GRU AND LSTM CODE

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import numpy as np
import tensorflow as tf
from tensorflow.keras.datasets import imdb
from tensorflow.keras.preprocessing.sequence import pad_sequences
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Embedding, GRU, Dense
np.random.seed(0)
tf.random.set_seed(0)
num_words = 10000
max_sequence_length = 100
(x_train, y_train), (x_test, y_test) = imdb.load_data(num_words = num_words)
x_train = pad_sequences(x_train, maxlen = max_sequence_length)
x_test = pad_sequences(x_test, maxlen = max_sequence_length)
model = Sequential()
model.add(Embedding(input_dim = num_words, output_dim = 32, input_lenght =
max sequence length)
model.add(GRU(units = 32))
model.add(Dense(units = 1, activation = 'sigmoid')
model.compile(optimizer = 'adam', loss='binary crossentropy', metrics = ['accuracy'])
model.fit(x_train, batch_size = 64, epochs = 7, validation_split = 0.2)
loss, accuracy = model.evaluate(x_test, y_test)
print(f"Test loss: {loss:.4f}, Test accuracy: {accuracy:.4f}")
```

LSTM CODE:

```
import numpy as np
import tensorflow as tf
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Embedding, LSTM, Dense
import matplotlib.pyplot as plt
def generate_time_series_data(num_points):
       t = np.linspace(0, 10, num_points)
        data = np.sin(t) + 0.1 * np.random.randn(num_points)
        return data
num_points = 1000
data = generate_time_series_data(num_points)
sequence_points = 10
X = []
Y = []
for i in range (num_points - sequence_length):
       X.append(data[i: i+sequence_length])
        y.append(data[i+sequence_length])
X = np.array(X).reshape(-1, sequence_length, 1)
y = np.array(y)
train_ratio = 0.8
train_size = int(train_ratio * len(X))
X_train, X_test = X[: train_size], X[train_size:]
y_train, y_test = y[: train_size], y[train_size:]
model = Sequential()
```

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model.add(LSTM(units = 50, input_size = (sequence_length, 1)))
model.add(Dense(units = 1))
model.compile(optimizer = 'adam', loss = 'mean_squared_error')
history = model.fit(X_train, y_train, batch_size = 32, epochs = 15, validation_split = 0.2)
loss = model.evaluate(X_test, y_test)
print(f"test loss: {loss:.4f}")
predictions = model.predict(X_test)
plt.figure(figsize = (12, 6))
plt.plot(y_test, label = 'Actual')
plt.plot(predictions, label = 'Predicted')
plt.legend()
plt.title('actual and predicted')
plt.xlabel('time')
plt.ylabel('value')
plt.show()
```