

SIDDHARTH SAHA

📝 [Blog](#) ♦ 🏠 [Homepage](#) ♦ [in LinkedIn](#) ♦ ✉ [Mail](#) ♦ 🔔 [trunc8](#)

EDUCATION

| Examination | University | Institute | Year | GPA |
|-------------|------------|---------------------------------------|-------------|------------|
| Graduation | IIT Bombay | Indian Institute of Technology Bombay | 2017 - 2021 | 9.43/10.00 |

Undergraduate Degrees: B.Tech. with Honors in Mechanical Engineering, IIT Bombay
Minor in Computer Science and Engineering, IIT Bombay

SCHOLASTIC ACHIEVEMENTS

- Bagged the **Technical Citation**, 2nd highest award for excellence in technical activities at IIT Bombay [’21]
- Ranked **top 5** in batch of 150 students on merit of GPA | Secured **perfect 10.0** GPA in 7th & 8th semesters [’21]
- Conferred **AP grade** (3/188 students) in Statistical Machine Learning course for exceptional performance [’20]
- Endowed with the **Economic Times Campus Star Award** from over 49,000 candidates across India [’20]
- Awarded the SSP scholarship (among 15 students from India) by **Japan Science & Technology Agency** [’19]

PROFESSIONAL EXPERIENCE & INTERNATIONAL EXCHANGE

Goldman Sachs, Structuring Analyst | Bengaluru Jul 2021 - Present

- Deriving critical insights into the upsides & downsides of structuring ideas vis-a-vis rating agency methodologies

Google Summer of Code – JdeRobot, Student Developer | [Final Report](#) Jun 2021 - Aug 2021

JdeRobot develops framework based on ROS, Docker & Django to simplify learning robotics & computer vision

- Built the **RADI-4.0** (Robotics Academy Docker Image) for **ROS2 Foxy**, and VNC-based RViz2 web template
- Implemented **BT (Behavior Tree)** Navigator | Extended pick-and-delivery exercise to ROS2 web-based template

Goldman Sachs, Quantitative Summer Analyst | Bengaluru May 2020 - Jun 2020

- Innovated and implemented **payment structuring** ideas for mortgage-backed securities to **maximize arbitrage**
- Achieved **sharp improvement** of 1.62% profits by optimizing cash-flows through different derivative instruments

Hiroshima University, Special Auditing Student | Japan Jun 2019

- Assimilated ongoing research in the **Cybernetics Laboratory** under the *Sakura Research Exchange Programme*

COMPETITIONS

Winner | International Micromouse Challenge | [Source](#) & [Demo](#) Dec 2020

Team Leader in Maze-solving challenge to program an autonomous bot simulated in ROS/Gazebo

- Implemented *online breadth-first planner* for optimal path & **omni-wheel** based drive to reduce steering latency

Winner | Off-Track Bot | Innervive ’20, Delhi Nov 2020

Autonomous bot simulated in Webots to produce given pattern on ground, minimizing number of blocks kept as cues

- Innovated vision-based **object detection in C** to sharply prune number of cues required by navigation algorithm

Winner | Operations GC | General Championship ’21, IIT Bombay, [Source](#) Feb 2021

- Devised optimization solutions in MathProg using the **GLPK Optimizer** | Solved machine learning problems

Vision Based Obstacle Avoidance Drone | 9th Inter IIT Tech Meet, [Source](#) Mar 2021

Team Leader of IIT Bombay in Autonomous Navigation challenge across complex static environments in ROS/Gazebo

- **Ranked 6th** across India | Designed & implemented navigation pipeline with three-layered intelligence algorithms

RoboCon, Team IIT Bombay | ABU RoboCon ’19 Ulaanbaatar, Mongolia Jan 2019 - Apr 2019

Competition to construct a manual bot with throwing capability & an autonomous walking bot

- Bagged **9th position** among 50+ national teams in stage-1 | Designed Solidworks model of **robotic gripper arm**

KEY PROJECTS

Mapping Regions of Dynamic Activity & Building Dynamic-free 3D Occupancy Maps | [Demo](#)

Bachelor’s Thesis — Guides: Prof. Leena Vacchani, Prof. Abhishek Gupta

Jun 2020 - Jul 2021

- Proved the occupancy & dynamic activity probabilities in an octree map to **form a field** in the range (0,1)
- Designed & implemented novel clustering algorithm in **ROS OctoMap** to reject nodes with high dynamic activity

Quadruped Robot | RoboCup Rescue League Challenge

Dec 2019 - May 2021

Founding member & Team Leader of two-tiered team with 15 members, overseeing technical budget of ~14K USD

- Explored **impedance control** to create virtual leg compliance | Simulated **gait trajectories** inside Gazebo
- Generated foot trajectory by modulating length and height of control points for a 11-order **Bézier curve**
- Implemented **sensor fusion** of *MPU6050* with *Intel RealSense D435* PointCloud2 data to demonstrate SLAM

