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References

- [1] Standardization Template
AUTOSAR_FO_TPS_StandardizationTemplate

1 Introduction

1.1 Scope of This Document

This document provides an overview of the AUTOSAR standard Classic Platform Release R23-11.

1.2 Terminology and Licenses

1.2.1 Terminology Statement

AUTOSAR has identified a use of previously common terminology that can be considered oppressive or racist, such as master/slave and black/white list, or in other contexts such as gender or age as harmful connotations. AUTOSAR has started a discussion with all the working groups to replace these terms. AUTOSAR is committed to provide all specification documents without these terminology in the coming and future releases. Nevertheless, it may take several releases before the terms are completely replaced, as AUTOSAR has to continue its operations and thousands of pages of existing specifications have to be reviewed and updated in parallel.

1.2.2 Usage of W3C XML Schema

The AUTOSAR XML Schema requires the XML namespace definition file `xml.xsd`.

There are several occurrences of the "xml.xsd" file within this release. For all occurrences the W3C license applies which can be found on <https://www.w3.org/Consortium/Legal/2015/copyright-software-and-document>.

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1.3 AUTOSAR Standards

1.3.1 Introduction

AUTOSAR addresses a wide range of use cases in automotive software development with its standards. These use cases have different requirements and lead to different technical solutions.

Packaging its deliverables into different "standards"

- eases the access to AUTOSAR solutions for users and
- allows AUTOSAR to scale with market needs.

1.3.2 Definition

An AUTOSAR standard is a consistent set of AUTOSAR deliverables, which are released at the same time. AUTOSAR deliverables can, but are not limited to be of the following kinds:

- textual explanations
- textual specifications
- test specifications
- source code
- other formal or semi-formal textual formats (e.g., ARXML, UML models, XML Schemata)

At the time of release, AUTOSAR ensures that dependencies are fulfilled.

1.3.3 Overview of AUTOSAR's Standards

AUTOSAR delivers the following standards:

| Standard | Abbreviation |
|-------------------|--------------|
| Adaptive Platform | AP |
| Classic Platform | CP |
| Foundation | FO |

1.3.3.1 Adaptive Platform

The Adaptive Platform is AUTOSAR's solution for high-performance computing ECUs to build safety-related systems for use cases such as highly automated and autonomous driving.

1.3.3.2 Classic Platform

The Classic Platform is AUTOSAR's solution for embedded systems with hard real-time and safety constraints.

1.3.3.3 Foundation

The purpose of the Foundation standard is to enforce interoperability between the AUTOSAR platforms.

Foundation contains the generic artifacts that are common for AP and CP to ensure compatibility between

- Classic- and Adaptive Platform
- Non-AUTOSAR platforms to AUTOSAR platforms

1.3.4 Naming Scheme for Files and Specification Items

AUTOSAR has extended the naming scheme for files and specification items. The objective is to consistently include the AUTOSAR Standard to which the file or specification item belongs in the name. This addition also provides namespaces for the three AUTOSAR Standards and avoids conflicting names for specifications on the same topic in different AUTOSAR Standards. According to the new naming scheme, the abbreviation of the AUTOSAR Standard (AP, CP or FO) is added as first part of specification item IDs and as second part of file names. For details, please refer to [\[1\]](#).

From R23-11 onwards, the names of all files that are part of the release follow the new naming scheme. The IDs of existing specification items are not changed to avoid issues and migrations for AUTOSAR Partners that use these IDs internally.

1.3.5 Dependencies Between Standards

Each release of Classic and Adaptive Platform relies on a dedicated version of Foundation. The specific dependency is documented in chapter [1.4.5](#).

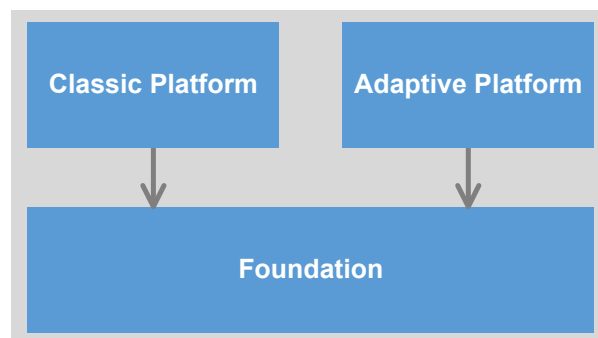


Figure 1.1: Dependencies of AUTOSAR standards

1.3.6 Dependencies to Other Standards

This release of the Classic Platform depends on the standard Foundation in release R23-11, which

- defines protocols implemented by Classic Platform
- contains the project objectives and the common requirements from which the features of the Classic Platform are derived
- contains common specification parts which apply to both, the Adaptive Platform and the Classic Platform.

These dependencies are refined in the trace information of the requirements in the respective specifications.

1.4 Release Numbering and Life Cycle

1.4.1 Release Life Cycle of a Major Release

Each major release goes through four consecutive steps within its life cycle (examples based on the internal release numbering scheme):

1. Development: Between start of life cycle and the initial release (e.g., R4.0.1)

2. Evolution: Following the initial release with zero, one or several minor releases and/or revisions (e.g., R4.0.2, R4.1.1)
3. Maintenance: No new content is added to a major release but only maintenance of the existing content with zero, one or several revisions (e.g., R3.2.2) is provided
4. Issue Notice: No more revisions but zero, one or several issue notices, i.e., updates of the list of known issues until end of life cycle.

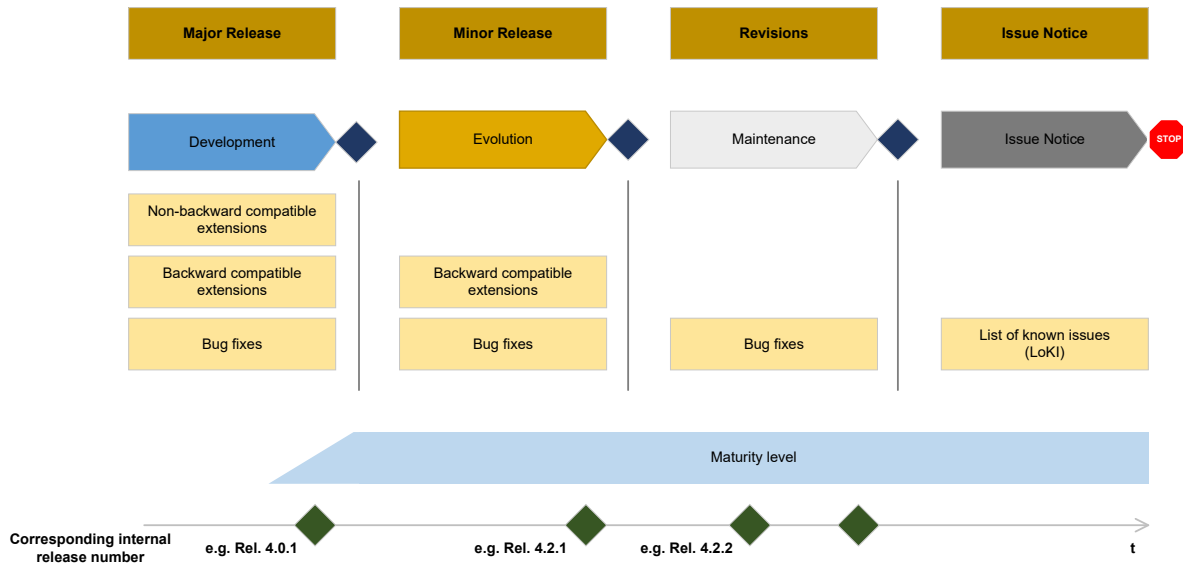


Figure 1.2: Life cycle model of AUTOSAR standards

1.4.2 Life Cycle States of Specification Items and Requirements

The life cycle state of a specification item is found after the specification item ID surrounded by curly brackets. The states are:

- {Valid}: This indicates that the related entity is a valid part of the document. This is the default and also applies if no dedicated life cycle status is annotated for the related entity.
- {Draft}: This indicates that the related entity is newly introduced but still experimental. This information is published but is subject to change without backward compatibility guarantee.
- {Obsolete}: This indicates that the related entity is subject to be removed in one of the following releases without further notice.

The life cycle state of a requirement is found in the attribute "type". The states are the same as the specification item states.

1.4.3 Platform Release Number

AUTOSAR applies a four-digit numbering scheme Ryy-mm to identify releases. The identifiers “yy” and “mm” depict the year and month of the release date, e.g., R20-11 for the November 2020 release.

1.4.4 Internal Release Number

AUTOSAR additionally maintains an internal release number for different purposes (e.g., usage in BSW modules in Classic Platform).

The internal release number is used for all platforms and follows up on the Classic Platform release number. In Adaptive Platform this is newly introduced. In Foundation this leads to a discontinuation of the former numbering pattern (e.g., R1.5.0).

A mapping list between Platform Releases and corresponding internal release numbers can be found in chapter [1.4.5](#). The internal release number uses a three-digit numbering scheme R<major>.<minor>.<revision> to identify releases. Its primary purpose is to identify a release as

- a major release: Valid and draft specification parts may be changed backward incompatibly.
- a minor release: Valid specification parts may only be changed backward compatibly. Draft specification parts may be changed backward incompatibly.
- a revision: Does not contain extensions but only backward compatible bugfixes.

1.4.5 Overview of AUTOSAR Releases and Corresponding AUTOSAR Schema Versions

Until the Releases CP R4.4.0 and AP R19-03, AUTOSAR released the platforms separately where a Foundation release went along with each platform release. Since compatibility between the platforms is essential to be able to have AP and CP ECUs within one vehicle project, an XML schema needs to be available that works with the different releases. The following table gives an overview about the different schema versions and the corresponding platform releases they can be used for.

The AUTOSAR schema does not have an impact on the Foundation. The Foundation releases are mentioned for the sake of completeness.

| Schema Version | Classic Platform release | Adaptive Platform release | Foundation release |
|----------------|--------------------------|---------------------------|--------------------|
| AUTOSAR_00042 | R4.3.0 | R17-03 | R1.1.0 |
| AUTOSAR_00043 | R4.3.0 | R17-10 | R1.2.0 |
| AUTOSAR_00044 | R4.3.1 | R17-10 | R1.3.0 |
| AUTOSAR_00045 | R4.3.1 | R18-03 | R1.4.0 |





| Schema Version | Classic Platform release | Adaptive Platform release | Foundation release |
|----------------|--------------------------|---------------------------|--------------------|
| AUTOSAR_00046 | R4.4.0 | R18-10 | R1.5.0 |
| AUTOSAR_00047 | R4.4.0 | R19-03 | R1.5.1 |

Starting with release R19-11, all platforms are released as one AUTOSAR release and therefore come along with one schema version.

| Schema Version | Platform release | Internal release number |
|----------------------|------------------|-------------------------|
| AUTOSAR_00048 | R19-11 | R4.5.0 |
| AUTOSAR_00049 | R20-11 | R4.6.0 |
| AUTOSAR_00050 | R21-11 | R4.7.0 |
| AUTOSAR_00051 | R22-11 | R4.8.0 |
| AUTOSAR_00052 | R23-11 | R4.9.0 |

According to the release life cycle of AUTOSAR the release R23-11 is a minor release.

1.5 Content of Chapters

This document is structured as follows:

- Chapter 1 introduces AUTOSAR's release strategy and its standardization approach.
- Chapter 2 provides a summary of changes since the previous release of the Classic Platform.
- Chapter 3 contains the overview of specifications comprising the AUTOSAR release R23-11. This chapter is structured according to the clusters of AUTOSAR release R23-11.
- Chapter 4 contains remarks about known technical deficiencies.
- Chapter 5 contains the detailed revision history of all released specifications.

