

LECTURE 12, QUANTITATIVE OPPENHEIM I

RUNLIN ZHANG

CONTENTS

1. Detect points by probabilistic methods	1
1.1. A coarse upper bound	2
1.2. The exact upper/lower bound	3
2. Proof of the Lemma	4
2.1. Nontrivial contribution to the integral	4
2.2. Representative in a K -orbit	5
2.3. Approximates I, the points	6
2.4. Approximates II, the measures	7
2.5. Proof of the lemma	9
References	10

Main reference: [EMM98, Section 3].

Notations

- $Q_0(x_1, x_2, x_3, x_4) := 2x_1x_4 + x_2^2 + x_3^2$ real quadratic form of signature $(3, 1)$ on \mathbb{R}^4 .
- Let $(\mathbf{e}_1, \dots, \mathbf{e}_4)$ be the standard basis of \mathbb{R}^4 ; and for a vector v , define its coefficients by $v = \sum (v)_i \mathbf{e}_i$ and we also write $v = ((v)_1, \dots, (v)_4)$.
- Let $(\mathbf{f}_1, \dots, \mathbf{f}_4)$ be another ONB (=orthogonal normal basis) defined by $\mathbf{f}_2 = \mathbf{e}_2, \mathbf{f}_3 = \mathbf{e}_3$ and $\mathbf{f}_1 = \frac{\mathbf{e}_1 + \mathbf{e}_4}{\sqrt{2}}, \mathbf{f}_4 = \frac{\mathbf{e}_1 - \mathbf{e}_4}{\sqrt{2}}$. If $v = \sum a_i \mathbf{f}_i$, we also write $v = (a_1, \dots, a_4)_{\mathbf{f}}$.
- One can verify that $Q_0((x_1, \dots, x_4)_{\mathbf{f}}) = x_1^2 + x_2^2 + x_3^2 - x_4^2$.
- $K := \text{SO}_{Q_0}(\mathbb{R}) \cap \text{SO}_4(\mathbb{R})$.
- $\mathbf{a}_t := \text{diag}(e^{-t}, 1, 1, e^t)$, contained in $\text{SO}_{Q_0}(\mathbb{R})$.

1. DETECT POINTS BY PROBABILISTIC METHODS

Assume $Q_0 \circ g_0$ is irrational. Define

$$V_{(a,b)}(\mathbb{Z}) := \{\mathbf{v} \in g_0 \cdot \mathbb{Z}^4 \mid Q_0(\mathbf{v}) \in (a, b)\},$$

$$N_T := \#V_{a,b}(\mathbb{Z}, T), \quad V_{a,b}(\mathbb{Z}, T) := \{\mathbf{v} \in V_{(a,b)}(\mathbb{Z}) \mid \|\mathbf{v}\| \leq T\}.$$

Consider the function

$$1_{\square}(x, y) := 1_{(1,2]}(x) \cdot 1_{(a,b)}(y).$$

Hence

$$N_{2T} - N_T = \sum_{\mathbf{v} \in g_0 \cdot \mathbb{Z}^4} 1_{\square}\left(\frac{\|\mathbf{v}\|}{T}, Q_0(\mathbf{v})\right).$$

Find a compactly supported continuous function h approximating 1_{\square} from above. Then one can find some (non-negative) $f \in C_c(\mathbb{R}_{>0} \times \mathbb{R}^3)$ such that

$$h(x, y) = \frac{1}{x^2} \int f(x, w_2, w_3, y') |dw_2 \wedge dw_3| \quad (1)$$

where $y' := \frac{y - w_2^2 - w_3^2}{2x}$.

1.1. A coarse upper bound. By abbreviating $V_{a,b}(\mathbb{Z}, 2T - T) := V_{a,b}(\mathbb{Z}, 2T) \setminus V_{a,b}(\mathbb{Z}, T)$, we have

$$\begin{aligned} N_{2T} - N_T &\leq \sum_{\mathbf{v} \in g_0 \cdot \mathbb{Z}^4, \mathbf{v} \in V_{a,b}(\mathbb{Z}, 2T - T)} h\left(\frac{\|\mathbf{v}\|}{T}, Q_0(\mathbf{v})\right) \\ &= \sum_{\mathbf{v} \in g_0 \cdot \mathbb{Z}^4, \mathbf{v} \in V_{a,b}(\mathbb{Z}, 2T - T)} \frac{T^2}{\|\mathbf{v}\|^2} \int f\left(\frac{\|\mathbf{v}\|}{T}, w_2, w_3, \frac{Q_0(\mathbf{v}) - w_2^2 - w_3^2}{2\|\mathbf{v}\| T^{-1}}\right) |dw_2 \wedge dw_3| \end{aligned} \quad (2)$$

Each summand here is either 0 or ≥ 1 since we are keeping the index $\mathbf{v} \in V_{a,b}(\mathbb{Z}, 2T - T)$.

Now we need the following lemma, to be proved later (see Lem. 2.10 where this is proved).

