

Quasi MC method

Note to approx. $I(f) := \int_{[0,1]^d} f(x) dx$. We use $X_k \stackrel{i.i.d.}{\sim} U[0,1]^d$ and set $J_n(f) = n^{-1} \sum_{i=1}^n f(x_i)$ to apply MC method.

But the idea of QMC is to replace (X_k) by seq of deterministic numbers $(x_i) \subset [0,1]^d$ which distributes "evenly" to mimic $X_k \stackrel{i.i.d.}{\sim} [0,1]^d$.

(1) Definition:

Def: $\lambda = \mathcal{L}_1|_{[0,1]^d}$ restriction of Lebesgue measure on $[0,1]^d$. $R = \bigotimes_{i=1}^d [a_i, b_i)$ is rectangle subset in $[0,1]^d$.

i) Discrepancy D_n of $(x_i)_{i=1}^n$ is:

$$D_n := \sup_R |n^{-1} \# \{x_i \in R, 1 \leq i \leq n\} - \lambda(R)|$$

ii) $D_n^* := \sup \{ |n^{-1} \# \{x_i \in R, 1 \leq i \leq n\} - \lambda(R)| :$

$$R = \bigotimes_{i=1}^d [0, b_i) \}.$$

iii) Markov - Kravarc Variation is recursively defined by: for $f: [0,1]^k \rightarrow \mathbb{R}'$.

$$V(f) = \int_{[0,1]^k} \left| \frac{\partial^k f}{\partial x^1 \dots \partial x^k} \right| dx + \sum_{j=1}^k V(f_j^{(j)}),$$

where $f_j^{(j)} = f|_{x_j=1}$

$$\text{And } V(f) = \int_0^1 \left| \frac{\partial f}{\partial x} \right| dx, \quad f: [0,1] \rightarrow \mathbb{R}'.$$

Remark: Note that the V will depend on $L(X_k)$ and regularity of f .
LHC will require more on f .

Thm. (Koksma - Mal'var inequality.)

$\forall f \in L^1([0,1]^k; \mathbb{R}') \cap C^{(1, \dots, 1)}$. We have:

$$|I(f) - I_m(f)| \leq V(f) D_m^*$$

Remark: i) It's a deterministic bound.

ii) Even we need regularity on f .
it still works better practically.

Pf: For $k=1$, $f \in C^1$. Note that

$$f(x) = f(1) - \int_0^1 f'(t) I_{[x,1]}(t) dt.$$

$$S_0: |I(f) - I_m(f)| =$$

$$\begin{aligned}
& \left| \int_0^1 f'(t) \left(\frac{1}{m} \sum_{i=1}^m I_{[x_i, 1]}(t) - \int_0^1 I_{[x, 1]}(t) dx \right) dt \right| \\
& \leq \int_0^1 |f'(t)| \left| \frac{1}{m} \sum_{i=1}^m I_{[x_i, 1]}(t) - \int_0^1 I_{[x, 1]}(t) dx \right| dt \\
& \leq V(f) D_m^*.
\end{aligned}$$

For k -dim:

$$\begin{aligned}
\text{Note } f(x_1, \dots, x_k) &= \int_0^1 \dots \int_0^1 \frac{\partial^k}{\partial x_1 \dots \partial x_k} f(t_1, \dots, t_k) I_{[x_1, t_1]}(x_1) \dots I_{[x_k, t_k]}(x_k) dt_1 \dots dt_k.
\end{aligned}$$

$$\Rightarrow |I(f) - I_m(f)| \leq V(f) D_m^*$$

Def: $(x_i)_{i=1}^m \in [0, 1]^k$ is low discrepancy if $D_m^* \leq C(\log m)^k / m$.