2 Summary of Changes in Release R23-11

This chapter contains a summary of the changes that have been implemented since the previous release R22-11.

2.1 Concepts

2.1.1 Introduced Concepts

The following concepts in [2.1.1.1](#) - [2.1.1.7](#) have been introduced.

2.1.1.1 Charging Interface

Charging Interface: [CP] Support for ISO-15118-2:2014 standard focusses on wired AC_DC charging which will be controlled using the module ChrgM using a set of messages as defined in the standard ISO15118-2.

2.1.1.2 Secure SOME/IP-ACL

This concept introduces the possibility to limit the SOME/IP communication from only known permitted listed authenticated communication partners to specific service instance, so secured service instance can only be accessed (Offered, Subscribed or Consumed) by defined partners.

2.1.1.3 Firewall in Classic AUTOSAR

The concept introduces a firewall to inspect and filter Ethernet traffic based on predefined firewall rules. The firewall supports stateless packet inspection, stateful packet inspection and deep packet inspection as well as rate-based filtering of network packets. Furthermore, the firewall also supports the Intrusion Detection System by raising Security Events to the IdsM.

2.1.1.4 DDS Support on CP

DDS on CP – concept part 5 – adds the DDS configuration parameters into the system template model. The DDS configuration at SystemTemplate level shall be used to derive the EcuC configuration of the DDS Entities, e.g. DDS DomainParticipants, Publishers, Subscribers, DataWriters, DataReaders.

Besides a DDS EcuC model refactoring has been done in order to have a more readable model, and to add configuration of queues used to interact with PduRouter.

2.1.1.5 Deterministic Communication with TSN

The concept part "Support of PTP physical clock adjustment" focused to support accuracy for syntonization/synchronization of the local clock to master clock, which is required for time sensitive use cases in an Ethernet switched network. Therefore rate ratio calculation, support of multiple PTP hardware clocks and PTP hardware clock adjustment where introduced.

The concept part "Introduce IEEE 1722 related features handling of streams and tunneling legacy communication (CAN and LIN)" focused to support IEEE1722 streams. Therefore a new transport layer has been introduced which provide the possibility to use IEEE1722-2016 standardized transport protocol for time-sensitive applications in a bridged local area network on classic platform in AUTOSAR. The transport layer fully support processing of audio / video streams and distribution of a generated clock rate provided by so called media clock. The transport layer support encapsulation of bus frames (e.g. CAN frames) transported via AVTP stream across the network (a.k.a. tunneling of legacy communication). Please note: Lower layer needs to be extended to fully support transportation of encapsulation of bus frames via an AVTP stream. The Ethernet communication stack has been extended to support efficient data handling (e.g. hardware supported data transfer (e.g. DMA), direct data provision, configurable egress/ingress data processing), which are relevant for time-sensitive use cases.

2.1.1.6 Time Validation

The Time Validation for the AUTOSAR Classic Platform is to perform all. the checks that can be done locally within the ECU in order to verify that the local instance of the synchronized time is safe.

Basic Functions:

- The Time Validation Component monitors the synchronization process, itself.
- The Time Validation Component monitors the progress of the (local instance of) GlobalTime.
- The Time Validation Component makes the integrity status information of the timebase available to other Software Components.
- The Time Validation Component ensures continuous time progression of the validated time base after detected errors by providing a local fallback extrapolation.

2.1.1.7 Service Discovery Control for Application Software

The concept introduces a standardized application interface for controlling Service Discovery. It provides an interface between BswM and Application SwC and a generation of configurations for the existing rules and actionlists capabilities in BswM to control the Service Discovery behavior.

2.1.2 Impact of Concepts

The introduced concepts had impact on several specifications. The following table provides a detailed overview.

Please note that some of the specifications are marked by special text formatting:

- Specifications in **bold** font are completely new specifications originating from the particular concept.
- Specifications in *italic* font are affected indirectly as they provide artefacts for the actually impacted specifications.

| Concept Name | Specification Long Name | Standard | Concept Lifecycle |
|--|---|------------------|-------------------|
| Charging Interface | Layered Software Architecture | Classic Platform | draft |
| | Specification of Ethernet State Manager | | |
| | Specification of Socket Adaptor | | |
| | Specification of TCP/IP Stack | | |
| | List of Basic Software Modules | | |
| | Specification of Charging Manager | | |
| | Requirements on Charging Manager | | |
| Service Discovery Control for Application Software | Requirements on Mode Management | Classic Platform | draft |
| | Specification of Basic Software Mode Manager | | |
| | Guide to Mode Management | | |
| Time Validation | Specification of Synchronized Time-Base Manager | Classic Platform | draft |
| | Requirements on Time Synchronization | | |
| Secure SOME/IP-ACL | Main Requirements | Foundation | draft |
| | Standardized M1 Models used for the Definition of AUTOSAR | | |
| | System Template | Classic Platform | |





| Concept Name | Specification Long Name | Standard | Concept Lifecycle |
|--------------------------------------|---|------------------|-------------------|
| | Specification of Socket Adaptor | | |
| | Requirements on Ethernet Support in AUTOSAR | | |
| | Specification of Service Discovery | | |
| DDS Support on CP | Specification of Data Distribution Service for Classic Platform | Classic Platform | draft |
| | System Template | | |
| Deterministic Communication with TSN | Specification of Communication Stack Types | Classic Platform | draft |
| | Specification of Ethernet Interface | | |
| | Requirements on Ethernet Support in AUTOSAR | | |
| | Specification of Synchronized Time-Base Manager | | |
| | Specification of Ethernet Driver | | |
| | Specification of Time Synchronization over Ethernet | | |
| | Requirements on Gateway | | |
| | System Template | | |
| | Specification of ECU Configuration | | |
| | Requirements on System Template | | |
| | Specification of Ethernet Switch Driver | | |
| | Specification for CAN XL Driver | | |
| | List of Basic Software Modules | | |
| | Specification of IEEE1722 Transport Protocol Module | | |
| | Specification of Linklayer Sdu Routing Module | | |
| | Time Synchronization Protocol Specification | Foundation | |
| | Requirements on Time Synchronization | | |
| | Main Requirements | | |
| | Glossary | | |
| | Explanation of Time Sensitive Network features | | |
| | Requirements on IEEE1722 | | |
| Firewall in Classic AUTOSAR | Layered Software Architecture | Classic Platform | draft |
| | System Template | | |





| Concept Name | Specification Long Name | Standard | Concept Lifecycle |
|--------------|---|------------|-------------------|
| | List of Basic Software Modules | | |
| | Specification of Basic Software Mode Manager | | |
| | Specification of Ethernet Interface | | |
| | Specification of Ethernet Switch Driver | | |
| | Specification of Firewall for Classic Platform | | |
| | Standardized M1 Models used for the Definition of AUTOSAR | Foundation | |
| | Requirements on Firewall | | |

Table 2.1: Impact of concepts

2.1.3 Validated Concepts

The following concepts have been validated:

- Classic Platform Flexibility, only the R20-11 feature set of Classic Platform Flexibility has been validated

2.2 Specifications

2.2.1 New Specifications

The following new specifications have been introduced via concepts:

- Specification of Firewall for Classic Platform (UID 1084, SWS)
- Specification of IEEE1722 Transport Protocol Module (UID 1093, SWS)
- Specification of Linklayer Sdu Routing Module (UID 1094, SWS)
- Specification of Charging Manager (UID 1095, SWS)
- Requirements on Charging Manager (UID 1096, RS)

In addition to the above listed new specifications, the following documents have been added with R23-11:

- none

2.2.2 Migrated Specifications

With this release, the following specifications have been moved from AUTOSAR Classic Platform to the AUTOSAR Foundation standard:

- none

2.2.3 Obsolete Specifications

The following specifications have been set to status "obsolete" in this release:

- none

2.2.4 Removed Specifications

The following specifications have been set to status "removed" in this release and hence are not released anymore:

- Requirements on Free Running Timer (UID 211, SRS)
- Explanation of Interrupt Handling within AUTOSAR (UID 307, EXP)

2.2.5 Reworked Specifications

The following documents have been changed fundamentally in R23-11:

- none

2.2.6 Moved Specification Parts

The following specification parts have been moved to other documents in R23-11.

- none

2.3 Release Documentation

There are no major changes in the Release Documentation.

3 Specification Overview

The published specifications are divided into the clusters:

- Release Documentation
- Communication
- Memory
- System Services
- MCAL
- IO
- Libraries
- Diagnostics
- Safety
- BSW General
- General
- Methodology and Templates
- Mode Management
- RTE
- Application Interfaces
- Crypto
- Global Time
- SWArch
- Security

The assignment of the specifications to these clusters is shown below.

| Long Name | File Name | Life cycle changes |
|---|------------------------------------|--------------------|
| Release Documentation | | |
| Classic Platform Release Overview | AUTOSAR_CP_TR_ReleaseOverview | |
| AUTOSAR Classic Platform Specification Hashes | AUTOSAR_CP_TR_Specification Hashes | |
| Communication | | |
| General Specification of Transformers | AUTOSAR_CP_ASWS_TransformerGeneral | |
| Requirements on BSW Modules for SAE J1939 | AUTOSAR_CP_SRS_SAEJ1939 | |
| Requirements on Bus Mirroring | AUTOSAR_CP_SRS_BusMirroring | |





| Long Name | File Name | Life cycle changes |
|---|---|--------------------|
| Requirements on CAN | AUTOSAR_CP_SRS_CAN | |
| Requirements on Charging Manager | AUTOSAR_CP_RS_ChargingManager | Initial release |
| Requirements on Chinese Vehicle-2-X Communication | AUTOSAR_CP_SRS_ChineseV2XCommunication | |
| Requirements on Communication | AUTOSAR_CP_SRS_COM | |
| Requirements on Ethernet Support in AUTOSAR | AUTOSAR_CP_SRS_Ethernet | |
| Requirements on FlexRay | AUTOSAR_CP_SRS_FlexRay | |
| Requirements on Gateway | AUTOSAR_CP_SRS_Gateway | |
| Requirements on I-PDU Multiplexer | AUTOSAR_CP_SRS_IPDUMultiplexer | |
| Requirements on LIN | AUTOSAR_CP_SRS_LIN | |
| Requirements on Module XCP | AUTOSAR_CP_SRS_XCP | |
| Requirements on Secure Onboard Communication | AUTOSAR_CP_SRS_SecureOnboardCommunication | |
| Requirements on SPI Handler/Driver | AUTOSAR_CP_SRS_SPIHandlerDriver | |
| Requirements on Transformer | AUTOSAR_CP_SRS_Transformer | |
| Requirements on TTCAN | AUTOSAR_CP_SRS_TTCAN | |
| Requirements on Vehicle-2-X Communication | AUTOSAR_CP_SRS_V2XCommunication | |
| Specification for CAN XL Driver | AUTOSAR_CP_SWS_CANXLDriver | |
| Specification of a Request Manager for SAE J1939 | AUTOSAR_CP_SWS_SAEJ1939RequestManager | |
| Specification of a Transport Layer for SAE J1939 | AUTOSAR_CP_SWS_SAEJ1939TransportLayer | |
| Specification of Bus Mirroring | AUTOSAR_CP_SWS_BusMirroring | |
| Specification of CAN Driver | AUTOSAR_CP_SWS_CANDriver | |
| Specification of CAN Interface | AUTOSAR_CP_SWS_CANInterface | |
| Specification of CAN Network Management | AUTOSAR_CP_SWS_CANNetworkManagement | |
| Specification of CAN State Manager | AUTOSAR_CP_SWS_CANStateManager | |
| Specification of CAN Transceiver Driver | AUTOSAR_CP_SWS_CANTransceiverDriver | |
| Specification of CAN Transport Layer | AUTOSAR_CP_SWS_CANTransportLayer | |
| Specification of CAN XL Transceiver Driver | AUTOSAR_CP_SWS_CANXLTransceiverDriver | |
| Specification of Cellular Vehicle-2-X Driver | AUTOSAR_CP_SWS_CellularV2XDriver | |
| Specification of Charging Manager | AUTOSAR_CP_SWS_ChargingManager | Initial release |
| Specification of Chinese Vehicle-2-X Management | AUTOSAR_CP_SWS_ChineseV2XManagement | |
| Specification of Chinese Vehicle-2-X Message | AUTOSAR_CP_SWS_ChineseV2XMessage | |
| Specification of Chinese Vehicle-2-X Network | AUTOSAR_CP_SWS_ChineseV2XNetwork | |
| Specification of Chinese Vehicle-2-X Security | AUTOSAR_CP_SWS_ChineseV2XSecurity | |
| Specification of COM Based Transformer | AUTOSAR_CP_SWS_COMBasedTransformer | |





