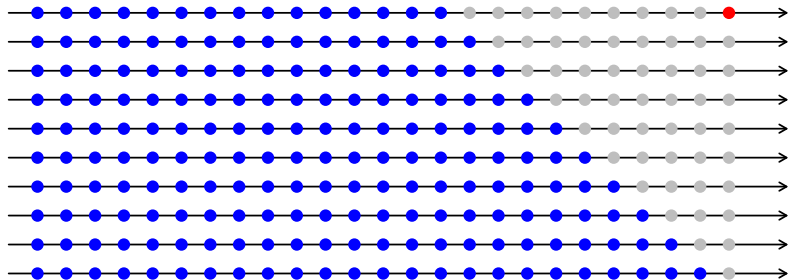


$$h = 9$$

# Experimental set up



**Rolling forecast origin: 1969–2008,  
forecasting up to 20 years ahead**



$$h = 10$$

# Out-of-sample MSE

Forecast Groups horizon		Model 1 PCFPC(6,0) (All common)	Model 2 PCFPC(6,6) (Cointegrated)	Model 3 PCFPC(6,6) (Stationary)	Model 4 PCFPC(0,6) (Divergent)
$h = 5$	Combined (F & M)	2.59	2.60	<b>2.50</b>	2.52
	Female (F)	2.81	2.75	2.70	<b>2.63</b>
	Male (M)	2.38	2.45	<b>2.29</b>	2.42
$h = 10$	Combined (F & M)	<b>4.57</b>	4.66	4.60	4.65
	Female(F)	4.67	4.43	4.63	<b>4.23</b>
	Male (M)	<b>4.48</b>	4.89	4.57	5.06
$h = 15$	Combined (F & M)	<b>7.72</b>	8.00	7.84	8.15
	Female (F)	7.31	6.64	7.23	<b>6.47</b>
	Male(M)	<b>8.14</b>	9.36	8.44	9.82
$h = 20$	Combined (F & M)	<b>12.97</b>	13.56	13.35	14.10
	Female (F)	12.26	10.41	12.08	<b>10.35</b>
	Male (M)	<b>13.69</b>	16.70	14.63	17.86



# Common functional PC

- The best coherent model has all principal components and scores in common. So the models differ only in mean.
- The independent models work better for female data – due to the hump in male mortality being captured in common components?
- PCFPC model more general, so poor performance a problem of model selection.
- PCFPC used  $K = L = 6$ . May be too many? How to do order selection?
- Maybe PCFPC (cointegrated) would be better if we had a good automated VECM procedure.

# Common functional PC

- The best coherent model has all principal components and scores in common. So the models differ only in mean.
- The independent models work better for female data – due to the hump in male mortality being captured in common components?
- PCFPC model more general, so poor performance a problem of model selection.
- PCFPC used  $K = L = 6$ . May be too many? How to do order selection?
- Maybe PCFPC (cointegrated) would be better if we had a good automated VECM procedure.

# Common functional PC

- The best coherent model has all principal components and scores in common. So the models differ only in mean.
- The independent models work better for female data – due to the hump in male mortality being captured in common components?
- PCFPC model more general, so poor performance a problem of model selection.
- PCFPC used  $K = L = 6$ . May be too many? How to do order selection?
- Maybe PCFPC (cointegrated) would be better if we had a good automated VECM procedure.

# Common functional PC

- The best coherent model has all principal components and scores in common. So the models differ only in mean.
- The independent models work better for female data – due to the hump in male mortality being captured in common components?
- PCFPC model more general, so poor performance a problem of model selection.
- PCFPC used  $K = L = 6$ . May be too many? How to do order selection?
- Maybe PCFPC (cointegrated) would be better if we had a good automated VECM procedure.

# Common functional PC

- The best coherent model has all principal components and scores in common. So the models differ only in mean.
- The independent models work better for female data – due to the hump in male mortality being captured in common components?
- PCFPC model more general, so poor performance a problem of model selection.
- PCFPC used  $K = L = 6$ . May be too many? How to do order selection?
- Maybe PCFPC (cointegrated) would be better if we had a good automated VECM procedure.

# Outline

- 1 Functional time series
- 2 Functional time series models
- 3 Common functional principal components
- 4 Australian mortality
- 5 References**

# Selected references



Hyndman, Booth, Yasmeen (2013). “Coherent mortality forecasting: the product-ratio method with functional time series models”.

*Demography* **50**(1), 261–283.



Hyndman (2014). *demography: Forecasting mortality, fertility, migration and population data*.

[cran.r-project.org/package=demography](https://cran.r-project.org/package=demography)