

* Groups :

Let G is non empty set, with binary operations $*$ on elements of G , then $(G, *)$ is said to be a group if,

- (1) " $*$ " is closed.
- (2) " $*$ " is -assoc associative.
- (3) Identity element exist in G . i.e there exist $e \in G$, such that $e * a = a$,
 $a * e = a \quad \forall a \in G$.
- (4) Inverse of each element exist in G i.e for a , $\exists a' \in G$ such that $a * a' = e$,
 $a' * a = e$.

Q Is the set of natural numbers and a group under multiplication $(\mathbb{N}, *)$

(1) $a, b \in \mathbb{N} \quad \therefore a * b = c \in \mathbb{N} \quad \therefore$ hence closed.

(2) $a(b(c)) = (a)(bc) \rightarrow$ hence associative.

(3) I.G.N $\therefore 1 * a = a, \quad a * 1 = a. \quad \therefore$ hence Identity element exist.

(4) For $2 \in \mathbb{N}$, $2^{-1} = \frac{1}{2}$ for multiplication

$\therefore 2 * \frac{1}{2} = 1$ but $\frac{1}{2} \notin \mathbb{N}$. Hence inverse

of each element doesn't exist.

$\rightarrow \therefore$ It is not a group.

Ex-2 $(R, *)$

(1) $a, b \in R \therefore a * b \in R \therefore$ hence closed.

(2) $a(bc) = (ab)c \rightarrow$ Hence associative.

(3) $1 \in R \therefore 1 * a = a, a * 1 = a \therefore$ Hence Identity exists.

(4) Inverse of each element exist. Hence It is a group.

If binary operation is commutative for group $(R, *)$ then $(R, *)$ is said to be abelian.

Finite sets are called self-inversive sets.

Reflexive $\forall a \in A, (a, a) \in R$

Irreflexive $\forall a \in A, (a, a) \notin R$

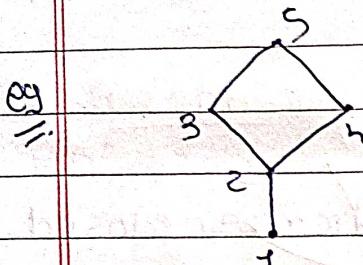
Ex- $A = \{1, 2, 3, 4\}$

$$R = \{(1, 1), (1, 2), (3, 2), (2, 1)\}$$

\hookrightarrow neither reflexive nor irreflexive.

\Rightarrow Sub lattice:

If (L, \leq) lattice, then $S \subseteq L$ is said to be sub lattice of (L, \leq) if (S, \leq) is itself a lattice.


 (L, \leq)

$S_1 = \{2, 3, 4\} \alpha$

$S_2 = \{1, 2, 3\} \checkmark$

$S_3 = \{1, 2, 4, 5\} \alpha$

$S_4 = \{3, 4, 5\} \alpha$

$S_5 = \{2, 3, 5\} \checkmark$

$S_6 = \{1, 4\} \checkmark$

✓ Sub lattice, α -sublattice.

→ If Rlb and lub exist then sublattice.

* Direct product of lattice:

$\Rightarrow (L_1, \leq_1), (L_2, \leq_2)$

$L_1 \times L_2 = \{(x_i, y_j) \mid x_i \in L_1, y_j \in L_2\}$

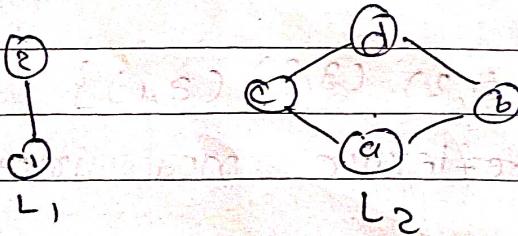
→ Rlb and lub will be defined as,

$rlb \{(x_1, y_1), (x_2, y_2)\} = (rlb(x_1, x_2), rlb(y_1, y_2))$

$OR (x_1, y_1) \wedge (x_2, y_2) = ((x_1 \wedge x_2), (y_1 \wedge y_2))$

$lub (x_1, y_1) \vee (x_2, y_2) = ((x_1 \vee x_2), (y_1 \vee y_2))$

Ex:- find the direct product of lattices given.



