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1	ORDER SYMMETRY: A NEW FAIRNESS CRITERION FOR ASSIGNMENT	1
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12	We introduce a new fairness criterion, order symmetry, for assignment mecha-	12
13	nisms that match n objects to n agents with ordinal preferences over the objects.	13
14	An assignment mechanism is order symmetric with respect to some probability	14
15	measure over preference profiles if every agent is equally likely to receive their	15
	favorite object, every agent is equally likely to receive their second favorite, and	
16	so on. When associated with a sufficiently symmetric probability measure, order	16
17	symmetry is a relaxation of anonymity that, crucially, can be satisfied by discrete	17
18	assignment mechanisms. Furthermore, it can be achieved without sacrificing other	18
19	desirable axiomatic properties satisfied by existing mechanisms. In particular, we	19
20	show that it can be achieved in conjunction with strategyproofness and ex post	20
	efficiency via the top trading cycles mechanism (but not serial dictatorship). We	
21	additionally design a novel mechanism that is both order symmetric and ordinally	21
22	efficient. The practical utility of order symmetry is substantiated by simulations	22
23	on Impartial Culture and Mallows-distributed preferences for four common as-	23
24	signment mechanisms.	24
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1. INTRODUCTION

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Imagine you are hosting a birthday party for a group of children. You have bought a selection of cheap plastic objects that strangely appeal to this age group, and must give one to each child as a gift. Naturally, you want to allocate the toys via a process that is fair to each child, while also guaranteeing that, overall, children are satisfied with their allocation. However, you have no idea as to the preferences of the children. How should you allocate

This toy (pun intended) problem (inspired by the title of [Thomson, 2007]) is an instance of the *house allocation problem* (also known as the assignment problem or the one-sided matching problem), in which n indivisible objects must be matched to n agents, each with an ordinal preference over the objects and monetary transfers not allowed. It models a number of real-world resource allocation settings such as assigning rooms to college students and assigning schools to students in a school district, and has been studied extensively in economics [Ergin, 2000, Bogomolnaia and Moulin, 2001, Sönmez and Ünver, 2010], operations research [Saban and Sethuraman, 2015, Crès and Moulin, 2001, Bade, 2020], and computer science [Abraham et al., 2004, Saban and Sethuraman, 2013, Krysta et al., 2019, Gan et al., 2019]. The model was introduced by Hylland and Zeckhauser [1979], who also mention assigning legislators to committees.

In the discrete setting as described above, some amount of unfairness is inherent in the problem. Consider the case where all agents have the same preference over the objects; one agent necessarily receives the best object, while another must receive the worst. For many traditional notions of fairness, this is the end of the story. For example, this instance already witnesses a violation of anonymity (requiring that agents are treated symmetrically), equal-treatment-of-equals (requiring that any agents with the same preference receive the same allocation), and envy-freeness (no agent should prefer another agent's allocation to her own) [Foley, 1967].

Owing to this difficulty, much of the attention in both theory and practice has focused on randomized assignment mechanisms. Following the seminal work of Hylland and Zeckhauser [1979], typically the goal is to provide both ex ante and ex post guarantees, with the

former applying in expectation over the mechanism's randomness, and the latter applying after the randomness has been realized [Bogomolnaia and Moulin, 2001, Chen and Sönmez, 2002, Nesterov, 2017]. Existing fairness properties are necessarily violated ex post, so are usually only considered in the ex ante sense, with ex post guarantees reserved for efficiency.

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Perhaps the most common mechanism used in practice is *random serial dictatorship* (RSD), which randomly chooses an ordering of the agents and allows each agent to choose, in that order, her favorite remaining object. RSD is simple to execute and enjoys compelling theoretical justification: it is known to be strategyproof, ex ante anonymous, and ex post efficient (however, it is not ex ante efficient—indeed this combination of properties is ruled out by Zhou [1990]). It also produces the same lottery over assignments as the *Top Trading Cycles* (TTC) procedure, which endows each agent an object at random, and performs specified mutually beneficial trades of objects among agents [Abdulkadiroğlu and Sönmez, 1998]. TTC is known to produce the unique core outcome in the endowed setting [Shapley and Scarf, 1974, Roth and Postlewaite, 1977]. Bade [2020] has generalized the result of Abdulkadiroğlu and Sönmez [1998] to show that all strategyproof, Pareto optimal, and nonbossy mechanisms, when suitably symmetrized, coincide with RSD.

By the result of Abdulkadiroğlu and Sönmez [1998], RSD and TTC with random endowment give the same mapping from preference profiles to lotteries over assignments. After the agents report their preferences, the mechanism can randomly choose an ordering of the agents and simulate the iterative choosing (or, equivalently, randomly choose an initial endowment and run the Top Trading Cycles procedure). However, we argue that in many settings this framework is still not sufficient, since it is often desirable for the mechanism's randomness to be realized *before* the agents reveal their preferences. For example, in the NBA draft, the exact order in which teams pick players is determined by a combination of random draw and team strength, but the ordering is decided upon before the draft occurs. When college housing is allocated via RSD, students will typically receive their position in the ordering before any preferences are revealed. This method has several advantages: it has lower communication complexity (each agent only needs to select one object in turn,

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not rank all of them), it allows agents to more easily reason about their decisions [Li, 2017], and it de-emphasizes the randomization. For the latter point, note that a malicious actor who is able to influence the randomization process will wield less power if the randomization occurs before preferences are elicited.

For these reasons, we study randomized assignment mechanisms that select a discrete assignment mechanism at random *before* eliciting agent preferences. For RSD, this means randomly choosing an agent ordering, while for TTC a random endowment, or initial assignment, is chosen. When defined in this manner, the two mechanisms are no longer equivalent. It is clear that RSD remains highly unfair, in the sense that the agent first in line has a substantial advantage over the last. However, TTC admits no such obvious systematic bias toward any specific agent. While some initial endowments may be better than others, it is not a priori clear which agents will benefit, without observing the preferences.

To illustrate this point, let us return to the example of the children's party. Running RSD amounts to randomly choosing an ordering of the children and having each child choose a toy in turn. This is fair in expectation because each child has equal probability of occupying each position in line. However, the realization of the mechanism's randomness has a large influence over how happy each child will be with their assigned toy—the first child receives their top choice for sure, while the last is left to take whatever toy is left at the end. Under TTC, the mechanism's randomness manifests in a preliminary random assignment of a toy to each child. Without knowing the preferences of the children, it is impossible to say whether a given initial allocation is good for a particular child or not, or whether there is systematic bias toward one child. This hints at the possibility of an elusive, nontrivial ex post fairness notion for house allocation mechanisms (that is, a fairness notion that retains meaning when applied to deterministic mechanisms).

Our proposal is to consider average case fairness: for some probability measure on profiles, a mechanism is fair (with respect to that measure) if all agents do equally well *in expectation*. This nicely captures the intuition for why serial dictatorship and other mechanisms that rely heavily on a fixed choosing order or tiebreak order are unfair, since some agents do better than (or at least as well as) others systematically across all profiles. Since

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agents only provide ordinal preferences and not cardinal utilities, we measure how highly they rank the object they receive. Each agent should have equal probability of receiving their top object, their second object, and so on. When these probabilities are exactly equal 3 for all agents according to some measure P on profiles, we say that the mechanism is order symmetric with respect to P, reflecting the intuition that agents are not systematically ordered by the mechanism. If probabilities are not exactly equal, then we can examine the discrepancy to yield a measure of unfairness that we call the *order bias* of the mechanism. 7 To our knowledge, average case fairness has not previously been considered for the house 8 allocation problem. Average case analysis has been conducted in the one-sided matching setting [Filos-Ratsikas et al., 2014, Deng et al., 2017, Gao and Zhang, 2019], but focuses 10 on social welfare approximation rather than achieving fairness. The work of Manshadi 11 et al. [2021] is conceptually similar, in that they design a mechanism with guarantees on the minimum expected (ex ante) and the expected minimum (ex post) utility, where the 1.3 expectation is taken with respect to randomness in the agents' demands. However, the exact 14 problem is quite different to ours, with agents arriving dynamically and demanding some quantity of a divisible good. 16

1.1. Why do we care about order symmetry?

Practitioners who are fully content with ex ante fairness guarantees may not be interested in the concept of order symmetry, since it deals with an ex post fairness criterion. However, we believe that there are many situations where order symmetry ought to be seriously

considered. We now consider several issues, in no particular order of importance.

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First, a randomized mechanism that is fair ex ante but unfair ex post assigns undue emphasis to the randomization component. Unlucky agents can be condemned to receiving bad assignments in a large fraction of all possible preference profiles. Even worse, an agent who can manipulate the source of randomness can realize large utility gains. Even if the randomization mechanism is uncompromised, its integrity may be called into question if, say, a powerful actor is drawn in a favorable position. Striving for ex post fairness reduces the importance of the randomness and mitigates these concerns.

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Second, in many situations there may be resistance from users (e.g., in school choice 1 situations) toward randomized mechanisms being used, for reasons of trust, replicability, 2 algorithmic simplicity, transparency, and ex-post fairness. The same issue occurs in voting, where tiebreaking issues are important. When randomization is disallowed, ex post 4 guarantees are the only ones available. It is consistent with the ideal of fairness that, in 5 the absence of information about preferences, no agent should have a systematic advantage over another. All else being equal, a mechanism that satisfies order symmetry should be preferred to one that does not.

Third, it is important to understand and quantify the deviation from order symmetry in settings where we cannot, or do not want to, achieve full order symmetry. For example, the picking order for some sports team drafts is partly or completely determined by the reverse of the success of the teams in the previous year, so there is an attempt made to equalize teams by using inherent bias toward the first teams in the picking order.

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1.2. *Our contribution, and outline of the paper*

We make three main theoretical contributions.

- (i) In Section 3 we define the concept of *order symmetry*, a natural and novel fairness guarantee for assignment mechanisms. With respect to a sufficiently symmetric measure on profiles, order symmetry is a weakening of anonymity which, unlike anonymity, can be satisfied by discrete assignment mechanisms.
- (ii) In Section 4.2, we show that the well-known Top Trading Cycles mechanism is order symmetric with respect to any fully symmetric probability measure on profiles (that is, on that is symmetric with respect to both agents and objects). The result separates the Top Trading Cycles with random endowment mechanism from the random serial dictatorship mechanism, suggesting an advantage of the former over the latter, despite both inducing the same fractional assignment.
- (iii) In Section 4.3, we show, by defining the *Rank Maximal Matching* mechanism, that ex ante efficiency is compatible with order symmetry when equipped with a fully symmetric probability measure.

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Section 2 carefully covers basic background definitions and notations. Experienced read-1 ers may skip much of this at a first reading, but should note the use of group actions to describe anonymity. In Section 5 we define measures of order bias, or failure of order sym-3 metry, and in Section 6 explore order bias of four standard mechanisms with respect to 4 4 Impartial Culture and Mallows-distributed preferences. Our simulation results confirm that 5 TTC is a better choice than RSD from the perspective of order bias. In the Mallows setting, we find that the Naive Boston mechanism incurs strikingly low order bias, even relative to 7 TTC. Despite lacking theoretical justification, our results suggest that it may be a strong 8 choice for reducing unfairness stemming from the mechanism's randomness in settings where some objects are inherently more valuable than others. We conclude with possible 10 directions for future research in Section 7. 11

2. PRELIMINARIES

We now collect some basic terminology.

