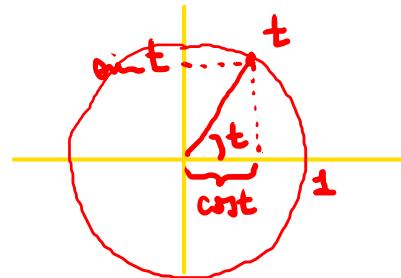


5. Limits of vector functions

A function $f: A \subseteq \mathbb{R} \rightarrow \mathbb{R}^m$ will be called vector function of a real variable.

Examples • $f: [0, 2\pi] \rightarrow \mathbb{R}^2$, $f(t) = (a \cos t, a \sin t)$

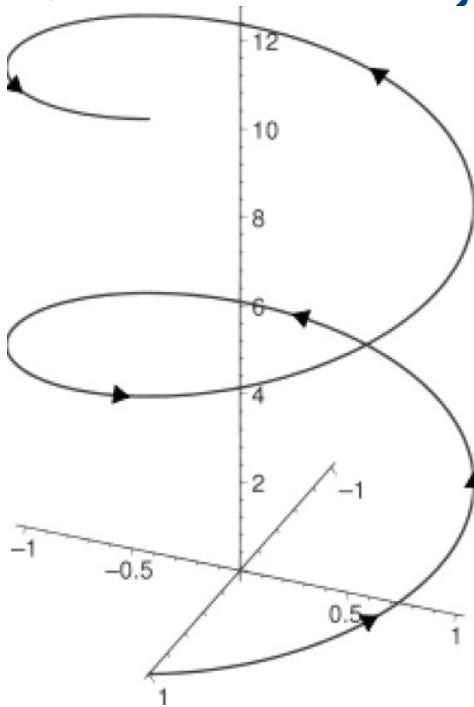


• $f: [0, 2\pi] \rightarrow \mathbb{R}^2$

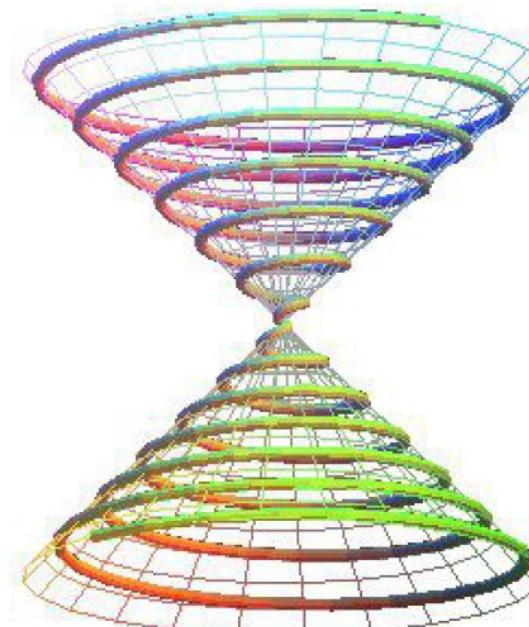
$$f(t) = (a \cos t, b \sin t) \quad a, b > 0$$

$$\text{Im } f = \left\{ (x, y) \mid \frac{x^2}{a^2} + \frac{y^2}{b^2} = 1 \right\} \rightarrow \text{ellipse}$$

• $f: [0, 4\pi] \rightarrow \mathbb{R}^3$, $f(t) = (a \cos t, a \sin t, ct)$.