$L_1 \times L_2 = \{(1, a), (1, b), (1, c), (1, d), (2, a), (2, b), (2, c), (2, d)\}.$

$$\Rightarrow (1, a) \wedge (1, d) = ((1 \wedge 1), (a \wedge d)) = (1, a)$$

$$\Rightarrow (1, a) \vee (1, d) = ((1 \vee 1), (a \vee d)) = (1, d)$$

$$\Rightarrow (2, c) \wedge (1, b) = (1, a)$$

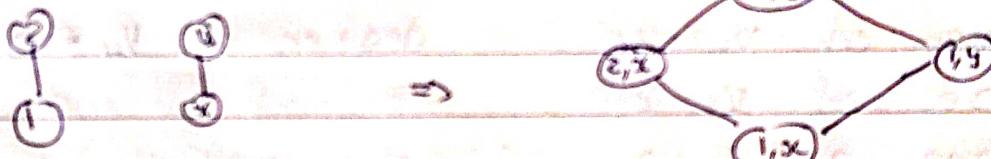
$$(2, c) \vee (1, b) = (2, d)$$

$$\Rightarrow (1, a) \wedge (2, b) = (1, a)$$

$$(1, a) \vee (2, b) = (2, b)$$

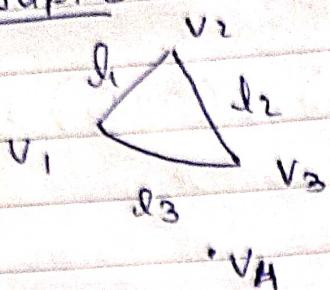
\Rightarrow

Ex:



Graph theory

* Graphs:



$G, (V, E)$

$V = \{v_1, v_2, v_3, v_4\}$

$E = \{(v_1, v_2), (v_2, v_3), (v_3, v_4)\}$

$= \{l_1, l_2, l_3\}$

$\Rightarrow G(V, E) :-$

A graph G is consist of a non-empty set, V : set of vertices/nodes/parts and set of edge is defined on V as

$$E = \{(v_i, v_j) / v_i, v_j \in V\}$$

Degree of $v_1 = 2$

Degree of $v_4 = 0$

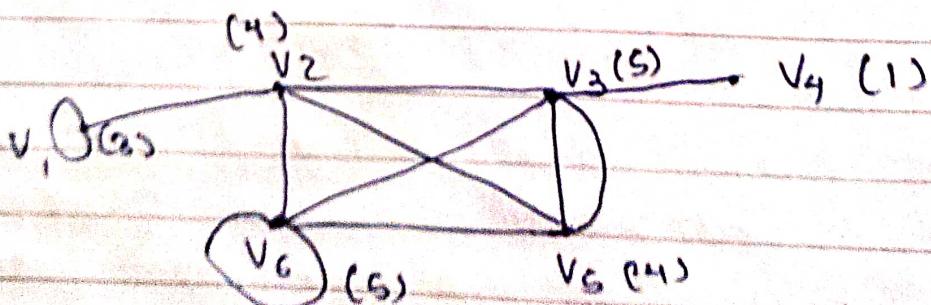
Degree of $v_2 = 2$

Degree of $v_3 = 2$

→ A vertex v is said to pendant vertex if the degree of that vertex is 1.

→ A vertex is said to be isolated vertex if its degree is zero(0).

→ An edge is said to be self loop if both vertices are same (v_i, v_i)



→ what is max degree in graph?

→ what is min degree in graph?

→ Find pendant vertices and isolated one

$$2l = \sum_{\text{odd}} \text{degree } v_i + \sum_{\text{even}} \text{degree } v_i$$

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No. of odd vertices are always even.

NOTE :-

Each edge will contribute 2 degree in graph total degree of G with 2 edges = $2 \times e$.

Odd vertex : vertex with odd degree

Even vertex : vertex with even degree

* Types of Graph :-

1) Simple graph :-

A graph G is said to be simple graph if there is no self such loop and parallel edges in the graph.

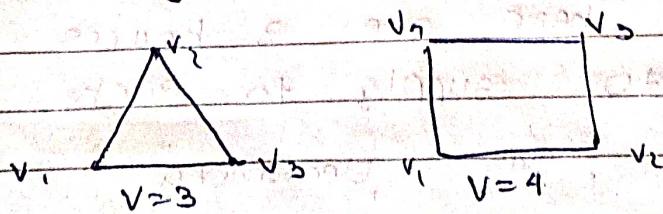
→ Parallel edge :-

Edges are called parallel edges if they have some end vertices.