| Long Name | File Name | Life cycle changes |
|---|---|--------------------|
| Specification of Communication | AUTOSAR_CP_SWS_COM | |
| Specification of Data Distribution Service for Classic Platform | AUTOSAR_CP_SWS_DataDistributionService | |
| Specification of Diagnostic Log and Trace | AUTOSAR_CP_SWS_DiagnosticLogAndTrace | |
| Specification of Diagnostic over IP | AUTOSAR_CP_SWS_DiagnosticOverIP | |
| Specification of Ethernet Driver | AUTOSAR_CP_SWS_EthernetDriver | |
| Specification of Ethernet Interface | AUTOSAR_CP_SWS_EthernetInterface | |
| Specification of Ethernet State Manager | AUTOSAR_CP_SWS_EthernetStateManager | |
| Specification of Ethernet Switch Driver | AUTOSAR_CP_SWS_EthernetSwitchDriver | |
| Specification of Ethernet Transceiver Driver | AUTOSAR_CP_SWS_EthernetTransceiverDriver | |
| Specification of FlexRay AUTOSAR Transport Layer | AUTOSAR_CP_SWS_FlexRayARTransportLayer | |
| Specification of FlexRay Driver | AUTOSAR_CP_SWS_FlexRayDriver | |
| Specification of FlexRay Interface | AUTOSAR_CP_SWS_FlexRayInterface | |
| Specification of FlexRay ISO Transport Layer | AUTOSAR_CP_SWS_FlexRayISOTransportLayer | |
| Specification of FlexRay Network Management | AUTOSAR_CP_SWS_FlexRayNetworkManagement | |
| Specification of FlexRay State Manager | AUTOSAR_CP_SWS_FlexRayStateManager | |
| Specification of FlexRay Transceiver Driver | AUTOSAR_CP_SWS_FlexRayTransceiverDriver | |
| Specification of IEEE1722 Transport Protocol Module | AUTOSAR_CP_SWS_IEEE1722TransportLayer | Initial release |
| Specification of I-PDU Multiplexer | AUTOSAR_CP_SWS_IPDUMultiplexer | |
| Specification of Large Data COM | AUTOSAR_CP_SWS_LargeDataCOM | |
| Specification of LIN Driver | AUTOSAR_CP_SWS_LINDriver | |
| Specification of LIN Interface | AUTOSAR_CP_SWS_LINInterface | |
| Specification of LIN State Manager | AUTOSAR_CP_SWS_LINStateManager | |
| Specification of LIN Transceiver Driver | AUTOSAR_CP_SWS_LINTransceiverDriver | |
| Specification of Linklayer Sdu Routing Module | AUTOSAR_CP_SWS_LSduRouter | Initial release |
| Specification of MACsec Key Agreement | AUTOSAR_CP_SWS_MACsecKeyAgreement | |
| Specification of Module E2E Transformer | AUTOSAR_CP_SWS_E2ETransformer | |
| Specification of Module XCP | AUTOSAR_CP_SWS_XCP | |
| Specification of Network Management for SAE J1939 | AUTOSAR_CP_SWS_SAEJ1939NetworkManagement | |
| Specification of Network Management Interface | AUTOSAR_CP_SWS_NetworkManagementInterface | |
| Specification of PDU Router | AUTOSAR_CP_SWS_PDURouter | |





| Long Name | File Name | Life cycle changes |
|---|--|--------------------|
| Specification of Secure Onboard Communication | AUTOSAR_CP_SWS_SecureOnboardCommunication | |
| Specification of Service Discovery | AUTOSAR_CP_SWS_ServiceDiscovery | |
| Specification of Socket Adaptor | AUTOSAR_CP_SWS_SocketAdaptor | |
| Specification of SOME/IP Transformer | AUTOSAR_CP_SWS_SOMEIPTransformer | |
| Specification of SPI Handler/Driver | AUTOSAR_CP_SWS_SPIHandlerDriver | |
| Specification of TCP/IP Stack | AUTOSAR_CP_SWS_Tcplp | |
| Specification of TTCAN Driver | AUTOSAR_CP_SWS_TTCANDriver | |
| Specification of TTCAN Interface | AUTOSAR_CP_SWS_TTCANInterface | |
| Specification of UDP Network Management | AUTOSAR_CP_SWS_UDPNetworkManagement | |
| Specification of Vehicle-2-X Basic Transport | AUTOSAR_CP_SWS_V2XBasicTransport | |
| Specification of Vehicle-2-X Data Manager | AUTOSAR_CP_SWS_V2XDataManager | |
| Specification of Vehicle-2-X Facilities | AUTOSAR_CP_SWS_V2XFacilities | |
| Specification of Vehicle-2-X Geo Networking | AUTOSAR_CP_SWS_V2XGeoNetworking | |
| Specification of Vehicle-2-X Management | AUTOSAR_CP_SWS_V2XManagement | |
| Specification of Wireless Ethernet Driver | AUTOSAR_CP_SWS_WirelessEthernetDriver | |
| Specification of Wireless Ethernet Transceiver Driver | AUTOSAR_CP_SWS_WirelessEthernetTransceiverDriver | |
| Specification on SOME/IP Transport Protocol | AUTOSAR_CP_SWS_SOMEIPTransportProtocol | |
| Memory | | |
| Explanation of Firmware Over-The-Air | AUTOSAR_CP_EXP_FirmwareOverTheAir | |
| NV Data Handling Guideline | AUTOSAR_CP_EXP_NVDataHandling | |
| Requirements on EEPROM Driver | AUTOSAR_CP_SRS_EEPROMDriver | |
| Requirements on Firmware Over-The-Air | AUTOSAR_CP_RS_FirmwareOverTheAir | |
| Requirements on Flash Driver | AUTOSAR_CP_SRS_FlashDriver | |
| Requirements on Flash Test | AUTOSAR_CP_SRS_FlashTest | |
| Requirements on Memory Hardware Abstraction Layer | AUTOSAR_CP_SRS_MemoryHWAbstractionLayer | |
| Requirements on Memory Services | AUTOSAR_CP_SRS_MemoryServices | |
| Requirements on RAM Test | AUTOSAR_CP_SRS_RAMTest | |
| Specification of EEPROM Abstraction | AUTOSAR_CP_SWS_EEPROMAbstraction | |
| Specification of EEPROM Driver | AUTOSAR_CP_SWS_EEPROMDriver | |
| Specification of Flash Driver | AUTOSAR_CP_SWS_FlashDriver | |
| Specification of Flash EEPROM Emulation | AUTOSAR_CP_SWS_FlashEEPROMEmulation | |
| Specification of Flash Test | AUTOSAR_CP_SWS_FlashTest | |
| Specification of Memory Abstraction Interface | AUTOSAR_CP_SWS_MemoryAbstractionInterface | |





| Long Name | File Name | Life cycle changes |
|---|---|--------------------|
| Specification of Memory Access | AUTOSAR_CP_SWS_MemoryAccess | |
| Specification of Memory Driver | AUTOSAR_CP_SWS_MemoryDriver | |
| Specification of Memory Mapping | AUTOSAR_CP_SWS_MemoryMapping | |
| Specification of NVRAM Manager | AUTOSAR_CP_SWS_NVRAMManager | |
| Specification of RAM Test | AUTOSAR_CP_SWS_RAMTest | |
| System Services | | |
| Explanation of Software Cluster Design And Integration Guideline for Classic Platform | AUTOSAR_CP_EXP_SwClusterDesignAndIntegrationGuideline | |
| Requirements on Function Inhibition Manager | AUTOSAR_CP_SRS_FunctionInhibitionManager | |
| Requirements on Hardware Test Manager on start up and shutdown | AUTOSAR_CP_SRS_HWTestManager | |
| Requirements on Operating System | AUTOSAR_CP_SRS_OS | |
| Requirements on Software Cluster Connection module | AUTOSAR_CP_SRS_SoftwareClusterConnection | |
| Requirements on Time Service | AUTOSAR_CP_SRS_TimeService | |
| Specification and Integration of Hardware Test Management at start up and shutdown | AUTOSAR_CP_TR_HWTestManagementIntegrationGuide | |
| Specification of Communication Manager | AUTOSAR_CP_SWS_COMManager | |
| Specification of Default Error Tracer | AUTOSAR_CP_SWS_DefaultErrorTracer | |
| Specification of Function Inhibition Manager | AUTOSAR_CP_SWS_FunctionInhibitionManager | |
| Specification of Hardware Test Manager on start up and shutdown | AUTOSAR_CP_SWS_HWTestManager | |
| Specification of Operating System | AUTOSAR_CP_SWS_OS | |
| Specification of Software Cluster Connection module | AUTOSAR_CP_SWS_SoftwareClusterConnection | |
| Specification of Time Service | AUTOSAR_CP_SWS_TimeService | |
| MCAL | | |
| General Requirements on SPAL | AUTOSAR_CP_SRS_SPALGeneral | |
| Requirements on Core Test | AUTOSAR_CP_SRS_CoreTest | |
| Requirements on GPT Driver | AUTOSAR_CP_SRS_GPTDriver | |
| Requirements on MCU Driver | AUTOSAR_CP_SRS_MCUDriver | |
| Specification of Core Test | AUTOSAR_CP_SWS_CoreTest | |
| Specification of GPT Driver | AUTOSAR_CP_SWS_GPTDriver | |
| Specification of MCU Driver | AUTOSAR_CP_SWS_MCUDriver | |
| IO | | |
| Requirements on ADC Driver | AUTOSAR_CP_SRS_ADCTDriver | |
| Requirements on DIO Driver | AUTOSAR_CP_SRS_DIODriver | |
| Requirements on I/O Hardware Abstraction | AUTOSAR_CP_SRS_IOHWAbstraction | |
| Requirements on ICU Driver | AUTOSAR_CP_SRS_ICUDriver | |
| Requirements on OCU Driver | AUTOSAR_CP_SRS_OCUDriver | |
| Requirements on Port Driver | AUTOSAR_CP_SRS_PortDriver | |





