

# Im2Flow: Motion Hallucination from Static Images for Action Recognition



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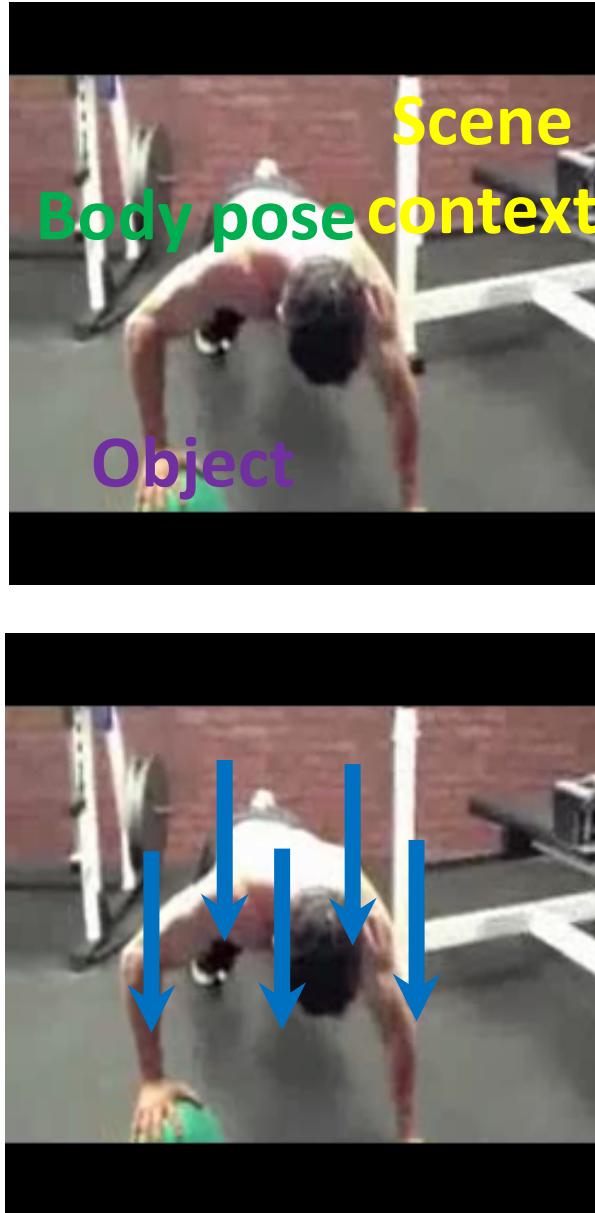


Project page: <http://vision.cs.utexas.edu/projects/im2flow>

## Static-image Action Recognition

**Static-image action recognition** exploits various high-level appearance cues such as human body pose/ scene context and objects in the image:

[Thurau & Hlaváč, CVPR 2008; Delaitre *et al.*, NIPS 2011; Sener *et al.*, ECCV 2012; Gkioxari *et al.*, CVPR 2015]