NOTE :- In a simple graph max degree possible is $n-1$.

2) Regular graph :-

A simple graph G is said to be regular if all vertices have same degree.



Total degree of regular graph
 (n, g) \Rightarrow $\text{degree} = n \cdot g$

Degree of $v_1, v_2, v_3 = 3$

Degree of $v_1, v_2, v_3, v_4 = 4$

3) Complete graph :-

A simple graph, having edges between each pair of vertices.

$$\therefore \text{degree of vertex} = n(n-1)$$

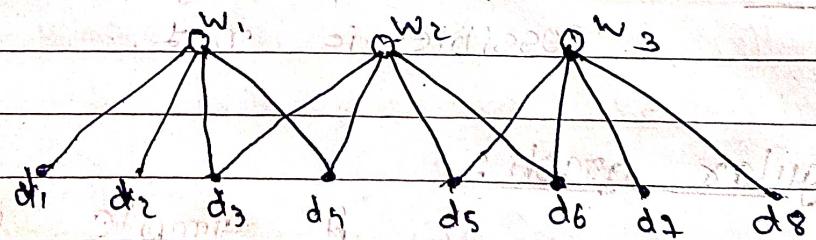
$$\therefore \text{no. of edges in a complete graph} = \frac{n(n-1)}{2}$$

$$\therefore \text{Total degree of } G = n(n-1).$$

4) Bipartite graph :-

A graph G is said to be bipartite graph if set of vertices V can be partitioned into two partitions V_1 and V_2 such that $V_1 \cap V_2 = \emptyset$, and $V_1 \cup V_2 = V$ such that no vertex $v_i \in V_1$ is not adjacent to any vertex in V_2 . i.e. each edge in G will have one end point in V_1 and another end point in V_2 .

Ex:-



Utility problem :-

There are 3 houses and three utility to supply to each house

Water

Gas

Electricity

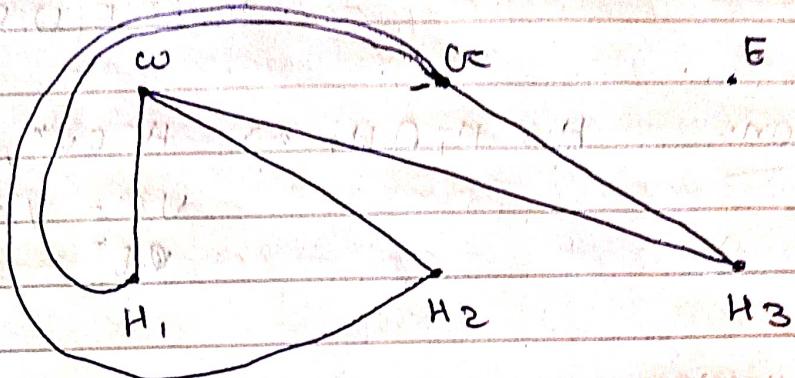
H₁

H₂

H₃

Can you supply this utilities without any crossover.

Ans:-



There is no such way to connect E to H, H₂, H₃ without crossover.

* Complete bipartite:-

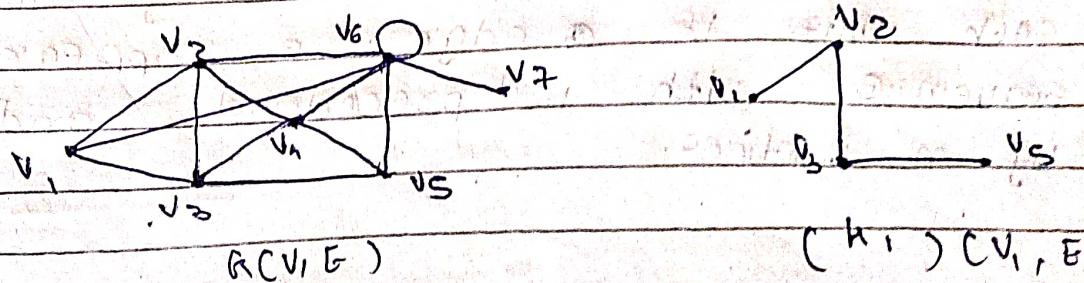
If G is a bipartite graph it is said to be complete bipartite graph if each vertex in first partition is adjacent to all vertices in second partition.

