

Representation of discrete signals ($x[n]$)

It is denoted by $x[n]$

$n \rightarrow$ sample index or time index

It can be represented by

1) graphical representation

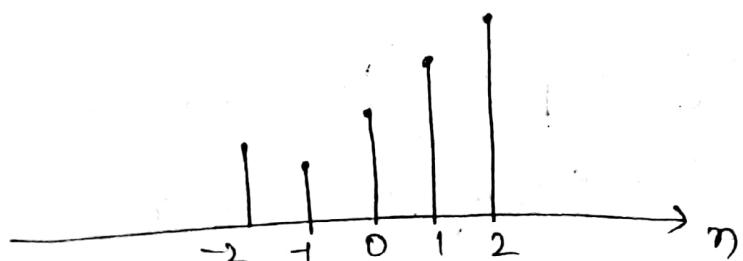
2) functional " "

3) Tabular " "

4) sequence " "

1) Graphical Representation:

$$x(-2)=2, x(-1)=1, x(0)=3, x(1)=4, x(2)=5$$



2) function representation:

$$x[n] = \begin{cases} 2 & n = -2 \\ 1 & n = -1 \\ 3 & n = 0 \\ 4 & n = 1 \\ 5 & n = 2 \end{cases}$$

3) Tabular Representation:

n	-2	-1	0	1	2
$x[n]$	2	1	3	4	5

ii) sequence Representations:

$$x[n] = \{ \underset{n=0}{\overset{\uparrow}{2}}, 1, 3, 4, 5 \}$$

Classification of discrete-time signals:

- 1) Energy & power signals.
- 2) Even & odd signals
- 3) Causal & Noncausal signals
- 4) Periodic and Aperiodic signals

Energy and Power signals:

→ Energy signal: Energy is finite, avg. power is zero.

→ Power signal: Avg. power is finite, energy is infinite

$$E = \sum_{n=-\infty}^{\infty} |x(n)|^2$$

$$P = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^{N} |x(n)|^2$$

$N \rightarrow$ sequence length.

Eg: $x[n] = \{ 1, 2, 3, 4 \}$

$$N=4$$

$$N=0 \text{ to } N-1$$

$E = \infty$, avg. power is zero \rightarrow energy signal

$E \rightarrow \infty$, P-finite \rightarrow power signal.

$$\textcircled{1} \quad x[n] = \left(\frac{1}{3}\right)^n u[n]$$

Sol: $E = \sum_{n=-\infty}^{\infty} |x(n)|^2$

$$= \sum_{n=0}^{\infty} \left(\frac{1}{3}\right)^{2n}$$

$$= 1 + \left(\frac{1}{9}\right) + \left(\frac{1}{9}\right)^2 + \dots$$

$$= \frac{1}{1 - \frac{1}{9}} = \frac{9}{8}$$

$E \rightarrow \text{finite} \rightarrow \text{Energy signal.}$

$$P = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^N |x(n)|^2$$

$$= \lim_{N \rightarrow \infty} \frac{1}{2N+1} \times \lim_{N \rightarrow \infty} \sum_{n=-N}^N |x(n)|^2$$

$$= \lim_{N \rightarrow \infty} \frac{1}{2N+1} (\text{finite value})$$

$$= 0$$

$E \rightarrow \text{finite}, P_{\text{avg}} = 0 \rightarrow \text{Energy signals.}$

(b)

$$= \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=0}^N \left(\frac{1}{3}\right)^n$$

$$= \lim_{N \rightarrow \infty} \frac{1}{2N+1} \frac{1 - \left(\frac{1}{3}\right)^{N+1}}{1 - \frac{1}{3}}$$

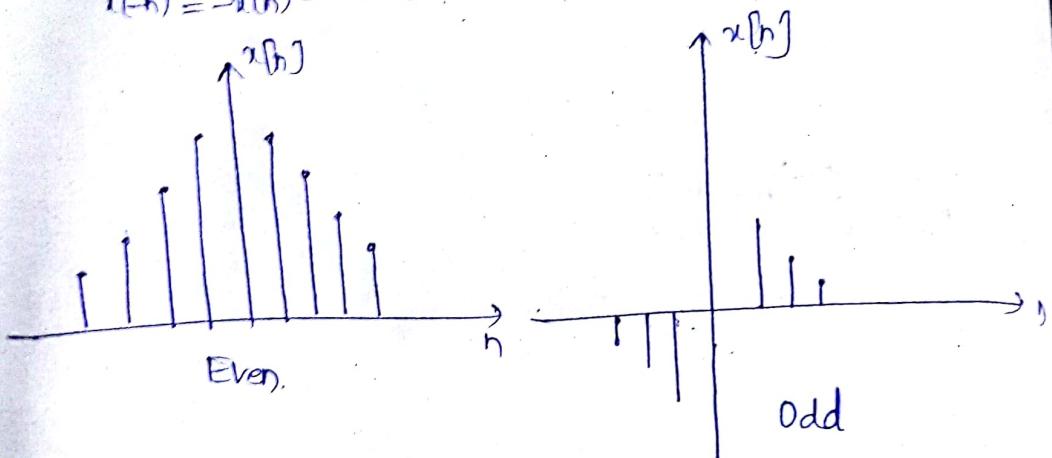
$\textcircled{2} \quad x[n] = e^{2n} u[n]$

2) Even and odd signals:

If $x[n]$ is a signal

\rightarrow If $x(-n) = x(n) \rightarrow$ even $\rightarrow \cos(\omega n), t^2$

$x(-n) = -x(n) \rightarrow$ odd $\rightarrow \sin(\omega n), t^3$



$$\text{Even part of signal } x_e(n) = \frac{x(n) + x(-n)}{2}$$

$$\text{Odd part of signal } x_o(n) = \frac{x(n) - x(-n)}{2}$$

3) Causal & Non-causal signals:

If $x(n) = 0$ for $n < 0 \rightarrow$ causal

otherwise it is noncausal signal.

E.g. causal

$$x(n) = a^n u(n)$$

$$x(n) = \{-1, 1, 2, 3, 4\}$$

Noncausal.

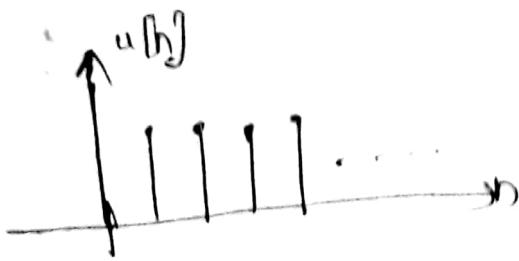
$$x(n) = a^n u(n+1)$$

$$x(n) = \{-1, 1, 2, 3, 4\}$$

Basic Signals:

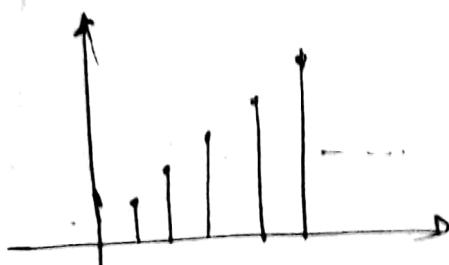
Unit Step

$$u[n] = \begin{cases} 1 & n \geq 0 \\ 0 & n < 0 \end{cases}$$



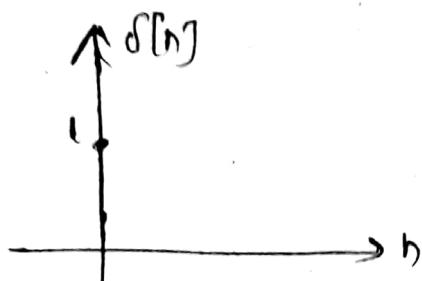
Ramp:

$$r[n] = \begin{cases} n & n \geq 0 \\ 0 & n < 0 \end{cases}$$



Impulse:

$$\delta[n] = \begin{cases} 1 & n=0 \\ 0 & n \neq 0 \end{cases}$$



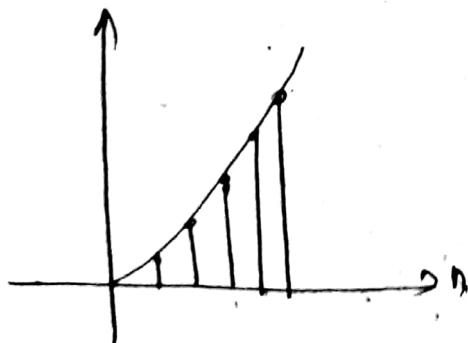
Exponential:

$$x[n] = a^n u[n]$$

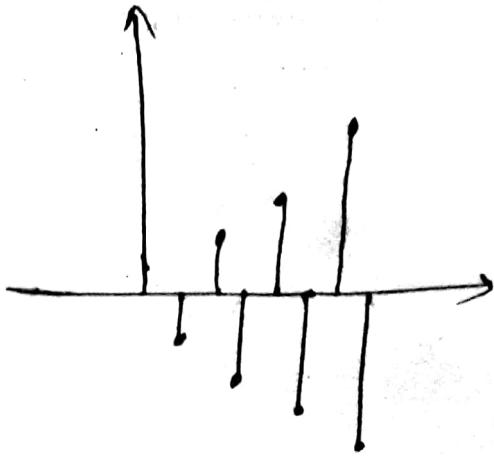
$$a > 0 \quad 0 < a < 1$$

$$a < 1 \quad -1 < a < 0$$

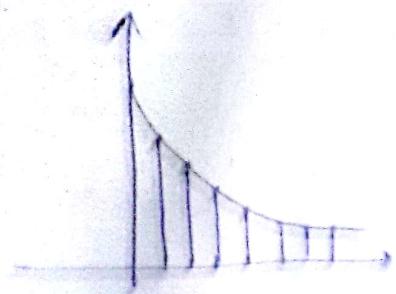
If $a > 1 \rightarrow$ increasing



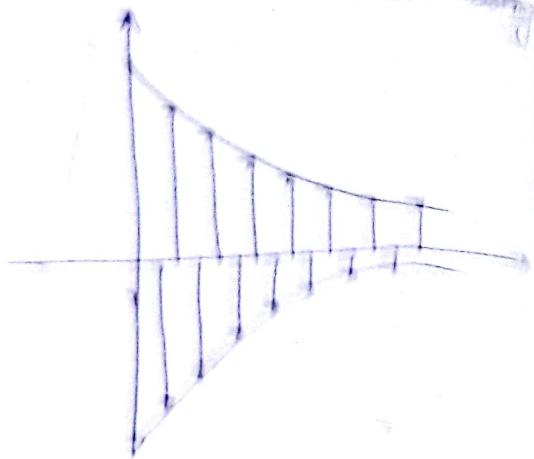
If $a < 1 \rightarrow$ both sides ↑



W oscill

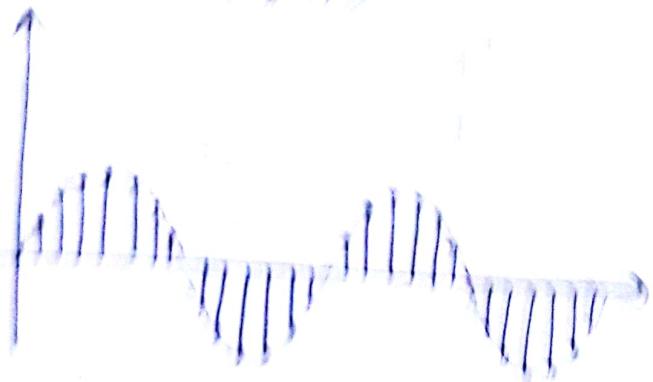


$\rightarrow \text{less } \omega_0 \rightarrow \text{bath enters resonance}$



Resonant signal

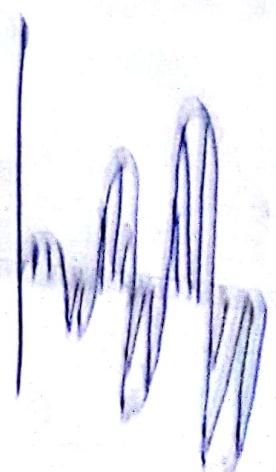
$$y(t) = A \sin(\omega_0 t + \phi)$$



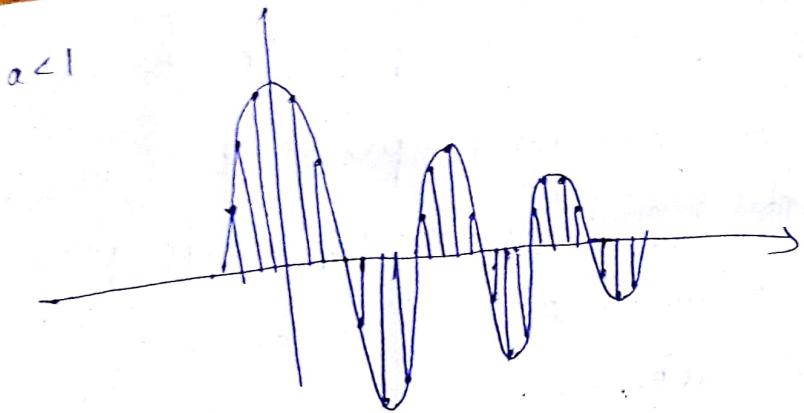
Long time approach

$$y(t) \approx A \sin(\omega_0 t)$$

$$y(t) \approx A \sin(\omega_0 t)$$



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4) Periodic & Aperiodic signals(sequences)

Signals which is having definite pattern and repeats for every 'N' are called periodic signals.

For continuous $x(t+pT) = x(t)$

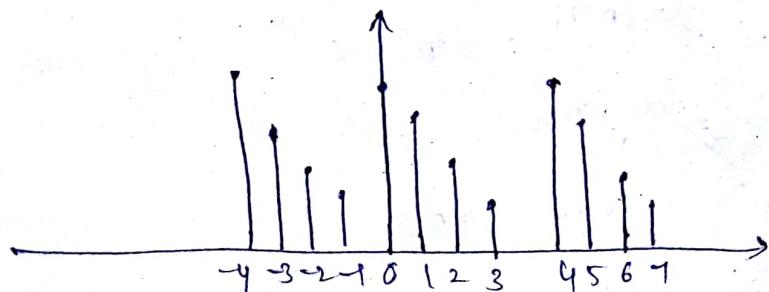
For discrete $x(n+pN) = x(n)$

$N \rightarrow$ sequence length.

The smallest value of 'N' at which the signal repeats is called fundamental period (which satisfies above condition)

→ A discrete-time signal $x[n]$ is said to be periodic with period 'N' if $x(n+pN) = x(n)$

Otherwise, it is aperiodic



→ If $x_1(n)$ is periodic with period 'N'

(2) sols

and $x_1(n)$ is periodic with period ' N_1 ' then there linear combination need not be periodic but all discrete-time sinusoidal signals may or may not be periodic.

Ex: $x[n] = A \sin(\omega_0 n + \phi)$

$$x[n+N] = x[n]$$

$$A \sin((\omega_0 n + \pi N) + \phi) = A \sin(\omega_0 n + \phi)$$

$$A \sin(\omega_0 n + \pi \omega_0 N + \phi) = A \sin(\omega_0 n + \phi)$$

It is periodic when ω_0 is an integral multiple of 2π .

$$\omega_0 N = 2\pi m$$

$$N = \frac{2\pi m}{\omega_0}$$

$$\boxed{\omega_0 = 2\pi \left(\frac{m}{N}\right)}$$

From the above equation, the discrete-time signal to be periodic, the fundamental period ω_0 must be rational multiple of 2π .

(1) $x(n) = e^{j\omega_0 n}$

Sols $x(n+N) = e^{j\omega_0(n+N)} = e^{jn\omega_0} e^{j\omega_0 N}$

~~$$e^{jn\omega_0} e^{j\omega_0 N} = e^{jn\omega_0}$$~~

$$\omega_0 N = 2\pi k$$

$$\boxed{N = \frac{2\pi k}{\omega_0}}$$

(3) sols

(3) x

sols

(4) sols

$$\textcircled{2} \quad x(n) = e^{\frac{j6\pi n}{3}}$$

Solve $e^{j6\pi(n+1)} = e^{j6\pi n}$

$$e^{j6\pi N} = 1$$

$$6\pi N = 2\pi k$$

$$N = \frac{k}{3}$$

$$N = \frac{2\pi m}{6\pi} = \frac{m}{3}$$

$N=1$ for $m=3$

$$\textcircled{3} \quad x(n) = e^{\frac{j3}{5}(n+\frac{1}{2})}$$

Solve $x(n+N) = x(n)$

$$e^{\frac{j3}{5}(n+N+\frac{1}{2})} = e^{\frac{j3}{5}(n+\frac{1}{2})}$$

$$e^{\frac{j3}{5}N} = 1$$

$$\frac{3}{5}N = 2\pi k$$

$$N = \frac{2\pi m}{3} \times 5$$

N is not an integer

' ω_0 ' is not an integral multiple of 2π

\therefore Aperiodic

$$\textcircled{4} \quad x(n) = \cos \frac{\pi}{3}n - \cos \frac{3\pi}{4}n$$

Solve $N_1 = 2\pi \cdot \frac{m}{\frac{\pi}{3}} = 6m, \quad N_2 = 2\pi \cdot \frac{m}{\frac{3\pi}{4}} = \frac{8m}{3}$

$$\frac{N_1}{N_2} = \frac{6m}{\frac{8m}{3}} = \frac{9}{4}$$

$$N = 4N_1 = 2N_2 = 24$$

$$\frac{2}{x(n) - x(n-1)} = \left\{ \begin{array}{l} 2 \\ -2 \end{array} \right\} = \chi_{\{n\}}(n)$$

$$\frac{2}{x(n) + x(n-1)} = \left\{ \begin{array}{l} 2 \\ 0 \end{array} \right\} = \chi_{\{n\}}(n)$$

$$\left\{ \begin{array}{l} \downarrow \\ 2, 3, 1 \end{array} \right\} = \chi_{\{n\}} \quad \text{for}$$

$$\left\{ \begin{array}{l} \downarrow \\ 2, 3, 4 \end{array} \right\} = \chi_{\{n\}} \quad \textcircled{2}$$

$$\left\{ \begin{array}{l} \downarrow \\ 4, 0, 1 \end{array} \right\} = \chi_{\{n\}}$$

$$\left\{ \begin{array}{l} \downarrow \\ 1, 1, 1, 1 \end{array} \right\} = \chi_{\{n\}}$$

$$\left\{ \begin{array}{l} \downarrow \\ 3, 1, -3, 5 \end{array} \right\} = \chi_{\{n\}}$$

$$\left\{ \begin{array}{l} \downarrow \\ 3, 1, -3 \end{array} \right\} = \chi_{\{n\}}$$

$$\frac{2}{x(n) + x(n-1)} = \chi_{\{n\}}$$

$$B = \{1\} \chi$$

$$I = \{0\} \chi$$

$$S = \{1\} \chi$$

$$Z = \{0\} \chi \quad \text{for } B$$

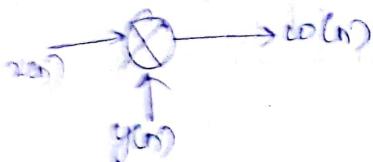
$$\left\{ \begin{array}{l} \downarrow \\ 3, 1, 1, -3 \end{array} \right\} = \chi_{\{n\}} \quad \textcircled{1}$$

Operations on signals

Signal multiplication:

$w(n)$ is product of 2 signals $x(n), y(n)$

$$w(n) = x(n) \cdot y(n)$$



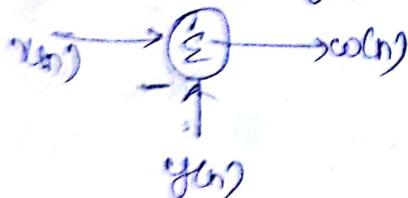
Two corresponding samples are multiplied ($1^{\text{st}} \times 1^{\text{st}}$)

It is used in FIR (Finite Impulse Response) filter
in bsp.

