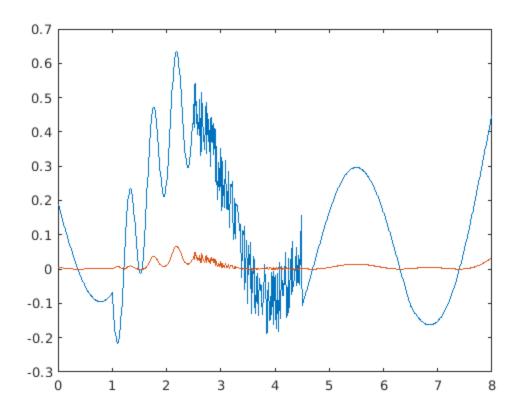
Laboratorijas darbs 4

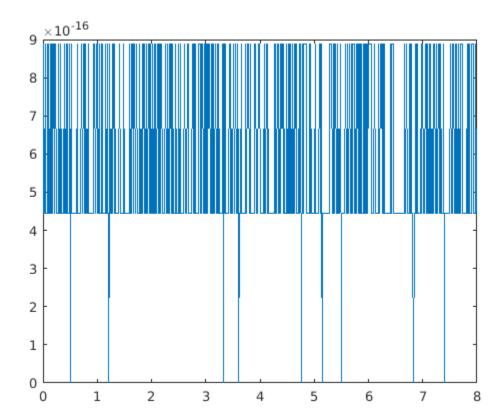
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Salvis Timošenko

```
R1=1;R2=2;R3=3;R4=10;R5=5;R6=6;R7=7;
t = 0:0.01:8;
E3=lab3_demo_fun(t);
E2=sin(2*t);
E1=2;
R8=8;
R = [R1+R2+R3 -R2 0;
-R2 R2+R4+R5+R6 -R5;
0 -R5 R5+R7+R8];
E1=2*ones(size(t));
E = [E1; -E2; -E3];
R_m_p = inv(R);
Ik = R \setminus E;
IR6 = Ik(2,:);
UR6 = IR6*R6;
plot(t,UR6)
PR6 = UR6.*IR6;
hold on
plot(t,PR6)
%Utst = Ur3+Ur2+Ur1-E1;
% figure, plot(t,Utst)
IR3 = Ik(1,:);
UR3 = IR3*R3;
IR2 = Ik(1,:)-Ik(2,:);
UR2 = IR2*R2;
IR1 = Ik(1,:);
UR1 = IR1*R1;
Utst = UR3+UR2+UR1-E1;
figure,plot(t,Utst)
```





Pats spriegums ir #oti main#gs,att#lot#j# grafik# ir redzems,k# sv#rst#s spriegums Jauda, k# redzams att#l#,ir diezgan l#dzsvarota.

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