Lemma 1.1. *Given $f \in C_c(\mathbb{R}_{>0} \times \mathbb{R}^3)$ and $\varepsilon \in (0, 1)$, there exists $T_0 = T_0(f, \varepsilon) > 0$ such that for every $T > T_0$, for every $\mathbf{v} \in \mathbb{R}^4$ we have*

$$\left| \frac{1}{2C_4} T^2 \int f(\mathbf{a}_{\ln T} k \cdot \mathbf{v}) \widehat{m}_K(k) - \frac{T^2}{\|\mathbf{v}\|^2} \int f\left(\frac{\|\mathbf{v}\|}{T}, w_2, w_3, w_4\right) |dw_2 \wedge dw_3| \right| < \varepsilon$$

where

$$w_4 := \frac{Q_0(\mathbf{v}) - w_2^2 - w_3^2}{2\|\mathbf{v}\| T^{-1}}$$

is a function in (w_2, w_3) , for every fixed \mathbf{v} and T .

Apply Lem. 1.1 with some $\varepsilon < 0.5$, then for T sufficiently large, each $\mathbf{v} \in V_{a,b}(\mathbb{Z}, 2T - T)$, either

$$\frac{T^2}{\|\mathbf{v}\|^2} \int f\left(\frac{\|\mathbf{v}\|}{T}, w_2, w_3, \frac{Q_0(\mathbf{v}) - w_2^2 - w_3^2}{2\|\mathbf{v}\| T^{-1}}\right) = \frac{1}{2C_4} T^2 \int 2f(\mathbf{a}_t k \cdot \mathbf{v}) \widehat{m}_K(k) = 0$$

or ≥ 0.5 .

Therefore

$$\begin{aligned} N_{2T} - N_T &\leq \sum_{\mathbf{v} \in g_0 \cdot \mathbb{Z}^4, \mathbf{v} \in V_{a,b}(\mathbb{Z}, 2T - T)} 2 \cdot \frac{1}{2C_4} T^2 \int f(\mathbf{a}_t k \cdot \mathbf{v}) \widehat{m}_K(k) \\ &\leq \sum_{\mathbf{v} \in g_0 \cdot \mathbb{Z}^4} 2 \frac{1}{2C_4} T^2 \int f(\mathbf{a}_t k \cdot \mathbf{v}) \widehat{m}_K(k) = 2 \frac{1}{2C_4} T^2 \int \widetilde{f}(\mathbf{a}_t k g_0 \cdot \mathbb{Z}^4) \widehat{m}_K(k). \end{aligned} \quad (3)$$

where

$$\widetilde{f}: X_4 \rightarrow \mathbb{R} \text{ defined by } \widetilde{f}(\Lambda) := \sum_{\mathbf{v} \in \Lambda} f(\mathbf{v}).$$

If \widetilde{f} were a bounded function, then immediately we see that for some constant $C = C(f) > 0$,

$$N_{2T} - N_T \leq T^2 C \implies N_{2^n T_0} \leq T_0^2 C(1 + 4^1 + \dots + 4^{n-1}) + N_{T_0} = \frac{1 - 4^n}{1 - 4} T_0^2 C + N_{T_0} \leq (2^n T_0)^2 C + N_{T_0}.$$

This shows that for T large,

$$N_T \leq 2CT^2.$$

Unfortunately our \widetilde{f} is not bounded. Nevertheless we still have

Theorem 1.2. *There exists a constant $C = C(f) > 0$ such that*

$$\int \tilde{f}(\mathbf{a}_t k g_0 \mathbb{Z}^4) \hat{m}_K(k) \leq C$$

for all $t > 0$.

By arguments outlined above and Thm. 1.2 we get

Theorem 1.3. *There exists a constant $C > 0$ such that $N_T \leq CT^2$ for T sufficiently large.*

1.2. The exact upper/lower bound. Equipped with Thm. 1.3, let us revisit Equa. (2):

$$\begin{aligned} \frac{N_{2T} - N_T}{T^2} &\leq T^{-2} \sum_{\mathbf{v} \in g_0 \cdot \mathbb{Z}^4, \mathbf{v} \in V_{a,b}(\mathbb{Z}, 2T)} h\left(\frac{\|\mathbf{v}\|}{T}, Q_0(\mathbf{v})\right) \\ &= T^{-2} \sum_{\mathbf{v} \in g_0 \cdot \mathbb{Z}^4, \mathbf{v} \in V_{a,b}(\mathbb{Z}, 2T)} \frac{T^2}{\|\mathbf{v}\|^2} \int f\left(\frac{\|\mathbf{v}\|}{T}, w_2, w_3, Q_0(\mathbf{v})\right) |dw_2 \wedge dw_3|. \end{aligned} \quad (4)$$

Fix an $\varepsilon > 0$, the range of T such that Lem. 1.1 is not applicable is bounded. Thus

$$\frac{N_{2T} - N_T}{T^2} \leq T^{-2} \sum_{\mathbf{v} \in g_0 \cdot \mathbb{Z}^4, \mathbf{v} \in V_{a,b}(\mathbb{Z}, 2T)} \left(\frac{1}{2C_4} T^2 \int f(\mathbf{a}_t k \cdot \mathbf{v}) \hat{m}_K(k) + O(\varepsilon) \right) + O_\varepsilon(T^{-2}). \quad (5)$$