| Long Name | File Name | Life cycle changes |
|---|---|--------------------|
| Requirements on PWM Driver | AUTOSAR_CP_SRS_PWMDriver | |
| Specification of ADC Driver | AUTOSAR_CP_SWS_ADCCDriver | |
| Specification of DIO Driver | AUTOSAR_CP_SWS_DIODriver | |
| Specification of I/O Hardware Abstraction | AUTOSAR_CP_SWS_IOHardwareAbstraction | |
| Specification of ICU Driver | AUTOSAR_CP_SWS_ICUDriver | |
| Specification of OCU Driver | AUTOSAR_CP_SWS_OCUDriver | |
| Specification of Port Driver | AUTOSAR_CP_SWS_PortDriver | |
| Specification of PWM Driver | AUTOSAR_CP_SWS_PWMDriver | |
| Libraries | | |
| Macro Encapsulation of Interpolation Calls | AUTOSAR_CP_EXP_MacroEncapsulationofInterpolationCalls | |
| Requirements on Libraries | AUTOSAR_CP_SRS_Libraries | |
| Specification of Basic Software Multicore Library | AUTOSAR_CP_SWS_BSWMulticoreLibrary | |
| Specification of Bit Handling Routines | AUTOSAR_CP_SWS_BFXLibrary | |
| Specification of CRC Routines | AUTOSAR_CP_SWS_CRCLibrary | |
| Specification of Extended Fixed Point Routines | AUTOSAR_CP_SWS_EFXLibrary | |
| Specification of Fixed Point Interpolation Routines | AUTOSAR_CP_SWS_IFXLibrary | |
| Specification of Fixed Point Math Routines | AUTOSAR_CP_SWS_MFXLibrary | |
| Specification of Floating Point Interpolation Routines | AUTOSAR_CP_SWS_IFLLibrary | |
| Specification of Floating Point Math Routines | AUTOSAR_CP_SWS_MFLLibrary | |
| Specification of SW-C End-to-End Communication Protection Library | AUTOSAR_CP_SWS_E2ELibrary | |
| Diagnostics | | |
| Specification of a Diagnostic Communication Manager for SAE J1939 | AUTOSAR_CP_SWS_SAEJ1939DiagnosticCommunicationManager | |
| Specification of Diagnostic Communication Manager | AUTOSAR_CP_SWS_DiagnosticCommunicationManager | |
| Specification of Diagnostic Event Manager | AUTOSAR_CP_SWS_DiagnosticEventManager | |
| Safety | | |
| Overview of Functional Safety Measures in AUTOSAR | AUTOSAR_CP_EXP_FunctionalSafetyMeasures | |
| Requirements on Watchdog Driver | AUTOSAR_CP_SRS_WatchdogDriver | |
| Safety Use Case Example | AUTOSAR_CP_EXP_SafetyUseCase | |
| Specification of Watchdog Driver | AUTOSAR_CP_SWS_WatchdogDriver | |
| Specification of Watchdog Interface | AUTOSAR_CP_SWS_WatchdogInterface | |
| Specification of Watchdog Manager | AUTOSAR_CP_SWS_WatchdogManager | |
| BSW General | | |
| Basic Software UML Model | AUTOSAR_CP_MOD_BSWUMLModel | |
| Complex Driver design and integration guideline | AUTOSAR_CP_EXP_CDDDesignAndIntegrationGuideline | |





| Long Name | File Name | Life cycle changes |
|--|--|--------------------|
| Description of the AUTOSAR standard errors | AUTOSAR_CP_EXP_ErrorDescription | |
| Explanation of Error Handling on Application Level | AUTOSAR_CP_EXP_ApplicationLevelErrorHandling | |
| General Requirements on Basic Software Modules | AUTOSAR_CP_SRS_BSWGeneral | |
| General Specification of Basic Software Modules | AUTOSAR_CP_SWS_BSWGeneral | |
| Guide to BSW Distribution | AUTOSAR_CP_EXP_BSWDistributionGuide | |
| List of Basic Software Modules | AUTOSAR_CP_TR_BSWModuleList | |
| Modeling Guidelines of Basic Software EA UML Model | AUTOSAR_CP_TR_BSWUMLModelModelingGuide | |
| Specification of Communication Stack Types | AUTOSAR_CP_SWS_CommunicationStackTypes | |
| Specification of Platform Types for Classic Platform | AUTOSAR_CP_SWS_PlatformTypes | |
| Specification of Standard Types | AUTOSAR_CP_SWS_StandardTypes | |
| General | | |
| Layered Software Architecture | AUTOSAR_CP_EXP_LayeredSoftwareArchitecture | |
| Requirements on AUTOSAR Features | AUTOSAR_CP_RS_Features | obsolete |
| Specification of Bulk NvData Manager | AUTOSAR_CP_SWS_BulkNvDataManager | |
| Virtual Functional Bus | AUTOSAR_CP_EXP_VFB | |
| Methodology and Templates | | |
| Basic Software Module Description Template | AUTOSAR_CP_TPS_BSWModuleDescriptionTemplate | |
| Diagnostic Extract Template | AUTOSAR_CP_TPS_DiagnosticExtractTemplate | |
| Integration of Franca IDL Software Component Descriptions | AUTOSAR_CP_TR_FrancaIntegration | |
| Methodology for Classic Platform | AUTOSAR_CP_TR_Methodology | |
| Modeling Show Cases Examples | AUTOSAR_CP_EXP_ModelingShowCases | |
| Modeling Show Cases Report | AUTOSAR_CP_TR_ModelingShowCases | |
| Requirements on Basic Software Module Description Template | AUTOSAR_CP_RS_BSWModuleDescriptionTemplate | |
| Requirements on Diagnostic Extract Template | AUTOSAR_CP_RS_DiagnosticExtractTemplate | |
| Requirements on ECU Configuration | AUTOSAR_CP_RS_ECUConfiguration | |
| Requirements on ECU Resource Template | AUTOSAR_CP_RS_ECUConfiguration | |
| Requirements on Software Component Template | AUTOSAR_CP_RS_SoftwareComponentTemplate | |
| Requirements on System Template | AUTOSAR_CP_RS_SystemTemplate | |
| Software Component Template | AUTOSAR_CP_TPS_SoftwareComponentTemplate | |
| Specification of ECU Configuration | AUTOSAR_CP_TPS_ECUConfiguration | |





| Long Name | File Name | Life cycle changes |
|---|---|--------------------|
| Specification of ECU Configuration Parameters (XML) | AUTOSAR_CP_MOD_ECUConfigurationParameters | |
| Specification of ECU Resource Template | AUTOSAR_CP_TPS_ECUResourceTemplate | |
| Specification of Timing Extensions for Classic Platform | AUTOSAR_CP_TPS_TimingExtensions | |
| Supplementary material of general blueprints for AUTOSAR | AUTOSAR_CP_TR_GeneralBlueprintsSupplement | |
| System Template | AUTOSAR_CP_TPS_SystemTemplate | |
| Mode Management | | |
| Guide to Mode Management | AUTOSAR_CP_EXP_ModeManagementGuide | |
| Requirements on Mode Management | AUTOSAR_CP_SRS_ModeManagement | |
| Specification of Basic Software Mode Manager | AUTOSAR_CP_SWS_BSWModeManager | |
| Specification of ECU State Manager | AUTOSAR_CP_SWS_ECUSTateManager | |
| RTE | | |
| Requirements on Runtime Environment | AUTOSAR_CP_SRS_RTE | |
| Specification of RTE Software | AUTOSAR_CP_SWS_RTE | |
| Application Interfaces | | |
| Application Design Patterns Catalogue | AUTOSAR_CP_TR_AIDesignPatternsCatalogue | |
| Application Interface Examples | AUTOSAR_CP_MOD_AISpecificationExamples | |
| Application Interfaces User Guide | AUTOSAR_CP_EXP_AIUserGuide | |
| Explanation of Application Interface of AD/ADAS vehicle motion control | AUTOSAR_CP_EXP_AIADASAndVMC | |
| Explanation of Application Interfaces of Occupant and Pedestrian Safety Systems Domain | AUTOSAR_CP_EXP_AIOccupantAndPedestrianSafety | |
| Explanation of Application Interfaces of the Body and Comfort Domain | AUTOSAR_CP_EXP_AIBodyAndComfort | |
| Explanation of Application Interfaces of the Chassis Domain | AUTOSAR_CP_EXP_AIChassis | |
| Explanation of Application Interfaces of the HMI, Multimedia and Telematics Domain | AUTOSAR_CP_EXP_AIHMIMultimediaAndTelematics | |
| Explanation of Application Interfaces of the Powertrain Engine Domain | AUTOSAR_CP_EXP_AIPowertrain | |
| Requirements on SW-C and System Modeling | AUTOSAR_CP_RS_SWCModeling | |
| SW-C and System Modeling Guide | AUTOSAR_CP_TR_SWCModelingGuide | |
| Unique Names for Documentation, Measurement and Calibration: Modeling and Naming Aspects including Automatic Generation | AUTOSAR_CP_TR_AIMeasurementCalibrationDiagnostics | |
| XML Specification of Application Interfaces | AUTOSAR_CP_MOD_AISpecification | |
| Crypto | | |





| Long Name | File Name | Life cycle changes |
|--|--|--------------------|
| Requirements on Crypto Stack | AUTOSAR_CP_SRS_CryptoStack | |
| Specification of Crypto Driver | AUTOSAR_CP_SWS_CryptoDriver | |
| Specification of Crypto Interface | AUTOSAR_CP_SWS_CryptoInterface | |
| Specification of Crypto Service Manager | AUTOSAR_CP_SWS_CryptoServiceManager | |
| Specification of Key Manager | AUTOSAR_CP_SWS_KeyManager | |
| Utilization of Crypto Services | AUTOSAR_CP_EXP_UtilizationOfCryptoServices | |
| Global Time | | |
| Specification of Synchronized Time-Base Manager | AUTOSAR_CP_SWS_SynchronizedTimeBaseManager | |
| Specification of Time Synchronization over CAN | AUTOSAR_CP_SWS_TimeSyncOverCAN | |
| Specification of Time Synchronization over Ethernet | AUTOSAR_CP_SWS_TimeSyncOverEthernet | |
| Specification of Time Synchronization over FlexRay | AUTOSAR_CP_SWS_TimeSyncOverFlexRay | |
| SWArch | | |
| Explanatory Document for usage of AUTOSAR RunTimeInterface | AUTOSAR_CP_EXP_ARTI | |
| Requirements on Debugging, Tracing and Profiling support of AUTOSAR Components | AUTOSAR_CP_RS_DebugTraceProfile | |
| Specification of AUTOSAR Run-Time Interface | AUTOSAR_CP_SWS_ARTI | |
| Security | | |
| Specification of Firewall for Classic Platform | AUTOSAR_CP_SWS_Firewall | Initial release |
| Specification of Intrusion Detection System Manager | AUTOSAR_CP_SWS_IntrusionDetectionSystemManager | |

Table 3.1: Specification overview

4 Remarks to Known Technical Deficiencies

The technical deficiencies per specification are – if applicable – mentioned inside the respective specification in a chapter “Known Limitations” located after the table of contents.

