

SIDDHARTH SAHA

📖 [Blog](#) ◊ 🏠 [Homepage](#) ◊ [in LinkedIn](#) ◊ ✉ [Mail](#) ◊ 🌐 [trunc8](#)

EDUCATION

Examination	University	Institute	Year	GPA
Graduation	IIT Bombay	Indian Institute of Technology Bombay	2017 - 2021	9.43/10.00

Undergraduate Degrees: B.Tech. with Honors in Mechanical Engineering, IIT Bombay
Minor in Computer Science and Engineering, IIT Bombay

SCHOLASTIC ACHIEVEMENTS

- Bagged the **Technical Citation**, 2nd highest award for excellence in technical activities at IIT Bombay [’21]
- Ranked **top 5** in batch of 150 students on merit of GPA | Secured **perfect 10.0** GPA in 7th & 8th semesters [’21]
- Conferred **AP grade** (3/188 students) in Statistical Machine Learning course for exceptional performance [’20]
- Endowed with the **Economic Times Campus Star Award** from over 49,000 candidates across India [’20]
- Awarded the SSP scholarship (among 15 students from India) by **Japan Science & Technology Agency** [’19]

PROFESSIONAL EXPERIENCE & INTERNATIONAL EXCHANGE

Goldman Sachs, Structuring Analyst | Bengaluru Jul 2021 - Present

- Deriving critical insights for the upsides & downsides of structuring ideas vis-a-vis Rating Agency methodologies

Google Summer of Code – JdeRobot, Student Developer | [Final Report](#) Jun 2021 - Aug 2021

JdeRobot develops framework based on ROS, Docker & Django to simplify learning robotics & computer vision

- Built the **RADI-4.0** (Robotics Academy Docker Image) for **ROS2 Foxy**, and VNC-based RViz2 web template
- Implemented **BT (Behavior Tree)** Navigator | Extended pick-and-delivery exercise to ROS2 web-based template

Goldman Sachs, Quantitative Summer Analyst | Bengaluru May 2020 - Jun 2020

- Innovated and implemented **payment structuring** ideas for mortgage-backed securities to **maximize arbitrage**
- Achieved **sharp improvement** of 1.62% profits by optimizing cash-flows through different derivative instruments

Hiroshima University, Special Auditing Student | Japan Jun 2019

- Assimilated ongoing research in the **Cybernetics Laboratory** under the *Sakura Research Exchange Programme*

COMPETITIONS

Winner | International Micromouse Challenge | [Source](#) & [Demo](#) Dec 2020

Team Leader in Maze-solving challenge to program an autonomous bot simulated in ROS/Gazebo

- Implemented *online breadth-first planner* for optimal path & **omni-wheel** based drive to reduce steering latency

Winner | Off-Track Bot | Innervest ’20, Delhi Nov 2020

Autonomous bot simulated in Webots to produce given pattern on ground, minimizing number of blocks kept as cues

- Innovated vision-based **object detection in C** to sharply prune number of cues required by navigation algorithm

Winner | Operations GC | General Championship ’21, IIT Bombay, [Source](#) Feb 2021

- Devised optimization solutions in MathProg using the **GLPK Optimizer** | Solved machine learning problems

Vision Based Obstacle Avoidance Drone | 9th Inter IIT Tech Meet, [Source](#) Mar 2021

Team Leader of IIT Bombay in Autonomous Navigation challenge across complex static environments in ROS/Gazebo

- **Ranked 6th** across India | Designed & implemented navigation pipeline with three-layered intelligence algorithms

RoboCon, Team IIT Bombay | ABU RoboCon ’19 Ulaanbaatar, Mongolia Jan 2019 - Apr 2019

Competition to construct a manual bot with throwing capability & an autonomous walking bot

- Bagged **9th position** among 50+ national teams in stage-1 | Designed Solidworks model of **robotic gripper arm**

KEY PROJECTS

Mapping Regions of Dynamic Activity & Building Dynamic-free 3D Occupancy Maps | [Demo](#)

Bachelor’s Thesis — Guides: Prof. Leena Vacchani, Prof. Abhishek Gupta

Jun 2020 - Jul 2021

- Proved the occupancy & dynamic activity probabilities in an octree map to **form a field** in the range (0,1)
- Designed & implemented novel clustering algorithm in **ROS OctoMap** to reject nodes with high dynamic activity

Quadruped Robot | RoboCup Rescue League Challenge

Dec 2019 - May 2021

Team Leader of two-tiered team with 15 members, overseeing a technical budget of over 10 lakhs INR (~14K USD)

- Explored **impedance control** to create virtual leg compliance | Simulated **gait trajectories** inside Gazebo
- Implemented **sensor fusion** of *MPU6050* with *Intel RealSense D435* PointCloud2 data to demonstrate SLAM

