Directional Wavelet Bases Construction on Dyadic Quincunx Lattice

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Abstract

We construct directional wavelet systems in the interest of building efficient signal representation scheme with good direction selectivity. In particular, we focus on wavelet bases on dyadic quincunx lattice where dilated quincunx downsampling is used to construct orthonormal and biorthogonal bases and standard dyadic downsampling for low-redundancy frames. We show that the supports of both orthonormal and bi-orthogonal wavelets in our framework are discontinuous in the frequency domain. However, this irregularity constraint be avoided in frames of redundancy less than 2.

1 Introduction

In image compression and analysis, 2D tensor wavelet schemes are widely used. Despite the time-frequency localization inherited from 1D wavelet, 2D tensor wavelets suffers from poor orientation selectivity: only horizontal or vertical edges are well represented by tensor wavelets. To obtain better representation of 2D images, several directional wavelet schemes have been proposed and applied to image processing, such as directional wavelet filterbanks(DFB) and its various extensions.

Conventional DFB [1] divides the frequency domain into eight equi-angular pairs of triangles and it is critically downsampled (maximally decimated) and perfect reconstruction (PR), but without multi-resolution structure. Different approaches have been proposed to generalize DFB to multi-resolution systems, including non-uniform DFB (nuDFB), contourlet, curvelet, shearlet and dual-tree wavelet. nuDFB is introduced in [2] based on multi-resolution analysis (MRA), where at each level of decomposition the square frequency domain is divided into a high frequency outer ring and a central low frequency domain. For nuDFB, the high frequency ring is primarily divided further into six equi-angular pairs of trapezoids and the central low frequency square is kept for division in the next level of decomposition, see Fig. 1. The nuDFB is solved by optimization which provides a non-unique near orthogonal or bi-orthogonal solution depending on the initialization. Contourlets [3] combine the Laplacian pyramid scheme

with DFB which has PR but with redundancy 4/3 inherited from the Laplacian pyramid. Shearlet [4, 5] and curvelet [6] systems construct a multi-resolution partition of the frequency domain by applying shear or rotation operators to a generator function in each level of frequency decomposition. Available shearlet and curvelet implementations have redundancy at least 4; moreover, the factor may grow with the number of directions in the decomposition level. Dual-tree wavelets [7] are linear combinations of 2D tensor wavelets (corresponding to multi-resolution systems) that constitute an approximate Hilbert transform pair, where the high frequency ring is divided into pairs of squares of different directional preference.

However, none of these multi-resolution schemes is PR, critically downsampled and regularized (localized in both time and frequency). In the framework of nuDFB ([2]), it is shown by Durand [8] that it's impossible to construct orthonormal filters localized in frequency without discontinuity in their frequency support, or equivalently regularized filters without aliasing. His construction of directional filters using compositions of 2-band filters associated to quincunx lattice, similar to that of uniform DFB in [2] and as pointed out in [2] the overall composed filters are not alias-free. Despite of Durand's disproof, it is not clear whether a regularized wavelet system exists if one slightly weaken the set of conditions.

To answer this question, we consider multi-resolution directional wavelets corresponding to the same partition of frequency domain as nuDFB and build a framework to analyze the equivalent conditions of PR for critically downsampled and more generally redundant schemes. In our previous work [9], we show that in MRA, PR is equivalent to an identity condition and shift-cancellation condition closely related to the frequency support of filters and their downsampling scheme. Based on these two conditions, we derive Durand's discontinuity result of orthonormal schemes and a relaxation of orthonormal schemes to frame with redundancy less than 2 that resolves the regularity limitation. Furthermore, we have an explicit approach to construct such regularized directional wavelet frames by smoothing the Fourier transform of the irregular directional wavelets. The main contribution of this paper is that we extend our previous work and show that the same irregularity in orthonormal schemes exists in biorthogonal schemes. Different from our previous approach in the orthonormal case, our analysis of bi-orthogonal schemes is based on a numerical algorithm introduced by Cohen et al in [10] for constructing compactly supported symmetric wavelet bases on hexagonal lattice. We extend and adapt this algorithm to our bi-orthogonal setting.

The paper is organized as follows, in section 2, we set up our framework of a dyadic MRA with dilated quincunx downsampling. In section 3, we review the irregularity of orthonormal schemes in [9]. In particular, we derive two conditions, *identity summation* and *shift cancellation*, equivalent to perfect reconstruction in this MRA with critical downsampling. These lead to the classification of *regular/singular* boundaries of the frequency partition and a *relaxed shift-cancellation* condition for low-redundancy MRA frame allows better regularity of the directional wavelets. In section 4, we show the irregularity for

bi-orthogonal schemes. We first review the wavelet construction algorithm in [10] which solves linear systems generated from regularity constraints. Next, we extend the algorithm to our framework and show that the resulting linear system doesn't have feasible solution satisfying all regularity constraints, especially continuity of Fourier transforms of wavelet filters. Finally, we conclude our results and discuss future work in section 7.

2 Framework Setup

We summarize 2D-MRA systems and the relation between frequency domain partition and sub-lattice of \mathbb{Z}^2 with critical downsampling following [9].

2.1 Notation

Throughout this paper, we use lower case normal font for function, upper case bold font for matrix, lower case bold font for vector and upper case normal font for frequency domain. We denote the conjugate transpose of a matrix \boldsymbol{A} by \boldsymbol{A}^* and same for a vector. For matrices and vectors, the indexing of rows and columns starts with zero.

2.2 Multi-resolution analysis and sub-lattice sampling

In an MRA, given a scaling function $\phi \in L^2(\mathbb{R}^2)$, s.t. $\|\phi\|_2 = 1$, the base approximation space is defined as $V_0 = span\{\phi_{0,k}\}_{k\in\mathbb{Z}^2}$, where $\phi_{0,k} = \phi(x-k)$. If $\langle \phi_{0,k}, \phi_{0,k'} \rangle = \delta_{k,k'}$, then $\{\phi_{0,k}\}$ is an orthonormal basis of V_0 . In addition, ϕ is associated with a scaling matrix $\mathbf{D} \in \mathbb{Z}^{2\times 2}$, s.t. the dilated scaling function $\phi_1(x) = |\mathbf{D}|^{-1/2}\phi(\mathbf{D}^{-1}x)$ is a linear combination of $\phi_{0,k}$'s. Equivalently, $\exists m_0(\omega) = m_0(\omega_1, \omega_2)$, 2π -periodic in ω_1, ω_2 , s.t. in the frequency domain

$$\widehat{\phi}(\mathbf{D}^T \boldsymbol{\omega}) = m_0(\boldsymbol{\omega})\widehat{\phi}(\boldsymbol{\omega}). \tag{1}$$

(1) implies that

$$\hat{\phi}(\boldsymbol{\omega}) = (2\pi)^{-1} \prod_{k=1}^{\infty} m_0(\mathbf{D}^{-k}\boldsymbol{\omega}).$$
 (2)

Let $\phi_{l,\mathbf{k}} = \phi(D^{-l}\mathbf{x} - \mathbf{k})$ and $V_l = \overline{span\{\phi_{l,\mathbf{k}}; \mathbf{k} \in \mathbb{Z}^2\}}, l \in \mathbb{Z}$ be the nested approximation spaces. Define W_l as the orthogonal complement of V_l with respect to V_{l-1} in MRA. Suppose there are J wavelet functions $\psi^j \in L^2(\mathbb{R}^2)$, 1 < j < J, and $\mathbf{Q} \in \mathbb{Z}^{2 \times 2}$, s.t.

respect to
$$V_{l-1}$$
 in MRA. Suppose there are J wavelet functions $\psi^{j} \in L^{2}(\mathbb{R}^{2})$
 $1 \leq j \leq J$, and $\mathbf{Q} \in \mathbb{Z}^{2 \times 2}$, s.t.
 $W_{1} = \bigcup_{j=1}^{J} W_{1}^{j} = \bigcup_{j=1}^{J} \overline{span\{\psi_{1,\mathbf{k}}^{j}; \mathbf{k} \in \mathbf{Q}\mathbb{Z}^{2}\}} = \bigcup_{j=1}^{J} \overline{span\{\psi^{j}(\mathbf{D}^{-1}\mathbf{x} - \mathbf{k}); \mathbf{k} \in \mathbf{Q}\mathbb{Z}^{2}\}},$

an L-level multi-resolution system with base space V_0 is then spanned by

$$V_L \oplus \bigoplus_{l=1}^L \left(\bigcup_{j=1}^J W_l^j \right) = \{ \phi_{L, \mathbf{k}}, \psi_{l, \mathbf{k'}}^j, \ 1 \le l \le L, \ \mathbf{k} \in \mathbb{Z}^2, \ \mathbf{k'} \in \mathbf{Q}\mathbb{Z}^2, \ 1 \le j \le J \}.$$
 (3)

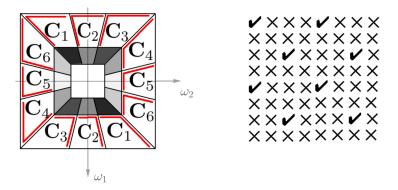


Figure 1: Left: partition of S_0 and boundary assignment of C_j , $j=1,\dots,6$ (each C_j has boundaries indicated by red line segments), Right: dilated quincunx sub-lattice.

In particular, we set $\mathbf{D} = \mathbf{D_2} \doteq \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}$ and $\mathbf{Q} := \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}$. As $W_1 \subset V_0$, each rescaled wavelet $\psi^j(\mathbf{D}^{-1}\cdot)$ is also a linear combination of $\phi_{0,\mathbf{k}}$, so that $\exists m_j$ analogous to m_0 satisfying

$$\widehat{\psi}^{j}(\mathbf{D}^{T}\boldsymbol{\omega}) = m_{j}(\boldsymbol{\omega})\widehat{\phi}(\boldsymbol{\omega}), \qquad 1 \leq j \leq J.$$
(4)

In this specific construction of MRA, the corresponding subsampling matrix of $\phi_{1,k}$ is **D** and that of $\psi_{1,k}^j$ is **QD**, the dilated quincunx subsample (see the right panel in Fig.1), as in [8].

2.3 Frequency domain partition and critical downsampling

Consider the canonical frequency square, $S_0 = [-\pi, \pi) \times [-\pi, \pi)$ associated with lattice $\mathcal{L} = \mathbb{Z}^2$. Consider a 1-level decomposition, (3) together with (1) and (4) implies that the union of the support of m_j , $0 \le j \le J$ covers S_0 . Furthermore, $\exists C_j \subset supp(m_j), 0 \le j \le J$, such that they form a partition of S_0 , and it is natural to take C_j as the main support of m_j . To build an orthonormal basis with good directional selectivity, we choose the partition of S_0 shown in the left of Fig.1, which is the same for Example B in [8] and the least redundant shearlet system. In this partition, S_0 is divided into a central square $C_0 = {2 \choose 0}^0 = {1 \choose 0}^{-1} S_0$ and a ring: the ring is further cut into six pairs of directional trapezoids C_j 's by lines passing through the origin with slopes $\pm 1, \pm 3$ and $\pm \frac{1}{3}$. The central square C_0 can be further partitioned in the same way to obtain a two-level multi-resolution system, as shown in Fig.1.

Here J=6 and $|\mathbf{D}|^{-1}+J|\mathbf{Q}\mathbf{D}|^{-1}=1/4+6/(2\cdot 4)=1$, hence the corresponding MRA generated by (3) achieves critical downsampling([8]). In addition, let $\boldsymbol{\pi}_0=(0,0),\boldsymbol{\pi}_1=(\pi/2,\pi/2),\boldsymbol{\pi}_2=(\pi,0),\boldsymbol{\pi}_3=(-\pi/2,\pi/2),\boldsymbol{\pi}_4=(0,\pi),\boldsymbol{\pi}_5=(\pi/2,-\pi/2),\boldsymbol{\pi}_6=(\pi,\pi),\boldsymbol{\pi}_7=(-\pi/2,-\pi/2)$, then each piece C_j together with its shifts form a tiling of S_0 , i.e.

$$S_0 = \bigcup_{\pi \in \Gamma_0} (C_j + \pi) = \bigcup_{\pi \in \Gamma_1} (C_0 + \pi), \quad j = 1, \dots, 6$$
 (5)

where $\Gamma_0 = \{ \boldsymbol{\pi}_i, i = 0, 2, 4, 6 \}$ and $\Gamma_1 = \{ \boldsymbol{\pi}_i, i = 0, 1, \dots, 7 \}$. Alternatively, we say that $\{ C_i, j = 0, \dots, J \}$ is an *admissible* partition of S_0 .

3 Orthonormal Bases

In this section, we discuss the conditions on m- functions such that the corresponding MRA forms an orthonormal bases.

We begin with the two key conditions, i.e. *identity summation* and *shift cancellation*, on m-functions such that the system (3) is perfect reconstruction (PR) or equivalently a Parseval frame in MRA.

3.1 orthonormal conditions on m-functions

In MRA, (3) is PR if $\forall f \in L_2(\mathbb{R}^2)$,

$$\sum_{k} \langle f, \phi_{0,k} \rangle \phi_{0,k} = \sum_{k} \langle f, \phi_{1,k} \rangle \phi_{1,k} + \sum_{j} \sum_{k} \langle f, \psi_{1,k}^{j} \rangle \psi_{1,k}^{j}. \tag{6}$$

Using (1) and (4) together with the admissibility of the frequency partition (5), condition (6) on ϕ and ψ^j 's yields:

Theorem 1. The perfect reconstruction condition holds for (3) iff the following two conditions hold

$$|m_0(\omega)|^2 + \sum_{j=1}^6 |m_j(\omega)|^2 = 1$$
 (7)

$$\begin{cases}
\sum_{j=0}^{6} m_j(\boldsymbol{\omega}) \overline{m_j(\boldsymbol{\omega} + \boldsymbol{\pi})} = 0, & \boldsymbol{\pi} \in \Gamma_0 \setminus \{\boldsymbol{0}\} \\
\sum_{j=1}^{6} m_j(\boldsymbol{\omega}) \overline{m_j(\boldsymbol{\omega} + \boldsymbol{\pi})} = 0, & \boldsymbol{\pi} \in \Gamma_1 \setminus \Gamma_0
\end{cases}$$
(8)

Theorem 1 is a corollary of Prop. 1 and Prop. 2 in [8]. We give an alternate proof in Appendix A. In Theorem 1, Eq. (7) is the *identity summation* condition, guaranteeing conservation of l_2 energy; Eq. (8) is the *shift cancellation* condition such that aliasing is canceled correctly in reconstruction from wavelet coefficients.