F1/10th — Autonomous Grand Prix | IROS '20, Las Vegas Oct 2020

International autonomous racing contest with standardized hardware simulated in ROS/Gazebo

- Used **Bernstein polynomial** based local trajectory planner & MPC for Ackermann steering in 4-membered team
- Attained global optimal path using **OSQP solver** | Implemented obstacle detection | Composed Docker submission

Two-wheeled Self-Balancing Bot | [Documentation](#) & [Demo](#) Aug 2020 - Nov 2020

- Stabilized Arduino bot using PD control and applied **complementary filter** on gyroscope & accelerometer output

Wifi De-auth Attacker Mar 2019

- Programmed *ESP8266* (Wi-Fi chip) to send de-authentication frames, **exploiting vulnerability** in IEEE 802.11

Sudoku Solver Using Block Printing | [Source](#) & [Demo](#) Apr 2018 - May 2018

- Implemented a *Raspbian* based machine to **physically imprint digits** into any given unsolved sudoku grid
- Leveraged *scikit-learn* & invoked **support vector machines** for recognition of handwritten digits in the sudoku

Gyro Brick Breaker Jul 2018

- **Led 5-membered** team to develop a **hand-gesture controlled** brick-breaking game coded in Processing IDE

[More projects...](#)

POSITIONS OF RESPONSIBILITY

Teaching Assistant | Student Mentorship Program, IIT Bombay Apr-May 2018 / Jan-Apr 2019

- *Physical Chemistry*: **Only student from freshmen year** appointed to guide class of **15 students** in tutorials
- *Electricity & Magnetism*: Conducted tutorial sessions for **52 students** focusing on the academically weak students

Summer of Science Mentor | Maths and Physics Club, IIT Bombay Apr 2020 - Jun 2020

- Guided **4 mentees** to proficiency in *Data Structures & Algorithms* with **conceptual aid** and meticulous roadmap

Convener | Electronics and Robotics Club, IIT Bombay Apr 2018 - Mar 2019

Part of a two-tiered team of 70 members constituting the Institute Technical Council of IIT Bombay

- Organized bootcamps and **delivered talks** on Arduino and Image Processing, attended by **200+ enthusiasts**

COMMUNITY SERVICE & VOLUNTEERING

- **Open-source contributor** at JdeRobot, a toolkit for developing robotics applications Mar 2021 - Present
- Mentoring 4 female undergraduates from low-income backgrounds under iWE Sep 2021 - Present
(**Indian Women in Engineering**), an initiative by Goldman Sachs
- Tutored a high-school junior under **Abhyasika**, a student initiative at IIT Bombay for Nov 2018 - May 2019
upliftment of economically disadvantaged children
- Facilitated **Juhu Beach Cleanup Drive** under IIT Bombay E-Cell's Swacch initiative Oct 2017

TECHNICAL SKILLS

| | |
|------------------------------------|---|
| Programming & Scripting | Python, C, C++, Java, R, Javascript, x10, Bash, Sed, Awk, Perl, RegEx |
| Frameworks | Git, Vim, Docker, OpenCV, PyTorch, TensorFlow, Tesseract-OCR, L ^A T _E X |
| Optimization | GNU MathProg, GLPK, Gurobi, PuLP, Ipopt, OSQP |
| Robotics tools | ROS1, ROS2, Gazebo, Webots, MRPT, Pinochhio, TSID, Crocoddyl |
| Controllers & Modules | Arduino, Raspberry Pi, Tiva C, NodeMCU, MPU6050, Intel RealSense D435 |

KEY COURSES

| | |
|-------------------------|---|
| Computer Science | Computer Vision, Reinforcement Learning, Data Structures and Algorithms, Design and Analysis of Algorithms, Digital Image Processing |
| Robotics | Advanced Topics in Mobile Robotics, Design of Mechatronic Systems, Microprocessors & Automatic Control, Kinematics & Dynamics of Machines, Machine Design, Robotics |
| Optimization | Optimization from Fundamentals, Optimization for Engineering Design, Operations Research |
| Certifications | Advanced Methods for Planning & Control of Legged Robots, ROS: Localization, Navigation & SLAM, Using GPUs to Scale & Speed-up Deep Learning |

EXTRA CURRICULAR ACTIVITIES

| | |
|------------------------|--|
| Competition | • First runners-up in Aerial Path Planning GC, IIT Bombay (Source) [’21] |
| Public Speaking | • Participated in Model United Nations by WeSpeak, IIT Bombay [’17] • Received Special Mention among 35 participants in English Debate, IIT Bombay [’17] |
| Journalism | • Curated article in Mechanical Media Newsletter with a reach of 700+ students [’17] |
| Sports | • Completed inter-hostel Crossy General Championship and the Cyclothon by TechFest [’17] |
| Leadership | • Headed 150+ students as House Captain in 10 th & Vice-Captain in 9 th grade [’14, ’15] |