# SIDDHARTH SAHA

Blog ♦ ♣ Homepage ♦ in LinkedIn ♦ ➡ Mail ♦ ♠ trunc8  EDUCATION				
Graduation	IIT Bombay	Indian Institute of Technology Bombay	2017 - 2021	9.43/10.00
Undergraduate De		Honors in Mechanical Engineering, IIT Bonputer Science and Engineering, IIT Bomb		
	S	CHOLASTIC ACHIEVEMENTS		
<ul> <li>Ranked top 5 in</li> <li>Conferred AP g</li> <li>Endowed with to</li> </ul>	n batch of 150 students ${f grade}$ (3/188 students the <b>Economic Times</b>	highest award for excellence in technical as on merit of GPA   Secured <b>perfect 10.0</b> ) in Statistical Machine Learning course for <b>Campus Star Award</b> from over 49,000 15 students from India) by <b>Japan Science</b>	GPA in $7^{th}$ & $8^t$ or exceptional per candidates across	h semesters ['21] formance ['20] s India ['20]
	PROFESSIONAL E	EXPERIENCE & INTERNATIONAL E	XCHANGE	
	s, Structuring Analyst l insights into the upsi	Bengaluru des & downsides of structuring ideas vis-a		d 2021 - Present methodologies
JdeRobot develops • Built the RADI	s framework based on -4.0 (Robotics Academ	bot, Student Developer   Final Report ROS, Docker & Django to simplify learning by Docker Image) for ROS2 Foxy, and Vavigator   Extended pick-and-delivery exer	ng robotics & com NC-based RViz2	web template
• Innovated and in	mplemented payment	er Analyst   Bengaluru structuring ideas for mortgage-backed sec 2% profits by optimizing cash-flows throug	ecurities to <b>maxi</b> i	_
	versity, Special Audit coing research in the C	ing Student   Japan ybernetics Laboratory under the Sakur	ra Research Exche	Jun 2019 ange Programme
Competitions				
Team Leader in M. • Implemented or	laze-solving challenge uline breadth-first plant	se Challenge   Source & Demo to program an autonomous bot simulated ner for optimal path & omni-wheel based	/	
Autonomous bot s		0, Delhi produce given pattern on ground, minimiz ion in C to sharply prune number of cues		-
• Devised optimiz	cation solutions in Mat	Championship '21, IIT Bombay, Source hProg using the <b>GLPK Optimizer</b>   Sol		Feb 2021 ning problems
		<b>Drone</b>   $9^{th}$ Inter IIT Tech Meet, Source ous Navigation challenge across complex, st.		$\begin{array}{c} {\rm Mar~2021} \\ \sin ROS/Gaze bo \end{array}$

• Ranked 6<sup>th</sup> across India | Designed & implemented navigation pipeline with three-layered intelligence algorithms

RoboCon, Team IIT Bombay | ABU RoboCon '19 Ulaanbaatar, Mongolia Jan 2019 - Apr 2019 Competition to construct a manual bot with throwing capability & an autonomous walking bot

• Bagged 9<sup>th</sup> position among 50+ national teams in stage-1 | Designed Solidworks model of robotic gripper arm

#### KEY PROJECTS

Mapping Regions of Dynamic Activity & Building Dynamic-free 3D Occupancy Maps | Demo Bachelor's Thesis — Guides: Prof. Leena Vacchani, Prof. Abhishek Gupta Jun 2020 - Jul 2021

- Proved the occupancy & dynamic activity probabilities in an octree map to form a field in the range (0,1)
- Designed & implemented novel clustering algorithm in ROS OctoMap to reject nodes with high dynamic activity

Quadruped Robot | RoboCup Rescue League Challenge

Dec 2019 - May 2021

Founding member & Team Leader of two-tiered team with 15 members, overseeing technical budget of ~14K USD

- Explored impedance control to create virtual leg compliance | Simulated gait trajectories inside Gazebo
- Generated foot trajectory by modulating length and height of control points for a 11-order Bézier curve
- Implemented sensor fusion of MPU6050 with Intel RealSense D435 PointCloud2 data to demonstrate SLAM

# F1/10<sup>th</sup> — Autonomous Grand Prix | IROS '20, Las Vegas

Oct 2020

International autonomous racing contest with standardized hardware simulated in ROS/Gazebo