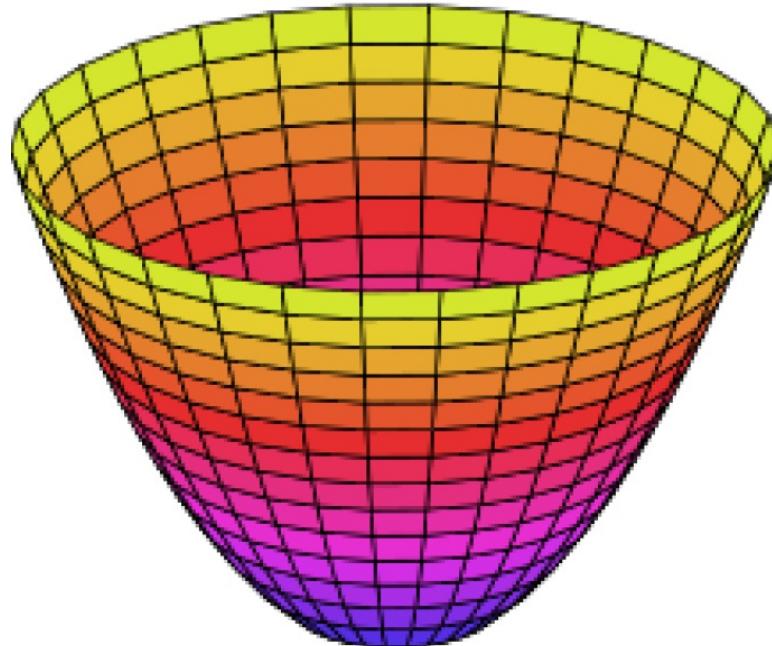
$$\bullet \vec{r}(t) = (t \cos t, t \sin t, ct) \quad t \in [0, \infty)$$



A function $f: A \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$ will be called a scalar function of vector variable (or scalar function of several variables).

Examples • $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ $f(x, y) = x^2 + y^2$

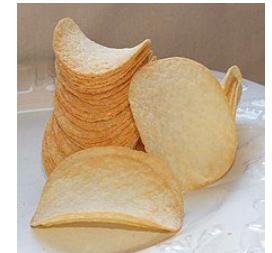
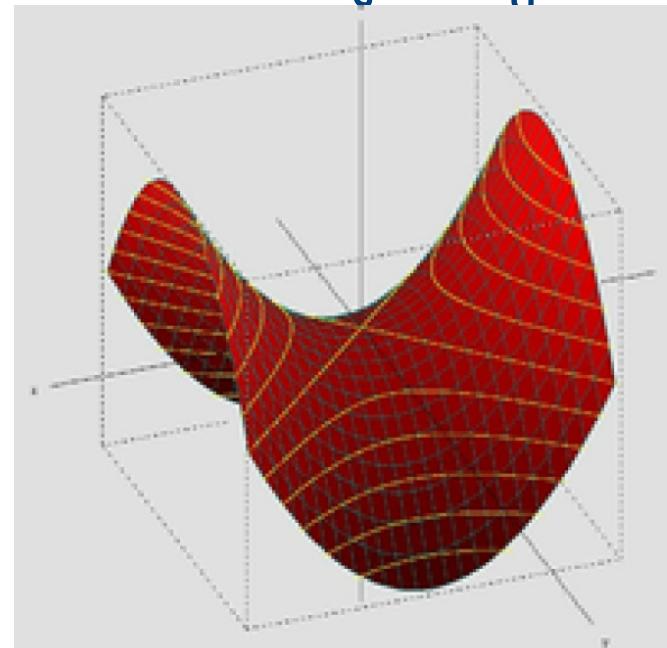
$$\Rightarrow z = f(x, y) = x^2 + y^2 \quad \text{paraboloid of revolution} \quad \left(z = \frac{x^2}{a^2} + \frac{y^2}{b^2} \right)$$



$$= \{(x, y, z) \in \mathbb{R}^3 \mid z = x^2 + y^2\}$$

• $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ $f(x, y) = x^2 - y^2$

$$\Rightarrow z = f(x, y) = x^2 - y^2 \quad \leftarrow \text{hyperbolic paraboloid}$$



Pringles chips

$$\cdot F: \mathbb{R}^3 \rightarrow \mathbb{R} \quad F(x, y, z) = \frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} - 1$$

$F(x, y, z) = 0 \leftarrow \text{one sheet hyperboloid}$

A function $f: A \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^m$ is called a vector function of vector variable

$$\cdot f: \mathbb{R}^2 \rightarrow \mathbb{R}^3 \quad f(x, y) = (\sin(x+y), \cos(xy), e^{x-y})$$

$$\cdot f: \mathbb{R}^3 \rightarrow \mathbb{R}^2 \quad f(x, y, z) = \underbrace{(x - 3y + z)}_{f_1(x, y, z)}, \underbrace{\ln(1 + x^2 + y^2 + z^2)}_{f_2(x, y, z)}$$

