

ELEC 204

Ruiheng Su 2019

Fundamentals

i is the rate of change in charge:

$$i = \frac{dq}{dt}$$

v is the energy required to move a positive unit charge through a circuit element. Charge moves from high to low potential

$$v = \frac{dW}{dq}$$

p is rate of change in energy per unit time

$$p = \frac{dW}{dt} = \frac{dW}{dq} \frac{dq}{dt} = vi$$

R is the ability to resist current

$$R \propto \rho \frac{l}{A} \quad l: \text{Length of resistor}; A: \text{Cross section area}$$

G is the ability to conduct current

$$G = \frac{1}{R} \quad \text{Units: Siemens [S]}$$

Node: Point where two or more elements join

Loop: Path whose last node is starting node

Mesh: A loop that does not enclose any other loops

Zeros: Root of the numerator

Pole: Root of the denominator

Cramer's Method

$$\mathbf{M} = \begin{pmatrix} a+jb & \alpha \\ \beta & c+jd \end{pmatrix} \begin{vmatrix} V_1 \\ V_2 \end{vmatrix}$$

$$V_1 = \frac{1}{\det \mathbf{M}} \begin{bmatrix} V_1 & \alpha \\ V_2 & c+jd \end{bmatrix} \quad V_2 = \frac{1}{\det \mathbf{M}} \begin{bmatrix} a+jb & V_1 \\ \beta & V_2 \end{bmatrix}$$

Decibel Scale

$$\log 1 = 0 \quad \log AB = \log A + \log B$$

$$\log \frac{A}{B} = \log A - \log B \quad \log A^n = n \log A$$

The dB is used for measuring the ratio of variables of the same unit. Use the **magnitude** of quantities.

$$1 \text{ Decibel: } 10 \log_{10} \frac{A}{B}$$

Passive Sign Convention

Given the assumption that current flows from + to -. Current that flow from - to + are multiplied -1

$$\text{Passive Component: Absorbing Power} \quad P \geq 0$$

$$\text{Active Component: Delivering Power} \quad P \leq 0$$

Tellegan's Theorem

Power consumed and produced by all elements in a circuit sum to zero at all time

$$\sum P = 0$$

KCL

Sum of currents entering any closed boundary is zero

KVL

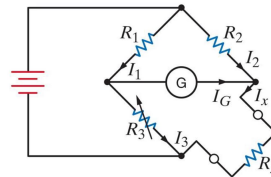
Sum of voltage drops around any closed path is zero

Resistors

Parallel Resistors

$$\frac{1}{R_{eq}} = \sum_{i=1}^n \frac{1}{R_i} \quad G_{eq} = \sum_{i=1}^n G_i$$

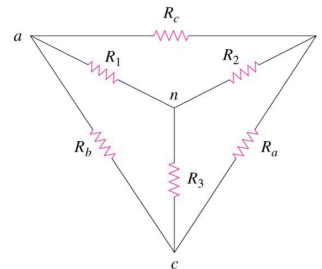
Wheatstone Bridge



Balanced when:

$$\frac{R_1}{R_3} = \frac{R_2}{R_x}$$

Y Δ Transformation



Let $R_a \leftrightarrow R_1$, $R_2 \leftrightarrow R_2$, $R_3 \leftrightarrow R_3$

Notice the pattern in the numerator and the denominator

$$R_1 = \frac{R_b R_c}{R_a + R_b + R_c} \quad R_a = \frac{R_1 R_2 + R_2 R_3 + R_3 R_1}{R_1}$$

If R values in the Y or Δ network are equal, then

$$R_Y = \frac{R_\Delta}{3} \quad R_\Delta = 3R_Y$$

Nodal Analysis

1. Simplify the circuit if possible
Choose a node for ground which minimizes the number of floating sources
2. Construct KCL for all leftover nodes. Pure assign a current variable to each floating source
3. Use the convention that $\Delta V = V_{\text{start}} - V_{\text{end}}$
4. Solve equations

