

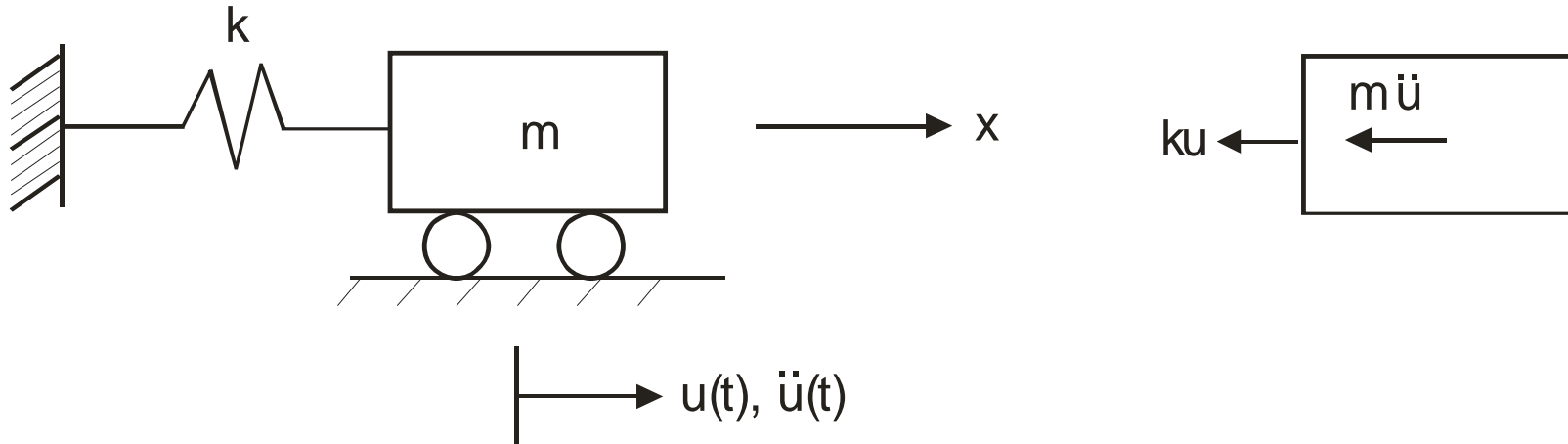
# Finite Elements for Engineers

## **Lecture 2: Structural Dynamics**

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# Introduction: Free Vibration



**D'Alembert's Principle**  $m\ddot{u} + ku = 0$

**Let**  $\omega^2 = \frac{k}{m} \Rightarrow \ddot{u} + \omega^2 u = 0$

# Introduction: Free Vibration

**Angular Frequency**       $\omega = \sqrt{k/m} \quad rad/s$

**Natural Frequency**       $f = \omega/2\pi \quad Hz$

**Natural Period**       $T = 1/f \quad s$

# Introduction: Free Vibration

## Solution

$$u(t) = C_1 \cos \omega t + C_2 \sin \omega t$$

$$t = t_0 \quad u = u_0 \quad \text{Initial displacement}$$

$$\dot{u} = \dot{u}_0 \quad \text{Initial velocity}$$

## Solution to free, undamped vibration

$$u = A \cos(\omega t - \alpha)$$

$$\text{Amplitude} \quad A = \sqrt{u_0^2 + \left(\frac{\dot{u}_0}{\omega}\right)^2} \quad \text{Phase Angle} \quad \alpha = \tan^{-1} \frac{\dot{u}_0}{\omega u_0}$$