Let $f: A \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a given function. We define

$$f_1, \dots, f_m: A \rightarrow \mathbb{R}$$

as follows : given any point $x \in A \Rightarrow f(x) \in \mathbb{R}^m$, so $f(x)$ is of the form $f(x) = (y_1, \dots, y_m)$. We set $f_1(x) := y_1, \dots, f_m(x) := y_m$

f_1, \dots, f_m are called the scalar components of f

$$\forall x \in A : f(x) = (f_1(x), \dots, f_m(x))$$

We write $f = (f_1, \dots, f_m): A \rightarrow \mathbb{R}^m$ whenever we want to emphasize the scalar components of the vector function f

5.1. Definition. Let $A \subseteq \mathbb{R}^n$, $f: A \rightarrow \mathbb{R}^m$ a given function, $a \in A'$, $b \in \mathbb{R}^m$.

One says that f has the limit b at the point a if

$$\forall \varepsilon > 0 \exists \delta > 0 \text{ s.t. } \forall x \in A \setminus \{a\} \text{ with } \|x - a\| < \delta : \|f(x) - b\| < \varepsilon$$

If the limit exists, then it is unique.

Notation $\lim_{x \rightarrow a} f(x) = b$.

5.2. Theorem (Characterization of the limit by using sequences). Let $A \subseteq \mathbb{R}^n$, $f: A \rightarrow \mathbb{R}^m$ a function, $a \in A'$, $b \in \mathbb{R}^m$. Then

$$\lim_{x \rightarrow a} f(x) = b \iff \exists (x_k) \text{ sequence in } A \setminus \{a\} \text{ s.t. } (x_k) \rightarrow a \\ \text{we have } \lim_{k \rightarrow \infty} f(x_k) = b$$

Proof \Rightarrow Assume that $\lim_{x \rightarrow a} f(x) = b$. Let (x_k) be an arbitrary seq. in $A \setminus \{a\}$ s.t. $(x_k) \rightarrow a$.

$$\exists \lim_{k \rightarrow \infty} f(x_k) = b \iff \forall \varepsilon > 0 \exists k_0 \in \mathbb{N} \text{ s.t. } k \geq k_0 : \|f(x_k) - b\| < \varepsilon$$

Let $\varepsilon > 0 \Rightarrow \exists \delta > 0 \text{ s.t. } \forall x \in A \setminus \{a\} \text{ with } \|x - a\| < \delta : \|f(x) - b\| < \varepsilon$
Since $(x_k) \rightarrow a \Rightarrow \exists k_0 \in \mathbb{N} \text{ s.t. } \forall k \geq k_0 : \|x_k - a\| < \delta$
 $x_k \in A \setminus \{a\}$

$$\left. \begin{array}{l} \forall k \geq k_0 : \\ \|f(x_k) - b\| < \varepsilon \end{array} \right\} =$$

\Leftarrow Suppose that f does not have the limit b at the point a

$\Rightarrow \exists \varepsilon > 0$ s.t. $\forall \delta > 0 \ \exists x \in A \setminus \{a\}$ with $\|x-a\| < \delta$ s.t. $\|f(x)-b\| \geq \varepsilon$

In particular for $\delta = \frac{1}{k} \Rightarrow \forall k \geq 1 \ \exists x_k \in A \setminus \{a\}$ with $\|x_k-a\| < \frac{1}{k}$ s.t.

$$\|f(x_k)-b\| \geq \varepsilon$$

$\Rightarrow (x_k)$ is a sequence in $A \setminus \{a\}$ with $\lim_{k \rightarrow \infty} x_k = a$ our hypothesis

$\Rightarrow \lim_{k \rightarrow \infty} f(x_k) = b$ \Leftarrow $\|f(x_k)-b\| \geq \varepsilon \quad \forall k \geq 1$.

The obtained contradiction shows that $\lim_{x \rightarrow a} f(x) = b$.

