

Acyclicity and Vorob'ev's theorem

deriving monogamy of non-locality and local macroscopic averages

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THE UNIVERSITY *of* EDINBURGH
informatics

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Contextuality

Overview

- ▶ Quantum mechanics predicts phenomena that run counter to our (classical) intuitions.
- ▶ This talk will focus on **non-locality**, and more generally, **contextuality**.
- ▶ Contextuality is a feature of **empirical data** that is a key signature of non-classicality.
- ▶ As such, we can study it in a **theory-independent** framework.

Non-local games

Alice and Bob cooperate in solving a task set by Verifier.

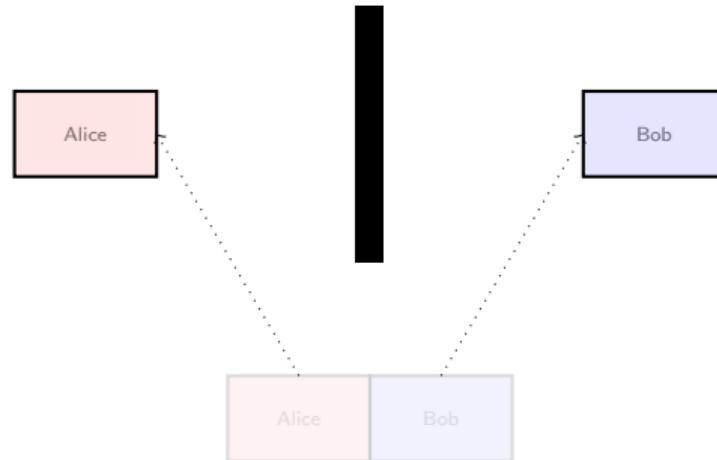
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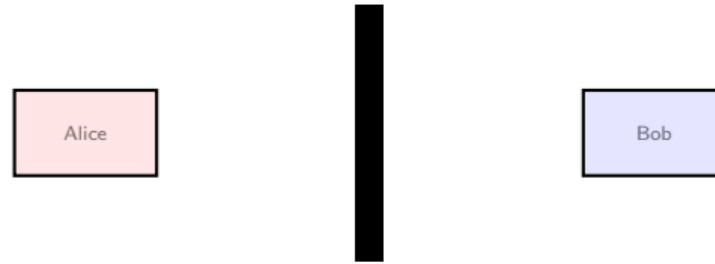
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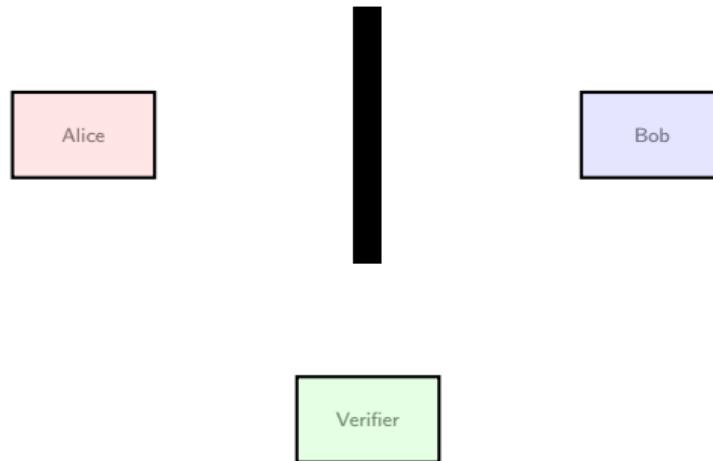
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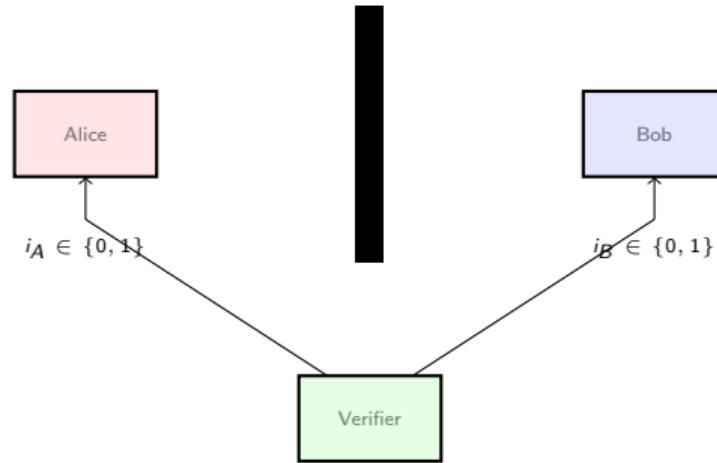
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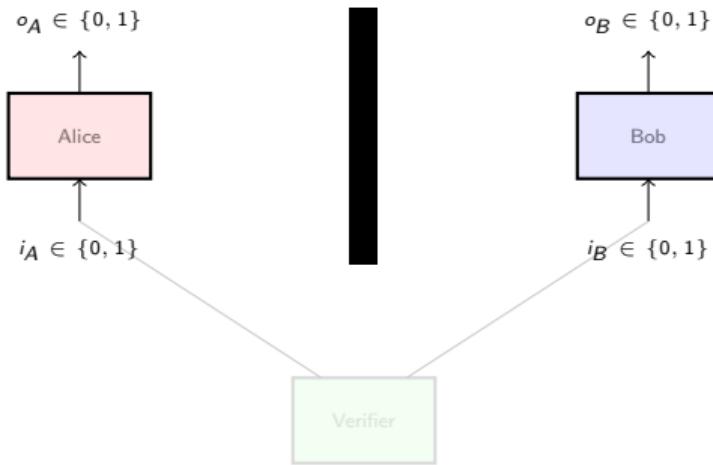
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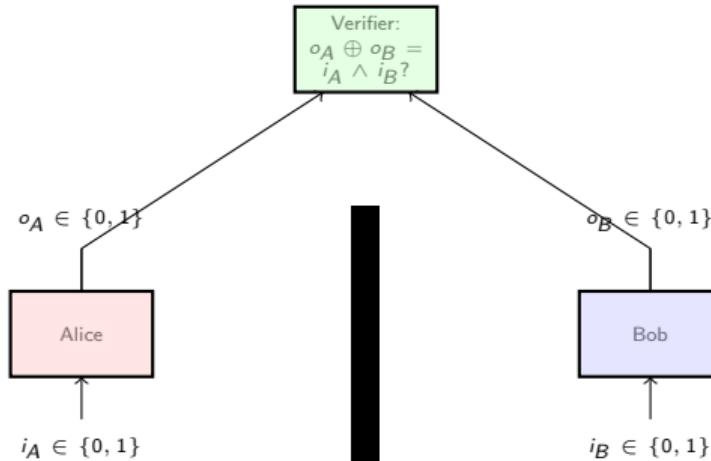
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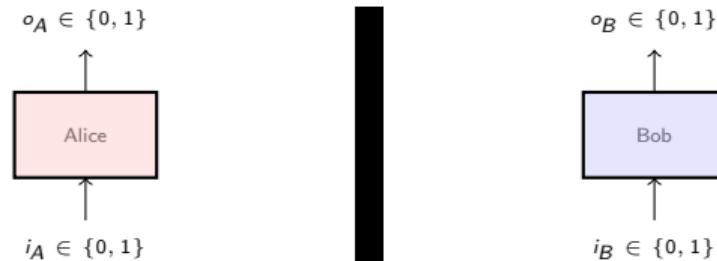
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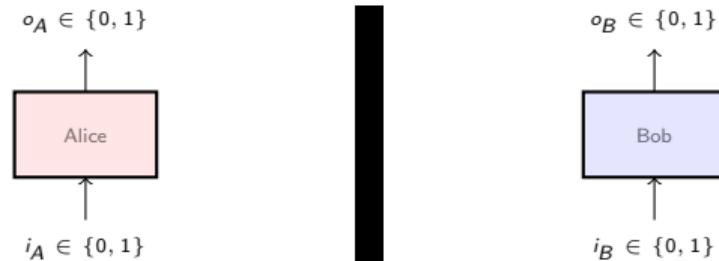
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They win a play if $o_A \oplus o_B = i_A \wedge i_B$.