* OPERATIONS ON GRAPH :-

→ Subgraph :-

Let G consist of (V, E) is a graph. H (V₁, E₁) is said to be subgraph of G if V₁ ⊂ V & E₁ ⊂ E, such that adjacency relation is preserved.

ex:-



(i) Union :- $H = H_1 \cup H_2 \Rightarrow H(V^*, E^*)$
 $V^* = V_1 \cup V_2$
 $E^* = E_1 \cup E_2$

(ii) Intersection :- $H = H_1 \cap H_2 \Rightarrow H(V^*, E^*)$
 $V^* = V_1 \cap V_2$
 $E^* = E_1 \cap E_2$

* Deletion of vertex :-

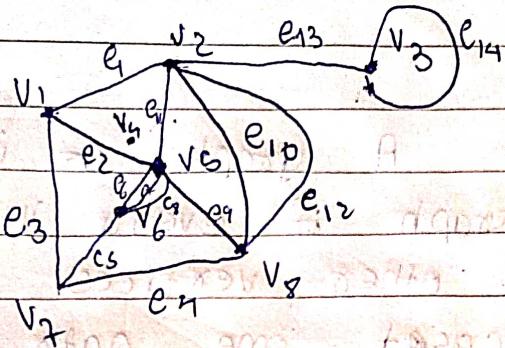
In a graph G deletion of one vertex v_i results into a new graph with vertex set $\{v - \{v_i\}\}$ and all the edges incident to v_i is deleted.

* Fusion of 2 vertices v_i & v_j :-

In a graph $G(V, E)$ results into a graph replacing v_i, v_j by single vertex v such that all edges incident with v_i, v_j will be now incident to v new vertex v .

* Graph traversing (Reachability) :-

A finite alternate sequence of vertices and edges starting with a vertex and ending to the vertex such that if an edge e appears in the sequence with it preceded and followed by m vertices.



Cx 1: $v_7 e_1 v_8 e_2 v_2 e_3 v_3$
 $e_{14} v_3 e_{13} v_2 e_1 v_1$

\Rightarrow If starting and ending vertex is same
It is called closed walk.

* Construct a walk that travels through every vertex except v_4 .

Ans:- $v_1 e_1 v_5 e_5 v_6 e_6 v_5 e_9 v_8 e_{10} v_2 e_{12} v_1$

* Path : A walk when we are not repeating any edge.

* No vertex and no edge is repeated except starting edge.

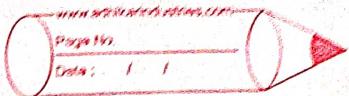
* If starting and ending vertex of path is same it is said to be closed path.

* A closed path is said to be a circuit.

* Smallest circuit :- self loop.

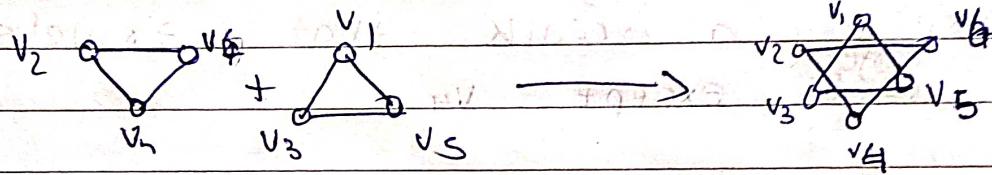
* Reachability :- In a graph if a vertex v_i is said to be reachable from v_j if there exist one path between v_i & v_j .

$\circ V$ (trivial graph)
(only one vertex)



* Connected Graph :-

A graph G is said to be connected graph if every vertex is reachable to all other vertices that is there exist at least one path between each and every pair of vertices. Otherwise G is said to be disconnected graph.



(Connected Subgraph)
(component)
(disconnected graph)

* A disconnected graph is collection of two or more than two components such that each component is a connected graph.

* Consider a simple graph G with n vertices and K components then G can have atmost $\frac{(n-K) * (n-K+1)}{2}$ edges.

=> Let us consider a simple graph with n vertices and K components.

$$\text{so } n \geq K.$$

=> Let i^{th} component has n_i vertices.
Hence max no. of edges in i^{th} components can be $n_i(n_i - 1)$.

