SIDDHARTH SAHA

Blog ♦ ♣ Homepage ♦ in LinkedIn ♦ ➡ Mail ♦ ♠ trunc8 EDUCATION				
Graduation	IIT Bombay	Indian Institute of Technology Bombay	2017 - 2021	9.43/10.00
Undergraduate De		Honors in Mechanical Engineering, IIT Bonputer Science and Engineering, IIT Bomb		
	S	CHOLASTIC ACHIEVEMENTS		
 Ranked top 5 in Conferred AP g Endowed with to 	n batch of 150 students ${f grade}$ (3/188 students the Economic Times	highest award for excellence in technical as on merit of GPA Secured perfect 10.0) in Statistical Machine Learning course for Campus Star Award from over 49,000 15 students from India) by Japan Science	GPA in 7^{th} & 8^t or exceptional per candidates across	h semesters ['21] formance ['20] s India ['20]
	PROFESSIONAL E	EXPERIENCE & INTERNATIONAL E	XCHANGE	
	s, Structuring Analyst l insights into the upsi	Bengaluru des & downsides of structuring ideas vis-a		d 2021 - Present methodologies
JdeRobot develops • Built the RADI	s framework based on -4.0 (Robotics Academ	bot, Student Developer Final Report ROS, Docker & Django to simplify learning by Docker Image) for ROS2 Foxy, and Vavigator Extended pick-and-delivery exer	ng robotics & com NC-based RViz2	web template
• Innovated and in	mplemented payment	er Analyst Bengaluru structuring ideas for mortgage-backed sec 2% profits by optimizing cash-flows throug	ecurities to maxi i	_
	versity, Special Audit coing research in the C	ing Student Japan ybernetics Laboratory under the Sakur	ra Research Exche	Jun 2019 ange Programme
Competitions				
Team Leader in M. • Implemented or	laze-solving challenge uline breadth-first plant	se Challenge Source & Demo to program an autonomous bot simulated ner for optimal path & omni-wheel based	/	
Autonomous bot s		0, Delhi produce given pattern on ground, minimiz ion in C to sharply prune number of cues		-
• Devised optimiz	cation solutions in Mat	Championship '21, IIT Bombay, Source hProg using the GLPK Optimizer Sol		Feb 2021 ning problems
		Drone 9^{th} Inter IIT Tech Meet, Source ous Navigation challenge across complex, st.		$\begin{array}{c} {\rm Mar~2021} \\ \sin ROS/Gaze bo \end{array}$

• Ranked 6th across India | Designed & implemented navigation pipeline with three-layered intelligence algorithms

RoboCon, Team IIT Bombay | ABU RoboCon '19 Ulaanbaatar, Mongolia Jan 2019 - Apr 2019 Competition to construct a manual bot with throwing capability & an autonomous walking bot

• Bagged 9th position among 50+ national teams in stage-1 | Designed Solidworks model of robotic gripper arm

KEY PROJECTS

Mapping Regions of Dynamic Activity & Building Dynamic-free 3D Occupancy Maps | Demo Bachelor's Thesis — Guides: Prof. Leena Vacchani, Prof. Abhishek Gupta Jun 2020 - Jul 2021

- Proved the occupancy & dynamic activity probabilities in an octree map to form a field in the range (0,1)
- Designed & implemented novel clustering algorithm in ROS OctoMap to reject nodes with high dynamic activity

Quadruped Robot | RoboCup Rescue League Challenge

Dec 2019 - May 2021

Founding member & Team Leader of two-tiered team with 15 members, overseeing technical budget of ~14K USD

- Explored impedance control to create virtual leg compliance | Simulated gait trajectories inside Gazebo
- Generated foot trajectory by modulating length and height of control points for a 11-order Bézier curve
- Implemented sensor fusion of MPU6050 with Intel RealSense D435 PointCloud2 data to demonstrate SLAM

F1/10th — Autonomous Grand Prix | IROS '20, Las Vegas

Oct 2020

International autonomous racing contest with standardized hardware simulated in ROS/Gazebo

- Used Bernstein polynomial based local trajectory planner & MPC for Ackermann steering in 4-membered team
- Attained global optimal path using OSQP solver | Implemented obstacle detection | Composed Docker submission