A strategy is described by the probabilities $P(o_A, o_B | i_A, i_B)$.

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This gives a winning probability of $3.25/4 \approx 0.81$!

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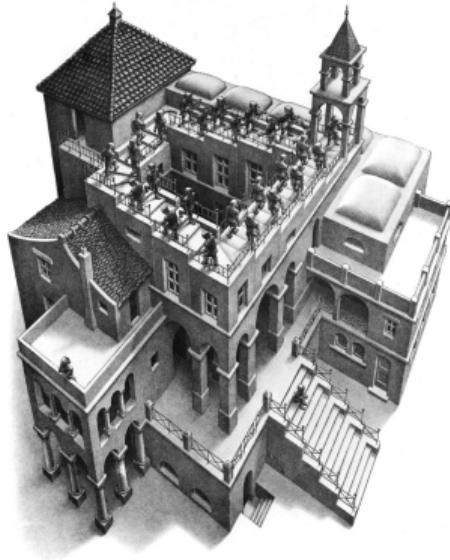
- ▶ But the Bell table can be realised in the real world.
- ▶ So, what is the unwarranted assumption?
- ▶ That all variables could *in principle* be observed simultaneously.

The essence of contextuality

- ▶ Not all properties may be observed at once.
- ▶ Jointly observable properties provide **partial snapshots**.

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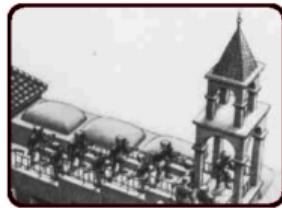
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M. C. Escher, *Ascending and Descending*

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Local consistency

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Local consistency *but* **Global inconsistency**

A recurring theme

- ▶ Non-locality and contextuality
- ▶ Relational databases
- ▶ Constraint satisfaction
- ▶ ...

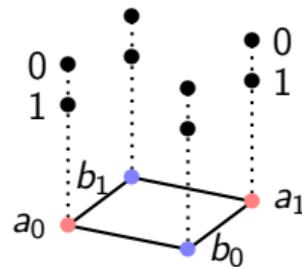
Formalising empirical data

A **measurement scenario** $\mathbf{X} = \langle X, \Sigma, O \rangle$:

- ▶ X – a finite set of measurements
- ▶ $O = (O_x)_{x \in X}$ – for each $x \in X$ a non-empty set of possible outcomes O_x
- ▶ Σ – an abstract simplicial complex on X faces are called the **measurement contexts**

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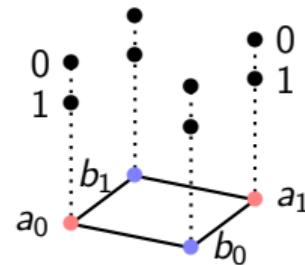
family of finite subsets of X such that:

- ▶ it contains all the singletons:
 $\forall x \in X. \ \{x\} \in \Sigma.$
- ▶ it is downwards closed: $\sigma \in \Sigma$ and $\tau \subseteq \sigma$ implies $\tau \in \Sigma$.

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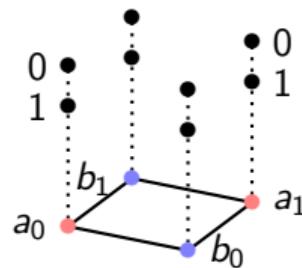
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- ▶ each $e_\sigma \in \text{Prob}(\prod_{x \in \sigma} O_x)$ is a probability distribution over joint outcomes for σ .
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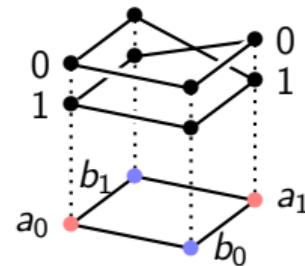
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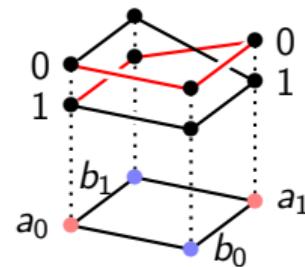
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The import of Bell's and Kochen–Spekker's theorems is that there are behaviours arising from quantum mechanics that are contextual.

Vorob'ev's theorem

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Vorob'ev (1962)

'Consistent families of measures and their extensions'

- ▶ In the context of game theory.
- ▶ Consider a collection of variables
- ▶ and distributions on the joint values of some variables.
- ▶ These distributions are pairwise consistent.

