

# Recent Advances in Fair Resource Allocation

Rupert Freeman  
Microsoft Research New York

and

Nisarg Shah  
University of Toronto

# Disclaimer

- In this tutorial, we will NOT
  - Assume any prior knowledge of fair division
  - Walk you through tedious, detailed proofs
  - Claim to present a *complete* overview of the entire fair division realm
  - Present unpublished results
- Instead, we will
  - Focus mostly on the case of “additive preferences” for coherence
    - With some results for and pointers to domains with non-additive preferences
- If you spot any errors, missing results, or incorrect attributions:
  - Please email [nisarg@cs.toronto.edu](mailto:nisarg@cs.toronto.edu) or [Rupert.Freeman@microsoft.com](mailto:Rupert.Freeman@microsoft.com)

# Outline

- Fairness Axioms
  - Proportionality
  - Envy-freeness
  - Maximin share guarantee
  - Groupwise fairness
    - Core
    - Group envy-freeness
    - Groupwise MMS
    - Group fairness
- Implications of fairness
  - Price of fairness
  - Interplay with strategyproofness and Pareto optimality
  - Restricted cases
- Settings
  - Cake-cutting
  - Homogeneous divisible goods
  - Indivisible goods

# A Generic Resource Allocation Framework

- A set of **agents**  $N = \{1, 2, \dots, n\}$
- A set of **resources**  $M$ 
  - May be finite or infinite
- **Valuations**
  - Valuation of agent  $i$  is  $v_i : 2^M \rightarrow \mathbb{R}$
  - Range is  $\mathbb{R}_+$  when resources are *goods*, and  $\mathbb{R}_-$  when they are *bads*
- **Allocations**
  - $A = (A_1, \dots, A_n) \in \Pi_n(M)$  is a partition of resources among agents
    - $A_i \cap A_j = \emptyset, \forall i, j \in N$  and  $\cup_{i \in N} A_i = M$
  - A **partial allocation**  $A$  may have  $\cup_{i \in N} A_i \neq M$

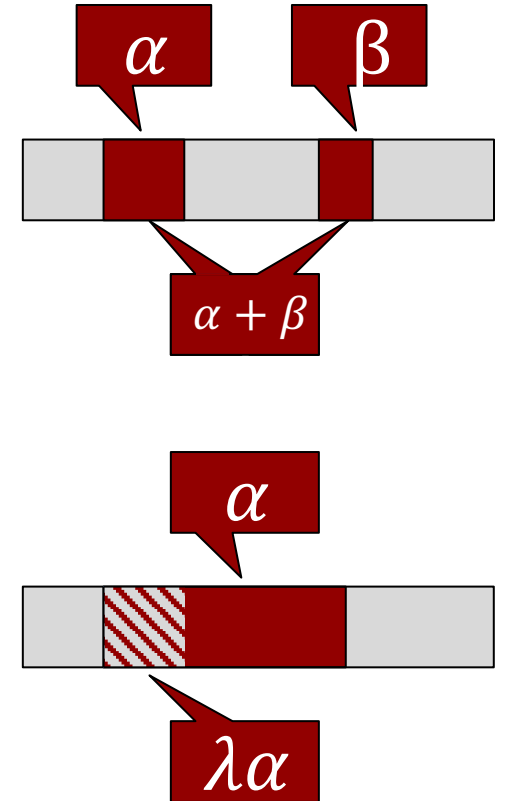
# Cake Cutting

- Formally introduced by Steinhaus [1948]
- Agents:  $N = \{1, 2, \dots, n\}$
- Resource (cake):  $M = [0, 1]$
- Constraints on an allocation  $A$ 
  - The entire cake is allocated (**full** allocation)
  - Each  $A_i \in \mathcal{A}$ , where  $\mathcal{A}$  is the set of finite unions of disjoint intervals
- **Simple** allocations
  - Each agent is allocated a single interval
  - Cuts cake at  $n - 1$  points



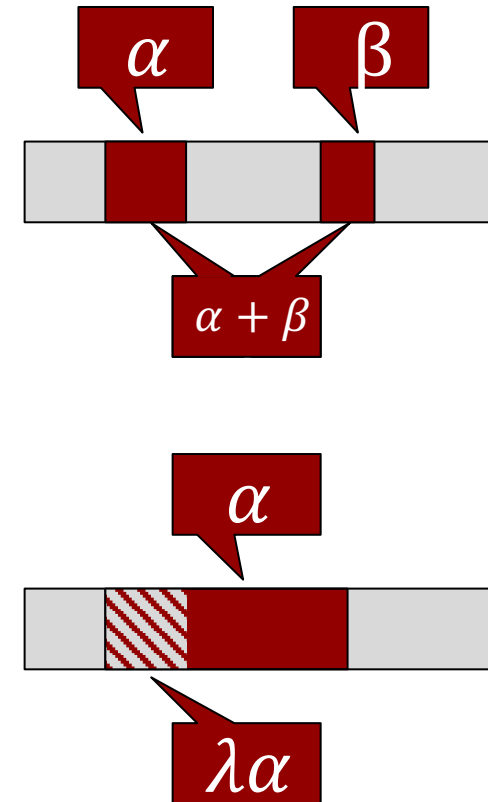
# Agent Valuations

- Each agent  $i$  has an integrable density function  $f_i: [0,1] \rightarrow \mathbb{R}_+$
- For each  $X \in \mathcal{A}$ ,  $v_i(X) = \int_{x \in X} f_i(x) dx$
- For normalization, we require  $\int_0^1 f_i(x) dx = 1$ 
  - Without loss of generality



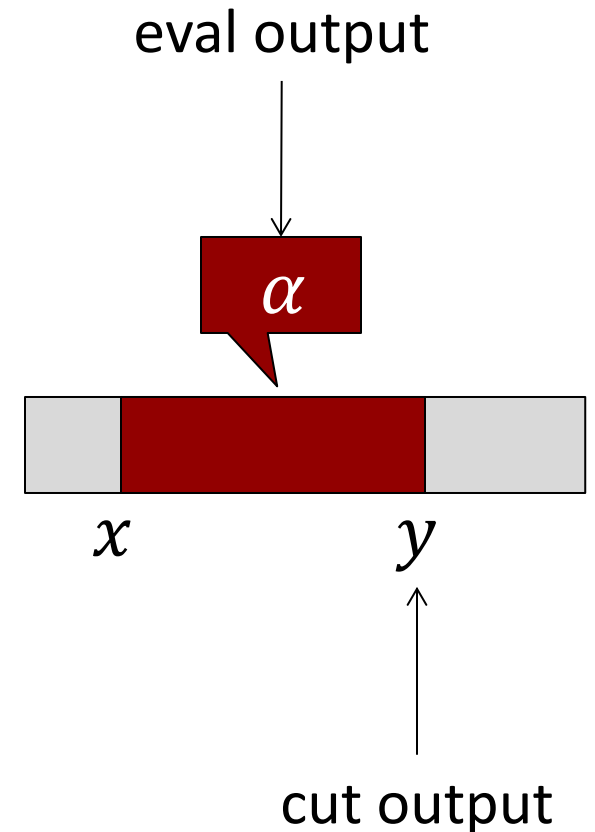
# Agent Valuations

- In this model, the valuations satisfy the following properties
- **Normalized:**  $v_i([0,1]) = 1$
- **Divisible:**  $\forall \lambda \in [0,1]$  and  $I = [x, y]$ ,  
 $\exists z \in [x, y]$  s.t.  $v_i([x, z]) = \lambda v_i([x, y])$
- **Additive:** For disjoint intervals  $I$  and  $I'$ ,  
 $v_i(I) + v_i(I') = v_i(I \cup I')$



# Complexity

- Inputs are functions
  - Infinitely many bits may be needed to fully represent the input
  - Query complexity is more useful
- **Robertson-Webb Model**
  - $\text{Eval}_i(x, y)$  returns  $v_i([x, y])$
  - $\text{Cut}_i(x, \alpha)$  returns  $y$  such that  $v_i([x, y]) = \alpha$



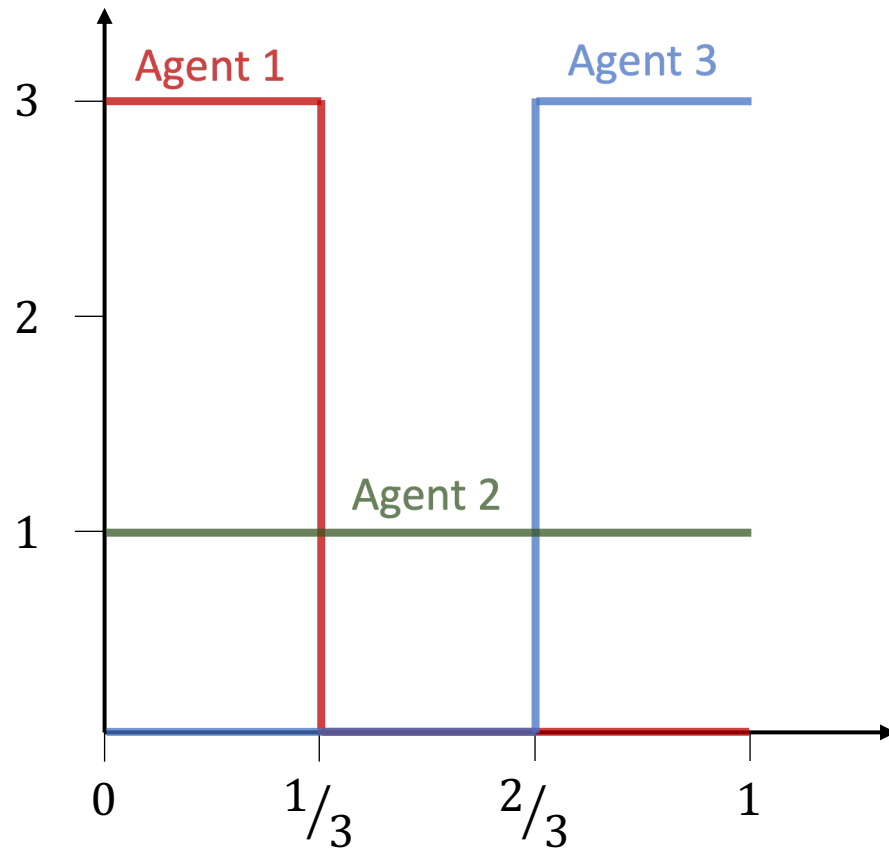


# Three Classic Fairness Desiderata

- **Proportionality (Prop):**  $\forall i \in N: v_i(A_i) \geq 1/n$ 
  - Each agent should receive her “fair share” of the utility.
- **Envy-Freeness (EF):**  $\forall i, j \in N: v_i(A_i) \geq v_i(A_j)$ 
  - No agent should wish to swap her allocation with another agent.
- **Equitability (EQ):**  $\forall i, j \in N : v_i(A_i) = v_j(A_j)$ 
  - All agents should have the exact same value for their allocations.
  - No agent should be jealous of what another agent received.

# Example

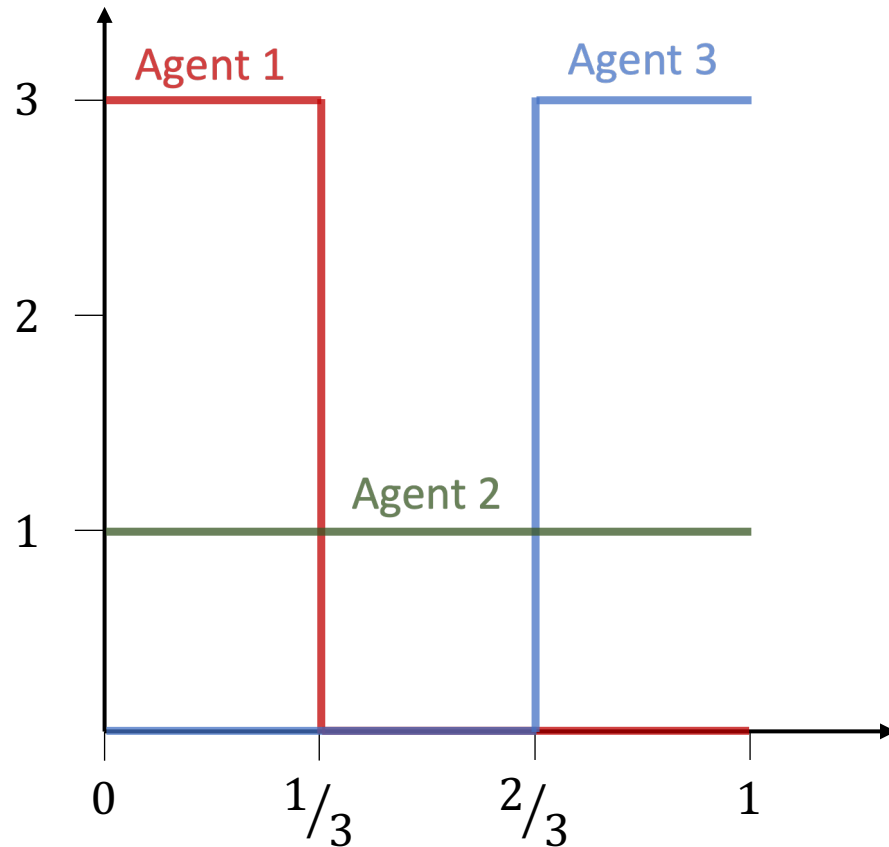
- Value density functions



- Agent 1 wants  $[0, 1/3]$  uniformly and does not want anything else
- Agent 2 wants the entire cake uniformly
- Agent 3 wants  $[2/3, 1]$  uniformly and does not want anything else

