Ruobing Zhao

Email: ruz015@ucsd.edu
Website: https://ruobingzhao.github.io/

OVERVIEW

Ph.D. Candidate at University of California, San Diego
Stochastic Control Theory

EDUCATION

M.S., Ph.D. Mechanical Engineering (Dynamics and Controls) 2013-Present
University of California, San Diego
   "A Method for Approximating Solutions of Schrödinger Equation Through Stochastic Control"
   Dissertation Committee:
   William M. McEneaney (Chair), Ruth J. Williams (Co-chair),
   Patrick J. Fitzsimmons, Jorge Cortés, Robert R. Bitmead

B.S. Chemical Engineering/Mathematics 2009-2013
University of California, Los Angeles
   with Honors

PAPERS

3. W. McEneaney and <u>R. Zhao</u>, "Employing the Staticization Operator in Conservative Dynamical Systems and the Schrödinger Equation", *Submitted to Asian Control Conference 2019.* [pdf](pdf)

2. W. McEneaney and <u>R. Zhao</u> , "Diffusion Process Representations for a Scalar-Field Schrödinger Equation Solution in Rotating Coordinates", *Numerical Methods for Optimal Control Problems, Springer INDAM Series, Vol. 29 (to appear)* [pdf](pdf)

1. W. McEneaney and <u>R. Zhao</u>, "A Diffusion-Based Solution Technique for Certain Schrödinger Equation Dynamical Systems", *Proceedings of European Control Conference* (2018).

CONTRIBUTED LECTURES AND PRESENTATIONS

3. SIAM Conference on Control & Its Applications 2017, Pittsburgh, PA
   "Hamilton-Jacobi Equations for Two-Point Boundary-Value Problems in Conservative Systems and Dequantized Schrödinger Equations" (with W. McEneaney, P. Dower)

2. SIAM Conference on Control & Its Applications 2017, Pittsburgh, PA
   "A Complex-valued Controlled-diffusion Representation for the Schrödinger Equation in a Rotating Frame" (with W. McEneaney)

1. Southern California Control Workshop 2017, Caltech
   "Diffusion Process Approximation for a Solution of the Schrödinger Equation" (with W. McEneaney)

SERVICE

- Reviewer: European Control Conference

HONORS

- 2013-2016 Charles Lee Powell Foundation Graduate Fellowship

- 2018 UCSD Dissertation Writing Fellowship

TEACHING EXPERIENCE

Graduate Level:

- **Optimal Control***
  Topics: Basics of measure theory, probability theory and graph theory, dynamic programming principle, Pontryagin's maximum principle, deterministic and stochastic Hamilton-Jacobi-Bellman equation, finite horizon and infinite horizon problems, value iteration and policy iteration, calculus of variations, conservative dynamical systems, Gauss-Markov processes, viscosity solutions, method of charateristics for solving PDEs, numerical methods

- **Real Analysis for Application**
  Topics: Measure theory and Lebesgue integration, point-set topology, metric space, normed space, inner product space, fixed-point theorems and application in solving integral and differential equations, dual spaces, reflexivity, linear operators, strong and weak convergence, topological vector space, Hahn-Banach Theorem, nonlinear functionals, L^p spaces, Sobolev spaces and other function spacess

Undegraduate Level:

- **Numerical Methods***
  Topics: Taylor's theorem, asymptotic order, error analysis, finite difference for derivative approximation, Euler's method, linear interpolation, numerical integration, boundary value problems, root finding, Newton's method, Lagrange interpolation, spline approximations, Runge-Kutta methods, Monte Carlo method.

* Recommended in 100% of student evaluations in most recent assignments (as of summer 2018)

GRADUATE COURSEWORK HIGHLIGHT

Mathematics: Real Analysis; Probability Theory; Functional Analysis; Convex Analysis
Control Theory: Linear Systems; Linear Control; Nonlinear Systems; Nonlinear Control; Optimal Control; Hybrid Systems
Audited: Stochastic Differential Equations; Game Theory