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DEFINITION 2.1: Let n be a positive integer and let $O = \{o_1, \dots, o_n\}$ be an ordered set of *objects* having cardinality n and $A = \{a_1, \dots, a_n\}$ an ordered set of *agents*. Each agent a_k has a strict linear order \succ_k over the objects, called its *preference order*. This yields a preference profile which we write $\pi = (\succ_1, \dots, \succ_n) = (\pi(1), \dots, \pi(n))$. We write the preference order of agent k as $(\pi(k)_1, \dots, \pi(k)_n)$. We let $\Pi(A, O)$ denote the set of all preference profiles.

DEFINITION 2.2—assignments: A *fractional assignment* α is a mapping taking each agent to a probability measure on O. Note that each assignment can be represented by a doubly stochastic matrix with rows indexed by agents and columns by objects. A fractional assignment is *discrete* if every entry of the matrix is either 0 or 1. We use "assignment" to mean a fractional assignment unless otherwise stated.

DEFINITION 2.3—assignment mechanisms: A fractional assignment mechanism A is a function associating a fractional assignment $\mathcal{A}(\pi)$ with each profile π . A fractional assignment mechanism is called discrete if it always outputs a discrete assignment. When

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we say "assignment mechanism" we will mean a fractional assignment mechanism unless 1 otherwise clear from context.

A randomized assignment mechanism \mathcal{A} is a lottery (probability measure) over discrete assignment mechanisms (we denote randomized mechanisms by bold letters for clarity). The set of discrete mechanisms occurring with positive probability is called the *support* of

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 \mathcal{A} . We write q_i for the probability of discrete algorithm \mathcal{A}_i .

Each randomized assignment mechanism \mathcal{A} induces a fractional assignment mechanism \mathcal{A} , via $\mathcal{A}(\pi) = \sum_{j} q_{j} \mathcal{A}_{j}(\pi)$. We say that \mathcal{A} implements \mathcal{A} , or that \mathcal{A} has implementation

 \mathcal{A} , and call the expression $\sum_{j} q_{j} \mathcal{A}_{j}$ a **decomposition** of \mathcal{A} .

Note that the induced fractional mechanism is simply the expectation with respect to the lottery of the randomized mechanism.

By the Birkhoff-von Neumann theorem [Birkhoff, 1946, von Neumann, 1953], every fractional assignment can be expressed as a convex combination of discrete assignments. In Appendix A we describe how any fractional assignment mechanism can be implemented by a randomized assignment mechanism. Note that a given assignment mechanism may have more than one decomposition.

EXAMPLE 2.4—serial dictatorship: The Serial Dictatorship (SD) mechanism works as follows: fix an exogenous order ρ on the agents, and let them choose according to ρ their highest ranked object from those remaining. The *Random Serial Dictatorship* (RSD) mechanism works by first selecting the order ρ uniformly at random, and then running SD with that order. Thus, **RSD** is a randomized assignment mechanism, with support indexed by the set of all n! orders of agents and the lottery being uniform. The induced fractional assignment mechanism RSD is given by

$$RSD(\pi) = \frac{1}{n!} \sum_{\rho} SD_{\rho}(\pi)$$
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where SD_{ρ} is SD with exogenous order ρ .

Let us also define the *Top Trading Cycles* (TTC) algorithm, originally presented by Shapley and Scarf [1974] and attributed to David Gale. Fix an initial assignment of

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objects to agents; this initial assignment is often known as an *endowment*. Begin by having each agent i point to the agent who is currently assigned to agent i's most preferred object. It is clear that there must be at least one cycle in this graph (potentially of length one, if 3 some agent i is already assigned their first choice). Choose one cycle and implement the 4 trade indicated by that cycle by reallocating each object to the agent pointing to it. Then, remove all agents and objects involved in the trade. If any agents remain, have agents once again point to their most-preferred remaining object and continue clearing cycles. The *Top* Trading Cycles with Random Endowment (TTC-RE) mechanism is the randomized allocation mechanism that first selects an initial assignment and then runs TTC with that initial assignment. 10 11

It is known that the induced fractional assignment TTC-RE is equal to RSD. That is, $TTC-RE(\pi) = RSD(\pi)$ for all profiles π . In fact, an even stronger equivalence holds. For every profile π , **RSD** and **TTC-RE** induce the same lottery over assignments in the sense that choosing an ordering at random and running SD with that ordering is exactly equivalent to choosing an initial endowment at random and running TTC with that endowment [Abdulkadiroğlu and Sönmez, 1998, Bade, 2020].

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We now introduce a number of properties that a fractional assignment mechanism may satisfy. For a property $\langle P \rangle$, we say that a randomized allocation mechanism \mathcal{A} satisfies $\langle P \rangle$ ex ante if the fractional allocation \mathcal{A} that it implements satisfies $\langle P \rangle$. We say that \mathcal{A} satisfies $\langle P \rangle$ ex post if every discrete assignment mechanism in the support of ${\cal A}$ satisfies $\langle P \rangle$.

It is intuitively clear that RSD treats agents symmetrically in a way that SD does not. This intuition is captured by notion of anonymity, which requires that the output of a mechanism should depend only on the preference orders and not on agent identities.

We define anonymity in terms of group actions. Let G denote the group Sym(A) of all permutations of the set of agents. Since we have ordered the set $A = \{a_1, \dots, a_n\}$ we may identify G as usual with the symmetric group S_n . The group G acts on $\Pi(A, O)$ via $(g \cdot \pi)(a) = \pi(g^{-1}(a))$, and on assignments by $(g \cdot \alpha)(a) = \alpha(g^{-1}(a))$.

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1	DEFINITION 2.5—anonymity: Assignment mechanism \mathcal{A} is <i>anonymous</i> if and only if	1
2	for each $g \in G$ and each $\pi \in \Pi(A, O)$, $\mathcal{A}(g \cdot \pi) = g \cdot \mathcal{A}(\pi)$.	2
3 4 5	Non-anonymous mechanisms privilege some agents over others, and anonymity is a widely used fairness criterion. However, anonymity can only be achieved ex ante.	3 4 5
6	PROPOSITION 2.6: Discrete assignment mechanisms are never anonymous. Equiva-	6
7	lently, randomized assignment mechanisms are never ex-post anonymous.	7
8 9 10	PROOF: Let $g \in G$ not be the identity, and let π be a profile where all agents have the same preference. Then $g \cdot \pi = \pi$ and so $\mathcal{A}(g \cdot \pi) = \mathcal{A}(\pi) \neq g \cdot \mathcal{A}(\pi)$. Q.E.D.	8 9 10
11	Given a discrete assignment mechanism, it is easy to construct an ex ante anonymous	11
12	randomized assignment mechanism that randomizes the agents' roles [Bade, 2020]. We	12
13	provide details of the construction in Appendix B.	13
14	We will be interested in the following notion of economic efficiency. An agent ordinally	14
15	prefers assignment α to assignment α' if, for every $k \in \{1, \dots, n\}$, she is allocated a greater	15
16	share of her k most preferred objects in α than α' . Ordinal efficiency requires that a mech-	16
17	anism never outputs an assignment $\boldsymbol{\alpha}$ when all agents weakly ordinally prefer a different	17
18	assignment α' and at least one agent strictly ordinally prefers α' to α . Ordinal efficiency is	18
19	often referred to as stochastic dominance efficiency (SD-efficiency) in the literature.	19
20	DEFINITION 2.7—efficiency: Let α, α' be assignments. We write $\alpha \succeq_i^{ord} \alpha'$, that is, agent i ordinally prefers assignment α to α' , if $\sum_{o_j \in \{o_k: o_k \succ o\}} \alpha_{i,j} \ge \sum_{o_j \in \{o_k: o_k \succ o\}} \alpha'_{i,j}$	20
22	for all $o \in O$. We write $\alpha \succeq_i^{ord} \alpha'$ if $\alpha \succeq_i^{ord} \alpha'$ and not $\alpha' \succeq_i^{ord} \alpha$.	22
23	We say that α is <i>ordinally efficient</i> if there does not exist an α' with $\alpha' \succeq_i^{ord} \alpha$ for all	23
24	agents a_i , and $\alpha' \succ_k^{ord} \alpha$ for some agent a_k . We say that an assignment mechanism \mathcal{A} is	24
25	ordinally efficient if $\mathcal{A}(\pi)$ is ordinally efficient for all $\pi \in \Pi(A, O)$.	25
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27	Note that if we restrict α, α' to be discrete assignments, there is only one natural way	27
28	to extend agents' preferences over objects to preferences over assignments. Thus, when	28
29	discussing efficiency in a discrete sense, we will use the standard terminology <i>Pareto effi-</i>	29
30	ciency, reserving ordinal efficiency for the fractional case.	30

It is known that ex ante ordinal efficiency implies ex post Pareto efficiency but the converse does not hold [Bogomolnaia and Moulin, 2001].

Finally, we would like assignment mechanisms for which an agent can never improve her assignment by misreporting her preference to the mechanism. For a profile π , let π_{-i} denote the reports of all agents other than a_i .

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DEFINITION 2.8—strategyproofness: Assignment mechanism \mathcal{A} is *strategyproof* if, for all profiles $\pi \in \Pi(A, O)$, there does not exist a report \succ_i' such that

$$\mathcal{A}(\succ_i', \pi_{-i}) \succ_i^{ord} \mathcal{A}(\pi).$$

Note that the ordinal preference relation is complete when restricted to discrete assignments, so that if \mathcal{A} is discrete then strategyproofness requires that $\mathcal{A}(\pi) \succeq_i^{ord} \mathcal{A}(\succ_i', \pi_{-i})$ for all \succ_i' .

THEOREM 2.9: If A is expost strategyproof then it is exante strategyproof.

PROOF: Fix a profile π and an agent a_i . For all j and all \succ_i' , it follows from ex post strategyproofness of \mathcal{A} that for each discrete assignment mechanism \mathcal{A}_j in the decomposition of \mathcal{A} , $\mathcal{A}_j(\pi) \succeq_i^{ord} \mathcal{A}_j(\succ_i', \pi_{-i})$. Therefore, $\sum_{j=1}^m q_j \mathcal{A}_j(\pi) \succeq_i^{ord} \mathcal{A}_j(\succ_i', \pi_{-i})$. Q.E.D.

With respect to the properties discussed so far, **RSD** and **TTC-RE** are indistinguishable. Both are ex ante anonymous, ex post strategyproof, and ex post Pareto efficient [Shapley and Scarf, 1974, Roth, 1982]. In the following section we introduce a property that distinguishes between the two.

3. ORDER SYMMETRY

While anonymity is a reasonable requirement for assignment mechanisms that output fractional assignments, it is too strong for discrete assignment mechanisms, as Proposition 2.6 shows. In this section we introduce a new fairness criterion that is implied by anonymity and allows us to discriminate between discrete assignment mechanisms. We have motivated this concept above, and it is now time to define it formally.