# Example

- Value density functions

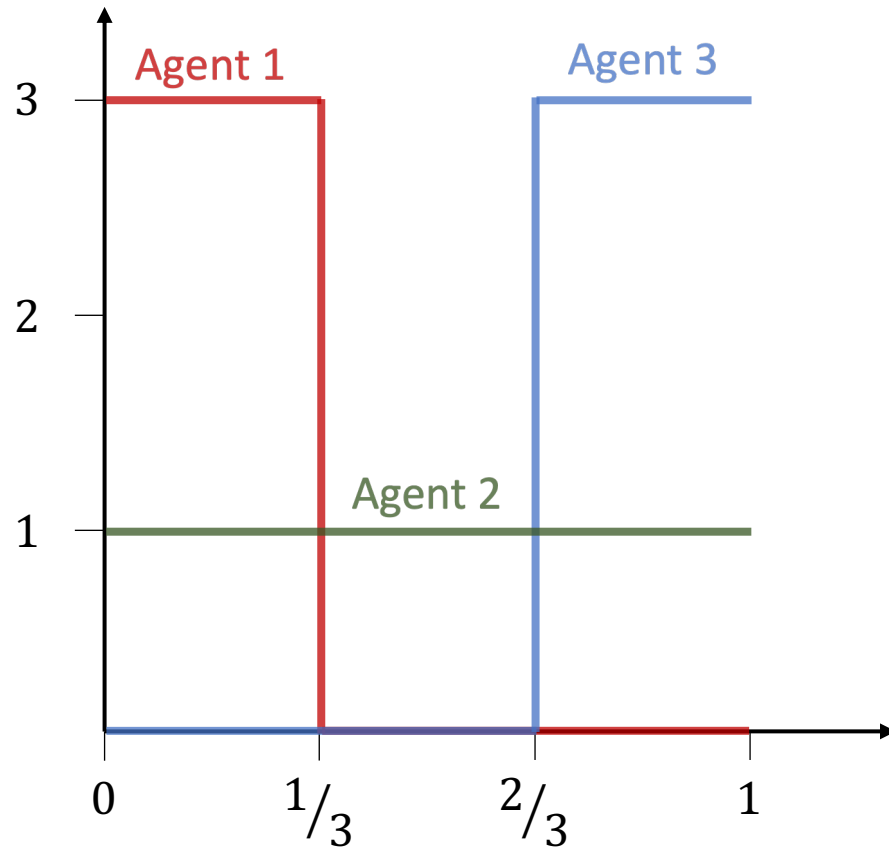


- Consider the following allocation

- $A_1 = [0, 1/9] \Rightarrow v_1(A_1) = 1/3$
- $A_2 = [1/9, 8/9] \Rightarrow v_2(A_2) = 7/9$
- $A_3 = [8/9, 1] \Rightarrow v_3(A_3) = 1/3$
- The allocation is proportional, but not envy-free or equitable

# Example

- Value density functions

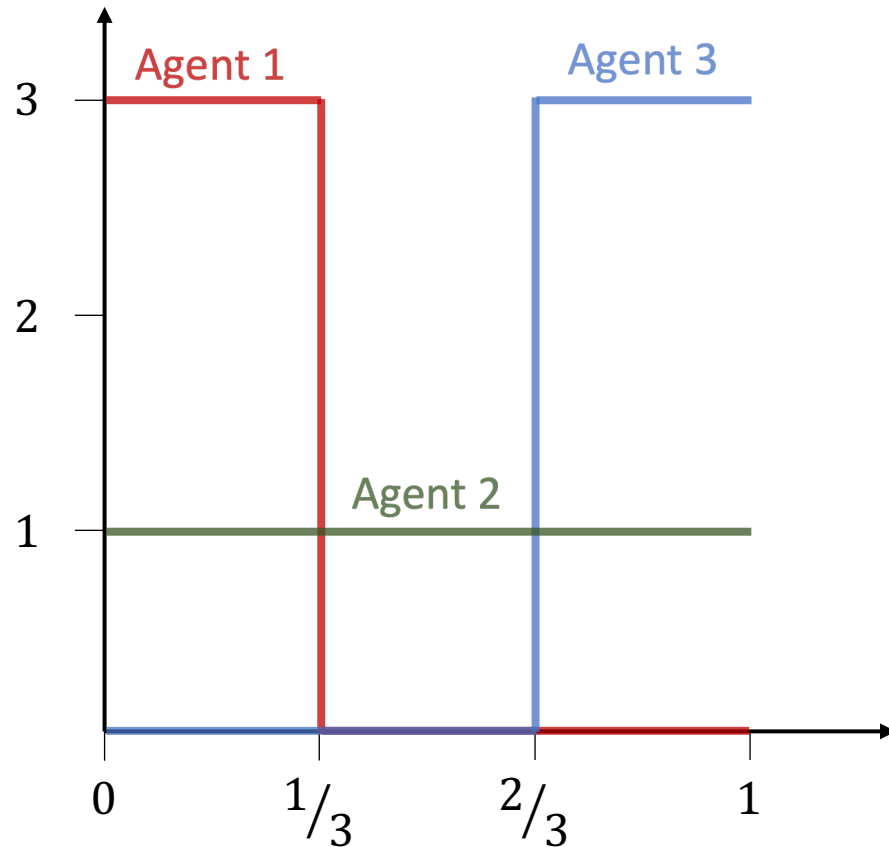


- Consider the following allocation

- $A_1 = [0, 1/6] \Rightarrow v_1(A_1) = 1/2$
- $A_2 = [1/6, 5/6] \Rightarrow v_2(A_2) = 2/3$
- $A_3 = [5/6, 1] \Rightarrow v_3(A_3) = 1/2$
- The allocation is proportional and envy-free, but not equitable

# Example

- Value density functions



- Consider the following allocation

- $A_1 = [0, 1/5] \Rightarrow v_1(A_1) = 3/5$
- $A_2 = [1/5, 4/5] \Rightarrow v_2(A_2) = 3/5$
- $A_3 = [4/5, 1] \Rightarrow v_3(A_3) = 3/5$
- The allocation is proportional, envy-free, and equitable

# Relations Between Fairness Desiderata

- Envy-freeness implies proportionality
  - Summing  $v_i(A_i) \geq v_i(A_j)$  over all  $j$  gives proportionality
- For 2 agents, proportionality also implies envy-freeness
  - Hence, they are equivalent.
- Equitability is incomparable to proportionality and envy-freeness
  - E.g. if each agent has value 0 for her own allocation and 1 for the other agent's allocation, it is equitable but not proportional or envy-free.

# Existence

- **Theorem [Alon, 1987]**

Suppose the value density function  $f_i$  of each agent valuation  $v_i$  is continuous. Then, we can cut the cake at  $n^2 - n$  places and rearrange the  $n^2 - n + 1$  intervals into  $n$  pieces  $A_1, \dots, A_n$  such that

$$v_i(A_j) = 1/n, \forall i, j \in N$$

- This is called a “**perfect partition**”
  - It is trivially envy-free (thus proportional) and equitable
- As we will later see, this cannot be found with finitely many queries in Robertson-Webb model

# Proportionality



# PROPORTIONALITY : $n = 2$ AGENTS

- CUT-AND-CHOOSE

- Agent 1 cuts the cake at  $x$  such that  $v_1([0, x]) = v_1([x, 1]) = 1/2$
- Agent 2 chooses the piece that she prefers.

- Elegant protocol

- Proportional (equivalent to envy-freeness for 2 agents)
- Needs only one cut and one eval query (optimal)

- More agents?

# PROPORTIONALITY: DUBINS-SPANIER

- **DUBINS-SPANIER**

- Referee starts a knife at 0 and moves the knife to the right.
- Repeat: When the piece to the left of the knife is worth  $1/n$  to an agent, the agent shouts “stop”, receives the piece, and exits.
- When only one agent remains, she gets the remaining piece.

- Can be implemented easily in Robertson-Webb model

- When  $[x, 1]$  is left, ask each remaining agent  $i$  to cut at  $y_i$  so that  $v_i([x, y_i]) = 1/n$ , and give agent  $i^* \in \arg \min_i y_i$  the piece  $[x, y_{i^*}]$ .

- **Query complexity:  $\Theta(n^2)$**

# PROPORTIONALITY: EVEN-PAZ

- **EVEN-PAZ**
- **Input:**
  - Interval  $[x, y]$ , number of agents  $n$  (assume a power of 2 for simplicity)
- **Recursive procedure:**
  - If  $n = 1$ , give  $[x, y]$  to the single agent.
  - Otherwise:
    - Each agent  $i$  marks  $z_i$  such that  $v_i([x, z_i]) = v_i([z_i, y])$
    - $z^* = (n/2)^{\text{th}}$  mark from the left.
    - Recurse on  $[x, z^*]$  with the left  $n/2$  agents, and on  $[z^*, y]$  with the right  $n/2$  agents.
- **Query complexity:  $\Theta(n \log n)$**

# Complexity of Proportionality

- Theorem [Edmonds and Pruhs, 2006]:
  - Any protocol returning a proportional allocation needs  $\Omega(n \log n)$  queries in the Robertson-Webb model.
- Hence, EVEN-PAZ is provably (asymptotically) optimal!

# Envy-Freeness

# Envy-Freeness : Few Agents

- $n = 2$  agents : CUT-AND-CHOOSE (2 queries)
- $n = 3$  agents : SELFRIDGE-CONWAY (14 queries)

Gets complex pretty quickly!

Suppose we have three players **P1**, **P2** and **P3**. Where the procedure gives a criterion for a decision it means that criterion gives an optimum choice for the player.

1. **P1** divides the cake into three pieces he considers of equal size.
2. Let's call **A** the largest piece according to **P2**.
3. **P2** cuts off a bit of **A** to make it the same size as the second largest. Now **A** is divided into: the trimmed piece **A1** and the trimmings **A2**. Leave the trimmings **A2** to the side for now.
  - If **P2** thinks that the two largest parts are equal (such that no trimming is needed), then each player chooses a part in this order: **P3**, **P2** and finally **P1**.
4. **P3** chooses a piece among **A1** and the two other pieces.
5. **P2** chooses a piece with the limitation that if **P3** didn't choose **A1**, **P2** must choose it.
6. **P1** chooses the last piece leaving just the trimmings **A2** to be divided.

It remains to divide the trimmings **A2**. The trimmed piece **A1** has been chosen by either **P2** or **P3**; let's call the player who chose it **PA** and the other player **PB**.

1. **PB** cuts **A2** into three equal pieces.
2. **PA** chooses a piece of **A2** - we name it **A21**.
3. **P1** chooses a piece of **A2** - we name it **A22**.
4. **PB** chooses the last remaining piece of **A2** - we name it **A23**.

# Envy-Freeness : Few Agents

- [Brams and Taylor, 1995]
  - The first finite (but unbounded) protocol for any number of agents
- [Aziz and Mackenzie, 2016a]
  - The first bounded protocol for 4 agents (at most 203 queries)
- [Amanatidis et al., 2018]
  - A simplified version of the above protocol for 4 agents (at most 171 queries)

# Envy-Freeness

- Theorem [Aziz and Mackenzie, 2016b]
  - There exists a bounded protocol for computing an envy-free allocation with  $n$  agents, which requires  $O(n^{n^{n^{n^{\mathbf{n}}}}})$  queries
  - After  $O(n^{2n+3})$  queries, the protocol can output a **partial** allocation that is both proportional and envy-free
- What about lower bounds?



# Complexity of Envy-Freeness

- Theorem [Procaccia, 2009]

Any protocol for finding an envy-free allocation requires  $\Omega(n^2)$  queries.

Open Problem

Bridge the gap between  $O(n^{n^{n^n}})$  upper bound and  $\Omega(n^2)$  lower bound for envy-free cake-cutting

- Theorem [Stromquist, 2008]

There is no finite (even unbounded) protocol for finding a simple envy-free allocation for  $n \geq 3$  agents.

# Equitability

# Upper Bound: $n = 2$ Agents

- Existence

- Suppose we cut the cake at  $x$  to form pieces  $[0, x]$  and  $[x, 1]$
- Let  $f(x) = v_1([0, x]) - v_2([x, 1])$ 
  - Note that  $f(0) = -1$ ,  $f(1) = 1$ , and  $f$  is continuous
- By the intermediate value theorem:  $\exists x^*$  such that  $f(x^*) = 0$
- Allocation  $A_1 = [0, x^*]$  and  $A_2 = [x^*, 1]$  is equitable

- Theorem [Cechlárová and Pillárová, 2012]

- Using binary search for  $x^*$ , we can find an  $\epsilon$ -equitable allocation for 2 agents with  $O(\ln(1/\epsilon))$  queries.

# Upper Bound: $n > 2$ Agents

- Theorem [Cechlárová and Pillárová, 2012]
  - This technique can be extended to  $n$  agents to find an  $\epsilon$ -equitable allocation in  $O(n \ln(1/\epsilon))$  queries.
- Theorem [Procaccia and Wang, 2017]
  - There exists a protocol for  $n$  agents which finds an  $\epsilon$ -equitable allocation in  $O(1/\epsilon \ln(1/\epsilon))$  queries.
  - Intuition:
    - If  $n \leq 1/\epsilon$ , use above protocol for finding an equitable  $\epsilon$ -equitable allocation.
    - If  $n > 1/\epsilon$ , use a variant of the Evan-Paz algorithm to find an *anti-proportional* allocation where  $n' = \lceil 1/\epsilon \rceil$  agents get value *at most*  $1/n'$ , and the rest receive nothing.
      - While this is a “bad” allocation, it is  $\epsilon$ -equitable.

# Lower Bound

- Theorem [Procaccia and Wang, 2017]

Any protocol for finding an  $\epsilon$ -equitable allocation must require  $\Omega\left(\frac{\ln(1/\epsilon)}{\ln \ln(1/\epsilon)}\right)$  queries.

- Theorem [Procaccia and Wang, 2017]

There is no finite (even if unbounded) protocol for finding an equitable allocation.

- Non-existence of bounded protocols follows from the previous result.
- But their proof works for non-existence of unbounded protocols as well.

# Price of Fairness

# Price of Fairness

- Measures the **worst-case loss in social welfare** due to requirement of a fairness property  $X$
- **Social welfare** of allocation  $A$  is the sum of values of the agents
  - Denoted  $sw(A) = \sum_{i \in N} v_i(A_i)$
- Let  $\mathcal{F}$  denote the set of feasible allocations and  $\mathcal{F}_X$  denote the set of feasible allocations satisfying property  $X$

$$PoF_X = \sup_{v_1, \dots, v_n} \frac{\max_{A \in \mathcal{F}} sw(A)}{\max_{A \in \mathcal{F}_X} sw(A)}$$

# Price of Fairness

- **Theorem [Caragiannis et al., 2009]**

For cake-cutting, the price of proportionality is  $\Theta(\sqrt{n})$ , and the price of equitability is  $\Theta(n)$ .

