SIDDHARTH SAHA

Blog ⋄ ♣ Homepage ⋄ in LinkedIn ⋄ ➤ Mail ⋄ ♠ trunc8 EDUCATION				
Graduation	IIT Bombay	Indian Institute of Technology Bombay	2017 - 2021	9.43/10.00
Undergraduate De	\cup	Honors in Mechanical Engineering, IIT Bo puter Science and Engineering, IIT Bomb		
	S	CHOLASTIC ACHIEVEMENTS		
Ranked top 5 inConferred AP gEndowed with t	n batch of 150 students grade (3/188 students he Economic Times	highest award for excellence in technical as on merit of GPA Secured perfect 10.0) in Statistical Machine Learning course for Campus Star Award from over 49,000 15 students from India) by Japan Science	GPA in 7^{th} & 8^{th} or exceptional per candidates across	semesters ['21] formance ['20] India ['20]
	PROFESSIONAL E	XPERIENCE & INTERNATIONAL E	XCHANGE	
	, Structuring Analyst insights into the upsid	Bengaluru les & downsides of structuring ideas vis-a-		l 2021 - Present methodologies
JdeRobot develops • Built the RADI-	s framework based on 14.4.0 (Robotics Academ	bot, Student Developer Final Report ROS, Docker & Django to simplify learning Docker Image) for ROS2 Foxy, and Vavigator Extended pick-and-delivery exercises.	g robotics & com NC-based RViz2	web template
• Innovated and in		r Analyst Bengaluru structuring ideas for mortgage-backed se 2% profits by optimizing cash-flows through	ecurities to maxi r	_
Hiroshima Univ	versity, Special Audit	- , - , -		Jun 2019
		Competitions		
Team Leader in M	aze-solving challenge t	se Challenge Source & Demo o program an autonomous bot simulated a ter for optimal path & omni-wheel based		Dec 2020 steering latency
Autonomous bot s		0, Delhi produce given pattern on ground, minimization in C to sharply prune number of cues	~	-
	•	Championship '21, IIT Bombay, Source hProg using the GLPK Optimizer Sol	ved machine learn	Feb 2021 ning challenges
		Drone 9^{th} Inter IIT Tech Meet, Source as Navigation challenge across complex, sta		Mar 2021 in ROS/Gazebo

• Ranked 6th across India | Designed & implemented navigation pipeline with three-layered intelligence algorithms

RoboCon, Team IIT Bombay | ABU RoboCon '19 Ulaanbaatar, Mongolia Oct 2018 - Apr 2019

Competition to construct a manual bot with throwing capability & an autonomous walking bot

• Bagged 9th position among 50+ national teams in stage-1 | Designed Solidworks model of robotic gripper arm

KEY PROJECTS

Mapping Regions of Dynamic Activity & Building Dynamic-free 3D Occupancy Maps | Demo Bachelor's Thesis — Guides: Prof. Leena Vacchani, Prof. Abhishek Gupta Jun 2020 - Jul 2021

- Proved the occupancy & dynamic activity probabilities in an octree map to form a field in the range (0,1)
- Designed & implemented novel clustering algorithm in ROS OctoMap to reject nodes with high dynamic activity

Quadruped Robot | RoboCup Rescue League Challenge

Dec 2019 - May 2021

Founding member & Team Lead of two-tiered team with 15 members, overseeing technical budget of ~14K USD

- Explored impedance control to create virtual leg compliance | Simulated gait trajectories inside Gazebo
- Generated foot trajectory by modulating length and height of control points for a 11-order Bézier curve
- Implemented sensor fusion of MPU6050 with Intel RealSense D435 PointCloud2 data to demonstrate SLAM

F1/10th — Autonomous Grand Prix | IROS '20, Las Vegas

Oct 2020

International autonomous racing contest with standardized hardware simulated in ROS/Gazebo

- Used Bernstein polynomial based local trajectory planner & MPC for Ackermann steering in 4-membered team
- Attained global optimal path using OSQP solver | Implemented obstacle detection | Composed Docker submission

