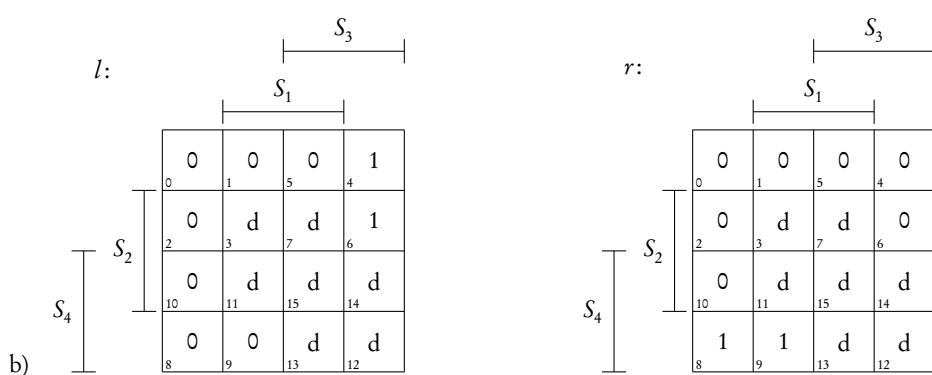


Musterlösung 7. Gruppenübung

Digitaltechnik und Rechnersysteme • Wintersemester 2025/2026

1.1 Transportwagensteuerung

| S_4 | S_3 | S_2 | S_1 | l | r |
|-------|-------|-------|-------|-----|-----|
| 0 | 0 | 0 | 0 | 0 | 0 |
| 0 | 0 | 0 | 1 | 0 | 0 |
| 0 | 0 | 1 | 0 | 0 | 0 |
| 0 | 0 | 1 | 1 | d | d |
| 0 | 1 | 0 | 0 | 1 | 0 |
| 0 | 1 | 0 | 1 | 0 | 0 |
| 0 | 1 | 1 | 0 | 1 | 0 |
| a) | 0 | 1 | 1 | d | d |
| 1 | 0 | 0 | 0 | 0 | 1 |
| 1 | 0 | 0 | 1 | 0 | 1 |
| 1 | 0 | 1 | 0 | 0 | 0 |
| 1 | 0 | 1 | 1 | d | d |
| 1 | 1 | 0 | 0 | d | d |
| 1 | 1 | 0 | 1 | d | d |
| 1 | 1 | 1 | 0 | d | d |
| 1 | 1 | 1 | 1 | d | d |



l:

| | | | |
|----|----|-------|-------|
| | | | S_3 |
| | | S_1 | |
| | | | |
| | 0 | 0 | 0 |
| 0 | 1 | 5 | 4 |
| 2 | 0 | d | d |
| 3 | 3 | 7 | 6 |
| 10 | 0 | d | d |
| 11 | 11 | 15 | 14 |
| 8 | 0 | 0 | d |
| 9 | 9 | 13 | 12 |

r:

| | | |
|----|----|-------|
| | | S_3 |
| | | S_1 |
| | | |
| | 0 | 0 |
| 0 | 1 | 5 |
| 2 | 0 | d |
| 3 | 3 | d |
| 10 | 0 | d |
| 11 | 11 | d |
| 15 | 15 | d |
| 14 | 14 | d |
| 8 | 1 | 1 |
| 9 | 9 | d |
| 13 | 13 | d |
| 12 | 12 | d |

Rot markierte Primimplikanten sind API's, der Rest sind KPI's.

d) kostengünstigste DNF:

$$l(S_1, S_2, S_3, S_4) = \overline{S_1} S_3$$

$$r(S_1, S_2, S_3, S_4) = \overline{S_2} S_4$$