**Video-level action recognition** methods exploit both appearance and motion:

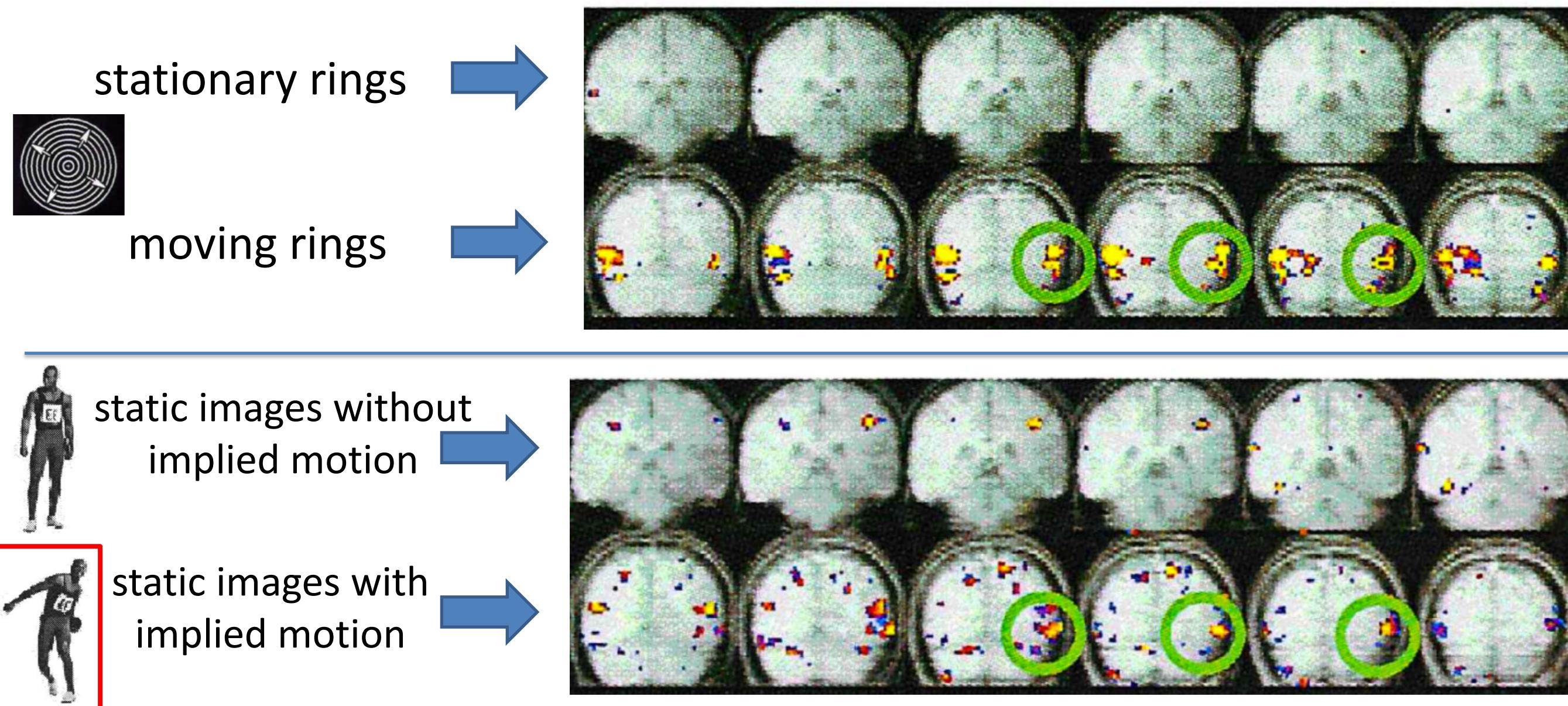
[Wang & Schmid CVPR 2013; Simonyan & Zisserman, NIPS 2014; Wang *et al.*, ECCV 2016; Girdhar *et al.*, CVPR 2017; Tran *et al.*, CVPR 2018; Feichtenhofer *et al.*, CVPR 2018]



But is motion really absent in static images?

## Implied Motion Perception in the Brain

Activation in human's medial temporal / medial superior temporal (MT/MST) cortex by static images with implied motion [Kourtzi & Kanwisher, 2000]:

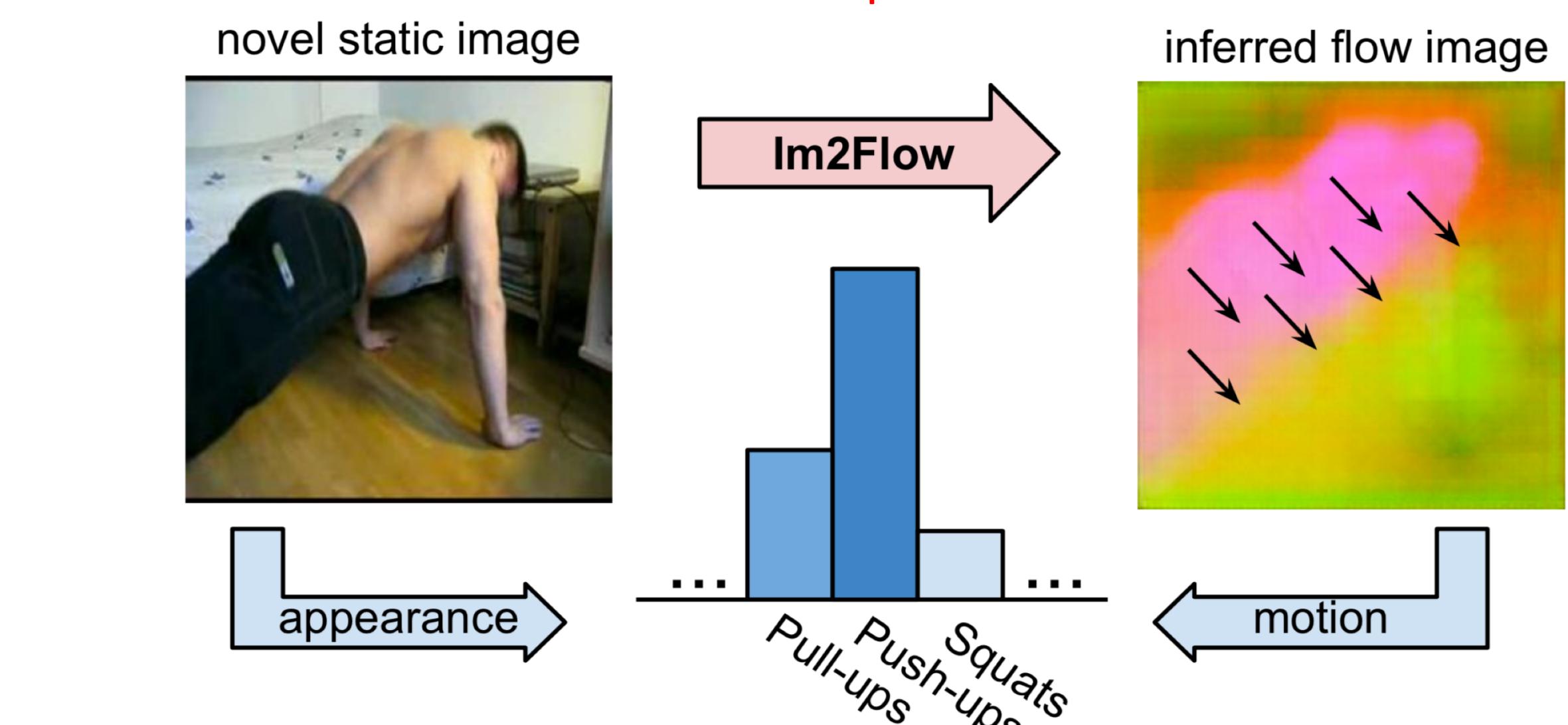


## Our Idea

We propose to learn a motion prior from unlabeled videos, and hallucinates motion implied by a single snapshot to help static-image action recognition.