The following technical deficiencies are to be mentioned, where clicking on the section reference will bring you to the respective document:

| Document UID | Long Name | Document Type | Section Reference |
|--------------|---|---------------|----------------------|
| 873 | Specification of Bus Mirroring | SWS | 4.1 |
| 795 | Specification of Vehicle-2-X Facilities | SWS | 4.2 |
| 612 | Specification of Network Management for SAE J1939 | SWS | 4.3 |
| 611 | Specification of a Request Manager for SAE J1939 | SWS | 4.4 |
| 610 | Specification of a Diagnostic Communication Manager for SAE J1939 | SWS | 4.5 |
| 425 | Specification of a Transport Layer for SAE J1939 | SWS | 4.6 |
| 414 | Specification of UDP Network Management | SWS | 4.7 |
| 80 | Specification of Watchdog Manager | SWS | 4.8 |
| 74 | Specification of FlexRay Transceiver Driver | SWS | 4.9 |
| 73 | Specification of LIN Interface | SWS | 4.10 |
| 42 | Requirements on LIN | SRS | 4.11 |
| 37 | Specification of PWM Driver | SWS | 4.12 |
| 182 | Specification of I-PDU Multiplexer | SWS | 4.13 |
| 11 | Specification of CAN Driver | SWS | 4.14 |
| 255 | Specification of LIN State Manager | SWS | 4.15 |
| 1093 | Specification of IEEE1722 Transport Protocol Module | SWS | 4.16 |
| 1094 | Specification of Linklayer Sdu Routing Module | SWS | 4.17 |

Table 4.1: Overview of known technical deficiencies

4.1 Specification of Bus Mirroring (UID 873 SWS)

- The Bus Mirroring module cannot be used to influence the traffic on one of the buses configured as a source bus. To ensure this and to avoid loop-back of messages leading to bus overload, the generation tool shall ensure that no bus is connected to the Bus Mirroring module both as source and destination bus (see [SWS_Mirror_00001]).
- The Bus Mirroring module is controlled by a diagnostic control application through the dedicated (service) API listed in chapter 8. The control functionality is made accessible to a diagnostic tester by special diagnostic services, which are handled by the DCM and implemented by the diagnostic control application. The DCM provides the necessary security to exclude inadvertent activation of the Bus Mirroring. The Bus Mirroring module does not provide another control interface, and it does not receive control messages on the destination bus.

- In general, the Bus Mirroring module does not support source buses that have a larger frame size or more additional information than the destination bus can carry, e.g. CAN XL to CAN-FD, CAN-FD to CAN, CAN to LIN, FlexRay to CAN, Ethernet to CAN, or Ethernet to FlexRay. The Bus Mirroring module does not fragment mirrored frames.
- The Bus Mirroring module will only mirror traffic that is actually received or transmitted by the bus interface modules. For CAN this means that besides the transmitted frames only those data frames that pass the hardware filter will be mirrored, and that remote frames and error frames will not be mirrored. For LIN, slave-to-slave communication will not be mirrored by a LIN master. And for FlexRay, only transmitted frames and those received frames for which reception buffers are assigned (possibly as a FIFO) will be mirrored.
- Another limitation of the mirroring from a FlexRay source bus concerns the reported time stamps and cycles. The Timestamp reported for a FlexRay frame contains the time when the corresponding job list entry was executed. The actual transmission time has to be calculated from the slot ID contained in the reported FrameID. The cycle contained in the reported FrameID is accurate only for received frames and frames transmitted in the static segment. For frames transmitted in the dynamic segment, the reported cycle can be inaccurate because it can happen that a frame cannot be transmitted in the expected cycle, it is then deferred to the next suitable cycle.
- A re-serialization of received serialized frames shall not be done by the Bus Mirroring module, because that would require too much resources. Instead, the serialized PDUs shall be routed directly to the destination bus.
- The Bus Mirroring module will also not support the forwarding from Ethernet to Ethernet. This use case is already covered by the Port Mirroring feature of the AUTOSAR Ethernet Switch Driver.

4.2 Specification of Vehicle-2-X Facilities (UID 795 SWS)

There are currently 80 errors. These errors appeared after the “no new AR” deadline.

These problems exist since R21-11 when we introduced the V2X Data Manager (DM) component in the V2X architecture and were not noticed thanks to the tooling because the document was a Word document.

Thirteen errors could be fixed because they corresponds to features and service API that are not any more performed by the Facilities layer but the V2X DM:

- V2xFac_IviS_MainFunction
- V2xFac_RItS_MainFunction
- V2xFac_TImS_MainFunction

- V2xFac_Port_V2xFac_V2xApplRxIndication_CAM
- V2xFac_Port_V2xFac_V2xApplRxIndication_DENM
- V2xFac_Port_V2xFac_V2xApplRxIndication_IVIM
- V2xFac_Port_V2xFac_V2xApplRxIndication_MAPEM
- V2xFac_Port_V2xFac_V2xApplRxIndication_SPATEM
- V2xFac_SenderReceiverInterface_V2xApplRxIndicationCam
- V2xFac_SenderReceiverInterface_V2xApplRxIndicationDenm
- V2xFac_SenderReceiverInterface_V2xApplRxIndicationIvim
- V2xFac_SenderReceiverInterface_V2xApplRxIndicationMapem
- V2xFac_SenderReceiverInterface_V2xApplRxIndicationSpatem

These can be removed safely. AR for R24-11 created: AR-122239

The 67 other errors correspond to data types. This is linked to an overengineered API with the VDP that was forgotten. This must be reworked. Following the recommendation from Friedebert, I added a comment in the document to precise that the API must be reworked and I created an AR for R24-11 AR-122237.

4.3 Specification of Network Management for SAE J1939 (UID 612 SWS)

The J1939 Network Management module does not support all features defined in SAE J1939-81, especially:

- Changing the address of a node after reception of CommandedAddress or after an address loss.
- Changing the NAME of a node using the Name Management protocol.
- Detection of address violations by messages other than AddressClaimed.

4.4 Specification of a Request Manager for SAE J1939 (UID 611 SWS)

The J1939 Request Manager only implements Request, Request2, and Acknowledgement PGs. It does not provide support for the Transfer PG.

4.5 Specification of a Diagnostic Communication Manager for SAE J1939 (UID 610 SWS)

- The J1939 Diagnostic Communication Manager implements only the subset of “Diagnostic Messages” defined in Table 7.1.
- The DM13 does not support “Suspend Signal” and “Suspend Duration”.
- NACK is not provided for received DMx messages that are not supported or not configured. This restriction mainly affects handling of DM07 and DM13.

4.6 Specification of a Transport Layer for SAE J1939 (UID 425 SWS)

- The AUTOSAR architecture contains several communication system specific transport layers (J1939Tp, CanTp, FrTp, etc.). All of these modules need to have identical APIs, with the exception of API functions for which the PduR has separate configuration abilities.
- The J1939Tp module does not implement the TriggerTransmit API, because it is only needed for time triggered bus architectures.

4.7 Specification of UDP Network Management (UID 414 SWS)

- One instance of UdpNm is associated with only one NM-Cluster in one network. One NM-Cluster can have only one instance of UdpNm in one node.
- One instance of UdpNm is associated with only one network within the same ECU.
- UdpNm is only applicable for TCP/IP based systems.

Figure 4.1 presents an AUTOSAR NM stack within an example ECU belonging to two UDP NM-clusters.

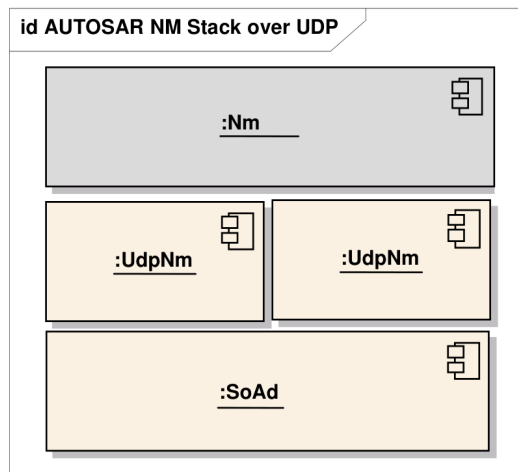


Figure 4.1: AUTOSAR NM stack within an example ECU belonging to two UDP NM-clusters

4.8 Specification of Watchdog Manager (UID 80 SWS)

- There're limitations for the Watchdog Manager module (WdgM). For details, see chap. 4 of CP SWS WdgM.
- Uptraces: AUTOSAR Foundation documents related to Health Monitoring (which are to be applicable to both AP PHM and CP WdgM) are not referred yet. Planned to make full updates (incl. uptraces to inappropriate documents such as CP SRS MemHwAb).
- Behavior of MainFunction-based Supervision Algorithms (Alive, Timeout part of Deadline) right after Mode Switch (incl. right after calling WdgM_Init) and resulting updates of the states (Local Supervision Status and Global Supervision Status) requires further clarification.
- Statemachine of Global Supervision Status: Transition numbers in parenthesis such as "(5)" have been broken since R21-11 by some trouble during updating the BSW UML model. Not fixed at R23-11, as the model wasn't updated and the figure is automatically generated one.

4.9 Specification of FlexRay Transceiver Driver (UID 74 SWS)

- The FlexRay Transceiver must provide functionality and an interface, mapped to the operation mode model assumed for the AUTOSAR FlexRay Transceiver Driver. See 7.1 AUTOSAR FlexRay Transceiver Operation Modes.

[SWS_FrTrcv_00231] dThe FlexRay Transceiver Driver shall use the APIs of underlying DIO drivers synchronously.c(SRS_Fr_05138)

[SWS_FrTrcv_00433] dThe FlexRay Transceiver Driver should use the APIs of underlying SPI drivers synchronously if possible and asynchronously where required.c()

[SWS_FrTrcv_00441] dThe FlexRay transceiver requires a LEVEL 2, Enhanced (Synchronous/Asynchronous) SPI Handler/Driverc()

[SWS_FrTrcv_00238] dThe FlexRay Transceiver Driver shall handle the transceiverspecific timing requirements internally.c(SRS_Fr_05152)

The communication between the C and the transceiver is performed via ports or SPI or both. If ports are used, applying values in a predefined sequence and with a given timing to the ports are used to communicate and change the hardware operation modes. These sequences and timings must be handled within the FlexRay Transceiver

4.10 Specification of LIN Interface (UID 73 SWS)

- There're limitations for the LIN Interface module (LinIf incl. LinTp submodule). For details, see chap. 4 of CP SWS LinIf.
- For LIN Slave (introduced at R4.4.0)
 - LIN stack control path (by LinIf, LinSM and ComM): Needs rework for due to inconsistent requirements between relevant modules.
 - SRF header transmission at LIN master: Currently no retry mechanisms, after no response from LIN slaves.
- As SWS_Lin_00021 is contradicting with ISO/TR 17987-5:2016, clause 4.5.6.2 Id_send_message, therefore LIN stack behavior (incl. LinIf) is also not compliant with ISO, in contrast to SRS_Lin_01577 and SRS_Lin_01578.

4.11 Requirements on LIN (UID 42 SRS)

- As SWS_Lin_00021 is contradicting with ISO/TR 17987-5:2016, clause 4.5.6.2 Id_send_message, therefore LIN stack behavior (incl. LinIf) is also not compliant with ISO, in contrast to SRS_Lin_01577 and SRS_Lin_01578.

4.12 Specification of PWM Driver (UID 37 SWS)

- [SWS_Pwm_00001] The Pwm SWS does not cover PWM emulation on general purpose I/O. (SRS_Pwm_12386)
- Power State Control APIs are implementable only if the MCAL driver owns the complete underlying HW peripheral i.e. the HW peripheral is not accessed by other MCAL modules.

4.13 Specification of I-PDU Multiplexer (UID 182 SWS)

- For transmission of multiplexed I-PDUs, minimum delay time observation cannot be taken into account. For more details, see [3] and Chapter 7.2.4.1.
- For transmission of container PDUs with static layout, minimum delay time cannot be ensured if two or more contained PDUs have each MDT configuration.

