

# ELEC 204

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## Fundamentals

$i$  is the rate of change in charge:

$$i = \frac{dq}{dt}$$

$v$  is the energy required to move a positive unit charge through a circuit element. Charge moves from high to low potential

$$v = \frac{dW}{dq}$$

$p$  is rate of change in energy per unit time

$$p = \frac{dW}{dt} = \frac{dW}{dq} \frac{dq}{dt} = vi$$

$R$  is the ability to resist current

$$R \propto \rho \frac{l}{A} \quad l: \text{Length of resistor}; A: \text{Cross section area}$$

$G$  is the ability to conduct current

$$G = \frac{1}{R} \quad \text{Units: Siemens [S]}$$

**Node:** Point where two or more elements join

**Loop:** Path whose last node is starting node

**Mesh:** A loop that does not enclose any other loops

**Zeros:** Root of the numerator

**Pole:** Root of the denominator

## Cramer's Method

$$\mathbf{M} = \begin{pmatrix} a+jb & \alpha \\ \beta & c+jd \end{pmatrix} \begin{vmatrix} V_1 \\ V_2 \end{vmatrix}$$

$$V_1 = \frac{1}{\det \mathbf{M}} \begin{bmatrix} V_1 & \alpha \\ V_2 & c+jd \end{bmatrix} \quad V_2 = \frac{1}{\det \mathbf{M}} \begin{bmatrix} a+jb & V_1 \\ \beta & V_2 \end{bmatrix}$$

## Decibel Scale

$$\log 1 = 0 \quad \log AB = \log A + \log B$$

$$\log \frac{A}{B} = \log A - \log B \quad \log A^n = n \log A$$

The dB is used for measuring the ratio of variables of the same unit. Use the **magnitude** of quantities.

$$1 \text{ Decibel: } 10 \log_{10} \frac{A}{B}$$

## Passive Sign Convention

Given the assumption that current flows from + to -. Current that flow from - to + are multiplied -1

Passive Component: Absorbing Power  $P \geq 0$

Active Component: Delivering Power  $P \leq 0$

## Tellegan's Theorem

Power consumed and produced by all elements in a circuit sum to zero at all time

$$\sum P = 0$$

## KCL

Sum of currents entering any closed boundary is zero

## KVL

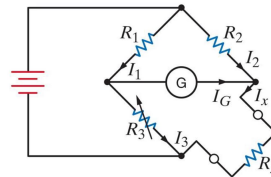
Sum of voltage drops around any closed path is zero

## Resistors

Parallel Resistors

$$\frac{1}{R_{eq}} = \sum_{i=1}^n \frac{1}{R_i} \quad G_{eq} = \sum_{i=1}^n G_i$$

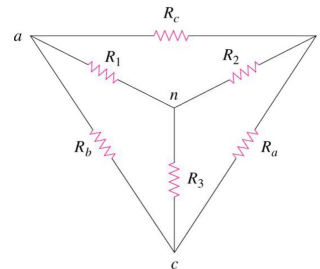
## Wheatstone Bridge



Balanced when:

$$\frac{R_1}{R_3} = \frac{R_2}{R_x}$$

## Y Δ Transformation



Let  $R_a \leftrightarrow R_1$ ,  $R_2 \leftrightarrow R_2$ ,  $R_3 \leftrightarrow R_3$

Notice the pattern in the numerator and the denominator

$$R_1 = \frac{R_b R_c}{R_a + R_b + R_c} \quad R_a = \frac{R_1 R_2 + R_2 R_3 + R_3 R_1}{R_1}$$

If  $R$  values in the  $Y$  or  $\Delta$  network are equal, then

$$R_Y = \frac{R_\Delta}{3} \quad R_\Delta = 3R_Y$$

## Nodal Analysis

1. Simplify the circuit if possible  
Choose a node for ground which minimizes the number of floating sources
2. Construct KCL for all leftover nodes. Pure assign a current variable to each floating source
3. Use the convention that  $\Delta V = V_{\text{start}} - V_{\text{end}}$
4. Solve equations