learn a motion prior from videos

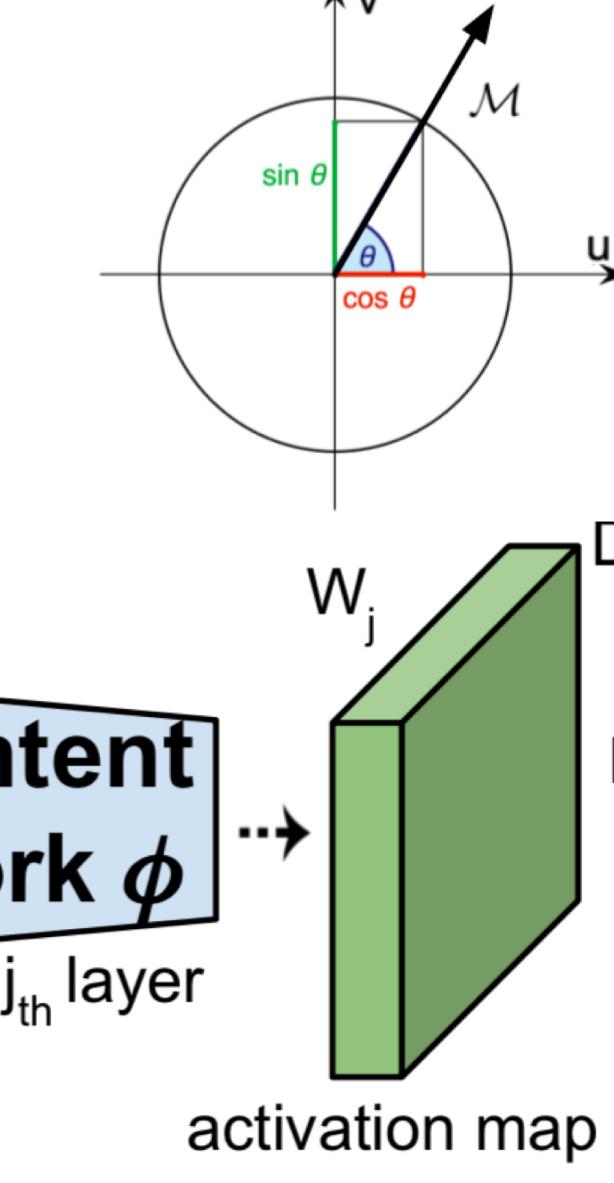


We formulate motion prediction as a novel image-to-image translation framework, and use predicted motion image to aid action recognition.

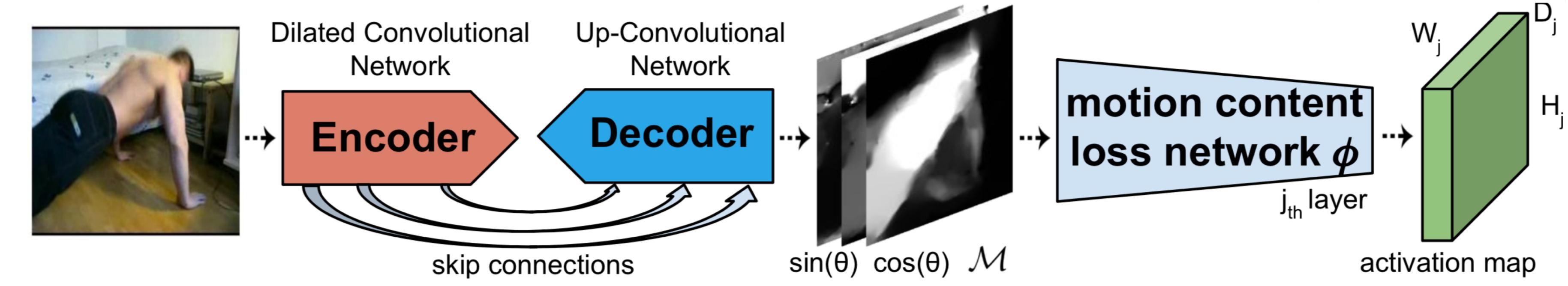
## Approach

**Motion Encoding:** Detangle flow direction and strength, and encodes as a single 3-channel flow image.

$$\mathcal{F}_1 = \sin(\theta) = \frac{v}{\mathcal{M}}; \quad \mathcal{F}_2 = \cos(\theta) = \frac{u}{\mathcal{M}}; \quad \mathcal{F}_3 = \mathcal{M}$$



**Im2Flow Network Architecture:** An encoder-decoder network, which takes a static image as input and outputs the predicted flow image.



Total Loss:

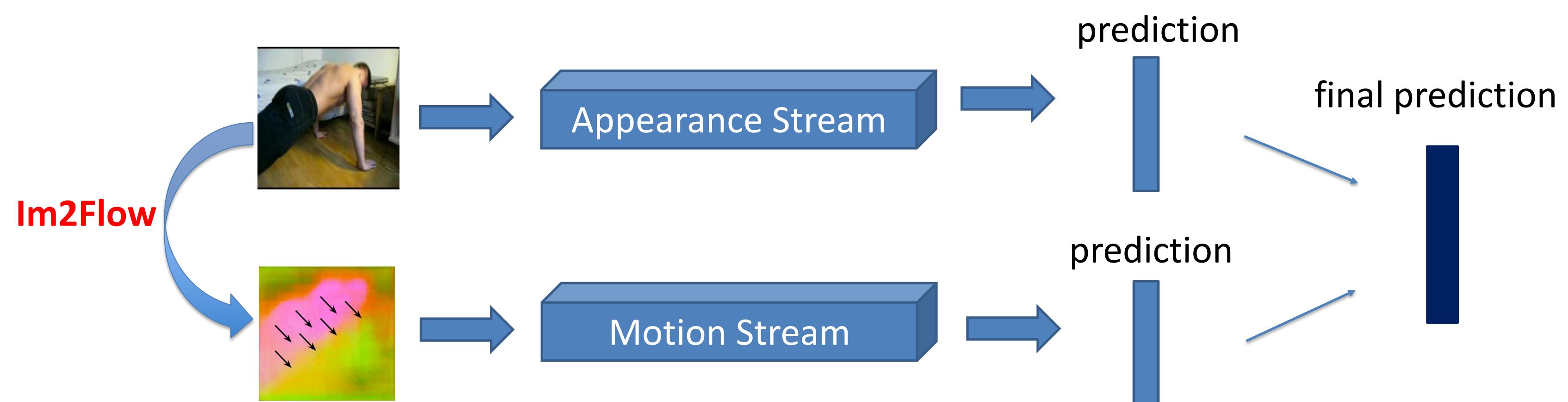
$$L = L_{pixel} + \lambda L_{content}^{\phi,j}$$

Pixel Error Loss:

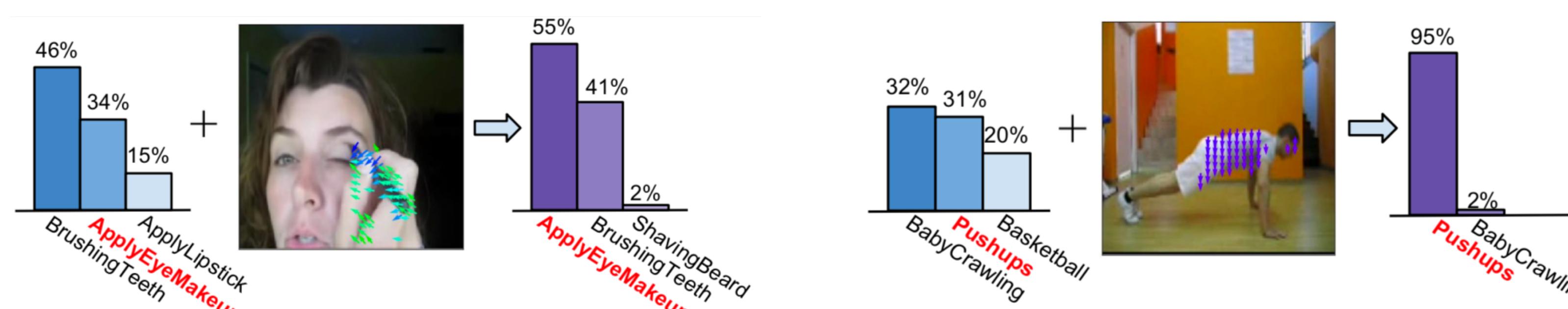
$$L_{pixel} = \mathbb{E}_{p,q \in \{x_i, y_i\}_{i=1}^N} [| | y_i - G(x_i) | |_2 ]$$

$$\text{Motion Content Loss: } L_{content}^{\phi,j} = \frac{1}{D_j \times H_j \times W_j} \mathbb{E}_{p,q \in \{x_i, y_i\}_{i=1}^N} [| | \phi_j(y_i) - \phi_j(G(x_i)) | |_2 ]$$

**Static-image Action Recognition:** We adopt the popular and effective two-stream CNN [Simonyan & Zisserman, NIPS 2014] to inject our Im2Flow predictions into action recognition.