Prop: (x_i) is 1-dim low discrepancy $\Rightarrow (x_{i-1}, x_{i+1}, \dots, x_k)$ is also k -dim low discrepancy. (Although it's true as for "uniform")

Ex. $\psi_p(k) = \sum_{j=0}^{p-1} a_j(k) / p^{j+1}$ for $k = \sum_{j=0}^{\infty} a_j(k) \cdot p^j$ (p -adic expansion)

$x_i = \psi_p(i)$, $i \in \mathbb{N}$. Van der Corput seq. is low discrepancy.

Prop: Multin Log. $X_i = (X_i^1, \dots, X_i^K)$. s.t.

$X_i^j = \gamma_{p_j}(i)$. (p_j 's are primes)
is K -dim generalization.

Low dim.:

level of even dist. deteriorates in the dimension. e.g., First two coordinates (X_i^1, X_i^2) has better uniformity than last two coordinates (X_i^{K-1}, X_i^K) .

And we require more regularity on f when $\dim \uparrow$.

Prop: Usually we expect $f(x_1, x_2, \dots, x_K)$ can be re-comp. in: $\sum f^{(i_1, \dots, i_K)}(x^{i_1}, \dots, x^{i_K})$. So: the accuracy can be improved.

(2) denormalized QMC:

Note that QMC has faster converge ($O(h^{1-\epsilon})$) than MC ($O(h^{\frac{1}{2}})$). But it lacks of good error control.

Next, we see we can actually combine QMC and MC.

For (X_i) a-dim low discrepancy. Use i.i.d. $U[0,1]^d$ r.v. Set $X_u := (X_i + U \pmod{1})$

$J_{m,m}^k(f) = \frac{1}{m} \sum_{i=1}^m J_m(f, X_u)$. mean of QMC

RM: m is to compute the error estimate which bases on $\text{Var}(J_m(f, X))$. And M controls error of it.

(3) Pricing American option:

For f payoff func. We want to know NA price: $\sup \{ E[e^{-rt} f(X_t) \mid Z \in W] \mid t \leq T \}$.

But in reality, we can't exercise the option continuously but only on finite times: t_1, \dots, t_m .

RM: It's called Bermudan options.

Next, we assume:

- i) interest rate $r = 0$.
- ii) Under risk-neutral p.m. IP.
- iii) The option can only be exercised at times $0 = t_0 < t_1 < t_2 \dots < t_m = T$.
- iv) Stock price $X_i := X_{t_i}$ is a $\tilde{\mathbb{P}}$ -Markov Chain (dist. is given)

Dynamic programming:

Denote $f_i(x)$ is payoff func. of option at time i given $X_i = x$ and $V_i(x)$ is value of option at time i given $X_i = x$

RMK: We have $f_m(x) = f(x) =$

$$\mathbb{E} \left(e^{-r(m-i)} f(X_m) \mid X_i = x \right) = V_m(x)$$

$$(V_i(x) = \mathbb{E} \left(e^{-r(m-i)} f(X_m) \mid X_i = x \right))$$

By Bellman's equation: for $i < m$,

$V_i(x) = \max \{ f_i(x), \text{expected value at next step if keeping holding} \}$.

$$= \max \{ f_i(x), \mathbb{E} \left(V_{i+1}(X_{i+1}) \mid X_i = x \right) \}.$$

\Rightarrow Recursively, we can determine the price $V_0(x)$ of the option.

Denote $C_i(x) = \mathbb{E}(V_{i+1}(X_{i+1}) | X_i = x)$ continuation value which should be calculated

at each time i . $\Rightarrow V_i(x) = f_i(x) \vee C_i(x)$

Set $Z^* = \min \{i \in \{1, \dots, n\} \mid f_i(X_i) \geq V_i(X_i)\}$.

LEM. Z^* is the optimal stopping time. i.e.

$$V_0^{(Z^*)}(X_0) = \mathbb{E}(f_{Z^*}(X_{Z^*})) = \sup_{\tau \geq 0} \mathbb{E}(f_\tau(X_\tau)) = V_0(X_0)$$

Proof: Replace $V_i(X_i)$ by $C_i(X_i)$ on Z^*

above. It still works.