Superposition

1. Turn off all independent source, except one.

$$V_{\text{source}} \rightarrow \text{Ideal wire} \quad I_{\text{source}} \rightarrow \text{Open circuit}$$

2. Calculate current or voltage contribution due to that source
3. Repeat for all independent sources
4. Sum up calculated values

Source Transformation

We can transform any voltage source in series with a resistor to a current source in parallel with that same resistor

$$V \rightarrow I \quad I = \frac{V}{R}$$

$$I \rightarrow V \quad V = \frac{I}{R}$$

Thevenin's Theorem

A linear two terminal network can be transformed into one involving a resistor and a voltage source

R_{th} represents: Dependent sources, resistors

V_{th} represents: Independent sources

Methods for R_{th}

1. Turn off all independent source. Find the equivalent resistance. If there are dependent sources, then apply V_{test} or I_{test} at the terminal, and

$$\frac{V_{\text{terminal}}}{I_{\text{test}}} \text{ or } \frac{V_{\text{test}}}{I_{\text{terminal}}} = R_{th}$$

2. Given V_{th} and find I_{sc} we can find R_{th} (Without turning any sources off)
3. 1A2A method (V_{th} we can find R_{th} by solving only one equation in the 1A2A method)

Methods for V_{th}

1. $V_{oc} = V_{th}$ without turning off any sources
2. Find I_{sc} and R_{th} and apply ohm's law
3. 1A2A method (R_{th} we can find V_{th} by solving only one equation in the 1A2A method)

1A2A Method

Find the voltage drop across a 1 A source (V_1) and a 2 A source (V_2), and

$$V_{th} + R_{th} = V_1 \quad V_{th} + 2R_{th} = V_2$$

Maximum Power Transfer in Thevenin Circuit

$$p = i^2 R_L = \left(\frac{V_{th}}{R_{th} + R_L} \right)^2 R_L \quad p_{max} \text{ when } R_L = R_{th}$$

First Order Circuits

The number of capacitors and inductors that cannot be combined tells the order of the circuit.

Natural Response: No sudden application of DC source

Stepped Response: Sudden switching

Capacitors

$$q = CV_c \quad i_c(t) = C \frac{dV_c}{dt} \quad E_c(t) = \frac{1}{2} CV_c^2(t)$$

$$\text{In parallel: } C_{eq} = \sum_i^n C_i \quad \text{In series: } \frac{1}{C_{eq}} = \sum_i^n \frac{1}{C_i}$$

RC Natural Response:

Capacitor Property: $v(0^-) = v(0) = v(0^+)$

Assuming $v_c(0) = V_o$

$$v_c(t) = V_o e^{-\frac{t}{\tau}} \quad \tau = RC \quad v_c(t) \approx 0 \text{ after } 5\tau$$

Inductors

$$v_L(t) = L \frac{di}{dt} \quad E_L = \frac{1}{2} Li_L^2(t)$$

$$\text{In parallel: } \frac{1}{L_{eq}} = \sum_i^n \frac{1}{L_i} \quad \text{In series: } L_{eq} = \sum_i^n L_i$$

RL Natural Response:

Inductor Property: $i(0^-) = i(0^+)$

Assuming $i(0) = I_o$

$$i_l(t) = I_o e^{-\frac{t}{\tau}} \quad \tau = \frac{L}{R}$$

DC Step Response

For a step applied at $t = t_o$, and condition at time $t = t_0^+$

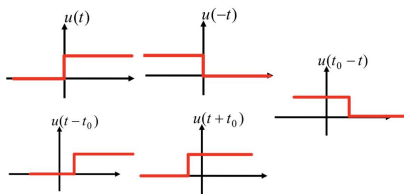
$$x(t) = [x(t_0^+) - x(\infty)]e^{-\frac{t-t_0}{\tau}} + x(\infty)$$

Second Order Circuits

Construct RCL series by using KVL, and RCL parallel by using KCL at top node.