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3.1. Order symmetry definition

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2 DEFINITION 3.1: Let A be an assignment mechanism and π a profile. The *rank distri*-3 **bution** under mechanism \mathcal{A} at profile π is the mapping $D_{\pi,\mathcal{A}}$ on $\{1,\ldots,n\}\times\{1,\ldots,n\}$ 4 whose value at (r, j) is the probability that \mathcal{A} assigns agent r the object it ranks as jth best. 5 5 EXAMPLE 3.2: Consider the profile where agents a_1, a_2, a_3 have respective preferences 6 over objects o_1, o_2, o_3 as follows. 7 8 8 $a_1: o_1 \succ o_2 \succ o_3$ 9 9 $a_2: o_1 \succ o_3 \succ o_2$ 10 10 $a_3 : o_2 \succ o_1 \succ o_3$ 11 11 12 12 The matrix representing the assignment made by SD with picking order a_1, a_2, a_3 is 13 13 where rows represent agents a_1, a_2, a_3 and columns represent objects o_1, o_2, o_3 . 14 14 The matrix representing the assignment made by RSD is computed by averaging over all 15 15 $\begin{bmatrix} \frac{3}{6} & \frac{1}{6} & \frac{2}{6} \\ \frac{3}{6} & 0 & \frac{3}{6} \end{bmatrix}$. Finally consider TTC with initial endowment that assigns object picking orders: o_i to agent a_i for each $i \in \{1, 2, 3\}$. We verify that it gives the same assignment as SD. The 17 top choice of agents a_1 and a_2 is object o_1 , so both agents point to a_1 . Agent a_3 has object o_2 as her top choice, so she points to agent a_2 . The only cycle in this graph is the cycle of 19 length one in which a_1 points to herself, so we allocate o_1 to a_1 and remove them. Of the remaining objects, agent a_2 prefers object o_3 (so points to a_3) and agent a_3 prefers object o_2 (so points to a_2). We clear the cycle by allocating o_3 to a_2 and o_2 to a_3 and remove the 22 23 agents. Since no agents remain, the algorithm terminates with the same assignment as that 23 made by SD. 24 24 The above matrices are doubly stochastic, as expected: each column and each row has 25 sum 1. The matrix representing the rank distribution arising from using SD with picking 26 order a_1, a_2, a_3 and TTC with initial endowment o_i to agent a_i is $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$ since agents a_1 27

and a_3 receive their top object, and agent a_2 receives their second-top object. The rank distribution matrix for RSD is $\begin{bmatrix} \frac{3}{6} & \frac{1}{6} & \frac{2}{6} \\ \frac{3}{6} & \frac{3}{6} & 0 \\ \frac{5}{6} & 0 & \frac{1}{6} \end{bmatrix}$.

In Example 3.2 the rows of the rank distribution matrices are very far from being equal. The case where they are equal gives the main new concept of this paper.

DEFINITION 3.3: Let P be a probability measure on the set of all profiles for a given n. The mechanism \mathcal{A} is *order-symmetric with respect to* P if for all j, the quantity

$$E_P[D_{\pi,\mathcal{A}}(r,j)] := \sum_{\pi \in \Pi(A,O)} P(\pi)D_{\pi,\mathcal{A}}(r,j)$$

is independent of r.

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Thus a mechanism is order-symmetric if and only if in the expectation of the rank distribution matrix, all rows are equal. The following example illustrates the idea. *Impartial Culture* (IC) is the probability measure obtained when each agent independently samples from the uniform measure on all permutations of the objects. This is just the uniform measure on profiles.

EXAMPLE 3.4—expected rank distribution under IC: Consider the case of agents a_1, a_2, a_3 and objects o_1, o_2, o_3 as in Example 3.2, and assignment mechanism SD with picking order a_1, a_2, a_3 . By symmetry we may assume that the preference order of a_1 is $o_1 \succ o_2 \succ o_3$. This leaves 36 possibilities for the other two preference orders. Then a_1 always chooses o_1, a_2 takes whichever of o_2 and o_3 is preferred and a_3 is left with the last object, which is equally likely to take any rank in her preference order. Unless the first choice of a_2 is o_1 , he gets his first object. The expected rank distribution matrix under IC is therefore $\begin{bmatrix} 1 & 0 & 0 \\ \frac{2}{3} & \frac{1}{3} & 0 \\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{bmatrix}$.

For TTC with initial endowment that assigns o_i to a_i for $i \in \{1,2,3\}$ and for RSD, the expected rank distribution matrix under IC follows from computing the outcome on each profile and is $\begin{bmatrix} \frac{2}{3} & \frac{2}{9} & \frac{1}{9} \\ \frac{2}{3} & \frac{2}{9} & \frac{1}{9} \\ \frac{2}{3} & \frac{2}{9} & \frac{1}{9} \end{bmatrix}.$

From Example 3.4, we see that RSD and TTC are order symmetric with respect to IC for n=3, but not with respect to the point mass concentrated at the profile from Example 3.2. Also, SD with picking order a_1, a_2, a_3 is not order symmetric with respect to either

1	measure. This is not surprising; the first chooser does strictly better than the second when	1
2	both have the same first preference, and just as well otherwise. We will soon see that this	2
3	example generalizes, with TTC-RE offering stronger ex post order symmetry guarantees	3
4	than RSD .	4
5	Before proceeding, we observe that order symmetry is a property of a mechanism that	5
6	cannot be verified by examining individual allocations in isolation. In this respect it is	6
7	similar to anonymity (we formalize a connection in the next section), but of a different	7
8	flavor to guarantees such as equal treatment of equals or envy-freeness, both of which	8
9	define behavior that a mechanism must satisfy on each and every input independently.	9
10		10
11	3.2. Relation to anonymity	11
12	When order symmetry is combined with sufficient symmetry in the probability measure,	12
13		13
14	we obtain a property that is a relaxation of anonymity. Recall that $G = \text{Sym}(A)$ denotes	14
15	the group of all agent permutations.	15
16	DEFINITION 3.5: An <i>anonymous probability measure</i> on Π is one for which $P(g \cdot \pi) =$	16
17	$P(\pi)$ for all $g \in G$ and all $\pi \in \Pi$.	17
18		18
19	Note that a probability measure is anonymous if and only if it takes a constant value	19
20	on each orbit of G . Further, every measure that is uniform on a subset of profiles that is a	20
21	union of G -orbits is anonymous. Examples of anonymous measures include Impartial Cul-	21
22	ture (where each profile has the same weight), Impartial Anonymous Culture (IAC, where	22
23	any two profiles within the same orbit have the same weight), and Impartial Anonymous	23
24	Neutral Culture (IANC) [Eğecioğlu and Giritligil, 2013]. Other examples include any mea-	24
25	sure concentrated on a single profile in which all agents have the same preference, the	25
26	uniform measure on single-peaked profiles, and indeed the uniform measure on any set of	26
27	profiles defined without reference to an order of agents.	27
28		28
29	THEOREM 3.6: If A is an anonymous assignment mechanism and P is an anonymous	29
30	probability measure on $\Pi(A,O)$ then A satisfies order symmetry with respect to P .	30

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The proof is presented in Appendix C. It relies on the fact that each permutation q of 1 the agents permutes the rank distribution matrix in the same way (since the mechanism is anonymous), and that each profile in the orbit of g is equally likely (by anonymity of the probability measure).

In the following section, we use order symmetry as a criterion to discriminate between assignment mechanisms on ex post fairness grounds.

4. SATISFYING ORDER SYMMETRY

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We focus our attention in this work on order symmetry with respect to anonymous probability measures. 1 By Theorem 3.6, in the presence of such a measure, order symmetry is a fairness property that is implied by anonymity. It is not a priori obvious whether order symmetry can be satisfied by discrete mechanisms (we know that anonymity cannot). As the following example shows, no discrete mechanism can satisfy order symmetry with respect to all anonymous measures.

EXAMPLE 4.1—order symmetry depends on the measure: Consider a profile where all agents have the same preference order, and let P put all its weight on this profile. Note that P is anonymous. Then every discrete assignment mechanism must allocate some agent her most-preferred object, while other agents will not get their first choice, so that the mechanism cannot be order symmetric with respect to P.

On the other hand, some probability measures make it easy to be order symmetric. Consider a measure with all its weight on the set of profiles for which all agents have a different first preference. Every Pareto efficient discrete assignment mechanism will assign each agent to their top choice, and thus order symmetry is satisfied.

4.1. Fully symmetric probability measures

In the light of Example 4.1, we will now further restrict attention to a natural subclass of anonymous measures: those which are additionally invariant to permutations of the objects.

¹Extending our theoretical results beyond anonymous measures is an interesting direction that we leave for future work. Easy examples show that some measures make

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DEFINITION 4.2: Let $H = \text{Sym}(\mathcal{O})$ be the group of all permutations of the set of ob-

jects. Note that H acts naturally on $\Pi(A, \mathcal{O})$ by $(h \star \pi)(a) = (h(\pi(a)_1), \cdots, h(\pi(a)_n)$ and

also on assignments by $(h \star \alpha)(a) = h(\alpha(a))$. A *neutral probability measure* on $\Pi(A, O)$

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is one for which $P(h \star \pi) = P(\pi)$ for all $h \in H$ and all $\pi \in \Pi$.

EXAMPLE 4.3: Consider the set of all profiles for which the last n-1 agents all have the same preference order, and agent 1 always has a different one. If $n \ge 3$ then the uniform measure on this set is neutral but not anonymous.

The actions of G and H commute with each other (reordering agents, then objects, gives the same result as reordering objects, then agents), so that

$$g \cdot (h \star \pi) = h \star (g \cdot \pi)$$
 for all $g \in G, h \in H$.

We have given a definition that allows for more general sets of agents and objects. In the specific case of the house allocation problem where $|A| = |\mathcal{O}| = n$ and we choose a fixed order on A and \mathcal{O} as we have done above, we may identify both A and \mathcal{O} with $\{1,\ldots,n\}$ and G and H with the symmetric group S_n .

EXAMPLE 4.4: Consider again the profile π used in Example 3.2. Let q be the 3-cycle $a_1 \rightarrow a_2 \rightarrow a_3 \rightarrow a_1$ and let h be the transposition $o_1 \rightarrow o_2 \rightarrow o_1$. The table shows the various profiles derived from π .

22	π	$g\cdot\pi$	$h\star\pi$	$g\cdot (h\star \pi)$
23	$a_1: o_1 \succ o_2 \succ o_3$	$a_1: o_2 \succ o_1 \succ o_3$	$a_1: o_2 \succ o_1 \succ o_3$	$a_1: o_1 \succ o_2 \succ o_3$
24	$a_2: o_1 \succ o_3 \succ o_2$	$a_2: o_1 \succ o_2 \succ o_3$	$a_2: o_2 \succ o_3 \succ o_1$	$a_2: o_2 \succ o_1 \succ o_3$
26	$a_3: o_2 \succ o_1 \succ o_3$	$a_3: o_1 \succ o_3 \succ o_2$	$a_3: o_1 \succ o_2 \succ o_3$	$a_3: o_2 \succ o_3 \succ o_1$

We can now define the class of fully symmetric probability measures.

DEFINITION 4.5: A probability measure is *fully symmetric* if and only if $P(g \cdot (h \star \pi)) =$ $P(\pi)$ for all $g \in G, h \in H$.