- **Theorem [Bertsimas et al., 2011]**

For cake-cutting, the price of envy-freeness is also  $\Theta(\sqrt{n})$ . This is achieved by an allocation maximizing the Nash welfare  $\prod_i v_i(A_i)$ .

➤ **Fun fact:** The price of EF in cake-cutting was mentioned as an open question in a previous version of this tutorial, and was also believed to be open by many groups of researchers until recently.



# Efficiency

# Efficiency

- Weak Pareto optimality (WPO)

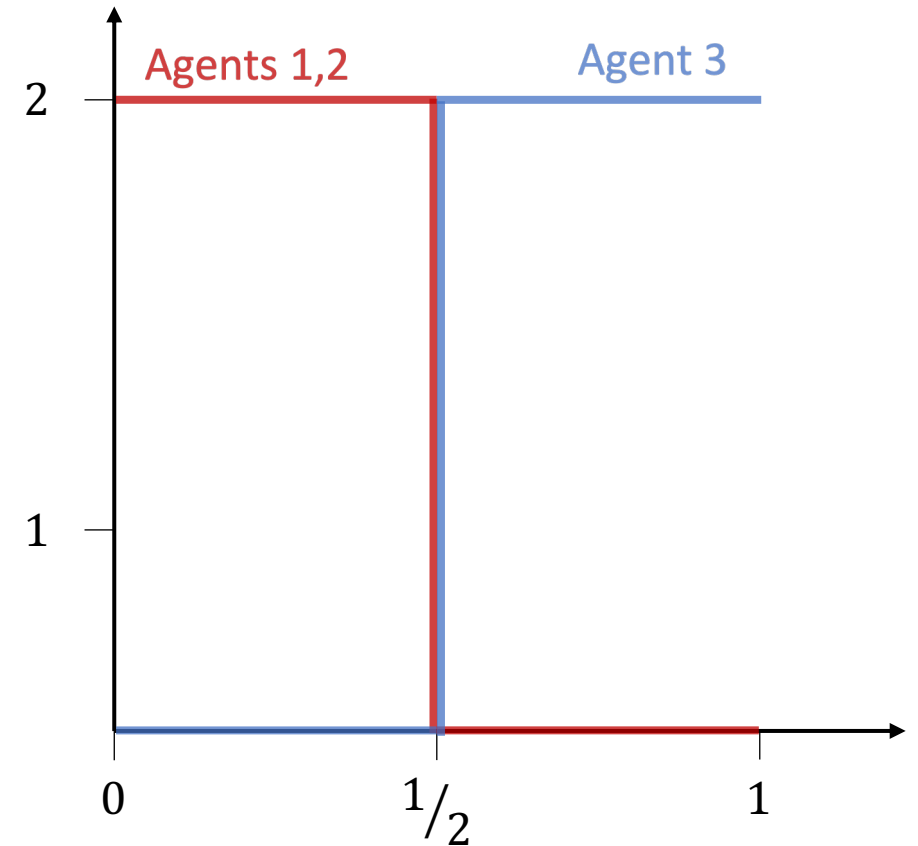
- Allocation  $A$  is weakly Pareto optimal if there is no allocation  $B$  such that  $v_i(B_i) > v_i(A_i)$  for all  $i \in N$ .
- “Can’t make everyone happier”

- Pareto optimality (PO)

- Allocation  $A$  is Pareto optimal if there is no allocation  $B$  such that  $v_i(B_i) \geq v_i(A_i)$  for all agents  $i \in N$ , and at least one inequality is strict.
- “Can’t make someone happier without making someone else less happy”
- Easy to achieve in isolation (e.g. “serial dictatorship”)

# PO+EF+EQ: (Non-)Existence

- **Theorem [Barbanel and Brams, 2011]**  
With two agents, there always exists an allocation that is envy-free (thus proportional), equitable, and Pareto optimal.
  - Their algorithm has similarities to the more popular “adjusted winner” algorithm, which we will see later in the tutorial.
- **With  $n \geq 3$  agents, PO+EQ is impossible**



# What about PO+EF?

- Competitive Equilibrium from Equal Incomes (CEEI)

- At equilibrium: there is an additive price function  $P$  on the cake, and each agent gets to buy their best piece from a budget of one unit of fake currency

- WCE:  $\forall i \in N, Z \subseteq [0,1]: P(Z) \leq P(A_i) \Rightarrow v_i(Z) \leq v_i(A_i)$

- EI:  $\forall i \in N: P(A_i) = 1$

- Theorem [Weller, 1985]

For cake-cutting, a CEEI always exists. Every CEEI is both envy-free and weakly Pareto optimal.

# s-CEEI

- **Strong Competitive Equilibrium from Equal Incomes (s-CEEI)**

- A positive slice  $Z$  is a subset of the cake valued positively by at least one agent
- Allocation  $A$  is called s-CEEI allocation if there exists an additive price function  $P$  satisfying

- $P(Z) > 0$  iff  $Z$  is a positive slice

- SCE:  $\forall i \in N$ , and positive slices  $Z \subseteq [0,1]$  and  $Z_i \subseteq A_i$ :  $\frac{v_i(Z_i)}{P(Z_i)} \geq \frac{v_i(Z)}{P(Z)}$

- EI:  $\forall i \in N: P(A_i) = 1$

Maximum bang-per-buck

- **Theorem [Segal-Halevi and Sziklai, 2018]**

For cake-cutting, an s-CEEI allocation always exists. Every s-CEEI allocation is envy-free and Pareto optimal.

# s-CEEI and Nash-Optimality

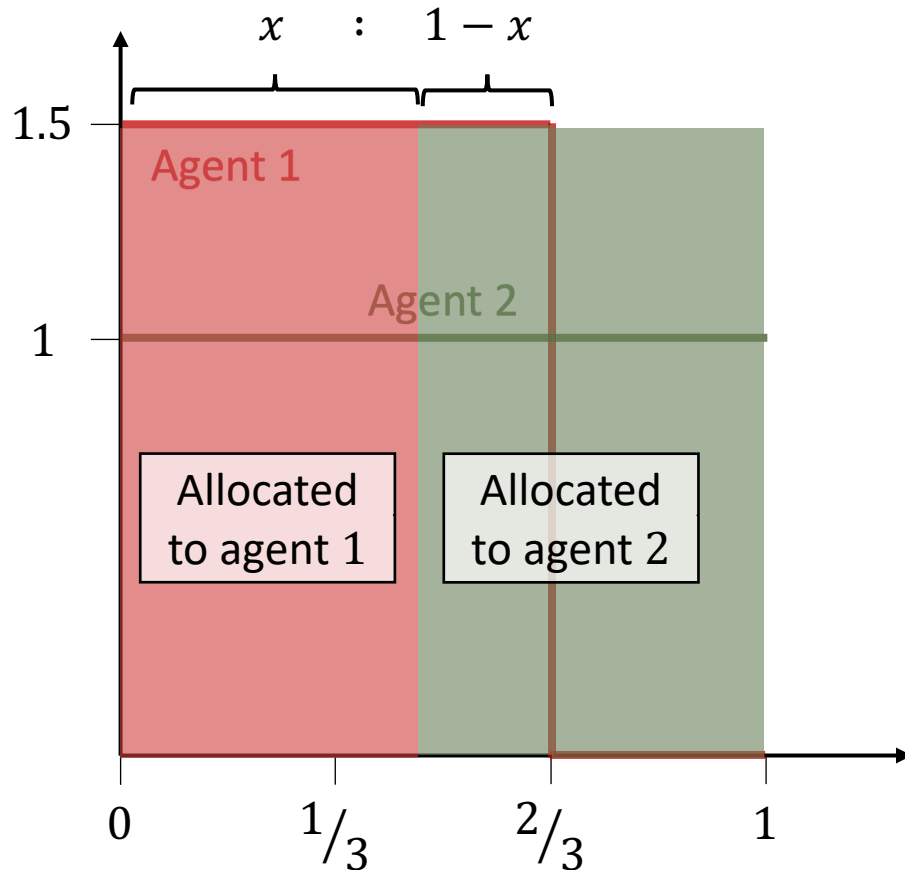
- An allocation  $A^*$  is called **Nash-optimal** if

$$A^* \in \arg \max_A \prod_{i \in N} v_i(A_i)$$

- **Theorem [Segal-Halevi and Sziklai, 2018]**

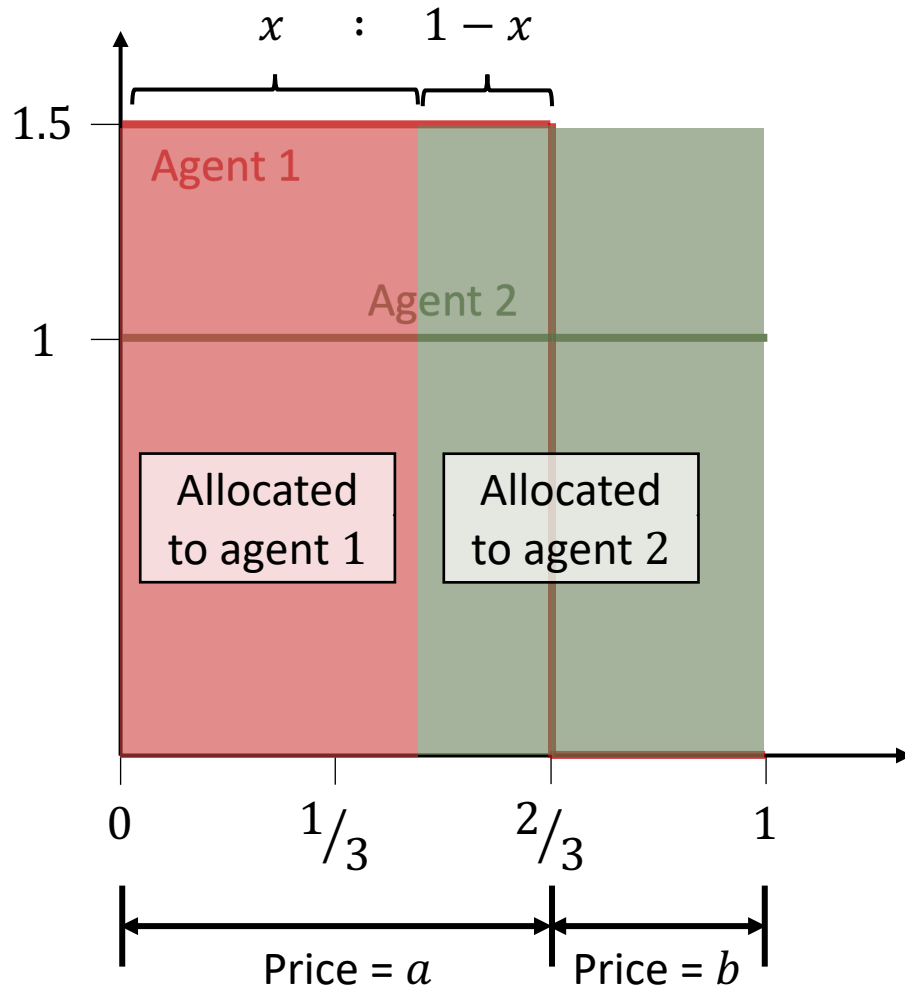
For cake-cutting, the set of s-CEEI allocations is exactly the same as the set of Nash-optimal allocations.

# Nash-Optimality Example



- Due to PO, suppose:
  - Agent 1 gets  $x$  fraction of  $[0, 2/3]$
  - Agent 2 gets  $1 - x$  fraction of  $[0, 2/3]$  and all of  $[2/3, 1]$
  - $v_1(A_1) = x$
  - $v_2(A_2) = (1 - x) \cdot 2/3 + 1/3 = (3 - 2x)/3$
- Maximize  $x \cdot (3 - 2x)/3 \Rightarrow x = 3/4$ 
  - Nash-optimal allocation:
    - $A_1 = [0, 1/2], v_1(A_1) = 3/4$
    - $A_2 = [1/2, 1], v_2(A_2) = 1/2$

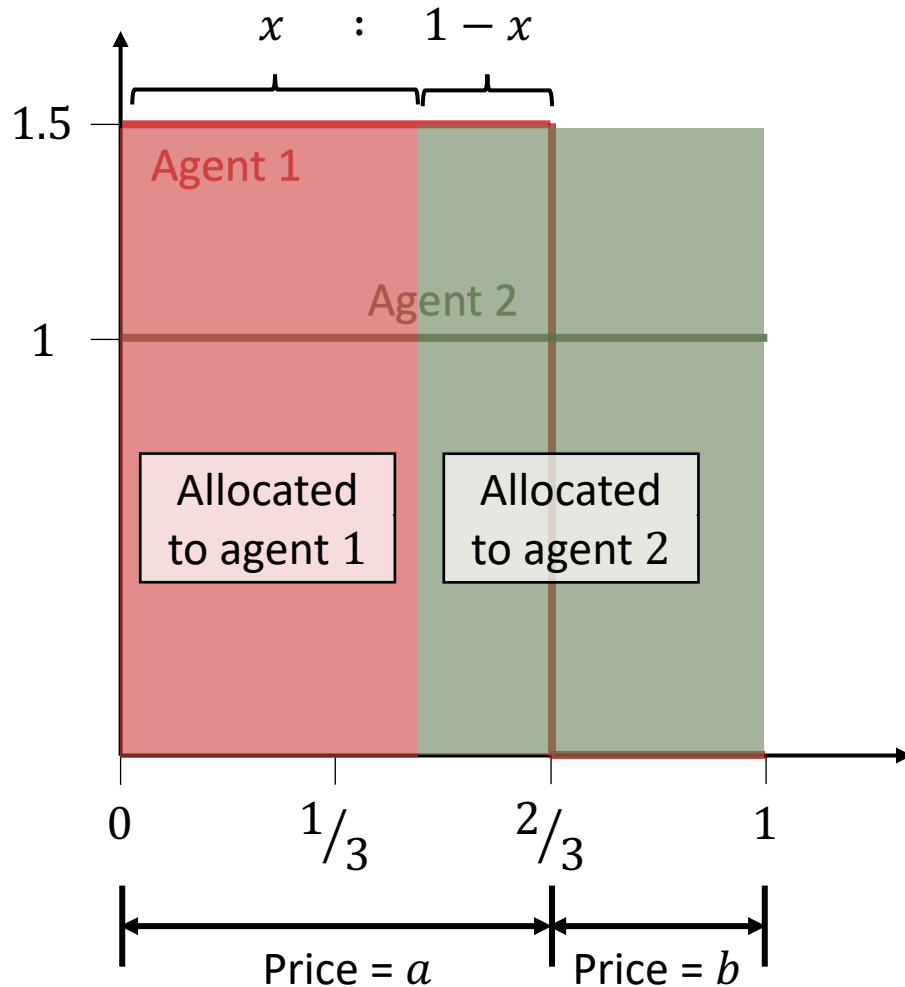
# Nash-Optimality = s-CEEI



- Still must be PO, so like before
  - Agent 1 buys  $x$  fraction of  $[0, 2/3]$
  - Agent 2 buys  $1 - x$  fraction of  $[0, 2/3]$  and all of  $[2/3, 1]$
- Prices:  $P([0, 2/3]) = a, P([2/3, 1]) = b$ 
  - Spending:  $a \cdot x = 1, a \cdot (1 - x) + b = 1$ 
    - Hence,  $a + b = 2$
- Two cases:  $x < 1$  or  $x = 1$