For (3) to be an orthonormal basis, $\{\phi_{\mathbf{k}}\}_{\mathbf{k}\in\mathbb{Z}^2}$ need to be an orthonormal basis, which is determined by m_0 in (2). In 1D MRA, Cohen's theorem in [11] provides a necessary and sufficient condition on m_0 such that (3) is an orthonormal basis. We generalized this theorem to 2D in [9].

Theorem 2. Assume that m_0 is a trigonometric polynomial with $m_0(0) = 1$, and define $\hat{\phi}(\boldsymbol{\omega})$ as in (2).

If $\phi(\cdot - \mathbf{k}), \mathbf{k} \in \mathbb{Z}^2$ are orthonormal, then $\exists K$ containing a neighborhood of 0, s.t. $\forall \boldsymbol{\omega} \in S_0, \, \boldsymbol{\omega} + 2\pi \mathbf{n} \in K$ for some $\mathbf{n} \in \mathbb{Z}^2$, and $\inf_{k>0, \, \boldsymbol{\omega} \in K} |m_0(\mathbf{D_2}^{-k}\boldsymbol{\omega})| > 0$. Further, if $\sum_{\boldsymbol{\pi} \in \Gamma_0} |m_0(\boldsymbol{\omega} + \boldsymbol{\pi})|^2 = 1$, then the inverse is true.

3.2 *m*-function Design and Boundary Regularity

We begin with the Shannon-type wavelet construction. Let each m_j be an indicator function, $m_j = \mathbb{1}_{C_j}$, $0 \le j \le 6$, and we use the boundary assignment



Figure 2: Boundary classification, singular (red) and regular (yellow)

of C_j in Fig.1, then the identity summation follows from the partition, and the shift cancellation follows from (5). Applying Theorem 2 to m_0 , we check that the Shannon-type wavelets generated from these m-functions form an orthonormal basis.

Such m_j 's are not regularized due to the discontinuity on ∂C_j 's, the boundaries of C_j 's, hence the corresponding wavelets are not spatially localized. m_j 's can be regularized by direct smoothing on ∂C_j 's. However, as shown in Proposition 3 in [8], it is not possible to smooth all the boundaries with discontinuity if m_j 's have to satisfy the perfect reconstruction condition. In [9], ∂C_j 's are segmented into singular and regular pieces. On regular boundaries, pairs of $(m_j, m_{j'})$ that share the boundary can be smoothed in a coherent way such that all the constraints in Theorem 2 are satisfied. Yet, on those singular pieces, it is shown that m_j cannot be smoothed without violating the shift cancellation condition. Fig. 2 shows the boundary classification, where the corners of S_0 and C_0 are singular, hence m_0 and the diagonal m— functions of an orthonormal bases are discontinuous there. A mechanism of constructing orthonormal bases by smoothing m_j on regular boundaries from indicator functions is provided in [9].

3.3 Extension to low-redundancy tight frame

The irregularity of orthonormal bases is overcome in the following low-redundancy tight frame construction,

$$\{\phi_{L,k}, \psi_{l,k'}^{j}, 1 \le l \le L, k, k' \in \mathbb{Z}^2, 1 \le j \le J\}.$$
 (9)

where all wavelet coefficients are sub-sampled on dyadic sub-lattice and the redundancy of any L-level MRA frame doesn't exceed $\frac{J/|D|}{1-1/|D|} = \frac{6/4}{1-1/4} = 2$. Similar to Theorem 2, we have

Theorem 3. The perfect reconstruction condition holds for (9) iff the following both hold

$$|m_0(\boldsymbol{\omega})|^2 + \sum_{j=1}^6 |m_j(\boldsymbol{\omega})|^2 = 1$$
 (10)

$$\sum_{j=0}^{6} m_j(\boldsymbol{\omega}) \overline{m_j(\boldsymbol{\omega} + \boldsymbol{\pi})} = 0, \quad \boldsymbol{\pi} \in \Gamma_0 \setminus \{\boldsymbol{0}\}$$
 (11)

Theorem 3 can be proved analogously to Theorem 1, but with fewer shift cancellation constraints. Following the same analysis of boundary regularity as previous, we show in [9] that all boundaries are regular and can be smoothed properly. We obtained directional wavelets with much better spatial and frequency localization than the one constructed by Durand in [8].

Heretofore, we have considered two directional wavelet MRA systems (3) and (9) such that the directional wavelets characterize 2D signals in six equi-angled directions. Furthermore, these wavelets are well localized in the frequency domain such that $supp(m_i)$ is convex and $\exists \epsilon s.t.$

$$\sup_{\boldsymbol{\omega}' \in supp(m_j)} \inf_{\boldsymbol{\omega} \in C_j} \|\boldsymbol{\omega'} - \boldsymbol{\omega}\| < \epsilon, \quad 0 \le j \le 6.$$
 (12)

This desirable condition is hard to obtain by multi-directional filter bank assembly of several elementary filter banks.

In the next section, we analyze the more general case of directional biorthorgonal filters constructed with respect to the same frequency partition.

4 Bi-orthogonal Bases

In this section, we analyze bi-orthogonal bases in the following form of MRA,

$$\{\phi_{L,\boldsymbol{k}}, \widetilde{\phi}_{L,\boldsymbol{k}}, \psi_{l,\boldsymbol{k}'}^{j}, \widetilde{\psi}_{l,\boldsymbol{k}'}^{j}, 1 \leq l \leq L, \, \boldsymbol{k} \in \mathbb{Z}^{2}, \, \boldsymbol{k}' \in \mathbf{Q}\mathbb{Z}^{2}, 1 \leq j \leq J\},$$
 (13)

where ϕ and ψ^j satisfy (1) and (4), as well as $\widetilde{\phi}$ and $\widetilde{\psi^j}$, respectively,

$$\widehat{\widetilde{\phi}}(\boldsymbol{D}^T\boldsymbol{\omega}) = \widetilde{m_0}(\boldsymbol{\omega})\widehat{\widetilde{\phi}}(\boldsymbol{\omega}), \quad \widehat{\widetilde{\psi}^j}(\boldsymbol{D}^T\boldsymbol{\omega}) = \widetilde{m_j}(\boldsymbol{\omega})\widehat{\widetilde{\phi}}(\boldsymbol{\omega}). \tag{14}$$

For such bi-orthogonal bases, we have the similar identity summation and shift cancellation condition to those in Theorem 1.

Theorem 4. The perfect reconstruction iff the following two conditions hold

$$m_0(\boldsymbol{\omega})\overline{\widetilde{m_0}}(\boldsymbol{\omega}) + \sum_{j=1}^6 m_j(\boldsymbol{\omega})\overline{\widetilde{m_j}}(\boldsymbol{\omega}) = 1$$
 (15)

$$\begin{cases}
\sum_{j=0}^{6} m_{j}(\boldsymbol{\omega}) \overline{\widetilde{m_{j}}}(\boldsymbol{\omega} + \boldsymbol{\pi}) = 0, & \boldsymbol{\pi} \in \Gamma_{0} \setminus \{\boldsymbol{0}\} \\
\sum_{j=1}^{6} m_{j}(\boldsymbol{\omega}) \overline{\widetilde{m_{j}}}(\boldsymbol{\omega} + \boldsymbol{\pi}) = 0, & \boldsymbol{\pi} \in \Gamma_{1} \setminus \Gamma_{0}
\end{cases}$$
(16)

The conditions (15) and (16) can be combined into a linear system as follows,

$$\begin{bmatrix} \overline{\widetilde{m}_{0}}(\boldsymbol{\omega}) & \overline{\widetilde{m}_{1}}(\boldsymbol{\omega}) & \dots & \overline{\widetilde{m}_{6}}(\boldsymbol{\omega}) \\ 0 & \overline{\widetilde{m}_{1}}(\boldsymbol{\omega} + \boldsymbol{\pi}_{1}) & \dots & \overline{\widetilde{m}_{6}}(\boldsymbol{\omega} + \boldsymbol{\pi}_{1}) \\ \overline{\widetilde{m}_{0}}(\boldsymbol{\omega} + \boldsymbol{\pi}_{2}) & \overline{\widetilde{m}_{1}}(\boldsymbol{\omega} + \boldsymbol{\pi}_{2}) & \dots & \overline{\widetilde{m}_{6}}(\boldsymbol{\omega} + \boldsymbol{\pi}_{2}) \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & \overline{\widetilde{m}_{1}}(\boldsymbol{\omega} + \boldsymbol{\pi}_{7}) & \dots & \overline{\widetilde{m}_{6}}(\boldsymbol{\omega} + \boldsymbol{\pi}_{7}) \end{bmatrix} \begin{bmatrix} m_{0}(\boldsymbol{\omega}) \\ m_{1}(\boldsymbol{\omega}) \\ m_{2}(\boldsymbol{\omega}) \\ \vdots \\ m_{6}(\boldsymbol{\omega}) \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ \vdots \\ m_{6}(\boldsymbol{\omega}) \end{bmatrix}$$
(17)

In addition, we have the following analogue of Theorem 2.

Theorem 5. Assume that $m_0, \widetilde{m_0}$ are trigonometric polynomials with $m_0(0) = \widetilde{m_0}(0) = 1$, which generate $\phi, \widetilde{\phi}$ respectively.

If $\phi(\cdot - \mathbf{k})$, $\widetilde{\phi}(\cdot - \mathbf{k})$, $\mathbf{k} \in \mathbb{Z}^2$ are bi-orthogonal, then $\exists K$ containing a neighborhood of 0, s.t. $\forall \boldsymbol{\omega} \in S_0$, $\boldsymbol{\omega} + 2\pi \mathbf{n} \in K$ for some $\mathbf{n} \in \mathbb{Z}^2$, and $\inf_{k>0, \boldsymbol{\omega} \in K} |m_0(\mathbf{D_2}^{-k}\boldsymbol{\omega})| > 0$, $\inf_{k>0, \boldsymbol{\omega} \in K} |\widetilde{m_0}(\mathbf{D_2}^{-k}\boldsymbol{\omega})| > 0$. Further, if $\sum_{\boldsymbol{\pi} \in \Gamma_0} m_0(\boldsymbol{\omega} + \boldsymbol{\pi}) \overline{\widetilde{m_0}}(\boldsymbol{\omega} + \boldsymbol{\pi}) = 1$, then the inverse is true.

By Theorem 5, m_0 and $\widetilde{m_0}$ need to satisfy the following identity constraint for the MRA (13) to be bi-orthogonal,

 $m_0\widetilde{m_0}(\omega) + m_0\widetilde{m_0}(\omega + \pi_2) + m_0\widetilde{m_0}(\omega + \pi_4) + m_0\widetilde{m_0}(\omega + \pi_6) = 1.$ (18) In sum, the construction of a bi-orthogonal basis (13) is equivalent to find feasible solutions of (17) with constraint (18)¹. To solve this, we use the same approach in [10], which constructs compactly supported symmetric bi-orthogonal filters on hexagon lattice. We next review the main scheme in [10] and adapt it to our setup of directional wavelet filter.

4.1 Summary of Cohen et al's construction

We summerize the main setup and the approach in [10]. Consider a bi-orthogonal scheme consists of 3 high-pass filters m_1, m_2 and m_3 and a low-pass filter m_0 together with their bi-orthogonal duals \widetilde{m}_j , s.t. m_0 is $\frac{2\pi}{3}$ -rotation invariant and m_1, m_2, m_3 are $\frac{2\pi}{3}$ -rotation co-variant.

This bi-orthogonal scheme satisfies the following linear system (Lemma 2.2.2 in $\lceil 10 \rceil$)

$$\begin{bmatrix} \overline{\widetilde{m_0}}(\omega) & \overline{\widetilde{m_1}}(\omega) & \overline{\widetilde{m_2}}(\omega) & \overline{\widetilde{m_3}}(\omega) \\ \overline{\widetilde{m_0}}(\omega + \nu_1) & \overline{\widetilde{m_1}}(\omega + \nu_1) & \overline{\widetilde{m_2}}(\omega + \nu_1) & \overline{\widetilde{m_3}}(\omega + \nu_1) \\ \vdots & \vdots & \vdots & \vdots \\ \overline{\widetilde{m_0}}(\omega + \nu_3) & \overline{\widetilde{m_1}}(\omega + \nu_3) & \overline{\widetilde{m_2}}(\omega + \nu_3) & \overline{\widetilde{m_3}}(\omega + \nu_3) \end{bmatrix} \begin{bmatrix} m_0(\omega) \\ m_1(\omega) \\ m_2(\omega) \\ m_3(\omega) \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$
(19)

where $\nu_i = \pi_i$, i = 1, 2, 3. Let $\widetilde{\mathbf{M}}(\boldsymbol{\omega}) \in \mathbb{C}^{4 \times 4}$ be the matrix consisting of $\widetilde{m_j(\boldsymbol{\omega})}$ and $\mathbf{m}(\boldsymbol{\omega}) \in \mathbb{C}^4$ be the vector consisting of m_j in (19), then (19) can be written

$$\widetilde{\mathbf{M}} \mathbf{m}(\boldsymbol{\omega}) = [1, 0, 0, 0]^{\top}.$$

Given $\widetilde{m}_1(\boldsymbol{\omega})$, $\widetilde{m}_2(\boldsymbol{\omega})$ and $\widetilde{m}_3(\boldsymbol{\omega})$ are determined by symmetry, and Lemma 2.2.2 in [10] shows that

$$m_{0}(\boldsymbol{\omega}) = D^{-1} \begin{vmatrix} \overline{\widetilde{m_{1}}}(\boldsymbol{\omega} + \boldsymbol{\nu}_{1}) & \overline{\widetilde{m_{2}}}(\boldsymbol{\omega} + \boldsymbol{\nu}_{1}) & \overline{\widetilde{m_{3}}}(\boldsymbol{\omega} + \boldsymbol{\nu}_{1}) \\ \overline{\widetilde{m_{1}}}(\boldsymbol{\omega} + \boldsymbol{\nu}_{2}) & \overline{\widetilde{m_{2}}}(\boldsymbol{\omega} + \boldsymbol{\nu}_{2}) & \overline{\widetilde{m_{3}}}(\boldsymbol{\omega} + \boldsymbol{\nu}_{2}) \end{vmatrix}$$
$$= D^{-1} \det(\widetilde{\mathbf{M}}_{1,1}(\boldsymbol{\omega})), \tag{20}$$

where $D \equiv \det(\widetilde{\mathbf{M}}) \in \mathbb{C}^* = \mathbb{C} \setminus \{0\}$. If $\widetilde{m_0}$ is solved, then m_1, m_2 and m_3 are

¹In fact, as long as (??) has unique solution of m_j given fixed $\widetilde{m_j}$, $j=0,\cdots,6$, (18) always holds.

obtained by solving the linear system (19). In particular, $\widetilde{m_0}(\boldsymbol{\omega})$ need to satisfy $m_0\widetilde{m_0}(\boldsymbol{\omega}) + m_0\widetilde{m_0}(\boldsymbol{\omega} + \boldsymbol{\nu}_1) + m_0\widetilde{m_0}(\boldsymbol{\omega} + \boldsymbol{\nu}_2) + m_0\widetilde{m_0}(\boldsymbol{\omega} + \boldsymbol{\nu}_3) = 1$, (21) which can be obtained by expanding $det(\widetilde{\mathbf{M}})$ with respect to the first column. According to Lemma 3.2.1 in [10], based on Hilbert's Nullstellensatz, (21) has a solution if and only if there does not exist $(z_1, z_2) \in (\mathbb{C}^*)^2$, $\mathbb{C}^* = \mathbb{C} \setminus \{0\}$ s.t. $(\pm z_1, \pm z_2)$ are all vanishing points of the z-transform of m_0 .