1	Proposition 4.6: For a probability measure P on Π , the following properties are	1
2	equivalent.	2
3	(i) P is fully symmetric.	3
4	(ii) P is anonymous and neutral.	4
5	(iii) P takes a constant value on each orbit of $G \times H$	5
6 7 8 9 10 11 12 13 14 15	PROOF: Assuming (i), take h to be the identity to get anonymity and g to be the identity to get neutrality, yielding (ii). Assuming (ii), let π, π' lie in the same orbit so that $\pi' = h \star (g \cdot \pi)$ for some $g \in G, h \in H$. Then $P(\pi') = P(g \cdot \pi)$ by neutrality and this value also equals $P(\pi)$ by anonymity, yielding (iii). Assuming (iii), let $\pi \in \Pi, g \in G, h \in H$. Then $g \cdot (h \star \pi)$ lies in the orbit of π under $G \times H$ and so $P(g \cdot (h \star \pi)) = P(\pi)$. This yields (i). Q.E.D. Examples of fully symmetric measures include IC, IAC, IANC and indeed the uniform measure on any set of profiles defined without reference to an order of agents or objects. A measure concentrated on a single profile in which all agents have the same preference is anonymous, but not fully symmetric since it is not invariant to permuting the objects.	6 7 8 9 10 11 12 13 14 15
17		17
18	4.2. Top Trading Cycles is order symmetric	18
19202122232425	We now show our first main result, that TTC is order symmetric with respect to any fully symmetric probability measure. The result generalizes Example 3.4, which showed that TTC is order symmetric with respect to IC for $n=3$. Intuitively, the result is true because, under the assumption that each agent and object is symmetric, no agent is systematically advantaged by their initial endowment. The proof, along with an illustrative example, appears in Appendix D.	19 20 21 22 23 24 25
26	THEOREM 4.7—TTC is order symmetric: TTC with any fixed endowment is order sym-	26
27	metric with respect to every fully symmetric probability measure.	27
28		28
29	Because we know that TTC with fixed endowment is strategyproof and Pareto efficient,	29
30	we obtain the following corollary.	30

1	COROLLARY 4.8: TTC-RE is ex ante anonymous, ex post strategyproof, ex post Pareto	1
2	efficient, and ex post order symmetric with respect to every fully symmetric probability	2
3	measure.	3
4		4
5	Since we know that TTC-RE is an implementation of RSD, we can state Corollary 4.8	5
6	in the following way.	6
7		7
8	COROLLARY 4.9: RSD can be implemented as a lottery over discrete assignment mech-	8
9	anisms each of which is strategyproof, Pareto efficient and order symmetric with respect to	9
10	every fully symmetric probability measure.	10
11	Note that the standard implementation of RSD (that is, RSD) violates order symmetry	11
12	not only with respect to Impartial Culture, as we have seen in Example 3.4, but also with	12
13	respect to all but a very special set of measures.	13
14	respect to an out a very special set of measures.	14
15	THEOREM 4.10: RSD violates ex post order symmetry with respect to any probability	15
16	measure that assigns positive probability to a profile in which two agents have the same	16
17	most-preferred object.	17
18		18
19	PROOF: Consider SD with a fixed picking order. The first agent in the picking order	19
20	always receives their most-preferred object. Thus, the only way for all rows of the expected	20
21	rank distribution matrix to be equal is if all agents always receive their most-preferred	21
22	object. However, on any profile where two agents have the same most-preferred object, one	22
23	of them will receive a lower-ranked object, violating order symmetry. Q.E.D.	23
24		24
25	In summary, RSD and TTC-RE induce the same fractional assignment mechanism and	25
26	therefore necessarily share any ex ante properties. They are also ex post Pareto efficient	26
27	and ex post strategyproof. However there is a substantial difference: only TTC-RE is ex	27
28	post order symmetric. The usual implementation of RSD does not give the correct type	28
29	of lottery over discrete assignment mechanisms, and implementing it using TTC-RE fixes	29
30	this problem.	30

4.3. Order symmetry and efficiency

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We have seen that **TTC-RE** satisfies many desirable properties. However, it is not ex ante ordinally efficient [Bogomolnaia and Moulin, 2001]. This begs a natural question: does there exist a randomized assignment mechanism that is ex ante ordinally efficient, ex ante anonymous, and ex post order symmetric?

To answer this question, we define a discrete assignment mechanism that we call the *Rank-Maximal Matching* (RMM) mechanism. A rank-maximal matching is an assignment that maximizes the number of agents who receive their most-preferred object, and subject to that maximize the number who receive their second most-preferred object, and so on [Irving, 2003, Irving et al., 2006]. RMM with a fixed tiebreak order ρ first finds the complete set of rank-maximal matchings, and then breaks ties by having each agent in turn (according to ρ) find their most preferred object of those she gets in one of the remaining assignments, and eliminates all assignments that give her anything worse. Clearly this terminates with a single assignment, since every agent gets exactly one object. This mechanism is exactly the welfare maximization method proposed by Featherstone [2020], since a rank-maximal matching is one that maximizes social welfare for agents with lexicographic utilities.

For any fixed tiebreak order ρ , RMM is clearly not order symmetric, systematically favoring agents higher in the tiebreak order. However, we propose breaking ties according to $\pi(i)$, the preference list of agent i (where each object o_j is associated with agent a_j). This tiebreaking method harnesses the randomness from the input to avoid biasing the mechanism in favor of any particular agent, provided that the input distribution is sufficiently symmetric.

EXAMPLE 4.11: Consider the profile where agents a_1, a_2, a_3 have respective preferences over objects o_1, o_2, o_3 as follows.

$$a_1 : o_3 \succ o_1 \succ o_2$$

$$a_2 : o_3 \succ o_1 \succ o_2$$

$$a_3 : o_2 \succ o_3 \succ o_1$$

$$a_3 : o_4 \succ o_3 \succ o_1$$

$$a_4 : o_5 \leftarrow o_5 \leftarrow o_5$$

1	The two rank maximal matchings are $a_1:o_3,a_2:o_1,a_3:o_2$ and $a_1:o_1,a_2:o_3,a_3:o_2$, since	1
2	both give two agents their most-preferred object and one agent their second most-preferred.	2
3	Suppose the tiebreak order is given by $\pi(1)=3,1,2.$ Since agent 3 is indifferent be-	3
4	tween the two assignments, neither is eliminated before agent 1's turn. Agent 1 chooses the	4
5	assignment she prefers of the two, yielding assignment matrix $\begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$.	5
6	LEMMA 4.12: Fix an agent i. Then RMM with tiebreaking order $\pi(i)$ is order symmetric	6
7	with respect to any fully symmetric probability measure.	7
8		8
9	The proof of Lemma 4.12 appears in Appendix E.	9
10	Equipped with an order symmetric discrete assignment mechanism, defining a random-	10
11	ized mechanism that is ex ante anonymous while preserving ex post order symmetry is	11
12	straightforward, as per the construction in Appendix B. In this case, it is equivalent to	12
13	simply choosing the agent whose preference defines the tiebreak order uniformly at ran-	13
14	dom. We term the resulting randomized assignment mechanism <i>Rank-Maximal Matching</i>	14
15	with Random Agent tiebreaking (RMM-RA). As well as being ex post order symmetric,	15
16	RMM-RA is ex ante ordinally efficient.	16
17	THEOREM 4.13: RMM-RA is ex ante ordinally efficient, ex ante anonymous, and ex	17
18	post order symmetric with respect to every fully symmetric measure.	18
19		19
20	Since we have shown order symmetry in Lemma 4.12, it only remains to show efficiency,	20
21	which follows easily from the definition of a rank maximal matching. The proof appears in	21
22	Appendix F.	22
23	From the proof of Theorem 4.13, we see that RMM-RA actually satisfies the stronger	23
24	efficiency property of ex ante rank efficiency [Featherstone, 2020].	24
25	Despite its strong efficiency guarantee, RMM-RA does have significant drawbacks. It	25
26	necessarily violates ex ante strategyproofness, since ex ante anonymity and ex ante ordi-	26
27	nal efficiency are known to be incompatible with ex ante strategyproofness [Zhou, 1990,	27
28	Bogomolnaia and Moulin, 2001]. Additionally, computing all rank-maximal matchings is	28
29	a #P-hard computational problem [Ghosal et al., 2014], rendering the mechanism impracti-	29
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order to a particular agent's preference is one that applies more generally. For example, the analogous construction with SD gives an order-symmetric algorithm (at the cost of strategyproofness). It might be possible that rather than computing rank-maximal matchings 3 and then breaking ties among them, some other set of assignments could be computed (in 4 polynomial time) that still guarantee ordinal efficiency.

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Let us also mention the *Probabilistic Serial* (PS) mechanism of Bogomolnaia and Moulin [2001]. PS constructs an assignment via a "simultaneous eating" procedure: agents all eat objects at unit speed, switching down their preference order to the next best remaining once an object is completely eaten. As a fractional assignment mechanism, PS is ordinally efficient, anonymous, and polynomial-time computable. However, its definition 10 does not lend itself to a natural implementation in the same way as, say, RSD does. Of 11 course, the method from Appendix A can be applied to exhibit PS as a lottery over discrete assignment mechanisms, but we have no guarantee that such an implementation would be ex post order symmetric. If such an implementation of PS does exist (and can be computed efficiently), then it would be a natural candidate for practical use, especially given its status as an existing mechanism with a somewhat more natural description than RMM-RA. Resolving this question is a compelling problem that we leave open.

To conclude this section, we briefly contextualize our theoretical results. It is known that ex ante ordinal efficiency, ex ante strategyproofness, and ex ante anonymity are incompatible [Bogomolnaia and Moulin, 2001]. The literature suggests two common approaches in light of this difficulty. The first, typically achieved by implementing random serial dictatorship, is to sacrifice ex ante ordinal efficiency, resorting instead to ex post efficiency. The second is to sacrifice strategyproofness by using the probabilistic serial mechanism. In both cases, we have shown that ex post order symmetry (with respect to a fully symmetric probability measure) can be additionally achieved at no cost, via the use of Top Trading Cycles and Rank Maximal Matching, respectively.

5. MEASURES OF ORDER BIAS

By Corollary 4.8 and Theorem 4.13, there are randomized assignment mechanisms with strong axiomatic properties including order symmetry. However it is still important for us

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to measure the deviation from order symmetry, for several reasons. First, some preference 1 distributions may not admit any order symmetric mechanism, and we may wish to get as close as we can. Second, a small failure of order symmetry may be tolerable in practice, 3 if for example it leads to higher overall welfare. Third, as in the example of sports drafts,

sometimes we do not want order symmetry, but rather a bias toward some agent(s). We therefore investigate how to measure the failure of order symmetry to hold.

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In the absence of knowledge of preferences beyond ordinal information, we often force a common utility function on agents via a scoring rule.

DEFINITION 5.1: A positional scoring rule is given by a sequence s of real numbers $s_1 \ge s_2 \ge \cdots \ge s_n$ with $s_1 > s_n$.

Commonly used scoring rules include *plurality* defined by $(1,0,0,\ldots,0)$, *antiplurality* defined by $(1,1,1,\ldots,0)$ and **Borda** defined by $s_i=(n-i)/(n-1)$. Note that we have normalized these scoring vectors so that the first element is 1 and the last 0, so strictly speaking these are normalized plurality, normalized antiplurality and normalized Borda rules. Borda is often used in the literature, sometimes under the name "linear utilities." By equating the entries in a scoring rule with utilities, we can define the expected utility of an agent for some measure on profiles.

