

Deep Learning Seminar Chapter 5. Machine Learning Basics

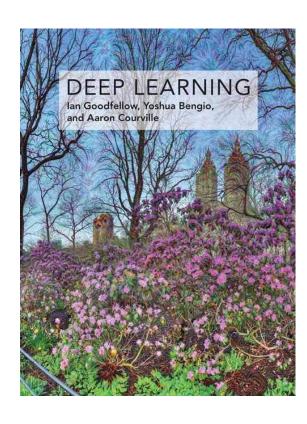
2017-07-14 Jinwook Kim



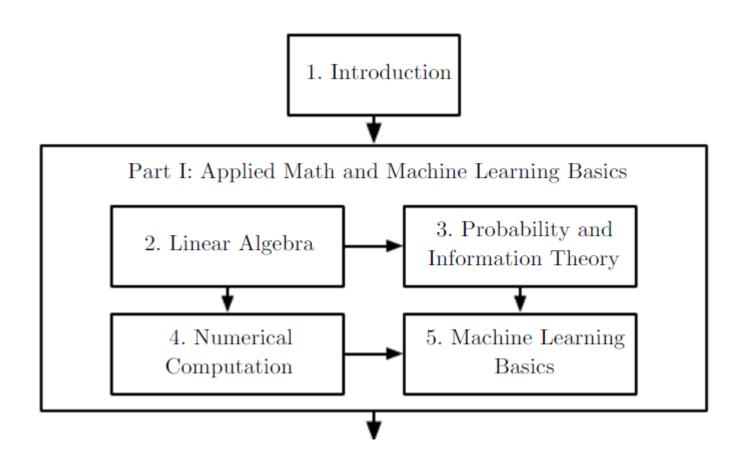


Book Information

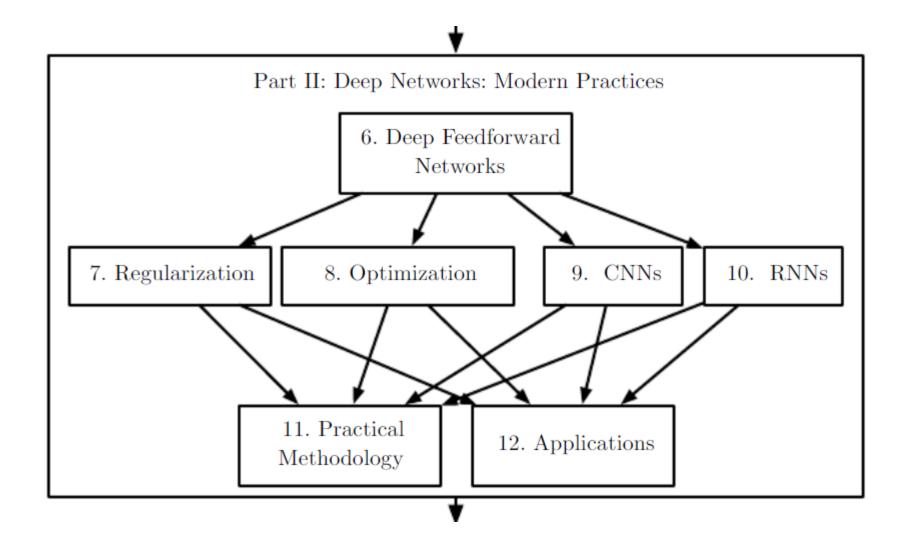
- **Title: Deep learning**
- Authors:
 - ➤ Ian Goodfellow
 - ➤ Yoshua Bengio
 - > Aaron Courville
- Released: November 10, 2016
- ISBN: 9780262337434