# Nash-Optimality = s-CEEI



- $x < 1$

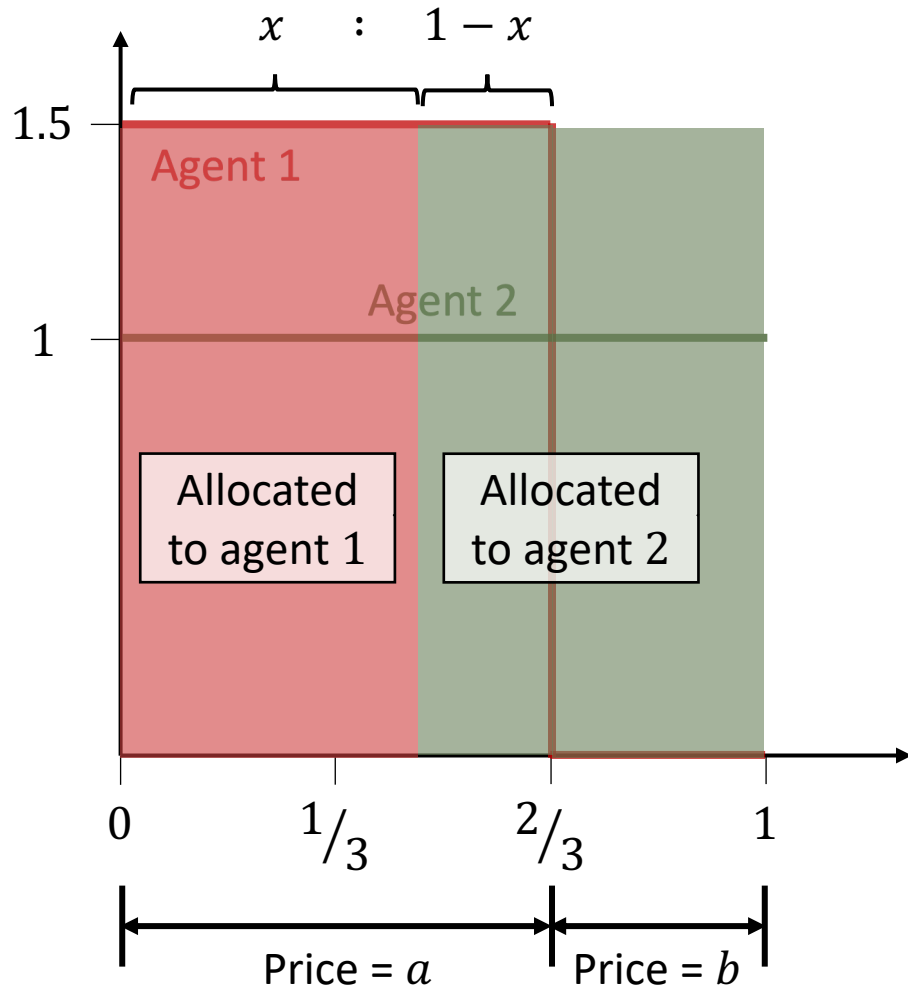
➤ Agent 2 buys parts of both pieces

➤ MBB:

$$\frac{1/3}{b} = \frac{2/3}{a} \Rightarrow a = 2b \Rightarrow (a, b) = (4/3, 2/3)$$

- Substituting in  $a \cdot x = 1$ , we get  $x = 3/4$
- Same as Nash-optimal solution

# Nash-Optimality = s-CEEI



- $x = 1$

- Since  $a \cdot x = 1$ ,  $a \cdot (1 - x) + b = 1$ , we get that  $a = b = 1$
- Agent 2 buys the second piece, so by MBB:

$$\frac{1/3}{b} \geq \frac{2/3}{a} \Rightarrow a \geq 2b$$

- Contradiction!
- So there is no s-CEEI with  $x = 1$

# Strategyproofness

# Strategyproofness (SP)

- Direct-revelation mechanisms

- A direct-revelation mechanism  $h$  takes as input all the valuation functions  $v_1, \dots, v_n$ , and returns an allocation  $A$
- Notation:  $h(v_1, \dots, v_n) = A, h_i(v_1, \dots, v_n) = A_i$

- Strategyproofness (deterministic mechanisms)

- A direct-revelation mechanism  $h$  is called strategyproof if

$$\forall v_1, \dots, v_n, \forall i, \forall v'_i : v_i(h_i(v_1, \dots, v_n)) \geq v_i(h_i(v_1, \dots, v'_i, \dots, v_n))$$

- That is, no agent  $i$  can achieve a higher value by misreporting her valuation, regardless of what the other agents report

# Strategyproofness (SP)

- Strategyproofness (randomized mechanisms)

- Technically, referred to as “truthfulness-in-expectation”
  - When referring to SP for randomized mechanisms, we will refer to this concept

- A randomized direct-revelation mechanism  $h$  is called strategyproof if

$$\forall v_1, \dots, v_n, \forall i, \forall v'_i : E[v_i(h_i(v_1, \dots, v_n))] \geq E[v_i(h_i(v_1, \dots, v'_i, \dots, v_n))]$$

- That is, no agent  $i$  can achieve a higher *expected* value by misreporting her valuation, regardless of what the other agents report
  - Expectation is over the randomness of the mechanism

# Deterministic SP Mechanisms

- **Theorem [Menon and Larson '17, Bei et al. '17]**  
No non-wasteful deterministic SP mechanism is (even approximately) **proportional**.
  - Since EF is at least as strict as Prop, SP+EF is also impossible subject to non-wastefulness.
  - Non-wastefulness can be replaced by a requirement of “connected pieces”, and the impossibility result still holds.

## Open Problem

Does the SP+Prop impossibility hold even without the non-wastefulness assumption?

# Deterministic SP Mechanisms

- SP+PO is easy to achieve
  - E.g. serial dictatorship
- SP+PO+EQ is impossible
  - We saw that even EQ+PO allocations may not exist

## Open Problem

Does there exist a direct revelation, deterministic SP+EQ mechanism?

# Randomized SP Mechanisms

- We want the mechanism *always* return an allocation satisfying a subset of {EQ,EF,PO}, and be SP in expected utilities
- Recall: PO+EQ allocations may not exist
  - Hence, we can only hope for SP+PO+EF or SP+EF+EQ
  - The first is an open problem, but the second combination is achievable!

## Open Problem

Does there exist a randomized SP mechanism which always returns a PO+EF allocation?



# Randomized SP Mechanisms

- **Theorem [Mossel and Tamuz, 2010; Chen et al. 2013]**

There is a randomized SP mechanism that *always* returns an EF+EQ allocation.

- Recall: In a perfect partition  $B$ ,  $v_i(B_k) = 1/n$  for all  $i, k \in N$
- **Algorithm:** Compute a perfect partition and return allocation  $A$  which randomly assigns the  $n$  pieces to the  $n$  agents
- **SP:** Regardless of what the agents report, agent  $i$  receives each piece of the cake with probability  $1/n$ , and thus has expected value exactly  $1/n$
- **EF:** Assuming agents report truthfully (due to SP), agent  $i$  always receives a cake she values at  $1/n$ , and according to her, so do others.

# Existential Summary

✗ = Impossibility  
✓ = Possibility

SP+PO+EF+EQ

✗ Rand

SP+PO+EF

✗ Det

? Rand

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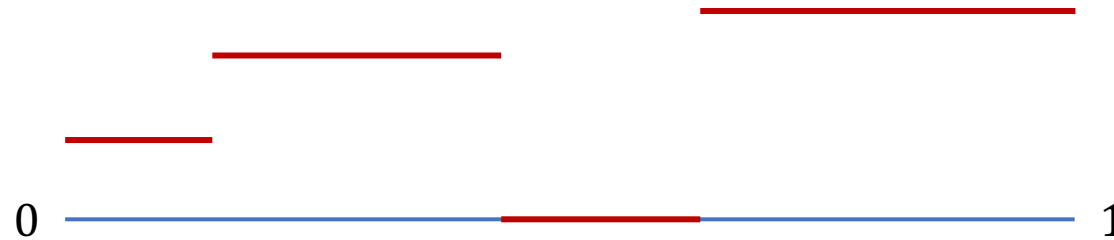
EF+EQ

✓ Det

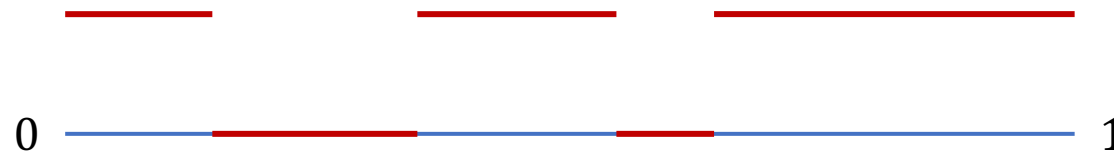
# Special Cases

# Piecewise Constant/Uniform Valuations

Piecewise constant  
density function



Piecewise uniform  
density function



Special case of piecewise constant

# Possibilities

- Theorem [Chen et al., 2013]

For piecewise uniform valuations, there exists a deterministic SP mechanism which returns an EF+PO allocation.

➤ Recall that for general valuations, even deterministic SP+EF is impossible.

- Theorem [Aziz and Ye, 2014]

For piecewise constant valuations, an s-CEEI (i.e. Nash-optimal) allocation can be computed in polynomial time.

➤ Recall that this is EF (thus Prop) and PO.

➤ But this is not SP.

# EF in Robertson-Webb

- Theorem [Kurokawa et al., 2013]

If an algorithm computes an envy-free allocation for  $n$  agents with **piecewise uniform valuations with at most  $g(n)$  queries**, **then** it can also compute an envy-free allocation for  $n$  agents with **general valuations with at most  $g(n)$  queries**.

- Let the same algorithm interact with general valuations  $v_1, \dots, v_n$  via CUT and EVAL queries and return an allocation  $A$
- The proof constructs piecewise uniform valuations  $u_1, \dots, u_n$  which would have resulted in the same responses and  $u_i(A_j) = v_i(A_j)$  for all  $i, j \in N$

# PO in Robertson-Webb

- **Non-wastefulness**

- An allocation  $A$  is called non-wasteful if no piece of the cake that is valued positively by at least one agent is assigned to an agent who has zero value for it
- PO implies non-wastefulness

- **Theorem [Ilanovski, 2012; Kurokawa et al., 2013]**

No finite protocol in the Robertson-Webb model can always produce a non-wasteful allocation, even for piecewise uniform valuations.

- This is the reason we did not provide query complexity results when discussing PO

# Burnt Cake Division



# Model

- Same as regular cake, except agents now have non-positive valuation for every piece of the cake
  - $f_i(x) \leq 0, \forall x \in [0,1]$
  - Hence,  $v_i(X) \leq 0, \forall X \in \mathcal{A}$
- Equitability and perfect partitions carry over from the goods case
  - Simply use  $-f_i$  and  $-v_i$



# Dividing a Burnt Cake

- Theorem [Peterson and Su, 2009]

For burnt cake division, there exists a finite (but unbounded) protocol for finding an envy-free allocation with  $n$  agents.

- Builds upon the Brams-Taylor protocol for dividing a good cake
- But certain operations require non-trivial transformations to the world of chores

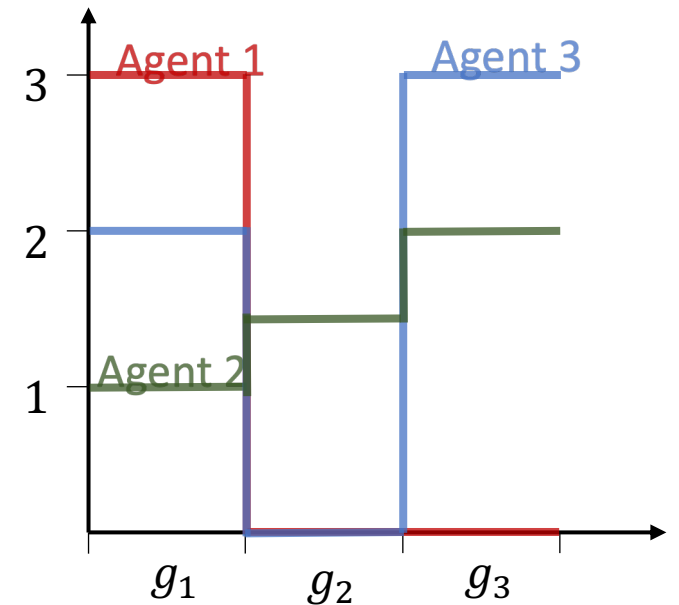
## Open Problem

Is there a bounded envy-free protocol for burnt cake division?