## Superposition

1. Turn off all independent source, except one.

$$V_{\text{source}} \rightarrow \text{Ideal wire} \quad I_{\text{source}} \rightarrow \text{Open circuit}$$

2. Calculate current or voltage contribution due to that source
3. Repeat for all independent sources
4. Sum up calculated values

## Source Transformation

We can transform any voltage source in series with a resistor to a current source in parallel with that same resistor

$$V \rightarrow I \quad I = \frac{V}{R}$$
$$I \rightarrow V \quad V = \frac{I}{R}$$

## Thevenin's Theorem

A linear two terminal network can be transformed into one involving a resistor and a voltage source

$R_{th}$  represents: Dependent sources, resistors

$V_{th}$  represents: Independent sources

## Methods for $R_{th}$

1. Turn off all independent source. Find the equivalent resistance. If there are dependent sources, then apply  $V_{\text{test}}$  or  $I_{\text{test}}$  at the terminal, and

$$\frac{V_{\text{terminal}}}{I_{\text{test}}} \text{ or } \frac{V_{\text{test}}}{I_{\text{terminal}}} = R_{th}$$

2. Given  $V_{th}$  and find  $I_{sc}$  we can find  $R_{th}$  (Without turning any sources off)
3. 1A2A method ( $V_{th}$  we can find  $R_{th}$  by solving only one equation in the 1A2A method)

## Methods for $V_{th}$

1.  $V_{oc} = V_{th}$  without turning off any sources
2. Find  $I_{sc}$  and  $R_{th}$  and apply ohm's law
3. 1A2A method ( $R_{th}$  we can find  $V_{th}$  by solving only one equation in the 1A2A method)

## 1A2A Method

Find the voltage drop across a 1 A source ( $V_1$ ) and a 2 A source ( $V_2$ ), and

$$V_{th} + R_{th} = V_1 \quad V_{th} + 2R_{th} = V_2$$

## Maximum Power Transfer in Thevenin Circuit

$$p = i^2 R_L = \left( \frac{V_{th}}{R_{th} + R_L} \right)^2 R_L \quad p_{max} \text{ when } R_L = R_{th}$$

## First Order Circuits

The number of capacitors and inductors that cannot be combined tells the order of the circuit.

Natural Response: No sudden application of DC source

Stepped Response: Sudden switching

## Capacitors

$$q = CV_c \quad i_c(t) = C \frac{dV_c}{dt} \quad E_c(t) = \frac{1}{2} CV_c^2(t)$$

$$\text{In parallel: } C_{eq} = \sum_i^n C_i \quad \text{In series: } \frac{1}{C_{eq}} = \sum_i^n \frac{1}{C_i}$$

## RC Natural Response:

**Capacitor Property:**  $v(0^-) = v(0) = v(0^+)$

Assuming  $v_c(0) = V_o$

$$v_c(t) = V_o e^{-\frac{t}{\tau}} \quad \tau = RC \quad v_c(t) \approx 0 \text{ after } 5\tau$$

## Inductors

$$v_L(t) = L \frac{di}{dt} \quad E_L = \frac{1}{2} Li_L^2(t)$$

$$\text{In parallel: } \frac{1}{L_{eq}} = \sum_i^n \frac{1}{L_i} \quad \text{In series: } L_{eq} = \sum_i^n L_i$$

## RL Natural Response:

**Inductor Property:**  $i(0^-) = i(0^+)$

Assuming  $i(0) = I_o$

$$i_l(t) = I_o e^{-\frac{t}{\tau}} \quad \tau = \frac{L}{R}$$

## DC Step Response

For a step applied at  $t = t_o$ , and condition at time  $t = t_0^+$

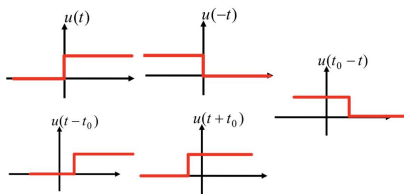
$$x(t) = [x(t_0^+) - x(\infty)]e^{-\frac{t-t_0}{\tau}} + x(\infty)$$

## Second Order Circuits

Construct RCL series by using KVL, and RCL parallel by using KCL at top node.

