L23: Graphs 2

1-Tut: Kruskal's Algorithm

Send Feedback

Given an undirected, connected and weighted graph G(V, E) with V number of vertices (which are numbered from 0 to V-1) and E number of edges.

Find and print the total weight of Minimum Spanning Tree (MST) using Kruskal's algorithm.

Input Format:

First line will contain T(number of test case), each test case follows as.

Line 1: Two Integers V and E (separated by space)

Next E lines: Three integers ei, ej and wi, denoting that there exists an edge between vertex ei and vertex ej with weight wi (separated by space)

Output Format:

Weight of MST for each test case in new line.

```
Constraints:
```

```
1 <= T <= 10
2 <= V, E <= 10^5
1 <= wt <= 10^4
```

Sample Input 1:

1 4 4

0 1 3

035

121

238

Sample Output 1:

9

```
1. #include <iostream>
2. #include <algorithm>
3. using namespace std;
4. // Class that store values for each vertex
5. class Edge
6. {
7. public:
8.
      int source;
9.
      int dest:
10.
      int weight;
11. };
12. // Comparator function used to sort edges
13. bool compare(Edge e1, Edge e2)
14. {
```

```
15.
      // Edges will sorted in order of their weights
16.
      return e1.weight < e2.weight;
17.}
18. // Function to find the parent of a vertex
19. int findParent(int v, int *parent)
20. {
21.
      // Base case, when a vertex is parent of itself
22.
      if (parent[v] == v)
23.
    {
24.
        return v;
25.
26.
      // Recursively called to find the topmost parent of the vertex.
27.
      return findParent(parent[v], parent);
28. }
29. void kruskals(Edge *input, int n, int E)
30. {
31. // In-built sort function: Sorts the edges in
32.
    // increasing order of their weights
33.
      sort(input, input + E, compare);
34.
     // Array to store final edges of MST
35.
      Edge *output = new Edge[n - 1];
      // Parent array initialized with their indexes
36.
37.
      int *parent = new int[n];
38.
      for (int i = 0; i < n; i++)
39.
     {
40.
        parent[i] = i;
41.
42.
      int count = 0; // To maintain the count of number of edges in the MST
43.
      int i = 0; // Index to traverse over the input array
44.
      while (count != n - 1)
      { // As the MST contains n-1 edges.
45.
46.
        Edge currentEdge = input[i];
47.
        // Figuring out the parent of each edge's vertices
48.
        int sourceParent = findParent(currentEdge.source, parent);
49.
        int destParent = findParent(currentEdge.dest, parent);
50.
        // If their parents are not equal, then we added that edge to
                                                                           output
51.
        if (sourceParent != destParent)
52.
53.
           output[count] = currentEdge;
54.
                                      // Increased the count
           count++;
55.
           parent[sourceParent] = destParent; // Updated the parent array
56.
        }
57.
        j++;
58.
     }
```

```
59.
      // Finally, printing the MST obtained.
60.
      long long int sum = 0;
61.
      for (int i = 0; i < n - 1; i++)
62.
63.
         if (output[i].source < output[i].dest)</pre>
64.
65.
           sum += (output[i].weight);
66.
         }
67.
         else
68.
69.
           sum += (output[i].weight);
70.
71.
     }
72.
73.
      cout << sum << endl;</pre>
74.}
75. int main()
76. {
77.
78.
      int t;
79.
      cin >> t;
80.
      while (t--)
81.
      {
82.
83.
         int n, E;
84.
         cin >> n;
85.
         cin >> E;
86.
         Edge *input = new Edge[E];
87.
         for (int i = 0; i < E; i++)
88.
89.
           int s, d, w;
90.
            cin >> s >> d >> w;
91.
           input[i].source = s;
92.
            input[i].dest = d;
93.
            input[i].weight = w;
94.
         kruskals(input, n, E);
95.
96.
97.
      return 0;
98.}
```

2-Tut: Prim's Algorithm

Send Feedback

Given an undirected, connected and weighted graph G(V, E) with V number of vertices (which are numbered from 0 to V-1) and E number of edges.

Find and print the total weight of Minimum Spanning Tree (MST) using Prim's algorithm.

Input Format:

First line will contain T(number of test case), each test case follows as.

