





Introduction to GPUs in HPC

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Concurrency

Concurrency

Concurrency is the ability to perform multiple CUDA operations simultaneously

- CUDA kernels
- copying from host to device
- copying from device to host
- operations on the host CPU

Concurrency enables

- both CPU and GPU can work at the same time
- multiple tasks can be run on GPU simultaneously
- overlapping of communication and computation





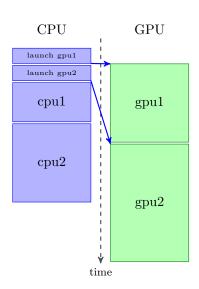
Host code kernel_1 <<< ... >>> (...); kernel_2 < < < . . . > >> (. . .); host_1(...); host_2(...);

The host:

- launches the two CUDA kernels
- then executes host calls sequentially

The GPU:

- executes asynchronously to host
- executes kernels sequentially





The CUDA language and runtime libraries provide mechanisms for coordinating asynchronous GPU execution:

- CUDA streams can concurrently run independent kernels and memory transfers;
- CUDA events can be used to synchronize streams and query the status of kernels and transfers.





Streams

A CUDA stream is a sequence of operations that execute in **issue order** on the GPU

 CUDA operations are kernels and copies between host and device memory spaces

Streams and concurrency

- operations in different streams may run concurrently
 - there have to be sufficient resources on the GPU (registers, shared memory, SMXs, etc)
- operations in the same stream are executed sequentially
- if no stream is specified, all kernels are launched in the default stream



Managing streams

A stream is represented using a cudaStream_t type

- cudaStreamCreate(cudaStream_t* s) and
 cudaStreamDestroy(cudaStream_t s) can be used to create and
 free CUDA streams respectively
- To launch a kernel on a stream specify the stream id as a fourth parameter to the launch syntax

```
kernel<<<grid_dim, block_dim, shared_size, stream>>>(...)
```

• the default CUDA stream is the NULL stream, or stream 0 (cudaStream_t is an integer)

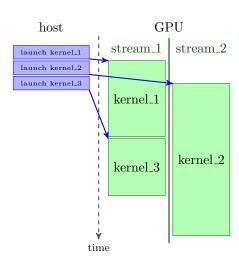
```
Basic cuda stream usage

// create stream
cudaStream_t stream;
cudaStreamCreate(&stream);
// launch kernel in stream
my_kernel << grid_dim, block_dim, shared_size, stream>>>(..)
// release stream when finished
cudaStreamDestroy(stream);
```



Host code kernel_1 <<< , , , stream_1 >>> (); kernel_2 <<< , , , stream_2 >>> (); kernel_3 <<< , , , stream_1 >>> ();

- kernel_1 and kernel_3 are serialized in stream_1
- kernel_2 can run asynchronously in stream_2
- note that kernel_2 will only run concurrently if there are sufficient resources available on the GPU, i.e. if kernel_1 is not using all of the SMXs.





Asynchronous copy

```
cudaMemcpyAsync(*dst, *src, size, kind, cudaStream_t stream = 0);
```

- Takes an additional parameter stream, which is 0 by default
- Returns immediately after initiating copy:
 - host can do work while copy is performed;
 - only if **pinned memory** is used.
- Copies in the same direction (i.e. H2D or D2H) are serialized
 - copies in opposite directions are concurrent if in different streams





Pinned memory

Pinned memory (or page-locked) memory will not be paged out to disk when memory runs low

- the GPU can safely remotely read/write the memory directly without host involvement
- only use for transfers, because it easy to run out of memory

```
Managing pinned memory
     cudaMallocHost(**ptr, size); and cudaFreeHost(*ptr);
```

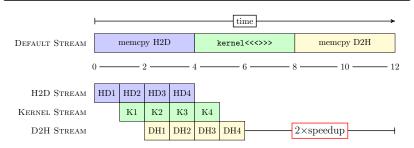
allocate and free pinned memory (size is in bytes).



Asynchronous copy example: streaming workloads

Computations that can be performed independently, e.g. our axpy example:

- data in host memory has to be copied to the device, and the result copied back after the kernel is computed.
- we can overlap the copies with the kernel calls by breaking the data into chunks.





CUDA events

To implement the streaming workload we have to coordinate operations on the GPU. CUDA events can be used for this purpose.

- synchronize tasks in different streams, e.g.:
 - don't start kernel in kernel stream until data copy stream has finished.
 - wait until required data has finished copy from host before launching kernel
- query status of concurrent tasks
 - has kernel finished/started yet?
 - how long did a kernel take to compute?