# (Homogeneous) Divisible Goods

# Model

- Agents:  $N = \{1, 2, \dots, n\}$
- Resource: Set of divisible goods  $M = \{g_1, g_2, \dots, g_m\}$
- Allocation  $A = (A_1, \dots, A_n)$ 
  - $A_i = (A_{i,j})_{j \in [m]}$
  - $\forall i, j: A_{i,j} \in [0, 1]$
  - $\forall j: \sum_i A_{i,j} \leq 1$
- Assume additive valuations  $v_i(A_i) = \sum_j A_{i,j} v_i(g_j)$
- Special case of cake cutting (up to normalization)



# $n = 2$ : Adjusted Winner Procedure

[Brams and Taylor 1996]

- Input: **Normalized** valuation functions
- Order the goods by ratio  $v_1(g)/v_2(g)$ .

	$g_1$	$g_2$	$g_3$	$g_4$	$g_5$	$g_6$
$a_1$	20	30	<del>15</del> 30	10	5	5
$a_2$	10	15	20 <del>10</del>	15	10	30

$v_1(g)/v_2(g)$  high  $\longleftrightarrow$   $v_1(g)/v_2(g)$  low

- Divide the goods so that agent 1 receives goods  $g_1, \dots, g_{j-1}$ , agent 2 receives goods  $g_{j+1}, \dots, g_m$  for some  $j$ , and  $v_1(A_1) = v_2(A_2)$ 
  - $g_j$  is divided between the agents, if necessary

# $n = 2$ : Adjusted Winner Procedure

[Brams and Taylor 1996]

- **Theorem [Brams and Taylor 1996]:**

- The adjusted winner procedure is envy-free (and therefore proportional), equitable and Pareto optimal

- Breaks down for  $n > 2$

- As in cake cutting, EF + EQ + PO is impossible, what about two of the three?
- EF+EQ: Divide each good equally among agents (“perfect partition”)
- EQ + PO: Impossible
- EF + PO: Can achieve with CEEI

	$g_1$	$g_2$
$a_1$	1	0
$a_2$	1	0
$a_3$	0	1

# CEEI

- With a fixed set of items, the definition of s-CEEI (that we will now call just CEEI) becomes simpler.

- Equilibrium price  $p_j > 0$  for each good  $g_j$ 
  - Assume for simplicity that  $\forall j \exists i$  with  $v_i(g_j) > 0$
- CE: If  $A_{i,j} > 0$  then  $\frac{v_i(g_j)}{p_j} \geq \frac{v_i(g_k)}{p_k}$  for all  $k$
- EI:  $\sum_j p_j A_{i,j} = 1$  for all  $i$

# Eisenberg-Gale convex program

- Can compute a CEEI allocation as the solution to the Eisenberg-Gale [1959] convex program:

$$\max \sum_{i \in N} \log u_i \text{ s.t.}$$

$$\forall i: u_i \leq \sum_{g_j \in M} A_{i,j} v_i(g_j)$$

$$\forall j: \sum_{i \in N} A_{i,j} \leq 1$$

$$\forall i, j: A_{i,j} \geq 0$$

- **Theorem [Orlin 2010, Végh 2012]:**
  - The Eisenberg-Gale convex program can be solved in strongly polynomial time.



# Strategyproofness

- CEEI solution is fair and efficient but not strategyproof.
  - It is **strategyproof in the large (SP-L)** [Azevedo and Budish 2018] though
- **Theorem [Han et al. 2011]:**
  - No strategyproof mechanism that always outputs a complete allocation can achieve better than a  $1/m$  approximation to the optimal **social welfare** for large enough  $n$ .
    - Social welfare =  $\sum_{i \in N} v_i(A_i)$
- **Theorem [Cole et al. 2013]:**
  - There is a strategyproof partial allocation mechanism that provides every agent with a  $1/e$  fraction of their CEEI utility.
  - Allocation is envy-free but not proportional

# SP + Prop + EF

- SP + Prop + EF is trivial! Just allocate everyone an equal fraction of each good.
  - What if we also want PO?
- **Theorem [Schummer 1996]:**
  - It is impossible to achieve SP + Prop + PO.
  - SP + PO: Serial dictatorship.
- SP + Prop + EF can also be achieved non-trivially [Freeman et al. 2019]
  - Additionally achieves strict SP: agents always achieve strictly higher utility by reporting their beliefs truthfully than by lying.
  - Exploits a correspondence between fair division and wagering mechanisms [Lambert et al. 2008] to utilize proper scoring rules (e.g. Brier score)

# Allocating Divisible Goods + Bads

# Model

- Agents:  $N = \{1, 2, \dots, n\}$
- Resources: Set of divisible “items”  $M = \{o_1, o_2, \dots, o_m\}$
- Allocation  $A = (A_1, \dots, A_n)$ 
  - $A_i = (A_{i,j})_{j \in [m]}$
  - $\forall i, j: A_{i,j} \in [0, 1]$
  - $\forall j: \sum_i A_{i,j} \leq 1$
- Assume additive valuations:  $v_i(A_i) = \sum_j A_{i,j} v_i(o_j)$ 
  - However,  $v_i(o_j)$  can be positive, zero, or negative
- We’ll refer to s-CEEI simply as CEEI in this case

# Achieving EF+PO

- Theorem [Bogomolnaia et al. 2017]

- There always exists a CEEI allocation, which is envy-free and Pareto optimal.
- The CEEI solution is “welfarist”, i.e., the set of feasible utility profiles is enough to identify the set of CEEI utility profiles.
- The CEEI utility profile is given by the following:
  1. If it is possible to give a positive utility to each agent (who can receive a positive utility), then maximizing the Nash welfare gives the unique CEEI utility profile.
  2. Else, if the all-zero utility profile is feasible and Pareto optimal, then it is the unique CEEI utility profile.
  3. Else, there can be **exponentially many** CEEI utility profiles, which give non-positive utility to each agent.
- Their actual result is stronger and in a more general model

# Not Covered

- Nash equilibria of cake-cutting
- Optimal cake-cutting
  - Algorithms for maximizing social welfare subject to fairness constraints
- Number of cuts and moving knives protocols
  - Possibility and impossibility results for  $n - 1$  cuts
- Multidimensional cakes
- Randomized or strategyproof Robertson-Webb protocols
- Non-additive valuations
- ...

# Indivisible Goods

# Model

- Agents:  $N = \{1, 2, \dots, n\}$
- Resource: Set of **indivisible goods**  $M = \{g_1, g_2, \dots, g_m\}$
- Allocation  $A = (A_1, \dots, A_n) \in \Pi_n(M')$  is a partition of  $M'$  for some  $M' \subseteq M$ .
- Each agent  $i$  has a valuation  $v_i : 2^M \rightarrow \mathbb{R}_+$ 
  - $v_i : 2^M \rightarrow \mathbb{R}_-$  in the case of **bads**,  $v_i : 2^M \rightarrow \mathbb{R}$  for both **goods and bads**

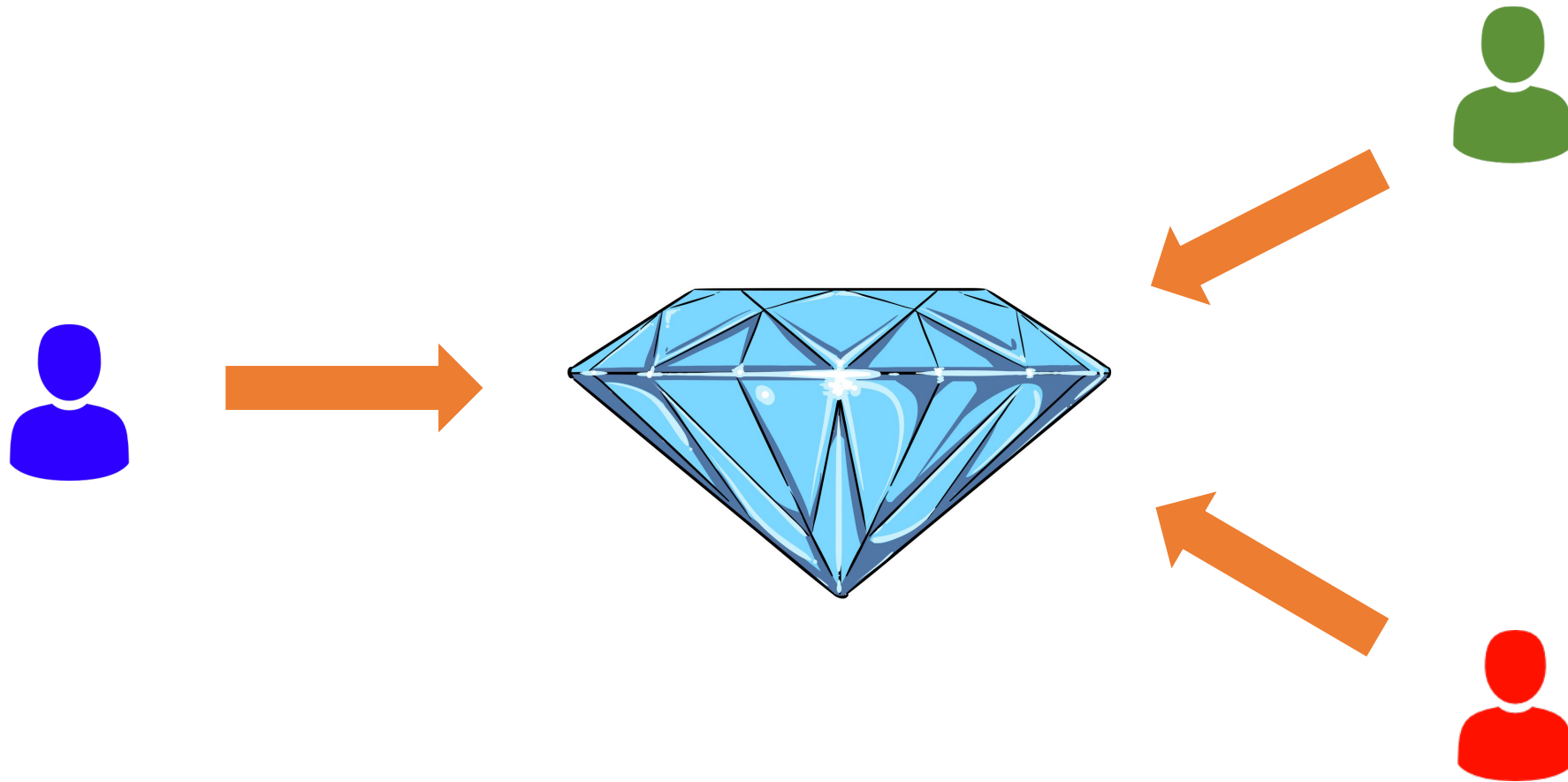


# Valuation Functions

- **Additive:**  $\forall X, Y$  with  $X \cap Y = \emptyset$ :  $v_i(X \cup Y) = v_i(X) + v_i(Y)$ 
  - Equivalently:  $v_i(X) = \sum_{g \in X} v_i(g)$
  - Value for a good independent of other goods received
- **Submodular:**  $\forall X, Y : v_i(X \cup Y) + v_i(X \cap Y) \leq v_i(X) + v_i(Y)$ 
  - Equivalently:  $\forall X, Y$  with  $X \subseteq Y$ :  $v_i(X \cup \{g\}) - v_i(X) \geq v_i(Y \cup \{g\}) - v_i(Y)$
- **Subadditive:**  $\forall X, Y$  with  $X \cap Y = \emptyset$ :  $v_i(X \cup Y) \leq v_i(X) + v_i(Y)$
- Submodular and subadditive definitions capture the idea of diminishing returns.

Most results for additive valuations unless stated otherwise

# Need new guarantees!



# Envy-Freeness up to One Good

# Envy-Freeness up to One Good (EF1)

[Lipton et al 2004, Budish 2011]

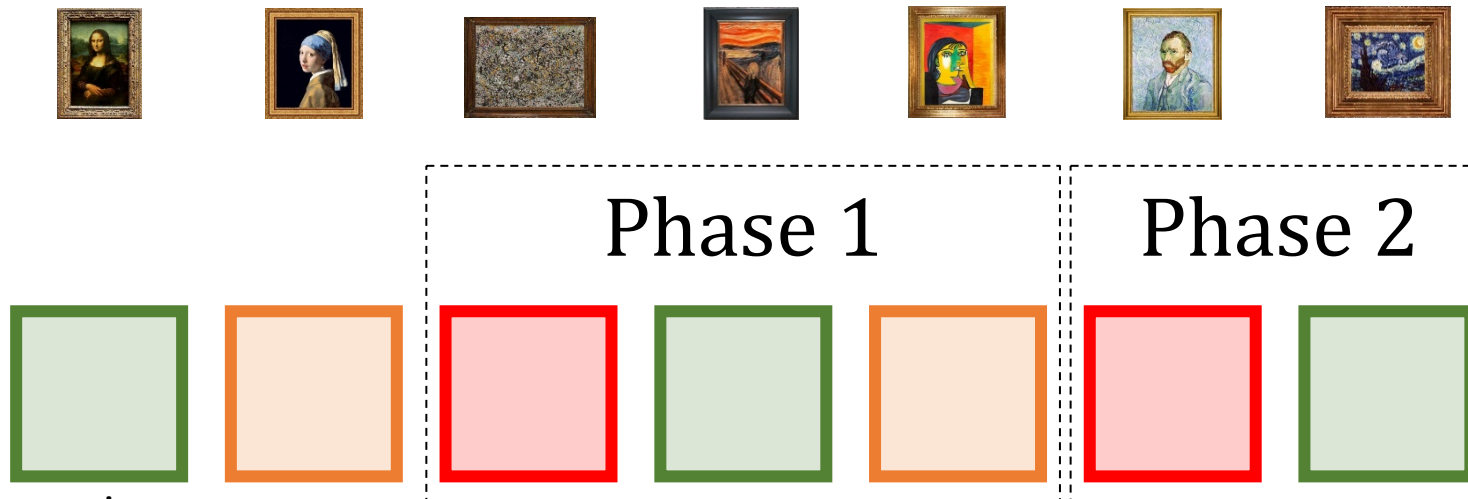
- An allocation is **envy-free up to one good (EF1)** if, for all agents  $i, j$ , there exists a good  $g \in A_j$  for which

$$v_i(A_i) \geq v_i(A_j - g)$$

- “Agent  $i$  may envy agent  $j$ , but the envy can be eliminated by removing a single good from  $j$ ’s bundle.”
  - Note: We don’t consider  $A_j = \emptyset$  a violation of EF1.