By Thm. 1.3, the number of indices is bounded by $C(2T)^2$, hence

$$\begin{aligned} \frac{N_{2T} - N_T}{T^2} &\leq T^{-2} \left(\sum_{\mathbf{v} \in g_0 \cdot \mathbb{Z}^4, \mathbf{v} \in V_{a,b}(\mathbb{Z}, 2T)} \frac{1}{2C_4} T^2 \int f(\mathbf{a}_t k \cdot \mathbf{v}) \hat{m}_K(k) \right) + O_\varepsilon(T^{-2}) + O(\varepsilon) \\ &\leq \frac{1}{2C_4} \left(\sum_{\mathbf{v} \in g_0 \cdot \mathbb{Z}^4} \int f(\mathbf{a}_t k \cdot \mathbf{v}) \hat{m}_K(k) \right) + O_\varepsilon(T^{-2}) + O(\varepsilon) \\ &= \frac{1}{2C_4} \int \tilde{f}(\mathbf{a}_t k g_0 \mathbb{Z}^4) \hat{m}_K(k) + O_\varepsilon(T^{-2}) + O(\varepsilon) \end{aligned} \quad (6)$$

Hence (let $\varepsilon \rightarrow 0$ after taking the limit \lim_T)

$$\limsup_{T \rightarrow +\infty} \frac{N_{2T} - N_T}{T^2} \leq \lim_{t \rightarrow +\infty} \int \frac{1}{2C_4} \tilde{f}(\mathbf{a}_t k g_0 \mathbb{Z}^4) \hat{m}_K(k).$$

That the RHS is a true limit is justified below.

The exact lower bound is proved similarly.

Theorem 1.4. *Assume $Q_0 \circ g_0$ is not rational, then for every $f \in C_c(\mathbb{R}^4)$,*

$$\lim_{t \rightarrow +\infty} \int \tilde{f}(\mathbf{a}_t k g_0 \mathbb{Z}^4) \hat{m}_K(k) = \int_{X_4} \tilde{f}(x) \hat{m}_{X_4}(x) = C_6 \int_{\mathbb{R}^4} f(\mathbf{v}) d\mathbf{v}$$

where $C_6 > 0$ depending only on the dimension.

Let us evaluate $\int_{\mathbb{R}^4} f(\mathbf{v}) d\mathbf{v}$ for our f . By change of variables $y' =: \frac{y - w_2^2 - w_3^2}{2x}$,

$$\int f(\mathbf{v}) d\mathbf{v} = \int f(x, w_2, w_3, y') dx dy' dw_2 dw_3 = \int \frac{1}{2x} f(x, w_2, w_3, \frac{y - w_2^2 - w_3^2}{2x}) dx dy dw_2 dw_3.$$

where we have used

$$dy' = \frac{dy - 2w_2 dw_2 - 2w_3 dw_3}{2x} - \frac{dx}{2x^2} (y - w_2^2 - w_3^2).$$

Recall Equa.(I), we have

$$\int f(\mathbf{v}) d\mathbf{v} = \int \frac{x}{2} h(x, y) dx dy.$$

As $h(x, y)$ approximates 1_{\square} we get

$$\int \frac{x}{2} h(x, y) dx dy \rightarrow \int_{y=a}^b \int_{x=1}^2 \frac{x}{2} dx dy = \frac{2^2-1}{4}(b-a).$$

Thus, by collecting the constants $C_7 := \frac{1}{2C_4} C_6 \frac{2^2-1}{4}$,

$$\lim_{T \rightarrow +\infty} \frac{N_{2T} - N_T}{T^2} = C_7(b-a).$$

Now a geometric series argument shows that

Corollary 1.5.

$$\lim_{T \rightarrow +\infty} \frac{N_T}{T^2} = \frac{1}{3} C_7(b-a).$$

2. PROOF OF THE LEMMA

2.1. Nontrivial contribution to the integral.

Definition 2.1. For $(x, y, z) \in \mathbb{R}^3$ with $x \neq 0$ and $a \in \mathbb{R}$, we let

$$\phi_a(x, y, z) := \frac{a - y^2 - z^2}{2x},$$

in other words, $\phi_a(x, y, z)$ is the unique real number such that

$$Q_0(x, y, z, \phi_a(x, y, z)) = a.$$

Definition 2.2. Given $f \in C_c(\mathbb{R}_{>0} \times \mathbb{R} \times \mathbb{R} \times \mathbb{R})$, we fix $C_1 = C_1(f) > 1$ such that

$$\text{Supp}(f) \subset (C_1^{-1}, C_1) \times (-C_1, C_1)^3.$$

Also fix $C_2 > |a_0|, |b_0|$.

The following two are something directly following from the definition.