Pf: Note $(V_i(X_i))_{i \leq Z^*}$ is mart.

Since $V_i(X_i) > f_i(X_i)$, $\forall i < Z^*$.

$$\begin{aligned} \Rightarrow \text{LHS} &\stackrel{\text{mf}}{\geq} \mathbb{E}(V_{Z^*}(X_{Z^*})) \\ &= \mathbb{E}(\mathbb{E}(V_{Z^*}(X_{Z^*}) | X_{Z^*-1})) \\ &= \mathbb{E}(V_{Z^*-1}(X_{Z^*-1})) \\ &= \dots = V_0(X_0). \end{aligned}$$

Assume we're given estimate price $\bar{V}_i(x)$

of $V_i(x)$ and define \bar{z} as above.

$$J_2 = V_0^{(\bar{z})}(x_0) \leq V_0(x_0). \quad (\bar{z} \text{ may not be optimal})$$

Let $\bar{V}_i(x)$ is obtained by:

$$\bar{V}_m(x) = f_m(x).$$

$$\bar{V}_{i-1}(x) := \max \{ f_{i-1}(x), I(V_i(x_i) | X_i = x) \}$$

where $I(Y|X)$ is unbiased estimator s.t.

$$\mathbb{E}(I(Y|X)) = \mathbb{E}(\mathbb{E}(Y|X)) = \mathbb{E}(Y)$$

Prop: $\bar{V}_i(x)$ is r.v. unless I is truly
conditional expectation.

Lemma: $(\bar{V}_i(x))$ bins higher. i.e. $i = 0, \dots, m$.

$$\mathbb{E}(\bar{V}_i(x_i) | x_i) \geq V_i(x_i).$$

Pf: By backward induction, note
that it holds if $i = m$.

$$\mathbb{E}(\bar{V}_{i-1}(x_{i-1}) | x_{i-1}) =$$

$$\mathbb{E}(\max \{ f_{i-1}(x_{i-1}), I(\bar{V}_i(x_i) | x_i) \} | x_{i-1})$$

$$\stackrel{\text{Jensen}}{\geq} \max \{ f_{i-1}(x_{i-1}), \mathbb{E}(\mathbb{E}(\bar{V}_i(x_i) | x_i)) \}$$

$$= \max \{ f_{i-1}(x_{i-1}), \mathbb{E}(\mathbb{E}(\bar{V}_i(x_i) | x_i) | x_{i-1}) \}$$

$$\text{hypo.} \Rightarrow \max \{ f_{i-1}(x_{i-1}), \mathbb{E}[V_i(x_i) | x_{i-1}] \} = V_{i-1}(x_{i-1})$$

Proof: So using $\bar{V}_i(x)$ to construct

\bar{V} implies $V_i^{(z)}$ will bias low

(since \bar{V} isn't optimal!)

\Rightarrow We use the estimate price

$$\in [V_0^{(z)}, \bar{V}_0].$$

① Random tree:

Next, we want to approxi. the condition expectations in Bellman's equation by MC simulation. It leads to a random tree with b branchings:

1) Sample $(X_1^i)_{i=1, \dots, b} \stackrel{i.i.d.}{\sim} X_1$

2) Sample $(X_2^{i,j})_{j=1, \dots, b} \stackrel{i.i.d.}{\sim} X_2 | X_1 = X_1^i, i=1, \dots, b.$

3) Repeat above. We have $(X_m^{j_1, \dots, j_m})_{m,j_1, \dots, j_m}.$

4) Set $V_m^{j_1, \dots, j_m} := f_m(X_m^{j_1, \dots, j_m})$ and recur-

sively $V_i^{j_1, \dots, j_i} := \max \{ f_i(X_i^{j_1, \dots, j_i}), \frac{1}{b} \sum_{j=1}^b V_{i+1}^{j_1, \dots, j_i, j} \}$

\Rightarrow We obtain $\bar{V}_0(x_0) = V_0^*$.

