

1.

1. By smoothness,

$$f(x^*) \leq f(x) + \langle \nabla f(x), x^* - x \rangle + \frac{L}{2} \|x^* - x\|_2^2$$

$$f(x) - f^* \geq \langle \nabla f(x), x - x^* \rangle - \frac{L}{2} \|x - x^*\|_2^2 = \langle \nabla f(x), u \rangle - \frac{L}{2} \|u\|_2^2 := h(u).$$

$$h(u) \text{ is concave. } \nabla h(u) = 0 \quad \nabla f(x) - Lu^* = 0. \quad u^* = \frac{1}{L} \nabla f(x)$$

$$\Rightarrow \sup_u h(u) = \frac{1}{L} \|\nabla f(x)\|_2^2 - \frac{L}{2} \cdot \frac{1}{L^2} \|\nabla f(x)\|_2^2 = \frac{1}{2L} \|\nabla f(x)\|_2^2.$$

$$2. \quad \underline{h_x(z) = f(z) - \langle \nabla f(x), z \rangle.}$$

How do we understand this function?

$$\text{is CVX: } h_x(z) \geq h_x(y) + \langle \nabla h_x(y), z - y \rangle.$$

$$\nabla h_x(y) = \nabla f(y) - \nabla f(x).$$

$$h_x(z) - h_x(y) = f(z) - f(y) - \langle \nabla f(x), z - y \rangle$$

$$\begin{aligned} \text{Only to prove } f(z) - f(y) &\geq \langle \nabla f(y) - \nabla f(x), z - y \rangle + \langle \nabla f(x), z - y \rangle \\ &= \langle \nabla f(y), z - y \rangle. \quad \square. \end{aligned}$$

$$\text{is } L\text{-smooth: } \|\nabla^2 h_x(y)\| = \|\nabla^2 f(y)\|_2 \underset{\substack{\uparrow \\ L\text{-smooth}}}{\leq} L$$

x, y are symmetric so same res works for $h_y(z)$.

Apply part I to $h_x(z)$, and set $z = y$,

$$f(y) - \langle \nabla f(x), y \rangle - h_x^* \geq \frac{1}{2L} \|\nabla h_x(y)\|_2^2 = \frac{1}{2L} \|\nabla f(y) - \nabla f(x)\|_2^2$$

Apply part I to $h_y(z)$, and set $z = x$.

$$f(x) - \langle \nabla f(y), x \rangle - h_y^* \geq \frac{1}{2L} \|\nabla h_y(x)\|_2^2 = \frac{1}{2L} \|\nabla f(x) - \nabla f(y)\|_2^2$$

Consider h_x^* : By convexity,

$$f(z) \geq f(x) + \langle \nabla f(x), z-x \rangle.$$

$$h_x(z) = f(z) - \langle \nabla f(x), z \rangle \geq f(x) - \langle \nabla f(x), x \rangle.$$

Found that equality holds if $z=x \Rightarrow h_x^* = f(x) - \langle \nabla f(x), x \rangle.$

Similarly, $h_y^* = f(y) - \langle \nabla f(y), y \rangle.$ Plug back,

$$\left\{ \begin{array}{l} f(y) - f(x) - \langle \nabla f(x), y-x \rangle \geq \frac{1}{2L} \|\nabla f(y) - \nabla f(x)\|_2^2 \quad \textcircled{1} \\ f(x) - f(y) - \langle \nabla f(y), x-y \rangle \geq \frac{1}{2L} \|\nabla f(y) - \nabla f(x)\|_2^2 \quad \textcircled{2} \end{array} \right.$$

$$\textcircled{1} + \textcircled{2} \Rightarrow \langle \nabla f(x) - \nabla f(y), x-y \rangle \geq \frac{1}{L} \|\nabla f(x) - \nabla f(y)\|_2^2.$$

2. Note that $\forall j \neq i, \nabla_j f(x + \delta e_i) - \nabla_j f(x) = 0.$

Hence condition implies $\forall i, \|\nabla f(x + \delta e_i) - \nabla f(x)\| \leq L_i |\delta| = L_i \|x + \delta e_i - x\|,$

which is a detailed version of smoothness (defined on different directions)
(I D K)

Apply L_i -smoothness,

$$\begin{aligned} \forall i, f(x + \delta e_i) - f(x) &\leq \langle \nabla f(x), \delta e_i \rangle + \frac{L_i}{2} \|\delta e_i\|_2^2 \\ &= \delta \nabla_i f(x) + \frac{L_i}{2} |\delta|^2 \end{aligned}$$

2. $x_{k+1} - x_k = \underbrace{-\alpha_{ik} \nabla_{ik} f(x_k)}_{\delta} e_{ik}$ Apply res in part I,

$$\Rightarrow f(x_{k+1}) - f(x_k) \leq -\alpha_{ik} (\nabla_{ik} f(x_k))^2 + \frac{L_{ik}}{2} (\alpha_{ik} \nabla_{ik} f(x_k))^2$$

$$= (\nabla_{ik} f(x_k))^2 \left(\frac{L_{ik}}{2} d_{ik}^2 - d_{ik} \right)$$

We wish RHS to be smaller. Since x_k is fixed, we can only adjust \square part.