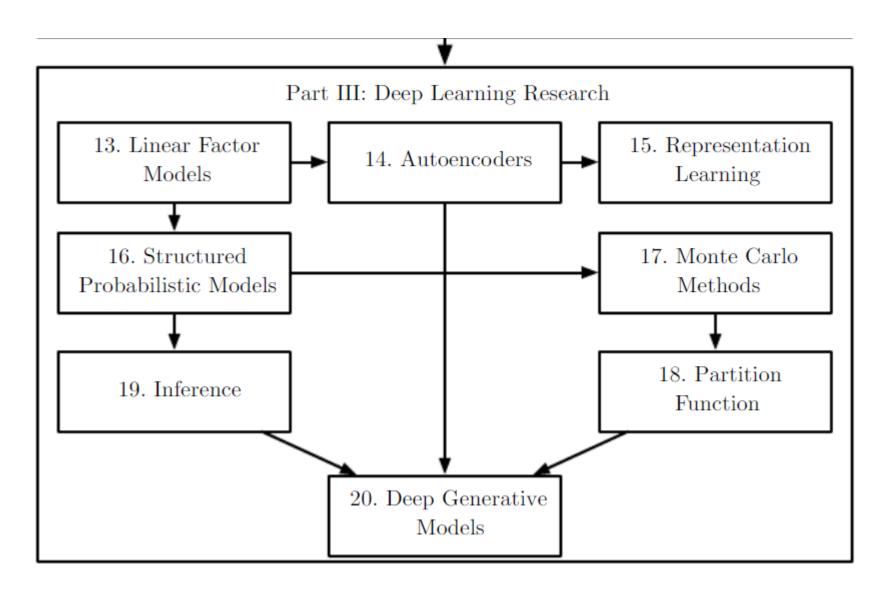
Chapter Organization (Part 1)



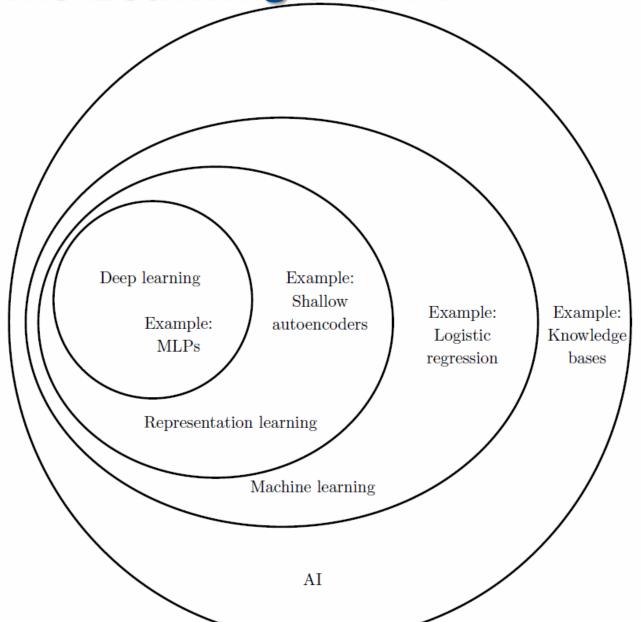
Chapter Organization (Part 2)



Chapter Organization (Part 3)



Machine Learning and Al



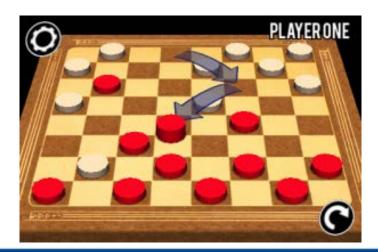
Chapter 5. Machine Learning Basics

- This chapter provides a brief course in the most important general principles
 - 5.1 Learning algorithms
 - 5.2 Capacity, overfitting and underfitting
 - 5.3 Hyperparameters and validation sets
 - 5.4 Estimators, bias and variance
 - 5.5 Maximum likelihood estimation
 - 5.6 Bayesian statistics
 - 5.7 Supervised learning algorithms
 - 5.8 Unsupervised learning algorithms
 - 5.9 Stochastic gradient descent
 - 5.10 Building a machine learning algorithm
 - 5.11 Challenges motivating deep learning

Checkers Game: The First ML Application

- The Samuel's Checkers-playing program appears to be the world's first self-learning program (Arthur Samuel, 1959)
 - ➤ Over thousands of games, the program started to learn to recognize the patterns, which patterns led to win or lose
- Finally, the program played much better than Samuel himself could





