

McDiarmid-Type Inequalities for Graph-Dependent Variables and Stability Bounds

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- 1 Introduction**
- 2 Concentration Results for Graph-Dependent Random Variables**
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Concentration of Measure

- Concentration inequalities

$$\Pr(f(\mathbf{X}) - \mathbb{E}[f(\mathbf{X})] \geq t) \leq ?$$

- common assumption: random variables are independent

- what if r.v. are not independent

- ▶ mixing coefficients: α -mixing [[Rosenblatt, 1956](#)], β -mixing [[Volkonskii and Rozanov, 1959](#)], ϕ -mixing [[Ibragimov, 1962](#)], η -mixing [[Kontorovich, 2007](#)], etc.
- ▶ dependency graph: Local Lemma [[Erdos and Lovász, 1975](#)], Normal/Poisson Approximation [[Chen, 1978](#), [Janson et al., 1988](#), [Baldi et al., 1989](#)]

- Goal: McDiarmid-type concentration inequality for graph-dependent random variables



Janson's Hoeffding-type inequality

Definition (Dependency Graphs)

An undirected graph G is called a dependency graph of a random vector $\mathbf{X} = (X_1, \dots, X_n)$ if

- 1 $V(G) = [n]$
- 2 if $I, J \subset [n]$ are non-adjacent in G , $\{X_i\}_{i \in I}$ and $\{X_j\}_{j \in J}$ are independent.

Theorem (Janson's inequality [Janson, 2004])

$$\Pr\left(\sum_{i=1}^n X_i - \mathbf{E}\left[\sum_{i=1}^n X_i\right] \geq t\right) \leq \exp\left(-\frac{2t^2}{\chi^*(G)\|\mathbf{c}\|_2^2}\right)$$

- $\chi^*(G)$: fractional coloring number of a dependency graph G of random variables \mathbf{X}
- idea: decomposition of summation to **summation over independent set**



McDiarmid's inequality

Definition (c-Lipschitz, bounded differences condition)

Given a vector $\mathbf{c} = (c_1, \dots, c_n) \in \mathbb{R}_+^n$, a function $f : \Omega \rightarrow \mathbb{R}$ is said to be \mathbf{c} -Lipschitz if for any $\mathbf{x} = (x_1, \dots, x_n), \mathbf{x}' = (x'_1, \dots, x'_n) \in \Omega$, it satisfies

$$|f(\mathbf{x}) - f(\mathbf{x}')| \leq \sum_{i=1}^n c_i \mathbf{1}_{\{x_i \neq x'_i\}}$$

where c_i is called the i -th Lipschitz coefficient of f .

originated from Hoeffding-Azuma [[Hoeffding et al., 1948](#), [Azuma, 1967](#)]

Theorem (McDiarmid's inequality [[McDiarmid, 1989](#)])

Suppose $f : \Omega \rightarrow \mathbb{R}$ is \mathbf{c} -Lipschitz, and $\mathbf{X} = (X_1, \dots, X_n)$ is a vector of independent r.v. with each X_i taking values in Ω_i . Then for any $t > 0$,

$$\Pr(f(\mathbf{X}) - \mathbb{E}[f(\mathbf{X})] \geq t) \leq \exp\left(-\frac{2t^2}{\|\mathbf{c}\|_2^2}\right) \quad (1)$$

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McDiarmid-type inequality for dependency tree

Theorem

Suppose that $f : \Omega \rightarrow \mathbb{R}$ is a \mathbf{c} -Lipschitz function and T is a dependency tree of a random vector \mathbf{X} that takes values in Ω . Then for any $t > 0$,

$$\Pr(f(\mathbf{X}) - \mathbf{E}[f(\mathbf{X})] \geq t) \leq \exp\left(-\frac{2t^2}{\sum_{\langle i,j \rangle \in E(T)} (c_i + c_j)^2 + c_{\min}^2}\right)$$

where c_{\min} is the minimum entry in \mathbf{c} .

