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### 8.5.3 The Method of Least Squares

Here, we use a different method to estimate  $\beta_0$  and  $\beta_1$ . This method will result in the same estimates as before; however, it is based on a different idea. Suppose that we have data points  $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$ . Consider the model

$$\hat{y} = \beta_0 + \beta_1 x.$$

The errors (residuals) are given by

$$e_i = y_i - \hat{y}_i = y_i - \beta_0 - \beta_1 x_i.$$

The *sum of the squared errors* is given by

$$g(\beta_0, \beta_1) = \sum_{i=1}^n e_i^2 = \sum_{i=1}^n (y_i - \beta_0 - \beta_1 x_i)^2. \quad (8.7)$$

To find the best fit for the data, we find the values of  $\hat{\beta}_0$  and  $\hat{\beta}_1$  such that  $g(\beta_0, \beta_1)$  is minimized. This can be done by taking partial derivatives with respect to  $\beta_0$  and  $\beta_1$ , and setting them to zero. We obtain

$$\frac{\partial g}{\partial \beta_0} = \sum_{i=1}^n 2(-1)(y_i - \beta_0 - \beta_1 x_i) = 0, \quad (8.8)$$

$$\frac{\partial g}{\partial \beta_1} = \sum_{i=1}^n 2(-x_i)(y_i - \beta_0 - \beta_1 x_i) = 0. \quad (8.9)$$

By solving the above equations, we obtain the same values of  $\hat{\beta}_0$  and  $\hat{\beta}_1$  as before

$$\begin{aligned} \hat{\beta}_1 &= \frac{s_{xy}}{s_{xx}}, \\ \hat{\beta}_0 &= \bar{y} - \hat{\beta}_1 \bar{x}, \end{aligned}$$

where

$$\begin{aligned} s_{xx} &= \sum_{i=1}^n (x_i - \bar{x})^2, \\ s_{xy} &= \sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y}). \end{aligned}$$

This method is called the method of **least squares**, and for this reason, we call the above values of  $\hat{\beta}_0$  and  $\hat{\beta}_1$  the **least squares estimates** of  $\beta_0$  and  $\beta_1$ .