# Introduction: Forced Vibration

**Harmonic forcing function**

$$m\ddot{u} + ku = P \sin \Omega t$$

$$p_m = \frac{P}{m} \Rightarrow \ddot{u} + \omega^2 u = p_m \sin \Omega t$$

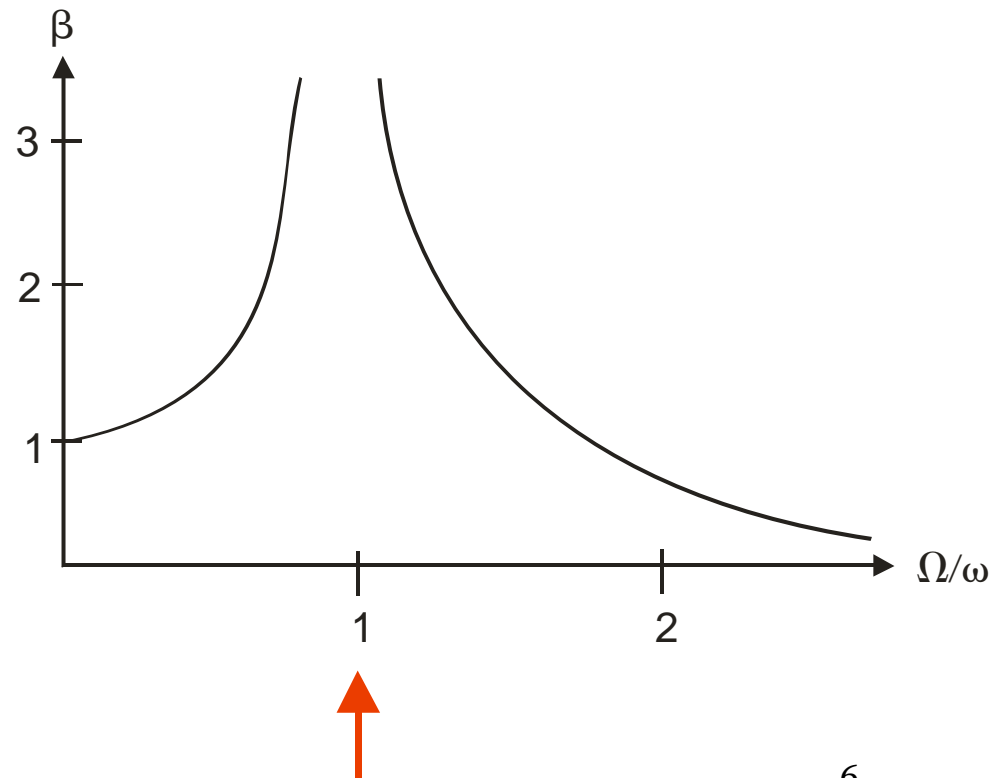
**Solution (particular solution + general solution)**

$$u = C_3 \sin \Omega t$$

$$u = C_1 \cos \omega t + C_2 \sin \omega t + C_3 \sin \Omega t$$

# Introduction: Forced Vibration

$$u = \left[ \frac{1}{1 - \left( \Omega/\omega \right)^2} \right] \frac{P}{k} \sin \Omega t = \frac{1}{\beta} \frac{P}{k} \sin \Omega t$$



# 1D Eigenproblem

**DE**

$$-\frac{d}{dx} \left\{ \alpha(x) \frac{du(x)}{dx} \right\} + \beta(x)u(x) - \lambda\gamma(x)u(x) = 0 \quad x_a < x < x_b$$

**BCs**

$$x_a \Rightarrow u(x_a) = 0 \quad or \quad \tau(x_a) = 0$$

$$x_b \Rightarrow u(x_b) = 0 \quad or \quad \tau(x_b) = 0$$

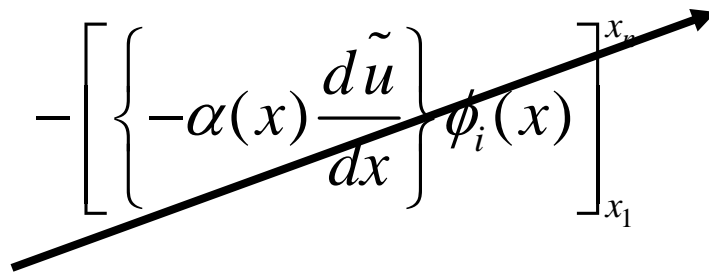
# Galerkin's Method

## Galerkin Step 1: Residual Equations

$$\int_{\Omega} \left[ -\frac{d}{dx} \left\{ \alpha(x) \frac{du(x)}{dx} \right\} + \beta(x)u(x) - \lambda\gamma(x)u(x) \right] \phi_i(x) dx = 0 \quad i = 1, 2, \dots, n$$

## Galerkin Step 2: Integration by parts

$$\int_{\Omega} \frac{d\phi_i(x)}{dx} \alpha(x) \frac{d\tilde{u}}{dx} dx + \int_{\Omega} \phi_i(x) \beta(x) \tilde{u} dx - \lambda \int_{\Omega} \phi_i(x) \gamma(x) \tilde{u} dx =$$

$$- \left[ \left\{ -\alpha(x) \frac{d\tilde{u}}{dx} \right\} \phi_i(x) \right]_{x_1}^{x_n}$$




# Galerkin's Method

## Galerkin Step 3: Use of trial solution

$$\tilde{u}(x, y) = \sum_{j=1}^n \phi_j(x, y) u_j$$

$$\sum_{j=1}^n \left\{ \int_{\Omega} \frac{d\phi_i(x)}{dx} \alpha(x) \frac{d\phi_j(x)}{dx} dx + \int_{\Omega} \phi_i(x) \beta(x) \phi_j(x) dx \right\} a_j - \lambda \sum_{j=1}^n \left\{ \int_{\Omega} \phi_i(x) \gamma(x) \phi_j(x) dx \right\} a_j = 0 \quad i = 1, 2, \dots, n$$

$$\mathbf{k}_{n \times n} \mathbf{a}_{n \times 1} - \lambda \mathbf{m}_{n \times n} \mathbf{a}_{n \times 1} = \mathbf{0}$$

