Assignment and Report

Course: Digital Signal Processing I (EEE 3217)

Submitted to

Prof. Dr. A.K.M. Baki

Professor & Head,

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Ahsanullah University of Science & Technology

Submitted by

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Section: A

3rd Year 2nd Semester

The objective of this assignment is to design a notch filter with the following specification using pole-zero placement method

Where, D2D3 = Last two digits of my student ID means 48

i. Find out the value of frequency in terms of Hz and radian.

Notch frequency in Radian=(108×2π)rad

 $=678.584 \, \text{rad}$

ii. Find out the value of 3 dB bandwidth.

Ans: 3 dB bandwidth of Notch =
$$\frac{\pm (60 + \frac{48}{10})}{2}$$
 Hz = 32.4 Hz

iii. The value of "r":

Given, Notch Frequency=(60+D2D3) Hz

Sampling Frequency = (60+D2D3) × 5 Hz

Sampling Frequency = (60+48) × 5 Hz

We know the relationship between r & bw is,

$$r \approx 1 - \left(\frac{bw}{sampling\ frequency}\right) \times \Pi$$

∴
$$r \approx 1 - (\frac{32.4}{540}) \times \pi \approx 0.811504$$

iv. Find out the value of feed forward and feedback coefficients

$$\theta = \pm \frac{360}{540} \times 108 \text{ degree}$$
$$= \pm 72 \text{ degree}$$

Zeros, (in polar form)

$$Z1 = e j\theta = e j(72)$$

$$Z2 = e^{-j\theta} = e^{-j(72)}$$

Zeros, (in rectangular form)

$$z1 = 0.309 + j0.951$$

Transfer function, H(z) =
$$\frac{(z-z1)(z-z2)}{(z-p1)(z-p2)}$$

Poles(in polar form)

p1=
$$rej\theta$$
=0.8115 ej (72)
p2= $re-j\theta$ =0.8115 $e-j$ (72)

Poles(in rectangular form)

Transfer function, H(z) =
$$\frac{(z-z1)(z-z2)}{(z-p1)(z-p2)}$$

= $\frac{(z-(0.309+j0.951))(z-(0.309-j0.951))}{(z-(0.2507+j0.7717))(z-(0.2507-j0.7717))}$
= $(\frac{1z^2-0.618z+0.999882}{1z^2-0.5014z+0.658385}) \times \frac{z^{-2}}{z^{-2}}$
= $(\frac{1-0.618z^{-1}+0.999882z^{-2}}{1-0.5014z^{-1}+0.658385z^{-2}})$

:: Feed-forward coefficients,

::Feed-backward coefficients,

MATLAB CODE:

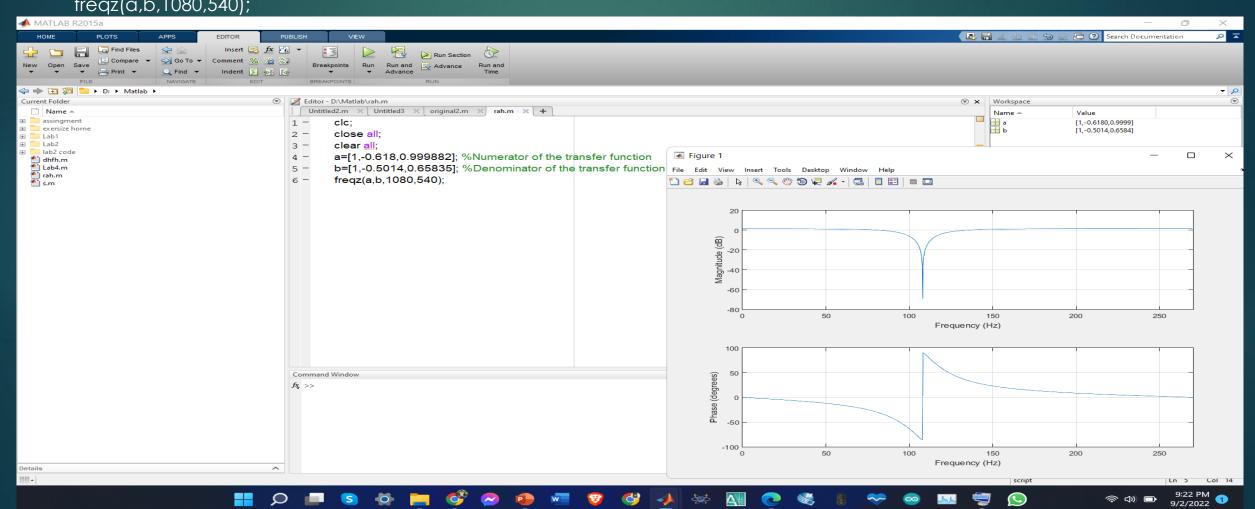
clc;