Lemma 2.3. Let $\mathbf{v} \neq 0 \in \mathbb{R}^4$ and $T > 1$. Let $(w_2, w_3) \in \mathbb{R}^2$ be such that

$$f\left(\frac{\|\mathbf{v}\|}{T}, w_2, w_3, \phi_{Q_0(\mathbf{v})}\left(\frac{\|\mathbf{v}\|}{T}, w_2, w_3\right)\right) \neq 0,$$

then

1. $C_1^{-1} T \leq \|\mathbf{v}\| \leq C_1 T$ and $|w_2|, |w_3| \leq C_1$;
2. $\left|\phi_{Q_0(\mathbf{v})}\left(\frac{\|\mathbf{v}\|}{T}, w_2, w_3\right)\right| \leq C_1$;
3. $|Q_0(\mathbf{v})| \leq 4C_1^2$.

For a vector \mathbf{w} , $\mathbf{w}(i) \in \mathbb{R}$ is defined by $\mathbf{w} = \sum \mathbf{w}(i) \mathbf{e}_i$.

Lemma 2.4. Let $\mathbf{v} \neq 0 \in \mathbb{R}^4$ and $T > 1$. Let $\mathbf{w} \in K \cdot \mathbf{v}$. If $f(\mathbf{a}_{\ln T} \cdot \mathbf{w}) \neq 0$, then

1. $C_1^{-1} T \leq \mathbf{w}(1) \leq C_1 T$, $|\mathbf{w}(2)|, |\mathbf{w}(3)| \leq C_1$ and $|\mathbf{w}(4)| \leq C_1 T^{-1}$;
2. $\|\mathbf{v}\| \leq 2C_1 T$;
3. $\|\mathbf{v}\| \geq C_1^{-1} T$;
4. $|Q_0(\mathbf{v})| \leq 4C_1^2$.

Proof. For item 3, $\|\mathbf{v}\| = \|\mathbf{w}\| \geq \mathbf{w}(1) \geq C_1^{-1} T$.

For item 4, $Q_0(\mathbf{v}) = Q_0(\mathbf{w}) = \mathbf{w}(1)\mathbf{w}(4) + \mathbf{w}(2)^2 + \mathbf{w}(3)^2 \leq 2C_1^2 + C_1^2 + C_1^2 = 4C_1^2$. \square

2.2. Representative in a K -orbit. By working with the basis \mathbf{f} , one sees that for every $\mathbf{v} \in \mathbb{R}^4$, there exists $k_{\mathbf{v}} \in K$ such that

$$k_{\mathbf{v}} \cdot \mathbf{v} = (u_1, 0, 0, u_4)_{\mathbf{f}} \text{ for some } u_1, u_4 \geq 0.$$

Indeed, if we set

$$r_1(\mathbf{v}) := \frac{\|\mathbf{v}\| + Q_0(\mathbf{v})}{2}, \quad r_2(\mathbf{v}) := \frac{\|\mathbf{v}\| - Q_0(\mathbf{v})}{2}$$

or equivalently,

$$r_1(\mathbf{v}) := \mathbf{v}_{\mathbf{f}(1)}^2 + \mathbf{v}_{\mathbf{f}(2)}^2 + \mathbf{v}_{\mathbf{f}(3)}^2, \quad r_2(\mathbf{v}) := \mathbf{v}_{\mathbf{f}(4)}^2$$

where we assume $\mathbf{v} = (\mathbf{v}_{\mathbf{f}(1)}, \dots, \mathbf{v}_{\mathbf{f}(4)})_{\mathbf{f}}$. Then there exists $k \in K$ such that

$$k \cdot \mathbf{v} = (\sqrt{r_1}, 0, 0, \sqrt{r_2})_{\mathbf{f}} =: \mathbf{v}^*.$$

To summarize the discussion in the basis \mathbf{e} :

Lemma 2.5. *For every $\mathbf{v} \in \mathbb{R}^4$ there exists a unique $\mathbf{v}^* \in \mathbb{R}^4$ satisfying*

1. $Q_0(\mathbf{v}^*) = Q_0(\mathbf{v})$;
2. $\|\mathbf{v}^*\| = \|\mathbf{v}\|$;
3. $\mathbf{v}^*(1) \geq |\mathbf{v}^*(4)|$ and $\mathbf{v}^*(2) = \mathbf{v}^*(3) = 0$.

Also $\mathbf{v}^* \in K \cdot \mathbf{v}$.

What we are going to need is the following slightly perturbed version.

Lemma 2.6. *Let $\mathbf{v} \in \mathbb{R}^4$ and $(w_2, w_3) \in \mathbb{R}$ satisfying $|w_2|, |w_3| \leq C_1$. Assume $\|\mathbf{v}\|^2 \geq Q_0(\mathbf{v}) + 4C_1^2$. Then there exists a unique $\mathbf{v}^*(w_2, w_3) = \mathbf{w} \in \mathbb{R}^4$ such that*

1. $Q_0(\mathbf{w}) = Q_0(\mathbf{v})$;
2. $\|\mathbf{w}\| = \|\mathbf{v}\|$;
3. $\mathbf{w}(1) \geq |\mathbf{w}(4)|$ and $\mathbf{w}(2) = w_2, \mathbf{w}(3) = w_3$.

Also $\mathbf{w} \in K \cdot \mathbf{v}$.

