

(Q1) what is the Data Structure? Differentiate between linear and non-linear data structure.

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- i) Data structure can be defined as the group of data elements which provides an efficient way of storing and organising data in the computer so that it can be used efficiently.
 - ii) ex: arrays, linked list etc.

* Linear data structure.

	non-linear data structure.
i)	Every item is related to its previous and next item
ii)	Data is arranged in linear sequence
iii)	Data items can be traversed in a single run
iv)	memory utilization is inefficient
v)	It is single-level
vi)	It is easier to implement
vii)	H. Array, linked list, queue, stack
viii)	ex. tree graph.

Q3) write an algorithm to delete node
in linked list

- ⇒ Step 1: copy the address of first node
Step 2: move ~~the~~ ~~to~~ the head to the second
node of the linked list
Step 3: disconnect the connection of first
node to second node.
Step 4: free the memory occupied by the
first node.

OR.

%%% input: head of the linked list.

Begin:

```
if (head != NULL) then  
    toDelete ← head  
    head ← head.next  
    dealloc(toDelete)
```

End if

End.

a) write an algorithm for linear search.
 Derive recurrence relation and
 find the time complexity.

\Rightarrow

- Step 1 set i to 1
- Step 2 if $i > n$ then go to step 7
- Step 3 if $A[i] = x$ then go to step 6.
- Step 4 set i to $i + 1$
- Step 5 go to step 2
- Step 6 print Element x found at index i
 and go to step 8
- Step 7 print element not found
- Step 8 Exit.

Recurrence Relation

$T(n)$ - Time complexity.

$$\begin{aligned}
 T(n) &= 2T(n-1) + 3n \\
 &= 2^2 T(n-2) + (2+1) \cdot 3n \\
 &= 2^3 T(n-3) + (2^2 + 2 + 1) \cdot 3n \\
 &= \sum_{i=0}^{n-1} 2^i \cdot 3n \\
 &= \frac{2^n - 1}{2 - 1} \cdot 3n
 \end{aligned}$$

$$T(n) = O(n \cdot 2^n).$$

Q 5] Explain the ASYMPTOTIC notation BIG O, omega and theta with suitable examples.

- i) ASYMPTOTIC NOTATION IS USED TO DESCRIBE THE RUNNING TIME OF AN ALGORITHM
- ii) HOW MUCH TIME AN ALGORITHM TAKES WITH A GIVEN INPUT, n .
- iii) THERE ARE THREE DIFFERENT NOTATION BIG O, BIG THETA (Θ), AND BIG OMEGA (Ω)
- iv) BIG- Θ IS USED WHEN THE RUNNING TIME IS THE SAME FOR ALL CASES
- v) BIG-O FOR THE WORST CASE RUNNING TIME
- vi) BIG- Ω FOR THE BEST CASE RUNNING TIME
- vii) a) BIG O : EXAMPLE

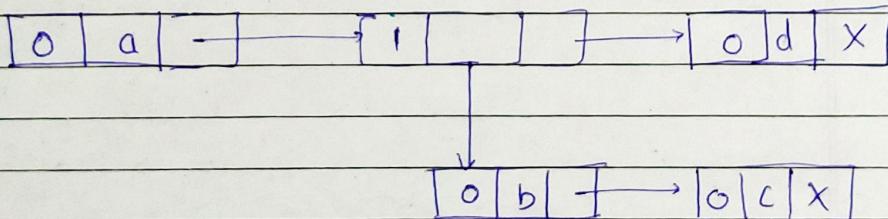
Q6) Explain generalized linked list with Example. Also write algorithm to create singly linked list.

- i) A generalized linked list L_i is defined as a finite sequence of $n \geq 0$ elements $(l_1, l_2, l_3, l_4, \dots, l_n)$, such that l_i are either atom or the list of atoms.
- ii) Thus $L = (l_1, l_2, l_3, l_4, \dots, l_n)$ where n is total number of nodes in the list.

example. of GLL

$(a, (b, c), d)$

head



- iv) when first field is 0, it indicates that the second field is variable.
- v) If first field is 1 means the second field is a down pointer means some list is starting.

Algorithm

Step 1

start the program

Step 2

start the program, get the choice from user

Step 3

if the choice is to add records, get the data from the user and add them to the list

Step 4

if the choice is to delete records get the data to be deleted and delete it from the list

Step 5

if the choice is to display number of records, count the items in the list and display

Step 6

if the choice is to search for an item, get the item to be searched and respond yes if the item is found otherwise no

Step 7

terminate the program



Q.8) write an algorithm to insert new node
in linked list.

=> step 1:- Declare a head pointer and make
it as NULL

step 2:- create a new node with the
given data.

step 3: make the new node points to
the head node.

step 4: Finally, make the new node as H
head node.

