

```
1 #include "Polygon.h"
2 #include <cmath>
3
4 float Polygon::getSignedArea() const noexcept {
5     float lArea = 0.0f;
6     for (size_t i = 0; i < fNumberOfVertices; ++i) {
7         size_t j = (i + 1) % fNumberOfVertices;
8         lArea += fVertices[i].x() * fVertices[j].y();
9         lArea -= fVertices[j].x() * fVertices[i].y();
10    }
11    return lArea / 2.0f;
12 }
13
14 Polygon Polygon::transform(const Matrix3x3& aMatrix) const noexcept {
15     Polygon lTransformedPolygon;
16     for (size_t i = 0; i < fNumberOfVertices; ++i) {
17         const Vector3D& lVertex3D = Vector3D(fVertices[i].x(), fVertices
18         [i].y(), 1.0f);
19         Vector3D lTransformedVertex = aMatrix * lVertex3D;
20         lTransformedPolygon.fVertices[i] = Vector2D(lTransformedVertex.x
21         (), lTransformedVertex.y());
22     }
23     lTransformedPolygon.fNumberOfVertices = fNumberOfVertices;
24     return lTransformedPolygon;
25 }
```