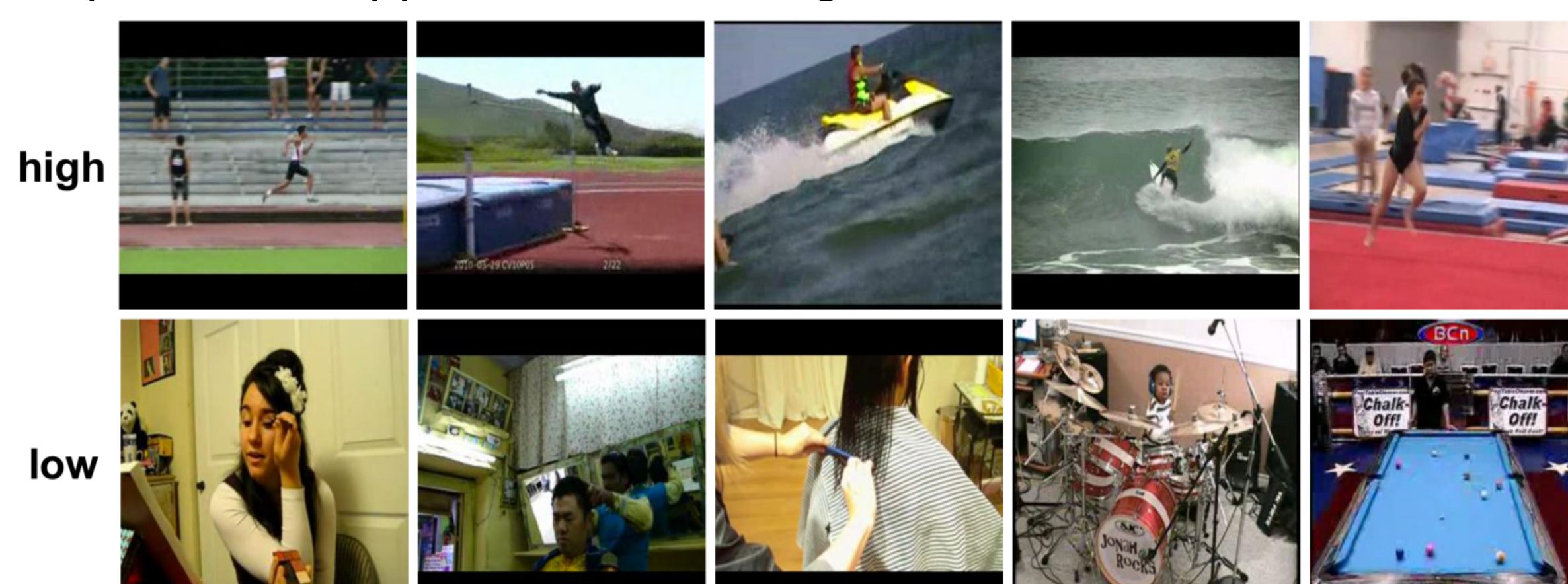


How does inferred motion help recognition?



While a classifier solely based on appearance can be confused by actions appearing in similar contexts, the inferred motion provides cues about the fine-grained differences to aid recognition.

