

Rob J Hyndman

Forecasting: Principles and Practice



7. Non-seasonal ARIMA models

OTexts.com/fpp/8/

Outline

- 1 Autoregressive models
- 2 Moving average models
- 3 Non-seasonal ARIMA models
- 4 Estimation and order selection
- 5 ARIMA modelling in R
- 6 Forecasting

Autoregressive models

Autoregressive (AR) models:

$$y_t = c + \phi_1 y_{t-1} + \phi_2 y_{t-2} + \cdots + \phi_p y_{t-p} + e_t,$$

where e_t is white noise. This is a multiple regression with **lagged values** of y_t as predictors.

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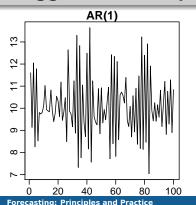
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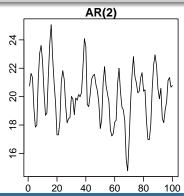
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$$y_t = 2 - 0.8y_{t-1} + e_t$$

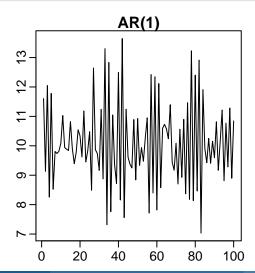
$$e_t \sim N(0, 1)$$

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$$\mathbf{y}_t = \mathbf{c} + \phi_1 \mathbf{y}_{t-1} + \mathbf{e}_t$$

- When $\phi_1 = 0$, y_t is **equivalent to WN**
- When $\phi_1 = 1$ and c = 0, y_t is equivalent to a RW
- When $\phi_1 = 1$ and $c \neq 0$, y_t is equivalent to a RW with drift
- When ϕ_1 < 0, y_t tends to oscillate between positive and negative values.

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$$y_t = 8 + 1.3y_{t-1} - 0.7y_{t-2} + e_t$$

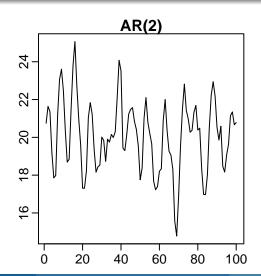
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- Estimation software takes care of this.

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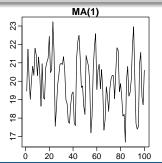
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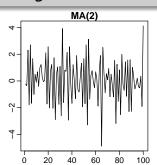
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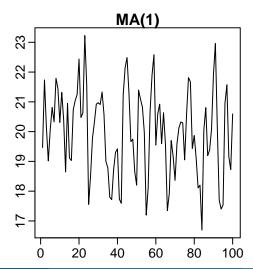
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MA(2) model

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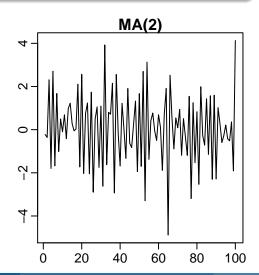
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ARIMA(p, d, q) model

AR: p =order of the autoregressive part

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- White noise model: ARIMA(0,0,0)
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or
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First
difference

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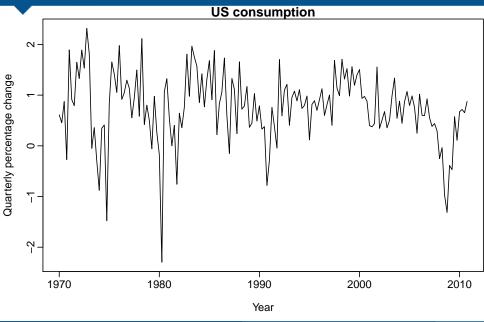
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Written out:

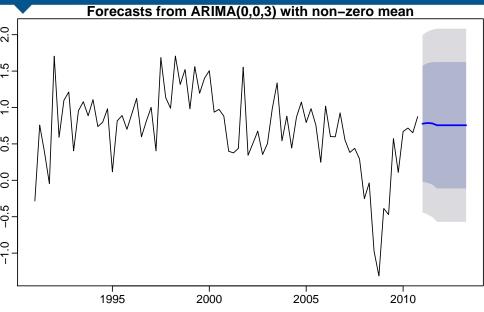
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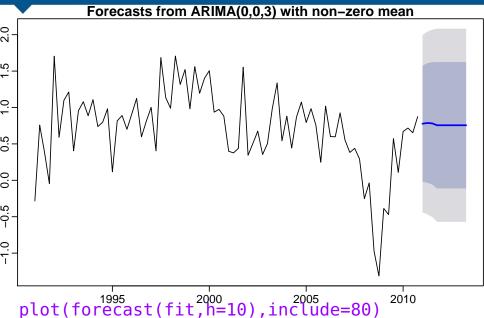