Vorob'ev's theorem

Vorob'ev (1962)

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What conditions on the arrangement guarantee that there is a global probability distribution for any prescribed pairwise consistent distributions?

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In our language:

For which measurement scenarios is it the case that any no-signalling (no-disturbing) behaviour is non-contextual?

Vorob'ev's theorem

Vorob'ev (1962)

'Consistent families of measures and their extensions'

- ▶ In the context of game theory.
- ▶ Consider a collection of variables
- ▶ and distributions on the joint values of some variables.
- ▶ These distributions are pairwise consistent.

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For which measurement scenarios is it the case that any no-signalling (no-disturbing) behaviour is non-contextual?

- ▶ Necessary and sufficient condition: **regularity!**

Relational databases

Codd (1970): Relational model of data

- ▶ Information is organised into tables (relations).
- ▶ Columns of each table are labelled by attributes
- ▶ Entries: a row with a value for each attribute of a table

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- ▶ Information is organised into tables (relations).
- ▶ Columns of each table are labelled by attributes
- ▶ Entries: a row with a value for each attribute of a table
- ▶ A database consists of a set of such tables, each with different attributes
- ▶ Database schema: blueprint of a database specifying attributes of each table and type of information: $\mathcal{S} = \{A_1, \dots, A_n\}$
- ▶ Database instance: snapshot of the contents of a database at a certain time, consisting of a relation instance (i.e. a set of entries) for each table: $\{R_A\}_{A \in \mathcal{S}}$.

Relational databases

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- ▶ It is **totally consistent** if it has a universal relation instance: T on attributes $\bigcup \mathcal{S}$ with
 $\forall A \in \mathcal{S}. \quad T|_A = R_A$

Dictionary

Databases	Empirical models
attributes	measurements
domain of attribute	outcome value of measurement
relation schema	set of compatible measurements
database schema	measurement scenario
tuple / entry	joint outcome

Dictionary

relation instance	distribution on joint outcomes
database instance	empirical model
projection	marginalisation
projection consistency	no-signalling condition
universal instance	global distribution
total consistency	locality / non-contextuality

An analogous question

For which database schemata does pairwise projection consistency imply total consistency?

- ▶ Necessary and sufficient condition: **acyclicity**.
- ▶ Acyclic database schemes extensively studied in late 70s / early 80s
- ▶ Many equivalent characterisations ...

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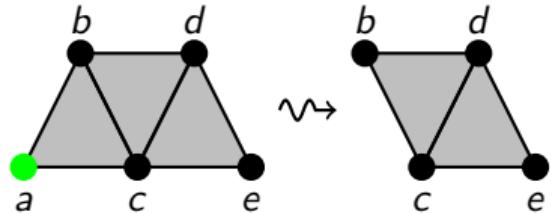
- ▶ Necessary and sufficient condition: **acyclicity**.
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- ▶ Many equivalent characterisations ...
- ▶ **Turns out to be equivalent to Vorob'ev's condition!**

Acyclicity

- ▶ Graham reduction step: delete a vertex that belongs to only one maximal face.

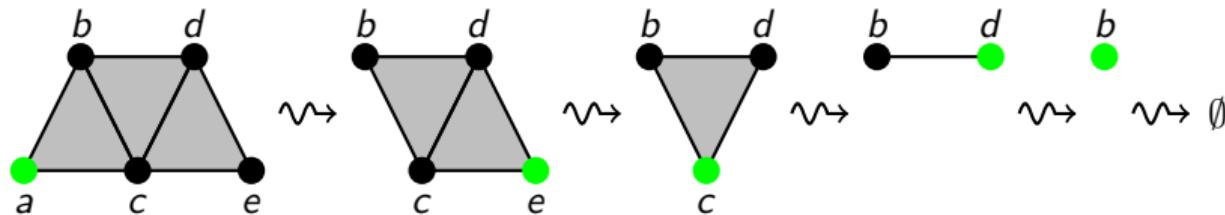
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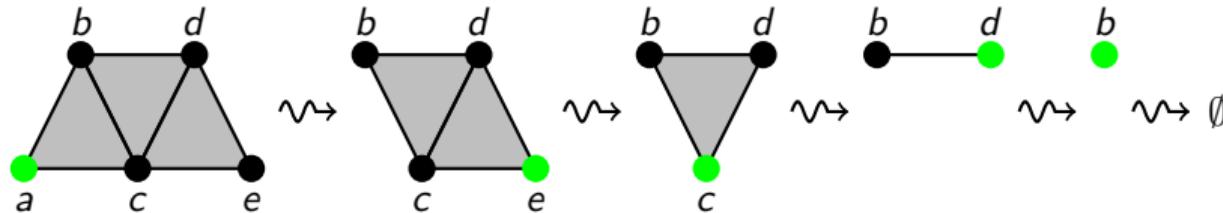
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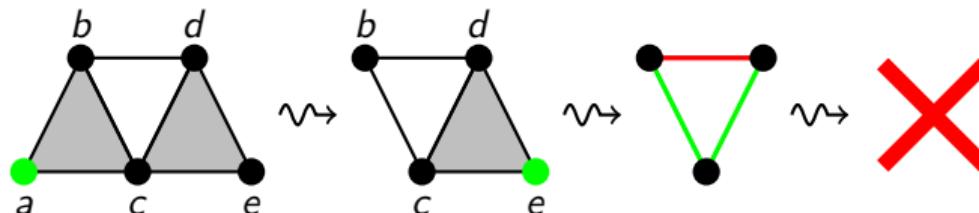


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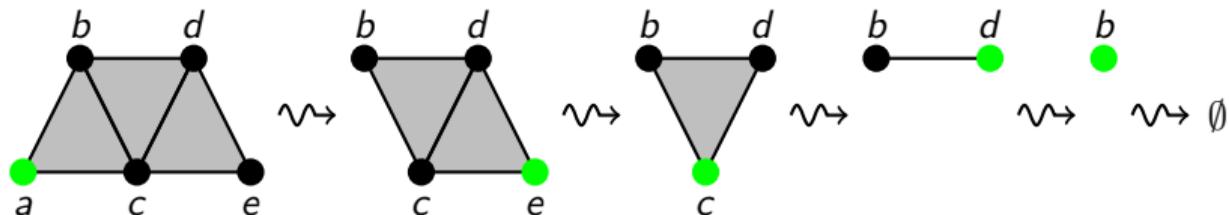
Vorob'ev's theorem