An infinite length sequence is multiplied with
window function (finite sequence) resulting in finite
length sequence.

Signal addition:

$$z(n) = x(n) + y(n)$$



Scalar multiplication:

$$w(n) = x(n) \cdot \alpha$$



Time shifting:

If $x(n)$ is a sequence, $x(n+k)$ is shifted version
of $x(n)$

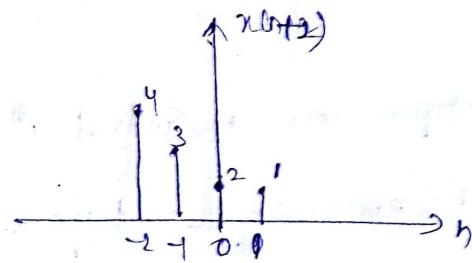
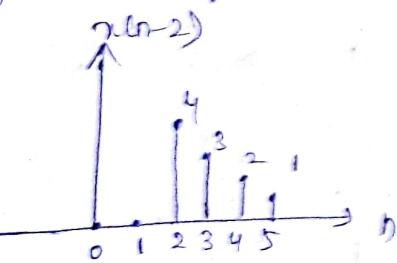
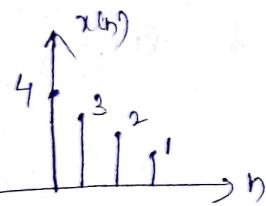
$$x(n+k)$$

k is the \Rightarrow Eq. $k=2$

~~It is right shifted by 2 units~~

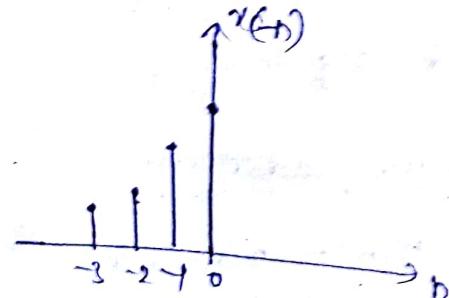
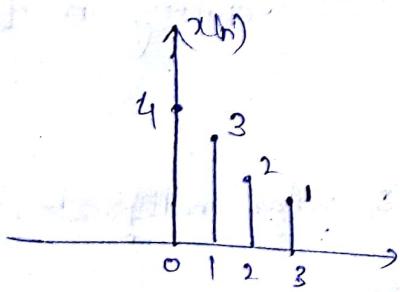
i.e. $x(n) \Rightarrow y(n) = x(n+2) \Rightarrow$ left shift by 2 units

e.g.

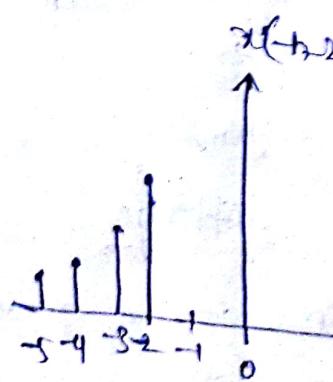


5) Time Reversal:

~~It is folded / flip over sequence of $x(n)$ i.e. $x(-n)$~~

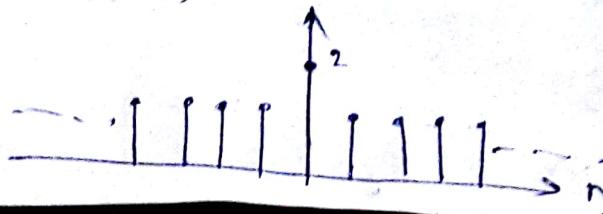


$x(n+2)$

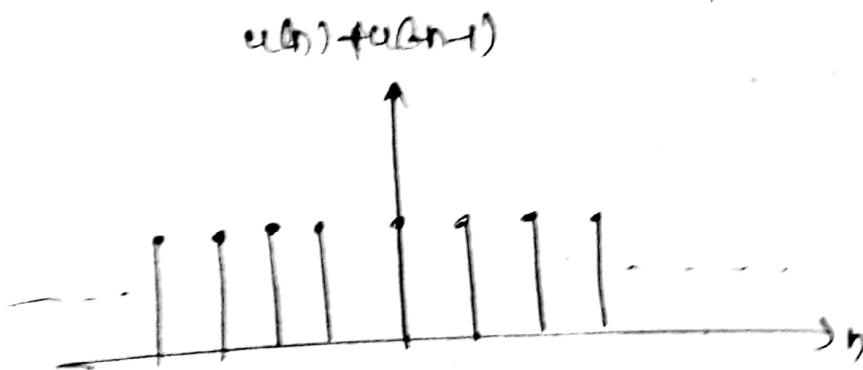
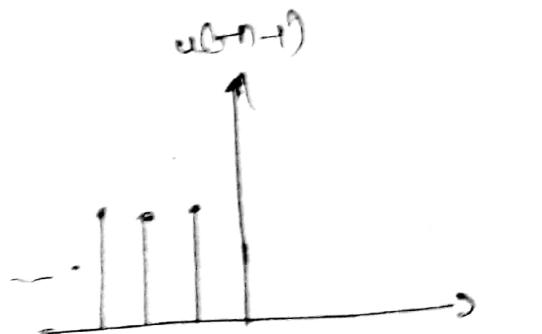
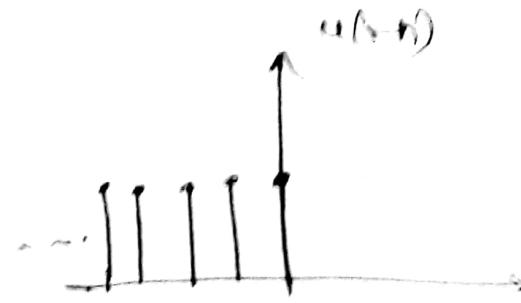
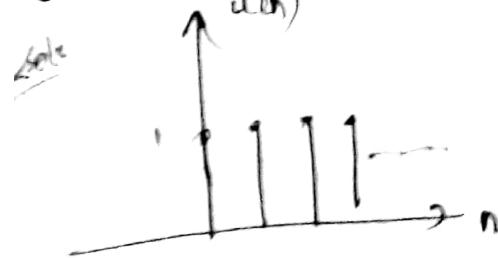


(P)

$$u(n) + u(-n) = 1 + \delta(n)$$



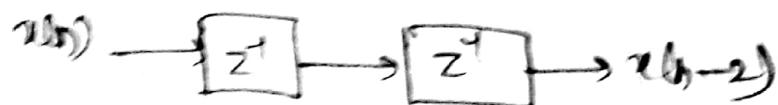
$$\text{Q2} \quad u(n) + u(n-1) = 1 \quad \forall n$$



i) Time scaling:

$$u(n) \rightarrow u(nk) \text{ or } u\left(\frac{n}{k}\right)$$

Time shifting can be represented as



For advanced



Classification of discrete-time systems

1) Linear or Nonlinear systems

A system is said to be linear if it satisfies homogeneity and superposition principle.

Homogeneity:

If y_p is multiplied by a factor, y_p should also be multiplied by the same factor.

$$x(n) \rightarrow y(n)$$

$$ax(n) \rightarrow ay(n)$$

Superposition:

Sum of weighted individual I/P results in

u u u u o/p's

$$T[a_1u_1(n) + a_2u_2(n)] = a_1T[u_1(n)] + a_2T[u_2(n)]$$

$$y(n) = T[u(n)]$$

$$\text{Soln: } y(n) = n u(n)$$

$$y_1(n) = n u_1(n)$$

$$y_2(n) = n [a_1u_1(n) + a_2u_2(n)]$$

$$= n a_1 u_1(n) + n a_2 u_2(n)$$

$$a_1 T[u_1(n)] + a_2 T[u_2(n)] = a_1 n u_1(n) + a_2 n u_2(n)$$

\therefore The

$$\textcircled{1} \quad y(n) = n$$

$$y(n) =$$

$$y_1(n)$$

$$y_2(n)$$

$$a_1 y_1(n)$$

$$\textcircled{2} \quad y(n)$$

Soln

$$y_3(n)$$

$$\textcircled{3} \quad y(n)$$

Soln

\therefore The system is linear.

$$\textcircled{2} \quad y(n) = u(n) + \frac{1}{u(n-1)}$$

$$y_1(n) = u(n) + \frac{1}{u_1(n-1)}$$

$$y_2(n) = u_1(n) + \frac{1}{u_2(n-1)}$$

$$y_3(n) = a_1 u_1(n) + a_2 u_2(n) + \frac{1}{a_1 u_1(n) + a_2 u_2(n-1)}$$

$$a_1 y_1(n) + a_2 y_2(n) = a_1 u_1(n) + \frac{a_1}{u_1(n-1)} + a_2 u_2(n) + \frac{a_2}{u_2(n-1)}$$

\therefore It is nonlinear.

$$\textcircled{3} \quad y(n) = \frac{1}{N} \sum_{k=0}^{N-1} u(n-k)$$

$$\underline{\text{soln}} \quad y_1(n) = \frac{1}{N} \sum_{k=0}^{N-1} u_1(n-k)$$

$$y_2(n) = \frac{1}{N} \sum_{k=0}^{N-1} u_2(n-k)$$

$$y_3(n) = \frac{1}{N} \sum_{k=0}^{N-1} a_1 u_1(n-k) + a_2 u_2(n-k)$$

$$= a_1 \frac{1}{N} \sum_{k=0}^{N-1} u_1(n-k) + a_2 \frac{1}{N} \sum_{k=0}^{N-1} u_2(n-k)$$

$$= a_1 y_1(n) + a_2 y_2(n)$$

\therefore It is linear.

$$\textcircled{4} \quad y(n) = n u^2(n)$$

$$\underline{\text{soln}} \quad y_1(n) = n u_1^2(n)$$

$$y_2(n) = n u_2^2(n)$$

$$y_3(n) = n (a_1 u_1(n) + a_2 u_2(n))^2$$

$$= n a_1^2 u_1^2(n) + a_2^2 u_2^2(n) + 2 a_1 a_2 u_1(n) u_2(n)$$

on past
Eg. y
 y
 y

$$a_1 y_1(n) + a_2 y_2(n) = a_1 n y_1(n) + a_2 n^2 y_2(n)$$

$$\neq y_3(n)$$

\therefore It is non-linear.

$$⑤ y(n) = x(n) + \frac{1}{2x(n-2)}$$

$$y_1(n) = x_1(n) + \frac{1}{2x_1(n-2)}$$

$$y_2(n) = x_2(n) + \frac{1}{2x_2(n-2)}$$

$$y_3(n) = a_1 x_1(n) + a_2 x_2(n) + \frac{1}{2(a_1 x_1(n-2) + a_2 x_2(n-2))}$$

$$a_1 y_1(n) + a_2 y_2(n) = a_1 x_1(n) + \frac{1}{2a_1 x_1(n-2)} + a_2 x_2(n) + \frac{1}{2a_2 x_2(n-2)}$$

$$= a_1 x_1(n) + a_2 x_2(n) + \frac{1}{2a_1 x_1(n-2)} + \frac{1}{2a_2 x_2(n-2)}$$

$$\neq y_3(n)$$

\therefore It is non-linear.

Initial

Static and Dynamic system:

Static system (memoryless system)

\rightarrow It is a memoryless system.

\rightarrow output depends only on the present I/p

Eg: $y(n) = x(n) \rightarrow$ static

A system is said to be dynamic system

or system with memory if the o/p depends

on past or future values and present in part 2/4

Eg: $y(n) = x(n) + x(n-2)$

$$y(n) = x(n) + x(n-2) \rightarrow \text{Non-causal}$$

$$y(n) - x(n) = x(n) - x(n-2)$$

$$y(n) - x(n) = x(n) + x(n-2)$$

It depends on past I/P's and past O/P's.

Causal and Non-causal systems

→ A system is said to be causal, if the O/P depends on past and present I/P's.

→ Causal systems are real systems (or) causal systems are physically realisable.

Eg: $y(n) = x(n) + x(n-2) \rightarrow \text{Non-causal system}$

$$n=1$$

$$y(1) = x(1) + x(0)$$



future I/P

$$y(n) = x(n) + x(n+1) \rightarrow \text{causal system.}$$

→ A system is said to be non-causal, if the O/P depends on future I/P's.

→ A system is said to be causal, if

$$h(n) = 0 \quad n < 0 \quad (\text{In terms of Impulse response})$$

$$① y(n) = x(-n)$$

$$\text{so } y(n) = x(1)$$

Noncausal.

$$② y(n) = x(2n)$$

$$y(n) = x(2)$$

Noncausal.

$$③ y(n) = [\sin(x(n))]$$

Causal.

Time-invariant system & Time variant system:

→ A system is said to be time invariant system if the I/O relationship does not change with time (or shifting).

$$\rightarrow \text{Eg: } x(n) \rightarrow y(n)$$

$$x(n-b) \rightarrow y(n-b)$$

→ It is said to be time invariant if the I/O characteristics does not change with time.

$$y(n, b) = y(n-b) \text{ i.e. delay in I/O leads to delay in O/P}$$

$$\text{Eg: } x(n) \rightarrow y(n)$$

$$x(n-b) \rightarrow y(n, b) = + [x(n-b)] = y(n) \quad |_{x(n)=x(n-b)}$$

$$y(n-b) = y(n) \quad |_{n=n-b}$$

$$\textcircled{1} \quad y(n) = x(n-1)$$

$$\text{sol: } y(n, k) = T[x(n-k)] = y(n) \Big|_{n \rightarrow n-k}$$

$$y(n-k) = y(n) \Big|_{n \rightarrow n-k}$$

$$y(n-k) = y(n-1)$$

$$y(n, k) = y(n-1)$$

T.IV

$$\textcircled{2} \quad y(n) = x\left(\frac{n}{2}\right)$$

$$\text{sol: } y(n, k) = x\left(\frac{n-k}{2}\right)$$

$$y(n-k) = x\left(\frac{n-k}{2}\right)$$

$$y(n, k) \neq y(n-k)$$

∴ T.V

$$\textcircled{3} \quad y(n) = x(2n)$$

$$y(n, k) = x(2n-k)$$

~~$$y(n-k) = x(2n-k)$$~~

$$y(n-k) = x(2(n-k)) \\ = x(2n-2k)$$

∴ T.V

LTI system

→ If a system satisfies linearity and time invariant property, then it is said to be LTI system.

→ All discrete-time systems are described by difference equations

→ All difference equations are differential equations

If the coefficients of difference (or) differential eqn. are constants, then it is time invariant.

Eg: $y(n) = x(n) + x(n-1) + 3x(n-2) \rightarrow \text{T.IV}$

$y(n) = x(n) + x(n-1) + 3x(n-2) \rightarrow \text{T.V}$

Difference equations consists of past or present I/P's
 only, i.e. $x(n)$, $x(n-1)$, $x(n-2)$ and past o/p's
 $y(n) + 2y(n-1) = x(n) + 3x(n-1) + 2x(n-2) \rightarrow T.V$

① $y(n) = x(n) + x(n-1)$

T.V

② $y(n) = x(n-1)$

T.I.V.

$$y(n, k) = x(n-k+1)$$

$$y(n+k) = x(n-k+1)$$

Stable and Unstable systems:

→ A system is said to be stable if bounded I/P produces bounded o/p (BIBO)

Bounded I/P: $|x(n)| \leq m \rightarrow$ (the real finite value)

$$|y(n)| \leq M_y$$

→ If I/P is bounded, o/p is infinite \rightarrow Unstable

The necessary and sufficient condition for

stability is

$$\sum_{n=-\infty}^{\infty} |h(n)| < \infty$$

i.e. if impulse response of the system has finite value, then it is stable

→ stability of system indicates usefulness of system.

$$\text{if } x(n) = \delta(n)$$

$$y(n) = h(n)$$

$$y(n) = x(n) * h(n)$$

$$\text{Proof: } y(n) = \sum_{k=-\infty}^{\infty} x(k) h(n-k) \quad y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$

$$|y(n)| = \left| \sum_{k=-\infty}^{\infty} (x(k) h(n-k)) \right|$$

$$\leq \sum_{k=-\infty}^{\infty} |x(k)| |h(n-k)|$$

$$|y(n)| \leq M_x \sum_{k=-\infty}^{\infty} |h(n-k)| \quad (\because \text{bounded if} \\ \Rightarrow |x(n)| = M_x)$$

Replace $n-k=m$

The if is bounded if

$$\sum_{n=-\infty}^{\infty} |h(n)| < \infty$$

① $h(n) = \left(\frac{1}{2}\right)^n u(n)$. The impulse response of the system

is $h(n) = \left(\frac{1}{2}\right)^n u(n)$. Check whether it is stable or unstable

$$\text{sol: } \sum_{n=-\infty}^{\infty} \left(\frac{1}{2}\right)^n u(n) \quad \left(\because \sum_{n=-\infty}^{\infty} h(n) \right)$$

$$= \sum_{n=0}^{\infty} \left(\frac{1}{2}\right)^n$$

$$= 1 + \left(\frac{1}{2}\right) + \dots - \infty \Rightarrow \frac{1}{1 - \frac{1}{2}} \quad \left(\because \frac{a}{1-r} \right)$$

$$\infty < \infty$$

\therefore it is stable.

③ $y(n) = a^n b^{n-7}$

~~as~~ $\Rightarrow u(n) = \delta(n) \Rightarrow y(n) = b(n)$

$b(n) = a^n + b^7 = 0$ for $n=7$
 $= 0$ for $n \neq 7$

$$\sum_{n=-\infty}^{\infty} b(n) = \sum_{n=0}^{\infty} a^n b^{n-7}$$
$$= a \delta(2)$$

\therefore it is stable.

④ $y(n) = a^n b^{n+1} + b(n+1)$

~~as~~ $u(n) = a \delta(n+1) + b \delta(n+1)$

$$\sum_{n=-\infty}^{\infty} u(n) = \dots + a \delta(0) + b \delta(1) + a \delta(1) + b \delta(1)$$
$$+ a \delta(2) + b \delta(0)$$

$$= a + b < \infty$$

\therefore it is stable.

⑤ $h(n) = a u(n)$

~~as~~ $\sum_{n=-\infty}^{\infty} h(n) = \sum_{n=0}^{\infty} u(n)$

$$= 1 + 1 + \dots + 1 < \infty$$

\therefore it is unstable.

drift

FIR & IIR systems

Any LTI discrete time system can be classified according to the type of impulse response.

If impulse response $h(n)$ is finite duration system is finite impulse Response system (FIR)

If impulse response $h(n)$ is infinite duration, system is infinite impulse Response system (IIR)

Impulse Response and convolution sums

Arbitrary sequence: A sequence of any extent or any order.