close all; clear all;

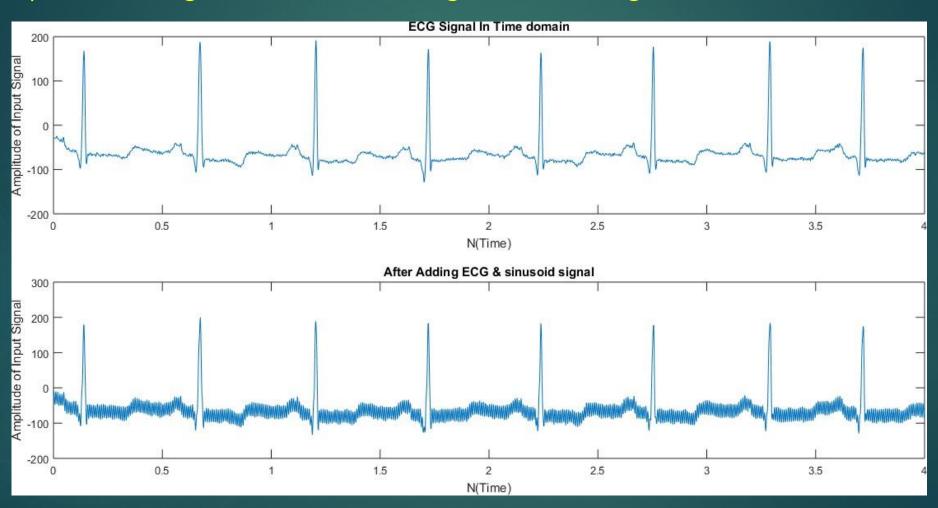
a=[1,-0.618,0.999882]; %Numerator of the transfer function

b=[1,-0.5014,0.65835]; %Denominator of the transfer function

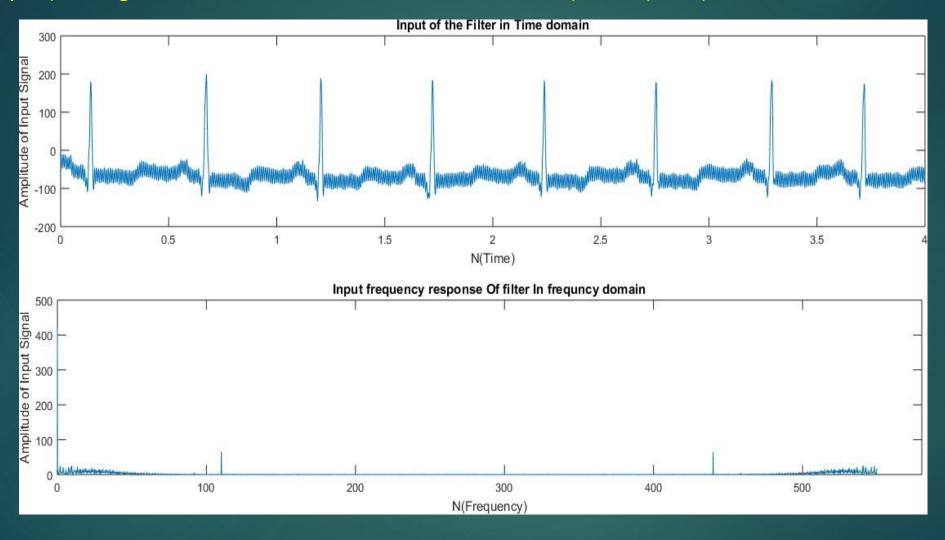
freqz(a,b,1080,540);