Line 1: Two Integers V and E (separated by space)

Next E lines: Three integers ei, ej and wi, denoting that there exists an edge between vertex ei and vertex ej with weight wi (separated by space)

Output Format:

Weight of MST for each test case in new line.

```
Constraints:
```

```
1 <= T <= 10
2 <= V, E <= 10^5
1 <= wt <= 10^4
```

Sample Input 1:

121

238

Sample Output 1:

9

```
1. #include <bits/stdc++.h>
2. using namespace std;
3.
4. int findMinVertex(int *weights, bool *visited, int n)
5. {
6.
      // Initialized to -1 means there is no vertex till now
7.
      int minVertex = -1;
      for (int i = 0; i < n; i++)
8.
9.
        // Conditions: the vertex must be unvisited and either minVertex value is -1
10.
11.
        // or if minVertex has some vertex to it, then weight of currentvertex
12.
        // should be less than the weight of the minVertex.
        if (!visited[i] && (minVertex == -1 || weights[i] < weights[minVertex]))</pre>
13.
14.
15.
           minVertex = i;
16.
        }
17. }
```

```
18.
      return minVertex;
19.}
20. void prims(int **edges, int n)
21. {
22.
      int *parent = new int[n];
23.
      int *weights = new int[n];
24.
      bool *visited = new bool[n];
25.
      // Initially, the visited array is assigned to false and weights array
26.
      // to infinity.
27.
      for (int i = 0; i < n; i++)
28.
29.
         visited[i] = false;
30.
         weights[i] = INT_MAX;
31.
32.
      // Values assigned to vertex 0.(the selected starting vertex to begin with)
33.
      parent[0] = -1;
34.
      weights[0] = 0;
35.
      for (int i = 0; i < n - 1; i++)
36.
37.
        // Find min vertex
38.
         int minVertex = findMinVertex(weights, visited, n);
39.
         visited[minVertex] = true;
40.
        // Explore unvisited neighbors
41.
         for (int j = 0; j < n; j++)
42.
         {
            if (edges[minVertex][j] != 0 && !visited[j])
43.
44.
45.
              if (edges[minVertex][j] < weights[j])</pre>
46.
47.
                 // updating weight array and parent array
                 weights[j] = edges[minVertex][j];
48.
49.
                 parent[j] = minVertex;
50.
              }
51.
           }
52.
         }
53.
      }
54.
      // Final MST printed
55.
      long long int sum = 0;
56.
      for (int i = 0; i < n; i++)
57.
58.
         sum += (weights[i]);
59.
      }
60.
61.
      cout << sum << endl;
```

```
62.}
63. int main()
64. {
65.
      int t;
66.
      cin >> t;
67.
      while (t--)
68.
69.
         int n;
70.
         int e;
71.
         cin >> n >> e;
72.
         int **edges = new int *[n]; // Adjacency matrix used to store the graph
73.
         for (int i = 0; i < n; i++)
74.
         {
75.
            edges[i] = new int[n];
76.
           for (int j = 0; j < n; j++)
77.
78.
              // Initially all pairs are assigned 0 weight which
              // means that there is no edge between them
79.
80.
              edges[i][j] = INT_MAX;
81.
           }
82.
         }
83.
         for (int i = 0; i < e; i++)
84.
85.
           int f, s, weight;
86.
            cin >> f >> s >> weight;
87.
88.
            if (edges[f][s] > weight)
89.
           {
90.
              edges[f][s] = weight;
91.
92.
            if (edges[s][f] > weight)
93.
94.
              edges[s][f] = weight;
95.
           }
96.
97.
         prims(edges, n);
98.
         for (int i = 0; i < n; i++)
99.
         {
100.
               delete[] edges[i];
101.
102.
             delete[] edges;
103.
          }
104.
105.
          return 0; }
```

3-Tut: Dijkstra's Algorithm

Send Feedback

Given an undirected, connected and weighted graph G(V, E) with V number of vertices (which are numbered from 0 to V-1) and E number of edges.

Find and print the shortest distance from the source vertex (i.e. Vertex 0) to all other vertices (including source vertex also) using Dijkstra's Algorithm.

Print the ith vertex number and the distance from source in one line separated by space. Print different vertices in different lines.

Note: Order of vertices in output doesn't matter.