Unit Step Function

$$u(t) = \begin{cases} 0 & t \leq 0 \\ 1 & t > 0 \end{cases}$$



Operation Amplifiers

Voltage output is limited by saturation

$$-V_{cc} \leq V_{out} \leq +V_{cc}$$

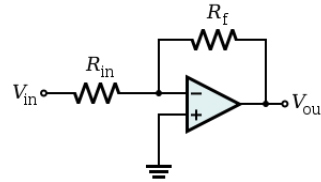
— end is the inverting input, and + end is the non-inverting input

An ideal opAmp has ∞ input impedance and 0 output impedance, and infinite gain

Given negative feedback, we can say

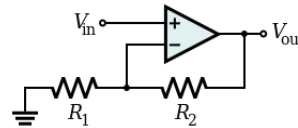
$$V_- = V_+ \quad I_- = I_+ = 0$$

Inverting Amplifier



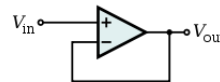
$$V_{out} = -\frac{R_f}{R_{in}} V_{in}$$

Non-Inverting Amplifier



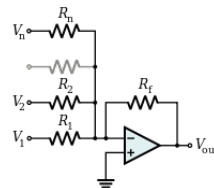
$$V_{out} = \left(1 + \frac{R_2}{R_1}\right) V_{in}$$

Buffer



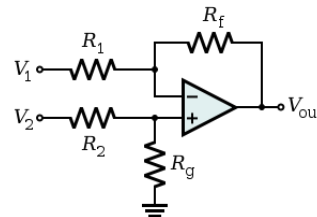
$$V_{out} = V_{in}$$

Summer



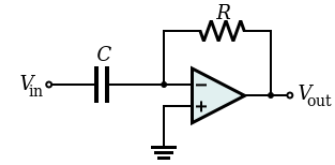
$$V_{out} = -R_f \sum_i^n \frac{V_i}{R_i}$$

Difference Amplifier



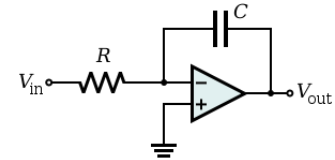
$$V_{out} = \frac{(R_f + R_1)R_g}{(R_g + R_2)R_1} V_2 - \frac{R_f}{R_1} V_1$$

Differentiator



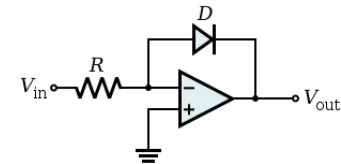
$$V_{out} = -RC \frac{dV_{in}}{dt}$$

Integrator



$$V_{out} = -\frac{1}{RC} \int v_i dt + V_{out}^{\text{initial}}$$

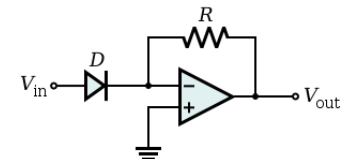
Logarithm



When $V_D > 0$, current through the diode is $I_D \approx I_S e^{\frac{V_D}{V_T}}$

$$V_{out} = V_T \ln \left(\frac{V_{in}}{I_S R} \right) \quad V_T: \text{Thermal Voltage}; I_S: \text{Saturation Current}$$

Exponentiation

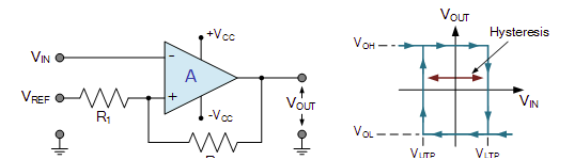


$$V_{out} = -RI_S e^{\frac{V_{in}}{V_T}} \quad V_T: \text{Thermal Voltage}; I_S: \text{Saturation Current}$$

Comparator

$$V_{out} = \begin{cases} -V_{cc} & V_- > V_+ \\ V_{cc} & V_+ > V_- \end{cases}$$