# Round Robin Algorithm

- Fix an ordering of the agents  $\sigma$ .
- In round  $k \bmod n$ , agent  $\sigma_k$  selects their most preferred remaining good.
- **Theorem:** Round robin satisfies EF1.



Animation Credit: Ariel Procaccia

# Algorithm for Achieving EF1

- Envy graph: Edge from  $i$  to  $j$  if  $i$  envies  $j$
- Greedy algorithm [Lipton et al. 2004]
  - One at a time, allocate a good to an agent that no one envies
  - While there is an envy cycle, rotate the bundles along the cycle.
    - Can prove this loop terminates in a polynomial number of steps
- Removing the most recently added good from an agent's bundle removes envy towards them.
- Neither this algorithm nor round robin is Pareto optimal.

# EF1 with Goods and Bads [Aziz et al. 2019]

- An allocation is **envy-free up to one item (EF1)** if, for all agents  $i, j$ , there exists an item  $o \in A_i \cup A_j$  for which

$$v_i(A_i \setminus \{o\}) \geq v_i(A_j \setminus \{o\})$$

- Round robin fails EF1

	$o_1$	$o_2$	$o_3$	$o_4$
$a_1$	2	1	-4	-4
$a_2$	2	-3	-4	-4

# Double Round Robin

- Let  $O^- = \{o \in O : \forall i \in N, v_i(o) \leq 0\}$  denote all **unanimous bads** and  $O^+ = \{o \in O : \exists i \in N, v_i(o) > 0\}$  denote all objects that are a **good for some agent**.
  - Suppose that  $|O^-| = an$  for some  $a \in \mathbb{N}$ . If not, add dummy bads with  $v_i(o) = 0$  for all  $i \in N$ .
- Double round robin:
  - Phase 1:  $O^-$  is allocated by round robin in order  $(1, 2, \dots, n - 1, n)$
  - Phase 2:  $O^+$  is allocated by round robin in order  $(n, n - 1, \dots, 2, 1)$
  - Agents can choose to skip their turn in phase 2



# Double Round Robin

- Theorem [Aziz et al. 2019]:

- The double round robin algorithm outputs an allocation that is EF1 for combinations of goods and bads in polynomial time.
- Proof idea: Let  $i < j$ . Agent  $i$  can envy  $j$  up to one item in phase 1 (but not vice versa), and agent  $j$  can envy  $i$  up to one item in phase 2 (but not vice versa)

	$O^+$		$O^-$	
	$o_1$	$o_2$	$o_3$	$o_4$
$a_1$	2	1	-4	-4
$a_2$	2	-3	-4	-4

# Maximum Nash Welfare

- **Maximum Nash Welfare (MNW):** Select the allocation that maximizes the geometric mean of agent utilities (more on this later).

$$A = \arg \max \left( \prod_i v_i(A_i) \right)^{1/n}$$

- This is just Nash-optimality from earlier
- What if  $\prod_i v_i(A_i) = 0$  for all allocations?
  - Find an allocation that maximizes  $|\{v_i(A_i) > 0\}|$ , and subject to that maximizes

$$\left( \prod_{i:v_i(A_i)>0} v_i(A_i) \right)^{1/n}$$

# EF1 + PO

- **Theorem [Caragiannis et al. 2016]:**
  - The MNW allocation satisfies EF1 and PO.
  - PO: A Pareto-improving allocation would have higher geometric mean of utilities for agents with non-zero utility or more agents with non-zero utility.
  - EF1: Let  $g_i^* = \arg \max_{g \in A_i} v_i(g)$ . Not-too-hard proof shows  $v_j(A_j) \geq v_j(A_i \setminus g_i^*)$  for all  $j$ .

	$g_1$	$g_2$	$g_3$	$g_4$	$g_5$	$g_6$
$a_1$	2	1	3	0	1	2
$a_2$	10	1	1	1	2	5
$a_3$	3	1	3	0	5	2

# Computing EF1 + PO

- The MNW allocation is strongly NP-hard to compute (reduction from X3C).
  - Actually, it's APX-hard [Lee 2017].
- Special case: Binary valuations
  - MNW allocation can be computed in polynomial time [Darmann and Schauer 2015, Barman et al. 2018].
  - However, round robin already guarantees EF1 + PO in this setting.

# Computing EF1 + PO

- Theorem [Barman et al. 2018]:

- There exists a pseudo-polynomial time algorithm for computing an allocation satisfying EF1 + PO
- Algorithm uses local search (sequence of item swaps and price rises) to compute an integral competitive equilibrium that is **price envy-free up to one good**.
- Price envy-free up to one good:  $\forall i, k, \exists j: p(A_i) \geq p(A_k \setminus \{g_j\})$
- Need different entitlements because CEEI might not exist with indivisibilities
  - Two agents, one item...

# Computing EF1 + PO

Open Problem:  
Complexity of computing an EF1 + PO allocation

Open Problem:  
Does there always exist an EF1 + PO allocation for  
submodular valuation functions?

# EF1 + PO for Bads

- Theorem [Aziz et al. 2019]:
  - When items can be either goods or bads and  $n = 2$ , an EF1 + PO allocation always exists and can be found in polynomial time

Open Problem:  
Does an EF1 + PO allocation always exists for bads?

# Proportionality up to One Good



# Proportionality up to One Good (Prop1)

[Conitzer et al. 2017]

- An allocation is **proportional up to one good (Prop1)** if, for every agent  $i$ , there exists a good  $g$  for which

$$v_i(A_i \cup \{g\}) \geq \frac{v_i(M)}{n}$$

	$g_1$	$g_2$	$g_3$
$a_1$	1	3	3
$a_2$	1	3	3

$$v_1(A_1 \cup \{g_2\}) = 4 \geq \frac{7}{2} = \frac{v_i(M)}{n}$$

# Prop1 + PO

- Any algorithm that satisfies EF1 + PO is also Prop1 + PO.
  - MNW
  - Barman et al. [2018] algorithm
- Theorem [Barman and Krishnamurthy 2019]:
  - An allocation satisfying Prop1 + PO can be computed in strongly polynomial time.
- Allocation is a careful rounding of the fractional CEEI allocation.
  - In contrast, there exist instances in which no rounding of the fractional CEEI allocation will give EF1 [Caragiannis et al., 2016].

# Envy-Freeness up to the Least Valued Good

# Envy-Freeness up to the Least Valued Good

[Caragiannis et al. 2016]

	$g_1$	$g_2$	$g_3$
$a_1$	10	5	5
$a_2$	10	$\epsilon$	$\epsilon$

- An allocation is **envy-free up to the least valued good (EFX)** if, for all agents  $i, j$ , and every  $g \in A_j$  with  $v_i(g) > 0$ ,

$$v_i(A_i) \geq v_i(A_j \setminus \{g\}).$$

# Leximin Allocation

- Leximin allocation:

- First, maximize the minimum utility any agent receives. Subject to this, maximize the second-minimum utility. Then the third-minimum utility, etc.

	$g_1$	$g_2$	$g_3$	$g_4$	$g_5$	$g_6$
$a_1$	2	1	3	0	1	2
$a_2$	10	1	1	1	2	5
$a_3$	3	1	3	0	5	2

# Satisfying EFX

	$g_1$	$g_2$	$g_3$	$g_4$
$a_1$	4	1	2	2
$a_2$	4	1	2	2
$a_3$	4	1	2	2

- Theorem [Plaut and Roughgarden, 2018]:
  - The Leximin allocation satisfies EFX + PO for agents with (general) identical valuations.
- Theorem [Plaut and Roughgarden, 2018]:
  - The Leximin allocation satisfies EFX + PO for two agents with (normalized) additive valuations.

Open Problem:  
Does there always exist a complete allocation satisfying EFX?

# Satisfying EFX

- What about partial allocations satisfying EFX?
  - Easy! We can just throw all goods away and take the empty allocation.
- Theorem [Caragiannis et al. 2019]:
  - There exists a partial allocation that satisfies EFX and achieves a 2-approximation to the optimal Nash welfare.
  - No (complete or partial) EFX allocation can achieve a better approximation.

	Existence		Computation	
	Without PO	With PO	Without PO	With PO
Envy-Freeness	No	No	NP-hard	NP-hard
EFX	Open	Open	Open	Open
EF1	Yes	Yes	Polytime	Open
Prop1	Yes	Yes	Polytime	Polytime



# Maximin Share

# Maximin Share [Budish 2011]

- “If I partition the goods into  $n$  bundles and receive an adversarially chosen bundle, how much utility can I guarantee myself?”
- Define  $MMS_i^k(S) = \max_{(P_1, \dots, P_k) \in \Pi_k(S)} \min_{1 \leq j \leq k} v_i(P_j)$
- MMS allocation: One for which  $v_i(A_i) \geq MMS_i^n(M)$
- Note that  $MMS_i^n(M) \leq \frac{v_i(M)}{n}$ , so Proportionality implies MMS

# Maximin Share [Budish 2011]

	$g_1$	$g_2$	$g_3$	$g_4$	$g_5$	$g_6$
$a_1$	2	1	3	0	1	2
$a_2$	10	1	1	1	2	5
$a_3$	3	1	3	0	5	2

$$MMS_1^n(M) = \min(3, 3, 3) = 3$$

$$MMS_2^n(M) = \min(10, 5, 5) = 5$$

$$MMS_3^n(M) = \min(4, 5, 5) = 4$$

# Achieving Maximin Allocations

- **Theorem [Procaccia and Wang 2014]:**
  - There exist instances for which no allocation satisfies MMS.
- Instead, consider approximations.
  - c-MMS: allocation for which  $v_i(A_i) \geq c \cdot MMS_i^n(M)$
  - Guarantee  $v_i(A_i) \geq MMS_i^k(M)$  for some  $k > n$
- **Theorem [Budish 2011]:**
  - There always exists an allocation that satisfies  $v_i(A_i) \geq MMS_i^{(n+1)}(M)$  for every agent  $i$ .

# c-MMS Allocations

- Theorem [Procaccia and Wang 2014]:
  - A  $(2/3)$ -MMS allocation always exists.
- Theorem [Amanatidis et al. 2017]:
  - A  $(2/3-\epsilon)$ -MMS allocation can be computed in polynomial time.
- Theorem [Ghodsi et al. 2018]:
  - A  $(3/4)$ -MMS allocation always exists and a  $(3/4-\epsilon)$ -MMS allocation can be computed in polynomial time.
- Theorem [Garg and Taki, 2020]:
  - A  $(3/4 + 1/(12n))$ -MMS allocation always exists and a  $(3/4)$ -MMS allocation can be computed in polynomial time.

# c-MMS Allocations

[Ghodsi et al. 2018]

	Additive	Submodular	Subadditive
Lower bound (existence)	$\frac{3}{4} + \frac{1}{12n}$	$\frac{1}{3}$	$\frac{1}{10} \lceil \log m \rceil$
Lower bound (polynomial algorithm)	$\frac{3}{4}$	$\frac{1}{3}$	-
Upper bound	$1 - \frac{1}{n^{n+1}}$	$\frac{3}{4}$	$\frac{1}{2}$

Open Problem:  
Close the gaps!

# c-MMS Allocations for Bads

- Theorem [Aziz et al. 2017]:
  - A 2-MMS allocation always exists and can be computed in polynomial time when dividing bads.
- Theorem [Barman and Krishnamurthy 2017]:
  - A  $(4/3)$ -MMS allocation always exists and can be computed in polynomial time when dividing bads.

# Groupwise MMS [Barman et al. 2018]

- Idea:  $MMS_i^k$  should be guaranteed for all groups  $J$  of agents of size  $k$  and set of goods  $\cup_{i \in J} A_i$

	$g_1$	$g_2$	$g_3$	$g_4$	$g_5$	$g_6$
$a_1$	5	5	$5 + \epsilon$	$5 - \epsilon$	$5 + \epsilon$	$5 - \epsilon$
$a_2$	5	5	$5 + \epsilon$	$5 - \epsilon$	$5 + \epsilon$	$5 - \epsilon$
$a_3$	10	10	0	0	$\epsilon$	$\epsilon$

- $v_3(A_3) \geq MMS_3^3(M)$  but  $v_3(A_3) < MMS_3^2(A_1 \cup A_3)$



# Groupwise MMS [Barman et al. 2018]

- Allocation  $A$  satisfies Groupwise Maximin Share (GMMS) if,

$$\forall i: v_i(A_i) \geq \max_{J \subseteq N} MMS_i^{|J|}(\cup_{j \in J} A_j)$$

- **Theorem [Barman et al. 2018]:**
  - When valuations are additive, a 0.5-GMMS allocation exists and can be found in polynomial time.
  - Algorithm: Select an agent who is not envied by any other agent, and allocate her her most preferred unallocated good.
  - Small refinement of EF1 algorithm from earlier

# (Relaxed) Equitability

# Equitability

- Recall equitability:

$$\forall i, j \in N: v_i(A_i) \geq v_j(A_j)$$

- We can relax it in the same way we did for envy-freeness [Gourves et al. 2014, Freeman et al. 2019].