In general, there is no efficient algorithm to solve *Hilbert's Nullstellensatz*, and how (21) is solved exactly is not mentioned in [10]. In the next section, we propose an optimization problem that solves $\widetilde{m_0}$, where (20)(which is the same as (18)) serves as a linear constraint and the objective function imposes regularity on $\widetilde{m_0}$.

5 Adaptation to dilated quincunx scheme

Following the same approach of Cohen et al, we first design $\widetilde{m_j}(\boldsymbol{\omega})$, $j=1,\cdots,6$, then solve $m_0,\widetilde{m_0}$ and m_j in order with respect to (17) and (18).

Since (17) takes the same form as (19), for simplicity, in the rest of this paper, we reuse matrix and vector notations $\widetilde{\mathbf{M}}(\boldsymbol{\omega})$, $\mathbf{m}(\boldsymbol{\omega})$ in (19) for those in (17), where $\widetilde{\mathbf{M}}(\boldsymbol{\omega}) \in \mathbb{C}^{8\times 7}$ and $\mathbf{m}(\boldsymbol{\omega}) \in \mathbb{C}^7$. In addition, let $\boldsymbol{b}_k \in \mathbb{R}^8$, $0 \le k \le 7$, whose only non-zero entry is $\boldsymbol{b}_k[k] = 1$, where the indexing starts with zero. Note that $\widetilde{\mathbf{M}} \mathbf{m}(\boldsymbol{\omega}) = \boldsymbol{b}_0 \in \mathbb{R}^8$ is over-determined, and it has unique solution if and only if

- (5.i) $\widetilde{\mathbf{M}}(\boldsymbol{\omega})$ is full rank,
- (5.ii) $[\mathbf{M}(\boldsymbol{\omega}), \boldsymbol{b}_0]$ is singular.

The matrix $\widetilde{\mathbf{M}}(\boldsymbol{\omega})$ is structured such that each row is associated with a shift $\boldsymbol{\pi}_i, i = 0 \cdots, 7$ and each column is associated with a dual function $\widetilde{m}_j(\boldsymbol{\omega}), j = 0, \cdots, 7$. We denote a sub-matrix of $\widetilde{\mathbf{M}}$ containing all but the row associated with $\boldsymbol{\pi}_k$ (the column associated with $\widetilde{m}_k(\boldsymbol{\omega})$) as $\widetilde{\mathbf{M}}[-k,:](\widetilde{\mathbf{M}}[:,-k])$. In particular, we denote $\widetilde{\mathbf{M}}[-0,-0]$ as $\widetilde{\mathbf{M}}^{\square}$.

We have the following observations of $\mathbf{M}(\boldsymbol{\omega})$.

Lemma 5.1. If (17) is solvable, then $\widetilde{\mathbf{M}}[-0,:](\boldsymbol{\omega})$ is singular $\forall \boldsymbol{\omega}$.

Proof. If (17) is solvable, then condition (ii) holds, which implies that $\det([\mathbf{M}, \boldsymbol{b}_0]) = 0$. Expanding the determinant with respect to the last column \boldsymbol{b}_0 yields $\det(\widetilde{\mathbf{M}}[-0,:]) = 0$.

Lemma 5.2. $M(\omega)$, $M(\omega + \pi_2)$, $M(\omega + \pi_4)$ and $M(\omega + \pi_6)$ are the same up to row permutations. (17) holds $\forall \omega$ if and only if

$$\widetilde{\mathbf{M}}(oldsymbol{\omega})ig\lceil\mathbf{m}(oldsymbol{\omega}),\mathbf{m}(oldsymbol{\omega}+oldsymbol{\pi}_2),\mathbf{m}(oldsymbol{\omega}+oldsymbol{\pi}_4),\mathbf{m}(oldsymbol{\omega}+oldsymbol{\pi}_6)ig
ceil=ig\lceiloldsymbol{b}_0,oldsymbol{b}_2,oldsymbol{b}_4,oldsymbol{b}_6ig
ceil.$$

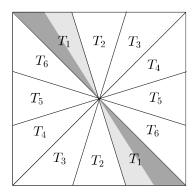


Figure 3: Partition of frequency square in six directions, where the essential support of $\widetilde{m_i}(\boldsymbol{\omega})$ is contained in each pair of triangles T_i . The pair of dark grey triangles is T_1^- and the light grey pair is T_1^+ .

Due to condition (5.i), $\forall \omega$, $\exists k_{\omega}$ such that $\widetilde{\mathbf{M}}[-k_{\omega},:]$ is non-singular. On the other hand, Lemma 5.1 and Lemma 5.2 together imply that $\widetilde{\mathbf{M}}[-k,:]$, k = 0, 2, 4, 6 are singular. Therefore, $k_{\omega} \in \{1, 3, 5, 7\}$. As in Section 4.1, we obtain the following expression of m_0 by applying Cramer's rule to $\widetilde{\mathbf{M}}[-k_{\omega},:]$,

$$m_0(\boldsymbol{\omega}) = \det(\widetilde{\mathbf{M}}^{\square}[-k_{\boldsymbol{\omega}},:]) / \det(\widetilde{\mathbf{M}}[-k_{\boldsymbol{\omega}},:]).$$
 (22)

Moreover, based on (22), the identity condition (18) on $m_0(\omega)$ and $\widetilde{m}_0(\omega)$ can be derived in the same way as (21) by expanding $\det(\widetilde{\mathbf{M}}[-k_{\omega},:])$.

In the following subsections, we first show our main result that for (17) to be solvable, the pre-designed $\widetilde{m_j}$'s are discontinuous, when the support of $\widetilde{m_j}(\boldsymbol{\omega})$ concentrates in the direction of C_j and a minimum symmetry of $\widetilde{m_j}(\boldsymbol{\omega})$'s is required. We then discuss how to design $\widetilde{m_j}$'s with more symmetry and solve the corresponding system (17).

5.1 Discontinuity of $\widetilde{m_j}(\boldsymbol{\omega})$

In this subsection, we assume that $|\widetilde{m}_1(\boldsymbol{\omega})|$ and $|\widetilde{m}_6(\boldsymbol{\omega})|$ are symmetric with respect to the diagonal $\omega_1 = \omega_2$, i.e.

$$|\widetilde{m_1}(\boldsymbol{\omega})| = |\widetilde{m_6}(\boldsymbol{\omega}')| \quad \forall \omega_1 = \omega_2', \, \omega_2 = \omega_1',$$

and likewise for $\widetilde{m_3}(\boldsymbol{\omega})$ and $\widetilde{m_4}(\boldsymbol{\omega})$,

$$|\widetilde{m}_3(\boldsymbol{\omega})| = |\widetilde{m}_4(\boldsymbol{\omega}')| \quad \forall \omega_1 = -\omega_2', \, \omega_2 = -\omega_1'.$$

Let $\widetilde{\mathbf{m}}^i(\boldsymbol{\omega}) = [\widetilde{m_1}(\boldsymbol{\omega} + \boldsymbol{\pi}_i) \cdots, \widetilde{m_6}(\boldsymbol{\omega} + \boldsymbol{\pi}_i)] \in \mathbb{C}^6$, $i = 0, \dots, 7$ be the rows of $\widetilde{\mathbf{M}}[:, -0]$. In the following, we introduce a triangular partition of frequency square and define formally the concentration of $\widetilde{m_j}$'s support.

Definition. The essential support Ω_i of a function $\widetilde{m_i}$ is the set $\{\boldsymbol{\omega} : |\widetilde{m_i}(\boldsymbol{\omega})| > |\widetilde{m_j}(\boldsymbol{\omega})|, \forall j \neq i\}$.

Let T_i be pairs of triangles shown in Figure 3, such that $C_i \subset T_i$, $i = 1, \dots, 6$.

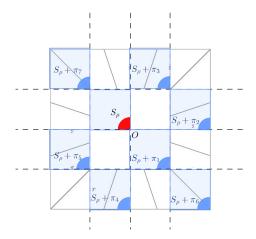


Figure 4: S_{ρ} and its shifts

Consider its decomposition, $T_i = T_i^- \bigcup T_i^+$, where T_i^-, T_i^+ are halves of T_i adjacent to T_{i-1} and T_{i+1} respectively.

Definition. $\widetilde{m_i}$ concentrates within T_i if

- (i) $\Omega_i \subset T_i$;
- (ii) $\operatorname{supp}(\widetilde{m_i}) \subset T_{i-1}^+ \bigcup T_i \bigcup T_{i+1}^-$ and $\int_{\Omega} |\widetilde{m_i}| > \int_{\Omega'} |\widetilde{m_i}|, \forall \Omega \subset T_i \cap \operatorname{supp}(\widetilde{m_i}),$ where $\Omega' \subset T_{i-1}^+ \bigcup T_{i+1}^-$ is symmetric to Ω with respect to the boundary of T_i .

Given $\widetilde{m}_i(\boldsymbol{\omega})$ that concentrates in T_i , we study the singularity condition on $\widetilde{\mathbf{M}}[-0,:(\boldsymbol{\omega})]$, specifically in the domain $S_{\rho} = \{(\omega_1,\omega_2)| \|\boldsymbol{\omega}\| < \rho, \omega_1 < 0, \omega_2 < 0\}$, see Figure 4.

Lemma 5.3. $\exists \rho > 0 \text{ s.t. } if \widetilde{\mathbf{M}}[-0,:](\boldsymbol{\omega}) \text{ is singular } \forall \boldsymbol{\omega} \in S_{\rho}, \text{ then } rank(\widetilde{\mathbf{m}}^{1}, \widetilde{\mathbf{m}}^{7}) = 1 \text{ or } rank(\widetilde{\mathbf{m}}^{3}, \widetilde{\mathbf{m}}^{5}) = 1.$

Lemma 5.3 can be proved by analyzing the linear dependency and independency between $\widetilde{\mathbf{m}}^i$ on S_{ρ} , which have known locations of zero entries when ρ is small due to concentration of $\widetilde{m_j}$. For the full proof of Lemma 5.3, see Appendix B.

Without loss of generality, in the following analysis, we assume $rank(\widetilde{\mathbf{m}}^1, \widetilde{\mathbf{m}}^7) = 1$ on S_{ρ} . Since only $\widetilde{m}_1(\boldsymbol{\omega} + \boldsymbol{\pi}_1), \widetilde{m}_6(\boldsymbol{\omega} + \boldsymbol{\pi}_1)$ could be non-zero in $\widetilde{\mathbf{m}}^1$ and $\widetilde{m}_1(\boldsymbol{\omega} + \boldsymbol{\pi}_7), \widetilde{m}_6(\boldsymbol{\omega} + \boldsymbol{\pi}_7)$ could be non-zero in $\widetilde{\mathbf{m}}^7$ on S_{ρ} , they are linearly related. Based on this, we can show that $\widetilde{m}_1(\boldsymbol{\omega}), \widetilde{m}_6(\boldsymbol{\omega})$ are zero almost everywhere on $S_{\rho} + \boldsymbol{\pi}_1$, which implies the discontinuity of $\widetilde{m}_1(\boldsymbol{\omega})$ and $\widetilde{m}_6(\boldsymbol{\omega})$ at $(\frac{\pi}{2}, \frac{\pi}{2})$ or $(-\frac{\pi}{2}, -\frac{\pi}{2})$.

Proposition 5.4. $\widetilde{m_1}(\boldsymbol{\omega}), \widetilde{m_6}(\boldsymbol{\omega})$ are not continuous at both $(\frac{\pi}{2}, \frac{\pi}{2})$ and $(-\frac{\pi}{2}, -\frac{\pi}{2})$.

Proof. If $\widetilde{m_1}(\boldsymbol{\omega})$ is continuous at $(\frac{\pi}{2}, \frac{\pi}{2})$, then $\widetilde{m_1}(\frac{\pi}{2}, \frac{\pi}{2}) = \lim_{\alpha \to 1^-} \widetilde{m_1}(\boldsymbol{\omega}(\alpha)) = 0$, where $\{\boldsymbol{\omega}(\alpha), 0 \leq \alpha < 1\} \subset S_\rho + \boldsymbol{\pi}_1 \text{ and } \boldsymbol{\omega}(1) = (\frac{\pi}{2}, \frac{\pi}{2})$. By symmetry, we have $\widetilde{m_6}(\frac{\pi}{2}, \frac{\pi}{2}) = 0$. Similarly, the continuity at $(-\frac{\pi}{2}, -\frac{\pi}{2})$ implies $\widetilde{m_1}(-\frac{\pi}{2}, -\frac{\pi}{2}) = \widetilde{m_6}(-\frac{\pi}{2}, -\frac{\pi}{2}) = 0$. Therefore $\widetilde{\mathbf{m}}^1(0) = \widetilde{\mathbf{m}}^7(0) = \mathbf{0}$ which results in contradiction with Lemma 5.3.

The following theorem summarizes our main result.

Theorem 5.5. If $\widetilde{m_i}(\omega)$ concentrates in T_i and $\widetilde{m_1}(\omega)$, $\widetilde{m_6}(\omega)$ are symmetric to each other, then (17) doesn't have feasible solution given continuous $\widetilde{m_1}(\omega)$ and $\widetilde{m_6}(\omega)$.