Input Format:

First line will contain T(number of test case), each test case follows as.

Line 1: Two Integers V and E (separated by space)

Next E lines: Three integers ei, ej and wi, denoting that there exists an edge between vertex ei and vertex ej with weight wi (separated by space)

Output Format:

In different lines, ith vertex number and its distance from source (separated by space)

```
Constraints:
```

```
1 <= T <= 10

2 <= V, E <= 10^3

Sample Input 1 :

1

4 4

0 1 3

0 3 5

1 2 1

2 3 8

Sample Output 1 :

0 0

1 3

2 4
```

```
    #include <iostream>
    #include <climits>
    using namespace std;
    int findMinVertex(int *distance, bool *visited, int n)
    {
    int minVertex = -1;
    for (int i = 0; i < n; i++)</li>
    {
    if (!visited[i] && (minVertex == -1 || distance[i] < distance[minVertex]))</li>
    {
    minVertex = i;
```

```
12.
         }
13.
      }
14.
      return minVertex;
15.}
16. void dijkstra(int **edges, int n)
17. {
18.
      int *distance = new int[n];
19.
      bool *visited = new bool[n];
20.
      for (int i = 0; i < n; i++)
21.
22.
         visited[i] = false;
23.
         distance[i] = INT_MAX;
24.
      }
25.
      distance[0] = 0; // 0 is considered as the starting node.
26.
      for (int i = 0; i < n - 1; i++)
27.
     {
28.
         // Find min vertex
29.
         int minVertex = findMinVertex(distance, visited, n);
30.
         visited[minVertex] = true;
31.
         // Explore unvisited neighbors
32.
         for (int j = 0; j < n; j++)
33.
34.
            if (edges[minVertex][j] != 0 && !visited[j])
35.
36.
              // distance of any node will be the current node's distance + the weight
37.
              // of the edge between them
38.
              int dist = distance[minVertex] + edges[minVertex][j];
39.
              if (dist < distance[j])</pre>
40.
              { // If required, then updated.
41.
                 distance[j] = dist;
42.
              }
43.
           }
44.
         }
45.
      // Final output of distance of each node with respect to 0
46.
47.
      for (int i = 0; i < n; i++)
48.
      {
49.
         cout << i << " " << distance[i] << endl;
50.
      }
51.}
52. int main()
53. {
54.
      int t;
<del>55</del>.
      cin >> t;
```

```
56.
      while (t--)
57. {
58.
         int n;
59.
         int e;
60.
         cin >> n >> e;
61.
         int **edges = new int *[n];
62.
         for (int i = 0; i < n; i++)
63.
64.
            edges[i] = new int[n];
65.
            for (int j = 0; j < n; j++)
66.
67.
              edges[i][j] = 0;
68.
           }
69.
70.
         for (int i = 0; i < e; i++)
71.
72.
            int f, s, weight;
73.
            cin >> f >> s >> weight;
74.
            edges[f][s] = weight;
75.
            edges[s][f] = weight;
76.
77.
         dijkstra(edges, n);
         for (int i = 0; i < n; i++)
78.
79.
80.
            delete[] edges[i];
81.
82.
         delete[] edges;
83.
      }
84.
      return 0;
85.}
```

4-Tut: Bellman-Ford Algorithm

Send Feedback

you are given a weighted directed graph G with n vertices and m edges, and two specified vertex src and des. You want to find the length of shortest paths from vertex src to des. The graph may contain the edges with negative weight.

Input Format:

First line of input will contain T(number of test case), each test case follows as.

Line1: contain two space-separated integers N and M denoting the number of vertex and number of edges in graph respectively.

Line2: contain two space-separated integers src, des.

Next M line will contain three space-separated integers a, b, wt representing the edge from a to b with weight wt.

Output Format:

For each test case print the distance of des from src in new line. Note: In case of no path is found print (10 ^ 9) in that case.