DEFINITION 5.2: The *expected utility* of agent r with respect to a scoring rule s, mechanism A and measure P on profiles is

$$U(r) := U_{\mathcal{A},s,P}(r) = \sum_{j} s_j E_P[D_{\pi,\mathcal{A}}(r,j)].$$

In other words, U is a vector formed by multiplying the expected rank distribution matrix by the fixed utility vector. We now require a measure of bias. An obvious choice is to consider the maximum difference between two agents' expected utilities, normalized by the difference in utility for receiving the most- and least-preferred objects:

$$\beta_n(\mathcal{A}; s; P) = \frac{\max_{1 \le p, q \le n} |U(p) - U(q)|}{s_1 - s_n}.$$

1	With the given normalization, $0 \le \beta_n(A; s; P) \le 1$, with order symmetry implying	1
2	$\beta_n(\mathcal{A}; s; P) = 0$. For scoring rules with that are strictly decreasing $(s_1 > \ldots > s_n)$,	2
3	$\beta_n(\mathcal{A}; s; P) = 0$ if and only if \mathcal{A} is order-symmetric for n with respect to P , while the	3
4	equality $\beta_n(A; s; P) = 1$ is attained only if there are fixed agents A, B such that with prob-	4
5	ability 1, A attains its first choice and B attains its worst choice.	5
6	We conclude this section by briefly discussing the relationship between welfare and order	6
7	bias. We recall some basic definitions.	7
8		8
9	DEFINITION 5.3: Let n be a positive integer, \mathcal{A} an assignment mechanism, s a scoring	9
10	rule and P a distribution over profiles with n agents. The <i>utilitarian welfare</i> $W_n(\mathcal{A}; s; P)$	10
11	for $\mathcal A$ with respect to s and P is the expectation under P of the arithmetic mean score	11
12	received by an agent, while the <i>egalitarian welfare</i> $E_n(A; s; P)$ is the expectation of the	12
13	minimum score. The <i>Nash welfare</i> $N_n(A; s; P)$ is the expectation of the geometric mean	13
14	of agent scores.	14
15		15
16	From the definitions it follows immediately that for a given $(A; s; P)$, $E_n \leq N_n \leq W_n$	16
17	for all n .	17
18		18
19	PROPOSITION 5.4: For each n, s, P, A , we have $\beta_n(A; s; P) + E_n(A; s; P) \leq 1$.	19
20		20
21	PROOF: Let ${\cal M}$ and ${\cal m}$ denote the maximum and minimum over agents of the normalized	21
22	expected utility of an agent. Then $m \geq E_n(\mathcal{A}; s; P)$ while $\beta_n(\mathcal{A}; s; P) = M - m$, so the	22
23	result follows since $M \le 1$. Q.E.D.	23
24		24
25	Thus low order bias is a necessary condition for high egalitarian welfare. It is certainly	25
26	not sufficient, since for example we could run TTC after reversing the preference order of	26
27	each agent.	27
28	If order symmetry holds, then the expected welfare of each agent is the same, and hence	28
29	equal to the utilitarian welfare. However the relationship between order bias and utilitarian	29
30	(or Nash) welfare is not clear in general.	30

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6. ORDER BIAS OF COMMON ALGORITHMS

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We study via analysis and simulation the order bias of four well known discrete assignment algorithms: TTC with fixed endowment, SD with fixed picking order, Naive Boston (NB) with fixed tiebreak order and Adaptive Boston (AB) with fixed tiebreak order. We

9 consider several different preference distributions.

The *Boston mechanism* for school choice proceeds in rounds. At round i, all unmatched agents are asked to submit their ith choice, and they are allocated that object unless there is a conflict, in which case a fixed order ρ is used as a tiebreak to allocate it to one of them. Alternatively, agents submit their first preference and if it has already been taken, they go back to the end of the queue of agents (initially built from ρ) and wait to submit their 2nd choice, etc. In the present situation we consider the restriction to the housing allocation model, so that each "school" is a single object.

Mennle and Seuken [2014] discuss what they call the *Adaptive Boston* mechanism (they call the original variant *Naive* Boston). In this case, in round i, all remaining agents submit a bid for their highest remaining object, rather than for the highest object for which they have not yet bid, as in the naive version. It is well known that the both variants are Pareto efficient but violate strategyproofness [Mennle and Seuken, 2014, Abdulkadiroğlu and Sönmez, 2003], although the adaptive version does satisfy a weaker incentive property known as partial strategyproofness [Mennle and Seuken, 2014, 2021].

For the remainder of this section, we will use the abbreviations SD, TTC, NB, and AB not to represent fractional assignment mechanisms, but to refer to the discrete form of the mechanisms when endowed with some fixed endowment/tiebreak order.

It is clear from their definitions that, as for SD, the Boston mechanisms are order symmetric only for very particular probability measures. Most of the time, an agent at position i in the tiebreak order will obtain strictly higher expected utility than an agent at position j > i in the order. This is very clearly shown in the numerical results that follow.

1	$r\mid j$	1	2	3	4	5	6	7	8
2	1	1	0	0	0	0	0	0	0
3	2	0.875	0.125	0	0	0	0	0	0
4	3	0.75	0.214	0.0357	0	0	0	0	0
5	4	0.625	0.268	0.0893	0.0179	0	0	0	0
6	5	0.500	0.286	0.143	0.0571	0.0143	0	0	0
	6	0.375	0.268	0.179	0.107	0.0536	0.0179	0	0
7	7	0.250	0.214	0.179	0.143	0.107	0.0714	0.0357	0
8	8	0.125	0.125	0.125	0.125	0.125	0.125	0.125	0.125
9					TABLE	ΕI			

Frequencies of rank achieved (j) by agent position (r) under SD assuming IC, for n=8

6.1. Results under Impartial Culture

6.1.1. Theoretical Results

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We already know that TTC with fixed endowment has zero order bias with respect to IC. We now consider SD with respect to a fixed picking order.

THEOREM 6.1: Let A be SD with picking order equal to $\{a_1, \ldots, a_n\}$, and let P be IC.

Then

$$E_P D_{\pi,\mathcal{A}}(r,j) = \begin{cases} \frac{\binom{n-j}{r-j}}{\binom{n}{r-1}} & \text{if } j \leq r \\ 0 & \text{if } j > r. \end{cases}$$

PROOF: By the time agent r gets an object, a random subset S of r-1 of the n objects is already taken. The probability that his jth choice is the best object left is the probability that S includes his first j-1 choices, but not the jth choice. The number of subsets satisfying this constraint is $\binom{n-j}{r-j}$ because we have to choose the remaining r-j objects from n-j possibilities. Q.E.D.

In particular if r = n, then agent r is equally likely to get each possible object. Table I shows the probabilities for n = 8, rounded to 3 significant figures.

PROPOSITION 6.2: We have
$$\beta_n(SD; s; IC) = \frac{s_1 - \overline{s}}{s_1 - s_n}$$
, where \overline{s} is the mean of s .

PROOF: Agent 1 always attains its first choice under SD. The last agent receives each object with equal probability.

Q.E.D. 2

For example, for the Borda rule $\beta_n(SD;s;IC)=1/2$ while for plurality $\beta_n(SD;s;IC)=1-1/n$, and for antiplurality $\beta_n(SD;s;IC)=1/n$.

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Detailed analysis of the order bias of the Boston mechanisms is more difficult. The first agent always gets her first choice, so the difficulty lies in deriving the distribution of the rank of the object eventually chosen by the last agent. It is not a priori clear what this distribution looks like. Under IC, the last agent receives her top choice only if it has not been chosen by another agent, and this occurs with probability $(1 - 1/n)^{n-1}$. Thus, for plurality, we have $\beta_n(NB; s; IC) = \beta_n(AB; s; IC) = 1 - (1 - 1/n)^{n-1}$, which is a strictly lower order bias than SD for n > 2. We leave further analysis for future work.

6.1.2. Empirical Results

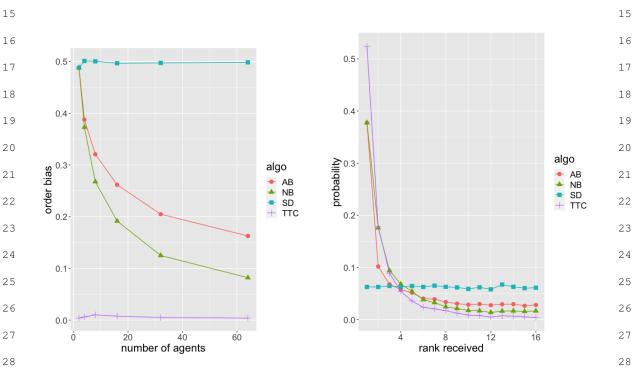


FIGURE 1.—(left) Borda order bias, Impartial Culture, mean of 10000 simulations, (right) distribution of rank received for last agent, n = 16, Impartial Culture, mean of 10000 simulations.

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Figure 1 explores the order bias of all four algorithms. On the left, we plot the sample mean under IC (from 10000 independent samples for each $n \in \{2, 4, 8, 16, 32, 64\}$) of order 2 bias with respect to the Borda utility. In line with the theory, the value for TTC is near zero and for SD near 1/2. The Boston mechanisms exhibit intermediate performance, improving as n increases, with the naive version outperforming its adaptive counterpart with respect 5 to order bias.

The Borda order bias reflects the difference in the average rank of the object received by the agents with highest and lowest average Borda utility, but not the distribution of ranks. On the right side of Figure 1, we plot the distribution of ranks for the agent with lowest average Borda utility (the agent with lowest priority for SD and the Boston algorithms, 10 an arbitrary agent for TTC since all agents are symmetric under IC). Recall that for all algorithms other than TTC, the highest agent in the priority order always gets its top choice.

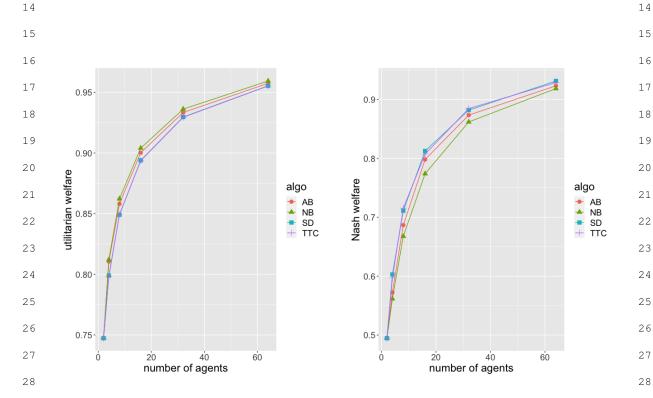


FIGURE 2.—(left) Borda utilitarian welfare, Impartial Culture, mean of 10000 simulations, (right) Borda Nash welfare, Impartial Culture, mean of 10000 simulations.

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Of course, there are design criteria other than order bias. In Figure 2 we present the 1 utilitarian and Nash welfare, again averaged over 10000 independent samples. As expected due to the results of Abdulkadiroğlu and Sönmez [1998] and Bade [2020], SD and TTC are almost identical in these measures. The Boston mechanisms exhibit a small advantage in terms of utilitarian welfare but a disadvantage in terms of Nash welfare, suggesting that the extra additive welfare they achieve relative to SD and TTC is distributed unevenly within each instance.