# 1D-C<sup>0</sup> Linear Element

## Galerkin Step 4

$$\phi_1(x) = \frac{x_2 - x}{x_2 - x_1}$$

$$\phi_2(x) = \frac{x - x_1}{x_2 - x_1}$$

$$\left[ \frac{\bar{\alpha}}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} + \frac{\bar{\beta}L}{6} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \right] \mathbf{a} - \lambda \frac{\bar{\gamma}L}{6} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \mathbf{a} = \mathbf{0}$$

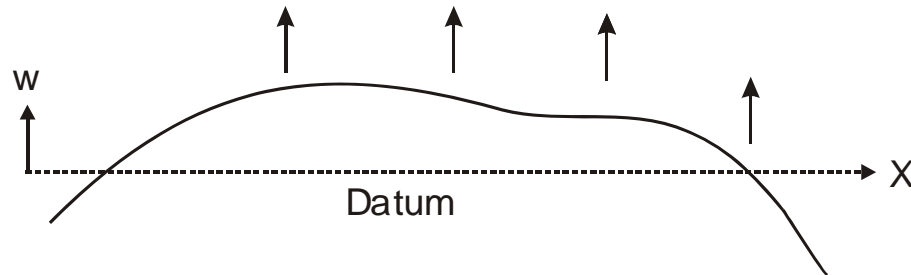
# System Equations

## Eigenproblem

$$\mathbf{K}_{n \times n} \boldsymbol{\Phi}_{n \times n} = \boldsymbol{\Lambda}_{n \times n} \mathbf{M}_{n \times n} \boldsymbol{\Phi}_{n \times n}$$

# Free Vibration of a Cable

## Transverse Equilibrium



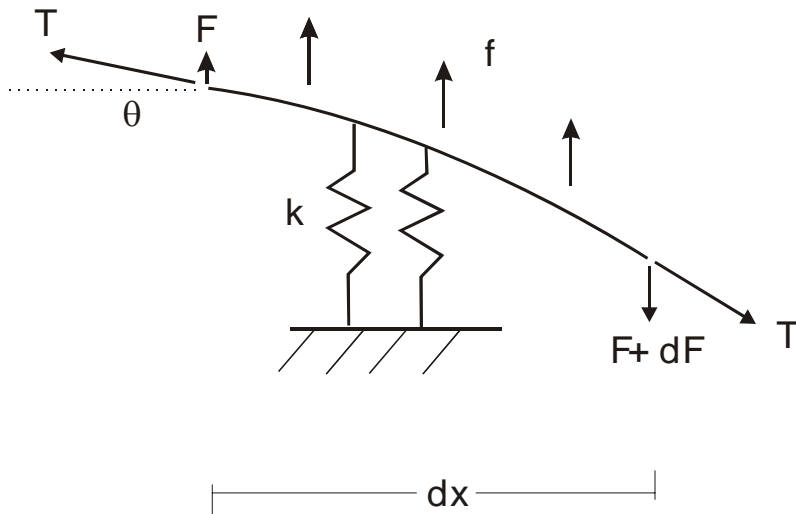
$$\frac{\partial F(x,t)}{\partial x} + k(x)w(x,t) = f(x) - \rho(x)\frac{\partial^2 w(x,t)}{\partial t^2}$$

## Free motion

$$\frac{\partial F(x,t)}{\partial x} + k(x)w(x,t) = -\rho(x)\frac{\partial^2 w(x,t)}{\partial t^2}$$

## Constitutive relation

$$F(x,t) = -T(x)\frac{\partial w(x,t)}{\partial x}$$



# Free Vibration

$$-\frac{\partial}{\partial x} \left[ T(x) \frac{\partial w(x,t)}{\partial x} \right] + k(x)w(x,t) = -\rho(x) \frac{\partial^2 w(x,t)}{\partial t^2}$$

## Harmonic solution

$$w(x,t) = W(x) \sin \omega t$$

## Governing DE

$$-\frac{d}{dx} \left[ T(x) \frac{dW(x)}{dx} \right] + k(x)W(x) - \omega^2 \rho(x)W(x) = 0$$

## BCs

$$W(0) = 0$$

$$W(L) = 0$$

# Free Vibration

## General 1D Eigenproblem

$$-\frac{d}{dx}\left[\alpha(x)\frac{du(x)}{dx}\right] + \beta(x)u(x) - \lambda\gamma(x)u(x) = 0$$

## Free vibration of a cable

$$-\frac{d}{dx}\left[T(x)\frac{dW(x)}{dx}\right] + k(x)W(x) - \omega^2\rho(x)W(x) = 0$$