5.2 Design of input $\widetilde{m_j}(\boldsymbol{\omega})$

In this sub-section, we construct $\widetilde{m_j}(\boldsymbol{\omega})$, $j=1,\dots,6$, which concentrate in T_i with high symmetry. Specifically, following the orthonormal construction in [9], we consider $\widetilde{m_j}(\boldsymbol{\omega})$ in the form

$$\widetilde{m}_{j}(\boldsymbol{\omega}) = e^{-i\boldsymbol{\eta}_{j}^{\mathsf{T}}\boldsymbol{\omega}}|\widetilde{m}_{j}(\boldsymbol{\omega})|, \quad j = 1, \cdots, 6$$
 (23)

where $|\widetilde{m_j}(\boldsymbol{\omega})|$'s have symmetries with respect to the two diagonals and the two axis. Figure ?? shows such a design of $|\widetilde{m_j}(\boldsymbol{\omega})|$ in the left.

Given the symmetries of $\widetilde{m_j}(\boldsymbol{\omega})$, for $|m_0(\boldsymbol{\omega})| > 0$, $\forall |\boldsymbol{\omega}| < \rho$, $\boldsymbol{\eta}_j$ have to satisfy certain constraints.

Lemma 5.6. If $\exists \boldsymbol{\omega} \in D_1 := \{\omega_1 = \omega_2, \omega_1 \in (-\frac{\pi}{2}, 0)\}, s.t. m_0(\boldsymbol{\omega}) > 0$, then $(\boldsymbol{\eta}_1 - \boldsymbol{\eta}_6)^{\top} (\boldsymbol{\pi}_6 - \boldsymbol{\pi}_7) \neq 0 (mod 2\pi)$.

Similarly, if $\exists \boldsymbol{\omega} \in \{\omega_1 = \omega_2, \omega_1 \in (0, \frac{\pi}{2})\}$, $s.t. m_0(\boldsymbol{\omega}) > 0$, then $(\boldsymbol{\eta}_1 - \boldsymbol{\eta}_6)^{\top}(\boldsymbol{\pi}_6 - \boldsymbol{\pi}_1) \neq 0 \pmod{2\pi}$. These two conditions are equivalent to

$$(\eta_1 - \eta_6)^{\top} (\pi/2, \pi/2) \neq 0 (\text{mod } 2\pi)$$
 (c1.1)

given that η_1 and η_6 are integer phases in \mathbb{Z}^2 . Considering the other diagonal segment $\{\omega_2 = -\omega_1, |\omega_1| < \frac{\pi}{2}\}$, we have

$$(\eta_3 - \eta_4)^{\top} (-\pi/2, \pi/2) \neq 0 (\text{mod } 2\pi)$$
 (c1.2)

Next, we investigate $\widetilde{\mathbf{M}}^{\square}(\boldsymbol{\omega})$ at the origin.

Proposition 5.7. If $\widetilde{m}_0(\mathbf{0}) \neq 0$, then $\boldsymbol{\pi}_1^{\top}(\boldsymbol{\eta}_1 - \boldsymbol{\eta}_6) \neq \pi(mod 2\pi)$ or $\boldsymbol{\pi}_3^{\top}(\boldsymbol{\eta}_3 - \boldsymbol{\eta}_4) \neq \pi(mod 2\pi)$.

We propose the following set of phases that satisfy the necessary conditions in Lemma 5.6 and Proposition 5.7,

$$\eta_1 = (0,0), \ \eta_2 = (-1,1), \ \eta_3 = (0,2),
\eta_4 = (1,0), \ \eta_5 = (0,-1), \ \eta_6 = (0,1).$$
(24)

5.3 Solving (17) and (18) for $m_0, \widetilde{m_0}$ and m_i

Once $\widetilde{m_i}(\boldsymbol{\omega}), j=1,\cdots,6$ are fixed, (17) can be reformulated as follows,

$$\widetilde{\mathbf{M}}[:,-0](\boldsymbol{\omega}) \begin{bmatrix} m_1(\boldsymbol{\omega}) \\ m_2(\boldsymbol{\omega}) \\ m_3(\boldsymbol{\omega}) \\ m_4(\boldsymbol{\omega}) \\ m_5(\boldsymbol{\omega}) \\ m_6(\boldsymbol{\omega}) \end{bmatrix} = \boldsymbol{b}_0 - m_0(\boldsymbol{\omega}) \begin{bmatrix} \overline{\widetilde{m}_0}(\boldsymbol{\omega}) \\ \overline{\widetilde{m}_0}(\boldsymbol{\omega} + \boldsymbol{\pi}_2) \\ 0 \\ \overline{\widetilde{m}_0}(\boldsymbol{\omega} + \boldsymbol{\pi}_4) \\ 0 \\ \overline{\widetilde{m}_0}(\boldsymbol{\omega} + \boldsymbol{\pi}_6) \\ 0 \end{bmatrix} \doteq \boldsymbol{b}_0'(\boldsymbol{\omega}), \qquad (25)$$

where $\widetilde{\mathbf{M}}[:, -0]$ is determined by $\widetilde{m_j}(\boldsymbol{\omega})$, $j = 1, \dots, 6$ and m_j , $j = 1, \dots, 6$ can be uniquely solved if and only if

- (5.3.i) $\widetilde{\mathbf{M}}[:, -0]$ is full rank,
- (5.3.ii) $b_0'(\omega)$ is in $col(\widetilde{\mathbf{M}}[:,-0](\omega))$, the column space of $\widetilde{\mathbf{M}}[:,-0]$.

Next, we show that (5.3.ii) breaks down to constraints on two submatrices of $\widetilde{\mathbf{M}}[:, -0]$ and quadruple $(m_0(\boldsymbol{\omega}), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_2), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_4), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_6))$.

Proposition 5.8. Let $\widetilde{\mathbf{M}}[odd, -0]$, $\widetilde{\mathbf{M}}[even, -0] \in \mathbb{C}^{4 \times 6}$ be the sub-matrices of $\widetilde{\mathbf{M}}[:, -0]$ consisting of odd and even rows respectively. Suppose (5.3.i) holds, then (5.3.ii) holds if and only if $\operatorname{rank}(\widetilde{\mathbf{M}}[odd, -0]) = \operatorname{rank}(\widetilde{\mathbf{M}}[even, -0]) = 3$ and

$$[m_0(\boldsymbol{\omega}), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_2), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_4), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_6)] \widetilde{\mathbf{M}}[even, -0](\boldsymbol{\omega}) = \mathbf{0}, \quad (26)$$

$$[m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_1), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_3), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_5), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_7)]\widetilde{\mathbf{M}}[odd, -0](\boldsymbol{\omega}) = \mathbf{0}. (27)$$

Remark. Both conditions (26) and (27) hold $\forall \omega \in [-\pi, \pi) \times [-\pi, \pi)$ if and only if (26) holds $\forall \omega \in [-\pi, 0) \times [-\pi, 0)$.

According to Proposition 5.8, $\mathbf{M}[:, -0]$ (or equivalently $\widetilde{m_j}$) has to satisfy the following rank constraints for (25) to be uniquely solvable,

$$rank(\widetilde{\mathbf{M}}[:,-0]) = 6$$
, $rank(\widetilde{\mathbf{M}}[odd,-0]) = rank(\widetilde{\mathbf{M}}[even,-0]) = 3$. (28)
Furthermore, given (28) holds, the quadruple $(m_0(\boldsymbol{\omega}), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_2), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_4), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_6))$ can be solved by (26) upto a non-zero constant $c(\boldsymbol{\omega})$. The next proposition shows that this is sufficient to obtain a feasible $m_0(\boldsymbol{\omega})$.

Proposition 5.9. If $\widetilde{m_j}(\boldsymbol{\omega}), m_j(\boldsymbol{\omega}), j = 0, 1, ..., 6$ satisfy (17) and (18), $m_0^c(\boldsymbol{\omega}) \doteq m_0(\boldsymbol{\omega})c(\boldsymbol{\omega}), \widetilde{m_0}^c(\boldsymbol{\omega}) \doteq \widetilde{m_0}(\boldsymbol{\omega})\overline{c}(\boldsymbol{\omega})^{-1}$ and $m_j(\boldsymbol{\omega}), \widetilde{m_j}(\boldsymbol{\omega}), j = 1, \cdots, 6$ satisfy (17) and (18) if $c(\boldsymbol{\omega}) = c(\boldsymbol{\omega} + \boldsymbol{\pi}_2) = c(\boldsymbol{\omega} + \boldsymbol{\pi}_4) = c(\boldsymbol{\omega} + \boldsymbol{\pi}_6) \neq 0$, i.e. $c(\boldsymbol{\omega})$ is π -periodic in both ω_1 and ω_2 .

Proof. It suffices to show that $m_0^c(\boldsymbol{\omega})\overline{\widetilde{m_0}^c}(\boldsymbol{\omega} + \boldsymbol{\pi}_i) = m_0(\boldsymbol{\omega})\overline{\widetilde{m_0}}(\boldsymbol{\omega} + \boldsymbol{\pi}_i)$, i is even.

Next, we solve quadruple $(\widetilde{m_0}(\boldsymbol{\omega}), \widetilde{m_0}(\boldsymbol{\omega} + \boldsymbol{\pi}_2), \widetilde{m_0}(\boldsymbol{\omega} + \boldsymbol{\pi}_4), \widetilde{m_0}(\boldsymbol{\omega} + \boldsymbol{\pi}_6))$ from the identity condition (18) on $[-\pi, 0) \times [-\pi, 0)$. We reformulate it as a quadratic

optimization problem that minimizes the total variation of $\widetilde{m_0}(\boldsymbol{\omega})m_0(\boldsymbol{\omega})$ as follows,

$$\min_{\mathbf{x}} \| \mathbf{D}(\mathbf{m}_0 \circ \mathbf{x}) \|^2, \quad s.t. \ \mathbf{A}\mathbf{x} = \mathbf{1}, \tag{29}$$

where \boldsymbol{D} is the gradient operator, \circ is Hadamard product and \boldsymbol{A} is the linear operator from (18). In particular, on a $2N \times 2N$ regular grid $\mathcal{G} = \{\boldsymbol{\omega}_i\}_{i=1}^{4N^2}$ of $[-\pi,\pi) \times [-\pi,\pi)$, (18) can be rewrite as

$$A\overline{\widetilde{\mathbf{m}_0}} = \mathbf{1}_{4N^2},\tag{30}$$

where $\widetilde{\mathbf{m}}_0 = [\widetilde{m}_0(\boldsymbol{\omega}_i)]_{i=1}^{4N^2}$ and $\boldsymbol{A} \in \mathbb{C}^{N^2 \times 4N^2}$ is a sparse matrix with entries

$$\mathbf{A}_{i,j} = m_0(\boldsymbol{\omega}_j) \sum_{k=0}^{3} \delta(\boldsymbol{\omega}_j - \boldsymbol{\omega}_i - \boldsymbol{\pi}_{2k}), \quad \boldsymbol{\omega}_j \in [-\pi, 0) \times [-\pi, 0).$$

Supplementary numerical results on solving $\widetilde{m_0}(\omega)$ by optimization are provided in Appendix C, where we test this optimization method on known biorthogonal filters m_0 and $\widetilde{m_0}$ and compare the solution from the optimization with the ground truth.

Finally, we plug $m_0(\omega)$ and $\widetilde{m_0}(\omega)$ into $b'_0(\omega)$ on the right of (25) and solve the linear system, which has guaranteed unique solution.

To sum up, we propose the following algorithm for bi-orthogonal directional filter construction with dilated quincunx downsampling scheme:

construction of m-, \widetilde{m} -functions in bi-orthogonal basis

Input: $\widetilde{m}_i(\boldsymbol{\omega}), j = 1, ..., 6$

step 1. construct $\widetilde{\mathbf{M}}[:,-0](\boldsymbol{\omega})$ on sub-grid $[-\pi,0)\times[-\pi,0)$ and check rank constraints (28).

step 2. solve quadruple $(m_0(\boldsymbol{\omega}), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_2), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_4), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_6))$ using (26) on $[-\pi, 0) \times [-\pi, 0)$,

step 3. solve the optimization (29) for $\widetilde{m_0}(\boldsymbol{\omega})$ on grid $[-\pi,\pi)\times[-\pi,\pi)$.

step 4. solve the reduced linear system (25) for $m_i(\boldsymbol{\omega}), j = 1, \dots, 6$.

Proposition 5.9 suggests that we can design $c(\boldsymbol{\omega})$ such that $(m_0^c, \widetilde{m_0}^c)$ have desired properties, e.g. continuity, smoothness or fast decay rate. In practice, we compute $m_0(\boldsymbol{\omega})\widetilde{m_0}(\boldsymbol{\omega})$ from $m_0(\boldsymbol{\omega})$ and $\widetilde{m_0}(\underline{\boldsymbol{\omega}})$ obtained in step 2 and 3, then re-decompose the product into $m_0^c(\boldsymbol{\omega})$ and $\widetilde{m_0}^c(\boldsymbol{\omega})$.

6 Numerical Experiments

In this section, we show an example of the numerical construction of biorthogonal directional wavelets on quincunx lattice using our proposed algorithm in Matlab.

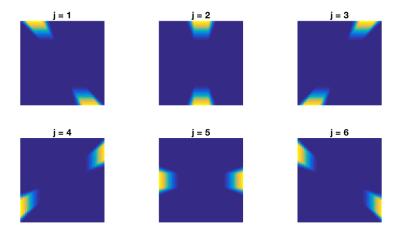


Figure 5: Input $|\widetilde{m_i}(\boldsymbol{\omega})|$ constructed in the same way as shearlets.

We design $\widetilde{m_j}$'s in the form of (23), using phases in (24) and amplitudes $|\widetilde{m_j}|$ shown in Figure 5. For the construction of $|\widetilde{m_j}|$, we start with $|\widetilde{m_2}|$, then compute $|\widetilde{m_1}|$ and $|\widetilde{m_3}|$ by shearing $|\widetilde{m_2}|$ counter-clockwise and clockwise respectively. $|\widetilde{m_4}|, |\widetilde{m_5}|$ and $|\widetilde{m_6}|$ are obtained by symmetry along the diagonal. This is the same approach used in the shearlet construction. Furthermore, $\widetilde{m_j}(\omega) = 0, \forall \omega \in C_0 = [-\frac{\pi}{2}, \frac{\pi}{2}) \times [-\frac{\pi}{2}, \frac{\pi}{2})$. In particular, by Proposition 5.4, we enforce $|\widetilde{m_1}(\frac{\pi}{2}, \frac{\pi}{2})| \neq 0$ and $\widetilde{m_6}(\frac{\pi}{2}, \frac{\pi}{2})| \neq 0$.