Any arbitrary sequence $x(n)$ can be expressed (or) represented by delayed and weighted impulse response δ_n

$$\text{Eg: } x(0). \delta(n) \rightarrow x(0) \quad n=0$$

$$0 \quad n \neq 0$$

$$x(-1) \delta(n+1) \rightarrow x(-1) \quad n=-1$$

$$0 \quad n \neq -1$$

$$x(n) \rightarrow -2 \leq n \leq 2$$

$$\begin{aligned} x(n) = & x(-2) \delta(n+2) + x(-1) \delta(n+1) + x(0) \delta(n+0) \delta(n) \\ & + x(1) \delta(n-1) \end{aligned}$$

For an infinite sequence $x(n)$ can be represented

as

$$x(n) = \sum_{k=-\infty}^{\infty} x(k) \delta(n-k)$$

If the I/P $x(n) = \delta(n)$

$$y(n) = T[x(n)] = T[\delta(n)] = h(n)$$

$$x(n) = \sum_{k=-\infty}^{\infty} x(k) \delta(n-k)$$

$$y(n) = T[x(n)] = \sum_{k=-\infty}^{\infty} T[x(k) \cdot \delta(n-k)]$$

$$= \sum_{k=-\infty}^{\infty} x(k) T[\delta(n-k)]$$

(If system is linear)

$$= \sum_{k=-\infty}^{\infty} x(k) h(n-k)$$

(i.e. If system is time invariant)

$$y(n) = \sum_{k=-\infty}^{\infty} x(k) \cdot h(n-k)$$

→ convolution sum

(or)

$$y(n) = x(n) * h(n)$$

and convolution sum is possible only when the system is LTI system.

~~not~~

→ If the input sequence $x(n)$ of length ' N_1 ',

and the impulse response $h(n)$ of length ' N_2 ',

then the
I/P of
the
modified
and eq
For a

For a

Case (E)

Case (F)

Case (G)

then the convolution of two sequences produce the
of length $N_1 + N_2 - 1$

→ The limits of the convolution sum can be
modified according to the type of the sequence
and system.

For causal system,

$$h(n) = 0 \quad n < 0$$

For causal S/P sequence, $x(n) = 0 \quad n < 0$

Case(I) For non-causal system excited by a noncausal
 S/P

$$y(n) = \sum_{k=-\infty}^{\infty} x(k) h(n-k) - \text{non-causal S/P}$$

$$= \sum_{k=-\infty}^{\infty} h(k) \cdot x(n-k) \rightarrow \text{a causal system,}$$

Case(II) For non-causal system, causal S/P sequence
 $(x(n)) = 0 \quad n < 0$

$$y(n) = \sum_{k=0}^{\infty} x(k) h(n-k)$$

$$= \sum_{k=-\infty}^n h(k) \cdot x(n-k)$$

Case(III) For causal system, non-causal S/P

$$y(n) = \sum_{k=0}^{\infty} h(k) \cdot x(n-k) = \sum_{k=-\infty}^n x(k) h(n-k)$$

Case (iv) For causal system, causal $\frac{y}{x}$

$$y(n) = \sum_{k=0}^n h(k)x(n-k) = \sum_{k=0}^n x(k)h(n-k)$$

$h(k) \rightarrow 0$ to ∞ , $x(n-k) \rightarrow -\infty$ to n

① Determine the convolution sum of 2 sequences.

$$x(n) = \{3, 2, 1, 2\}, h(n) = \{1, 2, 1, 2\}$$

Solve (i) Using Tabular method:

x(n)			
1	3	2	1 2
2	6	4	2 4
1	3	2	1 2
2	6	4	2 4

$$y(n) = \{3, 8, 8, 12, 9, 4, 4\}$$

$$N_1 + N_2 - 1 = 4 + 4 - 1 = 7$$

1111

Graphical

Steps - t

Step 1:-

give the

sequence

$h(n)$ start

choice.

Step 2:- t

index . 16

Step 3: f

shift by
left if

Step 4:

element

$y(n)$.

Step 5:

$h(n-k)$

Step 6: P

for re

11/11

Graphical Method :-

Steps to do convolution sum using graphical method:

Step 1:- Choose the initial value of 'n' that will give the starting time for evaluating the O/p sequence $y(n)$. If $a(n)$ starts at $n=n_1$ and $b(n)$ starts at $n=n_2$. Then $n=n_1+n_2$ is a good choice.

Step 2:- Express the both sequences in terms of index scale.

Step 3: fold $b(k)$ about $k=0$ to obtain $b(-k)$ & shift by n to the right if n is +ve & shift left if n is -ve. to obtain $b(n-k)$.

Step 4: Multiply the 2 sequences $a(k)$ & $b(n-k)$ element by element & sum of the products to get $y(n)$.

Step 5: Increment index n & shift the sequence $b(n-k)$ to the right by one sample & do step 4.

Step 6: Repeat steps 5 until the sum of products is zero for remaining values of 'n'

$$g(3) = \frac{1}{2}$$

$$y(4) = 2$$

$$g(5) = 4$$

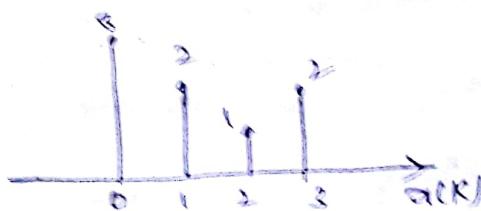
$$y(6) = 1$$

Matrix

$$* a(n) = \{3, 2, 1, 2\}, b(n) = \{1, 2, 1, 2\}$$

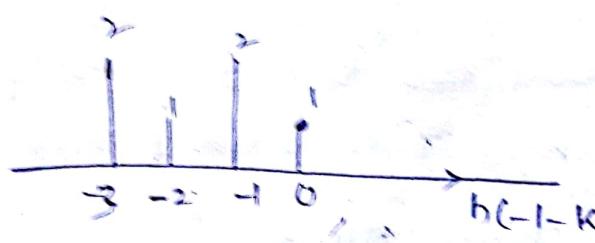
$$n_1 = 0, n_2 = -1$$

$$n = n_1 + n_2 = 0 - 1 = -1.$$



$$y(n) = \sum_{k=-\infty}^{\infty} a(k) b(n-k)$$

$$n = -1, \text{ shift by } k \leftarrow$$



$$y(0) = 6 + 2 = 8$$

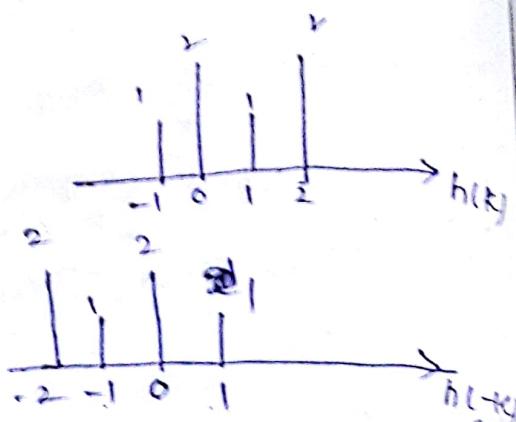
$$\cancel{y(1)} = \cancel{6+2+2} = 10$$

$$3+4+1 = 8$$

$$y(2) = 6 + 2 + 2 + 2$$

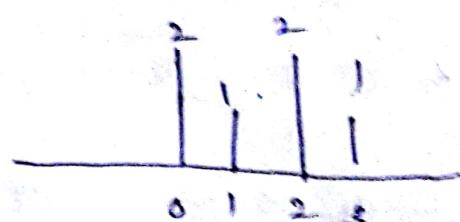
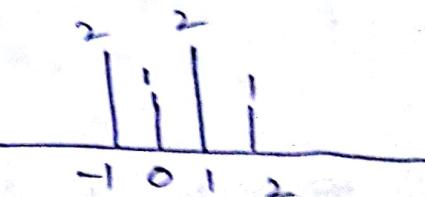
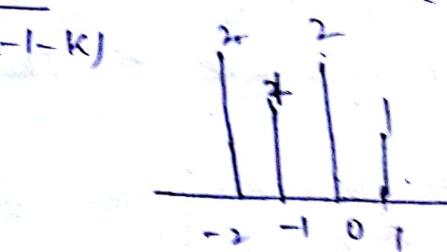
$$= 12$$

$$y(-1)$$



$$\Rightarrow y(-1) = 3 \quad y(+ \oplus G)$$

$$n(-1)$$



$$y(3) = 2 + 1 + u = 7$$

$$y(4) = 2 + 2 = 4$$

$$y(5) = 4$$

$$\begin{array}{r} 2 \\ \hline 1 & 1 & 1 & 1 \\ 2 & 2 & 2 & 1 \\ \hline 1 & 1 & 1 & 1 \\ 2 & 3 & 4 & 5 \end{array}$$

$$\begin{array}{r} 2 \\ \hline 1 & 1 & 1 & 1 \\ 2 & 2 & 2 & 1 \\ \hline 1 & 1 & 1 & 1 \\ 2 & 3 & 4 & 5 \end{array}$$

$$\rightarrow h(k)$$

$$y(n) = \{3, 8, 8, 12, 9, u, u, y\}$$

Matrix Method

$$\rightarrow h(k-1)$$

$$H X$$

$$H = \begin{bmatrix} b(0) & 0 & 0 & \dots & 1 \\ b(1) & b(0) & 0 & \dots & -1 \\ b(2) & b(1) & b(0) & \dots & 1 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ b(N-1) & b(N-2) & b(N-3) & \dots & -1 \\ 0 & b(N-1) & b(N-2) & \dots & 1 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & b(N-1) & 1 \end{bmatrix} \quad \alpha(0) \quad \alpha(1) \quad \alpha(2) \quad \dots \quad \alpha(N-1)$$

$$(N \times N-1) \times N-1$$

$$y[n] = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 2 & 1 & 0 & 0 \\ 1 & 2 & 1 & 0 \\ 2 & 1 & 2 & 1 \\ 0 & 2 & 1 & 2 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} 3 \\ 2 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 3 \\ 8 \\ 8 \\ 12 \\ 9 \\ 4 \\ 4 \end{bmatrix}$$

$$* a(n) = \{4, -$$

$$\rightarrow h(n) = a^n \cdot u(n)$$

find the convolution

$$\Rightarrow a=b,$$

$$\text{Sol: } y(n) = \sum_{k=0}^{\infty}$$

$$= \sum_{k=0}^{\infty}$$

$$a(n) =$$

impulse resp

$$\therefore y(n) =$$

Tabular array method:-

	-3	-2	-1	0	1	2	3	4	5	6
a(k)				3	2	1	2			
h(k)				1	2	1	2			
h(-k)	2	1	2							
h(-1-k)	2	1	2	1						
= 3										
h(-0-k)	8	2	1	2	1					
h(1-k)	8	2	1	2	1					
h(2-k)	12	2	1	2	1					
h(3-k)	9		2	11	12	1				
h(4-k)	4			2	1	2	1			
h(5-k)	4				2	1	2	1		

$$\text{if } a=b$$

$$y(n)$$

$$a(n) = \{4, 2, 1, 3\}, \quad h(n) = \{1, 2, 2, 1\}$$

$$\Rightarrow h(n) = a^n u(n) \text{ for } n \geq 0, \quad a(n) = b^n u(n)$$

find the convolution is of 2 finite duration sequences

$$\Rightarrow a=b, \quad \Rightarrow a \neq b.$$

$$a(n) = b^n u(n)$$

$$\text{Sol: } y(n) = \sum_{k=-\infty}^{\infty} a(k) h(n-k) = b^n; \quad n \geq 0$$

$$\sum_{k=-\infty}^n b^k a(k) \cdot a$$

$a(n) = 0, \quad h(n) = 0$ for $n < 0$, so, if sequence of impulse responses are causal.

$$\therefore y(n) = \sum_{k=0}^n a(k) h(n-k),$$

$$= \sum_{k=0}^n b^k \cdot a^{n-k}$$

$$= a^n \sum_{k=0}^n \left(\frac{b}{a}\right)^k$$

$$= a^n \left[1 + \frac{b}{a} + \left(\frac{b}{a}\right)^2 + \dots + \left(\frac{b}{a}\right)^n \right]$$

$$\text{if } a=b$$

$$y(n) = a^n (1 + 1 + \dots + 1)$$

$$= n \circledast (n+1) a^n.$$

Inverse -

of s

R/P to the

a(n)

$$\text{if } a \neq b \\ y(n) = a^n \left\{ \frac{1 - \left(\frac{b}{a}\right)^{n+1}}{1 - b/a} \right\}$$

$$= a^{n+1} \left(1 - \frac{(b/a)^{n+1}}{a-b} \right)$$

$$\rightarrow a(n) = 3^n u(n) \quad h(n) = \left(\frac{1}{3}\right)^n u(n).$$

$$a(n) * h(n)$$

$$a(n) * h(n) = \sum_{k=0}^n 3^k \left(\frac{1}{3}\right)^{n-k}$$

$$= \left(\frac{1}{3}\right)^n \sum_{k=0}^n 3^k \cdot 3^k$$

$$= \left(\frac{1}{3}\right)^n \sum_{k=0}^n 3^{2k} = \left(\frac{1}{3}\right)^n \sum_{k=0}^n 9^k$$

$$= \left(\frac{1}{3}\right)^n \cdot \frac{1 - 3^{2n+1}}{1 - 9} = \left(\frac{1}{3}\right)^n \frac{9^{n+1} - 1}{8}$$

$$= \left(\frac{1}{3}\right)^n \frac{q^{n+1} - 1}{8}$$

$$\rightarrow a(n) = n+3 \text{ for } 0 < n < 2, \quad h(n) = a^n u(n) + n \quad \text{find conv.}$$

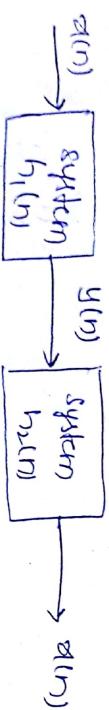
$a(n)$ & $h(n)$ are causal

$$y(n) = \sum_{k=0}^n (k+3) a^{n-k}$$

Defe -

Inverse System & de-convolution

A system is said to be invertible if the output of the system can be recovered from OF.



$$h_1(n) * h_2(n) = \delta(n)$$

$$y(n) = x(n) * h_1(n)$$

$$x(n) = y(n) * h_2(n)$$

$$= [x(n) * h_1(n)] * h_2(n)$$

$$= \cancel{x(n)} \text{ then } h_1(n) * h_2(n) = \delta(n).$$

Deconvolution:

$$y(n) = \sum_{k=-\infty}^{\infty} a(k) h(n-k)$$

for One sided sequence

$$y(n) = \sum_{k=0}^{\infty} a(k) h(n-k)$$

$$y(n) = \underbrace{a(0) h(n) + a(1) h(n-1) + \dots}_{y \text{ zero because one}}$$

odd sequence

$$y(0) = a(0) h(0)$$

$$a(0) = \frac{y(0)}{h(0)}$$

$$y(1) = a(0)h(1) + a(1)h(0)$$

$$a(1) = \frac{y(1) - a(0)h(1)}{h(0)}$$

$$y(2) = a(0)h(2) + a(1)h(1) + a(2)h(0)$$

$$a(2) = \frac{y(2) - a(0)h(2) - a(1)h(1)}{h(0)}$$

$$a(n) = \frac{y(n) - \sum_{k=0}^{n-1} a(k)h(n-k)}{h(0)}$$

$$\rightarrow h(n) = \{1, 2, 2, 1\}, \quad y(n) = \{4, 10, 13, 13, 10, 7, 3\}$$

$$a(0) = \frac{y(0)}{h(0)} = \frac{4}{1} = 4$$

$$T = N_1 + N_2 - 1$$

$$a(1) = \frac{y(1) - a(0)h(1)}{h(0)}$$

$$T = N_1 + N_2 - 1$$

$$= \frac{10 - 4(2)}{1}$$

$$T = N_1 + 3$$

$$= 2$$

$$a(2) = \frac{y(2) - a(0)h(2) - a(1)h(1)}{h(0)}$$

$$= \frac{13 - 4(2) - 2(2)}{1} = 1$$

$$a(3) = \frac{y(3) - \sum_{k=0}^2 a(k) h(3-k)}{h(0)}$$

$$= \frac{13 - 4(1) - 2(2) - 1(2)}{1}$$

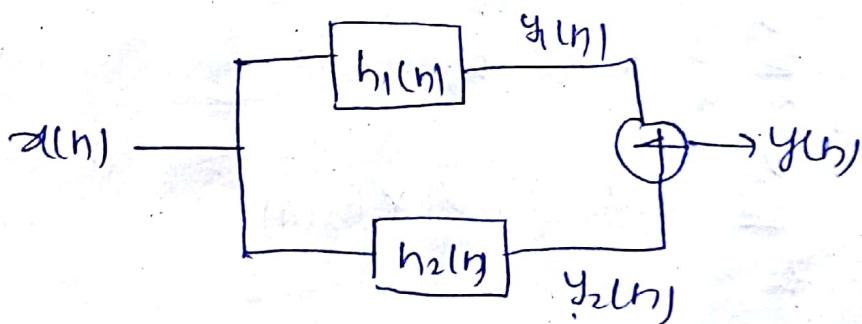
$$= 13 - 4 - 4 - 2$$

$$= 3$$

Interconnection of LTI System:-

→ Parallel Connection

The 2 systems are connected in parallel with impulse responses $a_1(n)$ & $a_2(n)$, then the overall impulse response is equal to the sum of 2 impulse responses.



$$y_1(n) = a(n) * h_1(n)$$

$$y_2(n) = a(n) * h_2(n)$$

$$y(n) = y_1(n) + y_2(n)$$

$$= \sum_{k=-\infty}^1 a(k) h_1(n-k) + \sum_{k=-\infty}^0 a(k) h_2(n-k)$$

$$\begin{aligned}
 &= \sum_{k=-\infty}^{\infty} \alpha(k) [h_1(n-k) + h_2(n-k)] \\
 &= \sum_{k=-\infty}^{\infty} \alpha(k) h_1(n-k) \\
 &\quad + \sum_{k=-\infty}^{\infty} \alpha(k) h_2(n-k)
 \end{aligned}$$

where $h(n) = h_1(n) + h_2(n)$.