$$\text{Set } d_{ik} = \frac{-1}{-2 \cdot \frac{L_{ik}}{2}} = \frac{1}{L_{ik}} \text{ and we got it.}$$

This is our choice of d_{ik} $\Rightarrow f(x_{k+1}) - f(x_k) \leq -\frac{1}{2L_{ik}} (\nabla_{ik} f(x_k))^2$

Then

$$\mathbb{E}[f(x_{k+1}) - f(x_k)] \leq \mathbb{E} \left[-\frac{1}{2L_{ik}} (\nabla_{ik} f(x_k))^2 \right]$$

\downarrow
uni

$$= -\frac{1}{2} \sum_{i=1}^d \frac{1}{L_i} (\nabla_i f(x_k))^2$$

$$\text{Set } L = \max_i L_i$$

$$\leq -\frac{1}{2L} \sum_{i=1}^d (\nabla_i f(x_k))^2 = -\frac{1}{2L} \|\nabla f(x_k)\|_2^2$$

$$\beta = \frac{1}{2L}, \text{ the largest } \beta \text{ I can get.}$$

2.3. follow part 2, for fixed k , $\|\nabla f(x_k)\|_2^2 \leq -\frac{2}{\beta} \mathbb{E}_{i_k} [f(x_{k+1}) - f(x_k)]$

$$\min_{0 \leq k \leq K} \mathbb{E} [\|\nabla f(x_k)\|_2^2] \leq -\frac{2}{\beta} \min_{0 \leq k \leq K} \mathbb{E} [f(x_{k+1}) - f(x_k)]$$

$$= -\frac{2}{\beta} \cdot \frac{1}{K+1} \sum_{i=0}^K f(x_{i+1}) - f(x_i) \stackrel{\text{Te}}{=} f^*$$

$$\leq -\frac{2(f(x_{K+1}) - f(x_0))}{\beta(K+1)} = \frac{2(f(x_0) - f(x_{K+1}))}{\beta(K+1)}$$

$$\leq \frac{2(f(x_0) - f^*)}{\beta(k+1)}$$

3.

$$1. \quad \nabla \varphi(y) = \frac{1}{2} \cdot 2 \|y - x_0\| \cdot \frac{y - x_0}{\|y - x_0\|} = y - x_0.$$

$$\begin{aligned} D\varphi(x, y) &= \frac{1}{2} \|x - x_0\|^2 - \frac{1}{2} \|y - x_0\|^2 - \langle y - x_0, (x - x_0) - (y - x_0) \rangle \\ &= \frac{1}{2} \|x - x_0\|^2 + \frac{1}{2} \|y - x_0\|^2 - \langle y - x_0, x - x_0 \rangle \\ &= \frac{1}{2} \|(x - x_0) - (y - x_0)\|^2 = \frac{1}{2} \|x - y\|^2. \end{aligned}$$

$$2. \quad \phi(x) = \psi(x) + \langle z, x \rangle. \quad \nabla \phi(y) = \nabla \psi(y) + z.$$

$$\begin{aligned} D\phi(x, y) &= \phi(x) - \phi(y) - \langle \nabla \psi(y) + z, x - y \rangle \\ &= \psi(x) - \psi(y) + \underbrace{\langle z, x - y \rangle} - \underbrace{\langle \psi(y), x - y \rangle} - \underbrace{\langle z, x - y \rangle} \\ &= D\psi(x, y). \end{aligned}$$

$$\begin{aligned} 3. \quad \text{RHS} &= \underbrace{\psi(z) - \psi(y) - \langle \nabla \psi(y), z - y \rangle} + \underbrace{\langle \psi(z), x - z \rangle - \langle \psi(y), x - z \rangle} \\ &\quad + \underbrace{\psi(x) - \psi(z) - \langle \nabla \psi(z), x - z \rangle} \\ &= \psi(x) - \psi(y) - \langle \psi(y), x - y \rangle. = \text{LHS}. \end{aligned}$$

$$4. \quad z, \bar{x} \text{ fixed.}$$

$$\begin{aligned} h(x) &= \langle z, x \rangle + D\varphi(x, \bar{x}) & \nabla h(y) &= z + \nabla_y D\varphi(y, \bar{x}) \\ & & &= z + \nabla \psi(y) - \nabla \psi(\bar{x}) \end{aligned}$$

$$\text{follow hint, } \langle \nabla h(y), x - y \rangle = \langle z + \nabla \psi(y) - \nabla \psi(\bar{x}), x - y \rangle \geq 0.$$

$$\langle z, x \rangle \geq \langle z, y \rangle + \langle \nabla \psi(\bar{x}) - \nabla \psi(y), x - y \rangle$$

$$h(x) = \langle z, x \rangle + \psi(x) - \psi(\bar{x}) - \langle \nabla \psi(\bar{x}), x - \bar{x} \rangle$$

$$\geq \langle z, y \rangle + \langle \nabla \psi(\bar{x}) - \nabla \psi(y), x - y \rangle + \psi(x) - \psi(\bar{x}) - \langle \nabla \psi(\bar{x}), x - \bar{x} \rangle$$

$$= \langle z, y \rangle - \underbrace{\langle \nabla \psi(\bar{x}), \bar{x} - y \rangle}_{\text{D}_\psi(x, y)} - \underbrace{\langle \nabla \psi(y), x - y \rangle + (\psi(x) - \psi(y)) - (\psi(\bar{x}) - \psi(y))}_{\text{D}_\psi(y, \bar{x})}$$

$$= \langle z, y \rangle + D_\psi(x, y) + D_\psi(y, \bar{x})$$

□.