Q.9. State and Explain characteristics of an Algorithm

⇒ It must have the following characteristics

i) clear and unambiguous :-

Algorithm should be clear and unambiguous. Each of its steps should be clear in all aspects and must lead to only one meaning.

ii) well-defined inputs :

If an algorithm says to take inputs, it should be well-defined inputs.

iii) well-defined outputs :

The algorithm must clearly define what output will be yielded and it should be well-defined as well.

iv) finite-ness :

The algorithm must be finite it should not end up in an infinite loops or similar

v) feasible : more on

The algorithm must be simple generic and practical such that it can be executed upon will the available resources.

Q10

what is complexity analysis of an algorithm? Explain the notations used in the complexity analysis.

- i) A technique to characterize the execution time of an algorithm independently from the machine, the language and the compiler.
- ii) It is useful for evaluating the variations of execution time with regard to the input data.
- iii) It is a notation used to comparing algorithm.
- * The notation are used in the complexity analysis.
- i) There are three different notations big O, big Theta (Θ), and big Omega (Ω)
- ii) big-O is used is used for the worst case running time.
- iii) big Theta (Θ) is used when the running time is the same for all cases
- iv) big ω for the best case running time

Q 11] Define.

1) ADT :-

ADT is a data structure and a set of operations which can be performed on it.

2) Data structures :-

The group of data elements which provides an efficient way of storing and ~~organising~~ organising data in the computer so that it can be used efficiently.

3) Recursion :-

Recursion is a process in which a problem is defined in terms of itself.

4) Stack :-

A collection of items in which only the most recently added item may be removed. is called a stack.

5) linked list :-

a linear collection of data element whose order is not given by their physical placement in memory. is called as linked list.

a12]

write a Pseudo C/C++ code to represent circular linked list as an ADT

```
#include <iostream>
using namespace std;
struct Node {
    int data;
    struct Node *next;
};
struct Node * head = NULL;
void insert(int Newdata)
{
    Newnode= new node();
    struct Node * ptr = head;
    Newnode->data = Newdata;
    Newnode->next = head;
    if (head != NULL)
    {
        while (ptr->next != head)
            ptr = ptr->next;
        ptr->next = newnode;
    }
    else
    {
        newnode->next = newnode;
        head = newnode;
    }
}
void display()
{
    struct Node* ptr;
    ptr = head;
    do
    {
        cout << ptr->data << " - ";
        ptr = ptr->next;
    }
}
```

```
        while (ptr != head) {
    }
int main()
{
    insert(3);
    insert(1);
    insert(7);
    insert(2);
    insert(9);
    cout << "The circular linked list is : ";
    display();
    return 0;
}
```

OUTPUT:

The circular linked list is : 9 2 7 1 3

Q13) write an algorithm to perform following operations on singly linked list.

Step 1: Define three nodes one with the reference to the head node, and other two nodes as NULL

Step 2: Now run a loop which will be used to traverse the linked list once until the next node does not become NULL

Step 3: Now inside the loop, the first NULL node is defined as the next node to the head node

Step 4: Secondly, the next node of the head node is defined as the second NULL node.

Step 5: Now, the second NULL node in step 4 is again redefined as the node which holds the reference to the head node in step 1

Step 6: And finally, the node holding the reference to the head node in step 1 is made to hold the reference to the next node in the linked list and hence, the pointer now points to its previous node.

Q14] write a Pseudo C/C++ code to concatenate two strings.

⇒ #include <iostream>

#include <string>

using namespace std;

int main()

{

char a[20], b[20];

cout << "Enter string a: " ;

cin.getline(a, 20);

cout << "Enter string b: " ;

cin.getline(b, 20);

strcat(a, b);

cout << " a = " << a << endl;

cout << " b = " << b ;

return 0;

}

Q1) Define and explain the following terms.
1) linear data structures

- i) A data structure is linear if all the elements are arranged in a linear order where the element are attached to its previous and next adjacent is called a linear data structure.
- ii) In linear data structure, single level is involved.
- iii) Therefore, we can traverse all the elements in single run only.
- iv) Linear data structures are easy to implement because computer memory is arranged in a linear way.
- v) ex. array, stack, queue & linked list etc.

Q2) Non-linear data structure.

- i) Data structures where data elements are not arranged sequentially or linearly are called non-linear data structure.
- ii) In non linear data structure single level is not involved.
- iii) Therefore, we can't traverse all the elements in single run only.

- iv) It is not easy to implement in comparison to linear data structure.
- v) It utilizes computer memory efficiently in comparison to a linear data structure.

vi) Example :- trees and graphs.

3] Time complexity:-

- i) The amount of time taken by an algorithm to run, as a function of the length of the input, is called as time complexity.
- ii) It measures the time taken to execute each statement of code in an algorithm.
- 4] Space complexity.
- i) The amount of memory used by the algorithm to execute it completely and produce the result is called as space complexity.