Using these $\widetilde{m_j}(\boldsymbol{\omega})$, $j=1,\cdots,6$ as input, the main algorithm in Section 5.3 yields $m_0,\widetilde{m_0}$ and $m_j,\,j=1,\cdots,6$. As the first step, we numerically check that this particular design of $\widetilde{m_j}$ satisfies the rank constraints (28). As shown in Figure 6 $m_0(\boldsymbol{\omega})$ obtained in step 2 is supported on the central square C_0 , where $|m_0(\boldsymbol{\omega})|=1$. Moreover, Figure 7 shows that $\widetilde{m_0}(\boldsymbol{\omega})=\overline{m_0^{-1}}(\boldsymbol{\omega})=m_0(\boldsymbol{\omega})$ on C_0 , i.e. $\widetilde{m_0}(\boldsymbol{\omega})$ solved in step 3 is numerically the same as $m_0(\boldsymbol{\omega})$. Figure 8 and Figure 9 show $|\widetilde{m_j}(\boldsymbol{\omega})|$ and $|m_j\widetilde{m_j}(\boldsymbol{\omega})|$ for $\widetilde{m_j}(\boldsymbol{\omega})$ obtained by solving (25). We also numerically check that $m_j(\boldsymbol{\omega})$ and $\widetilde{m_j}(\boldsymbol{\omega})$ have the same phase, i.e. $m_j\widetilde{m_j}(\boldsymbol{\omega}) \in \mathbb{R}$.

So far, we construct a set of $(m_j, \widetilde{m_j})_{j=0,\cdots,6}$ that satisfies (17) and (18), thus it can be used to construct biorthogonal wavelets based on (4) and (14). However, m_0 and $\widetilde{m_0}$ here are not continuous. To improve the regularity of the corresponding wavelets, by Proposition 5.9 and the observation $m_0 \overline{\widetilde{m_0}}(\omega) = \mathbf{1}_{C_0}$, we substitute $(m_0, \widetilde{m_0})$ by $(m'_0, \widetilde{m'_0})$, where $\widetilde{m'_0}$ is a smooth real function supported on C_0 and $m'_0(\omega) = \mathbf{1}_{C_0}(\widetilde{m'_0})^{-1}(\omega)$. Figure 10 shows such a pair of $(m'_0, \widetilde{m'_0})$. Finally, using pre-designed $\widetilde{m_j}(\omega)$ and post-designed $\widetilde{m'_0}$, we construct the dual wavelets $\widetilde{\psi}^j$ in (13) using (14). As shown in Figure 11, the dual wavelets are spatially localized and have good direction selection. The wavelets and scaling functions in (13) can be constructed using (14) similarly.

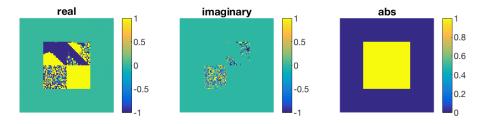


Figure 6: $m_0(\boldsymbol{\omega})$ constructed from $\widetilde{m_j}$. Left to right: $Re(m_0(\boldsymbol{\omega})), Im(m_0(\boldsymbol{\omega}))$ and $|m_0(\boldsymbol{\omega})|$.

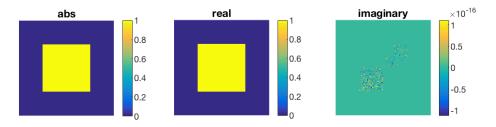


Figure 7: $|\widetilde{m_0}(\boldsymbol{\omega})|$ and $m_0\overline{\widetilde{m_0}}(\boldsymbol{\omega})$, where $\widetilde{m_0}(\boldsymbol{\omega})$ is solved by optimization (29), given $\widetilde{m_j}$ in Figure 5 and m_0 in Figure 6. Left to right: $|\widetilde{m_0}(\boldsymbol{\omega})|$, $Re(m_0\overline{\widetilde{m_0}}(\boldsymbol{\omega}))$ and $Im(m_0\overline{\widetilde{m_0}}(\boldsymbol{\omega}))$.

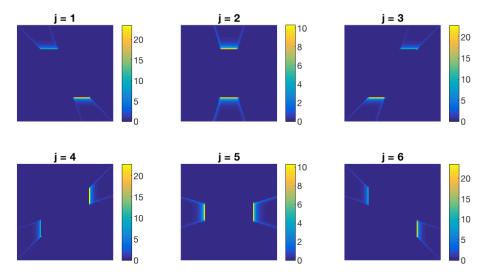


Figure 8: $|m_j(\boldsymbol{\omega})|$, where $m_j(\boldsymbol{\omega})$ is solved from (25) given $\widetilde{m_j}$ in Figure 5, m_0 in Figure 6 and $\widetilde{m_0}$ in Figure 7.

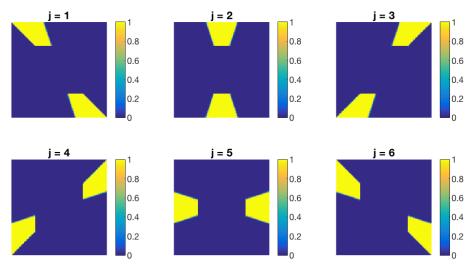


Figure 9: $|m_j(\boldsymbol{\omega})\widetilde{m_j}(\boldsymbol{\omega})|$

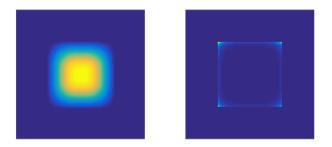


Figure 10: Left: $\widetilde{m_0}'$, designed smooth function mainly supported on the central square C_0 , right: m_0' , $s.t.m_0'\overline{\widetilde{m_0}'}(\boldsymbol{\omega}) = m_0\overline{\widetilde{m_0}}(\boldsymbol{\omega}) = \mathbf{1}_{C_0}(\boldsymbol{\omega})$.

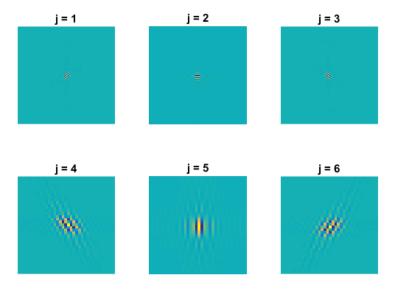


Figure 11: Real part of ψ^j constructed from $\widetilde{m_0}'$ in Figure 10 and $\widetilde{m_j}$, $j=1,\cdots,6$ in Figure 5 using (14). Top: $\widetilde{\psi^j}$ without scaling, bottom: $\widetilde{\psi^j}$ with eight time zoom-in

7 Conclusion and future work

In this paper, we consider directional wavelet schemes on dilated quincunx sublattice and analyze their regularity. We show that filters in bi-orthogonal bases have the same discontinuity in the frequency domain as that of the orthonormal bases at the corners of $S_1 = [-\pi/2, \pi/2) \times [-\pi/2, \pi/2)$, hence they cannot be not well localized in the time domain.

We construct the bi-orthogonal taking a different approach from the orthonormal case, where directional dual filters are first designed such that they can be completed to a bi-orthogonal frame and the remaining filters are obtained by solving feasible linear systems or quadratic optimization. Its extension to low-redundancy dual frame construction is not studied here and will be our future focus.

Appendices

A Proof of Theorem 1

Take the Fourier transform of both sides of (6), we have

$$\begin{split} \sum_{\boldsymbol{k}} \langle f, \phi_{\boldsymbol{k}} \rangle \hat{\phi}(\boldsymbol{\omega}) e^{-i\boldsymbol{\omega}^T \boldsymbol{k}} &= \sum_{\boldsymbol{k}} \langle f, \phi_{1, \boldsymbol{k}} \rangle e^{-i\boldsymbol{\omega}^T \boldsymbol{D_2} \boldsymbol{k}} |\boldsymbol{D_2}|^{1/2} \hat{\phi}(\boldsymbol{D_2}^T \boldsymbol{\omega}) \\ &+ \sum_{i=1}^J \sum_{\boldsymbol{k}} \langle f, \psi_{1, \boldsymbol{k}}^j \rangle e^{-i\boldsymbol{\omega}^T \boldsymbol{D} \boldsymbol{k}} |\boldsymbol{D}|^{1/2} \hat{\phi}(\boldsymbol{D}^T \boldsymbol{\omega}) \end{split}$$

Suppose m_j are trigonometric series

$$m_0(\boldsymbol{\omega}) = \sum_{\boldsymbol{k}} c_{\boldsymbol{k}} e^{-i\boldsymbol{\omega}^T \boldsymbol{k}} \quad m_j(\boldsymbol{\omega}) = \sum_{\boldsymbol{k}} g_{\boldsymbol{k}} e^{-i\boldsymbol{\omega}^T \boldsymbol{k}}, \quad j = 1, \cdots, J$$
 (31)

The first term on the right hand side can be represented by $\hat{\phi}(\omega)$ and $\langle f, \phi_k \rangle$ using (1) and (31).

the first term on R.H.S.
$$= \sum_{\boldsymbol{k}} \langle f, \phi_{1, \boldsymbol{k}} \rangle e^{-i\boldsymbol{\omega}^T \boldsymbol{D_2} \boldsymbol{k}} |\boldsymbol{D_2}|^{1/2} m_0(\boldsymbol{\omega}) \hat{\phi}(\boldsymbol{\omega})$$

$$= \sum_{\boldsymbol{k}} \Big(\sum_{\boldsymbol{k'}} \langle f, \phi_{\boldsymbol{k'}} \rangle \overline{c_{\boldsymbol{k'} - \boldsymbol{D_2} \boldsymbol{k}}} |\boldsymbol{D_2}|^{1/2} \Big) e^{-i\boldsymbol{\omega}^T \boldsymbol{D_2} \boldsymbol{k}} |\boldsymbol{D_2}|^{1/2} m_0(\boldsymbol{\omega}) \hat{\phi}(\boldsymbol{\omega})$$

$$= \sum_{\boldsymbol{k'}} \langle f, \phi_{\boldsymbol{k'}} \rangle \Big(|\boldsymbol{D_2}| \sum_{\boldsymbol{k}} \overline{c_{\boldsymbol{k'} - \boldsymbol{D_2} \boldsymbol{k}}} e^{i\boldsymbol{\omega}^T (\boldsymbol{k'} - \boldsymbol{D_2} \boldsymbol{k})} \Big) e^{-i\boldsymbol{\omega}^T \boldsymbol{k'}} m_0(\boldsymbol{\omega}) \hat{\phi}(\boldsymbol{\omega}).$$

Remark. If we have a shift \mathbf{k}_0 in the down-sample scheme, i.e. $\mathbf{D_2}\mathbb{Z}^2 - \mathbf{k}_0$ instead of $\mathbf{D_2}\mathbb{Z}^2$, so that we obtain coefficient of $\tilde{\phi}_{1,\mathbf{k}} = \phi_{1,\mathbf{k}+\mathbf{k}_0}$ instead of $\phi_{1,\mathbf{k}}$, and $\tilde{\phi}_1(\mathbf{x}) = \phi_1(\mathbf{x}-\mathbf{k}_0) = |\mathbf{D_2}|^{1/2} \sum_{\mathbf{k}} c_{\mathbf{k}} \phi(\mathbf{x}-\mathbf{k}-\mathbf{k}_0) = |\mathbf{D_2}|^{1/2} \sum_{\mathbf{k}} c_{\mathbf{k}-\mathbf{k}_0} \phi(\mathbf{x}-\mathbf{k})$. This change of down-sample scheme results in an extra phase term $e^{-i\boldsymbol{\omega}^T \mathbf{k}_0}$ in m_0 . Here, we use the down-sample scheme without translation.

Since $\bigcup_{\boldsymbol{\beta} \in B} \{ \boldsymbol{\beta} \} := \bigcup_{\boldsymbol{\beta} \in B} (\boldsymbol{D_2} \mathbb{Z}^2 + \boldsymbol{\beta}) = \mathbb{Z}^2$, where $B = \{(0,0), (1,0), (0,1), (1,1)\}$, the summation over $\boldsymbol{k}' \in \mathbb{Z}^2$ can be written as a double sum $\sum_{\boldsymbol{\beta} \in B} \sum_{\boldsymbol{k}' \in \{\boldsymbol{\beta}\}}$,

$$\sum_{\beta \in B} \sum_{\mathbf{k}' \in \{\beta\}} \langle f, \phi_{\mathbf{k}'} \rangle \sum_{\mathbf{k}} \overline{c_{\mathbf{k}' - \mathbf{D_2} \mathbf{k}}} e^{i\boldsymbol{\omega}^T (\mathbf{k}' - \mathbf{D_2} \mathbf{k})} e^{-i\boldsymbol{\omega}^T \mathbf{k}'} | \mathbf{D_2} | m_0(\boldsymbol{\omega}) \hat{\phi}(\boldsymbol{\omega})$$

$$= \sum_{\beta \in B} \sum_{\mathbf{k}' \in \{\beta\}} \langle f, \phi_{\mathbf{k}'} \rangle \sum_{\mathbf{k} \in \{\beta\}} \overline{c_{\mathbf{k}}} e^{i\boldsymbol{\omega}^T \mathbf{k}} e^{-i\boldsymbol{\omega}^T \mathbf{k}'} | \mathbf{D_2} | m_0(\boldsymbol{\omega}) \hat{\phi}(\boldsymbol{\omega})$$

The summation over k in the middle is similar to the trigonometric form of m_0 in (31), but k takes value on the shifted sub-lattice $\{\beta\}$ instead of \mathbb{Z}^2 . Therefore, the summation equals to instead a linear combination of m_0 with shifts Γ_0 ,

$$\sum_{\boldsymbol{\pi} \in \Gamma_0} m_0(\boldsymbol{\omega} + \boldsymbol{\pi}) \ e^{i\boldsymbol{\beta}^T \boldsymbol{\pi}} = \sum_{\boldsymbol{k} \in \{\boldsymbol{\beta}\}} c_{\boldsymbol{k}} e^{-i\boldsymbol{\omega}^T \boldsymbol{k}}$$
(32)