Sketch of proof. Indeed under the assumption above

$$\left| \frac{Q_0(\mathbf{v}) - w_2^2 - w_3^2}{2} \right| \leq \frac{1}{2}(Q_0(\mathbf{v}) + 2C_1^2)$$

and

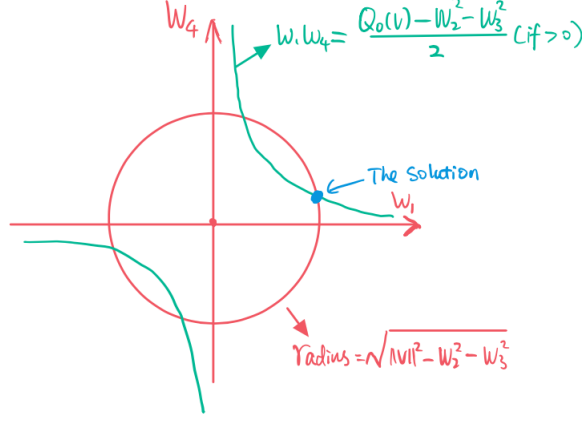
$$\|\mathbf{v}\|^2 - w_2^2 - w_3^2 \geq Q_0(\mathbf{v}) + 4C_1^2 - C_1^2 - C_1^2 = Q_0(\mathbf{v}) + 2C_1^2.$$

Hence the equation

$$\begin{cases} xy = \frac{Q_0(\mathbf{v}) - w_2^2 - w_3^2}{2} \\ x^2 + y^2 = \|\mathbf{v}\|^2 - w_2^2 - w_3^2 \end{cases}$$

admits a unique solution with $x \geq |y|$.

Here is a picture ($x = w_1, y = w_4$)



□

2.3. Approximates I, the points.

Lemma 2.7. *Assumption as in Lem.2.3. Further assume $T \geq 8C_1^3$ and $T^2 \geq 16C_1^4$. Define $\mathbf{w} = \mathbf{v}^*(w_2, w_3)$ as in Lem.2.6. Then for $C_3 = 46C_1^7$,*

$$\text{dist}_\infty \left(\left(\frac{\|\mathbf{v}\|}{T}, w_2, w_3, \phi_{Q_0(\mathbf{v})} \left(\frac{\|\mathbf{v}\|}{T}, w_2, w_3 \right) \right), \mathbf{a}_{\ln T} \cdot \mathbf{w} \right) \leq C_3 T^{-2}.$$

Note that $T \geq 8C_1^3 \implies \|\mathbf{v}\| \geq 4C_1^2 + 4C_1^2 \geq Q_0(\mathbf{v}) + 4C_1^2$ by Lem.2.3. Thus Lem.2.6 is applicable.

Proof. First we have

$$|\mathbf{w}(4)|^2 \leq |\mathbf{w}(1)| |\mathbf{w}(4)| = |Q_0(\mathbf{v}) - w_2^2 - w_3^2| \leq 4C_1^2 + 2C_1^2 = 6C_1^2.$$

Hence the difference of the first coordinate:

$$\begin{aligned} |\|\mathbf{v}\|^2 - \mathbf{w}(1)^2| &= \mathbf{w}(2)^2 + \mathbf{w}(3)^2 + \mathbf{w}(4)^2 \leq 8C_1^2 \\ \implies |T^{-1} \|\mathbf{v}\| - T^{-1} \mathbf{w}(1)| &\leq T^{-1} \frac{8C_1^2}{\|\mathbf{v}\| + \mathbf{w}(1)} \leq T^{-1} \frac{8C_1^2}{\|\mathbf{v}\|} \leq 8C_1^3 T^{-2} \leq C_3 T^{-2}. \end{aligned}$$

From here we also see that

$$|\mathbf{w}(1)| \geq \|\mathbf{v}\| - 8C_1^3 T^{-1} \geq \frac{1}{2} C_1^{-1} T + \left(\frac{1}{2} C_1^{-1} T - 8C_1^3 T^{-1} \right) \geq \frac{1}{2} C_1^{-1} T.$$

Here we are using the assumption $T^2 \geq 16C_1^4 \implies \frac{1}{2} C_1^{-1} T - 8C_1^3 T^{-1} \geq 0$.

Now the difference of the last coordinate (note that $w_2 = \mathbf{w}(2)$ and $w_3 = \mathbf{w}(3)$ from Lem.2.6)

$$\begin{aligned} & \left| \frac{Q_0(\mathbf{v}) - \mathbf{w}(2)^2 - \mathbf{w}(3)^2}{2 \|\mathbf{v}\| T^{-1}} - \frac{Q_0(\mathbf{v}) - \mathbf{w}(2)^2 - \mathbf{w}(3)^2}{2 \mathbf{w}(1) T^{-1}} \right| \\ & \leq \frac{1}{2} (6C_1^2) T \left| \frac{1}{\|\mathbf{v}\|} - \frac{1}{\mathbf{w}(1)} \right| = \frac{(6C_1^2) T}{2} \frac{|\|\mathbf{v}\| - \mathbf{w}(1)|}{\|\mathbf{v}\| \mathbf{w}(1)} \\ & \leq \frac{(6C_1^2) T}{2} \frac{8C_1^3 T^{-1}}{1/2 C_1^{-2} T^2} = 48C_1^7 T^{-2} \leq C_3 T^{-2}. \end{aligned}$$