# Example

## Problem data

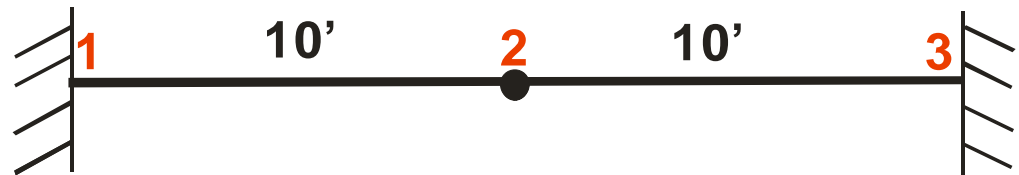
$$L = 20 \text{ ft}$$

$$T = 100 \text{ lb}$$

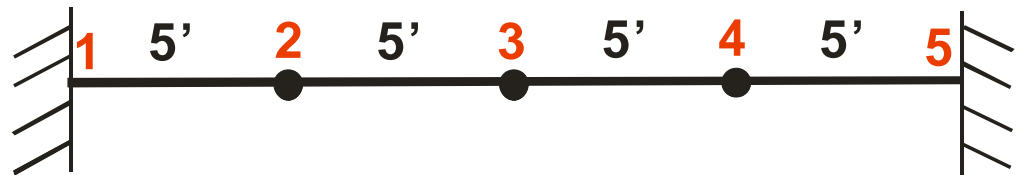
$$\rho = 0.01553 \text{ slug / ft}$$

$$k = 0$$

## 2-Element mesh



## 4-element mesh



## 2-Element Mesh

### Element 1

$$\frac{100}{10} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{Bmatrix} W_1 \\ W_2 \end{Bmatrix} - \lambda \frac{(0.01553)(10)}{6} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \begin{Bmatrix} W_1 \\ W_2 \end{Bmatrix} = 0$$

### Element 2

$$\frac{100}{10} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{Bmatrix} W_2 \\ W_3 \end{Bmatrix} - \lambda \frac{(0.01553)(10)}{6} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \begin{Bmatrix} W_2 \\ W_3 \end{Bmatrix} = 0$$



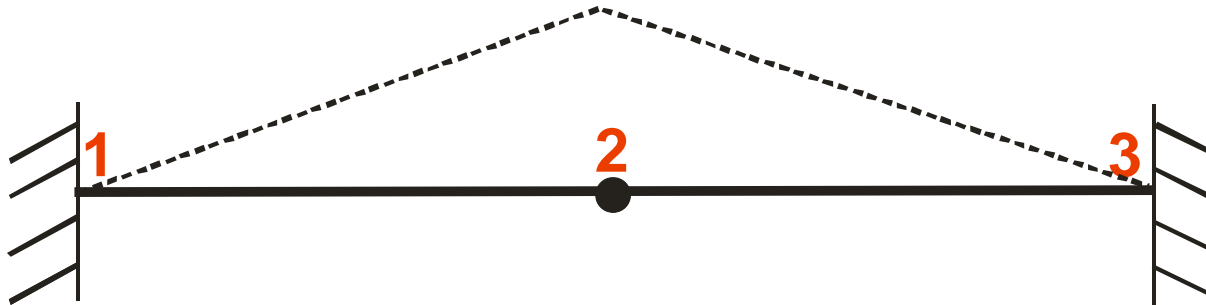
# 2-Element Model

## System Equation

$$[20]\{W_2\} - \lambda[0.103533]\{W_2\} = 0$$

## Solution

$$\det(20 - 0.103533\lambda) = 0 \Rightarrow \lambda_1 = 193$$



# 4-Element Model

## Element 1

$$\frac{100}{5} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{Bmatrix} W_1 \\ W_2 \end{Bmatrix} - \lambda \frac{(0.01553)(5)}{6} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \begin{Bmatrix} W_1 \\ W_2 \end{Bmatrix} = 0$$

$$20 \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{Bmatrix} W_1 \\ W_2 \end{Bmatrix} - \lambda (0.0129417) \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \begin{Bmatrix} W_1 \\ W_2 \end{Bmatrix} = 0$$

## Element 2, 3, 4

$$20 \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{Bmatrix} W_n \\ W_{n+1} \end{Bmatrix} - \lambda (0.0129417) \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \begin{Bmatrix} W_n \\ W_{n+1} \end{Bmatrix} = 0$$