Remark $\lim_{x \rightarrow a} f(x) = b \Leftrightarrow \lim_{x \rightarrow a} \|f(x)-b\| = 0$

5.3 Theorem Let $A \subseteq \mathbb{R}^n$, $a \in A'$, $f = (f_1, \dots, f_m) : A \rightarrow \mathbb{R}^m$,

and let $b = (b_1, \dots, b_m) \in \mathbb{R}^m$. Then

$\lim_{x \rightarrow a} f(x) = b \Leftrightarrow \lim_{x \rightarrow a} f_i(x) = b_i \quad \forall i \in \{1, \dots, m\}$

$$\lim_{x \rightarrow a} f(x) = (f_1(x), \dots, f_m(x))$$

$\downarrow \quad \downarrow \quad \dots \quad \downarrow$

$$b \quad b_1 \quad \dots \quad b_m$$

Example $b = \lim_{(x,y) \rightarrow (0,0)} \frac{xy}{x^2+y^2} = \lim_{\substack{x \rightarrow 0 \\ y \rightarrow 0}} \frac{xy}{x^2+y^2}$ $f(x,y) = \frac{xy}{x^2+y^2}$

We are going to prove that the limit b does not exist

Method I

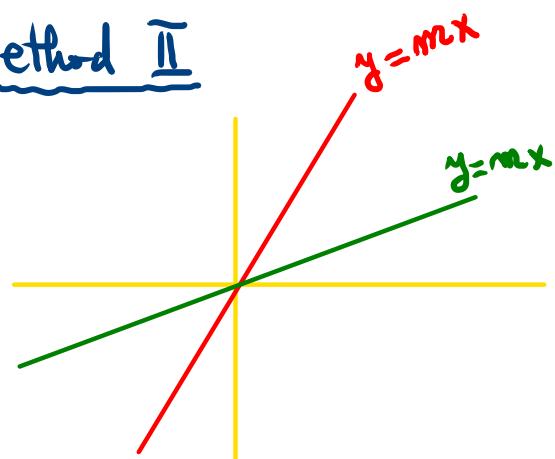
$$\left(\frac{1}{k}, \frac{1}{k}\right) \xrightarrow{k \rightarrow \infty} (0,0)$$

$$\left(\frac{2}{k}, \frac{1}{k}\right) \xrightarrow{k \rightarrow \infty} (0,0)$$

$$\left. \begin{aligned} f\left(\frac{1}{k}, \frac{1}{k}\right) &= \frac{1}{2} \xrightarrow{k \rightarrow \infty} \frac{1}{2} \\ f\left(\frac{2}{k}, \frac{1}{k}\right) &= \frac{2/k^2}{5/k^2} = \frac{2}{5} \xrightarrow{k \rightarrow \infty} \frac{2}{5} \end{aligned} \right\} \Rightarrow \text{D}\lim_{\substack{x \rightarrow 0 \\ y \rightarrow 0}} f(x,y)$$

T5.2

Method II



$$\lim_{x \rightarrow 0} f(x, mx) = \lim_{x \rightarrow 0} \frac{x \cdot mx}{x^2 + m^2 x^2} = \frac{m}{1+m^2}$$

If $\lim_{x \rightarrow 0} f(x, mx)$ depends on $m \Rightarrow$

$\Rightarrow \lim_{\substack{x \rightarrow 0 \\ y \rightarrow 0}} f(x,y)$ does not exist

! If $\lim_{x \rightarrow 0} f(x, mx)$ does not depend on $m \Rightarrow$?

6. Continuity of vector functions

6.1. Definition Let $A \subseteq \mathbb{R}^n$, $f: A \rightarrow \mathbb{R}^m$ a given function, and $a \in A$. One says that f is continuous at a if

$$\forall \varepsilon > 0 \quad \exists \delta > 0 \text{ s.t. } \forall x \in A \text{ with } \|x - a\| < \delta : \|f(x) - f(a)\| < \varepsilon$$

If a is an isolated point of A \Rightarrow f is continuous at a

6.2. Theorem (characterization of continuity by using sequences).

Let $A \subseteq \mathbb{R}^n$, $f: A \rightarrow \mathbb{R}^m$ a given function, and $a \in A$. Then

f is continuous at a \Leftrightarrow $\forall (x_k)$ sequence in A s.t $(x_k) \rightarrow a$
we have $\lim_{k \rightarrow \infty} f(x_k) = f(a)$

6.3. Theorem Let $A \subseteq \mathbb{R}^n$, $f: A \rightarrow \mathbb{R}^m$ a function, and $a \in A \cap A'$.

Then f is continuous at a $\Leftrightarrow \exists \lim_{x \rightarrow a} f(x) = f(a)$.