Theorem (Vorob'ev 1962, adapted)

All empirical models on Σ are extendable iff Σ is acyclic

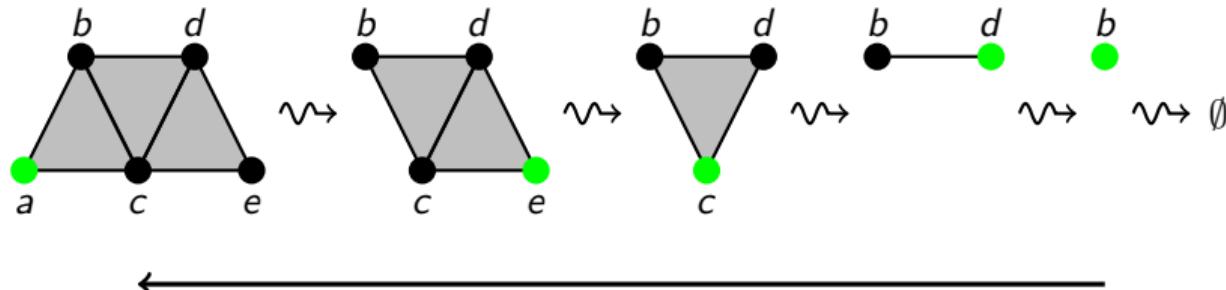
Sketch of proof of Vorob'ev's theorem

- If Σ is acyclic,



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then construct a global distribution by glueing

Given distributions P_{ab} over $\{a, b\}$ and P_{bc} over $\{b, c\}$ compatible on b ,

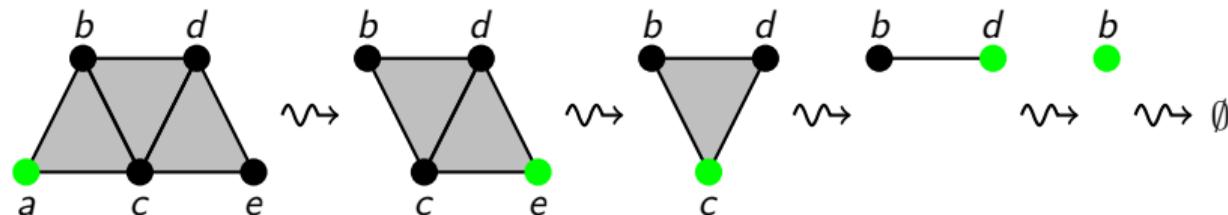
$$\sum_{x \in O} P(a, b = x, y) = \sum_{z \in O} P(b, c = y, z) ,$$

we can define an extension:

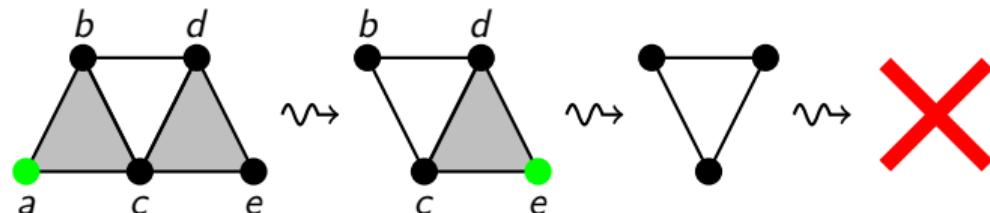
$$P(a, b, c = x, y, z) = \frac{P(a, b = x, y)P(b, c = y, z)}{P(b = y)} .$$

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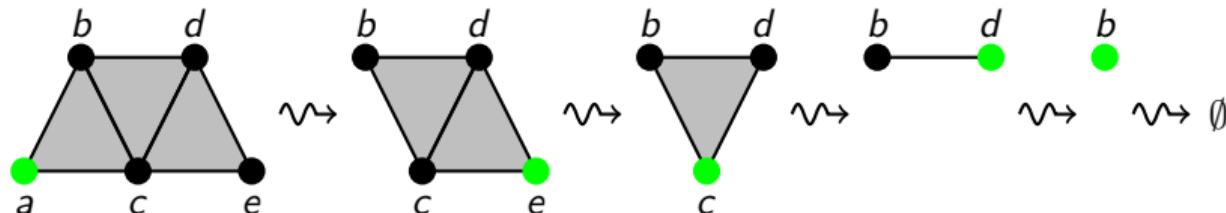


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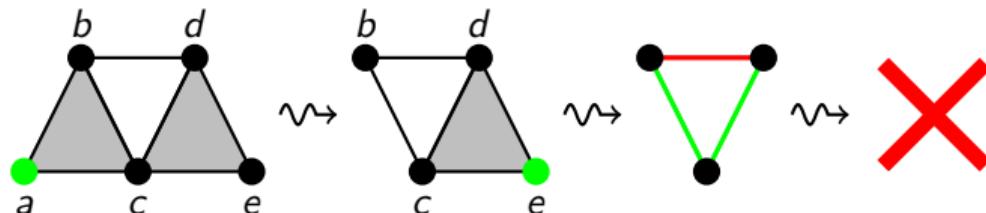


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There is a “cycle”!

Examples of glueing

- Relational databases:

- R_1 on attributes A_1 , R_2 on attributes A_2
- Define the natural join $R_1 \bowtie R_2$ on $A_1 \cup A_2$:

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- Both of these are examples of distributions
- $\langle \mathbb{R}_{\geq 0}, +, \cdot, 0, 1 \rangle$: probability
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- Flori–Fritz: metric spaces

- Logic: Robinson Joint Consistency Theorem

- Let T_i be a theory over the language L_i , with $i \in \{1, 2\}$. If there is no sentence ϕ in $L_1 \cap L_2$ with $T_1 \vdash \phi$ and $T_2 \vdash \neg \phi$, then $T_1 \cup T_2$ is consistent.

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Σ is acyclic if and only if for all $\sigma \in \Sigma$ $\text{lk}_\Sigma(\sigma)$ is contractible to a disjoint union of points.