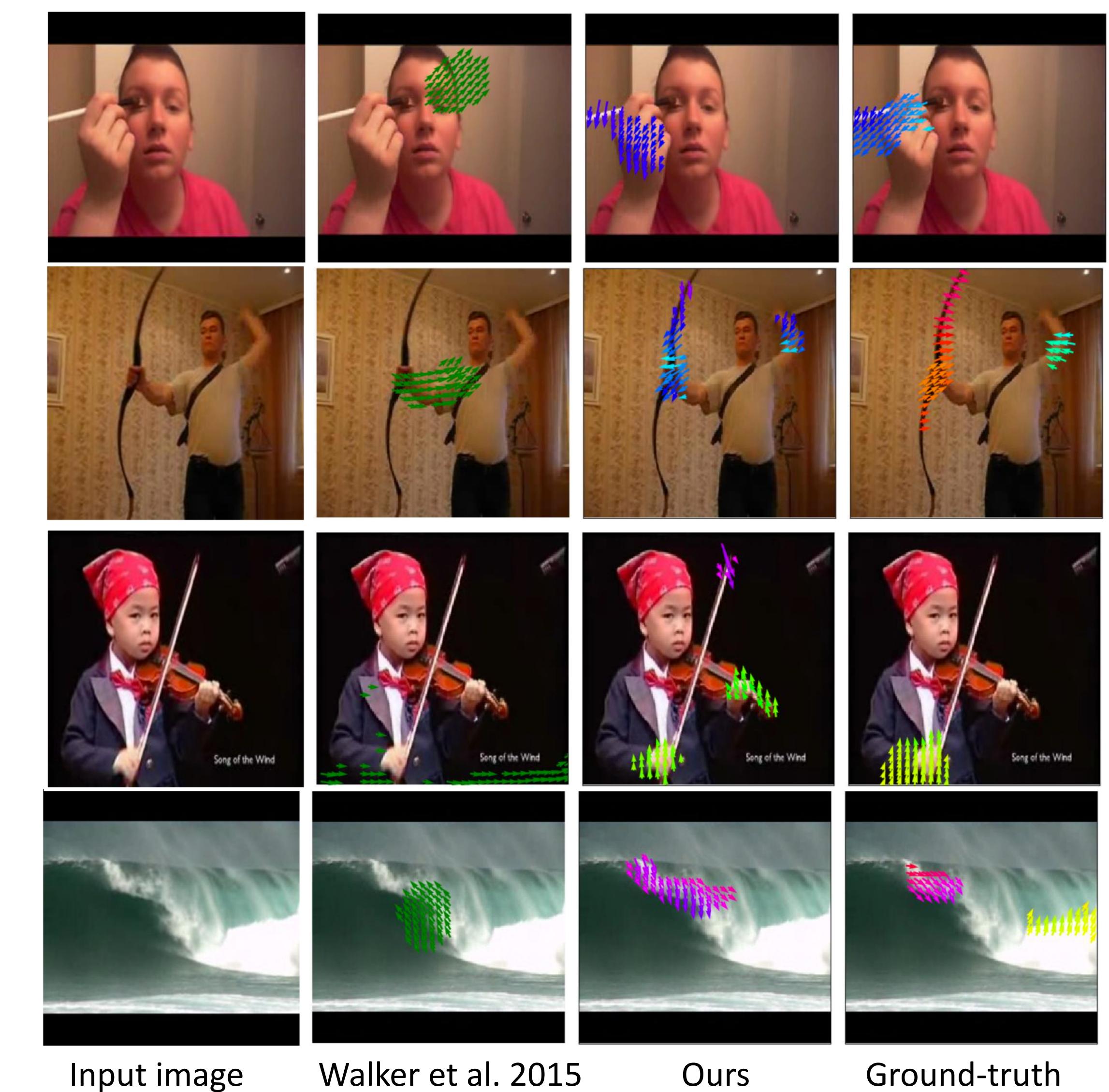
**Motion Potential:** the strength of movement and activity that is poised to happen in a static image.



Motion potential offers a high-level view of a scene's activity, identifying images that are most suggestive of coming events.

## Results

Flow prediction example qualitative results:



Flow prediction quantitative results:

Metrics: End-Point-Error (EPE), Direction Similarity (DS)  
Orientation Similarity (OS)

$$DS = \frac{u_1 u_2 + v_1 v_2}{\sqrt{u_1^2 + v_1^2} \sqrt{u_2^2 + v_2^2}}, \quad OS = \frac{|u_1 u_2 + v_1 v_2|}{\sqrt{u_1^2 + v_1^2} \sqrt{u_2^2 + v_2^2}}.$$