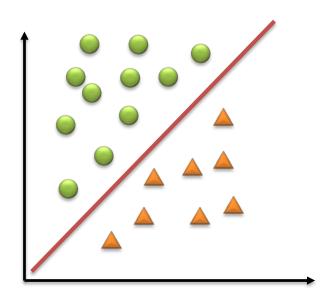
Learning Algorithms

- A field of study that gives computers the ability to learn without being *explicitly* programmed (Arthur Samuel, 1959)
- A computer program is said to learn from experience *E* with respect to some class of tasks *T* and performance measure *P*, if its performance at tasks in *T*, as measured by *P*, improves with experience *E* (Tom M. Michell, 1997)
 - \triangleright *E*: the experience of playing thousands of games
 - ➤ T: playing checkers game
 - $\triangleright P$: the fraction of games it wins against human opponents
 - > By its definition, Samuel's program has learned to play checkers

Task, T

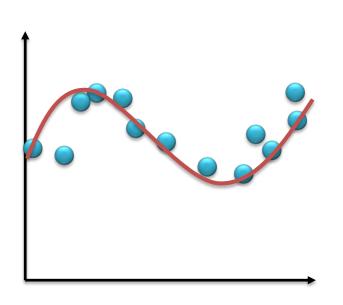
- Classification (with missing inputs)
- Regression
- Transcription
- Machine translation
- Structured output
- Anomaly detection
- Synthesis and sampling
- Imputation of missing values
- Denoising
- Density estimation
- Probability mass function estimation

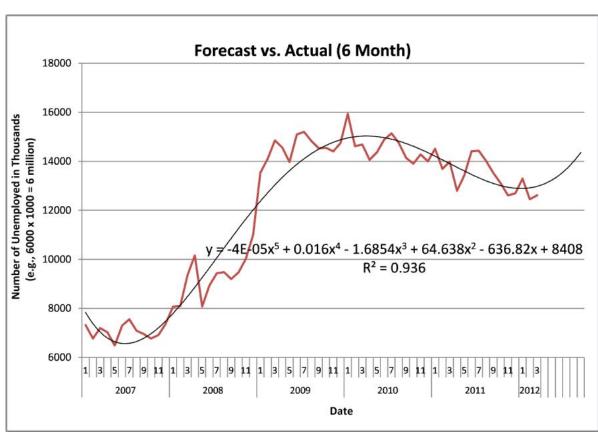
Classification





Regression





Transcription and Machine Translation







Avenue des Sapins

Performance Measure, P

- Accuracy (error rate) for categorical data
 - ➤ To measure the proportion of examples for which model produces the correct output
- Average log-probability for density estimation
 - > To measure continuous-valued score for each example
- **■** E.g., test set for validating model with unseen data
 - 1. Separate the data into training set and test set
 - 2. Train the model with training set
 - 3. Measure the model's performance with test set

Experience, E

Unsupervised learning algorithms,

- > Experiences a dataset containing many features
- Learns useful properties of the structure of the dataset