Substitute (32) into the previous expression,

$$\sum_{\boldsymbol{\beta} \in B} \sum_{\boldsymbol{k}' \in \{\boldsymbol{\beta}\}} \langle f, \phi_{\boldsymbol{k}'} \rangle \sum_{\boldsymbol{\pi} \in \Gamma_0} \overline{m_0(\boldsymbol{\omega} + \boldsymbol{\pi})} e^{-i\boldsymbol{\beta}^T \boldsymbol{\pi}} e^{-i\boldsymbol{\omega}^T \boldsymbol{k}'} m_0(\boldsymbol{\omega}) \hat{\phi}(\boldsymbol{\omega})$$

Since $e^{i\boldsymbol{\pi}^T\boldsymbol{\beta}} = e^{i\boldsymbol{\pi}^T\boldsymbol{k}'}$, $\forall \boldsymbol{k}' \in \{\boldsymbol{\beta}\}$, after rewriting the double sum over \boldsymbol{k}' back to a unit sum on \mathbb{Z}^2 , we get

$$\sum_{\mathbf{k'}} \langle f, \phi_{\mathbf{k'}} \rangle e^{-i\boldsymbol{\omega}^T \mathbf{k'}} \hat{\phi}(\boldsymbol{\omega}) \Big(\sum_{\boldsymbol{\pi} \in \Gamma_0} \overline{m_0(\boldsymbol{\omega} + \boldsymbol{\pi})} m_0(\boldsymbol{\omega}) e^{-i\boldsymbol{\pi}^T \mathbf{k'}} \Big)$$

Similarly, the second term on the R.H.S. of (6) equals to

$$\sum_{j=1}^{J} \sum_{\mathbf{k}'} \langle f, \phi_{\mathbf{k}'} \rangle e^{-i\boldsymbol{\omega}^T \mathbf{k}'} \hat{\phi}(\boldsymbol{\omega}) \Big(\sum_{\boldsymbol{\pi} \in \Gamma_1} \overline{m_j(\boldsymbol{\omega} + \boldsymbol{\pi})} m_j(\boldsymbol{\omega}) e^{-i\boldsymbol{\pi}^T \mathbf{k}'} \Big)$$

(For Theorem 3 on frame construction, the summation of shifts π is over Γ_0 instead of Γ_1 .) Combining the two terms on the R.H.S. of (6), and compare the coefficients of $\langle f, \phi_{\mathbf{k}'} \rangle e^{-i\boldsymbol{\omega}^T \mathbf{k}'} \hat{\phi}(\boldsymbol{\omega})$ on both sides, the perfect reconstruction condition is then equivalent to $\forall \mathbf{k}'$,

$$\sum_{\boldsymbol{\pi} \in \Gamma_0} e^{-i\boldsymbol{\pi}^T \boldsymbol{k}'} \overline{m_0(\boldsymbol{\omega} + \boldsymbol{\pi})} m_0(\boldsymbol{\omega}) + \sum_j \sum_{\boldsymbol{\pi} \in \Gamma_1} e^{-i\boldsymbol{\pi}^T \boldsymbol{k}'} \overline{m_j(\boldsymbol{\omega} + \boldsymbol{\pi})} m_j(\boldsymbol{\omega}) = 1.$$

This is equivalent to

$$|m_0(\boldsymbol{\omega})|^2 + \sum_j |m_j(\boldsymbol{\omega})|^2 = 1$$

and

$$\sum_{j=0}^{J} \overline{m_j(\boldsymbol{\omega} + \boldsymbol{\pi})} m_j(\boldsymbol{\omega}) = 0, \ \boldsymbol{\pi} \in \Gamma_0 \setminus \{\boldsymbol{0}\}$$

$$\sum_{j=1}^{J} \overline{m_j(\boldsymbol{\omega} + \boldsymbol{\pi})} m_j(\boldsymbol{\omega}) = 0, \ \boldsymbol{\pi} \in \Gamma_1 \setminus \Gamma_0$$

Remark. Because each m_j is $(2\pi, 2\pi)$ periodic, we only need to check the above equality $\forall \boldsymbol{\omega} \in S_0$. If we downsample ψ_1^j on a shifted sub-lattice $\boldsymbol{D}\mathbb{Z}^2 - \boldsymbol{k}_j$, we then have an extra phase $e^{i\boldsymbol{\pi}^T\boldsymbol{k}_j}$ before $\overline{m_j(\boldsymbol{\omega}+\boldsymbol{\pi})}m_j(\boldsymbol{\omega})$ in shift cancellation condition. This provides additional freedom in the construction yet it is not substantial.

B Proof of lemmas and propositions

B.1 Discontinuity of $\widetilde{m_j}(\boldsymbol{\omega})$

Lemma B.1. Define $d_{i,j}(\boldsymbol{\omega}) = \det([\widetilde{\mathbf{m}}^{k_1}(\boldsymbol{\omega})^\top, \cdots, \widetilde{\mathbf{m}}^{k_6}(\boldsymbol{\omega})^\top])$, where $0 \leq k_1 < \cdots < k_6 \leq 7$, s.t. $k_l \neq i, j$. (17) is solvable $\forall \boldsymbol{\omega}$ if and only if

$$\mathfrak{D}(\omega) \begin{bmatrix} \overline{\widetilde{m_0}}(\omega) \\ \overline{\widetilde{m_0}}(\omega + \pi_2) \\ \overline{\widetilde{m_0}}(\omega + \pi_4) \\ \overline{\widetilde{m_0}}(\omega + \pi_6) \end{bmatrix} \doteq \begin{bmatrix} 0 & d_{0,2} & d_{0,4} & d_{0,6} \\ -d_{0,2} & 0 & d_{2,4} & d_{2,6} \\ -d_{0,4} & -d_{2,4} & 0 & d_{4,6} \\ -d_{0,6} & -d_{2,6} & -d_{4,6} & 0 \end{bmatrix} \begin{bmatrix} \overline{\widetilde{m_0}}(\omega) \\ \overline{\widetilde{m_0}}(\omega + \pi_2) \\ \overline{\widetilde{m_0}}(\omega + \pi_4) \\ \overline{\widetilde{m_0}}(\omega + \pi_6) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}.$$
(33)

Proof. By Lemma 5.1 and Lemma 5.2, $\widetilde{\mathbf{M}}[-k,:]$, k = 0, 2, 4, 6 are singular, The singularity condition on $\widetilde{\mathbf{M}}[-0,:](\boldsymbol{\omega})$ can be rewritten as follows,

$$0 = \det(\widetilde{\mathbf{M}}[-0,:])$$

$$= \widetilde{m_0}(\boldsymbol{\omega} + \boldsymbol{\pi}_2) \cdot \det(\widetilde{\mathbf{M}}^{\square}[-2,:])$$

$$+ \widetilde{m_0}(\boldsymbol{\omega} + \boldsymbol{\pi}_4) \cdot \det(\widetilde{\mathbf{M}}^{\square}[-4,:]) + \widetilde{m_0}(\boldsymbol{\omega} + \boldsymbol{\pi}_6) \cdot \det(\widetilde{\mathbf{M}}^{\square}[-6,:])$$

$$= 0 \cdot \widetilde{m_0}(\boldsymbol{\omega}) + d_{0,2} \cdot \widetilde{m_0}(\boldsymbol{\omega} + \boldsymbol{\pi}_2)$$

$$+ d_{0,4} \cdot \widetilde{m_0}(\boldsymbol{\omega} + \boldsymbol{\pi}_4) + d_{0,6} \cdot \widetilde{m_0}(\boldsymbol{\omega} + \boldsymbol{\pi}_6)$$
(34)

Similarly, the second to fourth equations can be obtained by rewriting the singularity condition on $\widetilde{\mathbf{M}}[-2,:]$, $\widetilde{\mathbf{M}}[-4,:]$ and $\widetilde{\mathbf{M}}[-6,:]$ respectively.

The identity constraint (18) on m_0 and the singularity condition (33) together imply the following proposition,

Proposition B.2. Given $\widetilde{m_i}$, $i = 1, \dots, 6$, (17) has no solution for $\widetilde{m_0}$, if $\exists \omega, s.t. [m_0(\omega), m_0(\omega + \pi_2), m_0(\omega + \pi_4), m_0(\omega + \pi_6)]$ is a linear combination of the rows of $\mathfrak{D}(\omega)$.

Proof of Lemma 5.3:

Lemma 5.3. $\exists \rho > 0 \text{ s.t. } if \widetilde{\mathbf{M}}[-0,:](\boldsymbol{\omega}) \text{ is singular } \forall \boldsymbol{\omega} \in S_{\rho}, \text{ then } rank(\widetilde{\mathbf{m}}^{1}, \widetilde{\mathbf{m}}^{7}) = 1 \text{ or } rank(\widetilde{\mathbf{m}}^{3}, \widetilde{\mathbf{m}}^{5}) = 1.$

Proof. When ρ is small enough, due to the concentration property, $\widetilde{m_i}(\omega)$ is zero on all but a few sets $S_{\rho} + \pi_j$ (see Fig.4 for reference of S_{ρ} and its shifts), thus $\widetilde{\mathbf{m}}^i(\omega)$ is sparse on S_{ρ} and $\widetilde{\mathbf{M}}[:, -0]$ takes the following form

$$\widetilde{\mathbf{M}}[:,-0](\boldsymbol{\omega}) = \begin{bmatrix} \widetilde{\mathbf{m}}^{0} \\ \widetilde{\mathbf{m}}^{1} \\ \widetilde{\mathbf{m}}^{2} \\ \widetilde{\mathbf{m}}^{3} \\ \widetilde{\mathbf{m}}^{4} \\ \widetilde{\mathbf{m}}^{5} \\ \widetilde{\mathbf{m}}^{6} \\ \widetilde{\mathbf{m}}^{7} \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ * & 0 & 0 & 0 & 0 & * \\ 0 & 0 & 0 & * & * & 0 & 0 \\ 0 & 0 & * & * & 0 & 0 & 0 \\ 0 & 0 & * & * & 0 & 0 & 0 \\ * & 0 & * & * & 0 & 0 & * \\ * & 0 & 0 & 0 & 0 & * \end{bmatrix}$$
(35)

where *s denote possible non-zero entries. We make the following observation of $\widetilde{\mathbf{m}}^i$:

- (i) $\widetilde{\mathbf{m}}^0$ is a zero vector
- (ii) $\widetilde{\mathbf{m}}^2$ and $\widetilde{\mathbf{m}}^4$ are linearly independent of each other and the rest of $\widetilde{\mathbf{m}}^i$

(iii)
$$span\{\widetilde{\mathbf{m}}^1, \widetilde{\mathbf{m}}^7\} \perp span\{\widetilde{\mathbf{m}}^3, \widetilde{\mathbf{m}}^5\} \text{ and } rank(\widetilde{\mathbf{m}}^1, \widetilde{\mathbf{m}}^7) \leq 2,$$

 $rank(\widetilde{\mathbf{m}}^3, \widetilde{\mathbf{m}}^5) \leq 2$

(iv)
$$span\{\widetilde{\mathbf{m}}^1, \widetilde{\mathbf{m}}^7, \widetilde{\mathbf{m}}^3, \widetilde{\mathbf{m}}^5, \widetilde{\mathbf{m}}^6\} \le 4$$

Since S_{ρ} is in the low frequency domain, $m_0(\omega) \neq 0$. (22) then implies that $\det(\widetilde{\mathbf{M}}^{\square}[-k_{\omega},:]) \neq 0$ hence $\widetilde{\mathbf{M}}^{\square}$ is full rank, or equivantly, $rank(\widetilde{\mathbf{M}}[:,-0]) = 6$. It follows from (ii) and (iv) that $rank(\widetilde{\mathbf{m}}^1, \widetilde{\mathbf{m}}^6, \widetilde{\mathbf{m}}^7, \widetilde{\mathbf{m}}^3, \widetilde{\mathbf{m}}^5) = 4$. On the other hand, (ii) and (iv) imply that

$$rank(\widetilde{\mathbf{M}}^{\square}(\boldsymbol{\omega} + \boldsymbol{\pi}_2)) = rank(\widetilde{\mathbf{m}}^0, \widetilde{\mathbf{m}}^4, \widetilde{\mathbf{m}}^6, \widetilde{\mathbf{m}}^1, \widetilde{\mathbf{m}}^3, \widetilde{\mathbf{m}}^5, \widetilde{\mathbf{m}}^7) = 5$$

and likewise

$$rank(\widetilde{\mathbf{M}}^{\square}(\boldsymbol{\omega} + \boldsymbol{\pi}_4)) = rank(\widetilde{\mathbf{m}}^0, \widetilde{\mathbf{m}}^2, \widetilde{\mathbf{m}}^6, \widetilde{\mathbf{m}}^1, \widetilde{\mathbf{m}}^3, \widetilde{\mathbf{m}}^5, \widetilde{\mathbf{m}}^7) = 5.$$

Therefore, $\det(\widetilde{\mathbf{M}}^{\square}(\boldsymbol{\omega} + \boldsymbol{\pi}_2)) = \det(\widetilde{\mathbf{M}}^{\square}(\boldsymbol{\omega} + \boldsymbol{\pi}_4)) = 0$ and (22) implies $m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_2) = m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_4) = 0$.

If $\widetilde{\mathbf{m}}^1$ and $\widetilde{\mathbf{m}}^7$ are linearly independent and so are $\widetilde{\mathbf{m}}^3$ and $\widetilde{\mathbf{m}}^5$, then

$$rank(\widetilde{\mathbf{M}}^{\square}(\boldsymbol{\omega} + \boldsymbol{\pi}_6)) = rank(\widetilde{\mathbf{m}}^2, \widetilde{\mathbf{m}}^4, \widetilde{\mathbf{m}}^1, \widetilde{\mathbf{m}}^3, \widetilde{\mathbf{m}}^5, \widetilde{\mathbf{m}}^7) = 6,$$

hence $m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_6) \neq 0$. Therefore,

$$[m_0(\boldsymbol{\omega}), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_2), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_4), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_6)] = [*, 0, 0, *].$$

In addition, $d_{i,j} = 0$, $\forall (i,j)$ except (0,6), so in (33)

$$\mathfrak{D}(\boldsymbol{\omega}) = [d_{0,6}, 0, 0, 0]^{\top}[0, 0, 0, 1] + [0, 0, 0, d_{0,6}]^{\top}[-1, 0, 0, 0].$$

By Proposition B.2, the linear system (17) has no solution $\widetilde{m_0}$ and this proofs the lemma.