∴ Therefore, maximum number of edges in

$$\alpha = \sum_{i=1}^k \frac{m_i(m_i-1)}{2}$$

$$= \frac{1}{2} \left[\sum_{i=1}^k m_i^2 - \sum_{i=1}^k m_i \right]$$

~~$$= \frac{1}{2} \left(\cancel{m(m+1)(2n+1)} - \cancel{\frac{m(m+1)}{2}} \right)$$~~

$$= \frac{1}{2} \left[\sum_{i=1}^k (m_i^2) - \cancel{\frac{m}{2}} \right]$$

~~$$= \frac{1}{2} \sum_{i=1}^k (m_i-1)^2 + \sum_{i=1}^k m_i - \frac{1}{2} \sum_{i=1}^k 1 - \frac{1}{2} m$$~~

~~$$= \frac{1}{2} \sum_{i=1}^k (m_i-1)^2 + \frac{m^2}{2} - \frac{m}{2}$$~~

* Null Graph:-

If there are ~~n~~ vertices but not edges it is called Null graph.

* Connectivity :-

* Edge connectivity:- In a connected graph theory edge connectivity is the minimum no. of edges who's deletion makes the

graph disconnected.

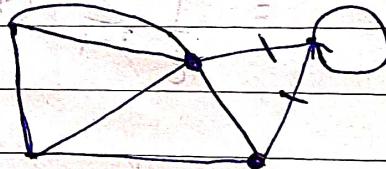
* Vertex connectivity :-

minimum number of vertices who's deletion will be result into disconnected graph.

- If we are denoting edge connectivity by $\lambda(G)$ and vertex connectivity by $K(G)$.

Here, $K(G)$ can not exceed $\lambda(G)$.

ex:-



$$\lambda(G) = 2$$

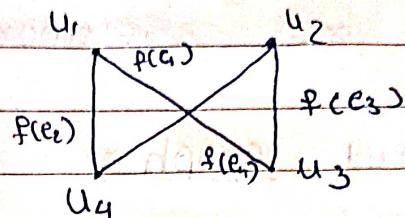
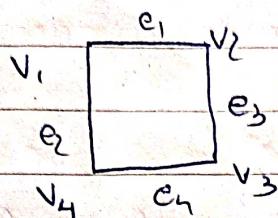
$$K(G) = 2$$

* Cut set :

It is a set of edges who's deletion increases the no. of components in the graph theory such that no proper subset of this set is a cutset.

* Cutpoint : A vertex in a graph (if exist) is said to be cut point if deletion of it results into disconnected graph.

* Isomorphism



(G_1) $\left(\because G_1 \approx G_2\right)$ (G_2) , $f^{-1}: G_2 \rightarrow G_1$.

$$f(v_1) = u_1$$

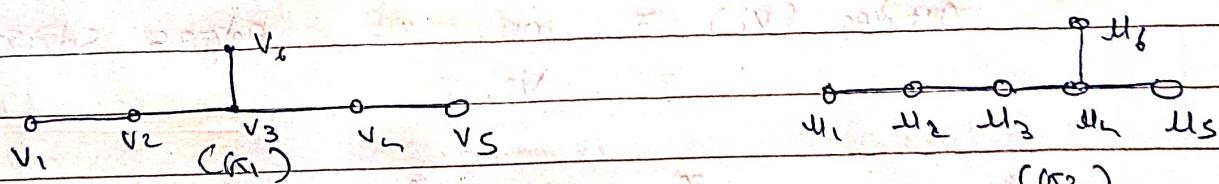
$$f(v_2) = u_3$$

$$f(v_4) = u_4$$

$$f(v_3) = u_2$$

* Conditions :-

- 1) No. of vertices same.
- 2) No. of edges same
- 3) degree sequence must be same.
- 4) Self loop / parallel edges (if exist) must be same.



In G_1 and G_2 the vertices v_3 and u_5 have degree 3 hence the isomorphism mapping from $(f: G_1 \rightarrow G_2)$ v_3 to u_5 .

* But in graph G_1 , v_3 is adjacent to only one pendant vertex v_6 . In G_2 , u_5 is adjacent to 2 pendant vertices u_6, u_5 .

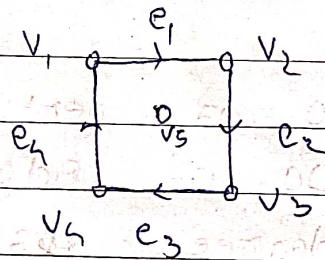
Hence, $f(v_3) = v_4$ cannot preserve adjacency relationship hence graphs are not isomorphic.

