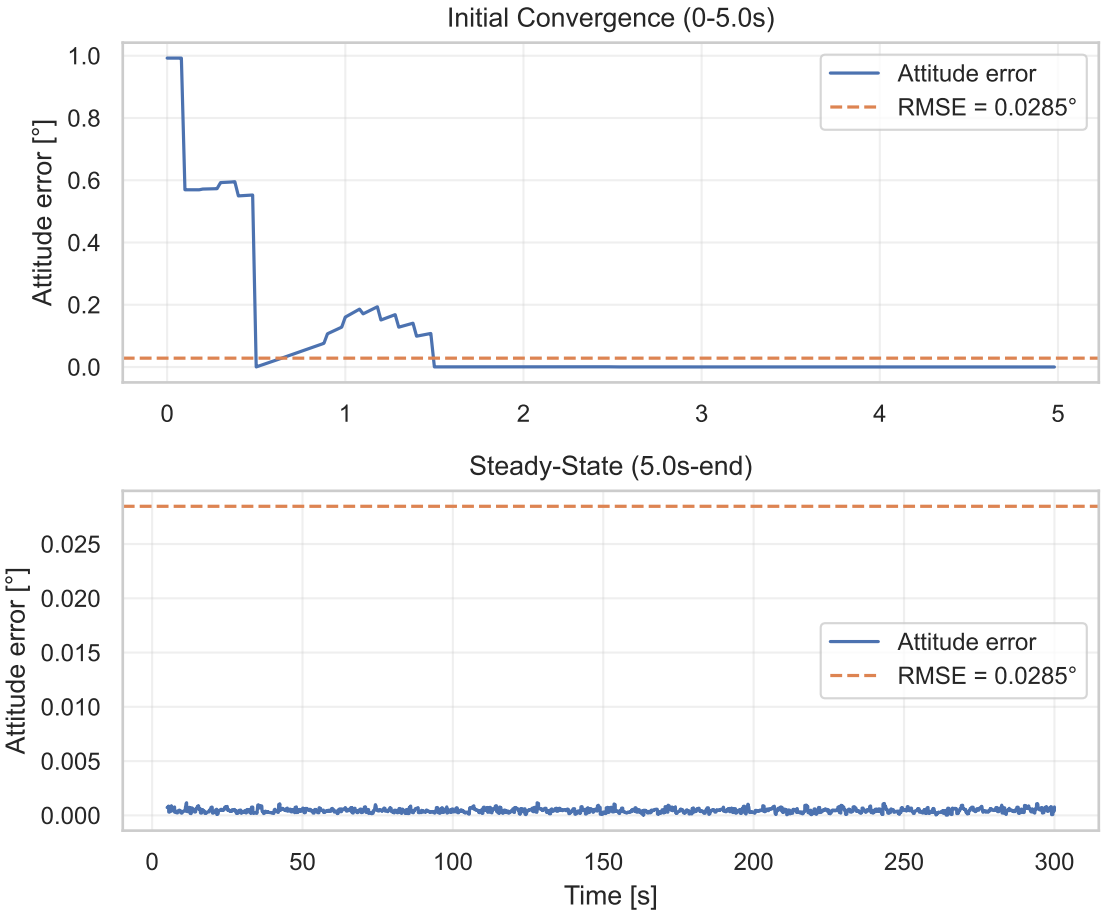
Initial Convergence (0-5.0s)
Attitude error [°]
1.0
0.8
0.6
0.4
0.2
0.0
0
1
2
3
4
5
Attitude error
RMSE = 0.0285°
Steady-State (5.0s-end)
Attitude error [°]
0.025
0.020
0.015
0.010
0.005
0.000
0
50
100
150
200
250
300
Time [s]
Attitude error
RMSE = 0.0285°