- **Equitability up to one good (EQ1):**

$$\forall i, j \in N, \exists g \in A_j: v_i(A_i) \geq v_j(A_j \setminus \{g\})$$

- **Equitability up to any good (EQX):**

$$\forall i, j \in N, \forall g \in A_j: v_i(A_i) \geq v_j(A_j \setminus \{g\})$$

# Algorithm for Achieving EQX

- Greedy Algorithm [Gourves et al. 2014]:
  - Allocate to the lowest-utility agent the unallocated good that she values the most.
- Almost the same as EF1 algorithm, but achieves EQX!
  - Compare to EFX, existence still unknown

# EQ1/EQX + PO

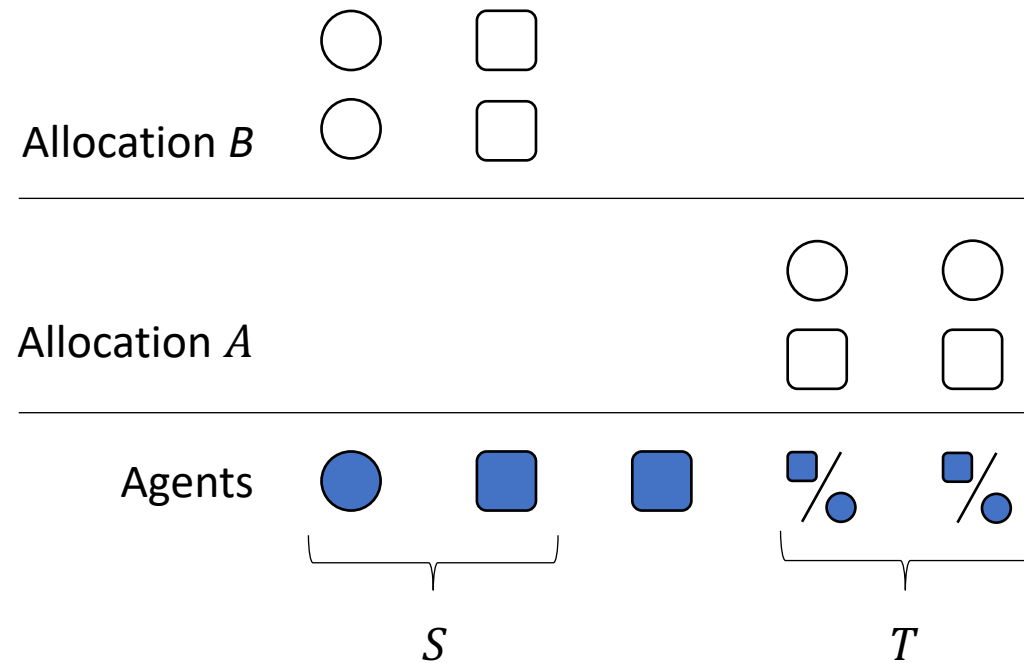
- Theorem [Freeman et al. 2019]:
  - An allocation satisfying EQ1 and PO may not exist.
  - Compare to EF1 + PO always exists

	$g_1$	$g_2$	$g_3$	$g_4$	$g_5$	$g_6$
$a_1$	1	1	1	0	0	0
$a_2$	0	0	0	1	1	1
$a_3$	0	0	0	1	1	1

- Theorem [Freeman et al. 2019]:
  - When valuations are strictly positive, the Leximin allocation is EQX + PO

# Group Fairness

# Beyond Individual Fairness



Envy-Free up to One Good (EF1)

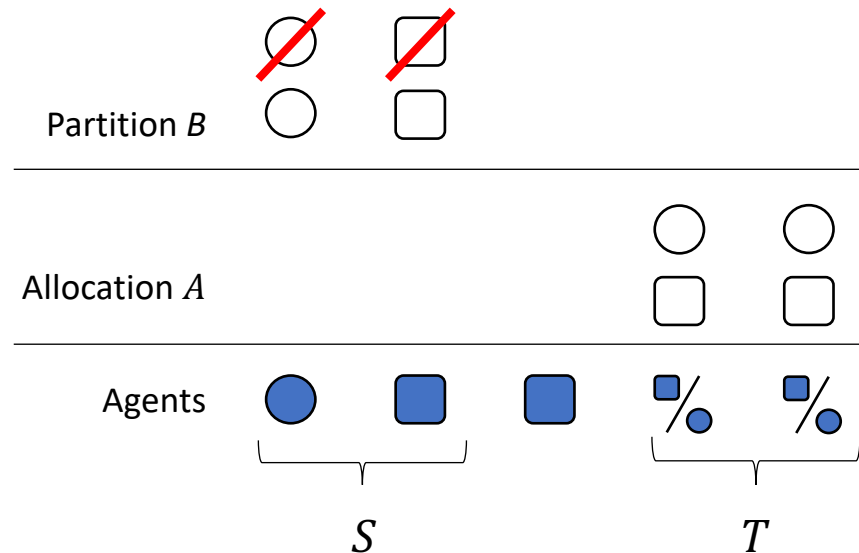
# Group Fairness

- An allocation  $A$  is **group fair** if for every non-empty  $S, T \subseteq N$  and every partition  $(B_i)_{i \in S}$  of  $\cup_{j \in T} A_j$ ,  $\left(\frac{|S|}{|T|}\right) \cdot (v_i(B_i))_{i \in S}$  does not Pareto dominate  $(v_i(A_i))_{i \in S}$
- “It should not be possible to **redistribute the goods allocated to group T amongst group S** in such a way that every member of group S is (weakly, with at least one strictly) **better off**, with utilities adjusted for group sizes”
- Group Fairness  $\Rightarrow$  EF + PO



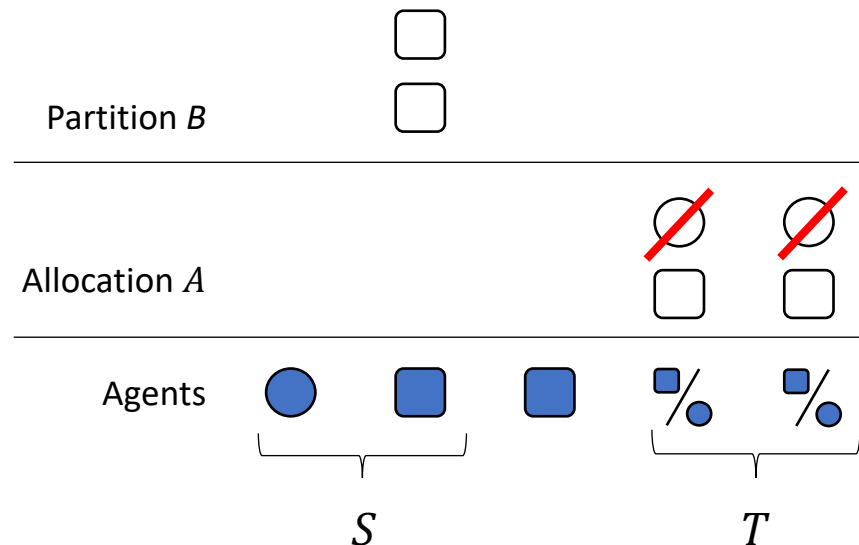
# Group Fairness Relaxations

- **Group Fairness up to One Good, After (GF1A) [Conitzer et al. 2019]**
  - “It should not be possible to redistribute the goods allocated to group T amongst group S in such a way that every member of group S is (weakly, with at least one strictly) better off, **even when one good is removed from each agent in S**, with utilities adjusted for group sizes”



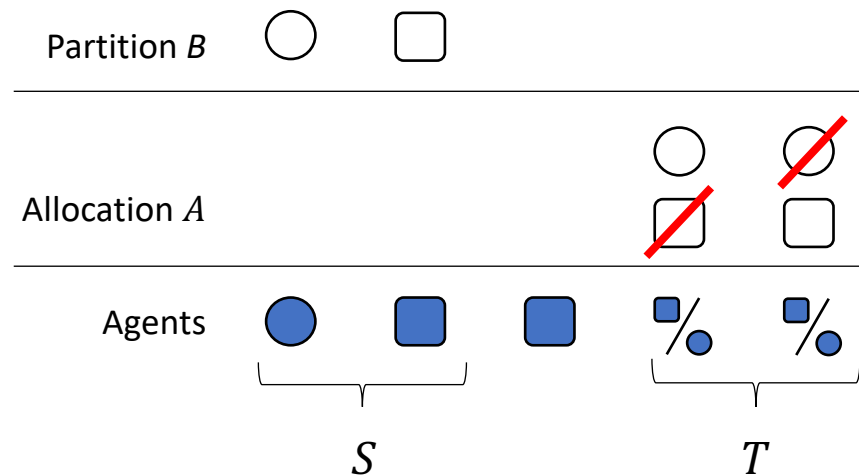
# Group Fairness Relaxations

- **Group Fairness up to One Good, Before (GF1B) [Conitzer et al. 2019]**
  - “It should not be possible to redistribute the goods allocated to group T, **with one good per agent in T removed**, amongst group S in such a way that every member of group S is (weakly, with at least one strictly) better off, with utilities adjusted for group sizes”



# Group Fairness Relaxations

- **Group Fairness up to One Good, Before (GF1B) [Conitzer et al. 2019]**
  - “It should not be possible to redistribute the goods allocated to group T, **with one good per agent in T removed**, amongst group S in such a way that every member of group S is (weakly, with at least one strictly) better off, with utilities adjusted for group sizes”



# Achieving GF1A/GF1B

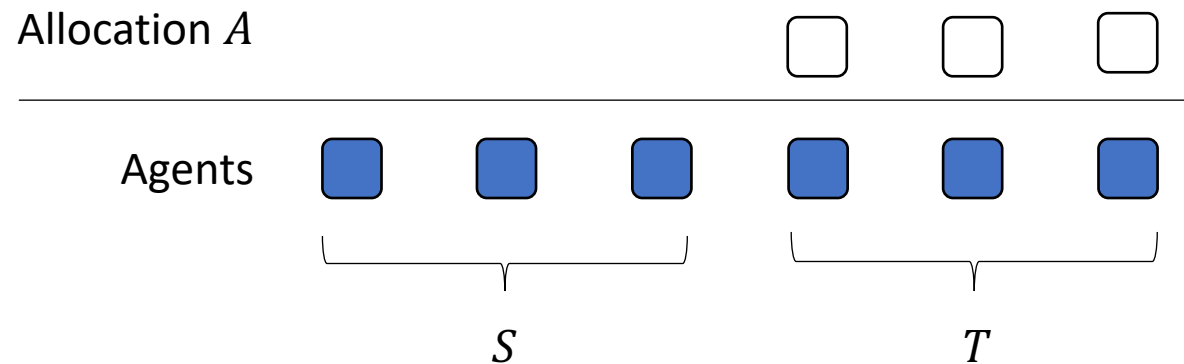
- **Locally Nash-optimal allocation:** Product of utilities cannot be improved by moving a single good.  
 $\forall i, j, g \in A_j: v_j(g) > 0 \text{ and } v_i(A_i) \cdot v_j(A_j) \geq v_i(A_i + g) \cdot v_j(A_j - g)$
- **Theorem [Conitzer et al. 2019]:**
  - Any locally Nash-optimal allocation satisfies GF1A and GF1B.
  - Can be computed in pseudo-polynomial time by local search
  - When valuations are identical, an allocation is locally Nash-optimal iff it is EFX/EQX.

Open Problem:

Can we compute a locally Nash-optimal allocation in polynomial time?

# Known Groups

- When we want to provide guarantees for **all** subsets of agents, “up to one good per agent” guarantees are the best we can give.



Open Problem:

Can we give stronger guarantees when  $S$  and  $T$  are fixed in advance?

# Nash Welfare Approximation

# Nash Welfare Approximation

- We have seen that MNW satisfies several nice properties.
  - GF1A/B ( $\Rightarrow$  EF1) + PO
  - Scale-free
  - Natural fairness/efficiency tradeoff
- But NP-hard to optimize. Can we approximate?
- **Theorem [Lee 2017]**
  - Computing an allocation that maximizes the geometric mean of agent utilities under additive valuation functions is APX-hard.
  - Approximating to within a factor of 1.00008 is NP-hard.

# Nash Welfare Approximation

- Theorem [Cole and Gkatzelis 2015, Cole et al 2017]:
  - There exists a polynomial time algorithm that approximates the MNW objective to within a constant multiplicative factor of 2.
- Theorem [Barman et al. 2018]:
  - There exists a polynomial time algorithm that approximates the MNW objective to within a constant multiplicative factor of 1.45.

Open Problem:

Close the gap between the 1.00008 lower bound and 1.45 upper bound.



# Nash Welfare Approximation

- Approximate MNW solutions may not retain the nice properties of the exact solution.
- **Theorem [Garg and McGlaughlin 2019]:**
  - There exists a polynomial time algorithm that approximates the MNW objective to within a constant multiplicative factor of 2 and achieves Prop1,  $(1/2n)$ -MMS and PO.
- And recall, there exists a partial allocation that satisfies EFX and is a 2-approximation to MNW objective [Caragiannis et al 2019].

# Price of Fairness

# Price of Fairness

- What effect does requiring a fairness property have on the social welfare?
- **Price of Fairness [Bertsimas et al. 2011, Caragiannis et al. 2012]:**
  - The price of fairness of fairness property  $P$  is defined as the ratio of the maximum possible social welfare and the maximum social welfare of an allocation that satisfies  $P$ .
- **Strong Price of Fairness [Bei et al. 2019]:**
  - The strong price of fairness of fairness property  $P$  is defined as the ratio of the maximum possible social welfare and the minimum social welfare of an allocation that satisfies  $P$ .
- Cf. Price of Stability and Price of Anarchy

# Price of Fairness

- **Theorem [Caragiannis et al. 2012]:**
  - The price of fairness for proportionality, envy-freeness and equitability are:

	Indivisible Goods	Cake Cutting
Proportionality	$\Theta(n)$	$\Theta(\sqrt{n})$
Envy-freeness	$\Theta(n)$	$\Theta(\sqrt{n})$
Equitability	$\infty$	$\Theta(n)$

- Caragiannis et al. also studied divisible items, and bads.

# Price of Fairness

- Theorem [Bei et al. 2019]:
  - Bounds on the (strong) price of fairness for indivisible goods

	Price of P	Strong Price of P
EF1	LB: $\Omega(\sqrt{n})$ , UB: $O(n)$	$\infty$
Round Robin	$n$	$n^2$
Max Nash Welfare	$\Theta(n)$	$\Theta(n)$
Leximin	$\Theta(n)$	$\Theta(n)$
Pareto optimality	1	$\Theta(n^2)$

# Strategyproofness

# Adding Strategyproofness

- None of the rules we have considered so far are strategyproof
- For divisible goods, structure of strategyproof mechanisms is fairly rich
  - Impossibilities from the divisible realm carry over
- What about indivisible goods?

