# SIDDHARTH SAHA

Blog ⋄ ♣ Homepage ⋄ in LinkedIn ⋄ ☑ Mail ⋄ ♠ trunc8  EDUCATION				
Graduation	IIT Bombay	Indian Institute of Technology Bombay	2017 - 2021	9.43/10.00
Undergraduate Degrees: B.Tech. with Honors in Mechanical Engineering, IIT Bombay Minor in Computer Science and Engineering, IIT Bombay				
	S	CHOLASTIC ACHIEVEMENTS		
<ul> <li>Ranked top 5 in</li> <li>Conferred AP g</li> <li>Endowed with t</li> </ul>	n batch of 150 students grade (3/188 students he Economic Times	highest award for excellence in technical as on merit of GPA   Secured <b>perfect 10.0</b> ) in Statistical Machine Learning course for <b>Campus Star Award</b> from over 49,000 15 students from India) by <b>Japan Science</b>	GPA in $7^{th}$ & $8^t$ or exceptional per candidates across	h semesters ['21] rformance ['20] s India ['20]
	PROFESSIONAL E	XPERIENCE & INTERNATIONAL E.	XCHANGE	
	, Structuring Analyst insights for the upside	Bengaluru es & downsides of structuring ideas vis-a-v		al 2021 - Present y methodologies
JdeRobot develops • Built the RADI	s framework based on 1-4.0 (Robotics Academ	bot, Student Developer   Final Report Django, Docker & ROS to simplify learning y Docker Image) for ROS2 Foxy, and Vavigator   Extended pick-and-delivery exercises.	ng robotics & com NC-based RViz2	web template
• Innovated and in		r Analyst   Bengaluru structuring ideas for mortgage-backed se 2% profits by optimizing cash-flows through	ecurities to <b>maxi</b>	_
	versity, Special Auditoing research in the C	ing Student   Japan ybernetics Laboratory under the Sakur	ra Research Exche	Jun 2019 ange Programme
		Competitions		
Team Leader in M	aze-solving challenge t	se Challenge   Source & Demo o program an autonomous bot simulated a ter for optimal path & omni-wheel based		Dec 2020 steering latency
Winner   Off-Tr	rack Bot   Innerve '20	0, Delhi		Nov 2020
		produce given pattern on ground, minimize $\mathbf{ion}$ in $\mathbf{C}$ to sharply prune number of cues	~	-
		Championship '21, IIT Bombay hProg using the <b>GLPK Optimizer</b>   Sol <sup>*</sup>	ved machine lear	Feb 2021 ning problems
Team Leader of IIT	Bombay in Autonome	<b>Drone</b>   $9^{th}$ Inter IIT Tech Meet, Source ous Navigation challenge across complex state implemented navigation pipeline with thr	$atic\ environments$	

across India | Designed & implemented navigation pipeline with three-layered intelligence algorithms

RoboCon, Team IIT Bombay | ABU RoboCon '19 Ulaanbaatar, Mongolia Jan 2019 - Apr 2019 Competition to construct a manual bot with throwing capability & an autonomous walking bot

ullet Bagged ullet position among 50+ national teams in stage-1 | Designed Solidworks model of robotic gripper arm

## KEY PROJECTS

Mapping Regions of Dynamic Activity & Building Dynamic-free 3D Occupancy Maps | Demo Bachelor's Thesis — Guides: Prof. Leena Vacchani, Prof. Abhishek Gupta Jun 2020 - Jul 2021

- Proved the occupancy & dynamic activity probabilities in an octree map to form a field in the range (0,1)
- Designed & implemented novel clustering algorithm in ROS OctoMap to reject nodes with high dynamic activity

Quadruped Robot | RoboCup Rescue League Challenge

Dec 2019 - May 2021

Team Leader of two-tiered team with 15 members, overseeing a technical budget of over 10 lakhs INR (~14K USD)

- Explored impedance control to create virtual leg compliance | Simulated gait trajectories inside Gazebo
- Implemented sensor fusion of MPU6050 data with Intel RealSense D435 PointCloud2 data to demonstrate SLAM

# F1/10<sup>th</sup> — Autonomous Grand Prix | IROS '20, Las Vegas

International autonomous racing contest with standardized hardware simulated in ROS/Gazebo