# 4-Element Solution

## System Equations

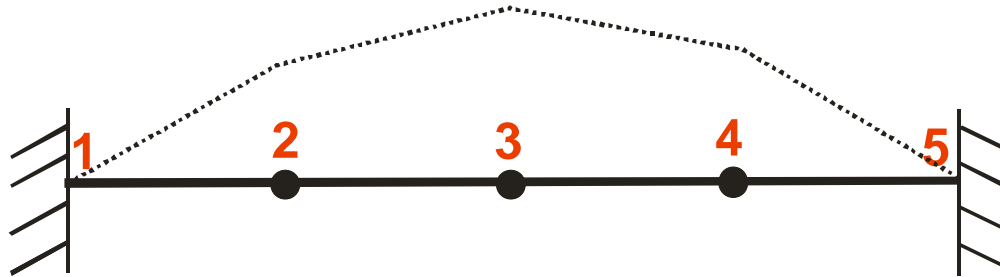
$$\begin{bmatrix} 40 & -20 & 0 \\ -20 & 40 & -20 \\ 0 & -20 & 40 \end{bmatrix} \begin{Bmatrix} W_2 \\ W_3 \\ W_4 \end{Bmatrix} - \lambda \begin{bmatrix} 0.0517668 & 0.0129417 & 0 \\ 0.0129417 & 0.0517668 & 0.0129417 \\ 0 & 0.0129417 & 0.0517668 \end{bmatrix} \begin{Bmatrix} W_2 \\ W_3 \\ W_4 \end{Bmatrix} = 0$$

## Solution

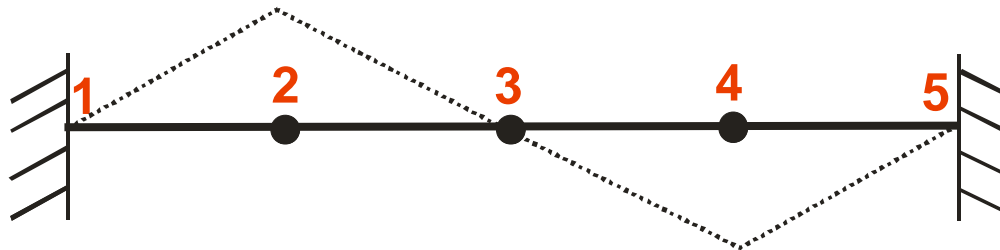
$$\begin{aligned} \lambda_1 &= 169.38 \\ \lambda_2 &= 782.8 \\ \lambda_3 &= 2067.1 \end{aligned} \quad \phi_1 = \begin{Bmatrix} 0.146 \\ 0.207 \\ 0.146 \end{Bmatrix} \quad \phi_2 = \begin{Bmatrix} 0.112 \\ 0 \\ -0.112 \end{Bmatrix} \quad \phi_3 = \begin{Bmatrix} 0.061 \\ -0.086 \\ 0.061 \end{Bmatrix}$$