6.2. Mallows

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Impartial culture is a helpful and tractable baseline, but often does not reflect realistic preference structures. In particular, in real-world assignment problems, some objects are typically more highly sought after than others but this is not captured by Impartial Culture. To explore a more realistic preference model, we consider the Mallows model [Mallows, 1957]. The Mallows model is parametrized by a reference order σ and a dispersion parameter $\phi \in (0,1]$. Let \succ be a strict linear order. Then the Mallows model specifies that the probability an agent has preference order \succ is $P(\succ) = P(\succ | \sigma, \phi) = \frac{1}{Z} \phi^{d(\succ, \sigma)}$, where Z is a normalization parameter and $d(\succ, \sigma)$ is the number of pairwise disagreements between \succ and σ (that is, the number of pairs of objects that are ordered differently by \succ than by σ), known as the Kendall-Tau distance. To generate preference profiles, we sample the preference of each agent independently from the same Mallows distribution. Note that the Mallows model is unimodal at σ , with lower ϕ implying a more concentrated distribution of preferences around σ . Note that when $\phi = 1$ the distribution is maximally dispersed, yielding Impartial Culture. Unless $\phi = 1$ the Mallows measure is not fully symmetric, since some orderings have higher probability than others in the same H-orbit.

Figure 3 is analogous to Figure 1, but with a Mallows distribution with $\phi = 0.6$. In this case, we see a consistent advantage for TTC over SD, but less than for IC. For intuition as to why, when some objects are systematically preferred to others then TTC is biased in favor of agents who receive favorable objects in the preliminary assignment. In the limit as the dispersion parameter goes to zero (all agents have the same preference), being initially

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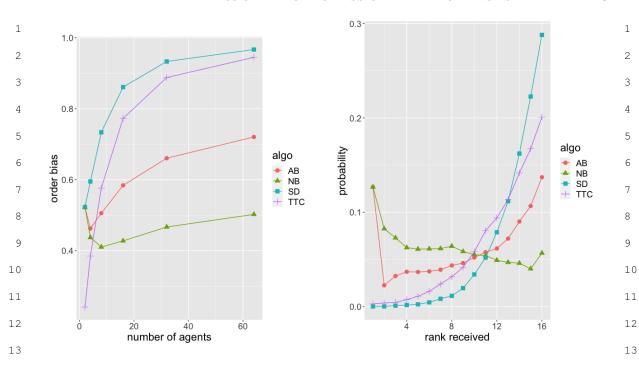


FIGURE 3.—(left) Borda order bias, Mallows ($\phi = 0.6$), mean of 10000 simulations, (right) distribution of rank received for last agent, n = 16, Mallows ($\phi = 0.6$), mean of 10000 simulations.

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assigned the k-th most favorable object is exactly equivalent to choosing k-th in the SD order. The Boston mechanisms, especially the naive version, achieve significantly lower order bias still. The drivers of this pattern are clear from the right hand side of the figure. Under SD and TTC, the worst-off agent rarely receives their most-preferred object. However, the Boston mechanisms (by design) give all agents a high probability of receiving their most-preferred object. Remarkably, under Naive Boston, the probability of receiving an object is (approximately) decreasing in the rank of that object, even for the last agent in the tiebreak order, which accounts for the low order bias.

Similarly, Figure 4 is analogous to Figure 2, displaying expected utilitarian and Nash welfare. In contrast to Figure 2, both welfare measures decrease with n. Otherwise, the relative performance of the mechanisms is similar to Figure 2, but the Boston mechanisms exhibit a larger advantage over SD/TTC for utilitarian welfare.

Finally, Figure 5 explores the relationship between the Mallows dispersion parameter and order bias, utilitarian welfare, and Nash welfare. Most strikingly, on the left, we see

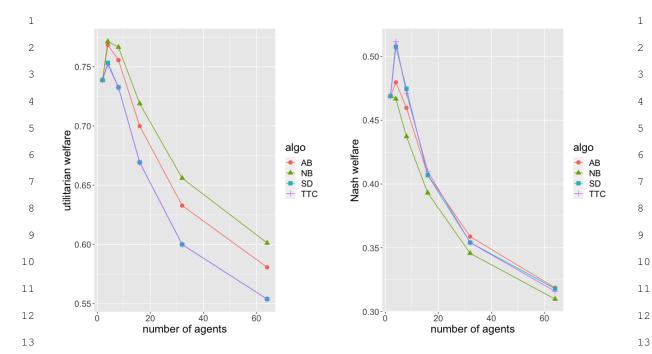


FIGURE 4.—(left) Borda utilitarian welfare, Mallows ($\phi = 0.6$), mean of 10000 simulations, (right) Borda Nash welfare, Mallows ($\phi = 0.6$), mean of 10000 simulations.

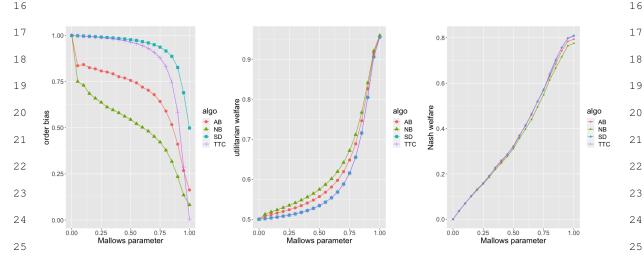


FIGURE 5.—(left) Borda order bias, n = 64, mean of 10000 simulations, (center) Borda utilitarian welfare, n = 64, mean of 10000 simulations, (right) Borda Nash welfare, n = 16, mean of 10000 simulations.

that the Boston mechanisms have lower order bias than TTC except for very high values of dispersion parameter. This suggests that the Boston mechanisms, and Naive Boston in

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particular, may be a better choice than TTC for minimizing order bias when some objects are systematically preferred over others. 2 3 3 4 4 7. DISCUSSION 5 5 6 We have defined and analysed order symmetry, a novel and natural fairness concept that 7 requires all agents to do equally well in expectation. When associated with a sufficiently symmetric probability measure on profiles, order symmetry is a relaxation of anonymity that, unlike anonymity, can be satisfied by discrete algorithms. For other measures, order symmetry cannot be satisfied exactly, and some order bias is inevitable. In situations where order bias is a consideration, our analysis suggests that the standard implementation of **RSD** should be avoided, and **TTC** used instead. The latter achieves the same ex ante re-13 13 sults as the former, while being much fairer ex post, in both theory and simulation. Of the 14 standard algorithms we explored here, the Boston mechanisms (under truthful behavior) perform well in terms of order bias, never satisfying order symmetry exactly but signifi-16 cantly outperforming even TTC on synthetic Mallows data for all but very large values of 17 dispersion parameter. Our results suggest that Naive Boston in particular should be consid-18 18 ered for a designer wishing to minimize the influence of the mechanism's randomness and 19 for whom strategyproofness is less important than welfare performance. 20 We have additionally shown that ex ante ordinal efficiency can be achieved in conjunc-21 tion with ex post order symmetry with respect to any fully symmetric probability mea-22 sure. While the RMM-RA mechanism that we invent is clearly not feasible for practical 23 implementation—it is computationally intractable and employs an unintuitive tiebreaking

procedure—we see it as a valuable proof of concept that illustrates the compatibility of these compelling properties.

We conclude with some additional observations and directions for future work.

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Order Symmetric Implementations. As we have already mentioned, it would be particularly interesting to determine whether or not it is possible to implement the Probabilis-

tic Serial mechanism, known to be ex ante ordinally efficient and ex ante weakly strate-gyproof [Bogomolnaia and Moulin, 2001]², in a way that is ex post order symmetric.

More generally, can we determine whether a given fractional assignment mechanism can be implemented over discrete assignment mechanisms satisfying order symmetry? It is known that the analogous question is computationally hard for some other properties. For example, determining whether a randomized mechanism is ex-post efficient, and hence can be expressed as a lottery over Pareto optimal assignment mechanisms, is NP-complete [Aziz et al., 2015].

Multi-unit assignment. We have not considered the case where the number of objects is more than the number of agents and a bundle of objects is assigned to each agent, but the idea of order bias remains relevant there and our definition could be generalized by extending preferences over individual objects to preferences over sets of objects [Barberà et al., 2004]. Indeed many common mechanisms, including sports league drafts, utilize a "picking sequence" (order in which agents choose objects, one by one) and this sequence has long been known to influence outcomes substantially. Many attempts have been made to balance outcomes between agent positions [Kohler and Chandrasekaran, 1971, Brams and Taylor, 2000, Bouveret and Lang, 2011, Beynier et al., 2019, Kalinowski et al., 2013], and order bias may help to compare different picking sequences.

We note that there is already a substantial stream of work aimed at measuring fairness in this setting. Concepts such as envy-freeness up to one object [Lipton et al., 2004], envy-freeness up to any object [Caragiannis et al., 2019], and proportionality up to one object [Conitzer et al., 2017] have been widely studied, and prior work has considered ex post fairness in conjunction with ex ante guarantees in more general multi-object assignment settings [Budish et al., 2013, Akbarpour and Nikzad, 2020, Freeman et al., 2020, Aziz, 2020, Babaioff et al., 2021]. None of this work is relevant to the house allocation setting

²An assignment mechanism is weakly strategyproof if an agent cannot obtain an assignment by misreporting that stochastically dominates their assignment from truthtelling.

that we consider in this work, since the fairness guarantees are too permissive when each agent receives only a single object.

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Two-sided matching. One may wonder why we have focused on one-sided matching and not the two-sided case. The answer is that, from the perspective of order symmetry, the two-sided case is significantly less interesting! In the two-sided setting, agents on both sides of the market express a preference, in contrast to the one-sided setting in which the objects do not have preferences over the agents. Two-sided matching mechanisms are therefore able to leverage the preferences of one side as a source of asymmetry over the other side, rather than having to introduce that asymmetry as part of the mechanism (as a tiebreak order or initial endowment). Two-sided mechanisms such as deferred acceptance and (the two-sided version of) TTC are defined without any reference to an ordering of agents and therefore satisfy a natural generalization of anonymity without any need for randomization.

General probability measures. A compelling direction for future work is to dive more deeply into the possibilities and limitations for general probability measures. While measures such as IC are a useful baseline, they are rarely realistic, and our empirical investigation suggests that the choice of probability measure has a large influence on order bias. For practical application, we imagine order symmetry being incorporated into mechanism design in a two step process. First, the designer estimates (say, from historical data) the probability measure from which the preference profile will be drawn. Second, the designer can search for a mechanism with low order bias with respect to this measure.

Other order bias definitions. The way we have defined order bias is not the only possibility. Abstractly, we could use any matrix norm to measure the distance between the given rank distribution matrix and the space of rank one matrices. It is not clear to us now whether this is more compelling axiomatically than the approach we have taken, but it is worth further exploration.

Obvious strategyproofness. We have used the concept of order symmetry to distinguish between **RSD** and **TTC-RE**. Another distinction between the two can be made via the notion of obvious strategyproofness [Li, 2017]. When implemented via the usual sequential

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choosing procedure, SD is obviously strategyproof, while TTC has no obviously strategyproof implementation. Given that obvious strategyproofness increasingly appears to be a desirable property for practical application [Schmelzer, 2017, Troyan, 2019], it would be natural to consider the possibility of achieving it in conjunction with order symmetry.