4.14 Specification of CAN Driver (UID 11 SWS)

- A CAN controller always corresponds to one physical channel. It is allowed to connect physical channels on bus side. Regardless the CanIf module will treat the concerned CAN controllers separately.
- A few CAN hardware units support the possibility to combine several CAN controllers by using the CAN RAM, to extend the number of message objects for one CAN controller. These combined CAN controller are handled as one controller by the Can module.
- The Can module does not support CAN remote frames.
- [SWS_Can_00237] The Can module shall not transmit messages triggered by remote transmission requests. (SRS_Can_01147)
- [SWS_Can_00236] The Can module shall initialize the CAN HW to ignore any remote transmission requests. (SRS_Can_01147)

4.15 Specification of LIN State Manager (UID 255 SWS)

- There is at most one instance of the LinSM in each ECU. If the underlying LIN Driver [5] supports multiple networks, the LinSM may be LIN master or LIN slave on more than one cluster.
- All references to (switching of) schedule tables do only apply to LIN master node; there are no schedule tables for LIN slave node.

4.16 Specification of IEEE1722 Transport Protocol Module (UID 1093 SWS)

- The IEEE1722Tp module support a subset of the AVTP stream data subtypes specified by IEEE1722:
 - audio and video streaming: AAF, RVF, 61883_IIDC
 - distribution of a generated clock rate provided by a media clock: CRF

- transport of encapsulated bus frames (ACF_CAN, ACF_CAN_BRIEF and ACF_-LIN) via an ACF-stream, where the time-synchronous TSCF or the non-time-synchronous NTSCF AVTP stream data subtype is used in the ACF-header.
- The IEEE1722Tp module is responsible to forward 1722Tp streams from the lower layers to stream data consumers, and from stream data producer to the lower layers. The time synchronous handling of the transported data with respect to the given AVTP presentation time is in responsibility of the according stream data consumer. Thus, the IEEE1722Tp module cannot ensure time synchronous handling with the accuracy of the AVTP presentation time in units of nanoseconds. An ACF-stream with ACF-header set to TSCF (time-synchronous control format) carries an AVTP presentation time. The AVTP presentation time is given in units of nanoseconds. The IEEE1722Tp module can only perform a forwarding of bus frames with a resolution accuracy of the main function period (e.g. 5 ms). Please note, synchronicity of forwarded bus frames across multiple bus cluster highly depends on the surrounding infrastructure and software implementation, e.g. internal data processing, accuracy of the synchronized global time, busload.

4.17 Specification of Linklayer Sdu Routing Module (UID 1094 SWS)

- The L-SDU Router module does not:
 - have mechanisms for signal extraction or conversion,
 - have mechanisms for data integrity checking (like checksums),
 - change or modify the L-SDU,
 - make any L-SDU payload dependent routing decisions,
- 4.1.1 of UID 1094 SWS
Limitations on supported functionality
In R23-11 the L-SDU Router is considered to act a pass-through module between the IEEE1722Tp and the EthIf
 - Gateway functionality is excluded from the L-SDU router
 - The L-SDU router interacts only with IEEE1722Tp and the EthIf

5 Release History

5.1 Release R23-11

The following deliverables had major changes.

| Name | Specification history entry |
|--|---|
| Application Design Patterns Catalogue | <ul style="list-style-type: none"> • Editorial changes |
| Application Interfaces User Guide | <ul style="list-style-type: none"> • No content changes |
| Basic Software Module Description Template | <ul style="list-style-type: none"> • Added BswInterruptEvent class • Editorial changes |
| Classic Platform Release Overview | <ul style="list-style-type: none"> • Release Life Cycle Status: R23-11 is in Evolution, R23-11 supersedes R22-11 |
| Complex Driver design and integration guideline | <ul style="list-style-type: none"> • No content changes |
| Description of the AUTOSAR standard errors | <ul style="list-style-type: none"> • Updated the names of the referred CP SWS documents. |
| Diagnostic Extract Template | <ul style="list-style-type: none"> • Improved diagnostic authentication • minor corrections / clarifications / editorial changes |
| Explanation of Application Interface of AD/ADAS vehicle motion control | <ul style="list-style-type: none"> • No content changes |
| Explanation of Application Interfaces of Occupant and Pedestrian Safety Systems Domain | <ul style="list-style-type: none"> • No content changes |
| Explanation of Application Interfaces of the Body and Comfort Domain | <ul style="list-style-type: none"> • No content changes |
| Explanation of Application Interfaces of the Chassis Domain | <ul style="list-style-type: none"> • No content changes |
| Explanation of Application Interfaces of the HMI, Multimedia and Telematics Domain | <ul style="list-style-type: none"> • No content changes |
| Explanation of Application Interfaces of the Powertrain Engine Domain | <ul style="list-style-type: none"> • No content changes |
| Explanation of Error Handling on Application Level | <ul style="list-style-type: none"> • Replaced symbols RESTART and • NO_RESTART by • OS_OSAPPLICATION_RESTART and • OS_OSAPPLICATION_NO_RESTART. |
| Explanation of Firmware Over-The-Air | <ul style="list-style-type: none"> • No content changes |
| Explanation of Software Cluster Design And Integration Guideline for Classic Platform | <ul style="list-style-type: none"> • No content changes |
| Explanatory Document for usage of AUTOSAR RunTimeInterface | <ul style="list-style-type: none"> • Updated ARTI macro example code • Updated ARXML examples • Minor corrections and updates |
| General Requirements on Basic Software Modules | <ul style="list-style-type: none"> • Removed (ARTI related) requirement ([SRS_BSW_00495]) |
| General Requirements on SPAL | <ul style="list-style-type: none"> • Editorial changes |
| General Specification of Basic Software Modules | <ul style="list-style-type: none"> • Update permissions for GetApplicationID • Add chapter "Debugging, Tracing, and Profiling Support of BasicSoftwareComponents" • Minor corrections / clarifications / editorial changes |
| General Specification of Transformers | <ul style="list-style-type: none"> • Editorial changes |
| Guide to BSW Distribution | <ul style="list-style-type: none"> • Cleanup of outdated parameter references |
| Guide to Mode Management | <ul style="list-style-type: none"> • Service Discovery Control for Application Software • Provide Interface to Ecu Mode Handling via BswM |





| Name | Specification history entry |
|--|--|
| Integration of Franca IDL Software Component Descriptions | <ul style="list-style-type: none"> • Editorial changes |
| Layered Software Architecture | <ul style="list-style-type: none"> • Added information about charging management (ChrgM) and firewall • Editorial changes |
| List of Basic Software Modules | <ul style="list-style-type: none"> • Added ChrgM • Added Firewall • Added HWTestManager |
| Macro Encapsulation of Interpolation Calls | <ul style="list-style-type: none"> • No content changes |
| Methodology for Classic Platform | <ul style="list-style-type: none"> • Be specific when using the term cluster (e.g. BSW cluster) • Clarify activity Create ECU System Description |
| Modeling Guidelines of Basic Software EA UML Model | <ul style="list-style-type: none"> • introduced stereotype «symbol» for symbol definitions • support for API functions with multiple Service IDs • described modeling of links from API functions to possible return values • described modeling of bsw.sequenceOffset |
| Modeling Show Cases Report | <ul style="list-style-type: none"> • No content changes |
| NV Data Handling Guideline | <ul style="list-style-type: none"> • No content changes |
| Overview of Functional Safety Measures in AUTOSAR | <ul style="list-style-type: none"> • Fixed AUTOSAR specification references • Changes in image and tables layout |
| Requirements on ADC Driver | <ul style="list-style-type: none"> • No content changes |
| Requirements on Basic Software Module Description Template | <ul style="list-style-type: none"> • No content changes |
| Requirements on BSW Modules for SAE J1939 | <ul style="list-style-type: none"> • Changed document name to include "CP" • Support for dynamic address allocation |
| Requirements on Bus Mirroring | <ul style="list-style-type: none"> • Changed document name to include "CP" |
| Requirements on CAN | <ul style="list-style-type: none"> • No content changes |
| Requirements on Charging Manager | <ul style="list-style-type: none"> • Initial release |
| Requirements on Chinese Vehicle-2-X Communication | <ul style="list-style-type: none"> • No content changes |
| Requirements on Communication | <ul style="list-style-type: none"> • Editorial changes |
| Requirements on Core Test | <ul style="list-style-type: none"> • No content changes |
| Requirements on Crypto Stack | <ul style="list-style-type: none"> • No content changes |
| Requirements on Debugging, Tracing and Profiling support of AUTOSAR Components | <ul style="list-style-type: none"> • No content changes |
| Requirements on Diagnostic Extract Template | <ul style="list-style-type: none"> • No content changes |
| Requirements on DIO Driver | <ul style="list-style-type: none"> • Editorial changes |
| Requirements on ECU Configuration | <ul style="list-style-type: none"> • No content changes |
| Requirements on ECU Resource Template | <ul style="list-style-type: none"> • No content changes |
| Requirements on EEPROM Driver | <ul style="list-style-type: none"> • Editorial changes |
| Requirements on Ethernet Support in AUTOSAR | <ul style="list-style-type: none"> • Introduction of Secure SOME/IP-ACL • Introduction of Deterministic Communication with TSN: Parts 1, 4 and 6 (DRAFT) |
| Requirements on Firmware Over-The-Air | <ul style="list-style-type: none"> • No content changes |
| Requirements on Flash Driver | <ul style="list-style-type: none"> • Editorial changes • Replaced references to BS BRF with RS BRF |
| Requirements on Flash Test | <ul style="list-style-type: none"> • References to "AUTOSAR SWS RAMTest.pdf" removed from the document |





| Name | Specification history entry |
|--|--|
| Requirements on FlexRay | <ul style="list-style-type: none"> No content changes |
| Requirements on Function Inhibition Manager | <ul style="list-style-type: none"> No content changes Editorial Changes |
| Requirements on Gateway | <ul style="list-style-type: none"> Added support for Linklayer Sdu Routing Module Editorial changes |
| Requirements on GPT Driver | <ul style="list-style-type: none"> No content changes |
| Requirements on Hardware Test Manager on start up and shutdown | <ul style="list-style-type: none"> No content changes |
| Requirements on I/O Hardware Abstraction | <ul style="list-style-type: none"> No content changes |
| Requirements on ICU Driver | <ul style="list-style-type: none"> No content changes |
| Requirements on I-PDU Multiplexer | <ul style="list-style-type: none"> No content changes |
| Requirements on Libraries | <ul style="list-style-type: none"> No content changes |
| Requirements on LIN | <ul style="list-style-type: none"> No content changes |
| Requirements on MCU Driver | <ul style="list-style-type: none"> No content changes |
| Requirements on Memory Hardware Abstraction Layer | <ul style="list-style-type: none"> Editorial changes |
| Requirements on Memory Services | <ul style="list-style-type: none"> Editorial changes |
| Requirements on Mode Management | <ul style="list-style-type: none"> Added chapter Service Discovery Control for SWCs Editorial Changes |
| Requirements on Module XCP | <ul style="list-style-type: none"> No content changes |
| Requirements on OCU Driver | <ul style="list-style-type: none"> Editorial changes |
| Requirements on Operating System | <ul style="list-style-type: none"> No content changes |
| Requirements on Port Driver | <ul style="list-style-type: none"> Editorial Changes |
| Requirements on PWM Driver | <ul style="list-style-type: none"> No content changes |
| Requirements on RAM Test | <ul style="list-style-type: none"> No content changes |
| Requirements on Runtime Environment | <ul style="list-style-type: none"> Removed PartitionRestart Set Requirements related to RTE_Implementation_Plug-ins and ClassicPlatformFlexibility to valid Added chapter "Change history of AUTOSAR traceable items" |
| Requirements on Secure Onboard Communication | <ul style="list-style-type: none"> No content changes |
| Requirements on Software Cluster Connection module | <ul style="list-style-type: none"> Requirements of R20-11 functionality are set to valid |
| Requirements on Software Component Template | <ul style="list-style-type: none"> No content changes. |
| Requirements on SPI Handler/Driver | <ul style="list-style-type: none"> No content changes |
| Requirements on SW-C and System Modeling | <ul style="list-style-type: none"> No content changes |
| Requirements on System Template | <ul style="list-style-type: none"> Added IEEE1722Tp Stream support requirement Added Ethernet Switch Filtering and Policing requirement For details please refer to the ChangeDocumentation |
| Requirements on Time Service | <ul style="list-style-type: none"> Editorial changes |
| Requirements on Transformer | <ul style="list-style-type: none"> Editorial Changes - No content changes |
| Requirements on TTCAN | <ul style="list-style-type: none"> Editorial changes |
| Requirements on Vehicle-2-X Communication | <ul style="list-style-type: none"> No content changes |
| Requirements on Watchdog Driver | <ul style="list-style-type: none"> No content changes |
| Safety Use Case Example | <ul style="list-style-type: none"> No content changes |