Q.16)

Explain sequential search and binary search with appropriate example and compare their time complexity and space complexity.

i) Sequential search :-

- ii) The sequential search is also called as linear search.
- iii) A sequential search scans one item at a time, without jumping to any item.
- iv) Start from the left most element of arr[] and one by one compare x with each element of arr[]
- v) If x matches with an element return the index.
- vi) If x doesn't match with any of elements return

vii) Examples:-

Find 20								
8	1	2	3	4	5	6	7	8
16	50	30	70	80	60	20	90	40

linear search

2) binary search :-

- i) A binary search however, cut down your search to half as soon as you find middle of a sorted list.
- ii) The middle element is looked to check if it is greater than or less than the value to be searched.
- iii) Accordingly, search is done to either half of the given list.

Find F

0	1	2	3	4	5	6	7	8	9	10	11	12	13
A	B	C	D	E	F	G	H	I	J	K	L	M	N

Binary search

~~Sequential search~~
Comparison
Algorithm

Algorithm	Time complexity	Space complexity
Sequential search	$O(n)$	$O(1)$
Binary search	$O(\log n)$	$O(1)$

Explain two-dimensional arrays with row and column major implementation Explain address calculation in both cases with example.

- i) The 2-D array is similar to that of 1-D array, but here we have two subscripts.
- ii) The syntax of declaration of a 2-D array is
`data-type array-name[rowsize][columnsize];`
- iii) Here `rowsize` specifies the number of rows and `columnsize` represents the number of columns in array.
- iv) The total number of array is
 $\text{rowsize} * \text{columnsize}$.

* Address calculation in Row

- i) The following formula for calculating address of Row.

Address of $A[I][J] = B + W * ((I - LR) * N + (J - LC))$.
 wherever

* Address calculation in column.

- i) The following formula for calculating address of column.

Address of $A[I][J] = B + W * ((J - LC) * M + (I - UR))$

Example:

Given an array $[1 \dots 10][1 \dots 15]$ with base value 100 and the size of each element is 1 Byte in memory

i) Find the address of $\text{arr}[8][6]$ with the help of row-major order.

ii) Find the address of $\text{arr}[8][6]$ with the help of column-major order.

\Rightarrow Given,

$$B = 100, w = 1, I = 8, J = 6, LR = 1$$

$$LC = 1$$

$N = \text{Number of column in matx}$

$$= \text{upper bound} - \text{lower bound} + 1$$

$$= 15 - 1 + 1$$

$$= 15$$

Address of row :

$$= B + w * (I - LR) * N + (J - LC)$$

$$= 100 + 1 * (8 - 1) * 15 + (6 - 1)$$

$$= 100 + 1 * 7 * 15 + 5$$

$$= 100 + 1 * 110$$

$$= 100 + 110$$

$$= 210.$$

Address of $A[8][6]$ is 210.

Column address :

$$= B + w * (J - LR) * N + (I - LC)$$

$$= 100 + 1 * (6 - 1) * 15 + (8 - 1)$$

$$= 100 + 1 * 5 * 15 + 7$$

$$= 100 + 1 * 50 + 7$$

$$= 100 + 1 * 57$$

$$= 157$$

a.8)

write Pseudo C/C++ code to perform
insert and delete operation on linear
linked list

→ #include <iostream>

using namespace std;

class Node.

{ int data;

Node* Next;

}

void print()

{

Node* ptr = Head;

while (ptr != NULL)

{

cout << " Element : " << ptr->data << endl;

ptr = ptr->next;

}

int main()

{

Node* Head;

Node* Second;

Node* Third;

Node* NewNode; — insertion

Head = NewNode();

Second = NewNode();

Third = NewNode();

Newnode = NewNode();

Head → data = 5;

Head → next = Second;

second → data = 6;

second → next = third;

third → data = 7;

third → next = Newnode

Newnode → data = 8;

Newnode → next = NULL;

Print();

head = head → next - Deletion.

Print();

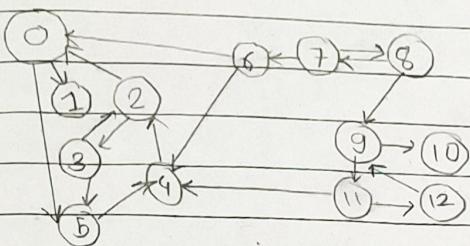
return 0;

?

Unit 5 and 6.

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- 1) for the digraph given below, obtain indegree and outdegree of each vertex
- 2) its adjacency matrix.
- 3) adjacency list.



- 1) In degree and outdegree of each vertex.

vertex	Indegree	outdegree
0	2	2
1	1	2
2	2	2
3	1	2
4	3	1
5	2	1
6	1	2
7	1	2
8	1	2
9	2	2
10	1	0
11	1	2
12	1	1