⇒ cascade connection:-



$$y_1(n) = \sum_{k=-\infty}^{\infty} \alpha(k) h_1(n-k)$$

$$y(n) = y_1(n) * h_2(n)$$

$$y_1(n) = \sum_{k=-\infty}^{\infty} \alpha(k) h_1(n-k)$$

$$\begin{aligned}
 y(n) &= \sum_{k=-\infty}^{\infty} \alpha(k) h_1(n-k) * h_2(n) \\
 &= \sum_{k=-\infty}^{\infty} \sum_{p=-\infty}^{\infty} \alpha(k) h_1(k-p) * h_2(n-k)
 \end{aligned}$$

$$K-V=p$$

$$\begin{aligned}
 &= \sum_{v=-\infty}^{\infty} \alpha(v) \underbrace{\sum_{p=-\infty}^{\infty} h(p) \cdot h_2(n-p)}_{h_1(n-v) * h_2(n-v)}
 \end{aligned}$$

$$h_1(n) * h_2(n)$$

$$= \sum_{k=-\infty}^{\infty} a(n) h(n-k)$$

$$\therefore h(n) = h_1(n) * h_2(n)$$

$$(h_1(k) h_2(n-k))$$

$$h(n-k) = h_1(k) h_2(n-k)$$

Time response analysis of discrete-time LTI systems

The op of LTI can also be determined by using time response analysis (one method is convolution sum)

$$y(n) = - \sum_{k=0}^{N-1} a_k y(n-k) + \sum_{k=0}^{M-1} b_k x(n-k)$$

Total response = zero-state response + zero η_p response
 ↓ ↓
 initial conditions are $x(n)=0$
 zero. depends on η_p depends on initial conditions

Order = $\max(N, m)$

The system satisfies both LTI (i.e. coefficients are constants) and causality (i.e. depends on past η_p 's and η_p 's)

$$\text{E.g.: } y(n) = a_1 y(n-1) + x(n)$$

Let $x(n)=0$ for $n < 0$ and initial condition of $y(n)$ for $n=-1$ exists i.e. $y(-1) \neq 0$

$y(n) = y_n(n)$

natural

forced res

Natural

The natural

with $x(n)$

$y(n)$

y_l

$\sum_{k=0}^N$

λ_k

at $n=0$

$$y(0) = a_0 y(-1) + x(0)$$

$n=1$

$$y(1) = a_1 y(0) + x(1)$$

$$= a_1(a_0 y(-1) + x(0)) + x(1)$$

$$= a^2 y(-1) + a x(0) + x(1)$$

$$y(2) = a [a^2 y(-1) + a x(0) + x(1)] + x(2)$$

$$= a^3 y(-1) + a^2 x(0) + a x(1) + x(2)$$

$$\therefore y(n) = a^{n+1} y(-1) + \sum_{k=0}^n a^k x(n-k) \quad n \geq 0$$

$$y(n) = a^{n+1} y(-1) \text{ when } x(n) = 0 \rightarrow \text{zero if}$$

$$y(n) = \sum_{k=0}^n a^k x(n-k) \text{ when initial conditions are zero. It depends only on if}$$

The zero if response is called as natural response is obtained by substituting if signal is zero.

It depends on the nature of the system and the initial states only. It is also called natural response.

Zero state response is also called as forced response and here the if depends only on the applied if and all the initial conditions are zero.

It is

Roots

Let

(i) if

soluti

$$y(n) = y_h(n) + y_p(n)$$

natural response - zero I/p response (or) homogeneous sol^h

fixed response \rightarrow zero state "

Natural Response

The natural response $y_h(n)$ is the sol^h of the D.E with I/p is equal to zero.

$$y(n) = - \sum_{k=1}^N a_k y(n-k) + \sum_{k=0}^m b_k u(n-k)$$

$$y(n) + \sum_{k=1}^N a_k y(n-k) = 0$$

$$\sum_{k=0}^K a_k y(n-k) = 0 \quad \text{let } a_0 = 1$$

$$y_h(n) = \lambda^n$$

$$\sum_{k=0}^N a_k \lambda^k = 0, \quad a_0 = 1$$

$$\lambda^0 + a_1 \lambda^1 + a_2 \lambda^2 + \dots + a_N \lambda^N = 0$$

$$\lambda^{N+1} [\lambda^N + a_1 \lambda^{N-1} + \dots + a_N] = 0$$

$$\lambda^{N+1} + a_1 \lambda^N + \dots + a_N = 0$$

It is called as characteristic equation of the system.

Roots decide the nature of the system.

Let the roots be $\lambda_1, \lambda_2, \dots, \lambda_N$

$$(\lambda - \lambda_1)(\lambda - \lambda_2) \dots (\lambda - \lambda_N) = 0$$

(i) If the roots are distinct, then it has ' N ' solutions. i.e. $\lambda_1^n \lambda_2^n \dots \lambda_N^n$

$$y_n(n) = a\lambda_1^n + b\lambda_2^n + c\lambda_3^n$$

+ $c_N \lambda_N^n$

Let $\lambda_1 = 3, \lambda_2 = 4$

$$y_n(n) = a3^n + b4^n$$

(iii) If the roots λ_i is repeated 'm' times, and the remaining $(N-m)$ roots are distinct - then the characteristic eqn is

$$(\lambda - \lambda_1)^m (\lambda - \lambda_{m+1}) \dots (\lambda - \lambda_N) = 0$$

$$y_n(n) = a$$

$$y_n(n) = (a + c_1 n + c_2 n^2 + \dots + c_{m-1} n^{m-1}) \lambda_1^n + c_m n^m \lambda_{m+1}^n + \dots + c_N \lambda_N^n$$

Eg: $\lambda_1 = -1, \lambda_2 = -1, \lambda_3 = -1, \lambda_4 = 3$

$$y_n(n) = (a + c_1 n + c_2 n^2) (-1)^n + c_4 (3)^n$$

(iv) If the roots are complex, solution is

$$\lambda_1 = a + jb, \lambda_2 = a - jb$$

$$y_n(n) = r^n (A_1 \cos \theta n + A_2 \sin \theta n)$$

$$r = \sqrt{a^2 + b^2}, \theta = \tan^{-1}(b/a)$$

12A13

→ find the note
by difference

$$y(n) =$$

with initial conditions

SOL: zero

$$y(n) +$$

Assume

$$\lambda^n$$

$$\lambda^n$$

$$\lambda^n$$

$$d$$

$$y_n(n)$$

$$n=0,$$

$$n=1,$$

from the

$$y_n = 0,$$

$$y(1)$$

12/12

→ find the natural response of an LTI system described by difference equation

$$y(n) + 2y(n-1) + y(n-2) = x(n) + x(n-1).$$

With the initial conditions $y(-1) = y(-2) = 1$,

SOL: zero $i_p \Rightarrow c(n) = 0$

$$y(n) + 2y(n-1) + y(n-2) = 0$$

Assume $y_h(n) = k^n$

$$k^n + 2k^{n-1} + k^{n-2} = 0$$

$$k^{n-2}[k^2 + 2k + 1] = 0$$

$$\begin{aligned} k^{n-2}(k+1)^2 &= 0 \\ (k+1)^2 &= 0 \end{aligned}$$

$$k_1 = -1, \quad k_2 = -1.$$

$$y_h(n) = (c_1 + c_2 n)(-1)^n$$

$$n=0, \quad y(0) = c_1$$

$$n=1, \quad y(1) = -c_1 + c_2$$

from the diff eqn

$$\begin{aligned} y_0 &= 0, \\ y(0) + 2y(-1) + y(-2) &= 0 \end{aligned}$$

$$\begin{aligned} y(0) + 3 &= 0 \\ y(0) &= -3 \end{aligned}$$

$$y(1) + 2y(0) + y(-1) = 0$$

$$y(1) - 6 + 1 = 0$$

$$y(1) = 5$$

-form 0

$$y(0) = c_1 \Rightarrow c_1 = -3$$

$$y(1) = -c_1 - c_2$$

$$5 = -3 - c_2$$

$$c_2 = -2$$

Homogeneous soln.

$$y_h(n) = 0(-3 - 2n)(-1)^n$$

$$y_h(n) = -3(-1)^n u(n) - 2n(-1)^n u(n)$$

→ forced response

→ find the NR $y(n) - 4y(n-1) + 4y(n-2) = a(n) - a(n)$

With the initial conditions

$$y(-1) = y(-2) = 1$$

Forced Response

Zero state R

the initial

e/p only.

particular

can be c

by finding
of the char

→ Particular

unit ste

$A n^k$

$A n^m$

$A \sin$

$A \cos$

δt

The co

these

The

condit

Forced Response: - $y_p(n)$

Zero state Response (Forced response) is the response where the initial conditions are zero and y_p depends on the $\frac{d}{dt}$ only. It consists of homogenous solution and particular solution.

$y_h(n) + y_p(n)$

can be obtained
by finding the roots
of the characteristic eqn

$x(n) \rightarrow n \geq 0$
 $x(n) = 0, n < 0$

→ Particular solⁿ depends on $\frac{d}{dt}$ only

<u>$\frac{d}{dt} n(n)$</u>	<u>$y_p(n)$</u>
unit step $u(n)$	$K u(n)$
$-A M^n$	$K M^n$
$A n^m$	$K_0 n^M + K_1 n^{M-1} + \dots + K_M$
$A \sin \omega n$	$Q \cos(\omega n) + C_2 \sin(\omega n)$
$A \cos \omega n$	
$\delta(n)$	0

The constants can be obtained by substituting
these sol's $y_p(n)$ & $n(n)$ in difference eqn.

The homogenous solⁿ is obtained without initial
conditions in case of forced response.

of the HTL system

→ find the forced response

the diff equation

$$y(n) + 2y(n-1) + y(n-2) = a(n) + a(n-1)$$

$$\text{with } y_p \quad a(n) = (y_2)^n u(n).$$

$$y_f(n) = y_h(n) + y_p(n)$$

$$y_h(n) = (c_1 + c_2 n) (-1)^n$$

$$a(n) = (y_2)^n u(n)$$

$$y_p(n) = K(y_2)^n u(n)$$

substitute in diff eqn.

$$K\left(\frac{1}{2}\right)^n + 2K\left(\frac{1}{2}\right)^{n-1} + \left(\frac{1}{2}\right)^{n-2} = \left(\frac{1}{2}\right)^n + \left(\frac{1}{2}\right)^{n-1}$$

$$n=2$$

$$\frac{K}{4} + \frac{K}{2} + K = \frac{1}{4} + \frac{1}{2}$$

$$K + \cancel{K+K} = 1+2$$

$$5 \cancel{K} = -1$$

$$\cancel{K} = \underline{\underline{K}}_3$$

$$\frac{K+8K}{4} = \frac{8+2}{4}$$

$$9K = 3$$

$$K = \underline{\underline{K}}_3$$

$$y_p(n) = \underline{\underline{K}}_3 (y_2)^n u(n)$$

$$y_f(n) = y_0(n) + y_1(n)$$

$$= (\gamma_1 + \gamma_2)(-1)^n u(n) + (\gamma_3)(\gamma_2)^n u(n)$$

γ_1, γ_2 can be obtained with the initial conditions

i.e. $y(-1) = y(-2) = 0$.

$$n=0; y(0) = \gamma_1 + \gamma_3$$

$$n=1; y(1) = -\gamma_1 - \gamma_2 + \gamma_6$$

from the diff eqn

$$n=0 \quad y(0) + 2y(-1) + y(-2) = \alpha(0) + \alpha(-1)$$

$$y(0) + 0 + 0 = 1 + 0$$

$$y(0) = 1 \quad \textcircled{1}$$

$$n=1 \quad y(1) + 2y(0) + y(-1) = \alpha(1) + \alpha(0)$$

$$y(1) + 2 = \gamma_2 + 1$$

$$y(1) = -\gamma_2 - 0$$

$$y(1) = 1$$

$$\gamma_1 + \gamma_3 = 1$$

$$\gamma_1 = 2\gamma_3$$

$$y(1) = -\gamma_2$$

$$-\gamma_1 - \gamma_2 + \gamma_6$$

$$\gamma_2 = \alpha$$

$$y_f(n) = (\gamma_1 + 0)(-1)^n u(n) + (\gamma_3)(\gamma_2)^n u(n)$$

$$y_f(n) = (\gamma_1)(-1)^n u(n) + (\gamma_3)(\gamma_2)^n u(n).$$

$$y(-1) =$$

you

y(0)

y(1)

y(2)

from the

initial condition

are

$$y(-1) = y(-2) = 1.$$

sol: Natural response

when $\alpha(n) = 0$

$$y(n) + 4y(n-1) + 4y(n-2) = 0$$

$$y(n) = \lambda^n$$

$$\lambda^n + 4\lambda^{n-1} + 4\lambda^{n-2} = 0$$

$$\lambda^{n-2} (\lambda^2 + 4\lambda + 4) = 0$$

$$\lambda^2 + 4\lambda + 4 = 0$$

$$\lambda^2 - 4\lambda + 4 = 0$$

$$\lambda = \frac{-4 \pm \sqrt{16 - 16}}{2} = 0$$

$$\lambda = 2, 2$$

$$= 2 \pm \sqrt{3}$$

$$y_1(n) = (c_1 + c_2 n) \lambda^n$$

$$y_2(n) = (c_1 + c_2 n) 2^n$$

$$y(-1) = y(-2) = 1$$

$$y(0) = q$$

$$y(1) = (c_1 + c_2 \omega)^2$$

from the homogeneous diff eqn.

$$y(0) - 4y(-1) + 4y(-2) = 0$$

$$y(0) - 4(1) + 4(-1) = 0$$

$$y(0) = 0$$

$$y(1) - 4y(0) + 4y(-1) = 0$$

$$y(1) = -4$$

$$c_1 = 0$$

$$(c_1 + c_2 \omega)^2 = -4$$

$$c_2 = -2$$

$$y_h(n) = y_h(n) = -2n \cdot 2^n u(n)$$

↓

Because we find it
for causal sequence.

$$y = y_h(n) + y_p(n)$$

$$y_h(n) = (c_1 + c_2 n)^2$$

We take without taking initial
conditions because it is zero after $n=0$.

$y(1) =$

$y(1)$

$1 =$

$a(n) = (-1)^n u(n)$

$y_p(n) = k(-1)^n u(n)$

Substitute in diff eqn.

$$k(-1)^n u(n) - 4k(-1)^{n-1} u(n-1) + 4k(-1)^{n-2} u(n-2) = (-1)^n u(n)$$
$$- (-1)^{n-1} u(n-1)$$

$n=2$

$k - 4k(-1) + 4k = 1 - (-1)$

$9k = 2$

$K = 2/9$

$y_p(n) = \frac{2}{9} (-1)^n u(n)$

$y(n) = (c_1 + c_2 n) 2^n + \frac{2}{9} (-1)^n u(n)$

$y(-1) = y(-2) = 0$

$\cancel{y(-1)} = (c_1 + c_2) \frac{1}{2} + \frac{2}{9} (-1)(0)$

$0 = \cancel{(c_1 + c_2)} + \frac{2}{9}$

$y(0) = c_1 + 2/9$

$y(1) = 2c_1 + 2c_2 + 2/9$

$y(0) - 4y(-1) + 4y(-2) = a(0) - a(-1) \rightarrow H + \text{prev val}$

$y(0) - 4(0) + 4(0) = ?$

$y(0) = 1$

y_f

$y(n)$

(on)

if we

f

1

$$y(1) - 4y(0) + 4y(-1) = \alpha(1) - \alpha(0)$$

$$y(1) - 4 = -1 - 1 \Rightarrow y(1) = 2$$

$$1 = c_1 + 2/9$$

$$c_1 = 1 - 2/9$$

$$= 7/9$$

$$y_{u1} = \frac{14}{9} + 2c_2 \xrightarrow{*} \frac{2}{9}$$

$$2 = \frac{12}{9} + 2c_2$$

$$2c_2 = 2 - \frac{12}{9}$$

$$= 6/9$$

$$c_2 = 3/9 = y_3$$

$$y_f(n) = \left(\frac{7}{9} + y_3 n\right) 2^n u(n) + \frac{2}{9} (-1)^n u(n)$$

$$y(n) = y_h(n) + y_f(n)$$

$$= -2n \cdot 2^n u(n) + \frac{7}{9} 2^n u(n) + \frac{1}{3} n 2^n u(n) + \frac{2}{9} (-1)^n u(n)$$

$$y(n) = \left(\frac{7}{9} - \frac{5}{3}n\right) 2^n u(n) + \frac{2}{9} (-1)^n u(n)$$

(On) $y(n) = (c_1 + c_2 n) 2^n + \frac{2}{9} (-1)^n u(n)$

If we substitute initial conditions at zero we get forced response

If we substitute initial conditions we get total response

$\rightarrow y(n) = y(n-1) + 0.5 y(n-2) + \alpha(n) + \alpha(n-1)$. find natural, forced, total response with $i/p \alpha(n) = 2^n u_{n_0}$
initial condition $y(-1) = y(-2) = 1$.

18/12

Impulse Response:

$y(n) = y_h(n) + y_p(n)$ if $\alpha(n) = \delta(n)$
 $= y_h(n) + y_p(n)$: $y_h(n) = y_h(n)$
 \rightarrow find the impulse response of LTI system described by
the diff equation $y(n) = 0.6 y(n-1) - 0.08 y(n-2) + \alpha$

Sol:-

- if δ_p is impulse the particular soln $y_p(n) = 0$
- Hence, the $y_h(n)$ can be computed from the homogeneous
solns with the initial conditions are zero.

$$y_h(n) = 0.6 y_h(n-1) - 0.08 y_h(n-2)$$

$$y_h(n) = \lambda^n$$

$$\lambda^n - 0.6\lambda^{n-1} + 0.08\lambda^{n-2} = 0$$

$$\lambda^{n-2}(\lambda^2 - 0.6\lambda + 0.08) = 0$$

$$\lambda^2 - 0.6\lambda + 0.08 = 0$$

$$\lambda^2 - 0.4\lambda + 0.2\lambda + 0.08 = 0$$

$$\lambda(\lambda - 0.4) + 0.2(\lambda - 0.4) = 0$$

$$\lambda = 0.4, 0.2$$

$$\lambda_1 = 0.4, \lambda_2 = 0.2$$

$$y(n) = c_1 \lambda_1^n + c_2 \lambda_2^n$$

$$y(n) = c_1 (0.4)^n + c_2 (0.2)^n, \quad n \geq 0.$$

$$c_1 (0.4)^n + c_2$$

$$n=0, \quad y(0) = c_1 + c_2$$

$$n=1, \quad y(1) = 0.4 c_1 + 0.2 c_2$$

from the diff eq.

$$n=0, \quad y(0) = 0.6 y(-1) - 0.08 y(-2) + a(0)$$

All the initial conditions are zero

$$c_1 + c_2 = 0 - 0 + 1 \quad y(0) = 0$$

$$c_1 \cancel{=} \quad c_1 + c_2 = 1$$

$$n=1, \quad y(1) = 0.6 y(0) - 0.08 y(-1) + a(1)$$

$$0.4 c_1 + 0.2 c_2 = 0.6 - 0 + 0$$

$$0.4 c_1 + 0.2 c_2 = 0.6$$

$$0.2 c_1 + 0.2 c_2 = 0.2$$

$$\underline{\underline{0.2 c_1 = 0.4}}$$

$$c_1 = 2, \quad c_2 = -1$$

$$y_1(n) = 2(0.4)^n - (0.2)^n; \quad n \geq 0$$

$$= 2(0.4)^n u(n) - (0.2)^n u(n)$$

Here we consider it because we are considering partial solns so, we have to consider only

Step response:

→ find impulse & step response of DT LTI system, whose diff eqn given by $y(n) = y(n-1) + 0.5y(n-2) + d_1 + d_2$

Sol:

$$y(n) = y_h(n) + y_p(n)$$

$$y_p(n) = K u(n)$$

$$y_h(n) = y(n-1) + 0.5y(n-2)$$

$$y(n) - y(n-1) - 0.5y(n-2) = 0$$

$$\lambda^2 - \lambda - 0.5\lambda^{-2} = 0$$

$$\lambda^2(\lambda - 1 - 0.5) = 0$$

$$\lambda - 1 - 0.5 = 0$$

$$\lambda^2 - \lambda + 0.5\lambda - 0.5 = 0 \quad \lambda = \frac{1 \pm \sqrt{1+2}}{2}$$

$$\lambda(\lambda - 1) + 0.5(\lambda - 1) = 0 \quad = \frac{1 \pm \sqrt{3}}{2}$$

$$\lambda = 1, \lambda = -0.5$$

$$\lambda_1 = 1, \lambda_2 = -0.5$$

$$\lambda_1 = 1.366,$$

$$\lambda_2 = -0.366.$$

$$y_h(n) = C_1(1)^n + C_2(-0.5)^n$$

$$= C_1 + C_2(-0.5)^n?$$

$$\text{By substi} \quad y_h(n) = \left(\frac{1}{2}\right)^n \left[C_1 \cos \frac{\sqrt{3}}{2} n + C_2 \sin \frac{\sqrt{3}}{2} n \right]$$

$$y_h(n) = C_1 \left(\frac{1+\sqrt{3}}{2}\right)^n + C_2 \left(\frac{1-\sqrt{3}}{2}\right)^n$$