Two-wheeled Self-Balancing Bot | Documentation & Demo

Aug 2020 - Nov 2020

• Stabilized Arduino bot using PD control and applied complementary filter on gyroscope & accelerometer output

Wifi De-auth Attacker

Mar 2019

• Programmed ESP8266 (Wi-Fi chip) to send de-authentication frames, exploiting vulnerability in IEEE 802.11

Sudoku Solver Using Block Printing | Source & Demo

Apr 2018 - May 2018

- Implemented a Raspbian based machine to physically imprint digits into any given unsolved sudoku grid
- Leveraged scikit-learn & invoked support vector machines for recognition of handwritten digits in the sudoku

Gyro Brick Breaker

Jul 2018

• Led 5-membered team to develop a hand-gesture controlled brick-breaking game coded in Processing IDE More projects...

Positions Of Responsibility

Teaching Assistant | Student Mentorship Program, IIT Bombay

Apr-May 2018 / Jan-Apr 2019

- Physical Chemistry: Only student from freshmen year appointed to guide class of 15 students in tutorials
- Electricity & Magnetism: Conducted tutorial sessions for 52 students focusing on the academically weak students

Summer of Science Mentor | Maths and Physics Club, IIT Bombay

Apr 2020 - Jun 2020

• Guided 4 mentees to proficiency in Data Structures & Algorithms with conceptual aid and meticulous roadmap

Convener | Electronics and Robotics Club, IIT Bombay

Apr 2018 - Mar 2019

Part of a two-tiered team of 70 members constituting the Institute Technical Council of IIT Bombay

• Organized bootcamps and delivered talks on Arduino and Image Processing, attended by 200+ enthusiasts

COMMUNITY SERVICE & VOLUNTEERING

- Open-source contributor at JdeRobot, a toolkit for developing robotics applications Mar 2021 - Present
- Mentoring 4 female undergraduates from low-income backgrounds under iWE

Sep 2021 - Present

- (Indian Women in Engineering), an initiative by Goldman Sachs
- Nov 2018 May 2019
- Tutored a high-school junior under Abhyasika, a student initiative at IIT Bombay for upliftment of economically disadvantaged children
- Facilitated Juhu Beach Cleanup Drive under IIT Bombay E-Cell's Swacch initiative

Oct 2017

TECHNICAL SKILLS

Programming & Scripting Frameworks

Python, C, C++, Java, R, Javascript, x10, Bash, Sed, Awk, Perl, RegEx Git, Vim, Docker, OpenCV, PyTorch, TensorFlow, Tesseract-OCR, LATEX

Optimization

GNU MathProg, GLPK, Gurobi, PuLP, Ipopt, OSQP

Robotics tools

ROS1, ROS2, Gazebo, Webots, MRPT, Pinochhio, TSID, Crocoddyl

Controllers & Modules

Arduino, Raspberry Pi, Tiva C, NodeMCU, MPU6050, Intel RealSense D435

KEY COURSES

Computer Science Computer Vision, Reinforcement Learning, Data Structures and Algorithms, Design and

Analysis of Algorithms, Digital Image Processing

Robotics

Advanced Topics in Mobile Robotics, Design of Mechatronic Systems, Microprocessors &

Automatic Control, Kinematics & Dynamics of Machines, Machine Design, Robotics

Optimization Certifications Optimization from Fundamentals, Optimization for Engineering Design, Operations Research Advanced Methods for Planning & Control of Legged Robots, ROS: Localization, Navigation

& SLAM, Using GPUs to Scale & Speed-up Deep Learning

EXTRA CURRICULAR ACTIVITIES

Competition

• First runners-up in Aerial Path Planning GC, IIT Bombay (Source)

['21]

Public Speaking

• Participated in Model United Nations by WeSpeak, IIT Bombay

['17]

• Received Special Mention among 35 participants in English Debate, IIT Bombay ['17]

Journalism

• Curated article in Mechanical Media Newsletter with a reach of 700+ students

Sports

• Completed inter-hostel Crossy General Championship and the Cyclothon by TechFest ['17]

Leadership

• Headed 150+ students as House Captain in 10th & Vice-Captain in 9th grade ['14,'15]