F1/10th — Autonomous Grand Prix IROS '20, Las Vegas	Oct 2020
<i>International autonomous racing contest with standardized hardware simulated in ROS/Gazebo</i>	
<ul style="list-style-type: none"> Used Bernstein polynomial based local trajectory planner & MPC for Ackermann steering in 4-membered team Attained global optimal path using OSQP solver Implemented obstacle detection Composed Docker submission 	
Two-wheeled Self-Balancing Bot Documentation & Demo	Aug 2020 - Nov 2020
<ul style="list-style-type: none"> Stabilized Arduino bot using PD control and applied complementary filter on gyroscope & accelerometer output 	
Wifi De-auth Attacker	Mar 2019
<ul style="list-style-type: none"> Programmed <i>ESP8266</i> (Wi-Fi chip) to send de-authentication frames, exploiting vulnerability in IEEE 802.11 	
Sudoku Solver Using Block Printing Source & Demo	Apr 2018 - May 2018
<ul style="list-style-type: none"> Implemented a <i>Raspbian</i> based machine to physically imprint digits into any given unsolved sudoku grid Leveraged <i>scikit-learn</i> & invoked support vector machines for recognition of handwritten digits in the sudoku 	
Gyro Brick Breaker	Jul 2018
<ul style="list-style-type: none"> Led 5-membered team to develop a hand-gesture controlled brick-breaking game coded in Processing IDE 	
More projects	

POSITIONS OF RESPONSIBILITY

Teaching Assistant Student Mentorship Program, IIT Bombay	Apr-May 2018 / Jan-Apr 2019
<ul style="list-style-type: none"> <i>Physical Chemistry</i>: Only student from freshmen year appointed to guide class of 15 students in tutorials <i>Electricity & Magnetism</i>: Conducted tutorial sessions for 52 students focusing on the academically weak students 	
Summer of Science Mentor Maths and Physics Club, IIT Bombay	Apr 2020 - Jun 2020
<ul style="list-style-type: none"> Guided 4 mentees to proficiency in <i>Data Structures & Algorithms</i> with conceptual aid and meticulous roadmap 	
Convener Electronics and Robotics Club, IIT Bombay	Apr 2018 - Mar 2019
<i>Part of a two-tiered team of 70 members constituting the Institute Technical Council of IIT Bombay</i>	
<ul style="list-style-type: none"> Organized bootcamps and delivered talks on Arduino and Image Processing, attended by 200+ enthusiasts 	

COMMUNITY SERVICE & VOLUNTEERING

Open-source contributor at JdeRobot, a toolkit for developing robotics applications	Mar 2021 - Present
Mentoring 4 female undergraduates from low-income backgrounds under iWE (Indian Women in Engineering), an initiative by Goldman Sachs	Sep 2021 - Present
Tutored a high-school junior under Abhyasika , a student initiative at IIT Bombay for the upliftment of economically disadvantaged children	Nov 2018 - May 2019
Facilitated the Juhu Beach Cleanup Drive under IIT Bombay E-Cell's Swacch initiative	Oct 2017

TECHNICAL SKILLS

Programming & Scripting	Python, C, C++, Java, R, Javascript, x10, Bash, Sed, Awk, Perl, RegEx
Frameworks	Git, Vim, Docker, OpenCV, PyTorch, TensorFlow, Tesseract-OCR, \LaTeX
Optimization	GNU MathProg, GLPK, Gurobi, PuLP, Ipopt, OSQP
Robotics tools	ROS1, ROS2, Gazebo, Webots, MRPT, Pinocchio, TSID, Crocoddyl
Controllers & Modules	Arduino, Raspberry Pi, Tiva C, NodeMCU, MPU6050, Intel RealSense D435

KEY COURSES

Computer Science	Computer Vision, Reinforcement Learning, Data Structures and Algorithms, Design and Analysis of Algorithms, Digital Image Processing
Robotics	Advanced Topics in Mobile Robotics, Design of Mechatronic Systems, Microprocessors & Automatic Control, Kinematics & Dynamics of Machines, Machine Design, Robotics
Optimization	Optimization from Fundamentals, Optimization for Engineering Design, Operations Research
Certifications	Advanced Methods for Planning & Control of Legged Robots, ROS: Localization, Navigation & SLAM, Using GPUs to Scale & Speed-up Deep Learning

EXTRA CURRICULAR ACTIVITIES

Competition	<ul style="list-style-type: none"> First runners-up in Aerial Path Planning GC, IIT Bombay (Source) 	[’21]
Public Speaking	<ul style="list-style-type: none"> Participated in Model United Nations by WeSpeak, IIT Bombay Received Special Mention among 35 participants in English Debate, IIT Bombay 	[’17]
Journalism	<ul style="list-style-type: none"> Curated article in Mechanical Media Newsletter with a reach of 700+ students 	[’17]
Sports	<ul style="list-style-type: none"> Completed inter-hostel Crossy General Championship & the Cyclothon by TechFest 	[’17]
Leadership	<ul style="list-style-type: none"> Headed 150+ students as House Captain in 10th & Vice-Captain in 9th grade 	[’14, ’15]