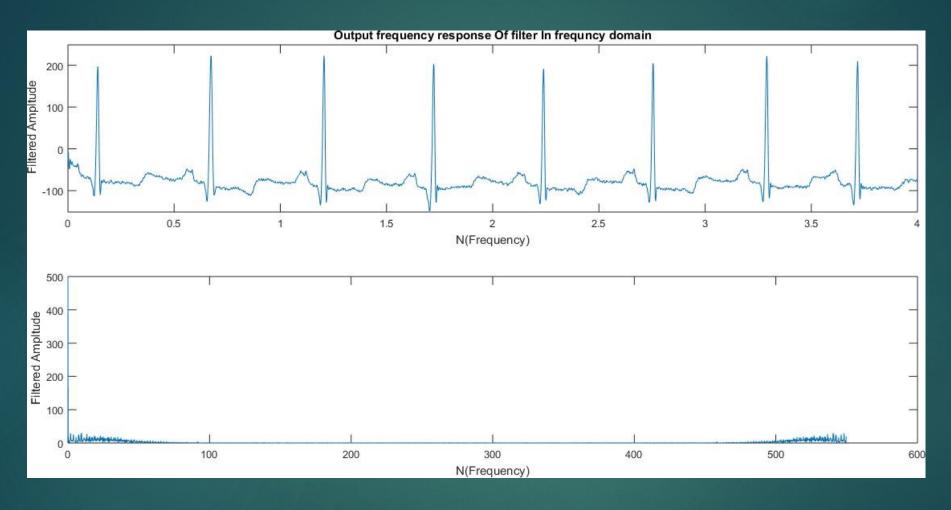
a) The ECG signal & added sine signal to ECG signal:



c) Input signal of filter's in Time domain & frequency response:



d) Output signal of filter's in Time domain & frequency response:



CODE

```
clc;
clear all; % clear all varaiables
close all; % close all figures
load('111m.mat')
y1=val(1,:);
fs=1000;
ts=1/fs
f0=108;
% Fs=1000;
% ts=1/Fs;
N1=length(y1);
t = ((0:N1-1)*ts)/fs;
% fs=540;
% f0=108;
w1=2*pi*f0*t;
x1=30*sin(w1);
x2=x1+y1;
k=fft(x2);
```

```
a=[1,-0.618,0.999882];% INITIALISING VECTOR A WITH COEFFICIENTS OF THE
NUMERATOR;
b=[1,-0.5032,0.66315]; %INITIALISING VECTOR B WITH COEFFICIENTS OF THE
DENOMINATOR;
y=filter(a,b,x2); %TIME DOMAIN OF OUTPUT FILTER
W = fft(y);
subplot(2,2,1)
plot(t,x2);
title('Input Of filter');
subplot(2,2,2)
plot(t,k);
title('Input frequency response Of filter');
subplot(2,2,3)
plot(t,y);
title('Output Of filter');
subplot(2,2,4)
plot(t,w);
title('frequency response Of filter o/p');
```

THANK YOU



AHSANULLAH UNIVERSITY OF SCIENCE AND TECHNOLOGY

Assignment REPORT

Course No: EEE 3217

Course Title: Digital Signal Processing I

SUBMITTED TO

Prof. Dr. A.K.M. Baki

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SUBMITTED BY

Name: MD Rudro Raihan

ID: 190105048

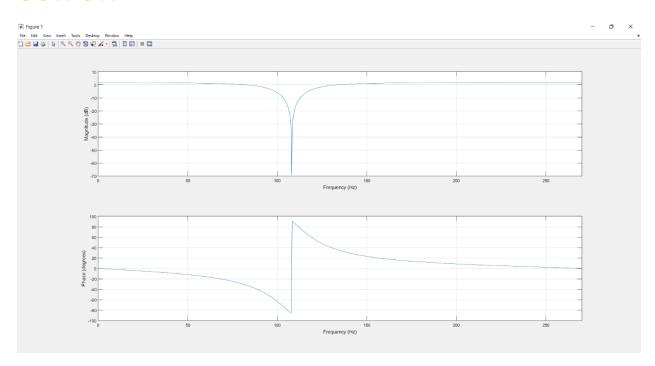
Year: 3rd Semester: 2nd

Section: A Department: EEE

CODE:

```
clc; close all; clear all; a=[1,-0.618,0.999882]; %Numerator of the transfer function b=[1,-0.5014,0.65835]; %Denominator of the transfer function freqz(a,b,1080,540);
```