- idea: vertex exposure ordering + Doob martingale + conditional probability coupling



McDiarmid-type inequality for dependency forest

Theorem

Suppose that $f : \Omega \rightarrow \mathbb{R}$ is a c -Lipschitz function and G is a dependency graph of a random vector \mathbf{X} that takes values in Ω . If G is a forest consisting of trees $\{T_i\}_{i \in [k]}$, then for any $t > 0$,

$$\Pr(f(\mathbf{X}) - \mathbb{E}[f(\mathbf{X})] \geq t) \leq \exp\left(-\frac{2t^2}{\sum_{\langle i,j \rangle \in E(G)} (c_i + c_j)^2 + \sum_{i=1}^k c_{\min,i}^2}\right)$$

where $c_{\min,i} = \min\{c_j : j \in V(T_i)\}$

- strict generalization of the McDiarmid's inequality for i.i.d. random variables



McDiarmid-type inequality for general dependency graph

idea: transform graph to forest via merging vertices

$$\lambda_{(\phi, F)} = \sum_{\langle u, v \rangle \in E(F)} \left(|\phi^{-1}(u)| + |\phi^{-1}(v)| \right)^2 + \sum_{i=1}^k \min_{u \in V(T_i)} |\phi^{-1}(u)|^2$$

We call

$$\Lambda(G) = \min_{(\phi, F) \in \Phi(G)} \lambda_{(\phi, F)}$$

the **Forest Complexity** of the graph G

Theorem

$$\Pr(f(\mathbf{X}) - \mathbf{E}[f(\mathbf{X})] \geq t) \leq \exp\left(-\frac{2t^2}{\Lambda(G)\|\mathbf{c}\|_\infty^2}\right)$$

independent case: $\Lambda(G) = n$, complete graph: $\Lambda(G) = n^2$



Examples

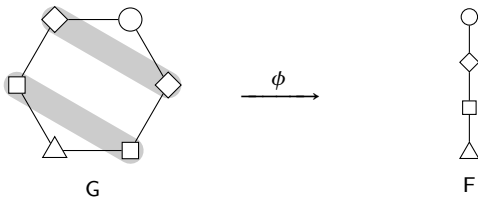


Figure: C_6 : $\Lambda(G) \leq 8n - 13 = O(n)$

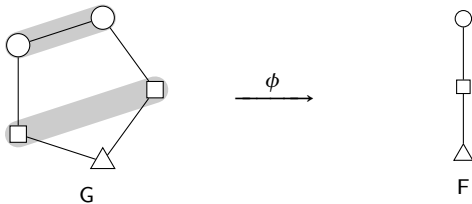


Figure: C_5 : $\Lambda(G) \leq 8n - 14 = O(n)$

Examples

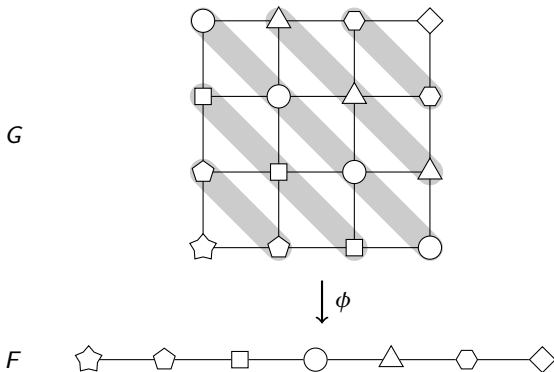


Figure: 4×4 -grid $\Lambda(G) = O(m^3) = O(n^{\frac{3}{2}})$

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Uniform stability

Define $f_{\mathbf{S}}^{\mathcal{A}} : \mathcal{X} \rightarrow \mathcal{Y}$ to be the hypothesis that \mathcal{A} has learned from the sample \mathbf{S}

Definition (Uniform stability [Bousquet and Elisseeff, 2002])