| Name | Specification history entry |
|--|--|
| Software Component Template | <ul style="list-style-type: none"> • Improve data type configuration • minor corrections / clarifications / editorial changes |
| Specification and Integration of Hardware Test Management at start up and shutdown | <ul style="list-style-type: none"> • No content changes |
| Specification for CAN XL Driver | <ul style="list-style-type: none"> • Introduce CanXL_GetCurrentTimeTuple() as draft and deprecate CanXL_GetCurrentTime() • Editorial changes • Update optional interfaces • Update imported datatypes |
| Specification of a Diagnostic Communication Manager for SAE J1939 | <ul style="list-style-type: none"> • Fixed non-diagnostic channels and return values of Dem_J1939DcmGetNumberOfFilteredDTC • Added missing service ports and interfaces for DM13 • Added information about automatic handle IDs to configuration • Converted to LATEX and changed document name to include "CP" |
| Specification of a Request Manager for SAE J1939 | <ul style="list-style-type: none"> • Fixed include file for configurable callouts • Fixed reference to J1939Rm_CheckReceivedComIPdu, fixed name of J1939RmRequest2QueueSize, fixed description of destAddress of J1939Rm_CancelRequestTimeout • Added information about automatic handle IDs to configuration • J1939Rm_AckCode and J1939Rm_ExtIdType changed to uint8 |
| Specification of a Transport Layer for SAE J1939 | <ul style="list-style-type: none"> • Changed document name to include "CP" • Added references to ComMChannels to configuration • Added information about automatic handle IDs to configuration |
| Specification of ADC Driver | <ul style="list-style-type: none"> • No content changes |
| Specification of AUTOSAR Run-Time Interface | <ul style="list-style-type: none"> • Extended stopwatch to allow nesting • Added imported types • Editorial changes |
| Specification of Basic Software Mode Manager | <ul style="list-style-type: none"> • Added BswM support for Service Discovery Control for Application Software • Added new action to set firewall state • Editorial Changes |
| Specification of Basic Software Multicore Library | <ul style="list-style-type: none"> • Added note for MemoryAllocation • Bugfixes |
| Specification of Bit Handling Routines | <ul style="list-style-type: none"> • Fixed CheckDocumentSource errors. |
| Specification of Bulk NvData Manager | <ul style="list-style-type: none"> • No content changes |
| Specification of Bus Mirroring | <ul style="list-style-type: none"> • Changed document name to include "CP" • Removed direct references to tables from SWS items • Added information about automatic handle IDs to configuration • Mirror_NetworkType changed to uint8 |





| Name | Specification history entry |
|---|--|
| Specification of CAN Driver | <ul style="list-style-type: none"> • Support for selective WakeUp via CAN-Controller • Changed document name to include "CP" • Added information about automatic handle IDs to configuration • Converted to LATEX |
| Specification of CAN Interface | <ul style="list-style-type: none"> • Support for selective WakeUp via CAN-Controller • Editorial changes |
| Specification of CAN Network Management | <ul style="list-style-type: none"> • Editorial changes • Improvements and harmonization |
| Specification of CAN State Manager | <ul style="list-style-type: none"> • Support for selective WakeUp via CAN-Controller • Clarification of "Available via: Configurable" • Added SWS IDs for "mandatory interfaces" & "optional interfaces" • Editorial changes |
| Specification of CAN Transceiver Driver | <ul style="list-style-type: none"> • Editorial changes |
| Specification of CAN Transport Layer | <ul style="list-style-type: none"> • Added Extended Production Errors to indicate timeouts and errors • Removed dependency of the addressing format for shared PDUs/SDUs |
| Specification of CAN XL Transceiver Driver | <ul style="list-style-type: none"> • Editorial changes |
| Specification of Cellular Vehicle-2-X Driver | <ul style="list-style-type: none"> • No content changes |
| Specification of Charging Manager | <ul style="list-style-type: none"> • Initial release |
| Specification of Chinese Vehicle-2-X Management | <ul style="list-style-type: none"> • No content changes |
| Specification of Chinese Vehicle-2-X Message | <ul style="list-style-type: none"> • Editorial Cleanup |
| Specification of Chinese Vehicle-2-X Network | <ul style="list-style-type: none"> • No content changes |
| Specification of Chinese Vehicle-2-X Security | <ul style="list-style-type: none"> • No content changes |
| Specification of COM Based Transformer | <ul style="list-style-type: none"> • No content changes |
| Specification of Communication | <ul style="list-style-type: none"> • Minor corrections / clarifications / editorial changes |
| Specification of Communication Manager | <ul style="list-style-type: none"> • Document structure rework • Introduced validation findings of concept "ReworkOfPNCrelatedComMandNM handling (part2)" |
| Specification of Communication Stack Types | <ul style="list-style-type: none"> • Added ListElemStructType • Added TimeTupleType, TimeStampType, TimeStampQualType • Changed the size of PNCHandleType |
| Specification of Core Test | <ul style="list-style-type: none"> • No content changes |
| Specification of CRC Routines | <ul style="list-style-type: none"> • Removed hardware supported CRC calculation • Minor corrections / clarifications / editorial changes |
| Specification of Crypto Driver | <ul style="list-style-type: none"> • Editorial Changes • Add support for KeyWrap / KeyUnwrap |
| Specification of Crypto Interface | <ul style="list-style-type: none"> • Changed pubValueLengthPtr into publicValueLengthPtr • Removed CRYPTO_E_QUEUE_FULL from SWS_CryIf_91003 • Minor changes • |





| Name | Specification history entry |
|---|--|
| Specification of Crypto Service Manager | <ul style="list-style-type: none"> • Add AES Key Wrap support • Remove inconsistency in parameter types and const type modifier • Remove key location check in Csm_KeyCopy() • Editorial changes |
| Specification of Data Distribution Service for Classic Platform | <ul style="list-style-type: none"> • EcuC model refactoring • Added details on Tx and Rx path and queue management • API renaming and clarification • Improved description of safety requirements and management |
| Specification of Default Error Tracer | <ul style="list-style-type: none"> • Editorial Changes |
| Specification of Diagnostic Communication Manager | <ul style="list-style-type: none"> • Fixed StartOfReception • Added Authentication TransmitCertificate • Introduced Secure Variant Coding • Reworked the structure of elements in SecurityEvents to enable usage in multiple platforms • minor corrections / clarifications / editorial changes; For details please • refer to the ChangeDocumentation |
| Specification of Diagnostic Event Manager | <ul style="list-style-type: none"> • Remove draft API Dem_SetEventFailedWithSyncFreeze Frame / Dem_CallbackEventSync StorageProcessed • Introduce DemResetPendingBitOnOverflow • Introduce IUMPR Denominator for evaporative system purge flow monitor • Adapt range for EDR 0xFE |
| Specification of Diagnostic Log and Trace | <ul style="list-style-type: none"> • Added Message Tags specifications • Minor corrections • Editorial changes |
| Specification of Diagnostic over IP | <ul style="list-style-type: none"> • incorporated DoIP Multiplexed Testers |
| Specification of DIO Driver | <ul style="list-style-type: none"> • Editorial changes |
| Specification of ECU Configuration | <ul style="list-style-type: none"> • Added EcucPartitionId and EcucPartitionCoreRef to Ecuc module • Added configuration for Complex Drivers, which interact with the L-Sdu • Router module • Added Pdu Meta-Data used for IEEE1722Tp • Changes in specification items and constraints: for details please see the change history |
| Specification of ECU Resource Template | <ul style="list-style-type: none"> • Editorial: wrap tables in specification items • Extend HwPin attributes |
| Specification of ECU State Manager | <ul style="list-style-type: none"> • Correct broken references • Minor content changes, clarifications |
| Specification of EEPROM Abstraction | <ul style="list-style-type: none"> • Editorial Changes |
| Specification of EEPROM Driver | <ul style="list-style-type: none"> • Editorial Changes • Assigned new ID [SWS_Eep_00247] to a duplicate ID under EEP_E_ERASE_FAILED |





| Name | Specification history entry |
|--|--|
| Specification of Ethernet Driver | <ul style="list-style-type: none"> • Adaptation to the Deterministic Communication with TSN • Editorial changes |
| Specification of Ethernet Interface | <ul style="list-style-type: none"> • New chapters for: • Firewall support • Communication • Editorial changes |
| Specification of Ethernet State Manager | <ul style="list-style-type: none"> • Add new Parameter EthSMTcplpUsed to enable/disable interaction with a TcpIp module for the EthSm Network • Removed unnecessary requirements: [SWS_EthSM_00008], [SWS_EthSM_00010],[SWS_EthSM_00013] |
| Specification of Ethernet Switch Driver | <ul style="list-style-type: none"> • Concept 710 (Deterministic communication with TSN) incorporated • Interaction with the Firewall module added |
| Specification of Ethernet Transceiver Driver | <ul style="list-style-type: none"> • Missing run time error added • withAuto=TRUE for EthTrcvIdx • Editorial changes |
| Specification of Extended Fixed Point Routines | <ul style="list-style-type: none"> • A statement has been added to define the T1rec resolution. |
| Specification of Firewall for Classic Platform | <ul style="list-style-type: none"> • Initial release |
| Specification of Fixed Point Interpolation Routines | <ul style="list-style-type: none"> • Fixed CheckDocumentSource errors. |
| Specification of Fixed Point Math Routines | <ul style="list-style-type: none"> • No content changes. |
| Specification of Flash Driver | <ul style="list-style-type: none"> • Editorial changes • Removed uptrace from [SWS_Fls_NA_00366] to SRS_BSW_00371 and SRS_BSW_00361 |
| Specification of Flash EEPROM Emulation | <ul style="list-style-type: none"> • Fixed incorrect description of return value in Fee_InvalidateBlock and Fee_EraseImmediateBlock |
| Specification of Flash Test | <ul style="list-style-type: none"> • Editorial changes |
| Specification of FlexRay AUTOSAR Transport Layer | <ul style="list-style-type: none"> • No content changes |
| Specification of FlexRay Driver | <ul style="list-style-type: none"> • Removed all HandleId configuration parameters |
| Specification of FlexRay Interface | <ul style="list-style-type: none"> • No content changes |
| Specification of FlexRay ISO Transport Layer | <ul style="list-style-type: none"> • Added Extended Production Errors to indicate timeouts and errors |
| Specification of FlexRay Network Management | <ul style="list-style-type: none"> • Removed all HandleId configuration parameters • Minor corrections |
| Specification of FlexRay State Manager | <ul style="list-style-type: none"> • Editorial changes • Naming harmonized • Specification IDs for production errors |
| Specification of FlexRay Transceiver Driver | <ul style="list-style-type: none"> • editorial cleanup. • withAuto tag set to true for Index and ID configuration parameters. • Editorial update of main function definition table |
| Specification of Floating Point Interpolation Routines | <ul style="list-style-type: none"> • No content changes. |
| Specification of Floating Point Math Routines | <ul style="list-style-type: none"> • Updated SWS_Mfl_00305. |





