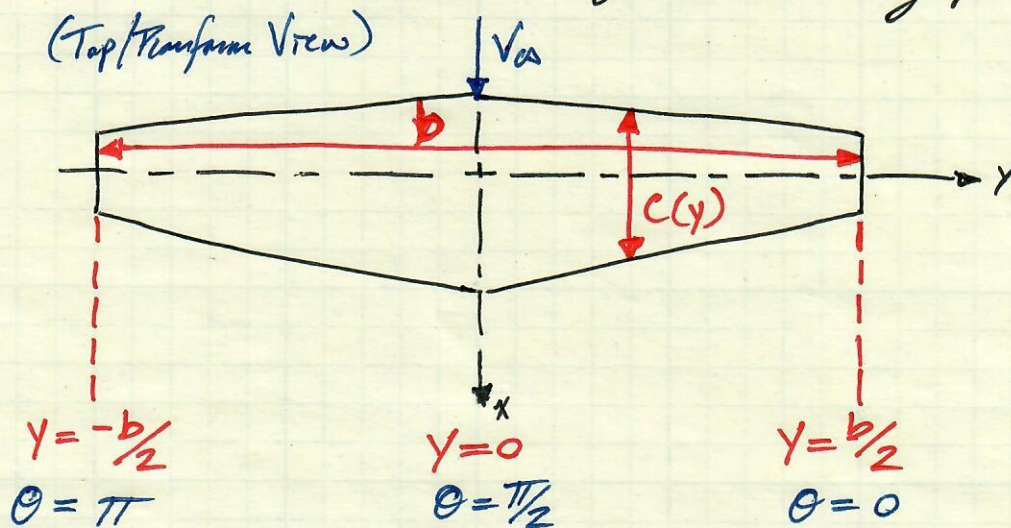


During lecture you derived the general Panetti Lifting Line Theory which predicts the influence of a General Finite Wing Planform on the total wing Lift Coefficient and Induced Drag Coefficient.

→ For Computational Assignment 4 we will apply this theory in a discrete computational framework within Matlab.

- Reference: Anderson "Fund. of Aerodynamics" (5th Ed.)  
Section 5.3.2 - General Lift Distribution

Assume we have some general wing planform,



→ Apply following transformation to spanwise position

$$y = +\frac{b}{2} \cos \theta \quad \leftarrow \text{Note Anderson defines this with } \theta=0 \text{ @ } y=-b/2 !!$$

So,

$$\theta = \cos^{-1}\left(2\frac{y}{b}\right)$$

$$y = -\frac{b}{2} \cos \theta$$

Let the wing geometry vary as a function of the wing spanwise position:

1)  $C(y) \approx C(\theta)$  - chord length varies with wing spanwise position in either  $y$  or  $\theta$ .

Note:  $C(y=0) = C(\theta=\pi/2) = C_{\text{root}}$

$C(y=\pm b/2) = C(\theta=0, \pi) = C_{\text{tip}}$



2)  $\alpha(y) \approx \alpha(\theta)$  - Geometric Angle of Attack

Note: This includes both the physical angle of attack of the wing/plane and any geometric twist applied to the wing!

3)  $\alpha_{L=0}(y) \approx \alpha_{L=0}(\theta)$  - Aerodynamic Zero-Lift Angle of Attack

Note: This accounts for changes in the zero-lift angle of attack caused by changing the airfoil profile/section across the wing!

4)  $a_0(y) \approx a_0(\theta)$  - Aerodynamic Lift-Slope

Note: This accounts for changes in the lift-slope due to changes in the airfoil thickness across the span!

↳ From Thin Airfoil Theory:  $a_0 = 2\pi$

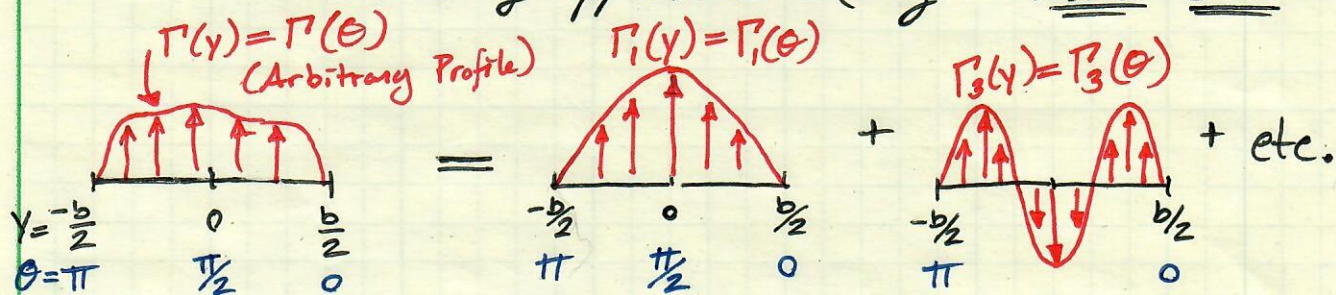
• If we assume the wing is composed of only thin sections then:

$\Gamma(y)$

$a_0(y) = \text{Constant} = 2\pi$

5)  $\Gamma(y) \approx \Gamma(\theta)$  - Bound Circulation

We assume the Bound Circulation can vary across the wing span and that the Arbitrary Profile/Distribution can be Mathematically approximated by a Fourier Series!



$$\Gamma(\theta) = \Gamma_1(\theta) + \Gamma_3(\theta) = 2bV_\infty \sin \theta + 2bV_\infty \sin 3\theta + \text{etc.}$$

$$\Gamma(\theta) = 2bV_\infty \sum_{j=1}^N A_{(2j-1)} \sin((2j-1)\theta)$$

$N=4 \quad j = \{1, 2, 3, 4\}$   
 $0, 1, 2, 3, 4$   
 $1, 3, 5, 7$



Now to solve for these "weighting" coefficients (i.e.  $A_1, A_3, \dots, A_{2N-1}$ ) we need to abide by the following equality:

$$\alpha_{\text{geometry}} = \alpha_{\text{effective}} + \alpha_{\text{induced}}$$

$$\alpha(\theta) = \frac{4b}{a_0(\theta)c(\theta)} \sum_{n=1}^{\infty} A_n \sin(n\theta) + \alpha_{L=0}(\theta) + \sum_{n=1}^N n A_n \frac{\sin(n\theta)}{\sin(\theta)}$$

*change from Anderson*  
Ideally we want to solve this for every ( $\infty$ ) spanwise positions along the wing, but to make the problem tractable we will instead solve this at  $N$  control point locations:

$$\theta_i = \frac{i\pi}{2N} \text{ where } i = 1, 2, \dots, N$$

We also limit the above "summations" to  $N$  unknown weightings in the Fourier series:

$$A_{2j-1} = A_1, A_3, \dots, A_{2N-1} \text{ where } j = 1, 2, \dots, N$$

$N$  odd modes!!

Or for an  $N=2$  system we have:

$$\begin{bmatrix} \alpha(\theta_1) - \alpha_{L=0}(\theta_1) \\ \alpha(\theta_2) - \alpha_{L=0}(\theta_2) \end{bmatrix} = \begin{bmatrix} \frac{4b}{a_0(\theta_1)c(\theta_1)} \sin(\theta_1) + 1 & \frac{4b}{a_0(\theta_1)c(\theta_1)} \sin(3\theta_1) + \frac{3\sin(3\theta_1)}{\sin(\theta_1)} \\ \frac{4b}{a_0(\theta_2)c(\theta_2)} \sin(\theta_2) + 1 & \frac{4b}{a_0(\theta_2)c(\theta_2)} \sin(3\theta_2) + \frac{3\sin(3\theta_2)}{\sin(\theta_2)} \end{bmatrix} \begin{bmatrix} A_1 \\ A_3 \end{bmatrix}$$

$b = A \cdot x$

Solve the linear system:  $Ax = b$  for  $x$  !!



Now that you have solved for  $x$  (or  $A_1, A_3, \dots, A_{2N-1}$ ), then you can compute:

$$C_L = A_1 \pi AR \quad \leftarrow \quad AR = \frac{b^2}{s}$$

$$C_{Di} = \frac{C_L^2}{\pi AR} (1 + \delta) = \frac{C_L^2}{\pi e AR}$$

where

$$\delta = \sum_{j=2}^N (2j-1) \left( \frac{A_{(2j-1)}}{A_1} \right)^2$$

↑ Span Efficiency Factor!!

$$e = \frac{1}{1+\delta}$$

Note we choose odd  $A$  coefficients because they produce symmetric contributions to  $T(\theta)$  that are consistent with level cruise.

When might we want to consider even  $A$  coefficients?