A comparator with positive feedback



Identities

$$\begin{aligned}
 e^{j\theta} &= \cos(\theta) + j\sin(\theta) \\
 \cos(-\alpha) &= \cos(\alpha) \\
 \sin(-\alpha) &= -\sin(\alpha) \\
 \cos(\omega t) &= \sin(\omega t + \pi/2) \\
 \sin(\omega t) &= \cos(\omega t - \pi/2) \\
 \cos(\omega t) &= -\cos(\omega t \pm \pi) \\
 \sin(\omega t) &= -\sin(\omega t \pm \pi) \\
 \cos(\alpha \pm \beta) &= \cos(\alpha)\cos(\beta) \mp \sin(\alpha)\sin(\beta) \\
 \sin(\alpha \pm \beta) &= \sin(\alpha)\cos(\beta) \pm \cos(\alpha)\sin(\beta) \\
 \cos(\alpha)\cos(\beta) &= \cos(\alpha + \beta)/2 + \cos(\alpha - \beta)/2 \\
 \sin(\alpha)\cos(\beta) &= \sin(\alpha + \beta)/2 + \sin(\alpha - \beta)/2
 \end{aligned}$$

Combination of $\cos(\omega t)$ and $\sin(\omega t)$

$$A \sin(\omega t) + B \cos(\omega t) = \sqrt{A^2 + B^2} \cos[\omega t - \tan(B/A)]$$

Phasors

$$X_M \cos(\omega t + \theta) = \text{Re}[X_M e^{j(\omega t + \theta)}] = X_M \angle \theta$$

$$|\mathbf{V}| = |V_M \angle \theta| = V_M$$

Multiplication by j shifts phasors by 90 degrees

$$jV \angle \theta = V \angle \theta + 90 = V \angle \theta + \frac{\pi}{2}$$

$$Z = X + jY = A \cos(\theta) + jB \sin(\theta) = A \angle \theta$$

Sinusoidal Steady State Analysis

$$\omega = 2\pi f \quad [\text{Rad/s}] \quad f = \frac{1}{T} \quad [\text{Hz}] \quad T = \frac{2\pi}{\omega} \quad x(t) = x(t + T)$$

Leading means approaching maximum first.

$$X_{rms} = \sqrt{\frac{1}{T} \int_{t_0}^{t_0+T} x(t)^2 dt} = \frac{X_M}{\sqrt{2}}$$

The same average power is consumed for a $4V_{rms}$ and a $4V_{DC}$

Impedances

$$\mathbf{Z} = R + jX \quad \text{Impedance} = \text{Resistance} + j(\text{Reactance})$$

$$\text{Resistance: In Phase} \quad R$$

$$\text{Capacitor: } I \text{ Lead } V \quad \frac{-j}{\omega C}$$

$$\text{Inductor: } V \text{ Leads } I \quad j\omega L$$

Admittance: $\frac{1}{Z}$

A positive reactance is **inductive**, whereas a negative inductance is **capacitive**

AC Power

Power Factor: $pf = \cos(\theta_v - \theta_i)$

Reactive Factor: $rf = \sin(\theta_v - \theta_i)$

A lagging pf means that the load is **inductive**. A leading power factor means that the load is **capacitive**

$$P = \frac{V_M I_M}{2} pf = V_{rms} I_{rms} pf \quad \text{Real/Active/Average [W]}$$

$$P = R I_{rms}^2 \quad R: \text{Real Part of Impedance}$$

$$Q = \frac{V_M I_M}{2} rf = V_{rms} I_{rms} rf \quad \text{Reactive [VAR]}$$

$$Q = X I_{rms}^2 \quad X: \text{Complex Part of Impedance}$$

$$\tan(\theta_v - \theta_i) = \frac{Q}{P}$$

$$\text{Instantaneous Power} \quad p = P + P \cos(2\omega t) - Q \sin(2\omega t)$$

Complex Power

$$\mathbf{S} = P + jQ = \mathbf{V}_{rms} \mathbf{I}_{rms}^* = \frac{1}{2} \mathbf{V} \mathbf{I}^* \quad [\text{VA}]$$

AC Maximum Average Power Transfer (No Restriction)

