Introduction to Optimization

Lecture 09: Subgradient descent. The proximal-gradient algorithm.



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Reminder

A vector $v \in \mathbb{R}^N$ is a subgradient of f a convex function $f : \text{dom}(f) \subset \mathbb{R}^N \to \mathbb{R}$ at the point x if

$$f(y) \ge f(x) + \langle v, y - x \rangle$$

for all $y \in \mathbb{R}^N$.

Proposition

If $f: dom(f) \subset \mathbb{R}^N \to \mathbb{R}$ is convex, for each $x \in int(dom(f))$, there exist $L_x, r_x > 0$ such that

$$|f(z)-f(y)|\leq L_x||z-y||$$

for all $z, y \in B(x, r_x)$. Moreover, $\emptyset \neq \partial f(x) \subseteq \bar{B}(0, L_x)$.

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The subgradient method

 $x_{n+1} = x_n - \alpha v_n$ with $v_n \in \partial f(x_n)$

Proposition

Let $f: \mathbb{R}^N \to \mathbb{R}$ be convex and Lipschitz-continuous with constant M $(|f(x) - f(y)| \le M||x - y||)$ with minimizers, and let (x_n) be defined by the subgradient method. Set $\bar{x}_n = \frac{1}{n+1} \sum_{k=0}^n x_k$. Then,

$$\min_{k=1,\ldots,n} \left(f(x_k) - \min(f) \right) \leq f(\bar{x}_n) - \min(f) \leq \frac{\alpha M^2}{2} + \frac{\operatorname{dist}(x_0, S)^2}{2\alpha(n+1)}.$$

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The subgradient method

 $x_{n+1} = x_n - \alpha v_n$ with $v_n \in \partial f(x_n)$

Proposition

Let $f: \mathbb{R}^N \to \mathbb{R}$ be convex and Lipschitz-continuous with constant M $(|f(x) - f(y)| \le M||x - y||)$ with minimizers, and let (x_n) be defined by the subgradient method. Set $\bar{x}_n = \frac{1}{n+1} \sum_{k=0}^n x_k$. Then,

$$\min_{k=1,\ldots,n} \left(f(x_k) - \min(f) \right) \leq f(\bar{x}_n) - \min(f) \leq \frac{\alpha M^2}{2} + \frac{\operatorname{dist}(x_0, S)^2}{2\alpha(n+1)}.$$

Question

Given $\varepsilon > 0$, after how many iterations can we be sure to have found a point \hat{x} such that $f(\hat{x}) - \min(f) \le \varepsilon$?

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- $\gamma(+\infty) = +\infty$ for all $\gamma > 0$, and $0(+\infty) = 0$.

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The (effective) domain and epigraph of a function $f:\mathbb{R}^N \to \mathbb{R} \cup \{+\infty\}$ is

dom
$$(f) = \{x \in \mathbb{R}^N : f(x) < +\infty\}$$

epi $(f) = \{(x, z) \in \mathbb{R}^{N+1} : f(x) \le z\},$

respectively. We will always assume that $dom(f) \neq \emptyset$.

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Notice that $dom(\lambda f + g) = dom(f) \cap dom(g)$.

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- The indicator function of $C \subset \mathbb{R}^N$ ($C \neq \emptyset$) is $\iota_C : \mathbb{R}^N \to \mathbb{R} \cup \{+\infty\}$, defined as $\iota_C(x) = 0$ if $x \in C$ and $\iota_C(x) = +\infty$ if $x \notin C$.

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If
$$f: \mathbb{R}^N \to \mathbb{R}$$
, $\min\{f(x): x \in C\} = \min\{f(x) + \iota_C(x): x \in \mathbb{R}^N\}$.

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Closedness and proximity operator

If $f: \mathbb{R}^N \to \mathbb{R} \cup \{+\infty\}$ is closed and convex, and $y \in \mathbb{R}^N$, the function

$$f_y(x) = f(x) + \frac{1}{2}||x - y||^2$$

is closed and strongly convex.

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$$\partial f_{y}(x) = \partial f(x) + x - y,$$

for each $x \in dom(f)$.

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$$\partial f_{y}(x) = \partial f(x) + x - y,$$

for each $x \in dom(f)$. The unique minimizer of f_y is denoted by $prox_f(y)$, and is characterized by

$$y - \operatorname{prox}_f(y) \in \partial f(\operatorname{prox}_f(y)).$$

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The proximal method

If $f: \mathbb{R}^N \to \mathbb{R} \cup \{+\infty\}$ is closed and convex, and fix $\alpha > 0$. From an initial point $x_0 \in \mathbb{R}^N$, define a sequence inductively by

$$x_{n+1} = \operatorname{prox}_{\alpha f}(x_n).$$

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Exercise

If $f: \mathbb{R}^N \to \mathbb{R} \cup \{+\infty\}$ is closed and convex, and $S \neq \emptyset$, then x_n converges to a point in S. Moreover,

$$f(x_n) - \min(f) \le \frac{\operatorname{dist}(x_0, S)^2}{2\alpha n}, \qquad n \ge 1.$$

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Suppose we want to find the minima of f = g + h, where $g : \mathbb{R}^N \to \mathbb{R} \cup \{+\infty\}$ is convex and lower-semicontinuous, and $h : \mathbb{R}^N \to \mathbb{R}$ is convex and L-smooth.

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Example

A typical example in image and signal processing, statistics, ML, is

$$f(x) = \frac{1}{2} ||Ax - b||^2 + \rho ||x||_1$$

for $x \in \mathbb{R}^N$.

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The proximal-gradient method consists in applying proximal iterations while linearizing the smooth function:

$$x_{n+1} = \operatorname{Argmin} \left\{ g(x) + h(x_n) + \langle \nabla h(x_n), x - x_n \rangle + \frac{1}{2\gamma} ||x - x_n||^2 \right\}$$

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This subproblem has a unique solution characterized by

$$0 \in \partial g(x_{n+1}) + \nabla h(x_n) + \frac{1}{\gamma}(x_{n+1} - x_n).$$

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Note that

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In turn, this can be rewritten as

$$x_{n+1} = (I + \gamma \partial g)^{-1} (I - \gamma \nabla h) x_n,$$

where we identify a gradient subiteration with respect to h, and then a proximal subiteration with respect to g.

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where we identify a gradient subiteration with respect to h, and then a proximal subiteration with respect to g. It is a splitting method.

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Convergence of proximal-gradient sequences

Theorem

Let f = g + h, where $g : \mathbb{R}^N \to \mathbb{R} \cup \{+\infty\}$ is convex and lower-semicontinuous, and $h : \mathbb{R}^N \to \mathbb{R}$ is convex and L-smooth. Take $\gamma \in (0, 2/L)$ and define (x_n) by

$$x_{n+1} = (I + \gamma \partial g)^{-1} (I - \gamma \nabla h) x_n, \qquad n \ge 0.$$

Then, x_n converges to a minimizer of f, and there is C > 0 such that

$$f(x_n) - \min(f) \le \frac{dist(x_0, \operatorname{Argmin}(f))^2}{2\gamma n}, \qquad n \ge 1.$$

Moreover, $\lim_{n\to\infty} n(f(x_n) - \min(f)) = 0.$

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