APPENDIX A: DECOMPOSING ASSIGNMENT MECHANISMS

By the Birkhoff-von Neumann theorem, every assignment can be expressed as the convex combination of discrete assignments. Let us define a matrix with $(n!)^n$ rows and n! columns, where each row corresponds to a profile and each column corresponds to a discrete assignment. Note that any assignment mechanism can be expressed as a row stochastic matrix, which corresponds to a mapping from profiles to distributions over discrete assignments. Further, any row stochastic matrix can be expressed as a convex combination of binary row stochastic matrices in which every entry is either 0 or 1. Note that any binary row stochastic matrix corresponds to a discrete assignment mechanism, since it maps each profile to a single assignment. Therefore, any assignment mechanism can be expressed as a convex combination of discrete assignment mechanisms.

APPENDIX B: SYMMETRIZATION

We now show that given any discrete assignment mechanism \mathcal{A} , we can define a corresponding randomized assignment mechanism $\overline{\mathcal{A}}$ whose associated fractional assignment mechanism $\overline{\mathcal{A}}$ is anonymous. We note that Bade [2020] defines the same construction, denoting it $\Delta \mathcal{A}$ and naming it the *symmetrization* of \mathcal{A} .

PROPOSITION B.1: Let A be a discrete assignment mechanism. For each $g \in G$, define

$$\mathcal{A}^g(\pi) := g \cdot \mathcal{A}(g^{-1} \cdot \pi).$$

2.2

Then A^g is a discrete assignment mechanism. Furthermore we can define a randomized mechanism \overline{A} whose associated fractional mechanism \overline{A} given by

$$\overline{\mathcal{A}} := \frac{1}{|G|} \sum_{g \in G} \mathcal{A}^g$$

is anonymous.

PROOF: Each \mathcal{A}^g clearly outputs a discrete assignment and the weights 1/|G| sum to 1, so $\overline{\mathcal{A}}$ and $\overline{\mathcal{A}}$ are well defined and of the correct type. Now let $h \in G$. Letting $k = h^{-1}g$ below,

$$\overline{\mathcal{A}}(h \cdot \pi) = \frac{1}{|G|} \sum_{g \in G} A^g(h \cdot \pi) = \frac{1}{|G|} \sum_{g \in G} g \cdot \mathcal{A}(g^{-1} \cdot (h \cdot \pi))$$

$$= \frac{1}{|G|} \sum_{g \in G} g \cdot \mathcal{A}((g^{-1}h) \cdot \pi) = \frac{1}{|G|} \sum_{k \in G} (hk) \cdot \mathcal{A}(k^{-1} \cdot \pi)$$

$$= h \cdot \left(\frac{1}{|G|} \sum_{k \in G} k \cdot \mathcal{A}(k^{-1} \cdot \pi) \right) = h \cdot \overline{\mathcal{A}}(\pi).$$

Q.E.D. 1.

Note that \mathcal{A} is anonymous if and only if $\mathcal{A}^g = \mathcal{A}$ for each $g \in G$. Also \mathcal{A}^g is equivalently defined by the identity

$$g^{-1} \cdot \mathcal{A}^g(\pi) = \mathcal{A}(g^{-1} \cdot \pi).$$

EXAMPLE B.2: Suppose that \mathcal{A} is SD with a fixed picking order $\rho=(a_1,\ldots,a_n)$. Then \mathcal{A}^g is SD with the picking order $(g(a_1),\ldots,g(a_n))$, and $\overline{\mathcal{A}}$ is **RSD**. This is because transforming to $g^{-1} \cdot \pi$ has the effect of changing the preference of a_1 to that of $g(a_1)$, etc. Thus a_1 now gets what $g(a_1)$ ranked first, etc, and then applying g ensures that $g(a_1)$ gets its first choice, etc. More precisely, writing $g \star \rho = \mu$ we have

$$SD_{g^{-1}\star\mu}(g^{-1}\cdot\pi) = g^{-1}\cdot SD_{\mu}(\pi)$$

so that $\mathcal{A}^g = SD_{\mu}$.

The same argument works for RMM with a fixed tiebreaking order. Here \mathcal{A}^g is RMM with the tiebreaking agent transformed by g, and $\overline{\mathcal{A}}$ is RMM-RA.

Similarly, if \mathcal{A} is TTC with a fixed endowment α , \mathcal{A}^g is TTC with endowment $g \cdot \alpha$, and $\overline{\mathcal{A}}$ is **TTC-RE**. The analogous argument works: writing $g \cdot \alpha = \beta$ we have

$$TTC_{g^{-1}\cdot\beta}(g^{-1}\cdot\pi) = g^{-1}\cdot TTC_{\beta}(\pi)$$

1	so that $\mathcal{A}^g = TTC_{\beta}$.	1
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3	APPENDIX C: PROOF OF THEOREM 3.6	3
4	Suppose that A is anonymous, and consider agent a_1 and a_k , where $1 \le k \le n$ and k is	4
5	arbitrary. By anonymity, for all $\pi \in \Pi$ and all $g \in G$,	5
6		6
7	$\mathcal{A}(g \cdot \pi) = g \cdot \mathcal{A}(\pi)$	7
8	which immediately yields for all r, j	8
9	which immediately yields for all r, y	9
10	$D_{g \cdot \pi, \mathcal{A}}(g(r), j) = D_{\pi, \mathcal{A}}(r, j). \tag{1}$	10
11		11
12	Suppose that $1 \le r \le n$ and let g be the permutation of A that simply swaps a_1 and a_r .	12
13	Then for each j such that $1 \le j \le n$,	13
14	$E_P[D_{\pi,\mathcal{A}}(r,j)] = \sum P(\pi)D_{\pi,\mathcal{A}}(r,j)$ by definition of expectation	14
15	$\prod_{\pi \in \Pi} (1, \pi, \pi, \pi, \pi)$	15
16	$= \sum_{r} P(\pi) D_{g \cdot \pi, \mathcal{A}}(g(r), j) $ by (1)	16
17	$\pi \in \Pi$	17
18	$= \sum P(g \cdot \pi) D_{g \cdot \pi, \mathcal{A}}(1, j) $ by anonymity of P	18
19	$\pi \in \Pi$	19
20	$=\sum P(\pi')D_{\pi',\mathcal{A}}(1,j)$ because g induces a bijection of $\Pi(A,O)$	20
21	$\pi' \in \Pi$	21
22	$=E_P[D_{\pi,\mathcal{A}}(1,j)]$ by definition of expectation.	22
23	APPENDIX D: PROOF OF THEOREM 4.7	23
24	We first give the proof, then an example to clarify the main idea.	24
25		25
26	PROOF: If $g \in G$ then permuting the agents and the endowment by g will also permute	26
27	the assignment given by TTC by g , since the output is entirely determined by the endow-	27
28	ment and the preferences. More formally, let \mathcal{A}_{α} be TTC with endowment α . Then	28
29		29
30	$\mathcal{A}_{g \cdot \alpha}(g \cdot \pi) = g \cdot \mathcal{A}_{\alpha}(\pi).$	30

Thus if we write $D_{\pi,\mathcal{A}}$ as $D_{\pi,\alpha}$ when \mathcal{A} is TTC with endowment α , we obtain for all r,j

$$D_{\pi,\alpha}(r,j) = D_{q,\pi,q,\alpha}(g(r),j). \tag{2}$$

Now relabeling the objects back to what they were will restore the original endowment α . Formally, define $\overline{q} \in H$ as the mapping that takes $\alpha(q^{-1}(k))$ to $\alpha(k)$. Then we have $\overline{g} \star g \cdot \alpha = \alpha$. Since relabeling the objects does not change the rank of any agent's allocation, only the label, we obtain

$$D_{g \cdot \pi, g \cdot \alpha}(g(r), j) = D_{\overline{g} \star g \cdot \pi, \alpha}(g(r), j). \tag{3}$$

Thus for each r, if we choose q so that q(r) = 1 we obtain

$$E_P[D_{\pi,\alpha}(r,j)] = \sum_{\pi \in \Pi} P(\pi)D_{\pi,\alpha}(r,j) \qquad \text{by definition of expectation}$$

$$= \sum_{\pi \in \Pi} P(\pi)D_{\overline{g}\star(g\cdot\pi),\alpha}(g(r),j) \qquad \text{by (2) and (3)}$$

$$= \sum_{\pi \in \Pi} P(\pi)D_{\overline{g}\star(g\cdot\pi),\alpha}(1,j) \qquad \text{by choice of } g$$

$$= \sum_{\pi' \in \Pi} P(\pi')D_{\overline{g}\star\pi',\alpha}(1,j) \qquad \text{by anonymity of } P$$

$$= \sum_{\pi' \in \Pi} P(\pi'')D_{\pi'',\alpha}(1,j) \qquad \text{by neutrality of } P$$

$$= \sum_{\pi'' \in \Pi} P(\pi'')D_{\pi'',\alpha}(1,j) \qquad \text{by neutrality of } P$$

$$= E_P[D_{\pi,\alpha}(1,j)] \qquad \text{by definition of expectation.}$$

Q.E.D.2.4

EXAMPLE D.1: Consider again the profile π given by

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$$a_1: o_1 \succ o_2 \succ o_3$$
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 $a_2: o_1 \succ o_3 \succ o_2$
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 $a_3: o_2 \succ o_1 \succ o_3$