Managing events

```
cudaEventCreate(cudaEvent_t*); and cudaEventDestroy(cudaEvent_t);
 create and free cudaEvent_t
cudaEventRecord(cudaEvent_t, cudaStream_t);
```

enqueue an event in a stream

```
cudaEventSynchronize(cudaEvent_t);
```

make host execution wait for event to occur.

```
cudaEventQuery(cudaEvent_t)
```

• test if the work before an event in a queue has been completed

```
cudaEventElapsedTime(float*, cudaEvent_t, cudaEvent_t);
```

get time between two events



Using events to time kernel execution

```
cudaEvent t start. end:
cudaStream_t stream;
float time_taken;
// initialize the events and streams
cudaEventCreate(&start);
cudaEventCreate(&end);
cudaStreamCreate(&stream):
cudaEventRecord(start, stream); // enqueue start in stream
my_kernel <<< grid_dim, block_dim, 0, stream>>>();
cudaEventRecord(end, stream); // enqueue end in stream
cudaEventSynchronize(end);  // wait for end to be reached
cudaEventElapsedTime(&time_taken, start, end);
std::cout << "kernel took " << 1000*time_taken << " s\n";
// free resources for events and streams
cudaEventDestroy(start);
cudaEventDestroy(end);
cudaStreamDestrov(stream):
```



Copy→kernel synchronization

```
cudaEvent_t event;
cudaStream_t kernel_stream, h2d_stream;
size_t size = 100*sizeof(double);
double *dptr. *hptr:
// initialize
cudaEventCreate(&event):
cudaStreamCreate(&kernel stream):
cudaStreamCreate(&h2d_stream);
cudaMalloc(&dptr. size):
cudaMallocHost(&hptr, size); // use pinned memory!
// start asynchronous copy in h2d_stream
cudaMemcpyAsync(dptr, hptr, size,
                cudaMemcpyHostToDevice, h2d_stream);
// enqueue event in stream
cudaEventRecord(event, h2d stream):
// make kernel_stream wait for copy to finish
cudaStreamWaitEvent(kernel stream. event. 0):
// enqueue my_kernel to start when event has finished
my_kernel << grid_dim, block_dim, 0, kernel_stream>>>();
// free resources for events and streams
cudaEventDestroy(event);
cudaStreamDestroy(h2d_stream);
cudaStreamDestroy(kernel_stream);
cudaFree(dptr):
cudaFreeHost(hptr);
```



Exercises

1. Open include/util.hpp and understand

```
copy_to_{host/device}_async() and malloc_pinned_host()
```

- 2. Open include/cuda_event.h and include/cuda_stream.h
 - what is the purpose of these classes?
 - what does cuda_stream::enqueue_event() do?
- 3. Open async/memcopy1.cu and run
 - what does the benchmark test?
 - what is the effect of turning on USE_PINNED? Hint: try small and large values for n (8, 16, 20, 24)
- 4. Inspect async/memcopy2.cu and run
 - what effect does changing the number of chunks have?
- 5. Inspect async/memcopy3.cu and run
 - how does it differ from memcopy2.cu?
 - what effect does changing the number of chunks have?



Using events to time kernel execution: with helpers

```
CudaStream stream(true);
auto start = stream.enqueue_event();
my_kernel <<< grid_dim, block_dim, 0, stream.stream()>>>();
auto end = stream.enqueue event():
end.wait():
auto time_taken = end.time_since(start);
std::cout << "kernel took " << 1000*time taken << " s\n":
```

Copy—kernel synchronization: with helpers

```
CudaStream kernel_stream(true), h2d_stream(true);
auto size = 100:
auto dptr = device_malloc < double > (size);
auto hptr = pinned_malloc < double > (size);
copy_to_device_async < double > (hptr,dptr,size,h2d_stream.stream());
auto event = h2d_stream.enqueue_event();
kernel_stream.wait_on_event(event);
my_kernel << grid_dim, block_dim, 0, kernel_stream.stream()>>>();
cudaFree(dptr):
cudaFreeHost(hptr):
```





Rough guidelines for concurrency

Ideally for most workloads you don't want to rely on streams to fill the GPU with work

- a sign that the working set per GPU is not large enough
- full concurrency is difficult in practice
 - a low-level optimization strategy for the last few %
- this isn't a hard and fast rule

Streams come into their own for overlapping communication and computation

 possible to transfer data in both directions concurrently with kernel execution