$y_p(n)$ sub. in diff eqn

$$\bullet K u(n) = K u(n-1) + 0.5 K u(n-2) + u(n) + u(n-1)$$

$$K = K + 0.5K + 1 + 1$$

$$-2 = 0.5K \Rightarrow K = -4.$$

$$y_p(n) = -4u(n)$$

$$y_h(n) = C_1 (1.366)^n + C_2 (-0.366)^n$$

$$y(n) = C_1 (1.366)^n + C_2 (-0.366)^n - 4u(n)$$

~~$$y(0) = C_1 + C_2 - 4$$~~

~~$$y(4) = 1.366 C_1 - 0.366 C_2 - 4$$~~

~~$$y(n) = C_1 (1.366)^{n-1} + C_2 (-0.366)^{n-2}$$~~

from diff eqn

$$y(n) = y(n-1) + 0.5 y(n-2) + u(n) + u(n-1)$$

$$y(0) = y(-1) + 0.5 y(-2) + u(0) + u(-1)$$

$$y(0) = ?$$

$$y(1) = y(0) + 0.5 y(-1) + u(1) + u(0)$$

$$y(1) = ?$$

$$C_1 + C_2 - 4 = 1 \Rightarrow C_1 + C_2 = 5$$

$$1.366 C_1 - 0.366 C_2 - 4 = 2$$

$$1.366 C_1 - 0.366 C_2 = 6$$

~~0.366~~

MSC

$$\begin{array}{r} 0.366 \\ \times 5 \\ \hline 1.830 \end{array}$$

$$0.366C_1 + 0.366C_2 = 1.830$$

$$1.366C_1 - 0.366C_2 = 6$$

$$1.732C_1 = 7.830$$

$$\begin{array}{r} 1.732 \\ \times 5 \\ \hline 8.660 \end{array}$$

$$C_1 = 5.09$$

$$C_2 = -0.9$$

$$y(n) = 5.09(1.366)^n - 0.9(0.366)^n - 1u(n)$$

Impulse

$$y(n) = C_1(1.366)^n + C_2(0.366)^n$$

$$y(0) = C_1 + C_2$$

$$y(1) = 1.366C_1 - 0.366C_2$$

By differen

$$y(0) = y(-1) + 0.5y(-2) + \delta(0) + \delta(-1)$$

$$y(0) = 1$$

$$y(1) = y(0) + 0.5y(-1) + \delta(1) + \delta(0)$$

$$y(1) = 1 + 1$$

$$y(1) = 2$$

$$C_1 + C_2 = 1$$

$$1.366C_1 - 0.366C_2 = 2$$

$$C_1 = 1.866, \quad C_2 = -0.866$$

19/12/17

frequency Domain Representation of discrete time signals & systems:-

$$X(\omega) = \int_{-\infty}^{\infty} x(t) \cdot e^{-j\omega t} dt$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) \cdot e^{j\omega t} d\omega$$

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} a(n) \cdot e^{-j\omega n}$$

$$a(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega}) \cdot e^{j\omega n} d\omega$$

$$\delta(n) = 0 \quad \text{if } a(n) = u(n)$$

$$X(e^{j\omega}) = \sum_{n=0}^{\infty} 1 \cdot e^{-j\omega n}$$

$$= \frac{1}{1 - e^{-j\omega}}$$

$$a^n u(n) = a(n)$$

$$X(\omega) = \sum_{n=-\infty}^{\infty} a(n) \cdot e^{-j\omega n}$$

$$= \sum_{n=0}^{\infty} a^n e^{-j\omega n}$$

$$= \sum_{n=0}^{\infty} (a \cdot e^{-j\omega})^n$$

$$= \frac{1}{1 - a \cdot e^{-j\omega}} \quad |a| < 1$$

$$X(e^{j\omega}) = X_R(e^{j\omega}) + j X_I(e^{j\omega})$$

$$|X(e^{j\omega})|, |\theta(\omega)|$$

~~Real~~ Real part \rightarrow even function.

Imaginary part \rightarrow odd function.

magnitude \rightarrow even function.

angle \rightarrow odd function.

Existence of DTFT

~~Ex:~~ It exists for all periodic signals, but aperiodic signals should satisfy certain conditions.

The sufficient condition for existence of DTFT for

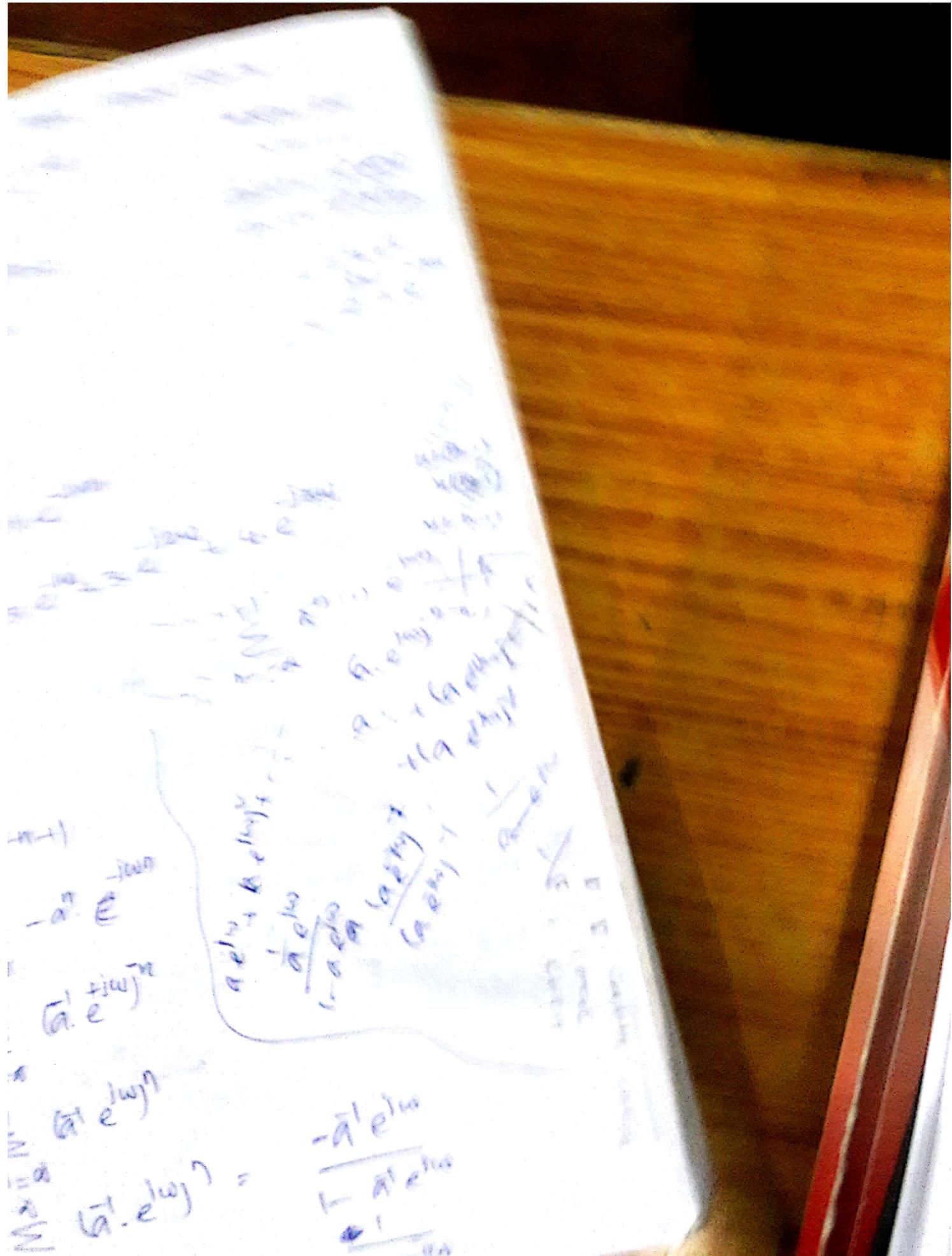
A ~~periodic~~ aperiodic sequence $a(nT)$ is

$$\sum_{n=-\infty}^{\infty} |a(n)| < \infty \quad (\text{Absolutely summable})$$

↓
should be finite.

If the sequence is not satisfied the above condition also the Fourier transform exist

Eg: Unit step, cos $\omega_0 n$, sin $\omega_0 n$, $e^{j\omega_0 n}$



→ find the DTFT of the input $\delta(n+3) - \delta(n-3)$

$$x(e^{j\omega}) = \sum_{n=-\infty}^{+\infty} a(n) \cdot e^{-jn\omega}$$

$$= \sum_{n=-\infty}^{+\infty} \delta(n+3) - \delta(n-3)$$

$$= e^{j3\omega} - e^{-j3\omega}$$

$$\delta(n) = \delta(n_0)$$

$$x(z) = 1$$

$$\delta(n+3) = z^3 \cancel{x(z)}$$

$$\delta(n-3) = z^{-3} x(z)$$

$$= z^3 + z^{-3}$$

$$j\omega - j\omega$$

$$= e + e$$

$$\rightarrow a(n) = \{1, 2, 3, 4\}$$

$$x(e^{j\omega}) = \sum_{n=0}^{N-1} a(n) \cdot e^{-jn\omega}$$

$$= 1 + 2e^{-j\omega} + 3e^{-j2\omega} + 4e^{-j3\omega}$$

$$\rightarrow a(n) = -a^n u(-n-1)$$

$$x(e^{j\omega}) = \sum_{n=-\infty}^{-1} -a^n \cdot e^{-jn\omega}$$

$$= - \sum_{n=-\infty}^{-1} (\bar{a} \cdot e^{j\omega})^n$$

$$= - \sum_{n=0}^{\infty} (\bar{a} \cdot e^{j\omega})^n$$

$$= - \sum_{n=1}^{\infty} (\bar{a} \cdot e^{j\omega})^n$$

$$\begin{aligned} & - \sum_{n=-\infty}^{-1} \bar{a}^n e^{-jn\omega} \\ & = \frac{1}{1 - \bar{a} e^{j\omega}} \end{aligned}$$

$$\begin{aligned} & \frac{-\bar{a} e^{j\omega}}{1 - \bar{a} e^{j\omega}} \\ & = \frac{1}{1 - \bar{a} e^{j\omega}} \end{aligned}$$

$$\rightarrow \sigma(n) = (Y_{21})^n u(n+1)$$

$$\sigma(n) = (0.5)^n u(n) - 2^n u(-n-1)$$

$$\sum_{n=-\infty}^{\infty} (Y_{21})^n e^{jn\omega} = (Y_{21})^{-1} + (Y_{21})^0 + (Y_{21})^1$$

$$= 1 - (Y_{21})^{-1} + (Y_{21})^0 + (Y_{21})^1$$

$$= 4 \left(\frac{1}{1-Y_{21}} \right)$$

$$= 4 \times \frac{1}{3/4}$$

$$= \frac{16}{3}$$

$$= \sum_{n=-1}^{\infty} (Y_{21} e^{j\omega})^n$$

$$= (Y_{21} e^{j\omega})^{-1} + (Y_{21} e^{j\omega})^0 + (Y_{21} e^{j\omega})^1$$

$$= (Y_{21} e^{j\omega})^{-1} \left[1 + (Y_{21} e^{j\omega})^0 + (Y_{21} e^{j\omega})^1 \right]$$

$$= \frac{4 e^{j\omega}}{1 - Y_{21} e^{j\omega}}$$

③ $x(n) = (0.5)^n u(n) \rightarrow u(n-1)$

$$\begin{aligned} x(e^{j\omega}) &= \sum_{n=0}^{\infty} (0.5)^n e^{jn\omega} - \sum_{n=-\infty}^0 (0.5)^n e^{jn\omega} \\ &= \frac{1}{1 - 0.5 e^{j\omega}} - \sum_{n=1}^{\infty} (2^{-n} e^{jn\omega})^n \\ &= \frac{1}{1 - 0.5 e^{j\omega}} - \frac{2^1 e^{j\omega}}{1 - 2^1 e^{j\omega}} \quad (\because a < 1) \\ &= \frac{1}{0.5 e^{j\omega}} + \frac{1}{2 e^{j\omega}} \end{aligned}$$

Properties of DTFT:-

⇒ Linearity

$$f[a_1(n)] = x_1(e^{j\omega}), f[a_2(n)] = x_2(e^{j\omega}).$$

$$f[a_1(n) + b_2(n)] = a_1 x_1(e^{j\omega}) + b_2 x_2(e^{j\omega}).$$

⇒ Periodicity.

$$f[a(n)] = x(e^{j\omega})$$

if $x(e^{j\omega})$ is periodic in ω . with period 2π

$$x(e^{j\omega}) = x(e^{j(\omega \pm 2\pi k)})$$

⇒ Time shifting

$$f[a(n)] = x(e^{j\omega}).$$

$$f[a(n-k)] = e^{-jk\omega} \cdot x(e^{j\omega})$$

$$= \sum_{n=-\infty}^{\infty} a(n-k) \cdot e^{-jn\omega}$$

$$= \sum_{n=k}^{\infty} a(n) \cdot e^{-jn\omega} \cdot e^{jk\omega}$$

$$= e^{-jk\omega} \cdot x(e^{j\omega}).$$

⇒ Frequency shifting property

$$f[a(n)] = x(e^{j\omega})$$

$$f[a(n), e^{j\omega_0 n}] = x[e^{j(\omega - \omega_0)}]$$

$$= \sum_{n=-\infty}^{\infty} a(n) \cdot e^{j\omega_0 n} \cdot e^{-jn\omega}$$

$$= \sum_{n=-\infty}^{\infty} a(n) e^{-j(\omega - \omega_0)n}$$

$$= X(e^{+j(\omega - \omega_0)})$$

Time reversal property

$$f(a(n)) = X(e^{j\omega}).$$

$$f(a(-n)) = X(e^{-j\omega}).$$

$$f(a(-n)) = \sum_{n=-\infty}^{\infty} a(-n) e^{-j\omega n}$$

$$= \sum_{n=-\infty}^{\infty} a(n) e^{-j\omega n}$$

$$= \sum_{n=-\infty}^{\infty} a(n) e^{-j(-\omega)n}$$

$$= X(e^{-j\omega}).$$

Differentiation in frequency

$$f(a(n)) = X(e^{j\omega})$$

$$f(na(n)) = j \cdot \frac{d}{d\omega} X(e^{j\omega}).$$

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} a(n) e^{-j\omega n}$$

$$\frac{d}{d\omega} X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} a(n) \frac{e^{-j\omega n}}{(-j\omega)}$$

$$-j \frac{d}{d\omega} X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} n a(n) e^{-j\omega n}$$

$$j \frac{d}{d\omega} X(e^{j\omega})$$

Time convolu

$$f(a_1(n))$$

$$f(a_2(n))$$

$$f(a_1(n) a_2(n))$$

$$a_1(n) a_2(n)$$

$$f(a_1(n))$$

frequency

$$f f'$$

$$f f'$$

$$f f'$$

$$\int \frac{d}{d\omega} X(e^{j\omega}) = f[n]x(n)$$

Time Convolution:-

$$f[x_1(n)] = X_1(e^{j\omega})$$

$$f[x_2(n)] = X_2(e^{j\omega})$$

$$f[x_1(n) * x_2(n)] = X_1(e^{j\omega}) \cdot X_2(e^{j\omega})$$

$$x_1(n) * x_2(n) = \sum_{k=-\infty}^{\infty} x_1(k) x_2(n-k),$$

$$f[x_1(n) * x_2(n)] = \sum_{n=-\infty}^{\infty} x_1(n) * x_2(n) \cdot e^{-jn\omega}$$

$$\begin{aligned} &= \sum_{n=-\infty}^{\infty} \sum_{k=-\infty}^{\infty} x_1(k) x_2(n-k) \cdot e^{-jn\omega} \\ &= \sum_{k=-\infty}^{\infty} \sum_{n=-\infty}^{\infty} x_1(n-k) \cdot x_2(n-k) \cdot e^{-jn\omega} \\ &= \sum_{k=-\infty}^{\infty} x_1(k) \cdot X_2(e^{jk\omega}) \cdot e^{-jn\omega} \end{aligned}$$

$$= \underline{\underline{x}_2(e^{j\omega})} \cdot \underline{\underline{X_1(e^{j\omega})}}$$

frequency convolution:-

$$f[x_1(n)] = X_1(e^{j\omega})$$

$$f[x_2(n)] = X_2(e^{j\omega})$$

$$f[x_1(n), x_2(n)] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X_1(e^{j\theta}) \cdot X_2(e^{j(\omega-\theta)}) d\theta.$$

Convolution Property:-

$$\text{if } F[x_1(n)] = X_1(e^{j\omega})$$

$$F[x_2(n)] = X_2(e^{j\omega}).$$

$$F[x_{1,2}(n)] = F_{1,2}(e^{j\omega}) = X_1(e^{j\omega}), X_2(e^{j\omega}).$$

Modulation Property:-

$$f[n(n) \cos(\omega_0 n)] = [X[e^{-j(\omega+\omega_0)}] + X[e^{j(\omega-\omega_0)}]]$$

Symmetry Property:-

$$X(e^{j\omega}) = X_R(e^{j\omega}) + jX_I(e^{j\omega}).$$

$$X(e^{j\omega}) = |X(e^{j\omega})| e^{j\theta(\omega)}$$

$$X(e^{j\omega}) = \sqrt{X_R^2(e^{j\omega}) + X_I^2(e^{j\omega})}$$

$$|X(e^{-j\omega})| = \sqrt{X_R^2(e^{-j\omega}) + X_I^2(e^{-j\omega})}$$

$$= |X(e^{j\omega})|$$

$$\theta(\omega) = \tan^{-1} \left(\frac{X_I(\omega)}{X_R(\omega)} \right)$$

$$\theta(\omega) \text{ for } X(e^{-j\omega}) = \tan^{-1} \left(\frac{X_I(-\omega)}{X_R(\omega)} \right)$$

$$= \tan^{-1} \left(- \frac{X_I(\omega)}{X_R(\omega)} \right)$$

$$= -\theta(\omega)$$

① $y(n)$

system

② $F[n]$

a)

b)

③ $x(n)$

the

④ x

the

⑤ yes

are

(

f

① $y(n) + y(n-1) = \cos 2n$. Find the total response of the system.

② Find the DTFT for the following I/P's

a) $x(n) = u(n)$

b) $x(n) = -e^{-2n} \text{ for } n=0, 1, 2$

• e^{3n} for $n=-1, -2, -3$

c) $x(n) = e^{2n}$

③ $x(n) = \left(\frac{3}{4}\right)^n u(n)$ $h(n) = \left(\frac{1}{2}\right)^n u(n)$ Find the DTFT of the O/P response ($Y(e^{j\omega})$)

④ $x(n) = (-1)^n u(n)$ $h(n) = \left(\frac{1}{2}\right)^n u(n)$ Find the DTFT of the O/P response.