	$g_1$	$g_2$	$g_3$
$a_1$	1	$x$	0
$a_2$	0	$y$	1

# Picking-Exchange Mechanisms

[Amanatidis et al. 2017]

- **Picking Mechanism:**

- Partition  $M = N_1 \cup N_2$
- Agent 1 receives a subset of offers  $O_1 \subseteq 2^{N_1}$ . Let  $S_1 = \arg \max_{S \in O_1} v_1(S)$ .
- Agent 2 receives a subset of offers  $O_2 \subseteq 2^{N_2}$ . Let  $S_2 = \arg \max_{S \in O_2} v_2(S)$ .
- $A_1 = S_1 \cup (N_2 \setminus S_2)$  and  $A_2 = S_2 \cup (N_1 \setminus S_1)$

- $N_1 = \{g_1, g_2, g_3, g_4\}, N_2 = \{g_5, g_6\}$

- $O_1 = \{\{g_1, g_2\}, \{g_2, g_3\}, \{g_4\}\}, O_2 = \{\{g_5\}, \{g_6\}\}$

	$g_1$	$g_2$	$g_3$	$g_4$	$g_5$	$g_6$
$a_1$	3	5	5	10	4	2
$a_2$	2	3	6	1	5	3



# Picking-Exchange Mechanisms

[Amanatidis et al. 2017]

- **Exchange Mechanism:**

- Partition  $M = E_1 \cup E_2$
  - Set of exchange deals  $D = \{(S_1, T_1), \dots, (S_k, T_k)\}$ , where each  $(S, T) \subseteq (E_1, E_2)$
  - Agent  $i$  receives allocation  $E_i$  by default, with exchanges performed if they are mutually beneficial
- $E_1 = \{g_1, g_2, g_3\}, E_2 = \{g_4, g_5\}$
  - $D = \{(\{g_2, g_3\}, \{g_4\})\}$

	$g_1$	$g_2$	$g_3$	$g_4$	$g_5$
$a_1$	6	2	3	7	1
$a_2$	1	6	1	4	7

# Picking-Exchange Mechanisms

[Amanatidis et al. 2017]

- **Picking-Exchange Mechanism:** Run a picking mechanism on  $N_1 \cup N_2 \subseteq M$  and an exchange mechanism on  $E_1 \cup E_2 \subseteq M$ , where  $N_1 \cup N_2 \cup E_1 \cup E_2 = M$  and  $N_1, N_2, E_1, E_2$  are pairwise disjoint.
  - Up to tiebreaking technicalities...

# Picking-Exchange Mechanisms

[Amanatidis et al. 2017]

- **Theorem [Amanatidis et al. 2017]:**
  - For  $n = 2$  an allocation mechanism that allocates all goods is strategyproof if and only if it is a picking-exchange mechanism
- **Corollary [Amanatidis et al. 2017]:**
  - For  $n = 2$ , any strategyproof mechanism that allocates all goods does not achieve any positive approximation of the minimum envy or best proportionality guarantee.
  - For  $n = 2$  and  $m \geq 5$ , no strategyproof mechanism can allocate all items and satisfy EF1.
  - For  $n = 2$ , no strategyproof mechanism guarantees better than  $\frac{1}{\lfloor m/2 \rfloor}$ -MMS.
    - This is a tight bound [Amanatidis et al. 2016]

# More General Strategyproof Mechanisms

Open Problem:

What is the structure of strategyproof mechanisms for  $n = 2$  when not all goods have to be allocated?

Open Problem:

What is the structure of strategyproof mechanisms for  $n > 2$ ?

# What's Not Covered

- Envy-freeness up to one less-preferred item (EFL) [Barman et al. 2018]
  - Stronger than EF1 and guaranteed to exist
  - Existence of EFL + PO allocations is an open question
- Various constraints and additional features
  - Agent social network structure
  - Connectivity constraints when items lie on a graph
- Asymptotic results
- ...

# Ordinal Preferences

# Ordinal Preferences

- Instead of valuation functions, take in preference orderings  $\succsim_i$  over items
  - E.g.  $g_2 \succsim_i g_3 \succsim_i g_1 \succsim_i g_4$
- Agents are assigned fractions of each item
  - $A = (A_{i,j})_{i \in [n], j \in [m]}$
  - Can be interpreted as lotteries over integral allocations

# Ordinal Preferences

- Partial preferences over bundles defined via **stochastic dominance** extension

$$A \succsim_i^{SD} B \quad \text{iff} \quad \forall k: \sum_{j \succsim_i k} A_{i,j} \geq \sum_{j \succsim_i k} B_{i,j}$$

- Many other extensions possible
  - Upper/downward lexicographic [Cho 2012]
  - Pairwise comparison [Aziz et al. 2014]
  - Bilinear dominance [Aziz et al. 2014]
- Can also elicit ordinal information over subsets directly [Bouveret et al. 2010]



# Two Mechanisms

- **Random Priority**

- Select a random ordering of the agents. Agents select their favorite  $m/n$  goods in order.

- **Probabilistic Serial [Bogomolnaia and Moulin 2001]**

- Agents “eat” at a constant (equal) rate. At any time, agents eat their most preferred good that is not completely consumed.

- $\succsim_1: g_1 \succsim_1 g_2 \succsim_1 g_3 \succsim_1 g_4$

**Random Priority**

	$g_1$	$g_2$	$g_3$	$g_4$
$a_1$	1	1/2	0	1/2
$a_2$	0	1/2	1	1/2

$$\succsim_2: g_2 \succsim_2 g_3 \succsim_2 g_1 \succsim_2 g_4$$

**Probabilistic Serial**

	$g_1$	$g_2$	$g_3$	$g_4$
$a_1$	1	0	1/2	1/2
$a_2$	0	1	1/2	1/2

# SD-efficiency

- SD-efficiency: There should not exist an alternative allocation that all agents weakly prefer and some agent strictly prefers.
- **Theorem [Bogomolnaia and Moulin 2001]:**
  - Probabilistic Serial satisfies SD-efficiency
- Random Priority is not SD-efficient
  - $\succsim_1: g_1 \succsim_1 g_2 \succsim_1 g_3 \succsim_1 g_4$                        $\succsim_2: g_2 \succsim_2 g_1 \succsim_2 g_4 \succsim_2 g_3$

	$g_1$	$g_2$	$g_3$	$g_4$
$a_1$	1/2	1/2	1/2	1/2
$a_2$	1/2	1/2	1/2	1/2

# SD-strategyproofness

- SD-strategyproofness: No agent should be able to improve their allocation by misreporting their preferences.

- **Theorem:**

- Random Priority is SD-strategyproof.

- Probabilistic Serial is not SD-strategyproof

- $\succsim_1: \cancel{g_1} \succsim_1 \cancel{g_2} \succsim_1 g_3 \succsim_1 g_4$

- $\succsim_2: g_2 \succsim_2 g_3 \succsim_2 g_1 \succsim_2 g_4$

$g_2 \succsim_1 g_1$

	$g_1$	$g_2$	$g_3$	$g_4$
$a_1$	1	0	1/2	1/2
$a_2$	0	1	1/2	1/2

	$g_1$	$g_2$	$g_3$	$g_4$
$a_1$	1	1/2	0	1/2
$a_2$	0	1/2	1	1/2

# SD-Efficiency + SD-Strategyproofness

- **Theorem [Bogomolnaia and Moulin 2001]:**
  - No mechanism satisfies SD-efficiency, SD-strategyproofness, and equal treatment of equals
- We can get SD-efficiency + SD-envy-freeness
  - **SD-envy-freeness:**  $\forall i, j: \sum_{j=1}^m A_{i,j} g_j \succsim_i^{SD} \sum_{j=1}^m B_{i,j} g_j$
  - Probabilistic Serial is SD-envyfree

# Public Decisions










# Public Decisions Model

- Set of agents  $N$
- Set of issues  $T$
- Each issue has associated set of alternatives  $C^t = \{c_1^t, \dots, c_{k_t}^t\}$
- Agents have utility functions  $u_i^t: A^t \rightarrow \mathbb{R}_+$

	Issue 1			Issue 2			...	Issue T		
	$c_1^1$	$c_2^1$	$c_3^1$	$c_1^2$	$c_2^2$	$c_3^2$		$c_1^T$	$c_2^T$	$c_3^T$
$a_1$	3	1	0	2	5	1		6	5	5
$a_2$	2	2	1	3	4	1		2	4	3
$a_3$	0	0	4	4	3	2		5	4	5

# Public Decisions Model

- Set of agents  $N$
- Set of issues  $T$
- Each issue has associated set of alternatives  $C^t = \{c_1^t, \dots, c_{k_t}^t\}$
- Agents have utility functions  $u_i^t: A^t \rightarrow \mathbb{R}_+$

	Monday			Tuesday			...	Sunday		
										
$a_1$	3	1	0	2	5	1		6	5	5
$a_2$	2	2	1	3	4	1		2	4	3
$a_3$	0	0	4	4	3	2		5	4	5

# Item Allocation as a Special Case

- Define the set of issues  $T = M = \{g_1, \dots, g_m\}$
- Alternatives  $C^t = N = \{a_1, \dots, a_n\}$
- $u_i^t(a_j) = \begin{cases} v_i(g_t) & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$

	$g_1$	$g_2$	$g_3$
$a_1$	5	2	3
$a_2$	0	3	1
$a_3$	2	3	4



	$g_1$			$g_2$			$g_3$		
	$a_1$	$a_2$	$a_3$	$a_1$	$a_2$	$a_3$	$a_1$	$a_2$	$a_3$
$a_1$	5	0	0	2	0	0	3	0	0
$a_2$	0	0	0	0	3	0	0	1	0
$a_3$	0	0	2	0	0	3	0	0	4



# Fairness for Public Decisions

- Envy-freeness (and relaxations) not sensible in the general case
  - Decisions are public, all agents receive the same outcome
- Proportionality is still sensible
  - Each agent should receive their “dictator utility” multiplied by  $1/n$
- **Proportionality up to one *issue* (Prop1)**
  - Each agent would receive their proportional share if they were allowed to change the outcome on a single issue
- **Theorem [Conitzer et al. 2017]:**
  - The MNW outcome satisfies Prop1 + PO in the public decisions setting
- Other fairness desiderata ((approximate) core, round robin share,...)

# Allocation of Public Goods

	Issue 1			Issue 2		
	$c_1^1$	$c_2^1$	$c_3^1$	$c_1^2$	$c_2^2$	$c_3^2$
$a_1$	3	1	0	2	5	1
$a_2$	2	2	1	3	4	1
$a_3$	0	0	4	4	3	2



	$g_1$	$g_2$	$g_3$	$g_4$	$g_5$	$g_6$
$a_1$	3	1	0	2	5	1
$a_2$	2	2	1	3	4	1
$a_3$	0	0	4	4	3	2

- Generalizes public decisions
- A set of **public goods**  $\{g_1, \dots, g_m\}$ 
  - Each good can give a positive utility to multiple agents simultaneously
- Constraints on which subsets of public goods are feasible

# Allocation of Public Goods

	Issue 1			Issue 2		
	$c_1^1$	$c_2^1$	$c_3^1$	$c_1^2$	$c_2^2$	$c_3^2$
$a_1$	3	1	0	2	5	1
$a_2$	2	2	1	3	4	1
$a_3$	0	0	4	4	3	2



	$g_1$	$g_2$	$g_3$	$g_4$	$g_5$	$g_6$
$a_1$	3	1	0	2	5	1
$a_2$	2	2	1	3	4	1
$a_3$	0	0	4	4	3	2

- Public decision example:
  - Exactly one of  $\{g_1, g_2, g_3\}$  and exactly one of  $\{g_4, g_5, g_6\}$  must be chosen
  - Partition matroid constraint

# Fairness Guarantees

- $(\delta, \alpha)$ -Core

- An allocation of public goods  $C$  is in  $(\delta, \alpha)$ -core if for every subset of agents  $S \subseteq N$ , there is no feasible allocation of public goods  $C'$  such that

$$\frac{|S|}{n} \cdot u_i(C') \geq (1 + \delta) \cdot u_i(C)$$

for all  $i \in S$ , and at least one inequality is strict.

- Valuations are normalized so that  $\max_j u_i(g_j) = 1$
- Core (i.e.  $(0,0)$ -core) generalizes proportionality
  - $(0,1)$ -core generalizes a guarantee very similar to Prop1

# Fair Allocation of Public Goods

- **Matroid constraints**

- Public goods are ground set elements
- Feasible allocations are basis of a matroid
- Generalizes public decisions (thus goods allocation) and multiwinner voting

- **Theorem [Fain et al. 2018]**

- For matroid constraints, a  $(0,2)$ -core allocation exists, and for constant  $\epsilon > 0$ , a  $(0,2 + \epsilon)$ -core allocation can be computed in polynomial time.
- **Algorithm:** Maximize **smooth Nash welfare**  $\prod_{i \in N} (1 + u_i(C))$
- For  $\epsilon > 0$ ,  $(0,1 - \epsilon)$ -core allocations may not exist.

Open Problem: Does there always exist a  $(0,1)$ -core allocation?

# Fair Allocation of Public Goods

- Theorem [Fain et al. 2018]

- For “matching constraints” and constant  $\delta \in (0,1]$ , a  $(\delta, 8 + 6/\delta)$ -core allocation can be computed in polynomial time.
- Algorithm: Maximize a slightly different smooth NW  $\prod_{i \in N} (1 + 4/\delta + u_i(C))$
- For  $\delta > 0$  and  $\alpha < 1$ , a  $(\delta, \alpha)$ -core allocation may not exist.
- Open problem: Does there always exist a  $(0,1)$ -core allocation?

- A slightly worse guarantee with logarithmically large  $\alpha$  in case of “packing constraints”

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