An application:
monogamy of non-locality and average
macroscopic locality

Monogamy and average macroscopic locality

- ▶ Average macro correlations from micro models are local
(Ramanathan, Paterek, Kay, Kurzyński & Kaszlikowski 2011:
multipartite quantum models)
- ▶ Monogamy of violation of Bell inequalities
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- ▶ connect and generalise the results above
- ▶ a structural explanation related to Vorob'ev's theorem
- ▶ Let us look at a simple illustrative example.

Macroscopic measurements

- ▶ (Micro) dichotomic measurement: a single particle is subject to an interaction a and collides with one of two detectors: outcomes 0 and 1.
- ▶ The interaction is probabilistic: $p(a = x)$, $x = 0, 1$.

Macroscopic measurements

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- ▶ The interaction is probabilistic: $p(a = x)$, $x = 0, 1$.
- ▶ Consider beam (or region) of N particles, differently prepared.
- ▶ Subject each particle to the interaction a : the beam gets divided into 2 smaller beams hitting each of the detectors.
- ▶ Outcome represented by the intensity of resulting beams:
 $I_a \in [0, 1]$ proportion of particles hitting the detector 1.
- ▶ We are concerned with the mean, or expected, value of such intensities.

Macroscopic average behaviour

- ▶ This mean intensity can be interpreted as the average behaviour among the particles in the beam or region:

if we would randomly select one of the N particles and subject it to the microscopic measurement a , we would get outcome 1 with probability I_a :

$$I_a = \sum_{i=1}^N p_i(a = 1) .$$

- ▶ The situation is analogous to statistical mechanics, where a macrostate arises as an averaging over an extremely large number of microstates, and hence several different microstates can correspond to the same macrostate.

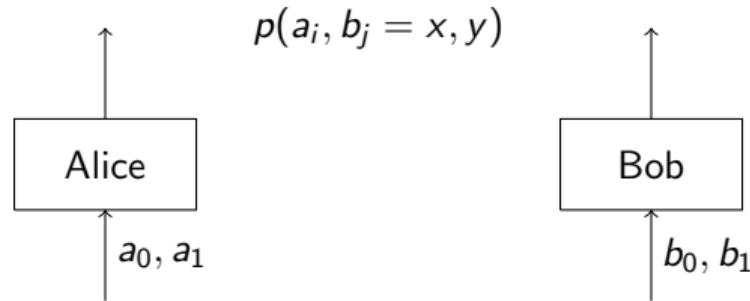
Macroscopic average behaviour: multipartite

- ▶ Multipartite macroscopic measurements:
 - ▶ several 'macroscopic' sites consisting of a large number of microscopic sites/particles;
 - ▶ several (macro) measurement settings at each site.
- ▶ Average macroscopic Bell experiment: the (mean) values of the macroscopic intensities indicate the behaviour of a randomly chosen tuple of particles: one from each of the beams, or sites.

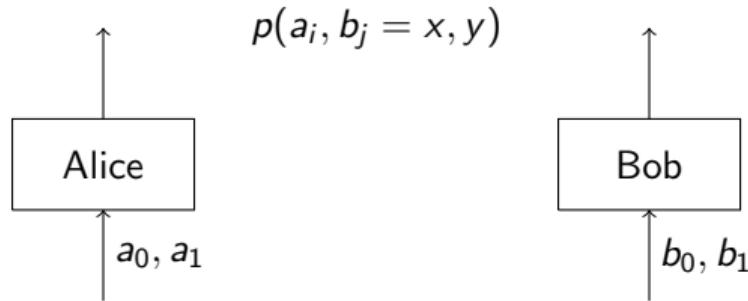
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- ▶ We shall show that, as long as there are enough particles (microscopic sites) in each macroscopic site, such average macroscopic behaviour is always local no matter which no-signalling model accounts for the underlying microscopic correlations.

Non-locality

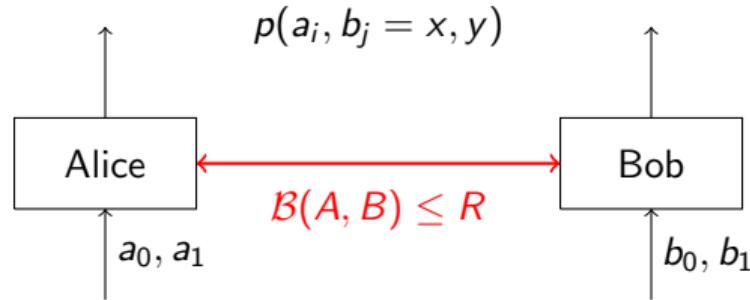


Non-locality



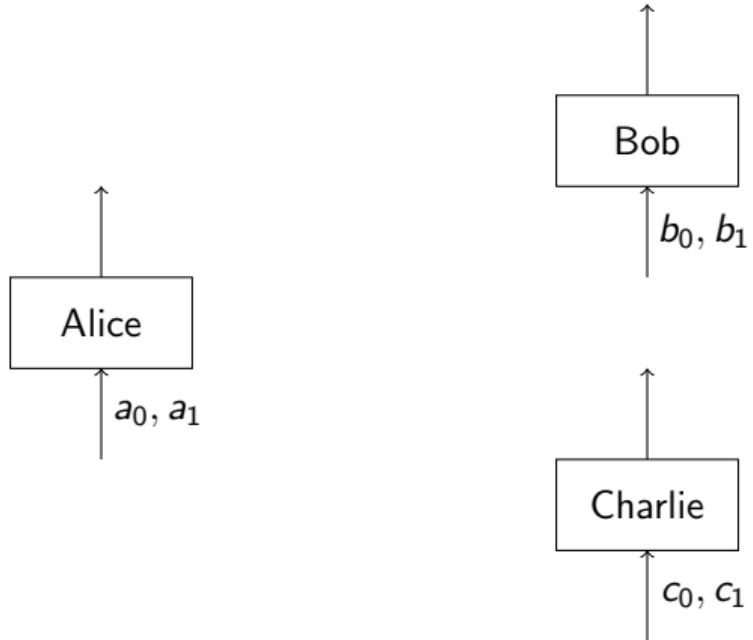
	00	01	10	11
$a_0 b_0$	1/2	0	0	1/2
$a_0 b_1$	3/8	1/8	1/8	3/8
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- ▶ Consider the subsystem composed of A and B only, given by marginalisation (in QM, partial trace):

