Date: 13-11-2020

Name: Rudramuni G.M
USN: 1BM18CS085

AI LAB TEST-1

(2)

```
def main():
    """
    Starting_node = [[0,0]]
    jugs = get_jugs()
    goal_amount = get_goal(jugs)
    check_dict = { }
    is_depth = get_search_type()
search(Starting_node, jugs, goal_amount, check_dict, is_depth)

def get_index(node):
    """
    return pow(7, node[0]) * pow(5, node[1])

def get_search_type():
    """
    S = input("Enter 'b' for BFS, 'd' for DFS: ")
    S = S[0].lower()
    while S != 'd' and S != 'b':
        S = input("The input is NOT valid. Enter 'b' for BFS
                   d for DFS: ")
        S = S[0].lower()
    return S == 'd'

def get_jugs():
    """
    print("Reciving volume of jugs:")
    jugs = []
    temp = int(input("Enter first jug volume(>1): "))
    while temp < 1:
        temp = int(input("Enter valid amount(>1): "))
        jugs.append(temp)
```

```
temb = int(input("Enter Second volume(>1): "))
while temb < 1:
    temb= int (input (" Enter valid amount(>1): "))
    jugs.append(temb)
    return jugs

def get_goal(jugs):
Print("Receiving desired amt of water")
max_amount = max(jugs[0], jugs[1])
S = " Enter desired amt of water(1 -{0}): "
    format(max_amount)
goal_amount = int(input("Enter valid amount
        (1-{0}): ". format(max_amount)))
return goal_amount

def is_goal(path, goal_amount):
  print(" checking if goal achieved")
return path[-1][0] == goal_amount or path[-1][1]==goal_amt

def been_there(node, check_dict):
  Print (" checking if {0} is visited before", format(node))
  return check_dict.get(get_index(node), False)

def next_transitions(jugs, path, check_dict):
Print ("Finding Next transitions & checking for loops")
  result = []
    next_nodes=[]
    node = []
    a_max=jugs[0]
    b_max=jugs[1]
    a=Path[-1][0]
    b = Path[-1][1]
```

```
node.append(a)
node.append(b_max)
if not been_there(node, check_dict):
    next_nodes.append(node)
    node=[]
node.append(min(a_max, a+b))
node.append(b-(node[0]-a)) # b-(a'-a)
if not been_there(node, check_dict):
    next_nodes.append(node)
    node=[]
Same for 4,5,6 jugs.
for i in range(0, len(next_nodes)):
    temp_b=list(path)
    temp_b.append(next_nodes[i])
    result.append(temp_b).
if len(next_nodes)==0:
    print("No more unvisited nodes")
else
    print("Possible transitions:")
    for node in next_nodes:
        print(node)
    return result
def transition(old, new, jugs):
    a=old[0]
    b=old[1]
    a_prime=new[0]
    b_prime=new[1]
    a_max=jugs[0]
    b_max=jugs[1]
```

```
    if a>a_paine:
    if b==b_paine:
     return Clear {0}. format(a_max)
    else:
   return "pour {0} litl jug into {1}-jug:
  else
  if b>b_paine:
    return "Clear {0}-liter jug:. format(a_max)
    elif a==a_paine:
        return "Clear {0} litLt", format(b_max),
    else:
     return Cpour {0}_litter jug into {1}. format
                (a_max, a_max),
    else
    if a==a_paine:
      return "Fill {0} -litter jug: ltLtLt", format(b_max
    else:
  return "Fill {0}-liter jug: lt LtLt": format(a_max)
def Search (starting_node, jugs, goal_amount, check_di
                is_depth):
  if is_depth:
    print ("Implementing DFS...")
    else
     print ("Impl. BFS...")
    goal=[]
    accomplished=False,
   av = collection.deque()
    av. appendleft (starting_node)
```

(BM18CS08J

```
while (len(v) != 0):
    Path = v.Popleft()
    check_dict[get_index(Path[-1])] = True.
if len(Path) >= 2:
Print(transition(path[-2], Path[-1], jugs) Path[-1])
    accomplished = True.
    goal = Path
    break
next_moves = next_transitions (jugs, Path, checkdict)
for i in next_moves:
    if is_depth:
        v.appendleft(i)
    else:
        v.append(i)
    if accomplished:
    Print ("achieved")
        Print_Path (goal, jugs)
    else
        print (Prob Cant Solved")
    if __name__ == '__main__':
        main()
```