Lemma B.3. If $\widetilde{m_1}(\omega)(\widetilde{m_6}(\omega))$ concentrates in $T_1(T_6)$, then $|\widetilde{m_6}(\omega)| > |\widetilde{m_1}(\omega)|$ a.e. on $T_6 \cap supp(\widetilde{m_6})$ $(|\widetilde{m_1}(\omega)| > |\widetilde{m_6}(\omega)|$ a.e. on $T_1 \cap supp(\widetilde{m_1})$.

Proof Let $B_6 = \{\boldsymbol{\omega} : |\widetilde{m_6}(\boldsymbol{\omega})| \leq |\widetilde{m_1}(\boldsymbol{\omega})|\} \bigcap T_6 \bigcap supp(\widetilde{m_1})$ and B_1 be its mirror set with respect to $\omega_1 = \omega_2$ and suppose $|B_6| > 0$, then $\int_{B_6} |\widetilde{m_6}(\boldsymbol{\omega})| \leq \int_{B_6} |\widetilde{m_1}(\boldsymbol{\omega})|$. On the other hand, since $\widetilde{m_1}(\boldsymbol{\omega})$ concentrates in T_1 , we know $\int_{B_1} |\widetilde{m_1}(\boldsymbol{\omega})| > \int_{B_6} |\widetilde{m_1}(\boldsymbol{\omega})|$. Moreover, due to the symmetry of $\widetilde{m_1}(\boldsymbol{\omega}), \widetilde{m_6}(\boldsymbol{\omega})$ and $B_1, B_6, \int_{B_1} |\widetilde{m_1}(\boldsymbol{\omega})| = \int_{B_6} |\widetilde{m_6}(\boldsymbol{\omega})|$, hence $\int_{B_6} |\widetilde{m_1}(\boldsymbol{\omega})| \geq \int_{B_6} |\widetilde{m_6}(\boldsymbol{\omega})| = \int_{B_1} |\widetilde{m_1}(\boldsymbol{\omega})|$ which results in contradiction.

Proposition B.4. If $m_1(m_6)$ concentrates within $T_1(T_6)$, then $\widetilde{m_1}(\boldsymbol{\omega}) = \widetilde{m_6}(\boldsymbol{\omega}) = 0$, a.e. on $S_{\rho} + \pi_1$.

Proof. Consider frequency domain $S'_{\rho} = S_{\rho} \bigcap \{\omega_1 < \omega_2\}$. By Lemma 5.3, $\exists \alpha_{\omega} \in \mathbb{C}$, $s.t.\widetilde{\mathbf{m}}^1(\omega) = \alpha_{\omega} \widetilde{\mathbf{m}}^7(\omega)$, $\forall \omega \in S'_{\rho}$, i.e. $\widetilde{m}_1(\omega + \pi_1) = \alpha_{\omega} \cdot \widetilde{m}_1(\omega + \pi_7)$ and $\widetilde{m}_6(\omega + \pi_1) = \alpha_{\omega} \cdot \widetilde{m}_6(\omega + \pi_7)$. On the other hand, Lemma B.3 implies that $|\widetilde{m}_1(\omega + \pi_7)| \geq |\widetilde{m}_6(\omega + \pi_7)|$, hence $|\widetilde{m}_1(\omega + \pi_1)| \geq |\widetilde{m}_6(\omega + \pi_1)|$. Let $\Omega'_6 := (S_{\rho} + \pi_1) \bigcap T_6$, then $\int_{\Omega'_6} |\widetilde{m}_1(\omega)| \geq \int_{\Omega'_6} |\widetilde{m}_6(\omega)|$, which will contradict Lemma B.3 unless $|\Omega'_6 \bigcap \text{supp}(\widetilde{m}_6)| = 0$, or equivalently $\alpha_{\omega} = 0$ and so $\widetilde{m}_6(\omega) = \widetilde{m}_1(\omega) = 0$, a.e. on Ω'_6 . By symmetry, $\widetilde{m}_6(\omega) = \widetilde{m}_1(\omega) = 0$, a.e. on $(S_{\rho} + \pi_1) \setminus \Omega'_6$ as well.

B.2 Design of input $\widetilde{m}_i(\omega)$

Proof of Lemma 5.6:

Lemma 5.6. If $\exists \boldsymbol{\omega} \in D_1 := \{\omega_1 = \omega_2, \omega_1 \in (-\frac{\pi}{2}, 0)\}, s.t. m_0(\boldsymbol{\omega}) > 0$, then $(\boldsymbol{\eta}_1 - \boldsymbol{\eta}_6)^{\top} (\boldsymbol{\pi}_6 - \boldsymbol{\pi}_7) \neq 0 (mod 2\pi)$.

Proof. As $\widetilde{m_1}(\boldsymbol{\omega})$ and $\widetilde{m_6}(\boldsymbol{\omega})$ concentrate in T_1 and T_6 respectively, $\widetilde{m_1}(\boldsymbol{\omega}+\boldsymbol{\pi}_i)=0$ and $\widetilde{m_6}(\boldsymbol{\omega}+\boldsymbol{\pi}_i)=0, \ i=1,\cdots,5$. Due to symmetry, $|\widetilde{m_1}(\boldsymbol{\omega})|=|\widetilde{m_6}(\boldsymbol{\omega})|$ on $\{\omega_1=\omega_2\}$. Let $A=|\widetilde{m_1}(\boldsymbol{\omega}+\boldsymbol{\pi}_7)|=|\widetilde{m_6}(\boldsymbol{\omega}+\boldsymbol{\pi}_7)|$ and $B=|\widetilde{m_1}(\boldsymbol{\omega}+\boldsymbol{\pi}_6)|=|\widetilde{m_6}(\boldsymbol{\omega}+\boldsymbol{\pi}_6)|$, then the first and the last columns of $\widetilde{\mathbf{M}}^{\square}$ are

$$\widetilde{\mathbf{M}}^{\square}[:,1] = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ Ae^{i\boldsymbol{\eta}_{1}^{\top}(\boldsymbol{\omega} + \boldsymbol{\pi}_{6})} \\ Be^{i\boldsymbol{\eta}_{1}^{\top}(\boldsymbol{\omega} + \boldsymbol{\pi}_{7})} \end{bmatrix} \quad \text{and} \quad \widetilde{\mathbf{M}}^{\square}[:,6] = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ Ae^{i\boldsymbol{\eta}_{6}^{\top}(\boldsymbol{\omega} + \boldsymbol{\pi}_{6})} \\ Be^{i\boldsymbol{\eta}_{6}^{\top}(\boldsymbol{\omega} + \boldsymbol{\pi}_{7})} \end{bmatrix}.$$

By (22), if $m_0(\omega) > 0$, $\omega \in D_1$ then $\widetilde{\mathbf{M}}^{\square}(\omega)$ is full rank, hence its columns are linearly independent. In particular, $\widetilde{\mathbf{M}}^{\square}[:,1]$ and $\widetilde{\mathbf{M}}^{\square}[:,6]$ are linearly independent, which implies that $e^{i(\boldsymbol{\eta}_1^{\top}\boldsymbol{\pi}_6+\boldsymbol{\eta}_6^{\top}\boldsymbol{\pi}_7)} \neq e^{i(\boldsymbol{\eta}_6^{\top}\boldsymbol{\pi}_6+\boldsymbol{\eta}_1^{\top}\boldsymbol{\pi}_7)}$ or equivalently $(\boldsymbol{\eta}_1 - \boldsymbol{\eta}_6)^{\top}(\boldsymbol{\pi}_6 - \boldsymbol{\pi}_7) \neq 0 \pmod{2\pi}$.

Proof of Proposition 5.7

Proposition 5.7. If $\widetilde{m_0}(\mathbf{0}) \neq 0$, then $\pi_1^{\top}(\eta_1 - \eta_6) \neq \pi(mod 2\pi)$ or $\pi_3^{\top}(\eta_3 - \eta_4) \neq \pi(mod 2\pi)$. Proof. Since $\widetilde{m_0}(\mathbf{0}) \neq 0$, as shown in Lemma 5.3, at $\boldsymbol{\omega} = \mathbf{0}$ $rank(\widetilde{\mathbf{m}}^1, \widetilde{\mathbf{m}}^6, \widetilde{\mathbf{m}}^7, \widetilde{\mathbf{m}}^3, \widetilde{\mathbf{m}}^5) = 4$. This is equivalent to the matrix \boldsymbol{A} defined in (36) to be full rank.

$$\mathbf{A} = \begin{bmatrix} \widetilde{m}_{1}(\boldsymbol{\pi}_{6}) & \widetilde{m}_{6}(\boldsymbol{\pi}_{6}) & \widetilde{m}_{3}(\boldsymbol{\pi}_{6}) & \widetilde{m}_{4}(\boldsymbol{\pi}_{6}) \\ \widetilde{m}_{1}(\boldsymbol{\pi}_{1}) & \widetilde{m}_{6}(\boldsymbol{\pi}_{1}) & 0 & 0 \\ \widetilde{m}_{1}(\boldsymbol{\pi}_{7}) & \widetilde{m}_{6}(\boldsymbol{\pi}_{7}) & 0 & 0 \\ 0 & 0 & \widetilde{m}_{3}(\boldsymbol{\pi}_{3}) & \widetilde{m}_{4}(\boldsymbol{\pi}_{3}) \\ 0 & 0 & \widetilde{m}_{3}(\boldsymbol{\pi}_{5}) & \widetilde{m}_{4}(\boldsymbol{\pi}_{5}) \end{bmatrix}$$
(36)

Let $|\widetilde{m}_1(\boldsymbol{\pi}_1)| = a$, $|\widetilde{m}_1(\boldsymbol{\pi}_6)| = b$. Due to the symmetry of $\widetilde{m}_j(\boldsymbol{\omega})$, $|\widetilde{m}_1(\boldsymbol{\pi}_1)| = |\widetilde{m}_1(\boldsymbol{\pi}_7)| = |\widetilde{m}_6(\boldsymbol{\pi}_1)| = |\widetilde{m}_6(\boldsymbol{\pi}_7)| = |\widetilde{m}_3(\boldsymbol{\pi}_3)| = |\widetilde{m}_3(\boldsymbol{\pi}_5)| = |\widetilde{m}_4(\boldsymbol{\pi}_3)| = |\widetilde{m}_4(\boldsymbol{\pi}_5)|$ and $|\widetilde{m}_1(\boldsymbol{\pi}_6)| = |\widetilde{m}_6(\boldsymbol{\pi}_6)| = |\widetilde{m}_3(\boldsymbol{\pi}_6)| = |\widetilde{m}_4(\boldsymbol{\pi}_6)|$. Rewrite \boldsymbol{A} as follows,

$$\boldsymbol{A} = \begin{bmatrix} be^{-i\boldsymbol{\pi}_{6}^{\top}\boldsymbol{\eta}_{1}} & be^{-i\boldsymbol{\pi}_{6}^{\top}\boldsymbol{\eta}_{6}} & be^{-i\boldsymbol{\pi}_{6}^{\top}\boldsymbol{\eta}_{3}} & be^{-i\boldsymbol{\pi}_{6}^{\top}\boldsymbol{\eta}_{4}} \\ ae^{-i\boldsymbol{\pi}_{1}^{\top}\boldsymbol{\eta}_{1}} & ae^{-i\boldsymbol{\pi}_{1}^{\top}\boldsymbol{\eta}_{6}} & 0 & 0 \\ ae^{i\boldsymbol{\pi}_{1}^{\top}\boldsymbol{\eta}_{1}} & ae^{i\boldsymbol{\pi}_{1}^{\top}\boldsymbol{\eta}_{6}} & 0 & 0 \\ 0 & 0 & ae^{-i\boldsymbol{\pi}_{3}^{\top}\boldsymbol{\eta}_{3}} & ae^{-i\boldsymbol{\pi}_{3}^{\top}\boldsymbol{\eta}_{4}} \\ 0 & 0 & ae^{i\boldsymbol{\pi}_{3}^{\top}\boldsymbol{\eta}_{3}} & ae^{i\boldsymbol{\pi}_{3}^{\top}\boldsymbol{\eta}_{4}} \end{bmatrix}$$

The product of singular values of \boldsymbol{A} is

$$\sqrt{\det(\mathbf{A}^*\mathbf{A})} = 4a^3 \sqrt{a^2 K_1^2 K_2^2 + b^2 (Q_1 K_2^2 + Q_2 K_1^2)},$$
 (37)

where $Q_1 = 1 - \cos(\boldsymbol{\pi}_6^{\top}(\boldsymbol{\eta}_1 - \boldsymbol{\eta}_6)) \cos(\boldsymbol{\pi}_1^{\top}(\boldsymbol{\eta}_1 - \boldsymbol{\eta}_6)), Q_2 = 1 - \cos(\boldsymbol{\pi}_6^{\top}(\boldsymbol{\eta}_3 - \boldsymbol{\eta}_6))$

 $\eta_4) \cos(\pi_3^{\top}(\eta_3 - \eta_4)), K_1 = \sin(\pi_1^{\top}(\eta_1 - \eta_6)), K_2 = \sin(\pi_3^{\top}(\eta_3 - \eta_4)).$ If $\pi_1^{\top}(\eta_1 - \eta_6) = \pi_3^{\top}(\eta_3 - \eta_4) = \pi(mod \, 2\pi)$, then $K_1 = K_2 = 0$ and A becomes singular.

B.3 Solving (17) and (18) for $m_0, \widetilde{m_0}$ and m_i

Lemma B.5. Let $P \in \mathbb{C}^{n \times n}$ be a projection matrix of rank 2 and $a, b, a', b' \in \mathbb{C}^n$, s.t. $a^*b = (a')^*b' = 1$, $a'^*b = a^*b' = b^*b' = 0$. If $P(I_n - a \otimes b - a' \otimes b') = 0$, then P is the projection of $span\{b, b'\}$.