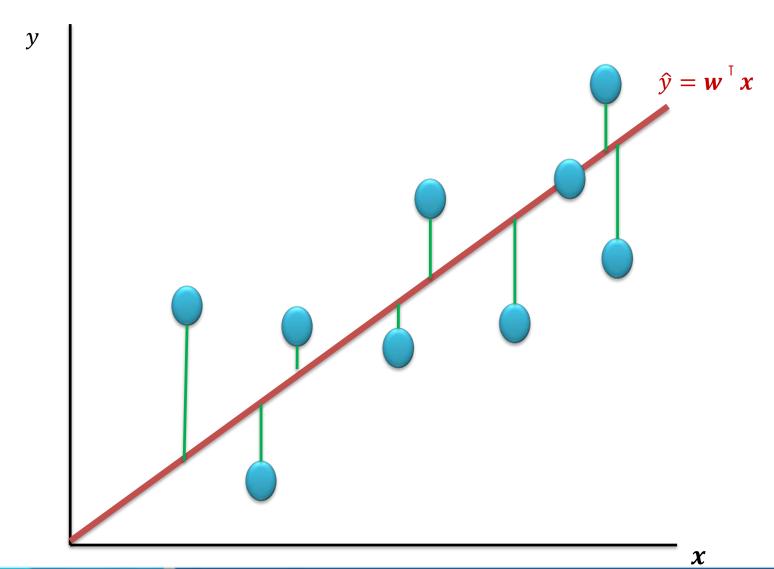
Supervised learning algorithms,

- > Experiences a dataset associated with labels
- Learns to predict the labels from the data

Reinforcement learning algorithms,

- ➤ Not just experience with a fixed dataset, but interact with an environment
- Learns actions to maximize cumulative rewards

Example: Linear Regression



Formal Definition of Linear Regression

■ Task, T: to predict y from x by outputting $\hat{y} = w^{\top} x$

 $x \in \mathbb{R}^n$: input data

 $y \in \mathbb{R}$: output value (\hat{y} : predicted by the model)

 $w \in \mathbb{R}^n$: parameters (or weights)

- **Experience**, *E*: training set (X^{train}, y^{train})
- Performance measure, P: mean squared error (MSE) on (X^{test}, y^{test})

$$MSE_{test} = \frac{1}{m} \sum_{i} (\hat{y}^{test} - y^{test})_{i}^{2}$$

m: number of dataset

Find w by Minimizing MSE_{train}

$$\nabla wMSE_{train} = 0$$

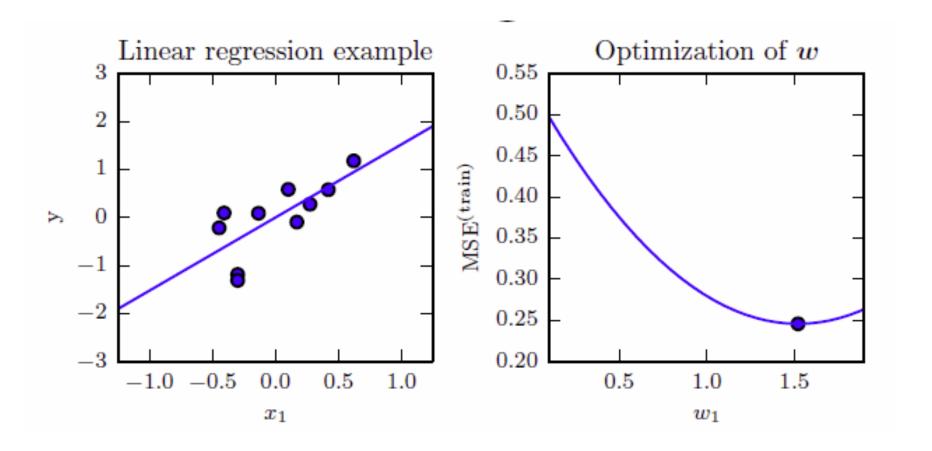
$$\Rightarrow \nabla wMSE_{train} = \frac{1}{m} \sum_{i} (\hat{y}^{train} - y^{train})_{i}^{2} = \mathbf{0}$$

$$\Rightarrow \nabla wMSE_{train} = \frac{1}{m} \sum_{i} (X^{train} w - y^{train})_{i}^{2} = 0$$

. . .

$$\Rightarrow \mathbf{w} = (\mathbf{X}^{train}^{\mathsf{T}} \mathbf{X}^{train})^{-1} \mathbf{X}^{train}^{\mathsf{T}} \mathbf{y}^{train}$$