Assuming \mathbf{V}_{th} is not given in rms values, Select \mathbf{Z}_L such that

$$\mathbf{Z}_L = R_{th} + jX_{th} = \mathbf{Z}_{th}^* \quad P_{max} = \frac{|\mathbf{V}_{th}|^2}{8R_{th}} = \frac{|\mathbf{V}_{th}^{rms}|^2}{4R_{th}}$$

AC Maximum Average Power Transfer (Restricted)

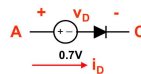
1. Choose X_L as close as possible to $-X_{th}$
2. Adjust R_L as close as possible to

$$\sqrt{R_{th}^2 + (X_L + X_{th})^2}$$

Diodes

A diode is conducting if it is "closed" or "on".

A diode is not conducting when it is "open" or off



The pn junction of the diode results in a depletion region, which requires a barrier voltage to overcome ($\approx 0.7V$).

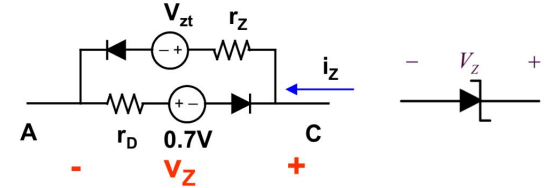
$$V_D - 0.7 \geq 0 \quad \text{Operation Condition}$$

$$\text{Diode current is a function of voltage} \quad i_D = I_0 \left(e^{\frac{V_D}{nV_T}} - 1 \right)$$

$$V_T = \frac{kT}{qe} = \frac{1.38 \times 10^{-23} T_{\text{Kelvin}}}{1.60 \times 10^{-19}}$$

$$T_K = T_{\text{Celsius}} + 273.15$$

For quality factor 1, and $v_D \gg V_T$ we have $i_D = I_0 e^{\frac{V_D}{V_T}}$ **Zener Diode**



Zener diodes act like a perfect negative voltage source for a range of negative current values.

\mathcal{L} ap lace Transform

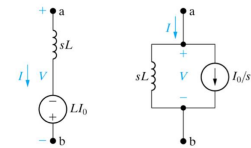
$$\mathcal{L}[f(t)] = \int_0^\infty f(t) e^{-st} dt = \mathbf{F}(s)$$

$$f(0) = \lim_{s \rightarrow \infty} sF(s) = \lim_{t \rightarrow 0^+} f(t) \quad \text{Initial Value Theorem}$$

$$f(\infty) = \lim_{s \rightarrow 0} sF(s) = \lim_{t \rightarrow \infty} f(t) \quad \text{Final Value Theorem}$$

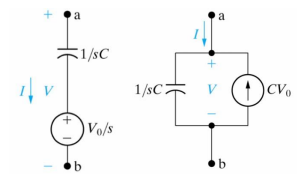
$$\begin{aligned}
 \frac{F(s)}{s+a} & \quad f(t) \\
 \frac{A}{s+a} & \quad Ae^{-at}u(t) \\
 \frac{A}{(s+a)^2} & \quad Ate^{-at}u(t) \\
 \frac{\mathbf{V}}{s+a-jB} + \frac{\mathbf{V}^*}{s+a+jB} & \quad 2|\mathbf{V}|e^{-at} \cos(Bt + \theta)u(t) \\
 \frac{\mathbf{V}}{(s+a-jB)^2} + \frac{\mathbf{V}^*}{(s+a+jB)^2} & \quad 2t|\mathbf{V}|e^{-at} \cos(Bt + \theta)u(t)
 \end{aligned}$$

S Domain Equivalents



$$V_L = L \frac{di}{dt} \quad i = \frac{1}{L} \int_0^t V_L dt + I_0 \quad \text{Time Domain}$$

$$V_L = sLI - LI_0 \quad I = \frac{V}{sL} + \frac{I_0}{s} \quad \text{S Domain}$$



$$V_c = \frac{1}{C} \int_0^t i dt + V_0 \quad i = C \frac{dV_c}{dt} \quad \text{Time Domain}$$

$$V_L = \frac{1}{sC} + \frac{V_0}{s} \quad I = sCV - CV_0 \quad \text{S Domain}$$