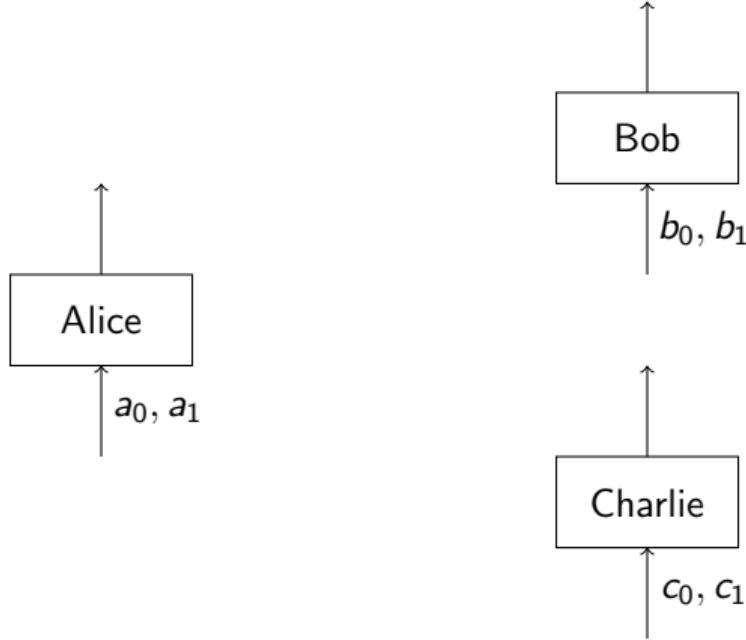
$$p(a_i, b_j = x, y) = \sum_z p(a_i, b_j, c_k = x, y, z)$$

(this is independent of c_k due to no-signalling).

Similarly define $p(a_i, c_k = x, z)$. (A and C)

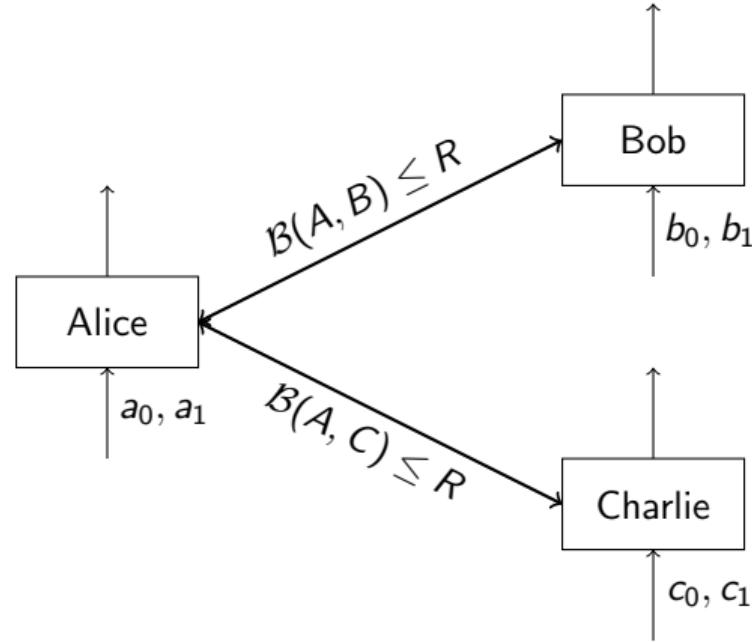
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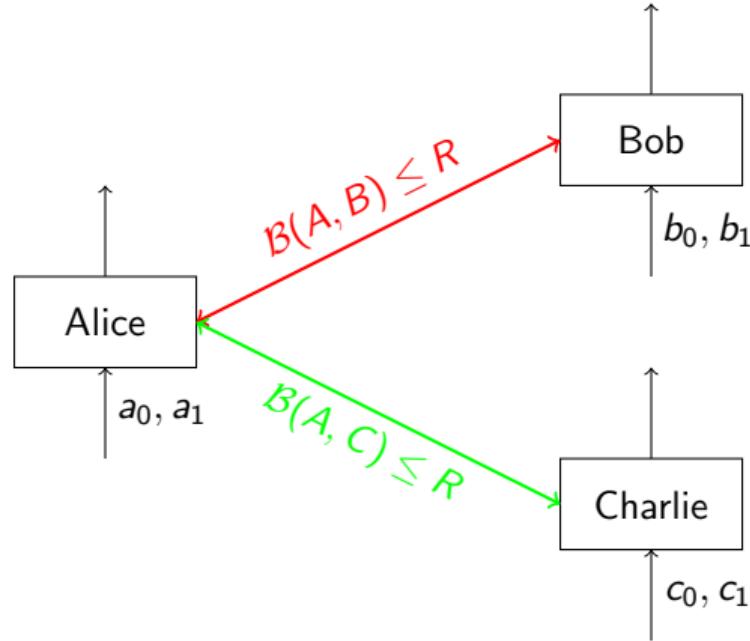
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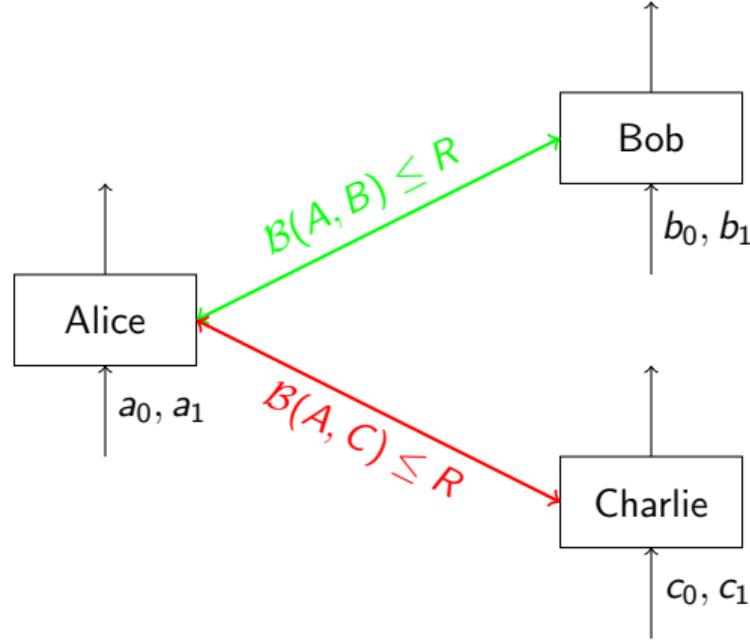
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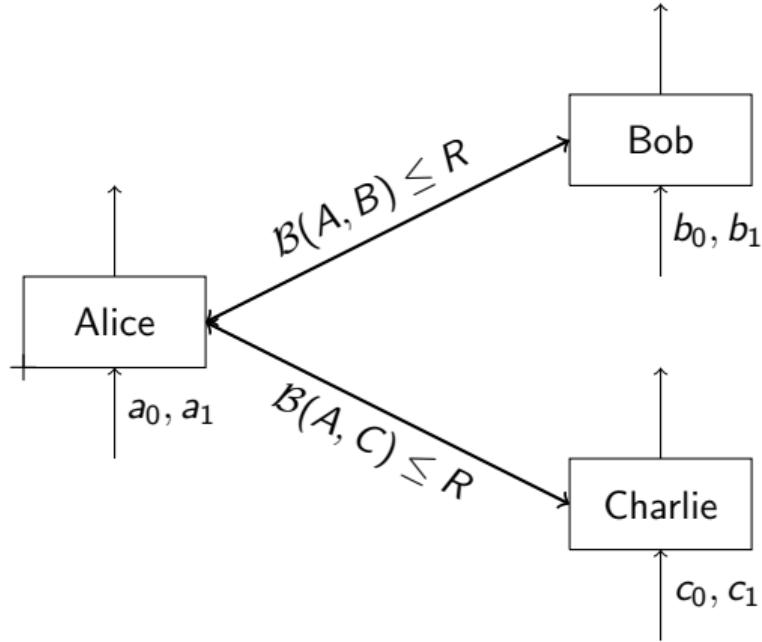
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$$\text{Monogamy relation: } \mathcal{B}(A, B) + \mathcal{B}(A, C) \leq 2R$$