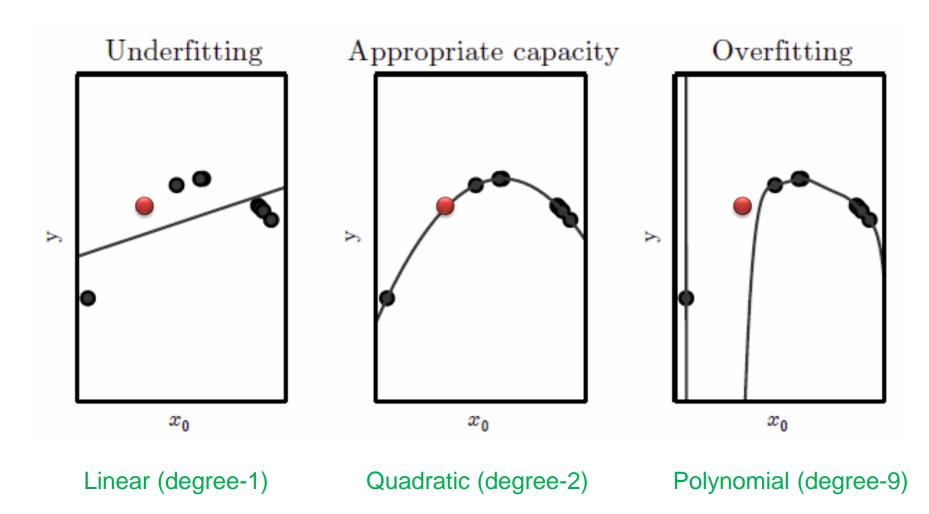
Linear Regression Problem



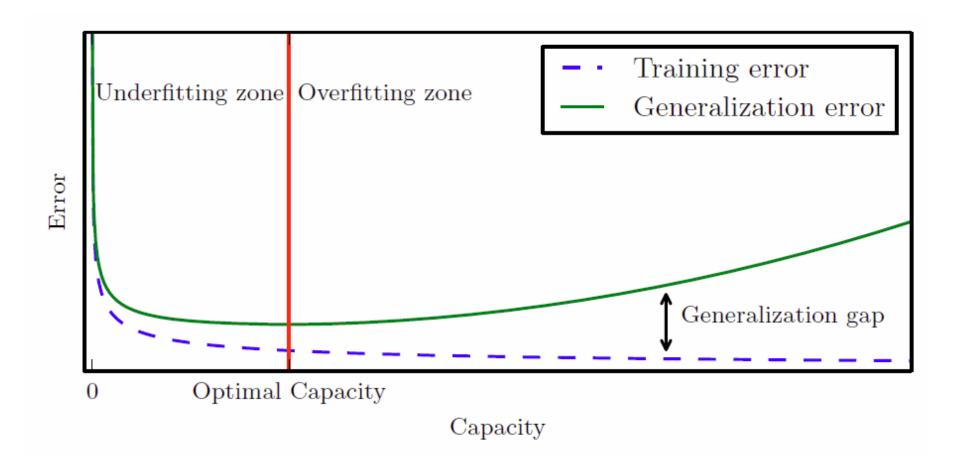
Generalization

- In ML, generalization is the ability to perform well on previously unobserved inputs
 - Making the training error small
 - 2. Making the gap between training and test error small
- Underfitting occurs when the model is not able to obtain a sufficiently low error value on training set
- Overfitting occurs when the gap between the training error and the test error is too large

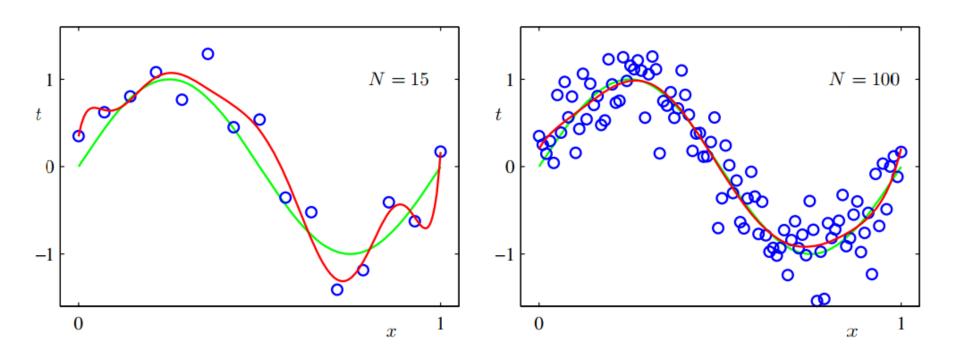
Controlling a Model with its Capacity



Relationship between Capacity and Error



Training Set Size and Generalization



Christopher, M. Bishop. PATTERN RECOGNITION AND MACHINE LEARNING. Springer-Verlag New York, Chapter 1.