Proof. Since

 $rank(\mathbf{I}_n) \leq rank(\mathbf{I}_n - \mathbf{a} \otimes \mathbf{b} - \mathbf{a}' \otimes \mathbf{b}') + rank(\mathbf{a} \otimes \mathbf{b}) + rank(\mathbf{a}' \otimes \mathbf{b}'),$ it follows that $rank(\mathbf{I}_n - \mathbf{a} \otimes \mathbf{b} - \mathbf{a}' \otimes \mathbf{b}') \geq n - 2$. On the other hand, because $rank(\mathbf{P}) = 2$, $\mathbf{P}(\mathbf{I}_n - \mathbf{a} \otimes \mathbf{b} - \mathbf{a}' \otimes \mathbf{b}') = \mathbf{0}$ implies that $rank(\mathbf{I}_n - \mathbf{a} \otimes \mathbf{b} - \mathbf{a}' \otimes \mathbf{b}') \leq n - 2$. Hence $rank(\mathbf{I}_n - \mathbf{a} \otimes \mathbf{b} - \mathbf{a}' \otimes \mathbf{b}') = n - 2$ and \mathbf{P} is the projection of $col(\mathbf{I}_n - \mathbf{a} \otimes \mathbf{b} - \mathbf{a}' \otimes \mathbf{b}')^{\perp}$. On the other hand,

$$b^*(I_n - a \otimes b - a' \otimes b') = b^* - (b^*a)b^* - (b^*a')(b')^*$$

= $b^* - b^* - 0 \cdot (b')^* = 0^*$

Therefore, Pb = b. Similarly, $(b')^*(I_n - a \otimes b - a' \otimes b') = 0^*$ and Pb' = b'. Moreover, as $b^*b' = 0$ and rank(P) = 2, $P = ||b||^{-2} \cdot b \otimes b + ||b'||^{-2} \cdot b' \otimes b'$.

Lemma B.6. Given $\widetilde{\mathbf{M}}[:,-0](\boldsymbol{\omega})$ is full rank $\forall \boldsymbol{\omega},\ \widetilde{\mathbf{M}}[-0,:](\boldsymbol{\omega})$ is singular if (18) holds.

Proof. If (18) holds, then by Lemma B.5, $\mathbf{m}_0^{\mathcal{E}}$, $\mathbf{m}_0^{\mathcal{O}}$ are orthogonal to $col(\widetilde{\mathbf{M}}[:,-0])$, therefore $\left[\mathbf{m}_0^{\mathcal{O}},\mathbf{m}_0^{\mathcal{E}},\widetilde{\mathbf{M}}[:,-0]\right] \in \mathbb{C}^{8\times8}$ is full rank. Due to (18), $\mathbf{m}_0^{\mathcal{E}}$ and $\widetilde{\mathbf{m}_0}^{\mathcal{E}}$ are not orthogonal to each other, hence $\left[\mathbf{m}_0^{\mathcal{O}},\widetilde{\mathbf{m}_0}^{\mathcal{E}},\widetilde{\mathbf{M}}[:,-0]\right] = \left[\mathbf{m}_0^{\mathcal{O}},\widetilde{\mathbf{M}}\right]$ is full rank as well. Because $(\mathbf{m}_0^{\mathcal{O}})^*\widetilde{\mathbf{M}}[:,i] = 0, i = 0, \cdots, 7$ and $\mathbf{m}_0^{\mathcal{O}}[-0]^*\widetilde{\mathbf{M}}[-0,i] = (\mathbf{m}_0^{\mathcal{O}})^*\widetilde{\mathbf{M}}[:,i], \mathbf{m}_0^{\mathcal{O}}[-0]$ is orthogonal to $col(\widetilde{\mathbf{M}}[-0,:])$. Since $\left[\mathbf{m}_0^{\mathcal{O}}[-0],\widetilde{\mathbf{M}}[-0,:]\right] \in \mathbb{C}^{7\times8}$ is full rank, $\widetilde{\mathbf{M}}[-0,:]$ must be singular.

Proof of Proposition 5.8:

Proposition 5.8. Let $\widetilde{\mathbf{M}}[odd, -0]$, $\widetilde{\mathbf{M}}[even, -0] \in \mathbb{C}^{4 \times 6}$ be the sub-matrices of $\widetilde{\mathbf{M}}[:, -0]$ consisting of odd and even rows respectively. Suppose (5.3.i) holds, then (5.3.ii) holds if and only if $\operatorname{rank}(\widetilde{\mathbf{M}}[odd, -0]) = \operatorname{rank}(\widetilde{\mathbf{M}}[even, -0]) = 3$ and

$$[m_0(\boldsymbol{\omega}), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_2), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_4), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_6)] \widetilde{\mathbf{M}}[even, -0](\boldsymbol{\omega}) = \mathbf{0}, \quad (26)$$

$$[m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_1), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_3), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_5), m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_7)]\widetilde{\mathbf{M}}[odd, -0](\boldsymbol{\omega}) = \mathbf{0}. (27)$$

Proof. Note that $\widetilde{\mathbf{M}}[:, -0]$ have the same rows at $\boldsymbol{\omega} + \boldsymbol{\pi}_i$, $i = 0, \dots, 7$, we define row permutation matrix \boldsymbol{P}_i , s.t. $\boldsymbol{P}_i(\widetilde{\mathbf{M}}[:, -0](\boldsymbol{\omega} + \boldsymbol{\pi}_i)) = \widetilde{\mathbf{M}}[:, -0](\boldsymbol{\omega})$. Let $\boldsymbol{P}_{\widetilde{\mathbf{M}}}(\boldsymbol{\omega})$ be the projection matrix of the $col(\widetilde{\mathbf{M}}[:, -0](\boldsymbol{\omega}))^{\perp} = null(\widetilde{\mathbf{M}}[:, -0]^*)$,

then (5.3.ii) is equivalent to $P_{\widetilde{\mathbf{M}}}b'_0(\omega) = \mathbf{0}$. Group this equality at $\omega + \pi_i$, we have

$$\mathbf{0} = [\mathbf{P}_{i}\mathbf{P}_{\widetilde{\mathbf{M}}}\mathbf{b}'_{0}(\boldsymbol{\omega} + \boldsymbol{\pi}_{i})]_{i=0,\dots,7}$$

$$= [\mathbf{P}_{i}\mathbf{P}_{\widetilde{\mathbf{M}}}(\boldsymbol{\omega} + \boldsymbol{\pi}_{i})\mathbf{P}_{i}^{2}\mathbf{b}'_{0}(\boldsymbol{\omega} + \boldsymbol{\pi}_{i})]_{i=0,\dots,7}$$

$$= [\mathbf{P}_{\widetilde{\mathbf{M}}}(\boldsymbol{\omega})\mathbf{P}_{i}\mathbf{b}'_{0}(\boldsymbol{\omega} + \boldsymbol{\pi}_{i})]_{i=0,\dots,7}$$

$$= \mathbf{P}_{\widetilde{\mathbf{M}}}(\boldsymbol{\omega})[\mathbf{P}_{i}\mathbf{b}'_{0}(\boldsymbol{\omega} + \boldsymbol{\pi}_{i})]_{i=0,\dots,7}$$
(38)

Let

$$\begin{split} & \overline{\widetilde{\mathbf{m}_0}}^{\mathcal{E}} = [(1+i \bmod 2) \cdot \overline{\widetilde{m_0}}(\boldsymbol{\omega} + \boldsymbol{\pi}_i)]_{i=0,\cdots,7}^{\top} = \widetilde{\mathbf{M}}[:,0](\boldsymbol{\omega}), \\ & \overline{\widetilde{\mathbf{m}_0}}^{\mathcal{O}} = [(i \bmod 2) \cdot \overline{\widetilde{m_0}}(\boldsymbol{\omega} + \boldsymbol{\pi}_i)]_{i=0,\cdots,7}^{\top}, \\ & \mathbf{m}_0^{\mathcal{E}} = [(1+i \bmod 2) \cdot m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_i)]_{i=0,\cdots,7}^{\top}, \\ & \mathbf{m}_0^{\mathcal{O}} = [(i \bmod 2) \cdot m_0(\boldsymbol{\omega} + \boldsymbol{\pi}_i)]_{i=0,\cdots,7}^{\top}. \end{split}$$

The identity constraint (18) thus can be written as $(\overline{\mathbf{m}_0^{\mathcal{E}}})^* \overline{\widetilde{\mathbf{m}_0}}^{\mathcal{E}} = 1$ and $(\overline{\mathbf{m}_0^{\mathcal{O}}})^* \overline{\widetilde{\mathbf{m}_0}}^{\mathcal{O}} = 1$. By definition,

$$P_i b_0'(\omega + \pi_i) = P_i (b_0 - m_0 \widetilde{\mathbf{M}}[:, 0](\omega + \pi_i)) = b_i - m_0(\omega + \pi_i) P_i (\widetilde{\mathbf{M}}[:, 0](\omega + \pi_i))$$

and

$$\boldsymbol{P}_{i}\big(\widetilde{\mathbf{M}}[:,0](\boldsymbol{\omega}+\boldsymbol{\pi}_{i})\big) = \begin{cases} \widetilde{\mathbf{M}}[:,0] = \overline{\widetilde{\mathbf{m}_{0}}}^{\mathcal{E}}, & i \text{ is even} \\ \overline{\widetilde{\mathbf{m}_{0}}}^{\mathcal{O}}, & i \text{ is odd} \end{cases}$$

Substitute the above expression of $P_i b_0'(\omega + \pi_i)$ in (38) and we have

$$\mathbf{0} = P_{\widetilde{\mathbf{M}}}(I_8 - \overline{\widetilde{\mathbf{m}_0}}^{\mathcal{E}} \otimes \overline{\mathbf{m}_0^{\mathcal{E}}} - \overline{\widetilde{\mathbf{m}_0}}^{\mathcal{O}} \otimes \overline{\mathbf{m}_0^{\mathcal{O}}})$$
(39)

Therefore, by Lemma B.5, $P_{\widetilde{\mathbf{M}}}$ is the projection of $span\{\overline{\mathbf{m}_0^{\mathcal{O}}}, \overline{\mathbf{m}_0^{\mathcal{E}}}\}$. This is equivalent to (26) and (27). Finally, since

$$6 = rank(\widetilde{\mathbf{M}}[:, -0]) \le rank(\widetilde{\mathbf{M}}[odd, -0]) + rank(\widetilde{\mathbf{M}}[even, -0]) \le (4-1) + (4-1),$$
$$rank(\widetilde{\mathbf{M}}[odd, -0]) = rank(\widetilde{\mathbf{M}}[even, -0]) = 3.$$

C Supplementary Numerical Results

C.1 Numerical optimization of $\widetilde{m}_0(\omega)$ in 1D

To test whether numerical optimization is a practical way to solve (18) and (21), we experiment on m_0 and $\widetilde{m_0}$ of existing bi-orthogonal wavelets. We consider a pair of low frequency filters corresponding to bi-orthogonal scaling functions ϕ , $\widetilde{\phi}$ with vanishing moments 3 and 5 respectively.

The 1D filters are shown in Fig.12. Suppose we know the decomposition filter, and we want to find the reconstruction filter by solving (21), such that the filter has support as concentrated as possible. Without loss of generality, (21) can be solved assuming that m_0 is real. It is not necessary that the corred-

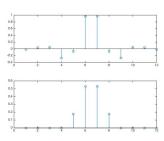


Figure 12: 1D filters, up: LoD, down: LoR

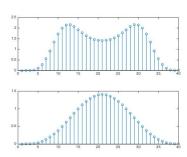


Figure 13: $m_0(\omega)$ and $\widetilde{m_0}(\omega)$

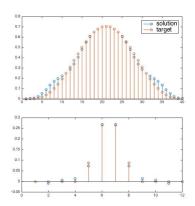


Figure 14: $\widehat{\widetilde{m}_0}$ vs. \widetilde{m}_0 , top: frequency domain, bottom: time domain

ponding $\widetilde{m_0}$ is also real, but in this testing case, m_0 and $\widetilde{m_0}$ are both real. Fig.13 shows the ground truth m_0 and $\widetilde{m_0}$ considered in this simulation.

Let $\widetilde{m_0}(\omega)$ be the approximation of $\widetilde{m_0}(\boldsymbol{\omega})$, which is solution of the following optimization problem

$$\min_{\mathbf{x}} \|\mathbf{D}\mathbf{x}\|^2 + \|\mathbf{x}\|^2, \quad s.t. \ \mathbf{A}\mathbf{x} = \mathbf{1}$$
 (40)

where \mathbf{A} in the constraint is the matrix generated from (18) (in 1D, only a single shift of π appears in the condition, so each row of **A** has two non-zero entries). Figure 14 compares the solution of (40) and the ground truth. The support of the solution is slightly more spread out than the ground truth.

C.2Numerical optimization of $\widetilde{m_0}(\boldsymbol{\omega})$ in 2D

In the 2D case, we use the pair of bi-orthogonal low-pass filters that are the tensor products of the 1D filters in Section C.1 as ground truth. We solve the 2D version of the optimization problem (40). Figure 15 shows the solution and compares it with the ground truth.

To make the support of $\widehat{m}_0(\omega)$ better concentrate within the low frequency domain, we change the squared ℓ_2 -norm penalty in (40) to a weighted version (corresponding to Modulation space) as follows, $\min_{\mathbf{v}} \| \mathbf{D} \mathbf{x} \|^2 + \lambda \| \mathbf{w} \circ \mathbf{x} \|^2, \quad s.t. \ \mathbf{A} \mathbf{x} = \mathbf{1}$

$$\min_{\mathbf{x}} \|\mathbf{D}\mathbf{x}\|^2 + \lambda \|\mathbf{w} \circ \mathbf{x}\|^2, \quad s.t. \ \mathbf{A}\mathbf{x} = \mathbf{1}$$
 (41)

where \circ is Hadamard product and \mathbf{w} is a weight vector. In particular, we choose $\forall \omega, \ \mathbf{w}(\omega) = \|\omega\|$. Fig.16 shows the solution of (41) with $\lambda = 600$.

Compared to (29) proposed to solve $\widetilde{m}_0(\omega)$, both optimization problems (40) and (41) in this simulation minimize total variation (TV) of $\widetilde{m_0}$ instead of $\overline{\widetilde{m_0}} \cdot m_0$ and have an extra (weighted) ℓ_2 regularization term. Although (40) and (41) work better than (29) for tensor wavelet construction here, they do not provide better solutions in the construction of directional wavelets and cost more computation time.

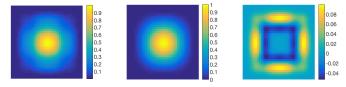


Figure 15: Left to right: solution of (40) in 2D, ground truth and their difference

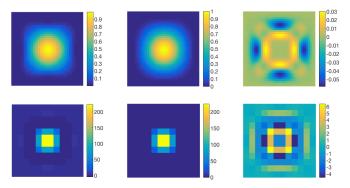


Figure 16: Left to right: solution of (41) ($\lambda=600$), ground truth and their difference; Top: frequency domain, bottom: time domain.

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