Impedance in the S Domain

Assuming zero initial conditions

Resistor	R
Capacitor	$\frac{1}{sC}$
Inductor	sL

Transfer Functions

Is the ratio of a ω dependent phasor output versus a phasor input.

$$\mathbf{H}(\omega) = \frac{\mathbf{V}_{out}(\omega)}{\mathbf{V}_{in}(\omega)} = \frac{\mathbf{I}_{out}(\omega)}{\mathbf{I}_{in}(\omega)} \quad \text{Voltage/Current Gain}$$

$$\mathbf{H}(\omega) = \frac{\mathbf{V}_{out}(\omega)}{\mathbf{I}_{in}(\omega)} = \frac{\mathbf{I}_{out}(\omega)}{\mathbf{V}_{in}(\omega)} \quad \text{Transfer Impedance/Admittance}$$

We plot the magnitude of \mathbf{H} versus frequency.

We may let $j\omega = s$ to ease analysis

Bode Plots

$$H_{db} = 20 \log_{10}(\mathbf{H})$$

1. Place transfer function into standard form, involving constant parts as 1
2. Rewrite into phasor
3. Use reference table to plot the frequency (dB vs frequency) and phase (degrees vs frequency) plots. Add the sections graphically

Magnitude	$20 \log H$ [dB]
0.001	-60
0.01	-40
0.1	-20
0.5	-6
$\frac{1}{\sqrt{2}}$	-3
1	0
$\sqrt{2}$	3
2	6
10	20
20	26
100	40
1000	60

Frequency Selective Circuits

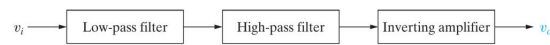
Passive: only involves R , L , or C

Active: uses opamps and transistors. We can combine high pass and low pass filters via opAmps to obtain a band pass or band reject filter.

For a first order low/high pass filter

$$\omega_c \text{ is found by setting } |\mathbf{H}(\omega)| = \frac{1}{\sqrt{2}}$$

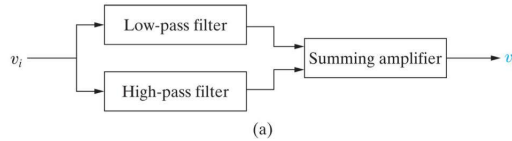
Band Pass



Given that ω_{CutOff} for the low pass filter is greater than the ω_{CutOff} for the high pass filter

$$\lim_{t \rightarrow 0} \mathbf{H} = 0 \quad \lim_{t \rightarrow \infty} \mathbf{H} = 0$$

Band Reject



Frequencies lying between cut off frequency of the low pass and the cut off frequency for the high pass is rejected, given that $\omega_{low} < \omega_{high}$

$$\lim_{t \rightarrow 0} \mathbf{H} = C \quad \lim_{t \rightarrow \infty} \mathbf{H} = C \quad C > 0$$

BJT Transistors

BJT Modes of Operation

	Emitter-Base	Collector-Base
Cutoff	Reverse	Reverse
Active	Forward	Reverse
Saturation	Forward	Forward

BJT Active Region

Collector Current (i_C is independent of V_{CE})

$$i_C = I_s e^{\frac{V_{BE}}{V_T}} \quad I_s \text{ Saturation Current}$$

$$i_C = \frac{\beta}{\beta + 1} i_E = \alpha i_E \quad \alpha \text{ Common Base Current Gain}$$