□

Lemma 2.8. *Assumption as in Lem. 2.4. Define $w_2 := \mathbf{w}(2)$ and $w_3 := \mathbf{w}(3)$. Then for $C_3 = 48C_1^7$,*

$$\text{dist}_\infty \left(\left(\frac{\|\mathbf{v}\|}{T}, w_2, w_3, \phi_{Q_0(\mathbf{v})} \left(\frac{\|\mathbf{v}\|}{T}, w_2, w_3 \right) \right), \mathbf{a}_{\ln T \cdot \mathbf{w}} \right) \leq C_3 T^{-2}.$$

Proof. The difference of the first coordinate:

$$\begin{aligned} \left| \|\mathbf{v}\|^2 - \mathbf{w}(1)^2 \right| &= \mathbf{w}(2)^2 + \mathbf{w}(3)^2 + \mathbf{w}(4)^2 \leq 3C_1^2 \\ \Rightarrow \left| T^{-1} \|\mathbf{v}\| - T^{-1} \mathbf{w}(1) \right| &\leq T^{-1} \frac{3C_1^2}{\mathbf{w}(1)} \leq 3C_1^3 T^{-2} \leq C_3 T^{-2}. \end{aligned}$$

And the difference of the last coordinate

$$\begin{aligned} &\left| \frac{Q_0(\mathbf{v}) - \mathbf{w}(2)^2 - \mathbf{w}(3)^2}{2 \|\mathbf{v}\| T^{-1}} - \frac{Q_0(\mathbf{v}) - \mathbf{w}(2)^2 - \mathbf{w}(3)^2}{2 \mathbf{w}(1) T^{-1}} \right| \\ &\leq \frac{T}{2} (6C_1^2) \left| \frac{1}{\|\mathbf{v}\|} - \frac{1}{\mathbf{w}(1)} \right| = \frac{(6C_1^2) T}{2} \frac{\|\mathbf{v}\| - \mathbf{w}(1)}{\|\mathbf{v}\| \mathbf{w}(1)} \\ &\leq \frac{(6C_1^2) T}{2} \frac{3C_1^3 T^{-1}}{C_1^{-2} T^2} = 9C_1^7 T^{-2} \leq C_3 T^{-2}. \end{aligned}$$

□

2.4. Approximates II, the measures. Let $S(r)$ be the sphere of radius r in \mathbb{R}^3 centered at the origin. Let $\hat{\mathbf{m}}_{S(r)}$ be the normalized (to be a probability measure) volume measure on $S(r)$.

Assume $r_1(\mathbf{v}) \geq 2C_1^2$. For $(x_2, x_3) \in \mathbb{R}^2$ with $|x_2|, |x_3| \leq C_1$, there exists a unique $x_1 > 0$ such that

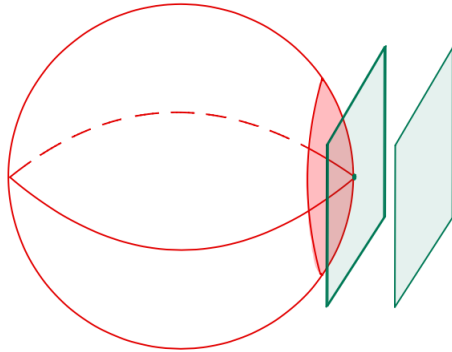
$$x_1^2 + x_2^2 + x_3^2 = r_1(\mathbf{v}).$$

Let $D(C_1)$ be the image of $\{(x_2, x_3), |x_2|, |x_3| \leq C_1\}$ in $S(\sqrt{r_1})$ thus defined. And identify $|\mathrm{d}x_2 \wedge \mathrm{d}x_3|_{|x_i| \leq C_1}$ as a measure on $D(C_1) \subset S(\sqrt{r_1})$ by this. Equivalently one may first restrict the differential form $\mathrm{d}x_2 \wedge \mathrm{d}x_3$ to $D(C_1)$ and then take the measure associated with it.

Lemma 2.9. *Let $\mathbf{v} \in \mathbb{R}^4$ be satisfying $\frac{\|\mathbf{v}\|^2}{2} \geq |Q_0(\mathbf{v})|$ and $\|\mathbf{v}\|^2 \geq 16C_1^2$.*

$$\left\| \|\mathbf{v}\|^2 \hat{\mathbf{m}}_{S(\sqrt{r_1})} - 2C_4 |\mathrm{d}w_2 \wedge \mathrm{d}w_3| \right\|_{D(C_1)} \leq \frac{1}{\|\mathbf{v}\|^2} (C_5 Q_0(\mathbf{v}) + C_5)$$

where $C_4 > 0$ is a constant depending only on the dimension and $C_5 > 1$ depends on C_1 . See Equa. (7), (8) below.