Two-wheeled Self-Balancing Bot | Documentation & Demo

Aug 2020 - Nov 2020

• Stabilized Arduino bot using PD control and applied complementary filter on gyroscope & accelerometer output

Wifi De-auth Attacker

Mar 2019

• Programmed ESP8266 (Wi-Fi chip) to send de-authentication frames, exploiting vulnerability in IEEE 802.11

Sudoku Solver Using Block Printing | Source & Demo

Apr 2018 - May 2018

- Implemented a Raspbian based machine to physically imprint digits into any given unsolved sudoku grid
- Leveraged scikit-learn & invoked support vector machines for recognition of handwritten digits in the sudoku

Gyro Brick Breaker

Public Speaking

Journalism

Jul 2018

• Led 5-membered team to develop a hand-gesture controlled brick-breaking game coded in Processing IDE More projects...

Positions Of Responsibility

Teaching Assistant | Student Mentorship Program, IIT Bombay

Apr-May 2018 / Jan-Apr 2019

- Physical Chemistry: Only student from freshmen year appointed to guide class of 15 students in tutorials
- Electricity & Magnetism: Conducted tutorial sessions for 52 students focusing on the academically weak students

Summer of Science Mentor | Maths and Physics Club, IIT Bombay

Apr 2020 - Jun 2020

• Guided 4 mentees to proficiency in Data Structures & Algorithms with conceptual aid and meticulous roadmap

Convener | Electronics and Robotics Club, IIT Bombay

Apr 2018 - Mar 2019

Part of a two-tiered team of 70 members constituting the Institute Technical Council of IIT Bombay

• Organized bootcamps and delivered talks on Arduino and Image Processing, attended by 200+ enthusiasts

COMMUNITY SERVICE & VOLUNTEERING

- Open-source contributor at JdeRobot, a toolkit for developing robotics applications Mar 2021 - Present
- Mentoring 4 female undergraduates from low-income backgrounds under iWE (Indian Women in Engineering), an initiative by Goldman Sachs

Sep 2021 - Present

- Tutored a high-school junior under Abhyasika, a student initiative at IIT Bombay for Nov 2018 - May 2019 upliftment of economically disadvantaged children
- Facilitated Juhu Beach Cleanup Drive under IIT Bombay E-Cell's Swacch initiative

Oct 2017

['21]

TECHNICAL SKILLS

Programming & Scripting Frameworks

Python, C, C++, Java, R, x10, Bash, Sed, Awk, Perl, RegEx, CMake, SQLite Git, Vim, Docker, OpenCV, PyTorch, TensorFlow, Tesseract-OCR, LATEX

Optimization GNU MathProg, GLPK, Gurobi, PuLP, Ipopt, OSQP

ROS1, ROS2, Gazebo, Webots, MRPT, Pinochhio, TSID, Crocoddyl Robotics tools

Controllers & Modules Arduino, Raspberry Pi, Tiva C, NodeMCU, MPU6050, Intel RealSense D435

KEY COURSES

Computer Science Computer Vision, Reinforcement Learning, Data Structures and Algorithms, Design and

Analysis of Algorithms, Digital Image Processing, Statistical Machine Learning

Robotics Advanced Topics in Mobile Robotics, Design of Mechatronic Systems, Microprocessors &

Automatic Control, Kinematics & Dynamics of Machines, Machine Design, Robotics

Optimization Optimization from Fundamentals, Optimization for Engineering Design, Operations Research

Certifications Advanced Methods for Planning & Control of Legged Robots, ROS: Localization, Navigation

& SLAM, Using GPUs to Scale & Speed-up Deep Learning

EXTRA CURRICULAR ACTIVITIES

Competition • First runners-up in Aerial Path Planning GC, IIT Bombay (Source)

> • Participated in Model United Nations by WeSpeak, IIT Bombay ['17]

> • Received Special Mention among 35 participants in English Debate, IIT Bombay ['17]

• Curated article in Mechanical Media Newsletter with a reach of 700+ students

Sports • Completed inter-hostel Crossy General Championship and the Cyclothon by TechFest ['17]

• Headed 150+ students as House Captain in 10th & Vice-Captain in 9th grade ['14,'15] Leadership