
8.4.2 General Setting and Definitions

[Example 8.22](#) provided a basic introduction to hypothesis testing. Here, we would like to provide a general setting for problems of hypothesis testing and formally define the terminology that is used in hypothesis testing. Although there are several new phrases such as null hypothesis, type I error, significance level, etc., there are not many new concepts or tools here. Thus, after going through a few examples, the concepts should become clear.

Suppose that θ is an unknown parameter. A hypothesis is a statement such as $\theta = 1$, $\theta > 1.3$, $\theta \neq 0.5$, etc. In hypothesis testing problems, we need to decide between two contradictory hypotheses. More precisely, let S be the set of possible values for θ . Suppose that we can partition S into two disjoint sets S_0 and S_1 . Let H_0 be the hypothesis that $\theta \in S_0$, and let H_1 be the hypothesis that $\theta \in S_1$.

H_0 (the **null** hypothesis): $\theta \in S_0$.

H_1 (the **alternative** hypothesis): $\theta \in S_1$.

In [Example 8.22](#), $S = [0, 1]$, $S_0 = \{\frac{1}{2}\}$, and $S_1 = [0, 1] - \{\frac{1}{2}\}$. Here, H_0 is an example of a **simple** hypothesis because S_0 contains only one value of θ . On the other hand, H_1 is an example of **composite** hypothesis since S_1 contains more than one element. It is often the case that the null hypothesis is chosen to be a simple hypothesis. Often, to decide between H_0 and H_1 , we look at a function of the observed data. For instance, in [Example 8.22](#), we looked at the random variable Y , defined as

$$Y = \frac{X - n\theta_0}{\sqrt{n\theta_0(1 - \theta_0)}},$$

where X was the total number of heads. Here, X is a function of the observed data (sequence of heads and tails), and thus Y is a function of the observed data. We call Y a *statistic*.

Definition 8.3. Let X_1, X_2, \dots, X_n be a random sample of interest. A **statistic** is a real-valued function of the data. For example, the sample mean, defined as

$$W(X_1, X_2, \dots, X_n) = \frac{X_1 + X_2 + \dots + X_n}{n},$$

is a statistic. A **test statistic** is a statistic based on which we build our test.

To decide whether to choose H_0 or H_1 , we choose a test statistic, $W = W(X_1, X_2, \dots, X_n)$. Now, assuming H_0 , we can define the set $A \subset \mathbb{R}$ as the set of possible values of W for which we would accept H_0 . The set A is called the **acceptance region**, while the set $R = \mathbb{R} - A$ is said to be the **rejection region**. In [Example 8.22](#), the acceptance region was found to be the set $A = [-1.96, 1.96]$, and the set $R = (-\infty, -1.96) \cup (1.96, \infty)$ was the rejection region.

There are two possible errors that we can make. We define **type I error** as the event that we reject H_0 when H_0 is true. Note that the probability of type I error in general depends on the real value of θ . More specifically,

$$\begin{aligned} P(\text{type I error} \mid \theta) &= P(\text{Reject } H_0 \mid \theta) \\ &= P(W \in R \mid \theta), \quad \text{for } \theta \in S_0. \end{aligned}$$

If the probability of type I error satisfies

$$P(\text{type I error}) \leq \alpha, \quad \text{for all } \theta \in S_0,$$

then we say the test has **significance level** α or simply the test is a **level** α test. Note that it is often the case that the null hypothesis is a simple hypothesis, so S_0 has only one element (as in [Example 8.22](#)). The second possible error that we can make is to accept H_0 when H_0 is false. This is called the **type II error**. Since the alternative hypothesis, H_1 , is usually a composite hypothesis (so it includes more than one value of θ), the probability of type II error is usually a function of θ . The probability of type II error is usually shown by β :

$$\beta(\theta) = P(\text{Accept } H_0 \mid \theta), \quad \text{for } \theta \in S_1.$$

We now go through an example to practice the above concepts.

Example 8.23

Consider a radar system that uses radio waves to detect aircraft. The system receives a signal and, based on the received signal, it needs to decide whether an aircraft is present or not. Let X be the received signal. Suppose that we know

$$X = W, \quad \text{if no aircraft is present.}$$

$$X = 1 + W, \quad \text{if an aircraft is present.}$$

where $W \sim N(0, \sigma^2 = \frac{1}{9})$. Thus, we can write $X = \theta + W$, where $\theta = 0$ if there is no aircraft, and $\theta = 1$ if there is an aircraft. Suppose that we define H_0 and H_1 as follows:

H_0 (null hypothesis): No aircraft is present.

H_1 (alternative hypothesis): An aircraft is present.