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and the initial allocation \alpha sending a_i to o_i for each i. Note that with endowment \alpha, the
     assignment made by TTC on \pi is a_1:o_1,a_2:o_3,a_3:o_2, and the corresponding rank distri-
     bution matrix is \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}.
                                                                                                                          3
 3
        Let g be the 3-cycle a_1 \rightarrow a_2 \rightarrow a_3 \rightarrow a_1. The bijections in the above proof yield the
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     following. First, running TTC with endowment g \cdot \alpha on g \cdot \pi we obtain a_1 : o_2, a_2 : o_1, a_3 :
     o_3, and the rank distribution matrix is permuted appropriately: \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}.
                                                                                                                          6
        Next, \overline{g} is the 3-cycle o_1 \rightarrow o_2 \rightarrow o_3 \rightarrow o_1, so that the endowment is transformed back to
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     a_1: o_1, a_2: o_2, a_3: o_3 and the profile to
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                                                   a_1 : o_3 \succ o_2 \succ o_1
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                                                   a_2: o_2 \succ o_3 \succ o_1
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                                                   a_3 : o_2 \succ o_1 \succ o_3.
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     The assignment under TTC with endowment \alpha is a_1: o_3, a_2: o_2, a_3: o_1 and the rank distri-
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     bution matrix is still \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}.
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        REMARK 1: Note that the proof of Theorem 4.7 fails for SD with fixed picking order \rho.
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     The analog of (2) does hold. If we permute \rho and the profile by g, we get the permutation of
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     the original assignment. Letting A_{\rho} denote SD with picking order \rho, we have \mathcal{A}_{g\star\rho}(g\cdot\pi)=
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     g \cdot \mathcal{A}_{\rho}(\pi) and so D_{\pi,\rho}(r,j) = D_{g \cdot \pi,g \star \rho}(g(r),j). However the right side of this last equation
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     corresponds to SD with a different order of agents from the original choosing order, and
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     there is no way to restore the original order using only permutations of the objects. That is,
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     there is no analog of (3).
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                                   APPENDIX E: Proof of Lemma 4.12
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        We begin the section with the proof, followed by an example illustrating the main con-
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     cepts.
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        PROOF: For the purposes of this proof, we denote RMM with tiebreak order \rho by \mathcal{A}_{\rho}.
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     Order the objects and agents and make an identification of G and H. That is, choose any
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bijection $\alpha: A \to \mathcal{O}$, and thereby obtain a bijection from G to H given by $g \to \overline{g} := \alpha \circ g \circ g$ α^{-1} , where \circ denotes function composition. Write $D_{\pi,\rho}$ to denote $D_{\pi,\mathcal{A}_{\rho}}$. Note that as in Remark 1, with $\rho = \pi(i)$ $\mathcal{A}_{q\star\rho}(q\cdot\pi)=q\cdot\mathcal{A}_{\rho}(\pi)$ so that for all r, j $D_{\pi,\rho}(r,j) = D_{q\cdot\pi,q\star\rho}(g(r),j).$ (4) Also, permuting the objects does not change the rank of the assigned object, only its name. Thus for every $h \in H$ and all r, j $D_{\pi,\rho}(q(r), j) = D_{h\star\pi,\rho}(q(r), j).$ (5) Now for each r, choose g so that g(r) = 1 and choose h so that $[h \star q \cdot \pi](i) = \overline{q} \star \pi(i).$ Note that this is possible because $[g \cdot \pi](i)$ and $\overline{g} \star \pi(i)$ are both strict linear orders over the objects and H acts transitively (there is a single orbit). We obtain $E_P[D_{\pi,\alpha^{-1}\pi(i)}(r,j)] = \sum_{\pi \subset \Pi} P(\pi) D_{\pi,\alpha^{-1}\pi(i)}(r,j)$ by definition of expectation 20 $= \sum_{\pi \in \Pi} P(\pi) D_{g \cdot \pi, g \star \alpha^{-1} \pi(i)}(g(r), j)$ by (4) $= \sum_{\boldsymbol{\pi}} P(\boldsymbol{\pi}) D_{g \cdot \boldsymbol{\pi}, \boldsymbol{\alpha}^{-1} \overline{g} \star \boldsymbol{\pi}(i)}(g(r), j)$ by definition of \overline{g} 2.4 $= \sum_{\boldsymbol{\tau}} P(\boldsymbol{\pi}) D_{h\star g\cdot\boldsymbol{\pi},\alpha^{-1}\overline{g}\star\boldsymbol{\pi}(i)}(g(\boldsymbol{r}),j)$ by (5) 2.7 $= \sum_{\pi \in \Pi} P(\pi) D_{h \star g \cdot \pi, \alpha^{-1}[h \star g \cdot \pi](i)}(g(r), j)$ by choice of h $= \sum_{\sigma \in \Pi} P(\pi) D_{h \star g \cdot \pi, \alpha^{-1}[h \star g \cdot \pi](i)}(1, j)$ by choice of g

```
= \sum_{\pi' \subset \Pi} P(\pi') D_{h \star \pi', \alpha^{-1} h \star \pi'(i)}(1, j)
                                                                                               by anonymity of P^{-1}
 2
                               = \sum_{\pi'' \in \Pi} P(\pi'') D_{\pi'', \alpha^{-1} \pi''(i)}(1, j)
                                                                                                 by neutrality of P
 3
 4
                               =E_P[D_{\pi \alpha^{-1}\pi(i)}(1,j)]
                                                                                    by definition of expectation.
 5
 6
                                                                                                              Q.E.D.
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                                                                                                                          8
 8
        EXAMPLE E.1: The bijections in the last proof can be demonstrated using Exam-
     ple 4.11, with \alpha(a_i) = o_i for each i. Let \pi be the profile in that example, let the tiebreak
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     order \rho = a_3 > a_1 > a_2 determined by the first agent (in other words i = 1), and let g be
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11
     the cycle a_1 \rightarrow a_2 \rightarrow a_3 \rightarrow a_1. Then g \cdot \pi is the profile
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                                                                                                                          12
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                                                                                                                          13
                                                   a_1 : o_2 \succ o_3 \succ o_1
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                                                                                                                          14
                                                   a_2: o_3 \succ o_1 \succ o_2
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                                                                                                                          15
                                                   a_3 : o_3 \succ o_1 \succ o_2
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     and the two rank maximal matchings are a_1:o_2,a_2:o_1,a_3:o_3 and a_1:o_2,a_2:o_3,a_3:o_1.
18
     With the picking order g \star \rho = a_1 > a_2 > a_3 the assignment is a_1 : o_2, a_2 : o_3, a_3 : o_1, so
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     that, for example, agent a_2 = g(a_1) receives her first choice, agent a_3 = g(a_2) receives her
                                                                                                                          20
20
     second choice, and agent a_1 = g(a_3) receives her first choice.
21
                                                                                                                          21
        We must choose h to satisfy h \star (o_2, o_3, o_1) = (o_1, o_2, o_3) so that h is the 3-cycle o_1 \rightarrow
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                                                                                                                          22
     o_3 \rightarrow o_2 \rightarrow o_1. The profile h \star g \cdot \pi is
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2.4
                                                   a_1: o_1 \succ o_2 \succ o_3
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                                                   a_2 : o_2 \succ o_3 \succ o_1
                                                                                                                          26
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27
                                                   a_3 : o_2 \succ o_3 \succ o_1
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     so with the picking order a_1 > a_2 > a_3 the mechanism outputs the assignment a_1 : o_1, a_2 :
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     o_2, a_3: o_3. Again, as they must, agents a_1 and a_2 receive their first choice and a_3 its second.
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APPENDIX F: Proof of Theorem 4.13

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We showed order symmetry in Lemma 4.12, and ex ante anonymity follows from Appendix B. For ordinal efficiency, we show that for any preference profile π , the fractional assignment RMM-RA(π) is rank-maximal in the space of fractional assignments. Since a rank-maximal matching is welfare maximizing when agents have lexicographic utilities, any rank-maximal matching satisfies rank efficiency [Featherstone, 2020], a strengthening of ordinal efficiency.

We proceed to show rank maximality. To see this, suppose to the contrary that there exists a fractional assignment α and associated rank distribution matrix D_{α} for which there exists an index j for which $\sum_{i=1}^n D_{\pi,RMM-RA}(i,j') = \sum_{i=1}^n D_{\alpha}(i,j')$ for all j' < j, and $\sum_{i=1}^n D_{\pi, \text{RMM-RA}}(i, j) < \sum_{i=1}^n D_{\alpha}(i, j)$. That is, the expected number of agents who receive their j'th most-preferred object is equal for both RMM-RA(π) and α for all j' < j, but the expected number of agents who receive their jth most-preferred object is higher for α than for RMM-RA(π).

Further, for every rank index j' we know that for every tiebreak order, $\sum_{i=1}^{n} D_{\pi,RMM}(i,j') =$ $\sum_{i=1}^{n} D_{\pi,RMM-RA}(i,j')$, because every output of RMM is a rank-maximal matching, which uniquely determines the distribution of ranks received by the agents.

18 Consider any Birkhoff-von Neumann decomposition of α into discrete assignments α_1,\dots,α_k such that $\alpha=\sum_{\ell=1}^kq_\ell\alpha_\ell$ and corresponding rank distribution matrices $D_{\alpha_1},\dots,D_{\alpha_k}$ Let j' < j. Then $\sum_{\ell=1}^k q_\ell \sum_{i=1}^n D_{\alpha_\ell}(i,j') = \sum_{i=1}^n D_{\alpha}(i,j')$. It must be the case that 21

$$\sum_{i=1}^{n} D_{\alpha_{\ell}}(i, j') = \sum_{i=1}^{n} D_{\alpha}(i, j')$$
(6)

for all $\ell \in \{1, ..., k\}$. If not, consider the smallest such j' for which Equation 6 is violated. Then there exists an ℓ' for which

$$\sum_{i=1}^{n} D_{\alpha_{\ell'}}(i,j') > \sum_{i=1}^{n} D_{\alpha}(i,j') = \sum_{i=1}^{n} D_{\pi,\text{RMM-RA}}(i,j') = \sum_{i=1}^{n} D_{\pi,\text{RMM}}(i,j'),$$
²⁹

violating rank-maximality of RMM(π), since $\alpha_{\ell'}$ and RMM(π) allocate the same number of agents to each of their top j'-1 objects, but α allocates more agents to their j'th mostpreferred object than RMM(π) does. 3 We therefore arrive at rank index j, where we have 4 4 5 $\sum_{\ell=1}^{k} q_{\ell} \sum_{i=1}^{n} D_{\alpha_{\ell}}(i,j) = \sum_{i=1}^{n} D_{\alpha}(i,j) > \sum_{i=1}^{n} D_{\pi,\text{RMM-RA}}(i,j) = \sum_{i=1}^{n} D_{\pi,\text{RMM}}(i,j),$ which is a contradiction of rank-maximality of RMM(π) by the same argument as applied immediately above. 9 10 10 REFERENCES 11 11 Atila Abdulkadiroğlu and Tayfun Sönmez. Random serial dictatorship and the core from random endowments in 12 12 house allocation problems. Econometrica, 66(3):689-701, 1998. URL http://www.jstor.org/stable/2998580. 13 13 Atila Abdulkadiroğlu and Tayfun Sönmez. School choice: A mechanism design approach. American Economic Review, 93(3):729-747, 2003. 14 14 David J Abraham, Katarína Cechlárová, David F. Manlove, and Kurt Mehlhorn. Pareto optimality in house 15 allocation problems. In International Symposium on Algorithms and Computation, pages 3-15. Springer, 16 16 2004. 17 17 Mohammad Akbarpour and Afshin Nikzad. Approximate random allocation mechanisms. Review of Economic 18 18 Studies, 87(6):2473-2510, 2020. Haris Aziz. Simultaneously achieving ex-ante and ex-post fairness. In International Conference on Web and 19 Internet Economics, pages 341–355. Springer, 2020. Haris Aziz, Simon Mackenzie, Lirong Xia, and Chun Ye. Ex post efficiency of random assignments. In Proceed-21 21 ings of the 2015 International Conference on Autonomous Agents and Multiagent Systems, pages 1639-22 22 1640. International Foundation for Autonomous Agents and Multiagent Systems, 2015. 23 23 Moshe Babaioff, Tomer Ezra, and Uriel Feige. Best-of-both-worlds fair-share allocations. arXiv preprint arXiv:2102.04909, 2021. 2.4 24 Sophie Bade. Random serial dictatorship: the one and only. *Mathematics of Operations Research*, 45(1):353– 368, 2020. 26 26 Salvador Barberà, Walter Bossert, and Prasanta K Pattanaik. Ranking sets of objects. In Handbook of utility 27 2.7 theory, pages 893-977. Springer, 2004. 28 28 Aurélie Beynier, Sylvain Bouveret, Michel Lemaître, Nicolas Maudet, Simon Rey, and Parham Shams. Effi-29 ciency, sequenceability and deal-optimality in fair division of indivisible goods. In Proceedings of the 18th 29

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