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ARIMA(0,0,3) with non-zero mean
Coefficients:
        ma1
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                       ma3 intercept
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s.e. 0.0767 0.0779 0.0692 0.0844
sigma^2 estimated as 0.3856: log likelihood=-154.73
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ARIMA(0,0,3) or MA(3) model:
    y_t = 0.756 + e_t + 0.254e_{t-1} + 0.226e_{t-2} + 0.269e_{t-3}
```

where e_t is white noise with standard deviation $0.62 = \sqrt{0.3856}$.





- If c = 0 and d = 0, the long-term forecasts will go to zero.
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Forecast variance and d

- The higher the value of *d*, the more rapidly the prediction intervals increase in size.
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- For d = 0, the long-term forecast standard deviation will go to the standard deviation of the historical data.

- For cyclic forecasts, p > 2 and some restrictions on coefficients are required
- If p=2, we need $\phi_1'+4\phi_2<0$. Then average cycle of length
 - $(2\pi)/[arc cos(-\phi_1(1-\phi_2)/(4\phi_2))]$

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Partial autocorrelations measure relationship between y_t and y_{t-k} , when the effects of other time lags — $1, 2, 3, \ldots, k-1$ — are removed.

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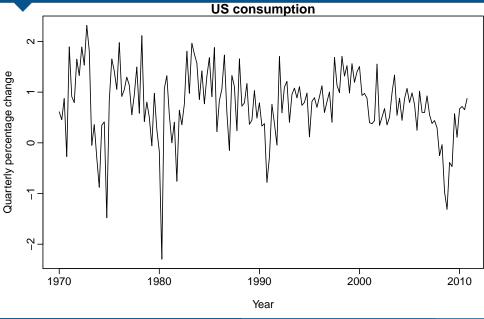
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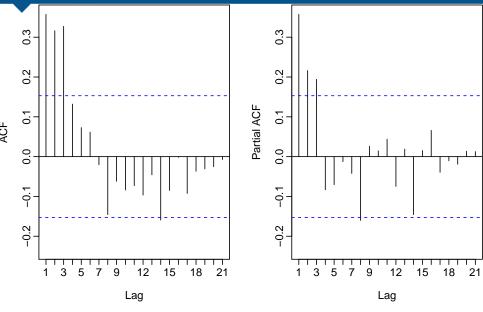
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Forecasting: Principles and Practice

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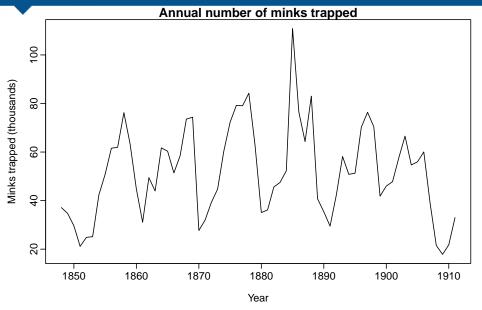
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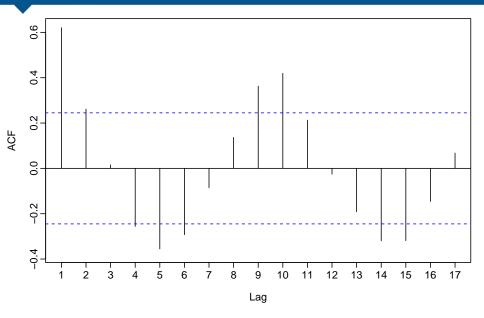
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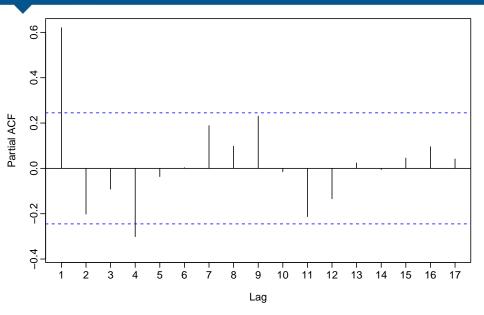
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Akaike's Information Criterion (AIC):

$$AIC = -2\log(L) + 2(p + q + k + 1),$$

where L is the likelihood of the data,

$$k = 1$$
 if $c \neq 0$ and $k = 0$ if $c = 0$.

Corrected AIC:

$$AIC_c = AIC + \frac{2(p+q+k+1)(p+q+k+2)}{T-p-q-k-2}$$

Bayesian Information Criterion:

$$BIC = AIC + \log(T)(p + q + k - 1).$$

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Hyndman and Khandakar (JSS, 2008) algorithm:

- Select no. differences d and D via unit root tests.
- Select p, q by minimising AICc.
- Use stepwise search to traverse model space.

$$AIC = -2 \log(L) + 2(p + q + k + 1)$$

where L is the maximised likelihood fitted to the *differenced* data, k = 1 if $c \neq 0$ and k = 0 otherwise.

- **Step 1:** Select current model (with smallest AIC) from:
 - ARIMA(2, d, 2)
 - ARIMA(0, d, 0)
 - ARIMA(1, d, 0)
 - ARIMA(0, d, 1)
- **Step 2:** Consider variations of current model:
 - ullet vary one of p,q, from current model by ± 1
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Choosing your own model