- Used Bernstein polynomial based local trajectory planner & MPC for Ackermann steering in 4-membered team
- Attained global optimal path using OSQP solver | Implemented obstacle detection | Composed Docker submission

# Two-wheeled Self-Balancing Bot | Documentation & Demo

Aug 2020 - Nov 2020

• Stabilized Arduino bot using PD control and applied complementary filter on gyroscope & accelerometer output

#### Wifi De-auth Attacker

Mar 2019

• Programmed ESP8266 (Wi-Fi chip) to send de-authentication frames, exploiting vulnerability in IEEE 802.11

# Sudoku Solver Using Block Printing | Source & Demo

Apr 2018 - May 2018

- Implemented a Raspbian based machine to physically imprint digits into any given unsolved sudoku grid
- Leveraged scikit-learn & invoked support vector machines for recognition of handwritten digits in the sudoku

## Gyro Brick Breaker

Jul 2018

• Led 5-membered team to develop a hand-gesture controlled brick-breaking game coded in Processing IDE More projects...

#### Positions Of Responsibility

Teaching Assistant | Student Mentorship Program, IIT Bombay

Apr-May 2018 / Jan-Apr 2019

- Physical Chemistry: Only student from freshmen year appointed to guide class of 15 students in tutorials
- Electricity & Magnetism: Conducted tutorial sessions for 52 students focusing on the academically weak students

Summer of Science Mentor | Maths and Physics Club, IIT Bombay

Apr 2020 - Jun 2020

• Guided 4 mentees to proficiency in Data Structures & Algorithms with conceptual aid and meticulous roadmap

Convener | Electronics and Robotics Club, IIT Bombay

Apr 2018 - Mar 2019

Part of a two-tiered team of 70 members constituting the Institute Technical Council of IIT Bombay

• Organized bootcamps and delivered talks on Arduino and Image Processing, attended by 200+ enthusiasts

## COMMUNITY SERVICE & VOLUNTEERING

- Open-source contributor at JdeRobot, a toolkit for developing robotics applications
  - Mar 2021 Present
- Mentoring 4 female undergraduates from low-income backgrounds under iWE (Indian Women in Engineering), an initiative by Goldman Sachs
- Sep 2021 Present
- Tutored a high-school junior under Abhyasika, a student initiative at IIT Bombay for upliftment of economically disadvantaged children
- Nov 2018 May 2019
- Facilitated Juhu Beach Cleanup Drive under IIT Bombay E-Cell's Swacch initiative
- Oct 2017

# TECHNICAL SKILLS

Programming & Scripting

Python, C, C++, Java, R, x10, Bash, Sed, Awk, Perl, RegEx, CMake, SQLite

Frameworks

Git, Vim, Docker, OpenCV, PyTorch, TensorFlow, Tesseract-OCR, LATEX

Optimization Robotics tools GNU MathProg, GLPK, Gurobi, PuLP, Ipopt, OSQP

Controllers & Modules

ROS1, ROS2, Gazebo, Webots, MRPT, Pinochhio, TSID, Crocoddyl Arduino, Raspberry Pi, Tiva C, NodeMCU, MPU6050, Intel RealSense D435

## **KEY COURSES**

Computer Science Computer Vision, Reinforcement Learning, Data Structures and Algorithms, Design and

Analysis of Algorithms, Digital Image Processing

Robotics

Advanced Topics in Mobile Robotics, Design of Mechatronic Systems, Microprocessors &

Automatic Control, Kinematics & Dynamics of Machines, Machine Design, Robotics

Optimization Certifications Optimization from Fundamentals, Optimization for Engineering Design, Operations Research

Advanced Methods for Planning & Control of Legged Robots, ROS: Localization, Navigation & SLAM, Using GPUs to Scale & Speed-up Deep Learning

#### EXTRA CURRICULAR ACTIVITIES

Competition

- First runners-up in Aerial Path Planning GC, IIT Bombay (Source)
- ['21] ['17]
- Public Speaking • Participated in Model United Nations by WeSpeak, IIT Bombay

  - Received Special Mention among 35 participants in English Debate, IIT Bombay ['17]

**Journalism** 

• Curated article in Mechanical Media Newsletter with a reach of 700+ students

Sports

• Completed inter-hostel Crossy General Championship and the Cyclothon by TechFest ['17]

Leadership

• Headed 150+ students as House Captain in 10<sup>th</sup> & Vice-Captain in 9<sup>th</sup> grade ['14,'15]