Note that our assumption implies that $r_1(\mathbf{v}) = 1/2(\|\mathbf{v}\|^2 + Q_0(\mathbf{v})) \geq 4C_1^2$. Thus the paragraph above the proposition makes sense.

Proof. First let us write $\widehat{m}_{S(\sqrt{r_1})}$ in terms of differential forms. By taking the differential

$$x_1^2 + x_2^2 + x_3^2 = r^2 \implies 2x_1 dx_1 + 2x_2 dx_2 + 2x_3 dx_3 = 2r dr.$$

Thus

$$dx_1 \wedge dx_2 \wedge dx_3 = \frac{r dx_2 \wedge dx_3}{x_1} \wedge dr$$

So up to constant (depending possibly on r), the spherical measure can be induced from $\frac{r dx_2 \wedge dx_3}{x_1}$. To make it have total mass independent of r , we consider

$$dx_1 \wedge dx_2 \wedge dx_3 = \frac{dx_2 \wedge dx_3}{r x_1} \wedge r^2 dr.$$

Since the volume of ball of radius R is some constant multiple of $R^3/3 = \int_0^R r^2 dr$, there exists some constant $C_4 > 0$ depending only on the dimension such that

$$\widehat{m}_{S(\sqrt{r_1})} = C_4 \frac{dx_2 \wedge dx_3}{\sqrt{r_1} x_1}. \quad (7)$$

By assumption,

$$2r_1 = \|\mathbf{v}\|^2 + Q_0(\mathbf{v}) \geq \|\mathbf{v}\|^2 - |Q_0(\mathbf{v})| \geq \frac{1}{2} \|\mathbf{v}\|^2 \implies r_1 \geq 4C_1^2.$$

Thus for $(x_1, x_2, x_3) \in S(\sqrt{r_1})$,

$$2\sqrt{r_1}x_1 = 2\sqrt{r_1}\sqrt{r_1 - x_2^2 - x_3^2} \geq \|\mathbf{v}\| \sqrt{r_1 - 2C_1^2} \geq \|\mathbf{v}\| \sqrt{\frac{1}{2}r_1} \geq \frac{\|\mathbf{v}\|^2}{8}.$$

On the other hand

$$|\|\mathbf{v}\|^2 - 2r_1| = |Q_0(\mathbf{v})|$$

and

$$|2r_1 - 2\sqrt{r_1}x_1| = 2\sqrt{r_1} \left| \frac{r_1 - (r_1 - x_2^2 - x_3^2)}{\sqrt{r_1} + \sqrt{r_1 - x_2^2 - x_3^2}} \right| \leq 2|x_2^2 + x_3^2| \leq 4C_1^2.$$

Therefore, when restricted to $D(C_1)$, we have

$$\begin{aligned} \left| \|\mathbf{v}\|^2 \widehat{m}_{S(\sqrt{r_1})} - 2C_4 |dx_2 \wedge dx_3| \right| &= 2C_4 \left| \frac{\|\mathbf{v}\|^2}{2\sqrt{r_1}x_1} - 1 \right| |dx_2 \wedge dx_3| \\ &= 2C_4 \left| \frac{\|\mathbf{v}\|^2 - 2\sqrt{r_1}x_1}{2\sqrt{r_1}x_1} \right| |dx_2 \wedge dx_3| \\ &\leq 2C_4 \left| \frac{|Q_0(\mathbf{v})| + 4C_1^2}{\frac{1}{4}\|\mathbf{v}\|^2} \right| |dx_2 \wedge dx_3| \end{aligned}$$

Thus if integrating a function taking value in $[-M, M]$, the difference is at most

$$2C_4 \left| \frac{Q_0(\mathbf{v}) + 4C_1^2}{\frac{1}{8}\|\mathbf{v}\|^2} \right| (2C_1)^2 \cdot M = \|\mathbf{v}\|^{-2} \cdot |64C_4 C_1^2 (|Q_0(\mathbf{v})| + 4C_1^2)| \cdot M.$$

Taking

$$C_5 := 256C_4 C_1^4 \quad (8)$$

completes the proof. \square

2.5. Proof of the lemma. Fix $\mathbf{v} \in \mathbb{R}^4$, we identify $S(r)$ with a subset of \mathbb{R}^4 by embedding

$$(x_1, x_2, x_3) \mapsto (x_1, x_2, x_3, \sqrt{r_2(\mathbf{v})})_{\mathbf{f}}.$$

Let us state Lem. 1.1 again:

Lemma 2.10. *Given $f \in C_c(\mathbb{R}_{>0} \times \mathbb{R}^3)$ and $\varepsilon \in (0, 1)$, there exists $T_0 = T_0(f, \varepsilon) > 0$ such that for every $T > T_0$, for every $\mathbf{v} \in \mathbb{R}^4$ we have*

$$\left| \frac{1}{2C_4} T^2 \int f(\mathbf{a}_{\ln T} k \cdot \mathbf{v}) \hat{m}_K(k) - \frac{T^2}{\|\mathbf{v}\|^2} \int f\left(\frac{\|\mathbf{v}\|}{T}, w_2, w_3, w_4\right) |dw_2 \wedge dw_3| \right| < \varepsilon$$

where

$$w_4 := \frac{Q_0(\mathbf{v}) - w_2^2 - w_3^2}{2\|\mathbf{v}\|T^{-1}}$$

is a function in (w_2, w_3) , for every fixed \mathbf{v} and T .