Polynomial (degree-9)

Regularization

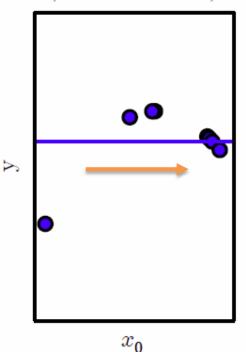
- Regularization is any modification to prevent overfitting
- Regularization is able to control the performance of an algorithm
 - ➤ Intended to reduce test error but not training error
- Example: weight decay for regression problem

$$J(w) = MSE_{train} + \lambda w^{\mathsf{T}} w$$

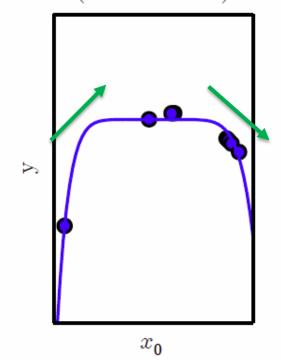
- $J(\cdot)$: cost function to be minimized on training
- λ : control factor of the preference for smaller weight ($\lambda \geq 0$)
- > Trades-off between fitting the training data and being small w

9-degree Regression Model with Weight Decay

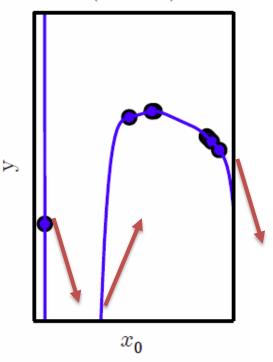
Underfitting (Excessive λ)



Appropriate weight decay (Medium λ)



Overfitting $(\lambda \to 0)$



Large *w* over-fits to training data

Hyperparameters vs. parameters

- Hyperparameters are higher-level properties for a model
 - ➤ Decides model's capacity (or complexity)
 - ➤ Not be learned during training
 - e.g., degree of regression model, weight decay
- Parameters are properties of the training data
 - ➤ Learned during training by a ML model
 - e.g., weights of regression model

Setting Hyperparameters with Validation Set

- Setting hyperparameters in training step is not appropriate
 - \triangleright Hyperparameters will be set to yield overfitting (e.g., higher degree of regression model, $\lambda \rightarrow 0$)
- Test set will not be seen for training nor model choosing (hyperparameter setting)
- So, we need validation set that the training algorithm does not observe
 - 1. Split validation set from training data
 - 2. Train a model with training data (not including validation set)
 - 3. Validate a model with validation set, update hyperparameters

k-fold Cross Validation



Estimation on Statistics

Point estimation

Attempt to provide the singe best prediction of the true but unknown property of a model using sample data, $\{x^1, ..., x^m\}$

Function estimation

➤ Types of estimation that predict the relationship between input and target variables

Point estimator

$$\widehat{\boldsymbol{\theta}}_{m} = g(\boldsymbol{x}^{1}, \dots, \boldsymbol{x}^{m})$$

 $\widehat{\boldsymbol{\theta}}$: point estimator for the property of a model (e.g., expectation)

m: number of data elements

 $\{x^1, \dots, x^m\}$: independent and identically distributed (i.i.d.) data points