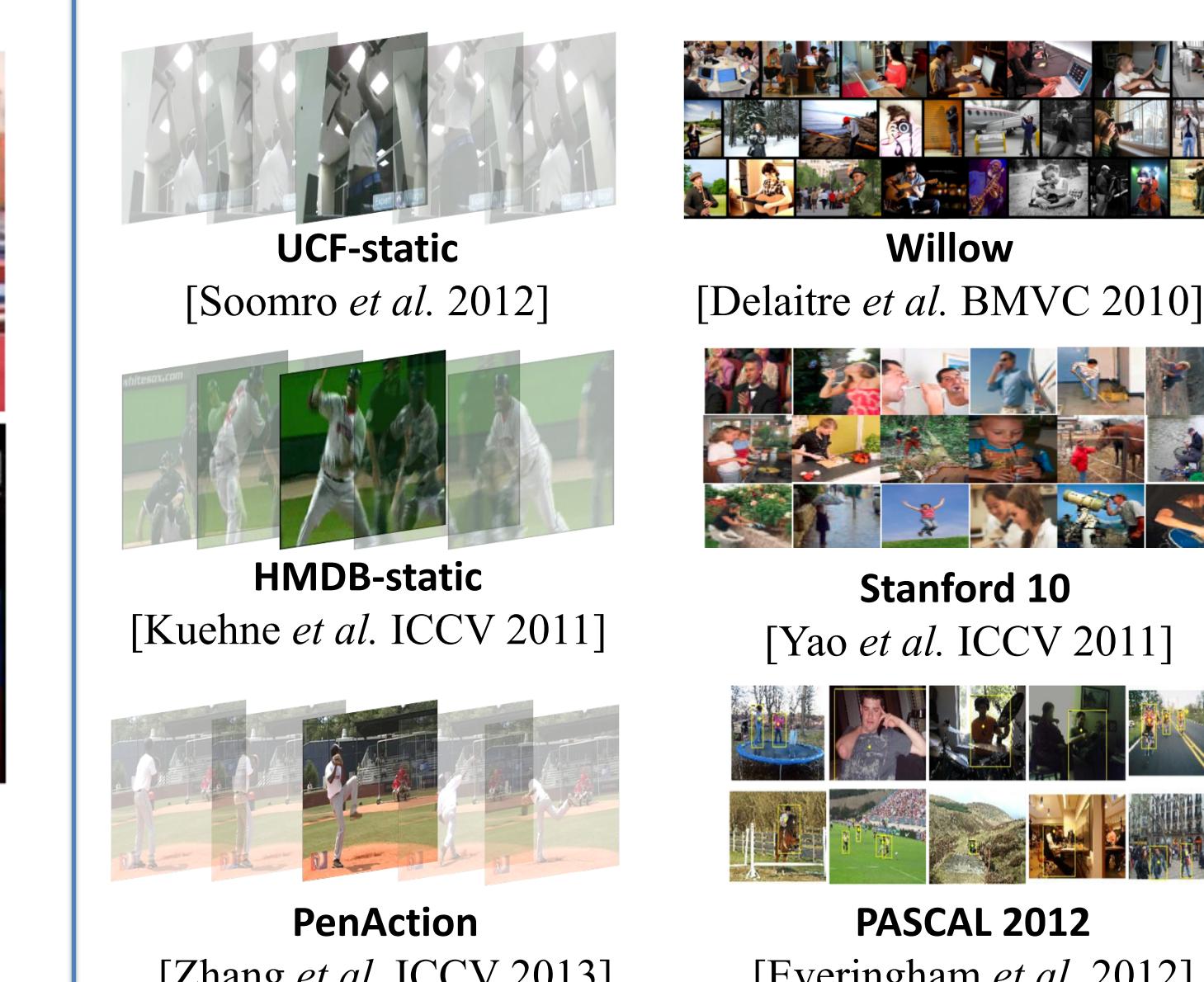
Evaluate prediction results over  
— all pixels in the whole image  
— masks on canny edges  
— masks on foreground (FG) regions

	EPE ↓	EPE-Canny	EPE-FG	DS ↑	DS-Canny	DS-FG	OS ↑	OS-Canny	OS-FG
Pintea <i>et al.</i> 2014	2.401	2.699	3.233	-0.001	-0.002	-0.005	0.513	0.544	0.555
Walker <i>et al.</i> 2015	2.391	2.696	3.139	0.003	0.001	0.014	0.661	0.673	0.662
Nearest Neighbor	3.123	3.234	3.998	-0.002	-0.001	-0.023	0.652	0.651	0.659
Ours	2.210	2.533	2.936	0.143	0.135	0.137	0.699	0.692	0.696

End-Point-Error (lower better)      Direction Similarity (higher better)      Orientation Similarity (higher better)

Results on HMDB-51 and Weizmann datasets are similar. Across all metrics, our method predicts more accurate optical flow.

## Static-image Action Recognition



Inferring motion from Im2flow improves the recognition accuracy for static-image action recognition.

