SEMINAR 13+14

1) a) Let $\varphi \in \mathbb{R}$. Show that the plane rotation

$$h: \mathbb{R}^2 \to \mathbb{R}^2, \ h(x,y) = (x\cos\varphi - y\sin\varphi, x\sin\varphi + y\cos\varphi),$$

is an automorphism of \mathbb{R}^2 . Write the matrix of h of \mathbb{R}^2 in the standard basis (i.e. the basis $E = (e_1, e_2)$, with $e_1 = (1, 0)$, $e_2 = (0, 1)$).

- b) Show that $f: \mathbb{R}^2 \to \mathbb{R}^2$, f(x,y) = (x,-y) (the symmetry with respect to Ox) and $g: \mathbb{R}^2 \to \mathbb{R}^2$, g(x,y) = (-x,y) (the symmetry with respect to Oy) are automorphisms of \mathbb{R}^2 . Find the matrices of f, g, f-g, f+2g and $g \circ f$ in the standard basis.
- 2) Let $f: \mathbb{R}^2 \to \mathbb{R}^3$, f(x,y) = (x+y,2x-y,3x+2y). Show that f is an \mathbb{R} -linear map, that B = ((1,2),(-2,1)) and B' = ((1,-1,0),(-1,0,1),(1,1,1)) are bases for \mathbb{R}^2 and \mathbb{R}^3 , respectively, then determine the matrix of f in the pair of bases (B,B').

Extra: Show that (v_1, v_2, v_3) and (v'_1, v'_2, v'_3) with

$$v_1 = (1, 2, 1), v_2 = (2, 3, 3), v_3 = (3, 7, 1)$$
 si $v_1' = (3, 1, 4), v_2' = (5, 2, 1), v_3' = (1, 1, -6)$

are bases of \mathbb{R}^3 and find a connection between the matrices of a given vector in these two bases.

3) Let $B = (v_1, v_2, v_3, v_4)$ be a basis of the \mathbb{R} -vector space \mathbb{R}^4 , the vectors

$$u_1 = v_1, \ u_2 = v_1 + v_2, \ u_3 = v_1 + v_2 + v_3, \ u_4 = v_1 + v_2 + v_3 + v_4$$

and $f \in End_{\mathbb{R}}(\mathbb{R}^4)$ with

$$[f]_B = \begin{pmatrix} 1 & 2 & 0 & 1 \\ 3 & 0 & -1 & 2 \\ 2 & 5 & 3 & 1 \\ 1 & 2 & 1 & 3 \end{pmatrix}.$$

Show that $B' = (u_1, u_2, u_3, u_4)$ is a basis of \mathbb{R}^4 and find the matrix $[f]_{B'}$.

4) Let V be a real vector space, $B = (v_1, v_2, v_3)$ a basis of V, the vectors

$$u_1 = v_1 + 2v_2 + v_3, \ u_2 = v_1 + v_2 + 2v_3, \ u_3 = v_1 + v_2$$

and $f \in End_{\mathbb{R}}(V)$. Show that $B' = (u_1, u_2, u_3)$ is a basis of V and determine the matrix $[f]_B$ provided that

$$[f]_{B'} = \left(\begin{array}{ccc} 1 & 1 & 3 \\ 0 & 5 & -1 \\ 2 & 7 & -3 \end{array}\right).$$

5) Let V, V' be \mathbb{R} -vector spaces, $a = (a_1, a_2, a_3)$, $b = (b_1, b_2, b_3)$ bases in V and V', respectively and $f: V \to V'$ a \mathbb{R} -linear map with

$$[f]_{a,b} = \left(\begin{array}{rrr} -1 & 0 & 1\\ 1 & 0 & -1\\ 0 & 0 & 0 \end{array}\right).$$

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Determine:

- i) f(v) for an arbitrary $v \in V$;
- ii) the dimensions of $\operatorname{Im} f$ and $\operatorname{Ker} f$;
- iii) the matrix $[f]_{a',b'}$ when $a' = (a_1, a_1 + a_2, a_1 + a_2 + a_3)$ and $b' = (b_1, b_1 + b_2, b_1 + b_2 + b_3)$.
- 6) Let V, V' be \mathbb{R} -vector spaces, $B = (v_1, v_2, v_3)$ a basis for $V, B' = (v'_1, v'_2, v'_3)$ a basis for V' and $f: V \to V'$ a \mathbb{R} -linear map with

$$[f]_{B,B'} = \left(\begin{array}{ccc} 0 & -1 & 5\\ 1 & 0 & 0\\ 0 & 1 & -5 \end{array}\right).$$

Determine:

- i) the dimension and a basis for each of the spaces $\operatorname{Im} f$ and $\operatorname{Ker} f$;
- ii) $[f]_{B,E'}$ when $V' = \mathbb{R}^3$, $v'_1 = (1,0,0)$, $v'_2 = (0,1,1)$, $v'_3 = (0,0,1)$ and E' is the standard basis of \mathbb{R}^3 ;
- iii) f(x) for $x = 2v_1 v_2 + 3v_3$, under the circumstances of ii).
- 7) Let $f \in End_{\mathbb{Q}}(\mathbb{Q}^4)$ with the matrix in the standard basis

a)
$$\begin{pmatrix} 1 & 2 & 1 & 2 \\ 3 & 2 & 3 & 2 \\ -1 & -3 & 0 & 4 \\ 0 & 4 & -1 & -3 \end{pmatrix}; b) \begin{pmatrix} 0 & 1 & 2 & 3 \\ -1 & 2 & 1 & 0 \\ 3 & 0 & -1 & -2 \\ 5 & -3 & -1 & 1 \end{pmatrix}.$$

Determine a basis for each of the \mathbb{Q} -vector spaces Ker f, Im f, Ker f + Im f and Ker $f \cap$ Im f.

HOMEWORK: 1) Let $S = \{(t, 2t, 3t) \mid t \in \mathbb{R}\}$ and $T = \{(x, y, z) \mid x + y + z = 0\}$.

- i) Show that S and T are subspaces of \mathbb{R}^3 .
- ii) Determine a basis for each of the subspaces S and T.
- iii) Determine $S \cap T$ and S + T.
- 2) Let $f: \mathbb{R}^3 \to \mathbb{R}^4$ the \mathbb{R} -linear map defined on the standard basis of \mathbb{R}^3 by:

$$f(e_1) = (1, 2, 3, 4), f(e_2) = (4, 3, 2, 1), f(e_3) = (-2, 1, 4, 1).$$

Determine:

- i) f(v) for any $v \in \mathbb{R}^3$;
- ii) the matrix of f in the standard bases;
- iii) a basis for $\operatorname{Im} f$ and a basis for $\operatorname{Ker} f$.