⑤ $y(n) + y(n-1) + 2y(n-2) = x(n-1) + 2x(n-2)$. Find the impulse response of the system.

($\because N=M=2$ so $y_h(n)$ includes an impulse function $A\delta(n)$)

27/12/19.

frequency Response analysis of discrete-time systems:

$$y(n) = \sum_{k=-\infty}^{\infty} a(k) h(n-k)$$

$$(or) y(n) = \sum_{k=-\infty}^{\infty} a(n-k) h(k)$$

Let $a(n) \cdot e^{j\omega n}$

$$y(n) = \sum_{k=-\infty}^{\infty} e^{j\omega(n-k)} \cdot h(k)$$

$$y(n) = e^{j\omega n} \sum_{k=-\infty}^{\infty} e^{-j\omega k} \cdot h(k)$$

$$y(n) = e^{j\omega n} \cdot H(e^{j\omega})$$

$$H(e^{j\omega}) = \sum_{k=-\infty}^{\infty} h(k) \cdot e^{-j\omega k}$$

$H(e^{j\omega})$ period is 2π

$$H(e^{j\omega}) = |H(e^{j\omega})| \cdot e^{j\theta(\omega)}$$

$$\theta(\omega) = \underline{|H(e^{j\omega})|}$$

$$y(n) - a y(n-1) = a(n)$$

Apply DTFT

$$Y(e^{j\omega}) - a e^{-j\omega} \cdot Y(e^{j\omega}) = X(e^{j\omega})$$

$$H(e^{j\omega}) = \frac{Y(e^{j\omega})}{X(e^{j\omega})} = \frac{1}{1 - a \cdot e^{-j\omega}}$$

$$H(e^{j\omega}) = \frac{1}{1 - a\cos\omega - j\sin\omega}$$

$$= \frac{1}{1 - a\cos\omega + ja\sin\omega}$$

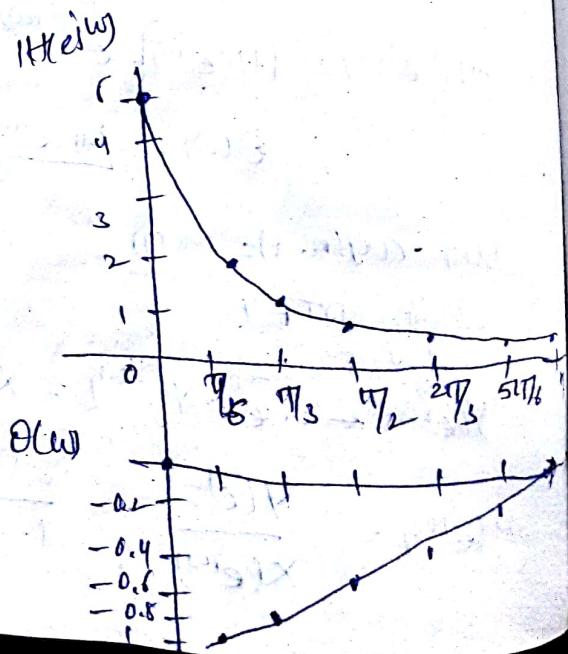
$$|H(e^{j\omega})| = \sqrt{(1 - a\cos\omega)^2 + (a\sin\omega)^2}$$

$$= \frac{1}{\sqrt{1 + a^2 - 2a\cos\omega}}$$

let $a = 0.8$

$$\theta(\omega) = -\tan^{-1}\left(\frac{a\sin\omega}{1 - a\cos\omega}\right)$$

ω	0	$\pi/6$	$\pi/3$	$\pi/2$	$2\pi/3$	$5\pi/6$	π
$ H(e^{j\omega}) $	1	1.98	1.09	0.78	0.64	0.52	0.5
$\angle H(e^{j\omega})$	0	-0.9	-0.8	-0.6	-0.45	-0.25	0



→ find the fr
 $y(n) = -$

sol: $y(0) = -$

$H(e^{j\omega})$

$H(e^{j\omega})$

$H(e^{j\omega})$

find the frequency response of

$$y(n) = \frac{1}{2} a(n) + \frac{1}{2} a(n-2)$$

$$\text{DFT: } Y(e^{j\omega}) = \frac{1}{2} X(e^{j\omega}) + \frac{1}{2} e^{-j2\omega} \cdot X(e^{j\omega})$$

$$H(e^{j\omega}) = \frac{1}{2} + \frac{1}{2} \cdot e^{-j2\omega}$$

$$= \frac{1 + e^{-j2\omega}}{2}$$

$$\begin{aligned} & \text{Factor out } e^{-j2\omega} \\ & H(e^{j\omega}) = e^{-j2\omega} \left(\frac{1}{2} + \frac{1}{2} e^{j2\omega} \right) \end{aligned}$$

$$\begin{aligned} & \frac{1}{2} + \frac{1}{2} e^{j2\omega} \\ & = \frac{1}{2} + \frac{1}{2} (\cos 2\omega + j \sin 2\omega) \\ & = \frac{1}{2} + \frac{1}{2} \cos 2\omega + j \frac{1}{2} \sin 2\omega \\ & = \frac{1}{2} \left(1 + \cos 2\omega \right) + j \frac{1}{2} \sin 2\omega \end{aligned}$$

$$H(e^{j\omega}) = \frac{1 + \cos 2\omega - j \sin 2\omega}{2}$$

$$|H(e^{j\omega})| = \sqrt{(1 + \cos 2\omega)^2 + (\sin 2\omega)^2}$$

$$= \frac{1}{2} \sqrt{1 + \cos^2 2\omega + 2 \cos 2\omega + \sin^2 2\omega}$$

$$= \frac{1}{2} \sqrt{2(1 + \cos 2\omega)}$$

$$= \frac{1}{2} \sqrt{2 \cdot 2 \cos^2 \omega}$$

$$= \frac{\sqrt{2}}{2} \cos \omega$$

$$= \cos \omega$$

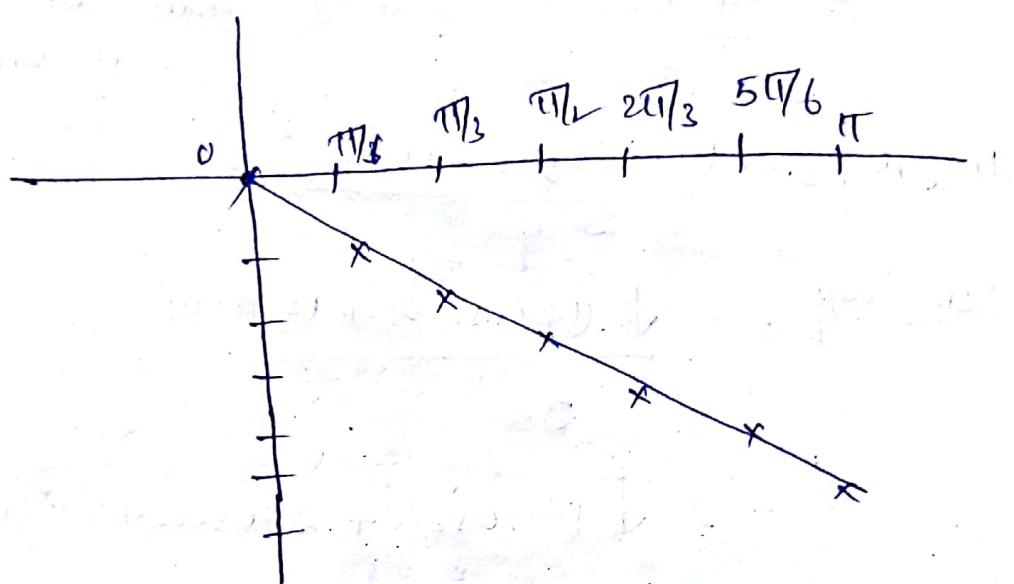
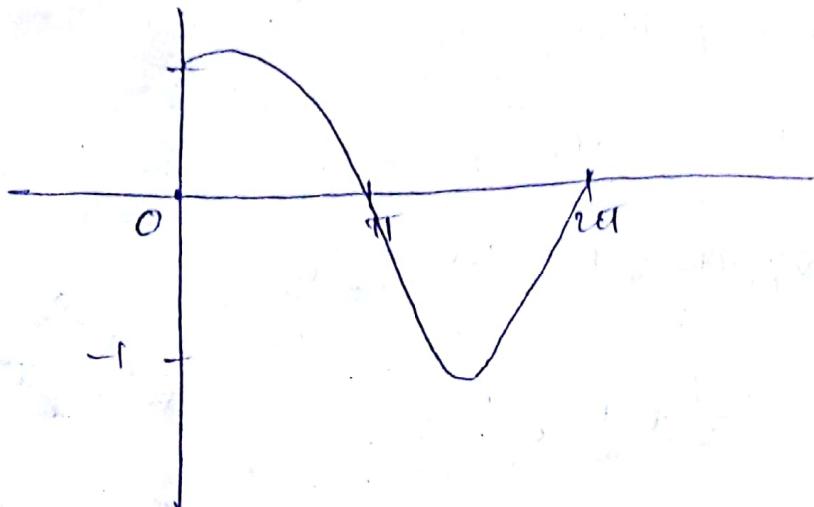
$$\theta(\omega) = \tan^{-1} \left(\frac{-\sin 2\omega}{1 + \cos 2\omega} \right)$$

$$\begin{aligned} & \tan^{-1} \left(\frac{-\sin 2\omega}{1 + \cos 2\omega} \right) \\ & = \tan^{-1} \left(\frac{-2 \sin \omega \cos \omega}{2 \cos^2 \omega} \right) \end{aligned}$$

$$\begin{aligned} & \frac{3.14}{2} \\ & = 1.57 \end{aligned}$$

$$= \tan^{-1} \left(\frac{-2 \sin \omega \cos \omega}{2 \cos^2 \omega} \right)$$

$$= \tan^{-1}(-\tan \omega) = -\omega$$



$$\rightarrow y(n) - h(n) = \frac{1}{2} \delta(n) + \delta(n-1) + \frac{1}{2} \delta(n-2)$$

$$\rightarrow y(n) - \frac{3}{4} y(n-1) + \frac{1}{4} y(n-2) = \alpha(n) - \alpha(n-1)$$

$$\rightarrow h(n) = \frac{1}{2} \left(\left(\frac{1}{2}\right)^n + \left(-\frac{1}{4}\right)^n \right) u(n), \quad$$

$$\rightarrow h(n) = \left(-\frac{1}{4}\right) \delta(n+1) + \frac{1}{2} \delta(n) + \cancel{\left(-\frac{1}{4}\right)} \delta(n-1) - \frac{1}{2} \delta(n-2)$$

a) Is it stable b) Causal or not

c) Free response

$$\begin{aligned}
 \rightarrow h(n) &= \frac{1}{2} \delta(n) + \delta(n-1) + \frac{1}{2} \delta(n-2) \\
 H(e^{j\omega}) &= \frac{1}{2} + e^{j\omega} + \frac{1}{2} e^{-j2\omega} \\
 &= \frac{1}{2} + \cos\omega - j\sin\omega + \frac{1}{2} (\cos 2\omega - j\sin 2\omega) \\
 &= \frac{1}{2} + \cos\omega + \frac{1}{2} \cos 2\omega - j(\sin\omega + \frac{1}{2} \sin 2\omega) \\
 &= \frac{1}{2} [1 + \cos 2\omega] + \cos\omega - j(\sin\omega + \frac{1}{2} \sin 2\omega \cos\omega) \\
 &= \frac{1}{2} (\cos^2\omega) + \cos\omega - j(\sin\omega + \sin\omega \cos\omega) \\
 &= \cos\omega(\cos\omega + 1) - j\sin\omega(1 + \cos\omega) \\
 &= \cos\omega \cdot \cos\omega_2 - j\sin\omega \cos\omega_2 \\
 &= \cos\omega_2 (\cos\omega - j\sin\omega) \quad \begin{matrix} a+jb \\ \sqrt{a^2+b^2} \end{matrix} \\
 |H(e^{j\omega})| &= \cos\omega_2 \cdot \sqrt{\cos^2\omega + \sin^2\omega} \\
 &= \cos\omega_2 \quad \begin{matrix} w=0 \\ w=\pi/4 \\ w=\pi/2 \\ w=3\pi/4 \\ w=\pi \end{matrix} \\
 \angle H(e^{j\omega}) &= \tan^{-1}\left(\frac{-\sin\omega}{\cos\omega}\right) \\
 &= -\frac{\omega}{2} \quad \begin{matrix} w=0 \\ w=\pi/4 \\ w=\pi/2 \\ w=3\pi/4 \\ w=\pi \end{matrix} \\
 \omega & 0 \quad \frac{\pi}{8} \quad \frac{\pi}{3} \quad \frac{\pi}{2} \quad \frac{2\pi}{3} \quad \frac{5\pi}{8} \quad \pi \\
 |H(e^{j\omega})| & 2 \quad 1.86 \quad 1.5 \quad \text{at } \sum h(n) \\
 \angle H(e^{j\omega}) & 0 \quad 0.52 \quad 1.04 \quad 0 \quad -1.04 \quad -0.52 \quad 0
 \end{aligned}$$

$$y(n) - \frac{3}{4} y(n-1) + \frac{1}{8} y(n-2) = x(n) - 3x(n-1)$$

$$Y(e^{j\omega}) - \frac{3}{4} e^{j\omega} Y(e^{j\omega}) + \frac{1}{8} e^{j2\omega} Y(e^{j\omega}) = X(e^{j\omega}) - 3X(e^{j\omega})$$

$$\frac{Y(e^{j\omega})}{X(e^{j\omega})} = \frac{1 - e^{j\omega}}{1 - \frac{3}{4} e^{j\omega} + \frac{1}{8} e^{j2\omega}}$$

$$\text{but } e^{j\omega} = z$$

$$H(z) = \frac{1 - \bar{z}}{1 - \frac{3}{4} z^1 + \frac{1}{8} z^2}$$

$$z^1 = z$$

$$\frac{H(z)}{z} = \frac{z(1-z)}{z^1 - \frac{3}{4} z^2 + \frac{1}{8}}$$

$$= \frac{8z(z-1)}{8z^2 - 6z + 1}$$

$$= \frac{8z(z-1)}{8z^2 - 4z^2 + 2z - 1}$$

$$= \frac{8z(z-1)}{(2z-1)(4z-1)}$$

$$H(z) = \frac{8z(z-1)}{(2z-1)(4z-1)} - ((2z-1)$$

$$\frac{H(z)}{z} = \frac{8(z-1)}{(2z-1)(4z-1)}$$

$$= \frac{z-1}{(z-\frac{1}{2})(z-\frac{1}{4})}$$

$$z = \frac{A}{z-\frac{1}{2}} + \frac{B}{z-\frac{1}{4}}$$

$$z-1 = A(z-\frac{1}{4}) + B(z-\frac{1}{2})$$

~~$$z=\frac{1}{4} \Rightarrow -3 = B(-\frac{1}{4}) \Rightarrow B=3$$~~

~~$$z=\frac{1}{2}, -\frac{1}{2} = A(\frac{1}{4}) \Rightarrow A=-2$$~~

$$\frac{H(z)}{z} = \frac{-2}{z-\frac{1}{2}} + \frac{3}{z-\frac{1}{4}}$$

$$H(z) = \frac{-2}{1-\frac{1}{2}z^{-1}} + \frac{3}{1-\frac{1}{4}z^{-1}}$$

$$H(e^{jw}) = \frac{-2}{1-\frac{1}{2}e^{-jw}} + \frac{3}{1-\frac{1}{4}e^{-jw}}$$

$$|H(e^{jw})| = \sqrt{\phi_1^2 + \phi_2^2}$$

~~$$= \sqrt{\tan^{-1} \frac{\frac{1}{2}\sin w}{1+\frac{1}{2}\cos w} + \tan^{-1} \frac{\frac{3}{4}\sin w}{1+\frac{1}{4}\cos w}}$$~~

$$|H(e^{jw})| = \sqrt{\frac{4}{\sqrt{\left(1-\frac{1}{2}\cos w\right)^2 + \sin^2 w}}} + \sqrt{\frac{9}{\sqrt{\left(1-\frac{1}{4}\cos w\right)^2 + \sin^2 w}}}$$

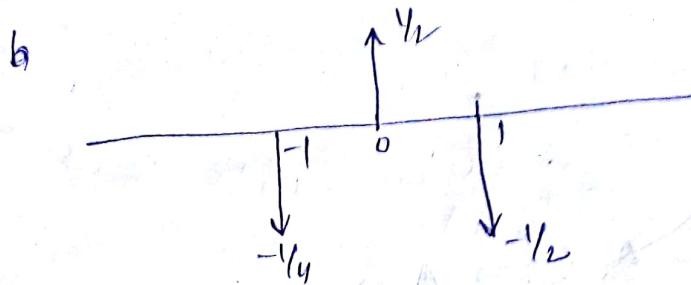
$$\angle H(e^{jw}) = -\tan^{-1} \frac{\frac{1}{2}\sin w}{1-\frac{1}{2}\cos w} - \tan^{-1} \frac{\frac{3}{4}\sin w}{1-\frac{1}{4}\cos w}$$

plotted with in notes

$$\rightarrow h(n) = -\frac{1}{4} \delta(n+1) + \frac{1}{2} \delta(n) + \frac{1}{2} \delta(n-1)$$

$$H(z) \stackrel{\text{def}}{=} \sum_{n=-\infty}^{\infty} h(n) z^{-n} = -\frac{1}{4}z^{-1} + \frac{1}{2} + \frac{1}{2}z$$

- Absolutely summable, so, stable.