- Write the null hypothesis, H_0 , and the alternative hypothesis, H_1 , in terms of possible values of θ .
- Design a level 0.05 test ($\alpha = 0.05$) to decide between H_0 and H_1 .
- Find the probability of type II error, β , for the above test. Note that this is the probability of missing a present aircraft.
- If we observe $X = 0.6$, is there enough evidence to reject H_0 at significance level $\alpha = 0.01$?
- If we would like the probability of missing a present aircraft to be less than 5%, what is the smallest significance level that we can achieve?

Solution

- The null hypothesis corresponds to $\theta = 0$ and the alternative hypothesis corresponds to $\theta = 1$. Thus, we can write

H_0 (null hypothesis): No aircraft is present: $\theta = 0$.

H_1 (alternative hypothesis): An aircraft is present: $\theta = 1$.

Note that here both hypotheses are simple.

- b. To decide between H_0 and H_1 , we look at the observed data. Here, the situation is relatively simple. The observed data is just the random variable X . Under H_0 , $X \sim N(0, \frac{1}{9})$, and under H_1 , $X \sim N(1, \frac{1}{9})$. Thus, we can suggest the following test: We choose a threshold c . If the observed value of X is less than c , we choose H_0 (i.e., $\theta = EX = 0$). If the observed value of X is larger than c , we choose H_1 (i.e., $\theta = EX = 1$). To choose c , we use the required α :

$$\begin{aligned} P(\text{type I error}) &= P(\text{Reject } H_0 \mid H_0) \\ &= P(X > c \mid H_0) \\ &= P(W > c) \\ &= 1 - \Phi(3c) \quad (\text{since assuming } H_0, X \sim N(0, \frac{1}{9})). \end{aligned}$$

Letting $P(\text{type I error}) = \alpha$, we obtain

$$c = \frac{1}{3}\Phi^{-1}(1 - \alpha).$$

Letting $\alpha = 0.05$, we obtain

$$c = \frac{1}{3}\Phi^{-1}(0.95) = 0.548$$

- c. Note that, here, the alternative hypothesis is a simple hypothesis. That is, it includes only one value of θ (i.e., $\theta = 1$). Thus, we can write

$$\begin{aligned} \beta &= P(\text{type II error}) = P(\text{accept } H_0 \mid H_1) \\ &= P(X < c \mid H_1) \\ &= P(1 + W < c) \\ &= P(W < c - 1) \\ &= \Phi(3(c - 1)). \end{aligned}$$

Since $c = 0.548$, we obtain $\beta = 0.088$.

- d. In part (b), we obtained

$$c = \frac{1}{3}\Phi^{-1}(1 - \alpha).$$

For $\alpha = 0.01$, we have $c = \frac{1}{3}\Phi^{-1}(0.99) = 0.775$ which is larger than 0.6. Thus, we cannot reject H_0 at significance level $\alpha = 0.01$.

- e. In part (c), we obtained

$$\beta = \Phi(3(c - 1)).$$

To have $\beta = 0.05$, we obtain

$$\begin{aligned} c &= 1 + \frac{1}{3}\Phi^{-1}(\beta) \\ &= 1 + \frac{1}{3}\Phi^{-1}(0.05) \\ &= 0.452 \end{aligned}$$

Thus, we need to have $c \leq 0.452$ to obtain $\beta \leq 0.05$. Therefore,

$$\begin{aligned} P(\text{type I error}) &= 1 - \Phi(3c) \\ &= 1 - \Phi(3 \times 0.452) \\ &= 0.0875, \end{aligned}$$

which means that the smallest significance level that we can achieve is $\alpha = 0.0875$.

Trade-off Between α and β : Since α and β indicate error probabilities, we would ideally like both of them to be small. However, there is in fact a trade-off between α and β . That is, if we want to decrease the probability of type I error (α), then the probability of type II error (β) increases, and vice versa. To see this, we can look at our analysis in [Example 8.23](#). In that example, we found

$$\begin{aligned} \alpha &= 1 - \Phi(3c), \\ \beta &= \Phi(3(c - 1)). \end{aligned}$$

Note that $\Phi(x)$ is an increasing function. If we make c larger, α becomes smaller, and β becomes larger. On the other hand, if we make c smaller, α becomes larger, and β becomes smaller. Figure 8.10 shows type I and type II error probabilities for [Example 8.23](#).

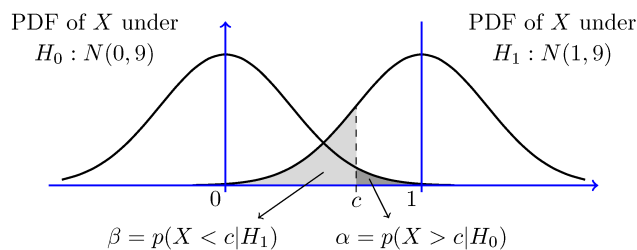


Figure 8.10 - Type I and type II errors in [Example 8.23](#).