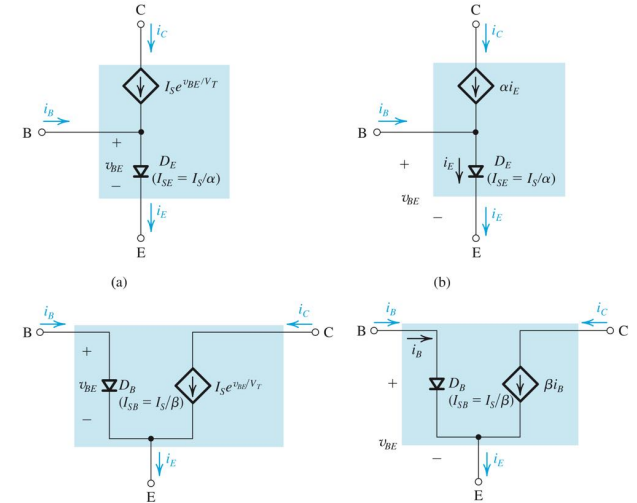
Base Current (Is a fraction of i_C)

$$i_B = \frac{i_C}{\beta} = \frac{i_s}{\beta} e^{\frac{V_{BE}}{V_T}} \quad \beta \text{ Common Emitter Current Gain}$$

Emitter Current

$$i_E = i_C + i_B = \frac{\beta + 1}{\beta} i_C$$

Large Signal Models



For a pnp BJT, the diode in the model above is reversed, and so is the current source.

For large β , the base current can be assumed as zero.

Biasing

MOS

Common Source: In-Gate Out-Drain

Common Gate: In-Source Out-Drain

Common Drain: In-Gate Out-Source

BJT

Common Emitter: In-Base Out-Collector

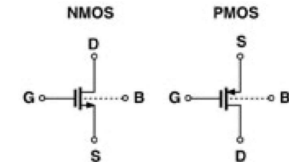
Common Base: In-Emitter Out-Collector

Common Collector: In-Base Out-Emitter

MOS Transistors

A MOS transistor has Gate, Source and Drain.

Infinite input impedance at gate, so $I_G \approx 0$ at steady state



Current flow determines the source and drain terminals

NMOS: I flows from Drain \rightarrow Source

PMOS: I flows from Source \rightarrow Drain

NMOS Current Equations

$$\Delta V = V_{GS} - V_{TH}$$

$$I_D = I_{DS} =$$

Cut Off

$$0 \quad V_{GS} < V_{TH}$$

Deep Triode

$$\mu_n C_{ox} \frac{W}{L} (\Delta V) V_{DS} \quad V_{GS} > V_{TH}, V_{DS} \ll 2(\Delta V)$$

Triode

$$\mu_n C_{ox} \frac{W}{L} \left[(\Delta V) V_{DS} - \frac{V_{DS}^2}{2} \right] \quad V_{GS} > V_{TH}, V_{DS} < \Delta V$$

Saturation

$$\frac{\mu_n C_{ox}}{2} \frac{W}{L} (\Delta V)^2 \quad V_{GS} > V_{TH}, V_{DS} > \Delta V$$

PMOS Current Equations

$$\Delta V = V_{SG} - |V_{TH}|$$

$$I_D = I_{SD} =$$

Cut Off

$$0 \quad V_{SG} < |V_{TH}|$$

Deep Triode

$$\mu_p C_{ox} \frac{W}{L} (\Delta V) V_{SD} \quad V_{SG} > |V_{TH}|, V_{SD} \ll 2(\Delta V)$$

Triode

$$\mu_p C_{ox} \frac{W}{L} \left[(\Delta V) V_{SD} - \frac{V_{SD}^2}{2} \right] \quad V_{SG} > |V_{TH}|, V_{SD} < \Delta V$$

Saturation

$$\frac{\mu_p C_{ox}}{2} \frac{W}{L} (\Delta V)^2 \quad V_{SG} > |V_{TH}|, V_{SD} > \Delta V$$

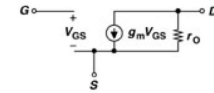
Transconductance

As I_D in saturation is function of overdrive or effective voltage ($V_{GS} - V_{TH}$), we define transconductance, g_m as how well the device converts voltage into current.

$$g_m = \frac{\partial I_D}{\partial V_{GS}}$$

g_m is max in saturation, and drops in the triode region

Small Signal Model



$$i_D = g_m V_{GS} + \frac{V_{DS}}{R}$$