# 4-Element Solution

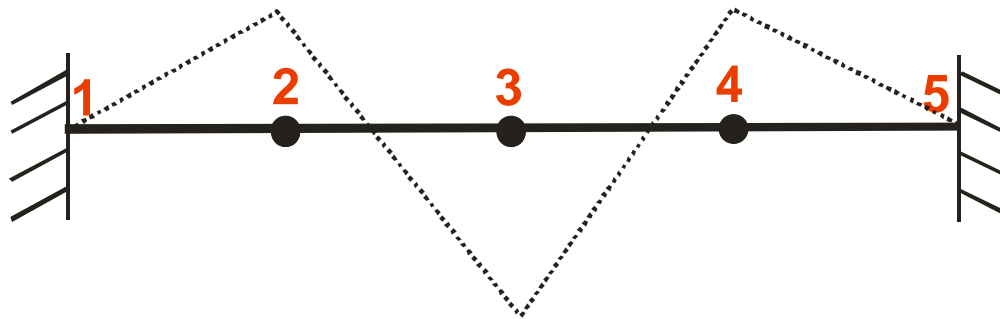
Mode 1



Mode 2



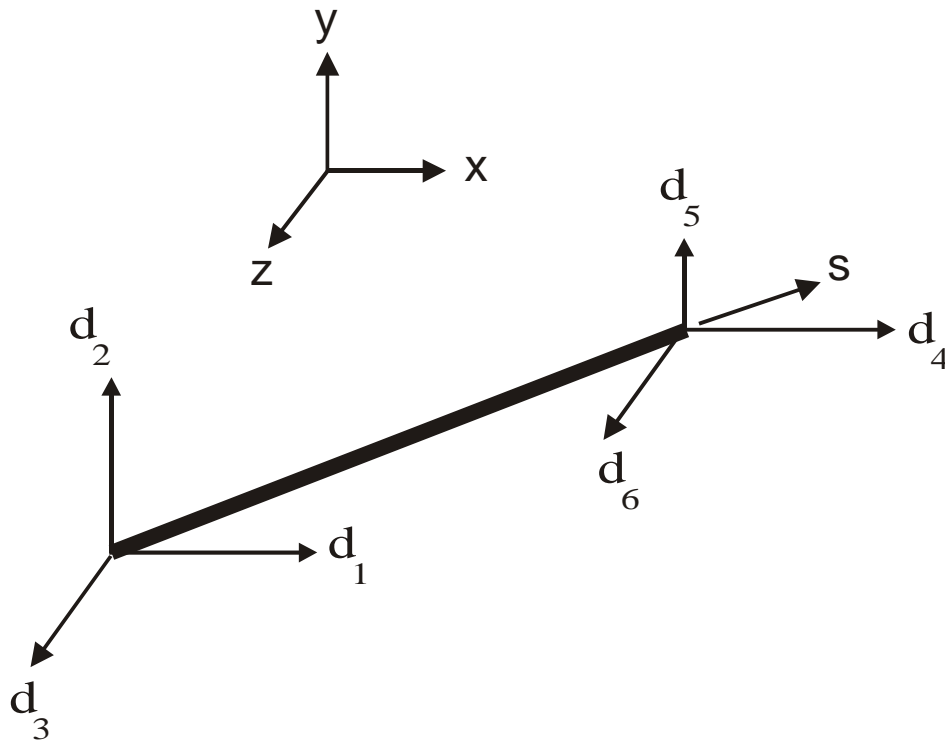
Mode 3



# Convergence Study

<b># of elements</b>	<b>Eigenvalue 1</b>	<b>Eigenvalue 2</b>
4	169.38	782.8
6	162.5	695.4
18	159.3	642.1
24	159.0	639.3
30	159.0	637.7

# Truss Element



## Consistent mass matrix

$$m_{ij} = \int_{\Omega} \phi_i(x) \gamma(x) \phi_j(x) dx$$

# Truss Element

$$\begin{Bmatrix} u \\ v \\ w \end{Bmatrix} = \begin{bmatrix} 1-a & 0 & 0 & a & 0 & 0 \\ 0 & 1-a & 0 & 0 & a & 0 \\ 0 & 0 & 1-a & 0 & 0 & a \end{bmatrix} \begin{Bmatrix} d_1 \\ d_2 \\ d_3 \\ d_4 \\ d_5 \\ d_6 \end{Bmatrix} = \mathbf{A}_{3 \times 6} \mathbf{d}_{6 \times 1}$$