| Name | Specification history entry |
|---|--|
| Specification of Function Inhibition Manager | <ul style="list-style-type: none"> Removed PartitionRestart Set Requirements related to RTE_Implementation_Plug-ins and ClassicPlatformFlexibility to valid Added chapter "Change history of AUTOSAR traceable items" |
| Specification of GPT Driver | <ul style="list-style-type: none"> No content changes |
| Specification of Hardware Test Manager on start up and shutdown | <ul style="list-style-type: none"> No content changes |
| Specification of I/O Hardware Abstraction | <ul style="list-style-type: none"> No content changes |
| Specification of ICU Driver | <ul style="list-style-type: none"> No content changes |
| Specification of IEEE1722 Transport Protocol Module | <ul style="list-style-type: none"> Initial release |
| Specification of Intrusion Detection System Manager | <ul style="list-style-type: none"> Introduction of Qualified Event Buffer New Security Event no Qualified Event Buffer available New Type Definition IdsM ExternalSecurityEventIdType |
| Specification of I-PDU Multiplexer | <ul style="list-style-type: none"> Added information about automatic handle IDs to configuration Changed document name to include "CP" |
| Specification of Key Manager | <ul style="list-style-type: none"> Supported certificate encodings in KeyM Minor bugfixes Editorial changes. |
| Specification of Large Data COM | <ul style="list-style-type: none"> Removed all HandleId configuration parameters |
| Specification of LIN Driver | <ul style="list-style-type: none"> LIN_E_TIMEOUT removed as Production Error Misleading note regarding Lin_CheckWakeup removed Editorial Changes |
| Specification of LIN Interface | <ul style="list-style-type: none"> Added Extended Production Errors regarding LinTp timeouts and relevant errors Added a note after [SWS_LinIf_00503] for clarification on implementation of LinIf_CheckWakeup API Clarification of "Available via: Configurable" in API tables (Header File Cleanup) Refined configuration structure Editorial changes (incl. correcting typos in spec. items) |
| Specification of LIN State Manager | <ul style="list-style-type: none"> Updated Chapter 7.1.8 & 8.3.2 Removed Chapter 7.1.8.1 Wakeup repetitions for slave Editorial Changes in Chapter 8.5.1 & 8.5.2 Corrected Figure in Chapter 9.1 Added new parameter [ECUC_LinSM_00212] in Chapter 10.3.2 |
| Specification of LIN Transceiver Driver | <ul style="list-style-type: none"> Editorial changes |
| Specification of Linklayer Sdu Routing Module | <ul style="list-style-type: none"> Initial release |
| Specification of MACsec Key Agreement | <ul style="list-style-type: none"> MKA Security Events incorporated |
| Specification of MCU Driver | <ul style="list-style-type: none"> Cleaned up unresolved references in traceability |
| Specification of Memory Abstraction Interface | <ul style="list-style-type: none"> Updated SWS_MemIf_00047 Removed Obsolete status of SWS_MemIf_00065 Editorial changes |
| Specification of Memory Access | <ul style="list-style-type: none"> Fixed inconsistencies |





| Name | Specification history entry |
|--|---|
| Specification of Memory Driver | <ul style="list-style-type: none"> • Fixed inconsistencies |
| Specification of Memory Mapping | <ul style="list-style-type: none"> • Clarify usage of GLOBAL and LOCAL coreScope • Improve document readability |
| Specification of Module E2E Transformer | <ul style="list-style-type: none"> • Rework flowcharts, sequence charts and explaining text • Description of E2E state machine results updated |
| Specification of Module XCP | <ul style="list-style-type: none"> • Removed all HandleId configuration parameters |
| Specification of Network Management for SAE J1939 | <ul style="list-style-type: none"> • Changed document name to include "CP" • Added configuration of dynamic addressing • Added information about automatic handle IDs to configuration |
| Specification of Network Management Interface | <ul style="list-style-type: none"> • NM harmonization • Editorial changes |
| Specification of NVRAM Manager | <ul style="list-style-type: none"> • NvM_SetBlockLockStatus removed • NvM_Externals.h provided conditionally |
| Specification of OCU Driver | <ul style="list-style-type: none"> • Editorial changes |
| Specification of Operating System | <ul style="list-style-type: none"> • Renaming of restart symbols • Added new API isOsStarted, configuration change in OS-Application/EcuPartition/Core assignment • Memory mapping update • Minor correction / clarification / editorial changes |
| Specification of PDU Router | <ul style="list-style-type: none"> • Sequence diagram chapters for TP Gatewaying have been improved • Editorial changes |
| Specification of Platform Types for Classic Platform | <ul style="list-style-type: none"> • No content changes. |
| Specification of Port Driver | <ul style="list-style-type: none"> • Editorial changes • Removed uptrace from [SWS_Port_NA_00227] to SRS_BSW_00371 |
| Specification of PWM Driver | <ul style="list-style-type: none"> • No content changes |
| Specification of RAM Test | <ul style="list-style-type: none"> • Editorial changes |
| Specification of RTE Software | <ul style="list-style-type: none"> • Extended support for Software Clusters • Support for termination and restart of partitions removed • VFB tracing of mode switch request completion • Minor corrections / clarifications/ editorial changes |
| Specification of Secure Onboard Communication | <ul style="list-style-type: none"> • Updated naming of Security Events for IdsM • Minor corrections / clarifications / editorial changes |
| Specification of Service Discovery | <ul style="list-style-type: none"> • Added Secure SOME/IP-ACL • Minor bugfixes and editorial changes |
| Specification of Socket Adaptor | <ul style="list-style-type: none"> • Added SoAdSocketIpAddrAssignmentChgNotifUpperLayerRef. • Added ACL support. • Removed module prefix from security events. • Improved TCP stream handling. • Improved nPdu transmit requirements [SWS_SoAd_00734] and [SWS_SoAd_00747]. • Resolved contradiction in [SWS_SoAd_00683]. |





| Name | Specification history entry |
|---|---|
| Specification of Software Cluster Connection module | <ul style="list-style-type: none"> • Support SW Cluster individual configuration ID check in NVM proxy • Requirements of R20-11 functionality are set to valid • Corrections and editorial changes of existing feature |
| Specification of SOME/IP Transformer | <ul style="list-style-type: none"> • Restrict SOME/IP session handling • Added information about use of maximum number of array elements • Removed chapter "Header file structure" • Clarification on byte order for SOME/IP header fields, additional fields in the payload and parameters in the payload |
| Specification of SPI Handler/Driver | <ul style="list-style-type: none"> • SWS_Spi_00389 moved to mandatory interfaces • Editorial changes |
| Specification of Standard Types | <ul style="list-style-type: none"> • Added Safety Transformer Error Codes in [SWS_Std_00028] • Editorial Changes |
| Specification of SW-C End-to-End Communication Protection Library | <ul style="list-style-type: none"> • Corrections of Length type in P44m |
| Specification of Synchronized Time-Base Manager | <ul style="list-style-type: none"> • Support for a Disciplined HW Clock added • Time Validation enhanced: Fallback Virtual Local Time, rate validation and time progression monitoring added • Validation findings for "Secured Time Synchronization" incorporated • Type of Time Base no longer depends on the ID but on the newly introduced Type parameter |
| Specification of TCP/IP Stack | <ul style="list-style-type: none"> • Minor corrections and clarifications • Editorial changes • Wildcards descriptions improvement • Introduction of IND, TCP window scale option, TCP SACK and TLS updates for Charging Interface |
| Specification of Time Service | <ul style="list-style-type: none"> • Editorial changes |
| Specification of Time Synchronization over CAN | <ul style="list-style-type: none"> • Clarification of / refinement of sequence counter validation • Clarification of / refinement of Timesync message transmission and debouncing behavior • Incorporation of validation findings for "Secured Time Synchronization" |
| Specification of Time Synchronization over Ethernet | <ul style="list-style-type: none"> • Integrated Support of PTP physical clock adjustment |
| Specification of Time Synchronization over FlexRay | <ul style="list-style-type: none"> • Clarification of / refinement of sequence counter validation • Clarification of / refinement of Timesync message transmission and debouncing behavior • Incorporation of validation findings for "Secured Time Synchronization" |
| Specification of Timing Extensions for Classic Platform | <ul style="list-style-type: none"> • Change primitive type of maxSlots/maxCycles in repetitiveEOC • Improve identification and constraints of root in hierarchicalEOC • Introduce Intra-LET paradigms • Remove EOC.ignoreOrderAllowed |





| Name | Specification history entry |
|---|--|
| Specification of TTCAN Driver | <ul style="list-style-type: none"> • Editorial changes • Add Definition of datatype Can_TTTURType • Fix Can_TTReceive Service ID |
| Specification of TTCAN Interface | <ul style="list-style-type: none"> • Extended Production Errors integrate table into requirement. |
| Specification of UDP Network Management | <ul style="list-style-type: none"> • NM harmonization • Editorial changes |
| Specification of Vehicle-2-X Basic Transport | <ul style="list-style-type: none"> • Removal of Tx confirmation and transaction ID • Clarification of upper layer interface of <User>_RxIndication() • Renamed V2Btp_GetVersionInfo to V2xBtp_GetVersionInfo |
| Specification of Vehicle-2-X Data Manager | <ul style="list-style-type: none"> • List non-applicable requirements from SRS V2x Communication • Editorial changes |
| Specification of Vehicle-2-X Facilities | <ul style="list-style-type: none"> • Removal of Tx confirmation and transaction ID • Removal of Verification on Demand |
| Specification of Vehicle-2-X Geo Networking | <ul style="list-style-type: none"> • Removal of Tx confirmation and transaction ID |
| Specification of Vehicle-2-X Management | <ul style="list-style-type: none"> • Removal of Tx confirmation and transaction ID • Various corrections in service API and V2XFac API mapping |
| Specification of Watchdog Driver | <ul style="list-style-type: none"> • No content changes |
| Specification of Watchdog Interface | <ul style="list-style-type: none"> • No content changes |
| Specification of Watchdog Manager | <ul style="list-style-type: none"> • Editorial changes |
| Specification of Wireless Ethernet Driver | <ul style="list-style-type: none"> • Removal of Tx confirmation and transaction ID • WEthCtrlId no anymore manually configured |
| Specification of Wireless Ethernet Transceiver Driver | <ul style="list-style-type: none"> • WEthTrcvId, WEthTrcvRadioid and WEthTrcvAntennaid no anymore manually configured |
| Specification on SOME/IP Transport Protocol | <ul style="list-style-type: none"> • Several minor bugfixes • Specified behavior of PduR_SomelpTpTransmit in case of E_NOT_OK |
| Supplementary material of general blueprints for AUTOSAR | <ul style="list-style-type: none"> • No content changes |
| SW-C and System Modeling Guide | <ul style="list-style-type: none"> • Changed semantics of valid short name |
| System Template | <ul style="list-style-type: none"> • Added support for DDS configuration • Added support for Firewall configuration • Added support for ACL checks • Added support for modeling of IEEE1722Tp streams and Ethernet Switch Filtering and Policing |
| Unique Names for Documentation, Measurement and Calibration: Modeling and Naming Aspects including Automatic Generation | <ul style="list-style-type: none"> • No content changes |
| Utilization of Crypto Services | <ul style="list-style-type: none"> • Editorial changes |
| Virtual Functional Bus | <ul style="list-style-type: none"> • Fixed specification items with colliding ID-s |

Table 5.1: Overview of specification release histories