## Unit Step Function

$$u(t) = \begin{cases} 0 & t \leq 0 \\ 1 & t > 0 \end{cases}$$



## Operation Amplifiers

Voltage output is limited by saturation

$$-V_{cc} \leq V_{out} \leq +V_{cc}$$

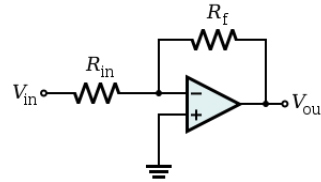
— end is the inverting input, and + end is the non-inverting input

An ideal opAmp has  $\infty$  input impedance and 0 output impedance, and infinite gain

Given negative feedback, we can say

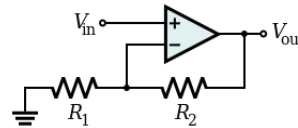
$$V_- = V_+ \quad I_- = I_+ = 0$$

## Inverting Amplifier



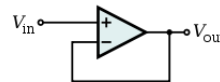
$$V_{out} = -\frac{R_f}{R_{in}} V_{in}$$

## Non-Inverting Amplifier



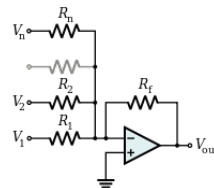
$$V_{out} = \left(1 + \frac{R_2}{R_1}\right) V_{in}$$

## Buffer



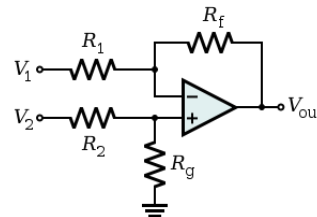
$$V_{out} = V_{in}$$

## Summer



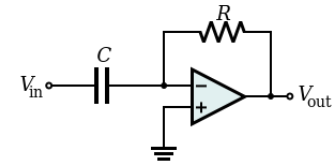
$$V_{out} = -R_f \sum_i^n \frac{V_i}{R_i}$$

## Difference Amplifier



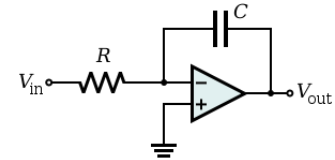
$$V_{out} = \frac{(R_f + R_1)R_g}{(R_g + R_2)R_1} V_2 - \frac{R_f}{R_1} V_1$$

## Differentiator



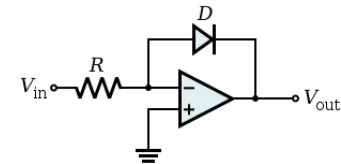
$$V_{out} = -RC \frac{dV_{in}}{dt}$$

## Integrator



$$V_{out} = -\frac{1}{RC} \int v_i dt + V_{out}^{\text{initial}}$$

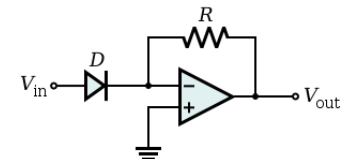
## Logarithm



When  $V_D > 0$ , current through the diode is  $I_D \approx I_S e^{\frac{V_D}{V_T}}$

$$V_{out} = V_T \ln \left( \frac{V_{in}}{I_S R} \right) \quad V_T: \text{Thermal Voltage}; I_S: \text{Saturation Current}$$

## Exponentiation

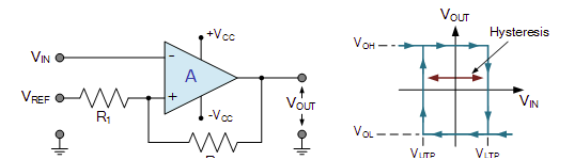


$$V_{out} = -RI_S e^{\frac{V_{in}}{V_T}} \quad V_T: \text{Thermal Voltage}; I_S: \text{Saturation Current}$$

## Comparator

$$V_{out} = \begin{cases} -V_{cc} & V_- > V_+ \\ V_{cc} & V_+ > V_- \end{cases}$$