Macroscopic average behaviour: tripartite example

- ▶ We regard sites B and C as forming one ‘macroscopic’ site, M , and site A as forming another.
- ▶ In order to be ‘lumped together’, B and C must be symmetric/of the same type: the symmetry identifies the measurements $b_0 \sim c_0$ and $b_1 \sim c_1$, giving rise to ‘macroscopic’ measurements m_0 and m_1 .

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$$p(a_i, m_j \mapsto x, y) = \frac{p(a_i, b_j \mapsto x, y) + p(a_i, c_j \mapsto x, y)}{2}$$

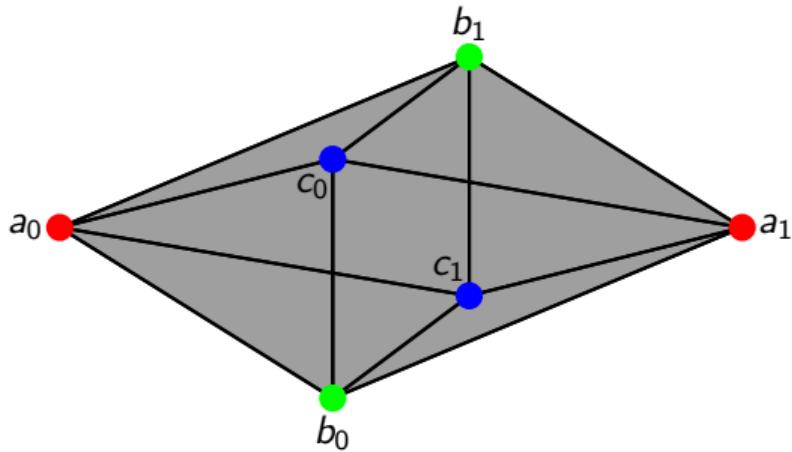
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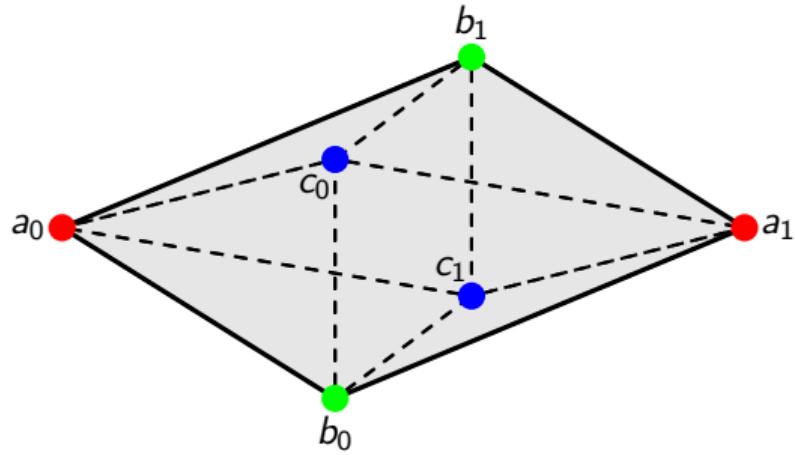
The average model p_{a_i, m_j} **satisfies a bipartite Bell inequality** if and only if in the microscopic model Alice is **monogamous** with respect to violating it with Bob and Charlie.

Structural Reason



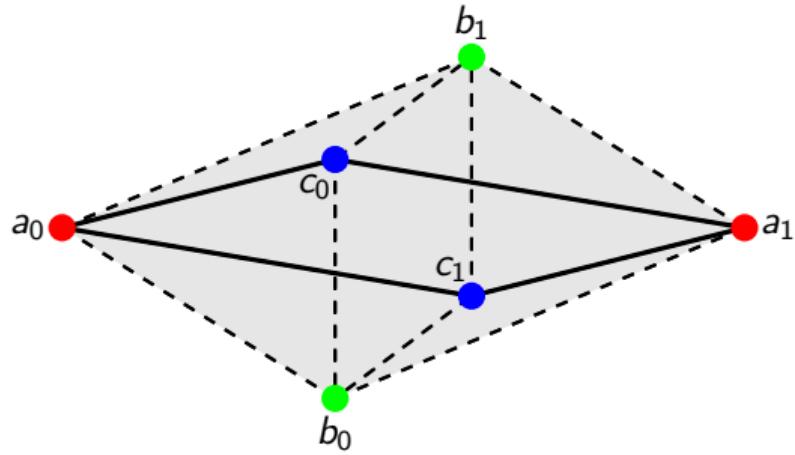
- ▶ Measurement scenario: simplicial complex $\mathfrak{D}_2 * \mathfrak{D}_2 * \mathfrak{D}_2$.