 $g(\cdot)$: any estimation function for the given data points

Properties of an Estimator

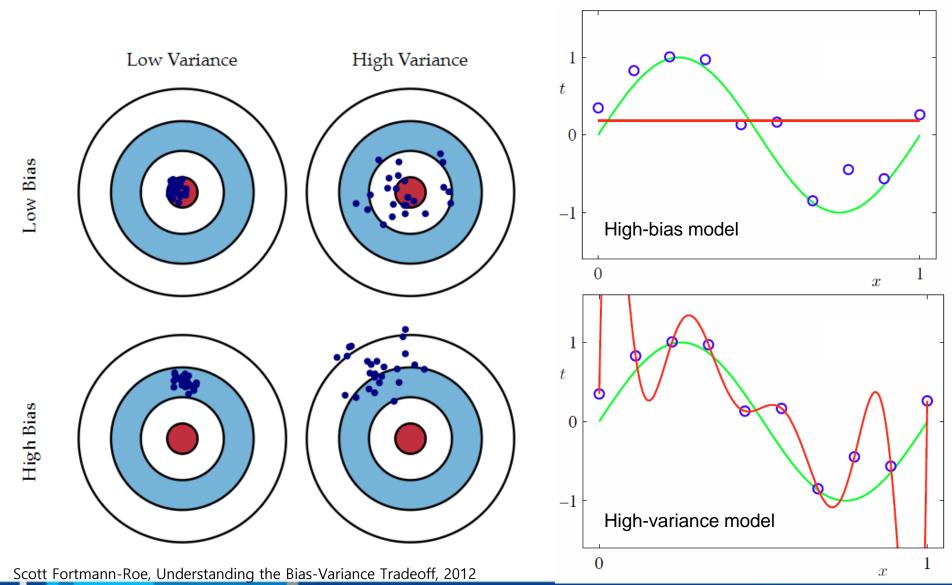
■ Bias measures the expected deviation from the true value of θ

$$bias(\widehat{\boldsymbol{\theta}}_m) = \mathbf{E}[\widehat{\boldsymbol{\theta}}_m] - \boldsymbol{\theta}$$

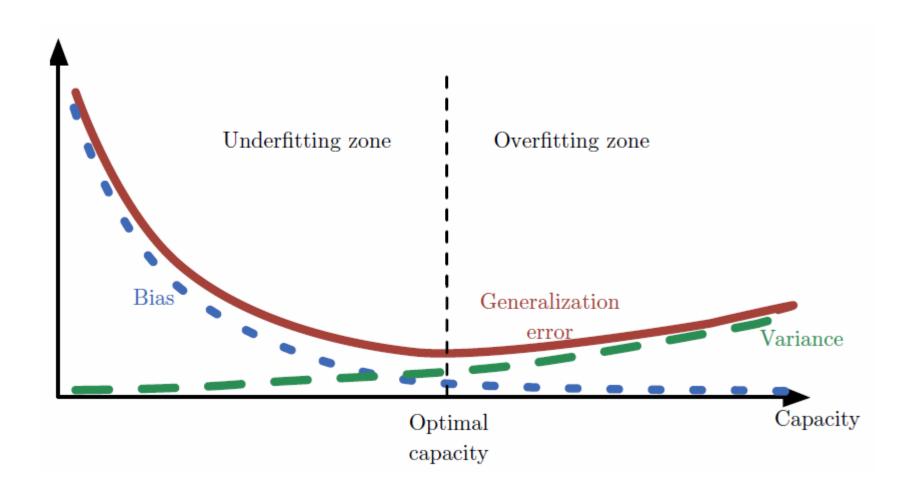
Variance measures the deviation from the expected estimator value that any particular sampling of the data is likely to cause

$$Var(\widehat{\theta})$$

Graphical Illustration of Bias and Variance



Bias-Variance Trade-off with Capacity



Bias & Variance on MSE

Let $h(\cdot; w)$ be a regression model defined by w

- $\triangleright \theta = t(x)$: the true (but unseen) distribution
- $\triangleright \widehat{\theta} = E[h(x; w)]$: the estimation of t(x)
- Then MSE of g is

$$MSE = E[(h(x; w) - t(x))^{2}] = E[(\widehat{\theta} - \theta)^{2}]$$

lacksquare Add and subtract $E[\widehat{m{ heta}}]$ on the internal term

$$E[(\widehat{\boldsymbol{\theta}} - E[\widehat{\boldsymbol{\theta}}] + E[\widehat{\boldsymbol{\theta}}] - \boldsymbol{\theta})^2]$$