A comparator with positive feedback



## Identities

$$\begin{aligned}
 e^{j\theta} &= \cos(\theta) + j\sin(\theta) \\
 \cos(-\alpha) &= \cos(\alpha) \\
 \sin(-\alpha) &= -\sin(\alpha) \\
 \cos(\omega t) &= \sin(\omega t + \pi/2) \\
 \sin(\omega t) &= \cos(\omega t - \pi/2) \\
 \cos(\omega t) &= -\cos(\omega t \pm \pi) \\
 \sin(\omega t) &= -\sin(\omega t \pm \pi) \\
 \cos(\alpha \pm \beta) &= \cos(\alpha)\cos(\beta) \mp \sin(\alpha)\sin(\beta) \\
 \sin(\alpha \pm \beta) &= \sin(\alpha)\cos(\beta) \pm \cos(\alpha)\sin(\beta) \\
 \cos(\alpha)\cos(\beta) &= \cos(\alpha + \beta)/2 + \cos(\alpha - \beta)/2 \\
 \sin(\alpha)\cos(\beta) &= \sin(\alpha + \beta)/2 + \sin(\alpha - \beta)/2
 \end{aligned}$$

## Combination of $\cos(\omega t)$ and $\sin(\omega t)$

$$A \sin(\omega t) + B \cos(\omega t) = \sqrt{A^2 + B^2} \cos[\omega t - \tan(B/A)]$$

## Phasors

$$X_M \cos(\omega t + \theta) = \text{Re}[X_M e^{j(\omega t + \theta)}] = X_M \angle \theta$$

$$|\mathbf{V}| = |V_M \angle \theta| = V_M$$

Multiplication by  $j$  shifts phasors by 90 degrees

$$jV \angle \theta = V \angle \theta + 90 = V \angle \theta + \frac{\pi}{2}$$

$$Z = X + jY = A \cos(\theta) + jB \sin(\theta) = A \angle \theta$$

## Sinusoidal Steady State Analysis

$$\omega = 2\pi f \quad [\text{Rad/s}] \quad f = \frac{1}{T} \quad [\text{Hz}] \quad T = \frac{2\pi}{\omega} \quad x(t) = x(t + T)$$

Leading means approaching maximum first.

$$X_{rms} = \sqrt{\frac{1}{T} \int_{t_0}^{t_0+T} x(t)^2 dt} = \frac{X_M}{\sqrt{2}}$$

The same average power is consumed for a  $4V_{rms}$  and a  $4V_{DC}$

## Impedances

$$\mathbf{Z} = R + jX \quad \text{Impedance} = \text{Resistance} + j(\text{Reactance})$$

$$\text{Resistance: In Phase} \quad R$$

$$\text{Capacitor: } I \text{ Lead } V \quad \frac{-j}{\omega C}$$

$$\text{Inductor: } V \text{ Leads } I \quad j\omega L$$

## Admittance: $\frac{1}{Z}$

A positive reactance is **inductive**, whereas a negative inductance is **capacitive**

## AC Power

Power Factor:  $pf = \cos(\theta_v - \theta_i)$

Reactive Factor:  $rf = \sin(\theta_v - \theta_i)$

A lagging pf means that the load is **inductive**. A leading power factor means that the load is **capacitive**

$$P = \frac{V_M I_M}{2} pf = V_{rms} I_{rms} pf \quad \text{Real/Active/Average [W]}$$

$$P = R I_{rms}^2 \quad R: \text{Real Part of Impedance}$$

$$Q = \frac{V_M I_M}{2} rf = V_{rms} I_{rms} rf \quad \text{Reactive [VAR]}$$

$$Q = X I_{rms}^2 \quad X: \text{Complex Part of Impedance}$$

$$\tan(\theta_v - \theta_i) = \frac{Q}{P}$$

$$\text{Instantaneous Power} \quad p = P + P \cos(2\omega t) - Q \sin(2\omega t)$$

## Complex Power

$$\mathbf{S} = P + jQ = \mathbf{V}_{rms} \mathbf{I}_{rms}^* = \frac{1}{2} \mathbf{V} \mathbf{I}^* \quad [\text{VA}]$$