Given integer $n > 0$, the learning algorithm \mathcal{A} is called β_n -uniformly stable with respect to the loss function ℓ , if for any $i \in [n]$, $\mathbf{S} \in (\mathcal{X} \times \mathcal{Y})^n$, and $(x, y) \in \mathcal{X} \times \mathcal{Y}$, it holds that

$$|\ell(y, f_{\mathbf{S}}^{\mathcal{A}}(x)) - \ell(y, f_{\mathbf{S}_{-i}}^{\mathcal{A}}(x))| \leq \beta_n.$$

define $\Phi_{\mathcal{A}}(\mathbf{S}) = R(f_{\mathbf{S}}^{\mathcal{A}}) - \widehat{R}(f_{\mathbf{S}}^{\mathcal{A}})$

Lemma

$$\mathbb{E}[\Phi_{\mathcal{A}}(\mathbf{S})] \leq 2\beta_{n,\Delta}(\Delta + 1).$$



Stability Bound for Learning Graph-dependent Data

Theorem

Given a sample \mathbf{S} of size n with dependency graph G , assume that the learning algorithm \mathcal{A} is β_i -uniformly stable for any $i \leq n$. Suppose the maximum degree G is Δ , and the loss function ℓ is bounded by M . Let $\beta_{n,\Delta} = \max_{i \in [0,\Delta]} \beta_{n-i}$. For any $\delta \in (0,1)$, with probability at least $1 - \delta$, it holds that

$$R(f_{\mathbf{S}}^{\mathcal{A}}) \leq \hat{R}(f_{\mathbf{S}}^{\mathcal{A}}) + 2\beta_{n,\Delta}(\Delta + 1) + \frac{4n\beta_n + M}{n} \sqrt{\frac{\Lambda(G) \ln(1/\delta)}{2}}.$$



Example (Spatial Poisson point process)

Consider a Poisson point process on \mathbb{R}^2 . The number of points in each finite region follows a Poisson distribution, and **the number of points in disjoint regions are independent**. Given a finite set $\mathcal{J} = \{I_i\}_{i=1}^n$ of regions in \mathbb{R}^2 , let X_i be the number of points in region I_i , $1 \leq i \leq n$. Then the graph

$$G\left([n], \left\{\langle i, j \rangle : I_i \cap I_j \neq \emptyset\right\}\right)$$

is a dependency graph of the random variables $\{X_i\}_{i=1}^n$.



m -dependence

Example (m -dependence [Hoeffding et al., 1948])

For some $m, n \in \mathbb{N}_+$, a sequence of random variables $\{X_i\}_{i=1}^n$ is called m -dependent if for any $i \in [n-m-1]$, $\{X_j\}_{j=1}^i$ is independent of $\{X_j\}_{j=i+m+1}^n$.

$$\Lambda(G) \leq \left(\left\lceil \frac{n}{m} \right\rceil - 1 \right) (m+m)^2 + m^2 \leq 4mn = O(mn)$$

$$R(f_{\mathbf{S}}^{\mathcal{A}}) \leq \hat{R}(f_{\mathbf{S}}^{\mathcal{A}}) + 2\beta_{n,2m}(2m+1) + (4n\beta_n + M) \sqrt{\frac{2m \ln(1/\delta)}{n}}.$$

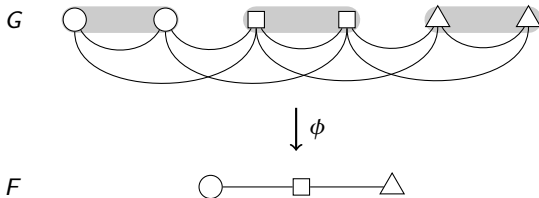
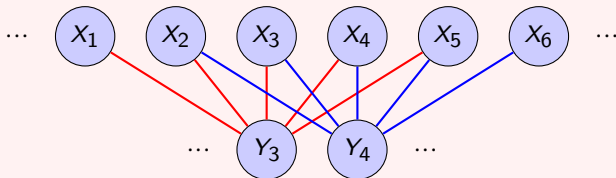


Figure: 2-dependent sequence

Example

Let y_i be the observation at location i , e.g., the house price, and x_i stand for the random variable modeling geographical effect at location i .

Example



$(\mathbf{X}_i, \mathbf{Y}_i)$: geographical effect, house price;
 $\{((X_1, X_2, X_3, X_4, X_5), Y_3), ((X_2, X_3, X_4, X_5, X_6), Y_4)\}$



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