

Introduction to Optimization

**Lecture 09: Simple constraints and projected gradient.
Nonsmooth convex functions and subgradient method.**



A quick reminder

Let $C \subset \mathbb{R}^N$ be nonempty, closed and convex. For each $x \in \mathbb{R}^N$, the **projection** of x onto C , denoted by $P_C(x)$, is the point in C , which is the closest to x .

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② Balls $\bar{B}(x_0, r)$ and boxes $\prod [a_i, b_i]$.



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- ① The positive orthant \mathbb{R}_+^N . 
- ② Balls $\bar{B}(x_0, r)$ and boxes $\prod [a_i, b_i]$. 
- ③ Affine spaces, such as $\{x_0\} + V$, or $\{x \in \mathbb{R}^N : Ax = b\}$. 

The projected gradient method

Consider the problem

$$\min_{x \in C} f(x),$$

where

- $f : \mathbb{R}^N \rightarrow \mathbb{R}$, and
- $C \subset \mathbb{R}^N$ is nonempty, closed, convex and easy to project onto.

The set of solutions is denoted by S , and the optimal value by f^* .

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Idea: At each iteration, perform a gradient step and then project onto C .

$$x_{n+1} = P_C(x_n - \alpha_n \nabla f(x_n)).$$

Convergence of the projected gradient method

Theorem

Let f be convex and L -smooth, and suppose $S \neq \emptyset$. Iterate $x_{n+1} = P_C(x_n - \alpha \nabla f(x_n))$ with $0 < \alpha \leq \frac{1}{L}$.

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① x_n converges to a point in S , and

$$f(x_n) - f^* \leq \frac{\text{dist}(x_0, S)^2}{2\alpha n}.$$

② If f is μ -strongly convex, then

$$f(x_n) - f^* \leq \frac{f(x_0) - f^*}{(1 + \alpha\mu)^n}.$$

Break

Nonsmooth convex functions

Let $f : A \subset \mathbb{R}^N \rightarrow \mathbb{R}$ be convex. If f is differentiable at x , then

$$f(y) \geq f(x) + \nabla f(x) \cdot (y - x)$$

for all $y \in A$.

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for all $y \in A$. The **subdifferential** of f at x , denoted by $\partial f(x)$, is the set of all the subgradients of f at x .

A few simple but important examples

Example (A big ice cream cone)

Let $f : \mathbb{R}^N \rightarrow \mathbb{R}$ be defined by $f(x) = \|x\|$.

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Example (The indicator function)

Let $C \subset \mathbb{R}^N$ be nonempty, closed and convex. The **indicator function** of C is the function $\iota_C : C \rightarrow \mathbb{R}$, defined as $\iota_C(x) = 0$ for all $x \in C$.

Convexity, continuity and subdifferentiability

Proposition

If $f : A \subset \mathbb{R}^N \rightarrow \mathbb{R}$ is convex, for each $x \in \text{int}(A)$, there exist $L_x, r_x > 0$ such that

$$|f(z) - f(y)| \leq L_x \|z - y\|$$

for all $z, y \in B(x, r_x)$. Moreover,

$$\emptyset \neq \partial f(x) \subseteq \bar{B}(0, L_x).$$

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Convex functions are continuous and subdifferentiable in the interior of their domains.

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Let $f : \mathbb{R}^N \rightarrow \mathbb{R}$ be convex and Lipschitz-continuous with constant M ,^a with minimizers, and let (x_n) be defined by the subgradient method. Then,

$$\min_{k=1,\dots,n} (f(x_k) - \min(f)) \leq \frac{\alpha M^2}{2} + \frac{\text{dist}(x_0, S)^2}{2\alpha(n+1)}.$$

^aRecall that this means that $|f(x) - f(y)| \leq M\|x - y\|$.

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Question

Given $\varepsilon > 0$, after how many iterations can we be sure to have found a point \hat{x} such that $f(\hat{x}) - \min(f) \leq \varepsilon$?