$$\mathbf{m}_{6 \times 6} = \int_{\Omega} \gamma \mathbf{A}^T \mathbf{A} dV$$

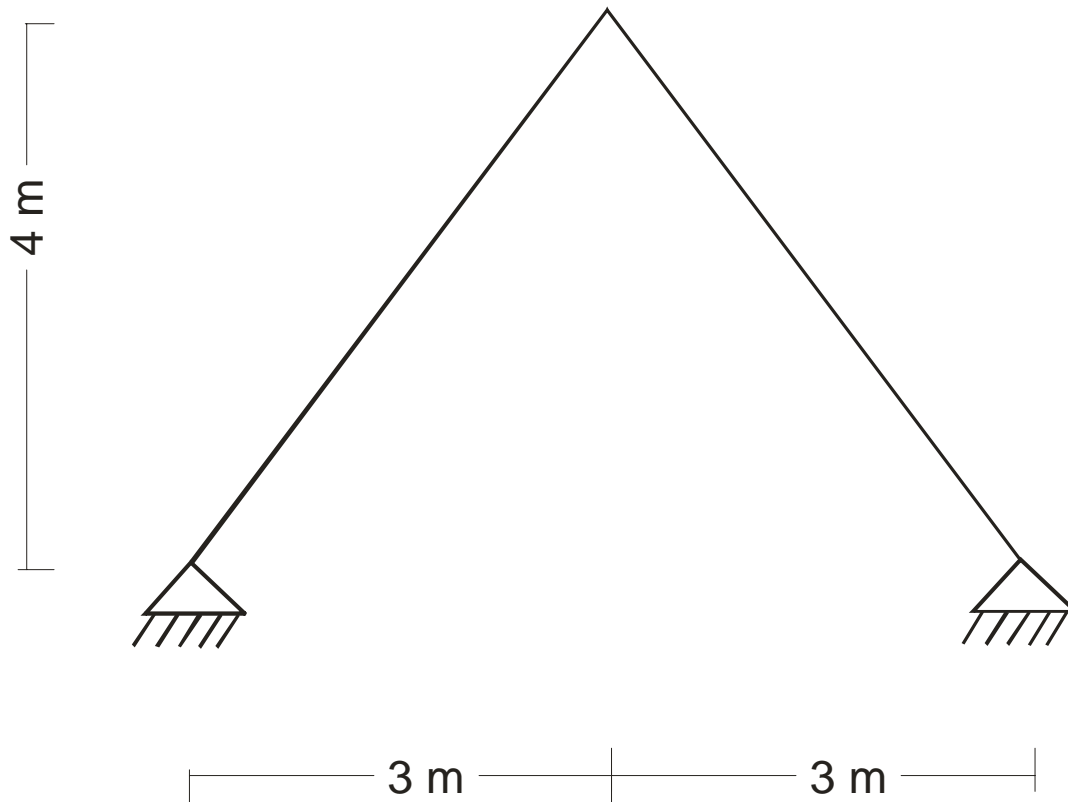
# Truss Element

## Consistent mass matrix

$$\mathbf{m}_{6 \times 6} = \frac{\gamma AL}{6} \begin{bmatrix} 2 & 0 & 0 & 1 & 0 & 0 \\ 0 & 2 & 0 & 0 & 1 & 0 \\ 0 & 0 & 2 & 0 & 0 & 1 \\ 1 & 0 & 0 & 2 & 0 & 0 \\ 0 & 1 & 0 & 0 & 2 & 0 \\ 0 & 0 & 1 & 0 & 0 & 2 \end{bmatrix}$$



# Example: Ex1



$$E = 200 \text{ GPa}$$

$$\rho = 7850 \text{ kg/m}^3$$

$$A = 0.01 \text{ m}^2$$

$$f_1 = 167 \text{ Hz}$$

$$f_2 = 223 \text{ Hz}$$

# Beam Element

**DE**

$$\frac{\partial}{\partial x^2} \left( EI \frac{\partial w}{\partial x^2} \right) = -\bar{\rho} \frac{\partial^2 w}{\partial t^2}$$

**Solution**

$$w(x, t) = W(x) \sin \omega t$$

**Substituting**

$$\frac{d^2}{dx^2} \left[ EI \frac{d^2 W}{dx^2} \right] - \bar{\rho} \omega^2 W = 0$$



# Beam Element

## Galerkin Step 1: Residual Equations

$$\int_{x_1}^{x_2} \left[ (EIW'')'' - \bar{\rho}\omega^2 W \right] \phi_i(x) dx = 0 \quad i = 1, 2, 3, 4$$

## Galerkin Step 2: Integration by parts

$$\int_{x_1}^{x_2} \left[ (EIW'')' \phi_i'' - \omega^2 \bar{\rho} W \phi_i \right] dx = \left[ (EIW'') \phi_i' \right]_{x_1}^{x_2} - \left[ (EIW'')' \phi_i \right]_{x_1}^{x_2}$$

# Beam Element

## Galerkin Step 3: Use of trial solution

$$W = \sum_{j=1}^4 a_j \phi_j$$

$$\left[ \mathbf{k}_{4 \times 4} - \omega^2 \mathbf{m}_{4 \times 4} \right] \mathbf{a}_{4 \times 1} = \begin{Bmatrix} -V(x_1) \\ M(x_1) \\ V(x_2) \\ -M(x_2) \end{Bmatrix}$$

## Sign Convention

$$EI \frac{\partial^2 w}{\partial x^2} = -M$$

$$\frac{d}{dx} \left[ EI \frac{\partial^2 w}{\partial x^2} \right] = -V$$

# Beam Element

## Planar beam element (2 dof/element)

$$\mathbf{m}'_{4 \times 4} = \frac{\rho AL}{420} \begin{bmatrix} 156 & & & \\ 22L & 4L^2 & & \\ 54 & 13L & 156 & \\ -13L & -3L^2 & -22L & 4L^2 \end{bmatrix} \begin{matrix} \\ \\ \\ \text{SYM} \end{matrix}$$

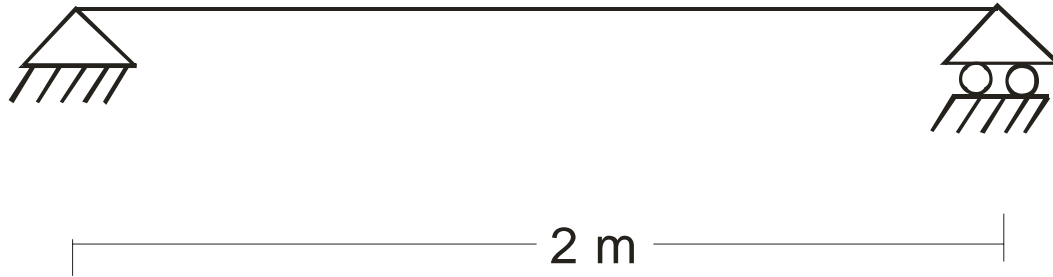
# Beam Element

## Planar beam element with axial deformation

$$\mathbf{m}'_{6 \times 6} = \frac{\rho AL}{420} \begin{bmatrix} 140 & & & & & \\ & 0 & 156 & & & \\ & 0 & 22L & 4L^2 & & \\ & 70 & 0 & 0 & 140 & \\ & 0 & 54 & 13L & 0 & 156 \\ & 0 & -13L & -3L^2 & 0 & -22L & 4L^2 \end{bmatrix} \quad \text{SYM}$$

$$\mathbf{m}_{6 \times 6} = \mathbf{T}_{6 \times 6}^T \mathbf{m}'_{6 \times 6} \mathbf{T}_{6 \times 6}$$

# Example



$$E = 10^{10} \text{ Pa}$$

$$\rho = 5000 \text{ kg/m}^3$$

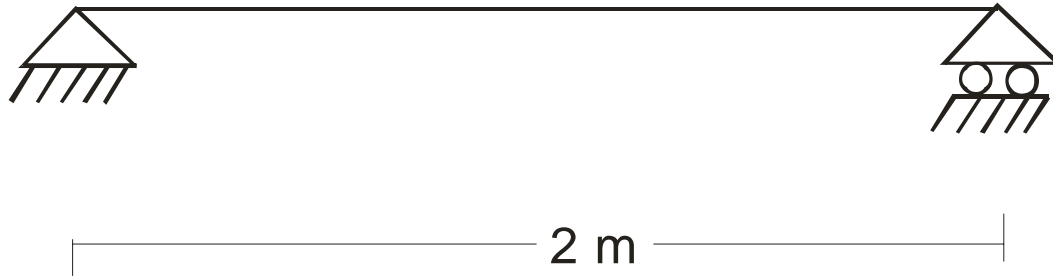
$$A = 0.001 \text{ m}^2$$

$$I = 0.0001 \text{ m}^4$$

## Analytical solution (bending modes)

$$\omega_n = \frac{(n\pi)^2}{L^2} \sqrt{\frac{EI}{\rho A}} \quad n = 1, 2, 3, \dots$$

## Example: Ex21 (1 Element)



$$E = 10^{10} \text{ Pa}$$

$$\rho = 5000 \text{ kg/m}^3$$

$$A = 0.001 \text{ m}^2$$

$$I = 0.0001 \text{ m}^4$$

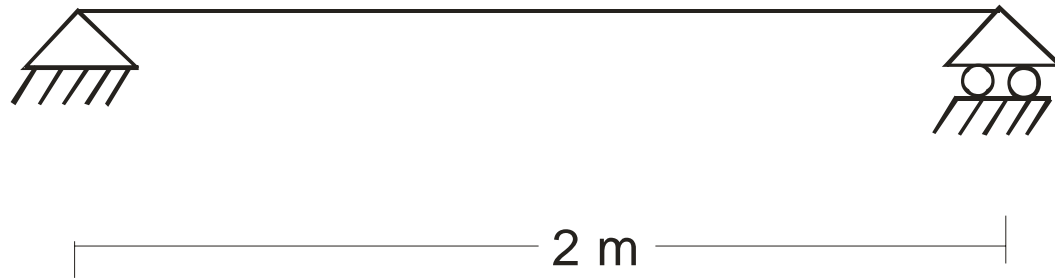
$$f_1 = 195 \text{ Hz}$$

$$f_2 = 195 \text{ Hz}$$

$$f_3 = 893 \text{ Hz}$$



## Example: Ex22 (2 Element)



$$E = 10^{10} \text{ Pa}$$

$$\rho = 5000 \text{ kg/m}^3$$

$$A = 0.001 \text{ m}^2$$

$$I = 0.0001 \text{ m}^4$$

$$f_1 = 176 \text{ Hz}$$

$$f_4 = 780 \text{ Hz}$$

$$f_2 = 181 \text{ Hz}$$

$$f_5 = 1960 \text{ Hz}$$

$$f_3 = 633 \text{ Hz}$$

# Convergence Study

Mode\ Elements	Frequency (Hz)				
	1	2	4	8	<b>Exact</b>
1	195	176	176	176	175.6
2	195	181	177	177	
3	893	633	561	538	
4	-	780	705	703	702.5
5	-	1960	1020	920	

# Lumped Mass Matrix

$$\mathbf{m}'_{6 \times 6} = \frac{\rho AL}{2} \begin{bmatrix} 1 & & & & & \\ & 1 & & & & \\ & 0 & 1 & & & \\ & 0 & 0 & 0 & & \\ & 0 & 0 & 0 & 1 & \\ & 0 & 0 & 0 & 0 & 1 \\ & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad \text{SYM}$$

# Consistent versus Lumped Mass (8 Elements)

Mode	Frequency (Hz)	
	Consistent	Lumped
1	176	176
2	177	176
3	538	523
4	703	702
5	920	849

# Summary

- $\mathbf{K}$  is symmetric and positive definite
- $\mathbf{M}$  is symmetric and possibly positive definite
- Eigenvalues are real and positive
- Eigenvalues converge from above

# Further Reading

- From the textbook
  - Chapter 11