Constraints:

```
1 <= T <= 100

1 <= N <= 200

1 <= M <= min(800, N*(N-1))

1 <= a,b <= N

-10^5 <= wt <= 10^5
```

Sample Input:

Sample output:

1. #include <bits/stdc++.h>

-2

```
2. using namespace std;
3. struct Edge
4. {
5.
      int src, dest, weight;
6. };
7. struct Graph
8. {
9.
      int V, E;
10.
      struct Edge *edge;
11. };
12. struct Graph *createGraph(int V, int E)
13. {
14. struct Graph *graph = new Graph;
15.
     graph->V = V;
16.
     graph->E=E;
17.
      graph->edge = new Edge[E];
18.
      return graph;
20. void printAns(int dist[], int n, int src, int dest)
21. {
22.
     for (int i = 1; i \le n; ++i)
        if (i == dest)
23.
```

```
24.
            if (dist[i] == INT MAX)
25.
26.
              cout << "100000000" << endl;
27.
28.
            else
29.
30.
              cout << dist[i] << endl;
31.
32.}
33. void BellmanFord(struct Graph *graph, int src, int dest)
35.
      int V = graph->V;
36.
      int E = graph->E;
37.
      int dist[V + 1];
38.
      for (int i = 0; i \le V; i++)
39.
         dist[i] = INT_MAX;
40.
      dist[src] = 0;
41.
      for (int i = 1; i \le V - 1; i++)
42.
43.
         for (int j = 0; j < E; j++)
44.
45.
            int u = graph->edge[j].src;
            int v = graph->edge[j].dest;
46.
47.
            int weight = graph->edge[i].weight;
48.
            if (dist[u] != INT_MAX && dist[u] + weight < dist[v])</pre>
49.
              dist[v] = dist[u] + weight;
50.
         }
51.
<del>5</del>2.
      for (int i = 0; i < E; i++)
53.
         int u = graph->edge[i].src;
54.
55.
         int v = graph->edge[i].dest;
56.
         int weight = graph->edge[i].weight;
57.
         if (dist[u] != INT_MAX && dist[u] + weight < dist[v])</pre>
58.
         {
59.
            cout << "100000000" << endl;
60.
            return; // If negative cycle is detected, simply return
61.
         }
62.
63.
      printAns(dist, V, src, dest);
64.
      return;
65.}
66. int main()
67. {
```

```
68.
      int t:
69.
      cin >> t;
70.
      while (t--)
71.
72.
         int V, E;
73.
        int src, dest;
74.
         cin >> V;
75.
         cin >> E;
76.
         cin >> src:
77.
         cin >> dest;
78.
         struct Graph *graph = createGraph(V, E);
79.
         for (int i = 0; i < E; i++)
80.
81.
           int u, v, w;
82.
           cin >> u >> v >> w;
83.
           graph->edge[i].src = u;
84.
           graph->edge[i].dest = v;
85.
           graph->edge[i].weight = w;
86.
         }
87.
         BellmanFord(graph, src, dest);
88.
     }
89.
90.
      return 0;
91.}
```

5-Tut : Floyd-Warshall Algorithm

Send Feedback

You are given an undirected weighted graph G with n vertices. And Q queries, each query consists of two integers a and b and you have print the distance of shortest path between a and b.

Note: If there is no path between a and b print 10⁹

Input Format:

First line of Input will contain T(number of test cases), each test case follows as.

Line1: contains two space-separated integers N and M denoting the number of vertex and edge in graph. Next M line contain three space-separated integers a, b, c denoting the edge between a and b with weight c.

Next line will contain Q (number of queries)

Next Q lines will contain two space-separated integers a and b.

Output Format:

For each query of each test case print the answer in a newline.

Constraints:

```
1 <= T <= 50

1 <= N <= 100

1 <= M <= 10^4

1 <= Q <= 10^4
```

```
1 <= wt <= 10^5 (for each edge)
Note: Graph may contain multiple edges.
Sample Input:
1
36
3 1 4
1 3 17
232
137
3 2 11
2 3 15
11
22
23
Sample output:
0
2
   1. #include <bits/stdc++.h>
   2. using namespace std;
   3. int INF = 1e9;
   4. int main()
   5. {
   6.
   7.
          int t;
   8.
          cin >> t;
   9.
          while (t--)
   10.
         {
   11.
            int n, m;
   12.
   13.
            cin >> n;
   14.
   15.
            cin >> m;
   16.
            int mat[n + 1][n + 1];
   17.
            for (int i = 0; i \le n; i++)
   18.
               for (int j = 0; j \le n; j++)
   19.
   20.
   21.
                 mat[i][j] = INF;
   22.
                 if (i == j)
   23.
```

mat[i][j] = 0;