```
tsdisplay(internet)
adf.test(internet)
kpss.test(internet)
kpss.test(diff(internet))
tsdisplay(diff(internet))
fit <- Arima(internet,order=c(3,1,0))</pre>
fit2 <- auto.arima(internet)</pre>
Acf(residuals(fit))
Box.test(residuals(fit), fitdf=3, lag=10,
  type="Ljung")
tsdiag(fit)
forecast(fit)
plot(forecast(fit))
```

- Plot the data. Identify any unusual observations.
- If necessary, transform the data (using a Box-Cox transformation) to stabilize the variance.
- If the data are non-stationary: take first differences of the data until the data are stationary.
- Examine the ACF/PACF: Is an AR(p) or MA(q) model appropriate?
- Try your chosen model(s), and use the AIC_c to search for a better model.
- Check the residuals from your chosen model by plotting the ACF of the residuals, and doing a portmanteau test of the residuals. If they do not look like white noise, try a modified model.
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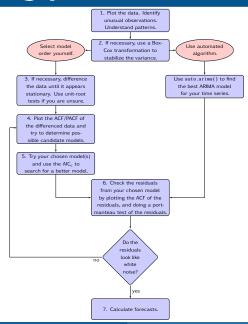
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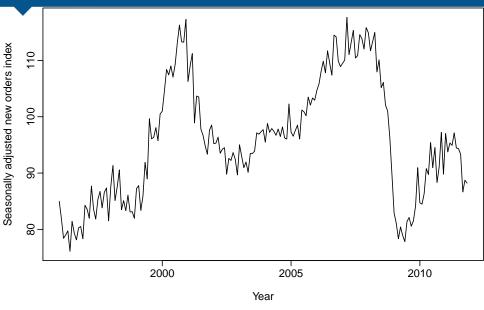
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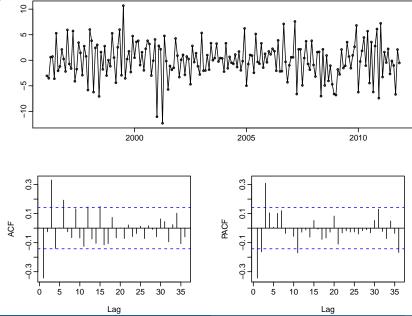


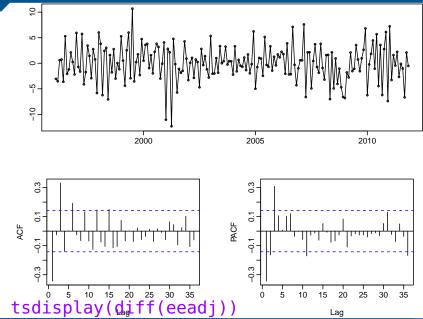


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```
> fit <- Arima(eeadj, order=c(3,1,1))</pre>
> summary(fit)
Series: eeadi
ARIMA(3,1,1)
Coefficients:
        ar1 ar2 ar3 ma1
     0.0519 0.1191 0.3730 -0.4542
s.e. 0.1840 0.0888 0.0679 0.1993
sigma^2 estimated as 9.532: log likelihood=-484.08
AIC=978.17 AICc=978.49 BIC=994.4
```

ACF plot of residuals from ARIMA(3,1,1) model look like white noise.

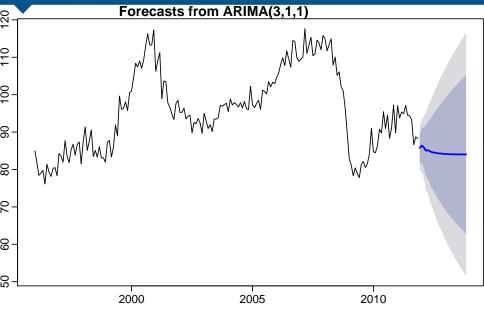
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Acf(residuals(fit))
Box.test(residuals(fit), lag=24,
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```

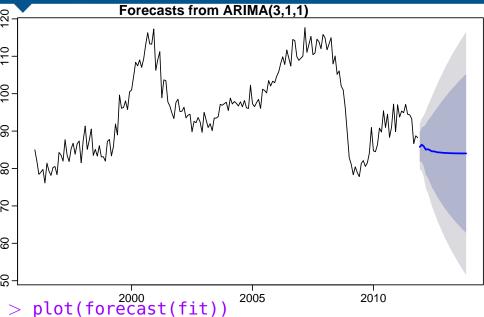
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- Rearrange ARIMA equation so y_t is on LHS.
- Rewrite equation by replacing t by T + h.
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Start with h = 1. Repeat for $h = 2, 3, \ldots$

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$$(1 - \phi_1 B - \phi_2 B^2 - \phi_3 B^3)(1 - B)y_t = (1 + \theta_1 B)e_t,$$

$$[1 - (1 + \phi_1)B + (\phi_1 - \phi_2)B^2 + (\phi_2 - \phi_3)B^3 + \phi_3B^4]y_t$$

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