Finite Elements for Engineers

Lecture 3: Isoparametric Formulation

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Isoparametric Formulation

- Equal number of parameters are used to represent the **geometry** and the unknown variable
- For example

Geometry
$$x(t) = a_0 + a_1 t + a_2 t^2$$

Unknown $u(t) = b_0 + b_1 t + b_2 t^2$

Mapping Options

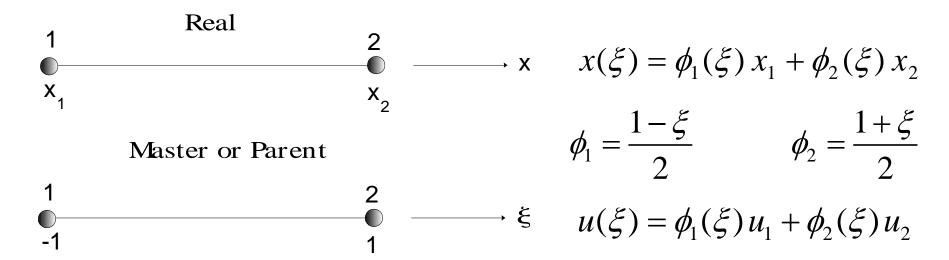
$$x(\xi) = \sum_{j=1}^{s} \hat{\phi}_{j}(\xi) x_{j}$$

$$u(\xi) = \sum_{i=1}^{r} \phi_i(\xi) u_i$$

$$s = r$$

1D Isoparametric Elements

1D-C⁰ Linear Isoparametric Element



Derivatives

$$\frac{dx}{d\xi} = \frac{(x_2 - x_1)}{2} = \frac{L}{2} = J \implies \frac{d\xi}{dx} = \frac{1}{dx/d\xi} = J^{-1} = \frac{2}{L}$$

1D-C⁰ Linear Isoparametric BVP Element

Step 2

$$\sum_{j=1}^{2} \left[\int_{\Omega} \frac{d\phi_i}{dx} \alpha(x) \frac{d\phi_j}{dx} dx + \int_{\Omega} \phi_i(x) \beta(x) \phi_j(x) dx \right] y_j =$$

$$\int_{\Omega} f(x)\phi_i(x) dx - \left[\tau\phi_i\right]^{\Gamma} \qquad i = 1, 2$$

$$\sum_{i=1}^{2} \left[k_{ij}^{\alpha} + k_{ij}^{\beta} \right] y_{j} = f_{i}^{\text{int}} + f_{i}^{bnd} \qquad i = 1, 2$$

1D-C⁰ Linear Element (cont'd)

Recall
$$\phi_1 = \frac{1-\xi}{2}$$
 $\phi_2 = \frac{1+\xi}{2}$ $J = \frac{dx}{d\xi} = \frac{L}{2}$
$$\frac{d\phi_1}{d\xi} = -\frac{1}{2} \qquad \frac{d\phi_2}{d\xi} = \frac{1}{2} \qquad \frac{d\phi_i}{dx} = \frac{d\phi_i}{d\xi} \frac{d\xi}{dx} = \frac{d\phi_i}{d\xi} \frac{2}{L}$$

$$k_{ij}^{\alpha} = \int_{\Omega} \frac{d\phi_{i}}{dx} \alpha(x) \frac{d\phi_{j}}{dx} dx = \int_{-1}^{1} \frac{d\phi_{i}}{d\xi} \alpha(x(\xi)) \frac{d\phi_{j}}{d\xi} \frac{4}{L^{2}} J d\xi$$

$$k_{ij}^{\beta} = \int_{\Omega} \phi_{i}(x) \beta(x) \phi_{j}(x) dx = \int_{-1}^{1} \phi_{i}(\xi) \beta(x(\xi)) \phi_{j}(\xi) \frac{L}{2} d\xi$$

1D-C⁰ Linear Element (cont'd)

Assuming that
$$\alpha(x) = \hat{\alpha}, \beta(x) = \hat{\beta}, f(x) = \hat{f}$$

For example

$$k_{11}^{\alpha} = \int_{-1}^{1} \frac{d\phi_{1}}{d\xi} \alpha(x(\xi)) \frac{d\phi_{1}}{d\xi} \frac{2}{L} d\xi = \int_{-1}^{1} \frac{1}{4} \alpha \frac{2}{L} d\xi = \frac{\alpha}{2L} (2) = \frac{\alpha}{L}$$

$$k_{12}^{\alpha} = \int_{-1}^{1} \frac{d\phi_{1}}{d\xi} \alpha(x(\xi)) \frac{d\phi_{2}}{d\xi} \frac{2}{L} d\xi = \int_{-1}^{1} \left(-\frac{1}{4} \right) \alpha \frac{2}{L} d\xi = -\frac{\alpha}{2L} (2) = -\frac{\alpha}{L}$$

$$k_{12}^{\beta} = \int_{-1}^{1} \phi_{1}(\xi) \beta \phi_{2}(\xi) \frac{L}{2} d\xi = \frac{\beta L}{8} \int_{-1}^{1} (1 - \xi^{2}) d\xi = \frac{\beta L}{6}$$

$$f_{1}^{\text{int}} = \int_{-1}^{1} \hat{f} \phi_{1}(\xi) \frac{L}{2} d\xi = \frac{\hat{f} L}{4} \int_{-1}^{1} (1 - \xi) d\xi = \frac{\hat{f} L}{2}$$

1D-C⁰ Linear Element (cont'd)

Element Equations

$$\left[\frac{\hat{\alpha}}{L} + \frac{\hat{\beta}L}{3} \quad -\frac{\hat{\alpha}}{L} + \frac{\hat{\beta}L}{6} \\
-\frac{\hat{\alpha}}{L} + \frac{\hat{\beta}L}{6} \quad \frac{\hat{\alpha}}{L} + \frac{\hat{\beta}L}{3} \right] - g_1 \left[\frac{1}{0} \mid 0 \right] + h_2 \left[\frac{0}{0} \mid 0 \right] \left\{ \frac{y_1}{y_2} \right\} =$$

$$\left\{ \frac{\widehat{f}L}{\widehat{f}L} \right\} + \left\{ \frac{c_1}{-c_2} \right\}$$

1D-C⁰ Quadratic Isoparametric BVP Element

Step 2

$$\sum_{j=1}^{3} \left[\int_{\Omega} \frac{d\phi_i}{dx} \alpha(x) \frac{d\phi_j}{dx} dx + \int_{\Omega} \phi_i(x) \beta(x) \phi_j(x) dx \right] y_j =$$

$$\int_{\Omega} f(x)\phi_i(x) dx - \left[\tau\phi_i\right]^{\Gamma} \qquad i = 1,3$$

$$\sum_{i=1}^{3} \left[k_{ij}^{\alpha} + k_{ij}^{\beta} \right] y_{j} = f_{i}^{\text{int}} + f_{i}^{bnd} \qquad i = 1, 3$$

1D-C⁰ Quadratic Isoparametric BVP Element

Always valid element geometry?

$$x = \frac{1}{2}\xi(\xi - 1)x_1 + (1 - \xi^2)x_2 + \frac{1}{2}\xi(\xi + 1)x_3$$

$$J = \frac{dx}{d\xi} = \left(\xi - \frac{1}{2}\right)x_1 + \left(-2\xi\right)x_2 + \left(\xi + \frac{1}{2}\right)x_3$$

$$J = \xi(x_1 - 2x_2 + x_3) + \frac{1}{2}(x_3 - x_1)$$

Need Jacobian to be positive throughout the element.

1D-C⁰ Quadratic Isoparametric BVP Element

$$J > 0 \quad -1 \le \xi \le 1$$

Hence

$$J(-1) = -\left(\frac{3}{2}\right)x_1 + (2)x_2 - \left(\frac{1}{2}\right)x_3 > 0 \implies x_2 > x_1 + \frac{L}{4}$$

$$J(+1) = \left(\frac{1}{2}\right)x_1 - (2)x_2 + \left(\frac{3}{2}\right)x_3 > 0 \implies x_2 < x_1 + \frac{3L}{4}$$

$$x_c - \frac{L}{4} \le x_2 \le x_c + \frac{L}{4}$$
 $x_c = \frac{x_1 + x_3}{2}$

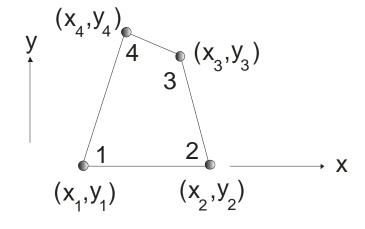
Optimal Flux Computations

Element		Location
1D Linear	$\xi = 0$	
1D Quadratic	$\xi_1 = -\frac{1}{\sqrt{3}}$	$\xi_2 = \frac{1}{\sqrt{3}}$

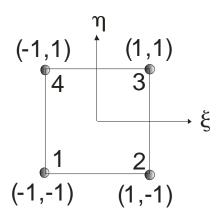
J. Barlow, Optimal stress locations in finite element models, Int. J. Numer. Methods Eng., 10, 243-251 (1976).

2D Isoparametric Elements

Real



Master



Mapping

$$x = \sum_{i=1}^{4} \phi_i(\xi, \eta) x_i \qquad y = \sum_{i=1}^{4} \phi_i(\xi, \eta) y_i$$

Derivatives

$$\frac{\partial x}{\partial \xi} = \sum_{i=1}^{4} \frac{\partial \phi_i}{\partial \xi} x_i \qquad \frac{\partial x}{\partial \eta} = \sum_{i=1}^{4} \frac{\partial \phi_i}{\partial \eta} x_i$$

$$\frac{\partial y}{\partial \xi} = \frac{4}{5} \frac{\partial \phi}{\partial \eta} x_i \qquad \frac{\partial y}{\partial \eta} = \frac{4}{5} \frac{\partial \phi}{\partial \eta} x_i$$

$$\frac{\partial y}{\partial \xi} = \sum_{i=1}^{4} \frac{\partial \phi_i}{\partial \xi} y_i$$

$$\frac{\partial x}{\partial \eta} = \sum_{i=1}^{4} \frac{\partial \phi_i}{\partial \eta} x_i$$

$$\frac{\partial y}{\partial \xi} = \sum_{i=1}^{4} \frac{\partial \phi_i}{\partial \xi} y_i \qquad \frac{\partial y}{\partial \eta} = \sum_{i=1}^{4} \frac{\partial \phi_i}{\partial \eta} y_i$$

2D Isoparametric Elements

Derivatives $u = u(\xi, \eta)$

$$\frac{\partial u}{\partial \xi} = \frac{\partial u}{\partial x} \frac{\partial x}{\partial \xi} + \frac{\partial u}{\partial y} \frac{\partial y}{\partial \xi} \qquad \qquad \frac{\partial u}{\partial \eta} = \frac{\partial u}{\partial x} \frac{\partial x}{\partial \eta} + \frac{\partial u}{\partial y} \frac{\partial y}{\partial \eta}$$

$$\frac{\partial u}{\partial \eta} = \frac{\partial u}{\partial x} \frac{\partial x}{\partial \eta} + \frac{\partial u}{\partial y} \frac{\partial y}{\partial \eta}$$

$$\left\{ \begin{array}{l} u, \zeta \\ u, \eta \end{array} \right\} = \begin{bmatrix} \frac{\partial x}{\partial \xi} & \frac{\partial y}{\partial \xi} \\ \frac{\partial x}{\partial \eta} & \frac{\partial y}{\partial \eta} \end{bmatrix} \left\{ \begin{array}{l} u, \zeta \\ u, \gamma \end{array} \right\} = \mathbf{J}_{2 \times 2} \left\{ \begin{array}{l} u, \zeta \\ u, \gamma \end{array} \right\}$$

$$\begin{cases} u,_{x} \\ u,_{y} \end{cases} = \mathbf{\Gamma}_{2 \times 2} \begin{cases} u,_{\xi} \\ u,_{\eta} \end{cases} \implies \mathbf{\Gamma} = \mathbf{J}^{-1}$$

Summary

- Isoparametric formulation has several advantages.
 - It ties in nicely with the manner in which shape functions are generated (the use of a master element and the family of low and higher-order elements)
 - It ties in nicely with numerical integration (Gauss Quadrature)
 - It helps detect elements that have bad aspect ratios

Summary

- Isoparametric Formulation
 - Lends itself to automation
 - Easy to write computer programs for the entire family of elements
 - Differences between the elements in a family are (a) the shape functions and (b) the number of integration points required for numerical integration