$h(n) \neq 0$ for $n < 0$ so, non causal

$$H(e^{j\omega}) = -\frac{1}{4} e^{j\omega} + \frac{1}{2} + \frac{1}{2} \bar{e}^{j\omega}$$

$$= \frac{1}{2} - \frac{1}{2} \cos \omega + j \frac{1}{2} \sin \omega - \frac{1}{4} (\cos \omega + j \frac{1}{2} \sin \omega)$$

$$= \frac{1}{2} \left(1 - \cos \omega \right) + j \frac{1}{2} \sin \omega$$

$$= \left(\frac{1}{2} - \frac{1}{2} \cos \omega - \frac{1}{4} \cos \omega \right) + j \left(\frac{1}{2} \sin \omega + \frac{1}{4} \sin \omega \right)$$

$$= \left(\frac{1}{2} - \frac{3}{4} \cos \omega \right) + j \left(\frac{1}{4} \sin \omega \right)$$

$$|H(e^{j\omega})| = \sqrt{\left(\frac{1}{2} - \frac{3}{4} \cos \omega \right)^2 + \left(\frac{1}{4} \sin \omega \right)^2}$$

$$\angle H(e^{j\omega}) = \tan^{-1} \left(\frac{\frac{1}{4} \sin \omega}{\frac{1}{2} - \frac{3}{4} \cos \omega} \right)$$

~~(14)~~

ω	$ H(e^{j\omega}) $
0°	1.0
30	0.4568
60	1.216
90	0.865
120	0.1825
150	0.180
180	0.96

$\angle H(e^{j\omega})$

0°

-0.57

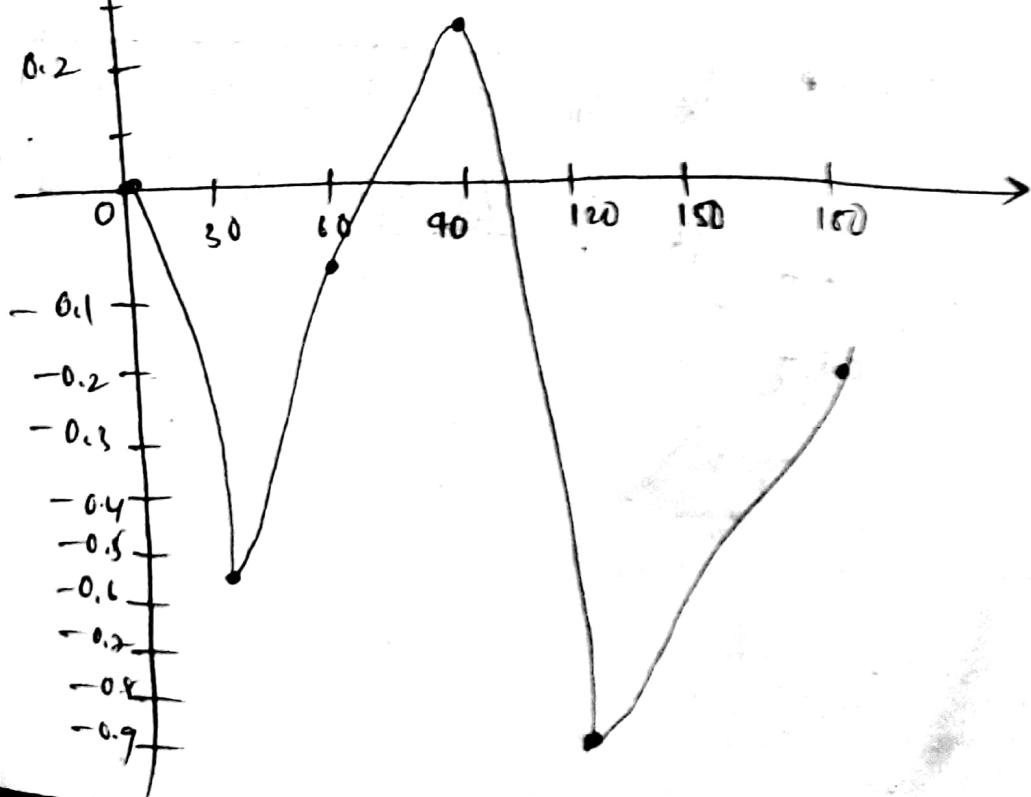
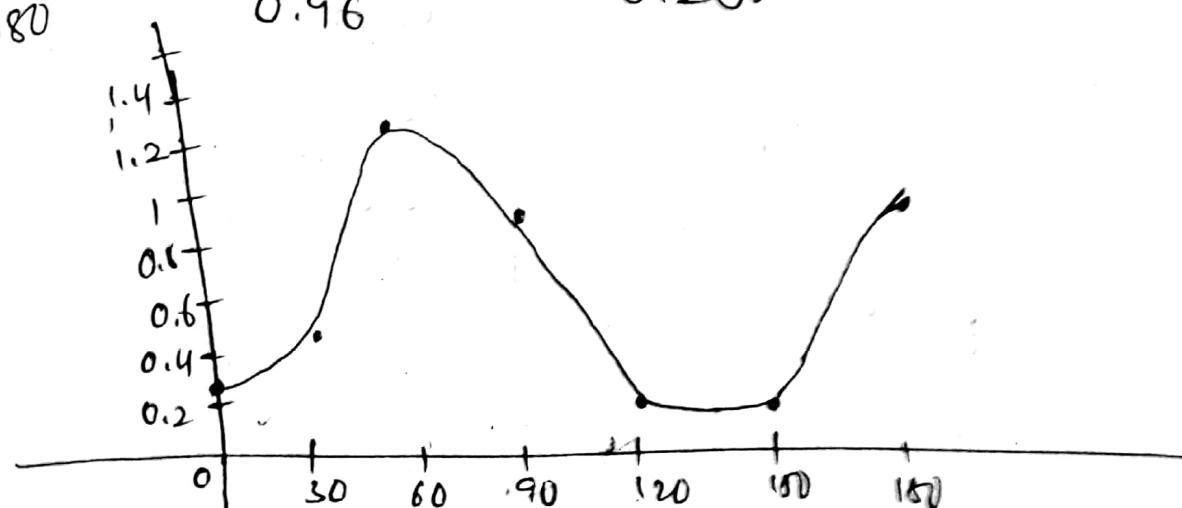
-0.0626

0.26

-0.919

1.43

-0.208



$$y(n) - \frac{3}{4}y(n-1) + \frac{1}{8}y(n-2) = a(n) - a(n-1)$$

w

$|H(e^{jw})|$

$\angle H(e^{jw})$

0

0

0

$\pi/6$

1.05

0.73

$\pi/3$

1.28

0.21

$\pi/2$

1.22

0.076

$2\pi/3$

1.14

0

$5\pi/6$

1.08

-0.013

π

1.06

0

$7\pi/6$

1.08

0.013

$|H(e^{jw})|$

1.6
1.5
1.4
1.3
1.2
1.1
1.0

0
0.1
0.2
0.3
0.4
0.5
0.6
0.7
0.8
0.9
1.0
1.1
1.2
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1.6

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1.0
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1.2
1.3
1.4
1.5
1.6

$$\frac{(m_1 \sin \theta + m_2 \cos \theta) + (m_1 \cos \theta - m_2 \sin \theta)}{(1 - \frac{m_1}{m_2} \cos \theta - \frac{m_2}{m_1} \sin \theta)} = \frac{(m_1 \sin \theta) + (m_2 \cos \theta - 1)}{(1 - \frac{m_1}{m_2} \sin \theta - \frac{m_2}{m_1} \cos \theta)}$$

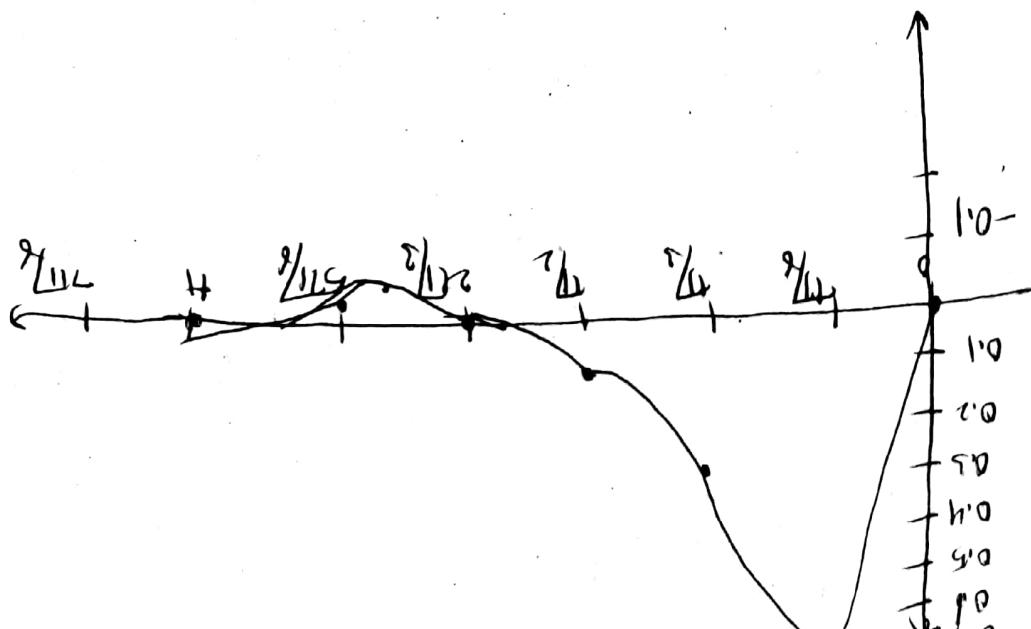
$$\left[\frac{m_1 \left(\frac{\partial}{\partial t} - \frac{\partial}{\partial x} \right) - m_2 \left(\frac{\partial}{\partial t} - \frac{\partial}{\partial x} \right) + 1}{m_1 \left(\frac{\partial}{\partial t} - 1 + \frac{\partial}{\partial x} \right) + m_2 \left(\frac{\partial}{\partial t} + 1 \right)} \right] \frac{\partial}{\partial t} =$$

$$\left[\frac{\left(m_1 \left(\frac{\partial}{\partial t} + 1 \right) \right) \left(m_2 \left(\frac{\partial}{\partial t} - 1 \right) \right)}{m_1 \left(\frac{\partial}{\partial t} - 1 + \frac{\partial}{\partial x} \right) + m_2 \left(\frac{\partial}{\partial t} + 1 \right)} \right] \frac{\partial}{\partial t} =$$

$$\left(\frac{m_1 \left(\frac{\partial}{\partial t} + 1 \right)}{1} + \frac{m_2 \left(\frac{\partial}{\partial t} - 1 \right)}{1} \right) \frac{\partial}{\partial t} = h_1 \partial_t u$$

$$(u(n)_{,t})_{,t} + u(n)_{,x} \left(\frac{\partial}{\partial t} \right)_x u(n) =$$

$$(u(n)_{,t})_{,t} + \left(\frac{\partial}{\partial t} \right)_x u(n) = h_1 u$$



$$\theta = \tan^{-1} \left(\frac{1/4 \sin \omega}{1 - 1/4 \cos \omega} \right) - \tan^{-1} \left(\frac{\frac{1}{2} \sin \omega + 1/8 \sin \omega}{1 - 1/2 \cos \omega - 1/4 \cos \omega} \right)$$

$$y(n) = e^{jn\theta} y_G$$

w	$H(e^{jw})$	θ
0	1.20	0
$\pi/6$	0.98	-0.45
$\pi/3$	0.83	-0.34
$\pi/2$	0.83	-0.17
$2\pi/3$	0.92	-0.052
$5\pi/6$	1.05	-6.6×10^{-4}
π	1.11	0

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Steady state & Transient response of a system:-

$a(n) = e^{jwn}$ (Causal signals are those which extends from $-\infty$ to ∞)

$$y(n) = e^{jwn} H(e^{jwn})$$

$$= \sum_{n=-\infty}^{\infty} h(k) a(n-k)$$

$$y(n) = a(n-1) + a(n)$$

$$y(n) = a^{n+1} y_G + \sum_{k=0}^n a^k x(n-k)$$

$$y(n) = a^{n+1} y_G + \sum_{k=0}^n a^k e^{j\omega(n-k)}$$

$$H(n) = a^{n+1} y_G + e^{jn\omega} \sum_{k=0}^n (a e^{j\omega})^k$$

$$= a^{n+1} y(-1) + \frac{e^{jn\omega} (1 - a^n + H e^{j\omega(n+1)})}{1 - a e^{j\omega}}$$

$$y(n) = a^{n+1} y(0) - e^{j\omega n} \left(\frac{d^n e^{-j\omega n}}{1 - a e^{j\omega n}} \right) + \frac{e^{j\omega n}}{1 - a e^{j\omega n}} H(e^{j\omega n})$$

Transient response Steady state

$$(\because Y(e^{j\omega}) = a e^{j\omega n} Y(e^{j\omega}) + x(e^{j\omega}), H(e^{j\omega}) = \frac{1}{1 - a e^{j\omega}})$$

Phase delay, Group delay

When \mathcal{Y}_p is sinusoidal, $x(n) = A \sin(\omega n)$ $-\infty < n < \infty$

$$\begin{aligned} x(n) &= \frac{A}{2j} [e^{j\omega n} - e^{-j\omega n}] \\ &= \frac{1}{2j} [A e^{j\omega n} |H(e^{j\omega})| e^{j\theta(\omega)} - A e^{-j\omega n} |H(e^{j\omega})| e^{j\theta(\omega)}] \\ &= \frac{1}{2j} A |H(e^{j\omega})| [e^{j\omega n} e^{j\theta(\omega)} - e^{-j\omega n} e^{j\theta(\omega)}] \\ &= \frac{A |H(e^{j\omega})|}{2j} [e^{j(\omega n + \theta(\omega))} - e^{j(-\omega n + \theta(\omega))}] \end{aligned}$$

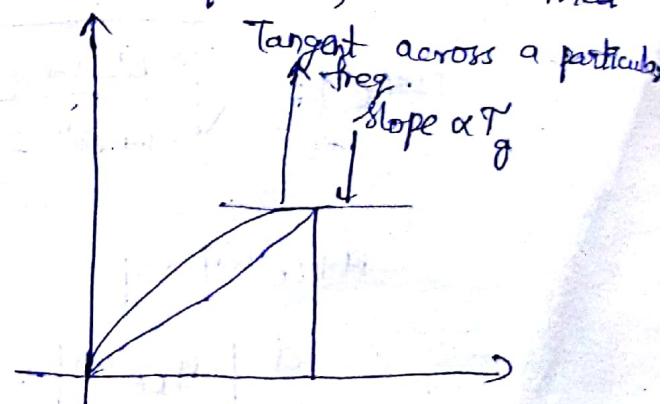
$$y(n) = A |H(e^{j\omega})| \sin(\omega n + \theta(\omega))$$

$$y(n) = A |H(e^{j\omega})| \sin(\omega(n + \frac{\theta(\omega)}{\omega}))$$

When \mathcal{Y}_p is sinusoidal signal, \mathcal{Y}_p is also sinusoidal signal multiplied with a factor of magnitude $|H(e^{j\omega})|$ & delay is defined as phase delay $\phi(\omega)$. This delay plays an important role when it is passed through filter, so it is referred as phase delay. When the \mathcal{Y}_p consists of more than one harmonics of sine, it is defined as group delay.

$$T_p = \frac{-\theta(\omega)}{\omega}$$

$$T_g = \frac{-d\theta(\omega)}{d\omega}$$



Problem

→ The causal LTI system is described by D.E
 $y(n) - a y(n-1) = b \sigma(n) + \sigma(n-1)$ where a is real &
 in magnitude. find the value of b condition $a \neq b$
 such that freq. response satisfies the condition

$$|H(e^{j\omega})| = 1, \forall \omega$$

Sol:

$$y(n) - a y(n-1) = b \sigma(n) + \sigma(n-1)$$

$$Y(e^{j\omega}) [1 - a e^{-j\omega}] = b \sigma(e^{j\omega}) + \sigma(e^{j\omega})$$

$$H(e^{j\omega}) = \frac{b + e^{j\omega}}{1 - a e^{-j\omega}}$$

$$H(e^{j\omega}) = \frac{(b + \cos \omega) - j \sin \omega}{1 - a \cos \omega + j \sin \omega}$$

$$(b + \cos \omega)^2 + \sin^2 \omega = (1 - a \cos \omega)^2 + \sin^2 \omega$$

$$b + \cos \omega = 1 - a \cos \omega$$

$$(1+a) \cos \omega = 1 - b$$

$$\cos \omega = \frac{1-b}{1+a}$$

$$|H(e^{j\omega})| = \sqrt{\frac{b^2 + 1 + 2b \cos \omega}{1 + a^2 - 2a \cos \omega}}$$

$$|H(e^{j\omega})| = 1$$

$$\frac{d}{d\omega} |H(e^{j\omega})| = 0$$

$$\frac{d}{d\omega} |H(e^{j\omega})|$$

$$\frac{d}{d\omega} |H(e^{j\omega})|$$

$$(1+a^2)$$

$$-2b \sin \omega$$

$$-2a \sin \omega$$

→ The freq.

find ω_n

ω_n

$$\frac{d}{d\omega} |1 + \tau e^{j\omega}|^2 = 0$$

$$\frac{d}{d\omega} \left(\frac{b'' + 1 + 2b(\cos\omega)}{1 + \alpha'' - 2\alpha(\cos\omega)} \right) = 0$$

$$\frac{-2a(-\sin\omega) - \cancel{(1 + \alpha'' - 2\alpha(\cos\omega))}}{(1 + \alpha'' - 2\alpha(\cos\omega))''}$$

$$(1 + \alpha'' - 2\alpha(\cos\omega))'' [-2b(\sin\omega)] - (1 + b'' + 2b(\cos\omega)) (2\alpha \sin\omega) = 0$$

$$-2b\sin\omega - 2\alpha''b\sin\omega + 4\alpha b\cos\omega \sin\omega - 2\alpha \sin\omega - 2\alpha b''\sin\omega$$

→ 4 absinomega ~ 0

$$-2\alpha b\sin\omega (\alpha + b) - 2\sin\omega (\alpha + b) \approx 0$$

$$(\alpha + b)(2\alpha b\sin\omega + 2\sin\omega (\alpha + b)) \approx 0$$

$$2\sin\omega (\alpha + b)(\alpha b + 1) = 0$$

$$b = -4\alpha$$

→ The free domain representation of R/p $\mathcal{X}(e^{j\omega}) = j(-\cancel{\alpha}_{\leq 0})$
 find $\mathcal{X}(n)$,
 $\rightarrow j (0 \leq \omega \leq \pi)$

$$\mathcal{X}(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} \mathcal{X}(e^{j\omega}) \cdot e^{-jn\omega} d\omega$$

$$= \frac{1}{2\pi} \int_0^\pi e^{jn\omega} d\omega + \int_\pi^\pi e^{jn\omega} d\omega$$

→ find the res

$$y(n) = \frac{1}{2}$$

$$x(n) = 3$$

sol: $y(n) =$

$$y(n) =$$

$$y(e^{j\omega})$$

H(e

$$= \frac{1}{2\pi} \left[j \left(\frac{e^{j\omega n}}{jn} \right)_0 - j \left(\frac{e^{j\omega n}}{jn} \right)_0^n \right]$$

$$= \frac{1}{2\pi} \left[j \left(\frac{1 - e^{-jn}}{n} \right) - \left(\frac{(-1)^n - 1}{n} \right) \right]$$

$$= \frac{1}{2\pi} \left[\cancel{j} \left(\frac{1 - e^{-jn}}{n} \right) + \cancel{j} e^{\cancel{j\omega n}} \right]$$

$$= \cancel{\frac{j}{2\pi}}$$

$$= \frac{1}{2\pi} \left[\frac{1 - e^{-jn}}{n} - \frac{e^{jn} - 1}{n} \right]$$

$$= \frac{1}{2\pi} \left[\frac{1 - e^{-jn} - e^{jn} + 1}{n} \right]$$

$$= \frac{1}{2\pi} \left[\frac{2 - 2 \cos(j\omega n)}{n} \right]$$

$$= \frac{1 - \cos(j\omega n)}{\pi n} = \left(\frac{2 \sin^2(\pi n/2)}{\pi n} \right)$$

$$= \left(\frac{\sin^2(\pi n/2)}{\pi n/2} \right)$$

H(e

f(e

$$= e^{j\omega t}$$

$$= \text{Tran} \left(\frac{1 - e^{j\omega t}}{\sin \frac{\omega t}{2}} \right)$$

$$= \text{Tran} = m \int_{-\infty}^{\infty} (m_1 e^{j\omega t}) dt$$

$$\text{Tran} = \overline{(B(w))} \quad 0 = 0 = m \int_{-\infty}^{\infty} (m_1 e^{j\omega t}) dt$$

$$0 = \overline{e^{j\omega t}} =$$

$$(m_1 e^{j\omega t}) = \overline{B(w)} - \overline{\frac{1 - e^{j\omega t}}{\sin \frac{\omega t}{2}}} = \overline{(B(w))}$$

$$\tan(\frac{\pi}{2} - \theta) = \cot \theta = \overline{\sin w} = |H(e^{j\omega t})|$$

$$H(e^{j\omega t}) = \sin w (\sin w + j \cos w)$$

$$= \overline{\sin w + j \sin w \cos w}$$

$$= \overline{1 - (\cos w + j \sin w \cos w)}$$

$$H(e^{j\omega t}) = \overline{1 - e^{-j\omega t}} = |H(e^{j\omega t})|$$

$$|H(e^{j\omega t})| = \frac{1}{2} [X(e^{j\omega t}) - X(e^{-j\omega t})] = |H(j\omega)|$$

$$|H(j\omega)| = \frac{1}{2} [\alpha(n) - \alpha(-n)]$$

$$y(n) = A \cdot H(e^{j\omega n}) \int_{-\infty}^{\infty} \sin(wn + \theta(w)) dw$$

$$x(n) = \sum_{k=-\infty}^{\infty} h(k) e^{j\omega k} \quad \text{in } -\pi \leq \omega \leq \pi$$

$$y(n) = \frac{1}{2} [x(n) - x(n-2)] \quad \text{to } H(j\omega)$$

Find the response of the system

$y(n) = 4 \times 0.866 \cdot \cos\left(\frac{\pi}{5}n + 60^\circ + 89^\circ\right)$

→ A LTI system is described by the D.E

$$y(n) = a y(n-1) + x(n) \quad \text{where } a = 0.9$$

determine the O/P of the system to the i/p

$$x(n) = 5 + \sin\left(\frac{\pi}{2}n\right) + 20 \cos(\pi n + \pi u)$$

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UNIT-II

DISCRETE FOURIER TRANSFORM

DTFT \rightarrow after performing transform on discrete signal, the result is a continuous function.