4. follow HW I, Q2

$$\nabla h_z(x) = z + \nabla \left(\frac{1}{2} \|x\|_p^2 \right)$$

$$h_z(y) - h_z(x) - \langle \nabla h_z(x), y - x \rangle = \langle z, y - x \rangle + \frac{1}{2} \|y\|_p^2 - \frac{1}{2} \|x\|_p^2 - \langle z + \nabla \left(\frac{1}{2} \|x\|_p^2 \right), y - x \rangle$$

$$= \frac{1}{2} \|y\|_p^2 - \frac{1}{2} \|x\|_p^2 - \langle \nabla \left(\frac{1}{2} \|x\|_p^2 \right), y - x \rangle$$

$$\geq \frac{1}{2} \|y\|_p^2 - \frac{1}{2} \|x\|_p^2 - \|x\|_p \|y - x\|_p \quad \|x\|_p \left(\frac{1}{2} \|x\|_p + \|y - x\|_p \right)$$

$$\stackrel{\text{p-norm}}{=} \frac{1}{2} \|y - x\|_p^2 + \frac{1}{2} \|x\|_p^2 + \|x\|_p \|y - x\|_p - \frac{1}{2} \|x\|_p^2 - \|x\|_p \|y - x\|_p = \frac{1}{2} \|y - x\|_p^2 \geq 0.$$

$\Rightarrow h_z$ is convex.

$$\text{Set } \nabla h_z(x^*) = 0. \quad \nabla \left(\frac{1}{2} \|x\|_p^2 \right) + z = 0.$$

$$\text{By Fenchel's conjugate theory, } x^* = -\nabla \left(\frac{1}{2} \|z\|_q^2 \right).$$

$$\min_x h_z(x) = h_z(x^*) = \langle z, -\nabla \left(\frac{1}{2} \|z\|_q^2 \right) \rangle + \frac{1}{2} \left\| -\nabla \left(\frac{1}{2} \|z\|_q^2 \right) \right\|_p^2$$

$$\begin{aligned}
&= \underbrace{\left\langle \tilde{z}, -\nabla \frac{1}{2} \|\tilde{z}\|_q^2 \right\rangle}_{\text{same direction}} + \frac{1}{2} \|\tilde{z}\|_q^2 \\
&= -\|\tilde{z}\|_q \underbrace{\left\| \nabla \left(\frac{1}{2} \|\tilde{z}\|_q^2 \right) \right\|_p}_{\|\tilde{z}\|_q} + \frac{1}{2} \|\tilde{z}\|_q^2 = -\frac{1}{2} \|\tilde{z}\|_q^2.
\end{aligned}$$

2. Let $S = u - x_k$.

Apply part 1,

$$h(s) = \langle \nabla f(x_k), s \rangle + \frac{L}{2} \|s\|_p^2. \quad \Rightarrow \quad h(s)_{\min} = -\frac{1}{2L} \|\nabla f(x_k)\|_q^2$$

L -smooth

$$f(x_{k+1}) = f(x_k) + \langle \nabla f(x_k), x_{k+1} - x_k \rangle + \frac{L}{2} \|x_{k+1} - x_k\|_p^2$$

$$\text{RHS min} = -\frac{1}{2L} \|\nabla f(x_k)\|_q^2 + f(x_k). \quad \Rightarrow \quad f(x_{k+1}) - f(x_k) \leq -\frac{1}{2L} \|\nabla f(x_k)\|_q^2.$$

$$\sum_{i=0}^K f(x_{i+1}) - f(x_i) = f(x_{K+1}) - f(x_0) \leq -\frac{1}{2L} \sum_{i=0}^K \|\nabla f(x_i)\|_q^2 \leq -\frac{K+1}{2L} \min_{i \in [K]} \|\nabla f(x_i)\|_q^2$$

$$\min_{i \in [K]} \|\nabla f(x_i)\|_q^2 \leq \frac{2(f(x_0) - f(x_{K+1}))}{K+1} \leq \frac{2L(f(x_0) - f^*)}{K+1}.$$

$$\min_{i \in [K]} \|\nabla f(x_i)\|_q \leq \sqrt{\frac{2L(f(x_0) - f^*)}{K+1}}.$$

Similar res.

3. $L_2 = L$ because $p=2, q=2$ is just a special case.

$$\sqrt{\frac{2L(f(x_0) - f^*)}{K+1}}.$$