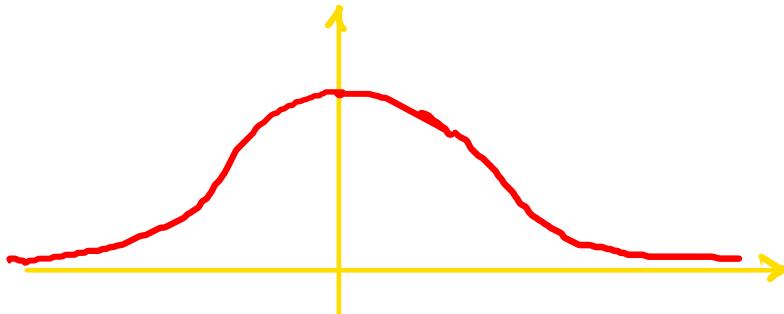
6.4. Theorem. Let $A \subseteq \mathbb{R}^n$, $f = (f_1, \dots, f_m): A \rightarrow \mathbb{R}^m$ a function, and $a \in A$.

Then f is continuous at a $\Leftrightarrow f_i: A \rightarrow \mathbb{R}$ is continuous at $a \quad \forall i=1, m$.

6.5. Theorem. If A is a compact subset of \mathbb{R}^m and $f: A \rightarrow \mathbb{R}^m$ is a continuous function on A , then $f(A)$ is a compact subset of \mathbb{R}^m

Remark A open / closed | $\nRightarrow f(A)$ is open / closed
 f continuous on A

Counterexample $f: \mathbb{R} \rightarrow \mathbb{R}$ $f(x) = \frac{1}{x^2+1}$ continuous



\mathbb{R} is both open and closed
but $f(\mathbb{R}) = (0, 1]$ which is not open nor closed

Proof. $\nabla f(A)$ is a compact set in $\mathbb{R}^m \Leftrightarrow f(A)$ is sequentially compact in \mathbb{R}^m
 $\Leftrightarrow \forall (y_k) \text{ seq. in } f(A) \exists (y_{k_j})_{j \geq 1} \text{ subseq.}$
and $\exists b \in f(A) \text{ s.t. } \lim_{j \rightarrow \infty} y_{k_j} = b$

Let (y_k) be an arbitrary seq. in $f(A)$

$\Rightarrow \forall k \geq 1 \exists x_k \in A \text{ s.t. } y_k = f(x_k)$

$\Rightarrow (x_k) \text{ is a seq. in } A \quad \left. \begin{array}{l} \\ A \text{ is compact} \end{array} \right\} \Rightarrow \exists (x_{k_j})_{j \geq 1} \text{ subseq. of } (x_k) \text{ and } \exists a \in A \text{ s.t. } \lim_{j \rightarrow \infty} x_{k_j} = a$

$$\text{Since } f \text{ is continuous at } a \Rightarrow \lim_{j \rightarrow \infty} \underbrace{f(x_{k_j})}_{= b_{k_j}} = f(a) =: b \in f(A)$$

$$\Rightarrow \lim_{j \rightarrow \infty} y_{k_j} = b \in f(A)$$

6.6. Theorem (K. Weierstrass). If A is a compact subset of \mathbb{R}^n , and $f: A \rightarrow \mathbb{R}$ is continuous on A , then f is bounded and attains its bounds on A , i.e., $\exists a, b \in A$ s.t. $f(a) = \inf f(A)$ and $f(b) = \sup f(A)$.