## AC Maximum Average Power Transfer (No Restriction)

Assuming  $\mathbf{V}_{th}$  is not given in rms values, Select  $\mathbf{Z}_L$  such that

$$\mathbf{Z}_L = R_{th} + jX_{th} = \mathbf{Z}_{th}^* \quad P_{max} = \frac{|\mathbf{V}_{th}|^2}{8R_{th}} = \frac{|\mathbf{V}_{th}^{rms}|^2}{4R_{th}}$$

## AC Maximum Average Power Transfer (Restricted)

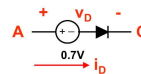
1. Choose  $X_L$  as close as possible to  $-X_{th}$
2. Adjust  $R_L$  as close as possible to

$$\sqrt{R_{th}^2 + (X_L + X_{th})^2}$$

## Diodes

A diode is conducting if it is "closed" or "on".

A diode is not conducting when it is "open" or off



The pn junction of the diode results in a depletion region, which requires a barrier voltage to overcome ( $\approx 0.7V$ ).

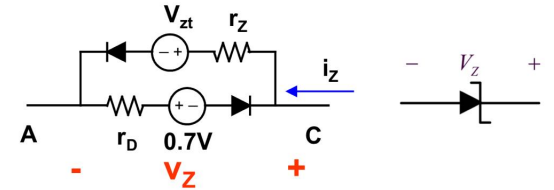
$$V_D - 0.7 \geq 0 \quad \text{Operation Condition}$$

$$\text{Diode current is a function of voltage} \quad i_D = I_0 \left( e^{\frac{V_D}{nV_T}} - 1 \right)$$

$$V_T = \frac{kT}{qe} = \frac{1.38 \times 10^{-23} T_{\text{Kelvin}}}{1.60 \times 10^{-19}}$$

$$T_K = T_{\text{Celsius}} + 273.15$$

For quality factor 1, and  $v_D \gg V_T$  we have  $i_D = I_0 e^{\frac{V_D}{V_T}}$  **Zener Diode**



Zener diodes act like a perfect negative voltage source for a range of negative current values.

## $\mathcal{L}$ ap lace Transform

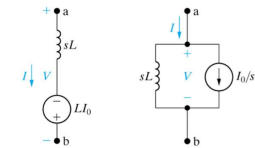
$$\mathcal{L}[f(t)] = \int_0^\infty f(t) e^{-st} dt = \mathbf{F}(s)$$

$$f(0) = \lim_{s \rightarrow \infty} sF(s) = \lim_{t \rightarrow 0^+} f(t) \quad \text{Initial Value Theorem}$$

$$f(\infty) = \lim_{s \rightarrow 0} sF(s) = \lim_{t \rightarrow \infty} f(t) \quad \text{Final Value Theorem}$$

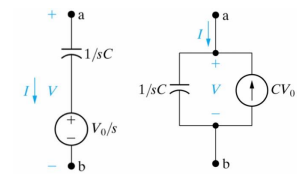
$$\begin{aligned}
 \frac{F(s)}{s+a} & \quad f(t) \\
 \frac{A}{s+a} & \quad Ae^{-at}u(t) \\
 \frac{A}{(s+a)^2} & \quad Ate^{-at}u(t) \\
 \frac{\mathbf{V}}{s+a-jB} + \frac{\mathbf{V}^*}{s+a+jB} & \quad 2|\mathbf{V}|e^{-at} \cos(Bt + \theta)u(t) \\
 \frac{\mathbf{V}}{(s+a-jB)^2} + \frac{\mathbf{V}^*}{(s+a+jB)^2} & \quad 2t|\mathbf{V}|e^{-at} \cos(Bt + \theta)u(t)
 \end{aligned}$$

## S Domain Equivalents



$$V_L = L \frac{di}{dt} \quad i = \frac{1}{L} \int_0^t V_L dt + I_0 \quad \text{Time Domain}$$

$$V_L = sLI - LI_0 \quad I = \frac{V}{sL} + \frac{I_0}{s} \quad \text{S Domain}$$



$$V_c = \frac{1}{C} \int_0^t i dt + V_0 \quad i = C \frac{dV_c}{dt} \quad \text{Time Domain}$$

$$V_L = \frac{1}{sC} + \frac{V_0}{s} \quad I = sCV - CV_0 \quad \text{S Domain}$$