* Directed graph:

A graph is said to be directed graph if direction is assigned to each and every vertex edge to the graph and edges are represented by ordered pair of vertices as their n^{th} vertices.

$$C_K = \langle v_i, v_j \rangle = (v_i, v_j)$$

Ex:-



$$e_i = (v_i, v_j) = (v_i, v_j)$$

$\text{indeg}(v_i) =$ no. of edges coming to v_i .

$\text{outdeg}(v_i) =$ no. of edges starting from v_i .

$$\Rightarrow \deg(C_G) = \sum_{\text{indeg}} v_i + \sum_{\text{outdeg}} v_i$$

\Rightarrow If $\text{indeg}(v_i) = 0$ and only $\text{outdeg}(v_i) > 0$, v_i is known as source vertex.

\Rightarrow If $\text{outdeg}(v_i) = 0$ and only $\text{indeg}(v_i) > 0$, v_i is known as sink vertex.

* The path to reach from v_1 to v_2 will be $v_1 \rightarrow v_4 \rightarrow v_3 \rightarrow v_2$ as v_1, v_2 we can't use second coz it's direction is different.

* Connectivity of digraph:

A digraph is said to be weakly connected if we connect it is a connected graph without directions of edges.

* Unilaterally connected:

A digraph is said to be unilaterally connected if for every pair of vertices (v_i, v_j) there exist path from $(v_i \rightarrow v_j)$ or from $(v_j \rightarrow v_i)$.

* Strongly connected:

A digraph is said to be strongly connected if each vertex v_i is reachable from each vertex v_j in graph G.

* For a directed graph a matrix representation is taken by a matrix with rows and columns filled with entries a_{ij} such that,

$$a_{ij} = \begin{cases} 1, & \text{if } v_i, v_j \text{ are edgecent} \\ 0, & \text{otherwise.} \end{cases}$$

there is edge from v_i to v_j .

* Properties:-

- i) A graph without direction has symmetric matrix.
- ii) A digraph may or may not have symmetric matrix.
- iii) For a directed graph sum of entries in j th column will be indegree of v_j .
- iv) For a directed graph sum of entries in i th row will be outdegree of v_i .
- v) If A is a matrix representing a graph G then entry in the (i, j) cell of A^n represents no. of path of length n between vertices v_i and v_j .

* weighted graph :

A graph G is said to be weighted graph if every edge is assigned a real number $w_{ij}^{(l)}$. For example w_{ij} may be cost, time, distance etc.

* Graph algorithms :

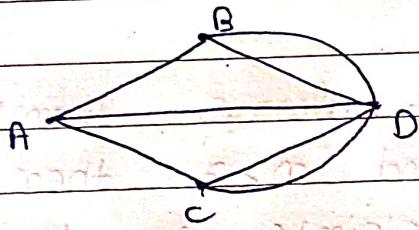
* Euler graph / Eulerian graph / Eulerian line / walk / circuit :

A graph (connected) G is said to be Euler graph if there exist euler walk (closed) in the graph.

* Closed Euler walk : (circuit)

A closed walk in a graph G is said to be euler walk if it passes through all the edges in the graph.

Ex *



(Root euler graph)

* Euler line :

An open walk in a connected graph G if exist which passes through every edge is said to be euler line.

* Necessary and sufficient condition for a
euler graph :

- 1) A connected graph G is a Eulerian graph if and only if all vertices in G are of even degree.

* Hamiltonian graph:

* Hamiltonian circuit:

In a connected graph a circuit is said to be Hamiltonian circuit if it contains all the vertices exactly one except starting and ending vertices.

\Rightarrow A graph which has hamilton circuit is said to be Hamiltonian graph.

(i) Complete graph is always Hamiltonian.

- If n is odd and $n \geq 3$ then it will have $\frac{(n-1)}{2}$ edge disjoint, in hamiltonian circuit.

(ii) G is a complete graph with n vertices where n is odd and $n \geq 3$.

We know that in a complete graph with n vertices there are $\frac{n(n-1)}{2}$ edges.

Also a circuit with n vertices has n edges.

Therefore from $n\left(\frac{n-1}{2}\right)$ edges we can have atmost $\frac{(n-1)}{2}$ edge disjoint.