Proof: i) We see now: this estimate also biased high by Lem. above is because it does depend on the future realizations ($\frac{1}{b} \sum_{j=1}^b V_{i+1}^{j,i}$ - term) since $(V_i(x_i))$ is actually supermart. and we refine \bar{U} by estimating the conditional expectation

ii) Low-biased estimator can be constructed by:

$$V_{i,k}^{j_1, \dots, j_i} = \begin{cases} f_i(x_i), & \frac{1}{b-1} \sum_{j \neq k} V_{i+1}^{j_1, \dots, j_i, j} \leq f_i(x_i) \\ V_{i+1}^{j_1, \dots, j_i, k}, & \text{else.} \end{cases}$$

$$\Rightarrow V_i^{j_1, \dots, j_i} := \frac{1}{b} \sum_{k=1}^b V_{i,k}^{j_1, \dots, j_i}$$

We can show V_0^a is biased low.

$$\text{iii) } V_0^x \rightarrow V_0(x_0) \quad (b \rightarrow \infty)$$

② Pricing by regression:

Given basis func. $\psi_j: \mathcal{X} \rightarrow \mathbb{R}$ and unknown

$$\text{coeff. } (\beta_{ij}), \psi(x) = (\psi_1(x), \dots, \psi_n(x))^T, \beta_i = (\beta_{i,1}, \dots, \beta_{i,n})$$

$$\text{Ansatz: } \mathbb{E}(V_{i+1} | X_i = x) = \sum_{j=1}^n \beta_{i,j} \varphi_j(x)$$

$$\Rightarrow \mathbb{E}(\varphi(X_i) V_{i+1} | X_i = x) \stackrel{\text{ind.}}{=} \mathbb{E}(\varphi(X_i) \beta_i^T \varphi(X_i) | X_i = x) \\ = \mathbb{E}(\varphi(X_i) \varphi^T(X_i) | X_i = x) \beta_i$$

$$\text{So: } \beta_i \stackrel{\Delta}{=} M_{\varphi}^{-1}(X_i) M_{\varphi V}(X_i) \text{ if } |M_{\varphi}| \neq 0.$$

Algorithm 2.40. Simulate b independent paths of the Markov chain X_1, \dots, X_m starting from $X_0 = x$. We denote the simulated values by $X_i^{(j)}$, $i = 1, \dots, m$, $j = 1, \dots, b$. Set $V_{m,j} := f_m(X_m^{(j)})$ and proceed for $i = m-1, \dots, 0$ (backwards in time):

(i) Compute matrices \hat{M}_{ψ} and $\hat{M}_{\psi V}$ by

$$(\hat{M}_{\psi})_{l,k} := \frac{1}{b} \sum_{j=1}^b \psi_l(X_i^{(j)}) \psi_k(X_i^{(j)}), \quad (\hat{M}_{\psi V})_k := \frac{1}{b} \sum_{j=1}^b \psi_k(X_i^{(j)}) V_{i+1,j}.$$

(ii) Set the regression coefficient $\hat{\beta}_i := \hat{M}_{\psi}^{-1} \hat{M}_{\psi V}$.

(iii) Obtain the new option price estimates by

$$(2.24) \quad V_{i,j} := \max(f_i(X_i^{(j)}), \hat{\beta}_i^T \psi(X_i^{(j)})).$$

Remark: i) $V_0 = \frac{1}{b} \sum_{j=1}^b V_{0,j} \rightarrow V_0(x_0) \quad (b \rightarrow \infty)$

ii) It's less restrictive on memory and speed (mb v.s. mb). And all $(X_i^{(j)})_{j=1 \dots b}$ are used to compute β_i . In RTM only use samples from each path

iii) $(\varphi_i)^T$ generally choose from L^2 -basis.