- Used Bernstein polynomial based local trajectory planner and MPC for Ackermann steering in 4-membered team
- Attained global optimal path using OSQP solver | Implemented obstacle detection | Composed Docker submission

## Two-wheeled Self-Balancing Bot | Documentation & Demo

Aug 2020 - Nov 2020

• Stabilized Arduino bot using PD control and applied complementary filter on gyroscope & accelerometer input

# Wifi De-auth Attacker

Oct 2020

• Programmed ESP8266 (Wi-Fi chip) to send de-authentication frames, exploiting vulnerability in IEEE 802.11

#### Sudoku Solver Using Block Printing | Source & Demo

Apr 2018 - May 2018

• Implemented a Raspbian based machine to physically imprint digits into any given unsolved sudoku grid

• Leveraged scikit-learn & invoked support vector machines for recognition of handwritten digits in the sudoku

#### Gyro Brick Breaker

• Led 5-membered team to develop a hand-gesture controlled brick-breaking game coded in Processing IDE More projects

#### Positions Of Responsibility

Teaching Assistant | Student Mentorship Program, IIT Bombay

Apr-May 2018 / Jan-Apr 2019

- Physical Chemistry: Only student from freshmen year appointed to guide class of 15 students in tutorials
- Electricity & Magnetism: Conducted tutorial sessions for 52 students focusing on the academically weak students

Summer of Science Mentor | Maths and Physics Club, IIT Bombay

Apr 2020 - Jun 2020

• Guided 4 mentees to proficiency in Data Structures & Algorithms with conceptual aid and meticulous roadmap

Convener | Electronics and Robotics Club, IIT Bombay

Apr 2018 - Mar 2019

Part of a two-tiered team of 70 members constituting the Institute Technical Council of IIT Bombay

Organized bootcamps and delivered talks on Arduino and Image Processing, attended by 200+ enthusiasts

#### COMMUNITY SERVICE & VOLUNTEERING

• Open-source contributor at JdeRobot, a toolkit for developing robotics applications

Mar 2021 - Present

Mentoring 4 female undergraduates from low-income backgrounds under iWE (Indian Women in Engineering), an initiative by Goldman Sachs

Sep 2021 - Present

Tutored a high-school junior under Abhyasika, a student initiative at IIT Bombay for the upliftment of economically disadvantaged children

Nov 2018 - May 2019

• Facilitated the Juhu Beach Cleanup Drive under IIT Bombay E-Cell's Swacch initiative

Oct 2017

#### TECHNICAL SKILLS

Programming & Scripting

Python, C, C++, Java, R, Javascript, x10, Bash, Sed, Awk, Perl, RegEx Git, Vim, Docker, OpenCV, PyTorch, TensorFlow, Tesseract-OCR, LATEX

Frameworks Optimization

GNU MathProg, GLPK, Gurobi, PuLP, Ipopt, OSQP

Robotics tools

ROS1, ROS2, Gazebo, Webots, MRPT, Pinochhio, TSID, Crocoddyl

Controllers & Modules Arduino, Raspberry Pi, Tiva C, NodeMCU, MPU6050, Intel RealSense D435

#### KEY COURSES

Computer Science Computer Vision, Reinforcement Learning, Data Structures and Algorithms, Design and

Analysis of Algorithms, Digital Image Processing

Robotics

Advanced Topics in Mobile Robotics, Design of Mechatronic Systems, Microprocessors & Automatic Control, Kinematics & Dynamics of Machines, Machine Design, Robotics

Optimization Certifications Optimization from Fundamentals, Optimization for Engineering Design, Operations Research

Advanced Methods for Planning & Control of Legged Robots, ROS for Beginners II: Localization, Navigation & SLAM, Using GPUs to Scale & Speed-up Deep Learning

### EXTRA CURRICULAR ACTIVITIES

Competition

• First runners-up in Aerial Path Planning GC, IIT Bombay (Source)

['21]

Public Speaking • Participated in Model United Nations by WeSpeak, IIT Bombay ['17]

• Received Special Mention among 35 participants in English Debate, IIT Bombay ['17]

**Journalism** Sports

• Curated article in Mechanical Media Newsletter with a reach of 700+ students

• Completed inter-hostel Crossy General Championship & the Cyclothon by TechFest ['17]

Leadership

• Headed 150+ students as House Captain in 10<sup>th</sup> & Vice-Captain in 9<sup>th</sup> grade ['14,'15]