## Impedance in the S Domain

Assuming zero initial conditions

Resistor	$R$
Capacitor	$\frac{1}{sC}$
Inductor	$sL$

## Transfer Functions

Is the ratio of a  $\omega$  dependent phasor output versus a phasor input.

$$\mathbf{H}(\omega) = \frac{\mathbf{V}_{out}(\omega)}{\mathbf{V}_{in}(\omega)} = \frac{\mathbf{I}_{out}(\omega)}{\mathbf{I}_{in}(\omega)} \quad \text{Voltage/Current Gain}$$

$$\mathbf{H}(\omega) = \frac{\mathbf{V}_{out}(\omega)}{\mathbf{I}_{in}(\omega)} = \frac{\mathbf{I}_{out}(\omega)}{\mathbf{V}_{in}(\omega)} \quad \text{Transfer Impedance/Admittance}$$

We plot the magnitude of  $\mathbf{H}$  versus frequency.

We may let  $j\omega = s$  to ease analysis

## Bode Plots

$$H_{db} = 20 \log_{10}(\mathbf{H})$$

1. Place transfer function into standard form, involving constant parts as 1
2. Rewrite into phasor
3. Use reference table to plot the frequency (dB vs frequency) and phase (degrees vs frequency) plots. Add the sections graphically

Magnitude	$20 \log H$ [dB]
0.001	-60
0.01	-40
0.1	-20
0.5	-6
$\frac{1}{\sqrt{2}}$	-3
1	0
$\sqrt{2}$	3
2	6
10	20
20	26
100	40
1000	60

## Frequency Selective Circuits

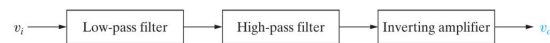
**Passive:** only involves  $R$ ,  $L$ , or  $C$

**Active:** uses opamps and transistors. We can combine high pass and low pass filters via opAmps to obtain a band pass or band reject filter.

For a first order low/high pass filter

$$\omega_c \text{ is found by setting } |\mathbf{H}(\omega)| = \frac{1}{\sqrt{2}}$$

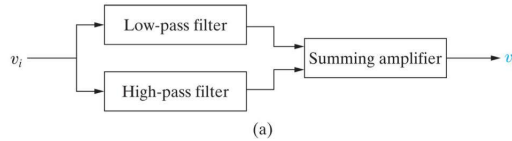
## Band Pass



Given that  $\omega_{CutOff}$  for the low pass filter is greater than the  $\omega_{CutOff}$  for the high pass filter

$$\lim_{t \rightarrow 0} \mathbf{H} = 0 \quad \lim_{t \rightarrow \infty} \mathbf{H} = 0$$

## Band Reject



Frequencies lying between cut off frequency of the low pass and the cut off frequency for the high pass is rejected, given that  $\omega_{low} < \omega_{high}$

$$\lim_{t \rightarrow 0} \mathbf{H} = C \quad \lim_{t \rightarrow \infty} \mathbf{H} = C \quad C > 0$$

## BJT Transistors

BJT Modes of Operation

	Emitter-Base	Collector-Base
Cutoff	Reverse	Reverse
Active	Forward	Reverse
Saturation	Forward	Forward

## BJT Active Region

**Collector Current** ( $i_C$  is independent of  $V_{CE}$ )

$$i_C = I_s e^{\frac{V_{BE}}{V_T}} \quad I_s \text{ Saturation Current}$$

$$i_C = \frac{\beta}{\beta + 1} i_E = \alpha i_E \quad \alpha \text{ Common Base Current Gain}$$