24.

```
25.
               }
26.
            }
27.
28.
         for (int i = 0; i < m; i++)
29.
30.
            int a, b, c;
31.
            cin >> a >> b >> c;
32.
            if (mat[a][b] < c)
33.
34.
               continue;
35.
36.
            else
37.
38.
               mat[a][b] = c;
39.
               mat[b][a] = c;
40.
            }
41.
42.
         int i, j, k;
43.
         for (k = 1; k \le n; k++)
44.
45.
            for (i = 1; i \le n; i++)
46.
47.
               for (j = 1; j \le n; j++)
48.
                  if (mat[i][j] > (mat[i][k] + mat[k][j]) && (mat[k][j] != INF && mat[i][k] != INF))
49.
                    mat[i][j] = mat[i][k] + mat[k][j];
50.
51.
               }
52.
            }
53.
         }
54.
         int q;
55.
         cin >> q;
56.
         while (q--)
57.
58.
            int aa;
59.
            int bb;
60.
            cin >> aa >> bb;
61.
62.
            if (aa == bb)
63.
64.
               cout << 0 << endl;
65.
66.
            else
67.
68.
               cout << mat[aa][bb] << endl;</pre>
```

```
69. }
70. }
71. }
72. }
```

6-Bonus: Disjoint Set Union

```
1. #include <bits/stdc++.h>
2. using namespace std;
3.
4. class DSNode
5. {
6. public:
7.
     int data;
8.
     DSNode *parent;
9.
     int rank;
10. };
11.
12. class DisjointSet
13. {
14. private:
15.
     map<int, DSNode *> hash;
16.
17.
     DSNode *searchInSetHelper(DSNode *node)
18. {
19.
20.
        if (node == node->parent)
21.
       {
          return node;
22.
23.
24.
        node->parent = searchInSetHelper(node->parent);
25.
        return node->parent;
26. }
27.
28. public:
29. void initializeSet(int data)
30. {
31.
       DSNode *node = new DSNode();
32.
       node->data = data;
33.
       node->parent = node;
34.
       node->rank = 0;
35.
        hash[data] = node;
36. }
```

```
37.
38.
     void Union(int data1, int data2)
39.
     {
40.
41.
        DSNode *node1 = hash[data1];
        DSNode *node2 = hash[data2];
42.
43.
44.
        DSNode *parent1 = searchInSetHelper(node1);
45.
        DSNode *parent2 = searchInSetHelper(node2);
46.
47.
        if (parent1->data == parent2->data)
48.
        {
49.
          return;
50.
51.
52.
        if (parent1->rank >= parent2->rank)
53.
54.
           if (parent1->rank == parent2->rank)
55.
56.
             parent1->rank = parent1->rank + 1;
57.
58.
           parent2->parent = parent1;
59.
        }
60.
        else
61.
62.
           parent1->parent = parent2;
63.
        }
64.
     }
65.
66.
     int searchInSet(int data)
67.
68.
        return searchInSetHelper(hash[data])->data;
69. }
70.};
71.
72. int main()
73. {
74.
75.
     DisjointSet ds;
76.
77.
     ds.initializeSet(0);
78.
     ds.initializeSet(1);
79.
     ds.initializeSet(2);
80.
     ds.initializeSet(3);
```

```
81.
      ds.initializeSet(4);
82.
      ds.initializeSet(5);
83.
      ds.initializeSet(6);
84.
85.
      ds.Union(0, 1);
86.
      ds.Union(1, 2);
87.
      ds.Union(3, 4);
88.
      ds.Union(2, 4);
89.
      ds.Union(5, 6);
90.
      ds.Union(4, 6);
91.
      ds.Union(0, 1);
92.
      cout << ds.searchInSet(0) << endl;</pre>
93.
94.
      cout << ds.searchInSet(1) << endl;</pre>
95.
      cout << ds.searchInSet(2) << endl;</pre>
96.
      cout << ds.searchInSet(3) << endl;</pre>
97.
      cout << ds.searchInSet(4) << endl;</pre>
98.
      cout << ds.searchInSet(5) << endl;</pre>
99.
      cout << ds.searchInSet(6) << endl;</pre>
100.
101.
          return 0;
102.
       }
```