Proof. A compact
 f continuous on A | $\overset{\text{T6.5}}{\Rightarrow} f(A)$ is compact in $\mathbb{R} \Rightarrow$

$$\Rightarrow f(A) \text{ is bounded} \Rightarrow f \text{ is bounded}$$

and

$$f(A) \text{ is closed} \Rightarrow \inf f(A) \underset{\Downarrow}{\in} f(A) \quad \text{and} \quad \sup f(A) \underset{\Downarrow}{\in} f(A)$$

$$\exists a \in A : f(a) = \inf f(A) \qquad \exists b \in A : f(b) = \sup f(A)$$

Chapter 2 DIFFERENTIAL CALCULUS IN \mathbb{R}^n

1. The normed space of linear mappings

1.1 Definition. A function $\varphi: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is called a linear mapping if

$$\forall \alpha, \beta \in \mathbb{R} \quad \forall x, y \in \mathbb{R}^n : \quad \varphi(\alpha x + \beta y) = \alpha \varphi(x) + \beta \varphi(y)$$

Denote

$$L(\mathbb{R}^n, \mathbb{R}^m) := \{ \varphi: \mathbb{R}^n \rightarrow \mathbb{R}^m \mid \varphi \text{ is a linear mapping} \}$$

If $\varphi \in L(\mathbb{R}^n, \mathbb{R}^m)$ \Rightarrow

- $\varphi(0_n) = 0_m$

- $\varphi(-x) = -\varphi(x) \quad \forall x \in \mathbb{R}^n$

- $\forall \alpha_1, \dots, \alpha_k \in \mathbb{R}$, $\forall x_1, \dots, x_k \in \mathbb{R}^n$ we have

$$\varphi(\alpha_1 x_1 + \dots + \alpha_k x_k) = \alpha_1 \varphi(x_1) + \dots + \alpha_k \varphi(x_k)$$

1.2 Theorem Let $\varphi: \mathbb{R}^n \rightarrow \mathbb{R}^m$. Then

$$\varphi \in L(\mathbb{R}^n, \mathbb{R}^m) \iff \exists v_1, \dots, v_m \in \mathbb{R}^m \text{ s.t. } \forall x = (x_1, \dots, x_n) \in \mathbb{R}^n :$$

$$\varphi(x) = x_1 v_1 + \dots + x_n v_n$$

$$v_1 = \varphi(e_1), \dots, v_m = \varphi(e_n)$$

1.3. Theorem Let $\varphi: \mathbb{R}^n \rightarrow \mathbb{R}$. Then

$$\varphi \in L(\mathbb{R}^n, \mathbb{R}) \Leftrightarrow \exists v \in \mathbb{R}^m \text{ s.t. } \varphi(x) = \langle x, v \rangle \quad \forall x \in \mathbb{R}^n$$

1.4. Definition (the matrix of a linear mapping) Let $\varphi \in L(\mathbb{R}^n, \mathbb{R}^m)$

and let $\{e_1, \dots, e_n\}$ be the canonical basis in \mathbb{R}^n

Set $v_1 := \varphi(e_1) \in \mathbb{R}^m \Rightarrow v_1 \text{ has the form } v_1 = (v_{11}, v_{12}, \dots, v_{1m})$

$v_2 := \varphi(e_2) \in \mathbb{R}^m \Rightarrow v_2 = \dots \quad v_2 = (v_{21}, v_{22}, \dots, v_{2m})$

\vdots

$v_n := \varphi(e_n) \in \mathbb{R}^m \Rightarrow v_n = \dots \quad v_n = (v_{n1}, v_{n2}, \dots, v_{nm})$

$$[\varphi] := \begin{pmatrix} v_{11} & v_{21} & \dots & v_{n1} \\ v_{12} & v_{22} & \dots & v_{n2} \\ \vdots & \vdots & \ddots & \vdots \\ v_{1m} & v_{2m} & \dots & v_{nm} \\ \hline \varphi(e_1) & \varphi(e_2) & \dots & \varphi(e_n) \end{pmatrix} \in M_{m \times n}(\mathbb{R})$$

→ the matrix of the linear mapping φ

Convention: a vector $\mathbf{x} = (x_1, \dots, x_n) \in \mathbb{R}^n$ in a matrix expression (equality) will be identified with the column matrix $\begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \in M_{n \times 1}(\mathbb{R})$

For instance $\langle \mathbf{x}, \mathbf{y} \rangle = \mathbf{x}^t \cdot \mathbf{y}$

$$\mathbf{x}^t \cdot \mathbf{y} = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}^t \cdot \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix} = (x_1, \dots, x_n) \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}_{n \times 1} = x_1 y_1 + \dots + x_n y_n$$

$$\Phi(\mathbf{x}) = [\varphi] \mathbf{x} = [\varphi] \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$$