$$E[(\widehat{\theta} - E[\widehat{\theta}] + E[\widehat{\theta}] - \theta)^{2}]$$

$$= E[\widehat{\theta}^{2} - \widehat{\theta}E[\widehat{\theta}] + \widehat{\theta}E[\widehat{\theta}] - \widehat{\theta}\theta$$

$$-\widehat{\theta}E[\widehat{\theta}] + E[\widehat{\theta}]^{2} - E[\widehat{\theta}]^{2} + E[\widehat{\theta}]\theta$$

$$+\widehat{\theta}E[\widehat{\theta}] - E[\widehat{\theta}]^{2} + E[\widehat{\theta}]^{2} - E[\widehat{\theta}]\theta$$

$$-\widehat{\theta}\theta + E[\widehat{\theta}]\theta - E[\widehat{\theta}]\theta + \theta^{2}]$$

$$= E[(\widehat{\theta} - E[\widehat{\theta}])^{2}] + (E[\widehat{\theta}] - \theta)^{2} + 2(E[\widehat{\theta} E[\widehat{\theta}] - \widehat{\theta}\theta - E[\widehat{\theta}]^{2} + E[\widehat{\theta}]\theta])$$

$$= \underbrace{E[(\widehat{\theta} - E[\widehat{\theta}])^{2}]}_{Var(\widehat{\theta})} + \underbrace{(E[\widehat{\theta}] - \theta)^{2}}_{bias(\widehat{\theta})^{2}}$$

Ways to Trade-off Bias & Variance

Cross-validation

➤ Highly successful on many real-world tasks

MSE of estimates

➤ MSE incorporates both bias and variance

$$MSE = E[(\widehat{\theta}_m - \theta)^2]$$

$$= bias(\widehat{\theta}_m)^2 + Var(\widehat{\theta}_m)$$

Maximum Likelihood Estimation

Maximum likelihood estimation (MLE) is a method of estimating the parameters of a statistical model

$$\begin{aligned} w_{ML} &= \arg\max p_{model}(X; w) \\ &= \arg\max \prod_{w}^{w_{m}} p_{model}(x^{i}; w) \\ &\equiv \arg\max_{w} \sum_{i}^{i} \log(p_{model}(x^{i}; w)) \end{aligned}$$

- $p_{data}(x)$: true but unknown data-generating distribution
- $X = \{x^1, ... x^m\}$: drawn independently from $p_{data}(x)$
- $p_{model}(x; w)$: a probability distribution estimating $p_{data}(x)$

Linear Regression as Maximum Likelihood

- Instead of single prediction \hat{y} , we consider of the model as producing a conditional distribution, p(y|x)
- Let $p(y|x) = \mathcal{N}(y \mid \hat{y}(x; w), \sigma^2)$
 - $\triangleright \hat{y}(x; w)$: the prediction of the mean of the Gaussian
 - $\triangleright \sigma^2$: variance of \mathcal{N} chosen by user
- Log-likelihood:

$$\sum_{i}^{m} \log(\boldsymbol{p}_{model}(\boldsymbol{x}^{i}; \boldsymbol{w})) = \sum_{i}^{m} \log(y^{i} | \boldsymbol{x}^{i}; \boldsymbol{w})$$
$$= -m \log(\sigma) - \frac{m}{2} \log 2\pi - \sum_{i}^{m} \frac{\|\hat{y}^{i} - y^{i}\|^{2}}{2\sigma^{2}}$$

Cf. MSE:

 $MSE_{\text{train}} = \frac{1}{m} \sum_{i} ||\hat{y}^i - y^i||^2$

The same estimate

of the parameter w

Contents on Part 2

- Bayesian statistics
- Supervised learning algorithms
- Unsupervised learning algorithms
- Stochastic gradient descent
- Building a machine learning algorithm
- Challenges motivating deep learning





Thank you