Proof. We are going to choose some $T_0 \geq 10C_1^3$.

Rewrite

$$\frac{1}{2C_4} T^2 \int f(\mathbf{a}_{\ln T} k \cdot \mathbf{v}) \hat{m}_K(k) = \frac{1}{2C_4} T^2 \int f(\mathbf{a}_{\ln T} \cdot \mathbf{w}) \hat{m}_{K, \mathbf{v}}(\mathbf{w})$$

By Lem. 2.4, 2.6, if $T \geq T_0$, by change of variable $\mathbf{w} \mapsto (w_2, w_3) := (\mathbf{w}(2), \mathbf{w}(3))$:

$$\begin{aligned} \frac{1}{2C_4} T^2 \int f(\mathbf{a}_{\ln T} \cdot \mathbf{w}) \hat{m}_{K, \mathbf{v}}(\mathbf{w}) &= \frac{1}{2C_4} T^2 \int_{f(\mathbf{a}_{\ln T} \cdot \mathbf{w}) \neq 0} f(\mathbf{a}_{\ln T} \cdot \mathbf{w}) \hat{m}_{K, \mathbf{v}}(\mathbf{w}) \\ &= \frac{1}{2C_4} T^2 \int_{D(C_1)} f(\mathbf{a}_{\ln T} \cdot \mathbf{v}^*(w_2, w_3)) \hat{m}_{S(\sqrt{r_1})}(w_2, w_3). \end{aligned}$$

Note that when $f(\mathbf{a}_{\ln T} k \cdot \mathbf{v}) \neq 0$ for some $k \in K$, $T \geq 10C_1^3 \implies \|\mathbf{v}\|^2 \geq Q_0(\mathbf{v}) + 4C_1^2$ by Lem. 2.4. So Lem. 2.6 is applicable to \mathbf{v} and $(w_2, w_3) := (\mathbf{w}(2), \mathbf{w}(3))$. Moreover, Lem. 2.6 implies that $\mathbf{w} = \mathbf{v}^*(\mathbf{w}(2), \mathbf{w}(3))$.

By Lem. 2.3, the RHS is equal to

$$\frac{T^2}{\|\mathbf{v}\|^2} \int f\left(\frac{\|\mathbf{v}\|}{T}, w_2, w_3, w_4\right) |dw_2 \wedge dw_3| = \frac{T^2}{\|\mathbf{v}\|^2} \int_{D(C_1)} f\left(\frac{\|\mathbf{v}\|}{T}, w_2, w_3, w_4\right) |dw_2 \wedge dw_3|$$

Recall from Lem. 2.3 and 2.4 that when $f(\mathbf{a}_{\ln T} \cdot \mathbf{w}) \neq 0$ or when $f\left(\frac{\|\mathbf{v}\|}{T}, w_2, w_3, w_4\right) \neq 0$, we always have

$$\frac{1}{C_1} T \leq \|\mathbf{v}\| \leq 2C_1 T$$

and

$$|Q_0(\mathbf{v})| \leq 4C_1^2. \quad (9)$$

Now it suffices to show that

$$\left| \|\mathbf{v}\|^2 \int_{D(C_1)} f(\mathbf{a}_{\ln T} \cdot \mathbf{w}) \hat{m}_{S(\sqrt{r_1})}(w_2, w_3) - 2C_4 \int_{D(C_1)} f\left(\frac{\|\mathbf{v}\|}{T}, w_2, w_3, w_4\right) |dw_2 \wedge dw_3| \right| < \varepsilon.$$

By Lem. 2.7 and 2.8, for T large enough,

$$\left| 2C_4 \int_{D(C_1)} f(\mathbf{a}_{\ln T} \cdot \mathbf{w}) |dw_2 \wedge dw_3| - 2C_4 \int_{D(C_1)} f\left(\frac{\|\mathbf{v}\|}{T}, w_2, w_3, w_4\right) |dw_2 \wedge dw_3| \right| < 0.5\varepsilon.$$

By Lem. 2.9 and Equa. (9), for T large enough,

$$\left| \|\mathbf{v}\|^2 \int_{D(C_1)} f(\mathbf{a}_{\ln T} \cdot \mathbf{w}) \hat{m}_{S(\sqrt{r_1})}(w_2, w_3) - 2C_4 \int_{D(C_1)} f(\mathbf{a}_{\ln T} \cdot \mathbf{w}) |dw_2 \wedge dw_3| \right| < 0.5\varepsilon.$$

Combining these two, we are done. \square

REFERENCES

- [EMM98] Alex Eskin, Gregory Margulis, and Shahar Mozes, *Upper bounds and asymptotics in a quantitative version of the Oppenheim conjecture*, Ann. of Math. (2) **147** (1998), no. 1, 93–141. MR 1609447