OUTPUT:

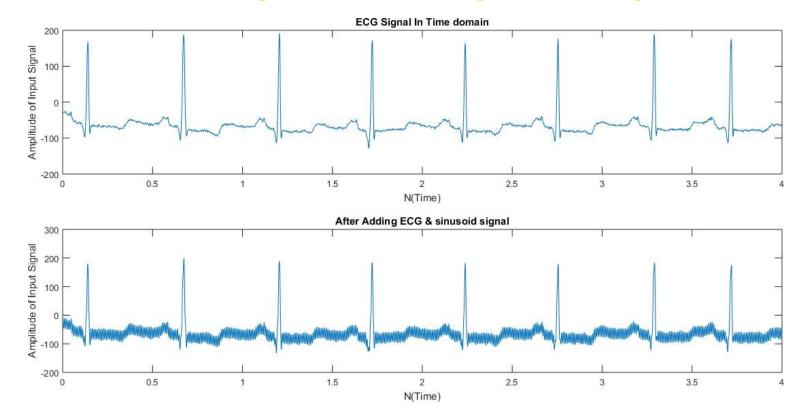


CODE:

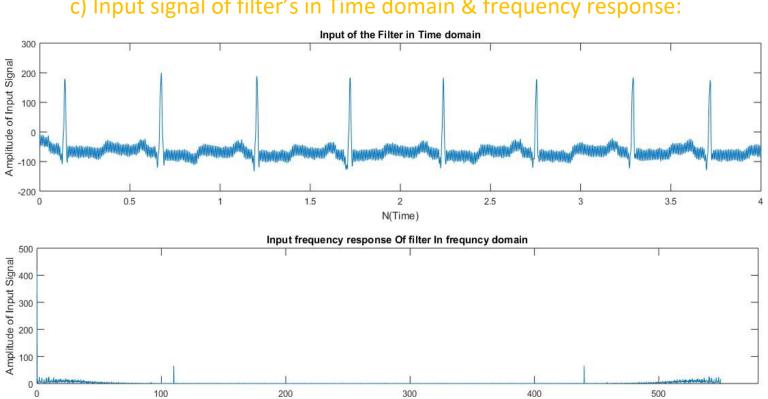
```
clc:
clear all; % clear all varaiables
close all; % close all figures
load('111m.mat')
y1=val(1,:);
fs=1000:
ts=1/fs
f0=108:
% Fs=1000:
% ts=1/Fs:
N1=length(y1);
t=((0:N1-1)*ts)/fs;
% fs=540:
% f0=108:
w1=2*pi*f0*t;
x1=30*sin(w1);
x2=x1+y1;
k=fft(x2);
a=[1,-0.618,0.999882];% INITIALISING VECTOR A WITH COEFFICIENTS
OF THE NUMERATOR;
b=[1,-0.5014,0.65835]; %INITIALISING VECTOR B WITH COEFFICIENTS
OF THE DENOMINATOR:
y=filter(a,b,x2); %TIME DOMAIN OF OUTPUT FILTER
w = fft(y):
subplot(2,2,1)
plot(t,x2);
title('Input Of filter');
subplot(2,2,2)
plot(t,k);
title('Input frequency response Of filter');
subplot(2,2,3)
plot(t,y);
title('Output Of filter');
subplot(2,2,4)
plot(t,w);title('frequency response Of filter o/p');
```

OUTPUT:

a) The ECG signal & added sine signal to ECG signal:



c) Input signal of filter's in Time domain & frequency response:



N(Frequency)

d) Output signal of filter's in Time domain & frequency

response:

