

# COURSE 13

## The matrix of a linear map

First, we define the matrix of a vector in a basis of a vector space. For certain reasons, it is presented as a column-matrix, but it must be said that this is rather a convention than a constraint. But if one changes the convention, the form of the next notions and results must be properly changed.

Let  $K$  be a field.

**Definition 1.** Let  $V$  be a  $K$ -vector space,  $v \in V$  and  $B = (v_1, \dots, v_n)$  a basis of  $V$ . If

$$\rightarrow v = k_1 v_1 + \dots + k_n v_n \quad (k_1, \dots, k_n \in K) \quad n \in \mathbb{N}^*$$

is the unique representation of  $v$  as a linear combination of the vectors of  $B$ , then the **matrix of the vector**  $v$  in the basis  $B$  is

$$\underline{\underline{[v]_B}} = \begin{pmatrix} k_1 \\ \vdots \\ k_n \end{pmatrix}$$

**Definition 2.** Let  $f : V \rightarrow V'$  be a  $K$ -linear map, let  $B = (v_1, \dots, v_n)$  be a basis of  $V$  and let  $B' = (v'_1, \dots, v'_m)$  be a basis of  $V'$ . Then we can uniquely write the vectors of  $f(B)$  as linear combinations of the vectors of  $B'$ , i.e. there exist  $a_{ij} \in K$  ( $i \in \{1, \dots, m\}, j \in \{1, \dots, n\}$ ) uniquely determined such that

[illegible]

→ Then the matrix of the  $K$ -linear map  $f$  in the pair of bases  $(B, B')$  (or, simply, in the bases  $B$  and  $B'$ ) is the matrix whose columns consist of the coordinates of the vectors of  $f(B)$  in the basis  $B'$ , that is,

These columns consist of the coordinates of the vectors of  $f$  (in  $B'$ )  
 ord.  $f(v_1)$   $f(v_2)$   $f(v_n)$  in  $B'$   
 $\rightarrow \underline{[f]_{BB'}} = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix} \in M_{\underline{m}, \underline{n}}(K)$

For  $V = V'$  and  $B = B'$ , we denote  $[f]_B = [f]_{BB}$  and we call it the **matrix of  $f$**  in the basis  $B$ .

**Remarks 3.** (1) We complete the matrix of a linear map by columns. This is also a part of the convention we mentioned at the beginning of this section.

→ (2) As we will see next, the matrix of a linear map depends on the map, on the considered bases, but also by the order of the elements in each basis.

**Examples 4.** a) For any  $n$ -dimensional  $K$ -vector space  $V$  and any basis  $B$  of  $V$ , we have

$$[1_V]_B = I_n.$$

$$\{ \{ v \}_{B, B'} \neq I_u$$

b) Consider the  $\mathbb{R}$ -linear map  $f : \mathbb{R}^4 \rightarrow \mathbb{R}^3$  defined by

$$f(x, y, z, t) = (x + y + z, y + z + t, z + t + x), \quad \forall (x, y, z, t) \in \mathbb{R}^4.$$

h.w. ( $\neq \mathbb{R}$ -linear map)

Let  $E = (e_1, e_2, e_3, e_4)$  and  $E' = (e'_1, e'_2, e'_3)$  be the standard bases in  $\mathbb{R}^4$  and  $\mathbb{R}^3$  respectively. Since

$$\begin{cases} f(e_1) = f(1, 0, 0, 0) = (1, 0, 1) = e'_1 + e'_3 \quad \leftarrow \\ f(e_2) = f(0, 1, 0, 0) = (1, 1, 0) = e'_1 + e'_2 \quad \leftarrow \\ f(e_3) = f(0, 0, 1, 0) = (1, 1, 1) = e'_1 + e'_2 + e'_3 \quad \leftarrow \\ f(e_4) = f(0, 0, 0, 1) = (0, 1, 1) = e'_2 + e'_3 \quad \leftarrow \end{cases}$$

it follows that the matrix of  $f$  in the bases  $E$  and  $E'$  is

$$[f]_{EE'} = \begin{pmatrix} 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \end{pmatrix}.$$

$\leftarrow f(e_1) \quad f(e_2) \quad f(e_3) \quad f(e_4)$

→ c) Let  $\mathbb{R}_n[X]$  be the  $\mathbb{R}$ -vector space of the polynomials with the degree at most  $n$  and real coefficients. The map

$$\varphi : \mathbb{R}_3[X] \rightarrow \mathbb{R}_2[X], \quad \varphi(a_0 + a_1X + a_2X^2 + a_3X^3) = a_1 + 2a_2X + 3a_3X^2$$

(which associates a polynomial  $f$  its formal derivative  $f'$ ) is a linear map. Let us write the matrix of  $\varphi$  in the pair of basis  $B = (1, X, X^2, X^3)$ ,  $B' = (1, X, X^2)$ , and then in the pair of basis  $B = (1, X, X^2, X^3)$ ,  $B'' = (X^2, 1, X)$ . We have

$$\begin{aligned} \varphi(1) &= 0 \cdot 1 + 0 \cdot X + 0 \cdot X^2 = 0 \cdot X^2 + 0 \cdot 1 + 0 \cdot X \\ \varphi(X) &= 1 \cdot 1 + 0 \cdot X + 0 \cdot X^2 = 0 \cdot X^2 + 1 \cdot 1 + 0 \cdot X \\ \varphi(X^2) &= 0 \cdot 1 + 2 \cdot X + 0 \cdot X^2 = 0 \cdot X^2 + 0 \cdot 1 + 2 \cdot X \\ \varphi(X^3) &= 0 \cdot 1 + 0 \cdot X + 3 \cdot X^2 = 3 \cdot X^2 + 0 \cdot 1 + 0 \cdot X \end{aligned}$$

thus,

$$[\varphi]_{BB'} = \begin{pmatrix} \downarrow & \downarrow & \downarrow & \downarrow \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{pmatrix} \quad \text{and} \quad [\varphi]_{BB''} = \begin{pmatrix} \downarrow & \downarrow & \downarrow & \downarrow \\ 0 & 0 & 0 & 3 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \end{pmatrix}.$$

→ d) Let  $K$  be a field,  $m, n \in \mathbb{N}^*$ ,  $A \in M_{m,n}(K)$ ,  $E$  the standard basis of  $K^n$  and  $E'$  the standard basis of  $K^m$ . Then

$$f_A : K^n \rightarrow K^m, \quad f_A(x_1, \dots, x_n) = A \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n \\ \vdots \\ a_{m1}x_1 + \dots + a_{mn}x_n \end{pmatrix}$$

$\leftarrow (a_{ij})$

h.w. is a linear map and  $[f_A]_{EE'} = A$ .

→ **Theorem 5.** Let  $f : V \rightarrow V'$  be a  $K$ -linear map,  $B = (v_1, \dots, v_n)$  a basis of  $V$ ,  $B' = (v'_1, \dots, v'_m)$  a basis of  $V'$  and  $v \in V$ . Then

$$\begin{array}{c} \rightarrow \\ \underline{[f(v)]_{B'}} = \underline{[f]_{BB'}} \cdot \underline{[v]_B} \\ \uparrow \qquad \qquad \uparrow \end{array}$$

*Proof.* Let  $[f]_{BB'} = (a_{ij}) \in M_{mn}(K)$ . Let  $v = \sum_{j=1}^n k_j v_j$  and  $f(v) = \sum_{i=1}^m k'_i v'_i$  with  $k_i, k'_i \in K$ . On the other hand, using the definition of the matrix of  $f$  in the bases  $B$  and  $B'$ , we have

$$f(v) = f\left(\sum_{j=1}^n k_j v_j\right) = \sum_{j=1}^n k_j f(v_j) = \sum_{j=1}^n k_j \left(\sum_{i=1}^m a_{ij} v'_i\right) = \sum_{i=1}^m \left(\sum_{j=1}^n a_{ij} k_j\right) v'_i.$$

But there is only one way to write  $f(v)$  as a linear combination of the vectors of the basis  $B'$ , hence we have

$$k'_i = \sum_{j=1}^n a_{ij} k_j, \forall i \in \{1, \dots, m\}.$$

Therefore,  $[f(v)]_{B'} = [f]_{BB'} \cdot [v]_B$ . □

For a  $K$ -linear map  $f : V \rightarrow V'$  the dimension  $\dim(\text{Im} f)$  is also called the rank of  $f$ . We denote it by  $\text{rank}(f)$ . The rank of a linear map and the rank of its matrix in a pair of bases are strongly connected.

→ **Theorem 6.** Let  $f : V \rightarrow V'$  be a  $K$ -linear map. Then

$$\text{rank}(f) = \text{rank}[f]_{BB'},$$

where  $B$  and  $B'$  are arbitrary bases of  $V$  and  $V'$  respectively.

*Proof.* Let  $B = (v_1, \dots, v_n)$  and  $[f]_{BB'} = A$ . We have

$$\begin{aligned} \text{rank}(f) &= \dim(\text{Im} f) = \dim f(V) = \dim f(\langle v_1, \dots, v_n \rangle) = \dim \langle f(v_1), \dots, f(v_n) \rangle = \\ &= \text{rank}({}^t A) = \text{rank}(A) = \text{rank}[f]_{BB'}. \end{aligned}$$

□

**Remark 7.** The matrices of a linear map in different pairs of bases have the same rank.

We continue this section by presenting one of the key results in Linear Algebra, connecting linear maps and matrices.

→ **Theorem 8.** Let  $V, V'$  and  $V''$  be vector spaces over  $K$  with  $\dim V = n$ ,  $\dim V' = m$  and  $\dim V'' = p$  and let  $B, B'$  and  $B''$  be bases of  $V, V'$  and  $V''$  respectively. If  $f, g \in \text{Hom}_K(V, V')$ ,  $h \in \text{Hom}_K(V', V'')$  and  $k \in K$ , then

$$[f + g]_{BB'} = [f]_{BB'} + [g]_{BB'}, \quad [kf]_{BB'} = k \cdot [f]_{BB'},$$

$$\rightarrow [h \circ f]_{BB''} = [h]_{B'B''} \cdot [f]_{BB'}.$$

*Proof.* If  $[f]_{BB'} = (a_{ij}) \in M_{mn}(K)$ ,  $[g]_{BB'} = (b_{ij}) \in M_{mn}(K)$  and  $[h]_{B'B''} = (c_{ki}) \in M_{pm}(K)$  then

$$f(v_j) = \sum_{i=1}^m a_{ij} v'_i, \quad g(v_j) = \sum_{i=1}^m b_{ij} v'_i, \quad h(v'_i) = \sum_{k=1}^p c_{ki} v''_k$$

for any  $j \in \{1, \dots, n\}$  and for any  $i \in \{1, \dots, m\}$ .

Then for any  $k \in K$  and for any  $j \in \{1, \dots, n\}$  we have

$$(f + g)(v_j) = f(v_j) + g(v_j) = \sum_{i=1}^m a_{ij} v'_i + \sum_{i=1}^m b_{ij} v'_i = \sum_{i=1}^m (a_{ij} + b_{ij}) v'_i,$$

$$(kf)(v_j) = kf(v_j) = k \cdot \left( \sum_{i=1}^m a_{ij} v'_i \right) = \sum_{i=1}^m (ka_{ij}) v'_i,$$

hence  $[f + g]_{BB'} = [f]_{BB'} + [g]_{BB'}$  and  $[kf]_{BB'} = k \cdot [f]_{BB'}$ .

Finally, for any  $j \in \{1, \dots, n\}$  we have

$$\begin{aligned} (h \circ f)(v_j) &= h(f(v_j)) = h \left( \sum_{i=1}^m a_{ij} v'_i \right) = \sum_{i=1}^m a_{ij} h(v'_i) = \sum_{i=1}^m a_{ij} \left( \sum_{k=1}^p c_{ki} v''_k \right) = \\ &= \sum_{k=1}^p \sum_{i=1}^m (c_{ki} a_{ij}) v''_k = \sum_{k=1}^p \left( \sum_{i=1}^m c_{ki} a_{ij} \right) v''_k, \end{aligned}$$

hence  $[h \circ f]_{BB''} = [h]_{B'B''} \cdot [f]_{BB'}$ . □

→ **Theorem 9.** Let  $V$  and  $V'$  be vector spaces over  $K$  with  $\dim V = n$  and  $\dim V' = m$  and let  $B$  and  $B'$  be bases of  $V$  and  $V'$  respectively. Then the map  $\varphi : \text{Hom}_K(V, V') \rightarrow M_{mn}(K)$  defined by

$$\varphi(f) = [f]_{BB'}, \quad \forall f \in \text{Hom}_K(V, V')$$

is an isomorphism of vector spaces.

*Proof.* Let us prove first that  $\varphi$  is bijective.

Let  $f, g \in \text{Hom}_K(V, V')$  such that  $\varphi(f) = \varphi(g)$ . Then  $[f]_{BB'} = [g]_{BB'} = (a_{ij})$  and

$$f(v_j) = a_{1j} v'_1 + a_{2j} v'_2 + \dots + a_{mj} v'_m = g(v_j), \quad \forall j \in \{1, \dots, n\}.$$

Then  $f = g$  by the universal property of vector spaces. Thus,  $\varphi$  is injective.

Now let  $A = (a_{ij}) \in M_{mn}(K)$ , seen as a list of column-vectors  $(a^1, \dots, a^n)$ , where  $a^j = \begin{pmatrix} a_{1j} \\ \vdots \\ a_{mj} \end{pmatrix}$ .

Consider  $B = (v_1, \dots, v_n)$  and  $B' = (v'_1, \dots, v'_m)$  and consider the  $K$ -linear map  $f : V \rightarrow V'$  defined on the basis  $B$  of  $V$  by

$$f(v_j) = a_{1j} v'_1 + \dots + a_{mj} v'_m, \quad \forall j \in \{1, \dots, n\}.$$

Then

$$\varphi(f) = [f]_{BB'} = (a_{ij}) = A.$$

Thus,  $\varphi$  is surjective.

The proof is completed by Theorem 8. □

**Remark 10.** The extremely important isomorphism given in Theorem 9 allows us to work with matrices instead of linear maps, which is much simpler from a computational point of view.

As we previously saw,  $(\text{End}_K(V), +, \circ)$  is a unitary ring.

→ **Theorem 11.** Let  $V$  be a vector space over  $K$  with  $\dim V = n$  and let  $B$  be a basis of  $V$ . Then the map  $\varphi : \text{End}_K(V) \rightarrow M_n(K)$  defined by

$$\varphi(f) = [f]_B, \quad \forall f \in \text{End}_K(V)$$

is an isomorphism of vector spaces and of rings.

*Proof.* It follows by Theorem 8 and Theorem 9.

**Corollary 12.** Let  $V$  be a  $K$ -vector space,  $B$  an arbitrary basis of  $V$  and  $f \in \text{End}_K(V)$ . Then

$$f \in \operatorname{Aut}_K(V) \Leftrightarrow \det[f]_B \neq 0.$$

Indeed,  $f \in \text{Aut}_K(V)$  (i.e.  $f$  is a unit in the ring  $(\text{End}_K(V), +, \circ)$ ) if and only if  $[f]_B$  is a unit in  $(M_n(K), +, \cdot)$  which means that  $\det[f]_B \neq 0$ .

**Definition 13.** Let  ~~$B = (v_1, \dots, v_n)$~~   $B = (v_1, \dots, v_n)$  and  $B' = (\underline{v'_1}, \dots, \underline{v'_n})$  be bases of  $V$ . Then we can write

[illegible]

for some  $t_{ij} \in K$ . Then the matrix  $(t_{ij}) \in M_n(K)$ , having as columns the coordinates of the vectors of the basis  $B'$  in the basis  $B$ , is called the transition matrix from  $B$  to  $B'$  and is denoted by  $T_{BB'}$ .

**Remarks 14.** 1) Sometimes the basis  $B$  is referred to as the "old" basis and the basis  $B'$  is referred to as the "new" basis.

→ 2) The  $j$ -th column of  $T_{BB'}$  ( $j = 1, \dots, n$ ) consists of the coordinates of  $v'_j = 1_V(v'_j)$  in the basis  $B$ , hence  $T_{BB'} = [1_V]_{B'B}$ .

**Theorem 15.** Let  $B = (v_1, \dots, v_n)$  and  $B' = (v'_1, \dots, v'_n)$  be bases of  $V$ . Then the transition matrix  $T_{BB'}$  is invertible and its inverse is the transition matrix  $T_{B'B}$ .

*Proof.* Since  $T = T_{BB'}$  is the transition matrix from the basis  $B$  to the basis  $B'$  we have

$$v'_j = \sum_{i=1}^n t_{ij} v_i, \quad \forall j \in \{1, \dots, n\}.$$

Denote  $S = (s_{ij}) \in M_{mn}(K)$  the transition matrix from the basis  $B'$  to the basis  $B$ . Then

$$v_i = \sum_{k=1}^n s_{ki} v'_k, \quad \forall i \in \{1, \dots, n\}.$$

It follows that

$$v'_j = \sum_{i=1}^n t_{ij} \left( \sum_{k=1}^n s_{ki} v'_k \right) = \sum_{k=1}^n \left( \sum_{i=1}^n s_{ki} t_{ij} \right) v'_k.$$

By the uniqueness of writing of each  $v'_j$  as linear combination of the vectors of the basis  $B'$ , it follows that

$$\sum_{i=1}^n s_{ki} t_{ij} = \begin{cases} 1 & \text{if } k = j \\ 0 & \text{if } k \neq j \end{cases},$$

that is,  $S \cdot T = I_n$ .

Similarly, one can show that  $T \cdot S = I_n$ . Thus,  $T$  is invertible and its inverse is  $S$ .

→ **Theorem 16.** Let  $B = (v_1, \dots, v_n)$  and  $B' = (v'_1, \dots, v'_n)$  be bases of  $V$  and let  $v \in V$ . Then

$$\underline{[v]_B} = T_{BB'} \cdot \underline{[v]_{B'}}.$$

Proof. Let  $v \in V$  and let us write  $v$  in the two bases  $B$  and  $B'$ . Then

$$v = \sum_{i=1}^n k_i v_i \text{ and } v = \sum_{j=1}^n k'_j v'_j$$

for some  $k_i, k'_j \in K$ . Since  $T_{BB'} = (t_{ij}) \in M_n(K)$ , we have

$$v'_j = \sum_{i=1}^n t_{ij} v_i, \quad \forall j \in \{1, \dots, n\}.$$

It follows that

$$v = \sum_{j=1}^n k'_j \left( \sum_{i=1}^n t_{ij} v_i \right) = \sum_{i=1}^n \left( \sum_{j=1}^n t_{ij} k'_j \right) v_i.$$

By the uniqueness of writing of  $v$  as a linear combination of the vectors of  $B$ , it follows that

$$k_i = \sum_{j=1}^n t_{ij} k'_j,$$

hence  $[v]_B = T_{BB'} \cdot [v]_{B'}$ . □

**Remark 17.** Usually, we are interested in computing the coordinates of a vector  $v$  in the new basis  $B'$ , knowing the coordinates of the same vector  $v$  in the old basis  $B$  and the transition matrix from  $B$  to  $B'$ . Then by Theorem 16, we have

$$[v]_{B'} = T_{BB'}^{-1} \cdot [v]_B = T_{B'B} \cdot [v]_B.$$

**Theorem 18.** Let  $f \in \text{Hom}_K(V, V')$ , let  $B_1$  and  $B_2$  be bases of  $V$  and let  $B'_1$  and  $B'_2$  be bases of  $V'$ . Then

$$[f]_{B'_2 B'_1} = T_{B'_1 B'_2}^{-1} \cdot [f]_{B_1 B'_1} \cdot T_{B_1 B_2}.$$

*Proof.* We have  $T_{B_1 B_2} = [1_V]_{B_2 B_1}$  and  $T_{B'_1 B'_2} = [1_{V'}]_{B'_2 B'_1}$  (see Remark 14 2)). Of course, we also have  $T_{B'_1 B'_2}^{-1} = [1_{V'}]_{B'_1 B'_2}$  and by applying Theorem 8 to the equality  $f = 1_{V'} \circ f \circ 1_V$  we get

$$[f]_{B'_2 B'_1} = [1_{V'}]_{B'_1 B'_2} \cdot [f]_{B_1 B'_1} \cdot [1_V]_{B_2 B_1} = T_{B'_1 B'_2}^{-1} \cdot [f]_{B_1 B'_1} \cdot T_{B_1 B_2},$$

hence the expected conclusion. □

If we take  $V' = V$ ,  $B_1 = B'_1$  and  $B_2 = B'_2$ , we deduce:

**Corollary 19.** Let  $f \in \text{End}_K(V)$  and let  $B_1$  and  $B_2$  be bases of  $V$ . Then

$$[f]_{B_2} = T_{B_1 B_2}^{-1} \cdot [f]_{B_1} \cdot T_{B_1 B_2}.$$

### Exercise

*h.w.*

Let  $f : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ ,  $f(x, y) = (x + y, 2x - y, 3x + 2y)$ . Show that  $f$  is an  $\mathbb{R}$ -linear map, that  $B = ((1, 2), (-2, 1))$  and  $B' = ((1, -1, 0), (-1, 0, 1), (1, 1, 1))$  are bases for  $\mathbb{R}^2$  and  $\mathbb{R}^3$ , respectively, then determine the matrix of  $f$  in the pair of bases  $(B, B')$ .

Solution 1:  $B$  basis in  $\mathbb{R}^2 \iff \begin{vmatrix} 1 & -2 \\ 2 & 1 \end{vmatrix} \neq 0$

$B'$  basis in  $\mathbb{R}^3 \iff \begin{vmatrix} 1 & -1 & 1 \\ -1 & 0 & 1 \\ 0 & 1 & 1 \end{vmatrix} \neq 0$   $\checkmark$  l.w.

$[f]_{BB'} = \begin{pmatrix} \frac{10}{3} & \frac{5}{3} \\ \frac{11}{3} & -\frac{2}{3} \\ \frac{10}{3} & -\frac{10}{3} \end{pmatrix} \in M_{3,2}(\mathbb{R})$

$(3, 0, 7) = f(1, 2) = a_{11}(1, -1, 0) + a_{21}(-1, 0, 1) + a_{31}(1, 1, 1) \iff$

$\iff \begin{cases} a_{11} - a_{21} + a_{31} = 3 \\ -a_{11} + a_{31} = 0 \\ a_{21} + a_{31} = 7 \end{cases} \implies \begin{aligned} a_{11} &= \frac{10}{3} \\ a_{21} &= \frac{11}{3} \\ 3a_{31} &= 10 \implies a_{31} = \frac{10}{3} \end{aligned}$

$(-1, -5, -4) = f(-2, 1) = a_{12}(1, -1, 0) + a_{22}(-1, 0, 1) + a_{32}(1, 1, 1) \iff$

$\iff \begin{cases} a_{12} - a_{22} + a_{32} = -1 \\ -a_{12} + a_{32} = -5 \\ a_{22} + a_{32} = -4 \end{cases} \implies \begin{aligned} a_{12} &= \frac{5}{3} \\ a_{22} &= -\frac{8}{3} \\ 3a_{32} &= -10 \implies a_{32} = -\frac{10}{3} \end{aligned}$

Solution 2:  $E, E'$  standard bases of  $\mathbb{R}^2$  and  $\mathbb{R}^3$ , respectively

$[f]_{EE'} = \begin{pmatrix} 1 & 1 \\ 2 & -1 \\ 3 & 2 \end{pmatrix}$   $f(e_1) = f(1, 0) = (1, 2, 3)$   
 $f(e_2) = f(0, 1) = (1, -1, 2)$

$E \implies B$  ,  $T_{EB} = \begin{pmatrix} 1 & -2 \\ 2 & 1 \end{pmatrix}$  invertible  $\implies B$  basis for  $\mathbb{R}^2$

$E' \implies B'$  ,  $T_{E'B'} = \begin{pmatrix} 1 & -1 & 1 \\ -1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix} \xrightarrow{\text{row ops}} \implies B'$  basis for  $\mathbb{R}^3$

$$[f]_{BB'} = \overset{\uparrow}{T_{E'B'}^{-1}} \cdot \underset{\uparrow}{[f]_{EE'}} \cdot \underset{\uparrow}{T_{EB}} = \dots$$