Structural Reason



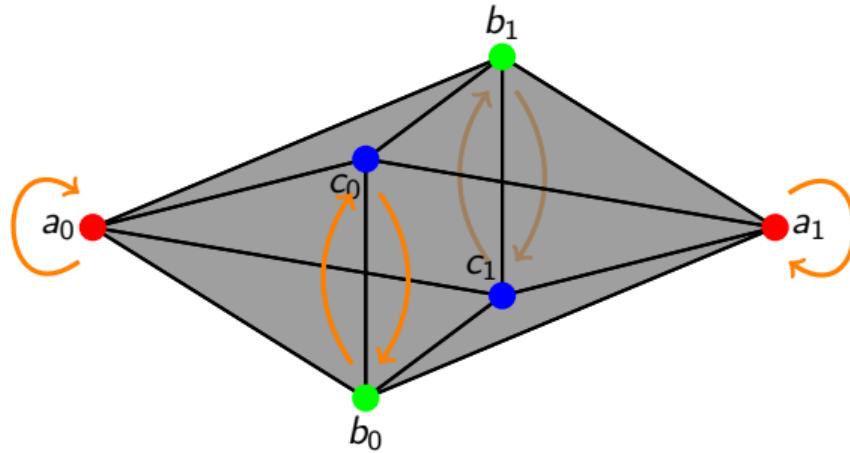
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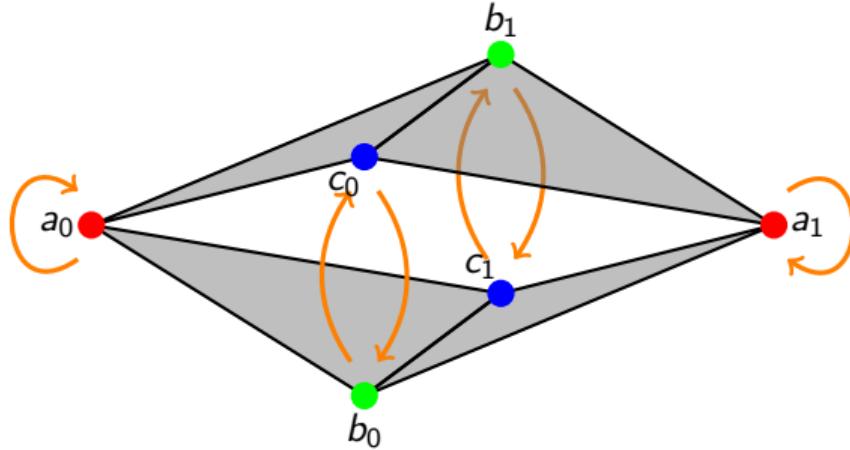
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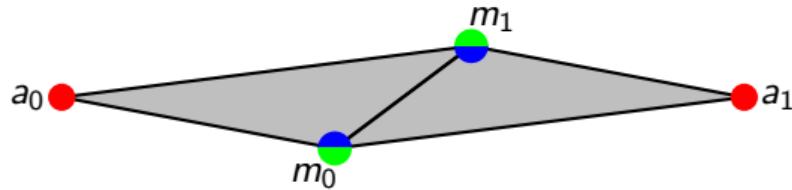
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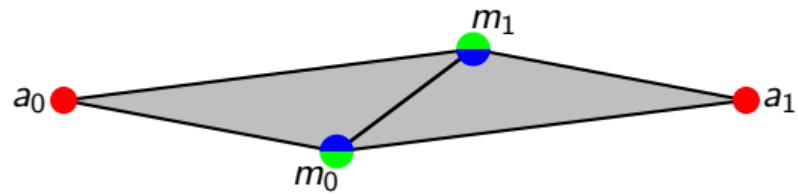
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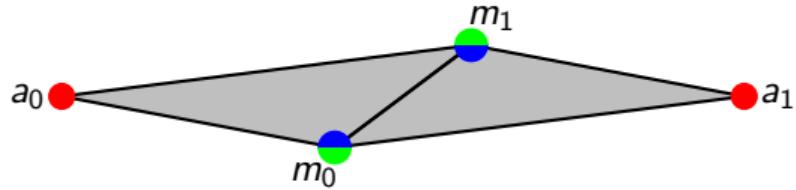


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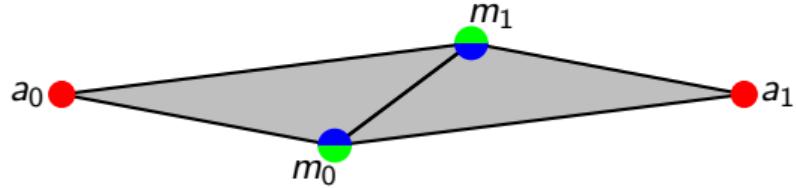


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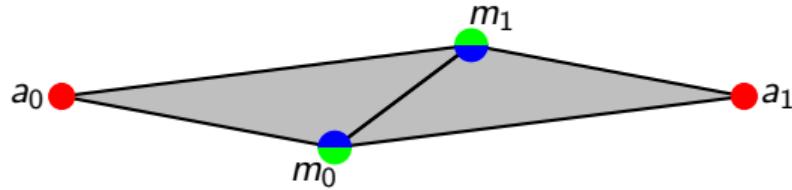
- ▶ This quotient complex is **acyclic**.

Structural Reason



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- ▶ Therefore, no matter from which micro model p_{a_i, b_j, c_k} we start, the averaged macro correlations p_{a_i, m_j} are local.

Structural Reason



- ▶ This quotient complex is **acyclic**.
- ▶ Therefore, no matter from which micro model p_{a_i, b_j, c_k} we start, the averaged macro correlations p_{a_i, m_j} are local.
- ▶ In particular, they satisfy any Bell inequality.
- ▶ Hence, the original tripartite model also satisfies a monogamy relation for any Bell inequality.

Questions...

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