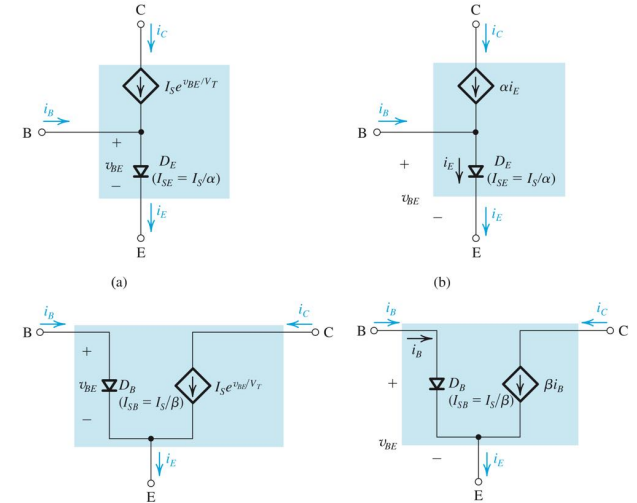
**Base Current** (Is a fraction of  $i_C$ )

$$i_B = \frac{i_C}{\beta} = \frac{i_s}{\beta} e^{\frac{V_{BE}}{V_T}} \quad \beta \text{ Common Emitter Current Gain}$$

**Emitter Current**

$$i_E = i_C + i_B = \frac{\beta + 1}{\beta} i_C$$

Large Signal Models



For a pnp BJT, the diode in the model above is reversed, and so is the current source.

For large  $\beta$ , the base current can be assumed as zero.

## Biasing

MOS

Common Source: In-Gate Out-Drain

Common Gate: In-Source Out-Drain

Common Drain: In-Gate Out-Source

BJT

Common Emitter: In-Base Out-Collector

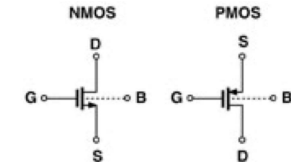
Common Base: In-Emitter Out-Collector

Common Collector: In-Base Out-Emitter

## MOS Transistors

A MOS transistor has Gate, Source and Drain.

Infinite input impedance at gate, so  $I_G \approx 0$  at steady state



Current flow determines the source and drain terminals

NMOS:  $I$  flows from Drain  $\rightarrow$  Source

PMOS:  $I$  flows from Source  $\rightarrow$  Drain

## NMOS Current Equations

$$\Delta V = V_{GS} - V_{TH}$$

$$I_D = I_{DS} =$$

Cut Off

$$0 \quad V_{GS} < V_{TH}$$

Deep Triode

$$\mu_n C_{ox} \frac{W}{L} (\Delta V) V_{DS} \quad V_{GS} > V_{TH}, V_{DS} \ll 2(\Delta V)$$

Triode

$$\mu_n C_{ox} \frac{W}{L} \left[ (\Delta V) V_{DS} - \frac{V_{DS}^2}{2} \right] \quad V_{GS} > V_{TH}, V_{DS} < \Delta V$$

Saturation

$$\frac{\mu_n C_{ox}}{2} \frac{W}{L} (\Delta V)^2 \quad V_{GS} > V_{TH}, V_{DS} > \Delta V$$

## PMOS Current Equations

$$\Delta V = V_{SG} - |V_{TH}|$$

$$I_D = I_{SD} =$$

Cut Off

$$0 \quad V_{SG} < |V_{TH}|$$

Deep Triode

$$\mu_p C_{ox} \frac{W}{L} (\Delta V) V_{SD} \quad V_{SG} > |V_{TH}|, V_{SD} \ll 2(\Delta V)$$

Triode

$$\mu_p C_{ox} \frac{W}{L} \left[ (\Delta V) V_{SD} - \frac{V_{SD}^2}{2} \right] \quad V_{SG} > |V_{TH}|, V_{SD} < \Delta V$$

Saturation

$$\frac{\mu_p C_{ox}}{2} \frac{W}{L} (\Delta V)^2 \quad V_{SG} > |V_{TH}|, V_{SD} > \Delta V$$

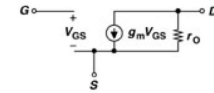
## Transconductance

As  $I_D$  in saturation is function of overdrive or effective voltage ( $V_{GS} - V_{TH}$ ), we define transconductance,  $g_m$  as how well the device converts voltage into current.

$$g_m = \frac{\partial I_D}{\partial V_{GS}}$$

$g_m$  is max in saturation, and drops in the triode region

## Small Signal Model



$$i_D = g_m V_{GS} + \frac{V_{DS}}{R}$$