

Algorithms Foundations

From Stacks to Binary Heaps

Structure Determines Performance

Table of Contents

- 1. Data Structures vs Algorithms
- 2. Stacks and Queues
- 3. Recursion vs Iteration
- 4. Trees and Traversals
- 5. Binary Search Trees
- 6. Binary Search
- 7. Graphs
- 8. Array-Based Trees
- 9. Binary Heaps
- 10. Structural Synthesis & Final Review

1. Data Structures vs Algorithms

A data structure is a container with guarantees. An algorithm is a rule set that assumes those guarantees. Performance emerges from structure, not from implementation tricks.

Concept Anchor: Algorithms assume. Containers guarantee.

Review Questions

- Why does binary search require random access?
- What structural property allows heapify to work efficiently?

2. Stacks and Queues

Stacks enforce Last-In-First-Out discipline. Queues enforce First-In-First-Out discipline. Both operate in constant time when properly implemented.

Concept Anchor: Control discipline shapes traversal behavior.

Review Questions

- Why is DFS naturally paired with a stack?
- Why is BFS naturally paired with a queue?

3. Recursion vs Iteration

Recursion leverages the call stack. Iteration uses explicit control structures. Recursive structures like trees align naturally with recursive algorithms.

Concept Anchor: Recursion is a stack you didn't write.

Review Questions

- When does recursion become dangerous?
- Can DFS be implemented without recursion?

4. Trees and Traversals

A tree is a connected, acyclic graph with $n-1$ edges. Tree height governs performance. Balanced trees achieve logarithmic height.

Concept Anchor: Height determines complexity.

Review Questions

- Why must a tree with n nodes have $n-1$ edges?
- Why does inorder traversal sort only BSTs?

5. Binary Search Trees

BSTs impose ordering: $\text{left} < \text{root} < \text{right}$. Insertion order determines balance. Skewed BSTs degrade to linear time.

Concept Anchor: A skewed BST is a linked list in disguise.

Review Questions

- What causes BST degeneration?
- Explain the role of inorder successor in deletion.

6. Binary Search

Binary search requires sorted data and random access. It reduces search space by half each step, achieving $O(\log n)$.

Concept Anchor: Binary search exploits ordering and indexing.

Review Questions

- Why does binary search fail on linked lists?
- Compare BST search with binary search.

7. Graphs

Graphs generalize trees. Representation choices (list vs matrix) depend on edge growth rate.

Concept Anchor: Sparse vs dense is about growth rate.

Review Questions

- Why is adjacency matrix inefficient for sparse graphs?
- What is the complexity of BFS?

8. Array-Based Trees

Complete trees map perfectly into arrays using index formulas. Sparse trees waste space when represented this way.

Concept Anchor: Completeness enables efficient array mapping.

Review Questions

- What are the parent/child index formulas?
- Why do sparse trees waste space in arrays?

9. Binary Heaps

Binary heaps maintain a complete tree and heap-order property. Insert and remove are $O(\log n)$. Heapify is $O(n)$.

Concept Anchor: Heaps guarantee urgency, not total ordering.

Review Questions

- Why must heaps be complete?
- Explain why heapify runs in $O(n)$.

10. Structural Synthesis & Final Review

Throughout this course, we have seen how structure dictates performance. From stacks to heaps, the consistent theme is that constraints enable efficiency.

Concept Anchor: Structure determines performance.

Review Questions

- Why does height govern complexity in trees and heaps?
- Why is local ordering sufficient for priority queues?
- Explain sparse vs dense using asymptotic growth.