DTFT is suitable for infinite length sequence & finite length also.

DFT \rightarrow DFT can be performed on only finite length sequence and both x_p & x_{op} are of discrete time.

\rightarrow When DTFT is sampled into N finite components from 0 to 2π , DFT is obtained.

\rightarrow The op of DFT is finite, discrete & periodic.

If ' ω ' is replaced by $\frac{2\pi}{N}k$ in DTFT, it is DFT
 $k = \text{Integral multiple of fundamental frequency}$
 $N = \text{No. of samples.}$

Discrete Fourier Series

Fourier series is for periodic sequences.

\rightarrow Let the x_p sequence is $x_p(n)$ which is periodic with period of 'N' samples.

$$x_p(n) = x_p(n+N)$$

\rightarrow If any signal/sequence is periodic, it

Dis

Discrete

can be exponenti.

$$n \rightarrow 0$$

$$k \rightarrow 0$$

DPS of

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30/12/17

~~UNIT-11~~

~~Discrete Fourier Transform.~~

~~Discrete Fourier Series:-~~

can be represented by weighted sum of complex exponentials.

$n \rightarrow 0$ to $N-1$

$k \rightarrow 0$ to $N-1$

$$\text{DFS of } x_p(n) = \frac{1}{N} \sum_{k=0}^{N-1} x_p(k) e^{\frac{j2\pi kn}{N}}$$

$x_p(k) \rightarrow$ Discrete Fourier series coefficient

& $k \rightarrow 0$ to $N-1$.

To compute $x_p(k)$ multiply the whole eqn with $e^{-j\frac{2\pi}{N}mn}$ and take the summation over n is values from 0 to $N-1$.

$$\begin{aligned} \Rightarrow \sum_{n=0}^{N-1} x_p(n) e^{-j\frac{2\pi}{N}mn} &= \frac{1}{N} \sum_{n=0}^{N-1} \sum_{k=0}^{N-1} x_p(k) e^{-j\frac{2\pi}{N}nk} e^{-j\frac{2\pi}{N}mn} \\ &= \frac{1}{N} \sum_{k=0}^{N-1} x_p(k) \sum_{n=0}^{N-1} e^{-j\frac{2\pi}{N}(k-m)n} \end{aligned}$$

from above $\sum_{n=0}^{N-1} e^{j \frac{2\pi}{N} (k-m)n} = N$ for $k-m = 0, \pm N, \pm 2N, \dots$

$$\sum_{n=0}^{N-1} a_p(n) e^{-j \frac{2\pi}{N} mn} = \frac{1}{N} \sum_{k=0}^{N-1} x_p(k), \quad \text{from } k=0 \text{ to } N-1$$

$$x_p(k) = \sum_{n=0}^{N-1} a_p(n) e^{-j \frac{2\pi}{N} nk}$$

Properties:-

1) Linearity:

$$\text{DFS}[a_1 a_p(n)] = X_p(k)$$

$$\text{DFS}[a_2 a_p(n)] = X_{2p}(k)$$

$$a_1 a_p(n) + a_2 a_{2p}(n) = a_1 X_p(k) + a_2 X_{2p}(k).$$

2) Time shifting

$$\text{if } \text{DFS}[a_p(n)] = X_p(k)$$

$$\text{DFS}[a_p(n-m)] = e^{-j \frac{2\pi}{N} mk} \cdot X_p(k)$$

frequency shifting
if DFS $\{x_p(n)\} = X_p(k)$

✓ $\frac{M}{N}$
and

$$e^{j \frac{2\pi}{N} k n} x_p(n) \longleftrightarrow X_p(k-l).$$

B

Convolution:

$$\text{if DFS } \{x_{1p}(n)\} = X_{1p}(k)$$

$$\text{DFS } \{x_{2p}(n)\} = X_{2p}(k)$$

$$x_{1p}(n) * x_{2p}(n) \longleftrightarrow X_{1p}(k) \cdot X_{2p}(k),$$

$$\text{DFS} \left[\sum_{n=0}^{N-1} x_{1p}(n) \cdot x_{2p}(m-n) \right] = X_{1p}(k) \cdot X_{2p}(k).$$

03/10/18

Time aliasing due to frequency sampling

Discrete Fourier Transform:

a(10)

In DFT, both $x(n)$ & its DFT $X(k)$ a(2)

are discrete and of finite length.

When $x(n)$ is discrete (0 to $N-1 \rightarrow$ finite length)

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x(n) e^{-j\omega n}$$

↓

continuous

If the DTFT, $X(e^{j\omega})$ is sampled at 'N' distinct points equally spaced, DFT is obtained.

* (Frequency domain sampling)

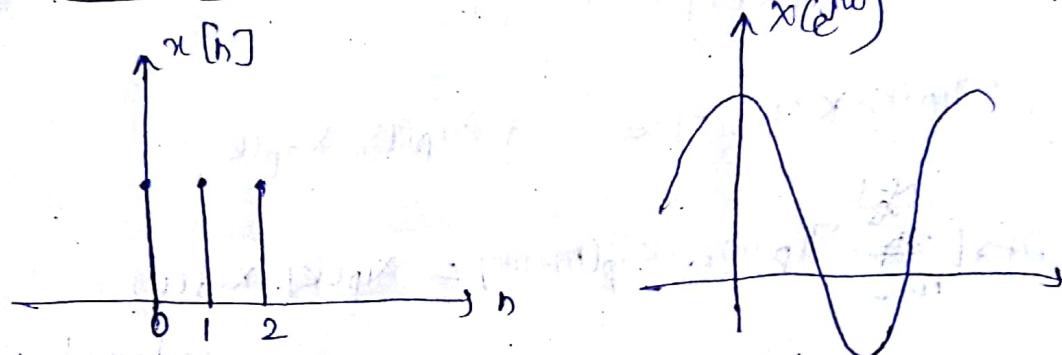
$X(e^{j\omega_k})$ is DFT $k \rightarrow 0 \text{ to } N-1$

$$\omega_k = \frac{2\pi}{N}$$

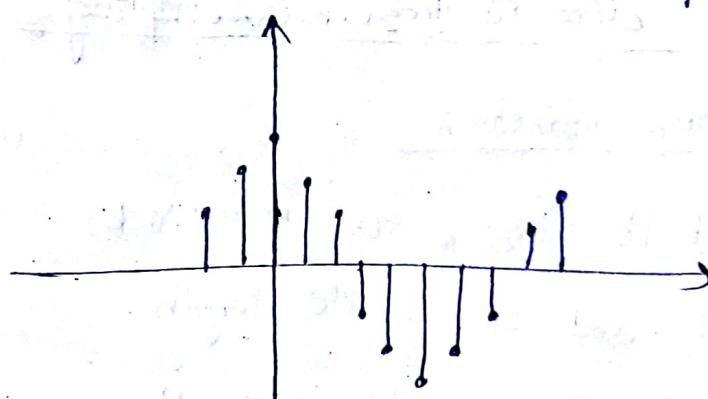
C: sampled into N samples
 → Time domain sampling leads to frequency domain aliasing

→ Frequency ω time domain aliasing

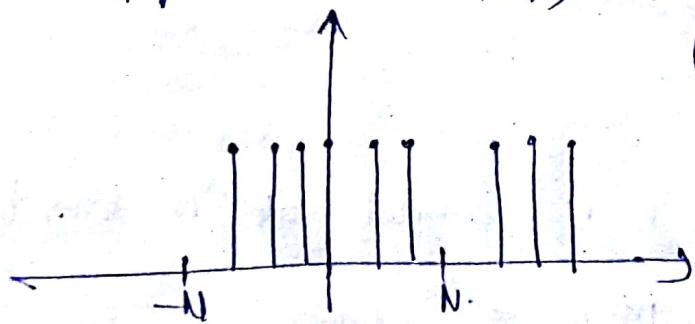
Time domain aliasing due to frequency sampling



$X(e^{j\omega})$ after frequency domain sampling



Apply DFT to $x(n)$



C: If $X(k)$ is discrete periodic in freq. domain
 $X_p(k)$ is also discrete and periodic

$N > L \rightarrow$ condition for no aliasing

$N \rightarrow$ no. of samples/length of DFT

$L \rightarrow$ sequence length

new domain
aliasing
domain
ring
sampling:

Ex: if $N=9$, $L=10$ (as above) ($N \geq L$)

then there will not any overlap

if $L=9$, $N=7$, samples will be overlapped.

→ To perform DFT or IDFT, $N \geq L$ should be satisfied

→ If $N \geq L$, $L=1$ then $(N-L)$ no. of zeros are appended

to perform DFT

$$x(n) = \begin{cases} x_p(n) & ; 0 \leq n \leq N-1 \\ 0 & ; \text{otherwise} \end{cases}$$

$$x(n) = x_p(n) \cdot w_p(n)$$

$$w_p(n) = \text{Rectangular funct} = \begin{cases} 1 & ; 0 \leq n \leq N-1 \\ 0 & ; \text{otherwise} \end{cases}$$

DFT → sampling in frequency domain

$$X(e^{j\omega_k}) = \sum_{n=0}^{N-1} x(n) e^{-j\frac{2\pi}{N} nk}$$

$$\omega_k = \frac{2\pi}{N} k$$

$$X(e^{j\frac{2\pi}{N} k}) = \sum_{n=0}^{N-1} x(n) e^{-j\frac{2\pi}{N} nk}$$

↓

$x(n)$

$k \rightarrow 0 \text{ to } N-1$

DFT

$$\text{of } x(n) \Rightarrow X(k) = \sum_{n=0}^{N-1} x(n) e^{-j\frac{2\pi}{N} nk}$$

$k \rightarrow 0 \text{ to } N-1$

\Rightarrow If $x[n]$ is periodic with period N then $X[k]$ is also periodic with period N .
 Then $X[k+N] = X[k] \forall k$

$$X[k+N] = \sum_{n=0}^{N-1} x[n] e^{-j\frac{2\pi}{N}kn}$$

$$X[k+N] = X[k] \forall k$$

then,

$$\text{DFT of } x[n] = \sum_{k=0}^{N-1} X[k] e^{-j\frac{2\pi}{N}kn}$$

$$\begin{aligned} \text{DFT of } x[n] &= X[k] = \sum_{n=0}^{N-1} x[n] e^{-j\frac{2\pi}{N}kn} \\ \text{IDFT of } X[k] &= x[n] = \sum_{k=0}^{N-1} X[k] e^{j\frac{2\pi}{N}kn} \end{aligned}$$

\rightarrow When $N > L$, zeros are added in $x[n]$ is called zero padding.

Advantages:

- Frequency resolution is increased
- To perform DCT

Twiddle factors:

Denoted by w_N

$$w_N = e^{-j\frac{2\pi}{N}}$$

$\Rightarrow x_p(n)$ is periodic with period N .
 sequence can be represented with F.S (Fourier Series).
 then IDFT $\Rightarrow x_p(n) = \frac{1}{N} \sum_{k=0}^{N-1} X_p(k) e^{\frac{j2\pi}{N} nk}$
 $n \rightarrow 0$ to $N-1$

$$X_p(k) = \begin{cases} x_p(n) & ; 0 \leq n \leq N-1 \\ 0 & ; \text{otherwise} \end{cases}$$

$$X_p(k) = x_p(k) \cdot w_p(k)$$

then,

$$\text{IDFT of } x_p(n) \Rightarrow x(n) = \frac{1}{N} \sum_{k=0}^{N-1} X_p(k) e^{\frac{j2\pi}{N} nk}$$

$n \rightarrow 0$ to $N-1$

$$\text{DFT}[x(n)] = X(k) = \sum_{n=0}^{N-1} x(n) \cdot e^{-\frac{j2\pi}{N} nk}$$

$$\text{IDFT}[X(k)] = x(n) = \frac{1}{N} \sum_{k=0}^{N-1} X(k) e^{\frac{j2\pi}{N} nk}$$

\rightarrow N-point DFT

\rightarrow When $N > L$, zeros are added which is called zero padding.

Advantages:

\rightarrow Frequency resolution is increased

\rightarrow To perform DFT

Twiddle factor:

Denoted by w_N

$$w_N = e^{\frac{j2\pi}{N}}$$

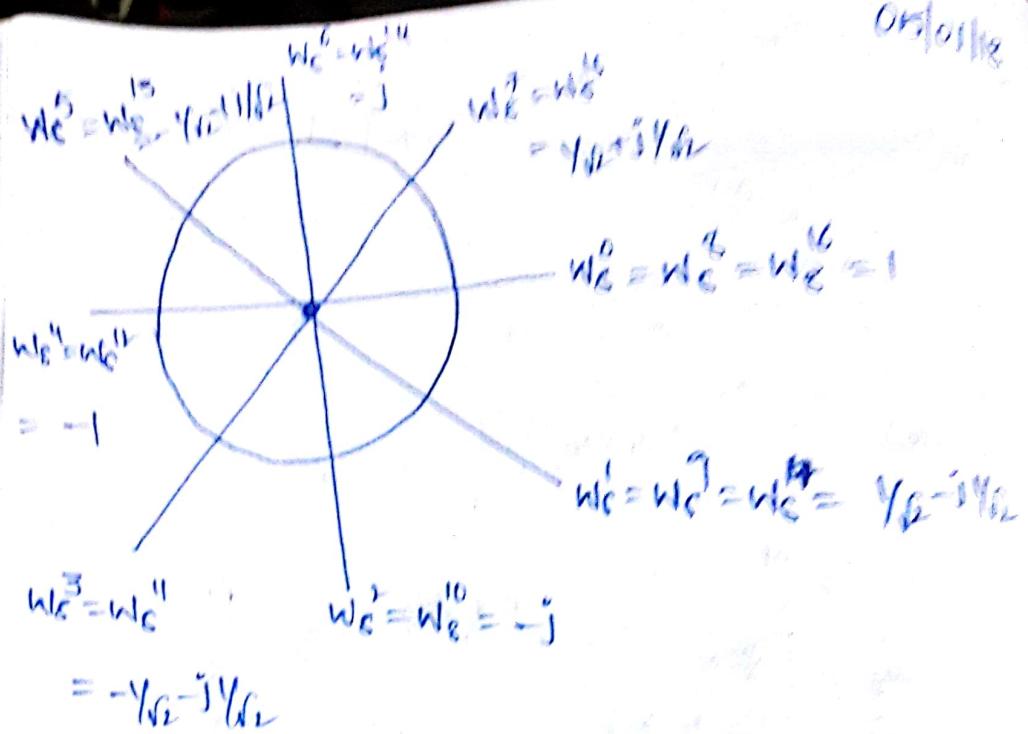
$$|W_N| = \left| e^{j \frac{2\pi}{N}} \right| = \left| \cos \frac{2\pi}{N} - j \sin \frac{2\pi}{N} \right| = 1$$

$$\angle W_N^{nk} = \frac{-2\pi}{N}(nk)$$

$$\Rightarrow X(k) = \sum_{n=0}^{N-1} x(n) w_N^{nk} \rightarrow \text{DFT}$$

$$x(n) = \frac{1}{N} \sum_{k=0}^{N-1} X(k) \cdot w_N^{-nk} \rightarrow \text{IDFT}$$

$k n = r$	w_N^{nk}	magnitude	Phase
0	$w_8^0 = e^{j \frac{2\pi}{8}(0)}$	1	0
1	$w_8^1 = e^{j \frac{2\pi}{8}(1)} = \frac{1-j}{\sqrt{2}}$	1	$\pi/4$
2	$w_8^2 = e^{j \frac{2\pi}{8} \cdot 2} = e^{j \frac{\pi}{4}}$ $= j$	1	$-\pi/2$
3.	$w_8^3 = e^{j \frac{2\pi}{8}(3)}$ $= \frac{1}{\sqrt{2}} + j \frac{1}{\sqrt{2}}$	1	$-3\pi/4$
4	$w_8^4 = e^{j \frac{2\pi}{8}(4)}$	+1	π



$$e^{-j \frac{2\pi}{N} nk} = w_N^{nk}$$

Twiddle factor is periodic with period N .

$$w_N^r = w_N^{(\pm N)} = w_N^{(r \pm 2N)} = \dots$$

Twiddle is symmetric

$$w_N^r = w_N^{(r \pm N/2)}$$

* To overcome time aliasing effect $N \geq L$

So, that $N-L$ i.e. zeros to the $\%_p$ it is called zero padding.

Find the DFT of a sequence $a(n) = \{1, 1, 0, 0\}$

IDFT of $X(k) = \{1, 0, 1, 0\}$. Proceed only with distinct values

$$\begin{bmatrix} X(0) \\ X(1) \\ X(2) \\ X(3) \end{bmatrix} = \begin{bmatrix} W_N^0 & W_N^1 & W_N^2 & W_N^3 \\ W_N^1 & W_N^0 & W_N^3 & W_N^2 \\ W_N^2 & W_N^3 & W_N^0 & W_N^1 \\ W_N^3 & W_N^2 & W_N^1 & W_N^0 \end{bmatrix} \begin{bmatrix} a(0) \\ a(1) \\ a(2) \\ a(3) \end{bmatrix}$$

$$W_N^0 = W_N^1 = W_N^2 = 1$$

$$W_N^3 = \begin{bmatrix} 1 & -j\sqrt{2}/2 & -j & -j\sqrt{2}-j/\sqrt{2} \\ j\sqrt{2}/2 & 1 & -j & j \\ -j & j\sqrt{2}/2 & 1 & -j\sqrt{2}-j/\sqrt{2} \\ -j & -j & j\sqrt{2}/2 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

$$= \cancel{1 + j\sqrt{2} - j/\sqrt{2}}$$

$$X(k) = \sum_{n=0}^{N-1} a(n) e^{-j \frac{2\pi}{N} n k}$$

$$X(0) = \sum_{n=0}^3 a(n) = 1 + 1 + 0 + 0 = 2$$

$$X(1) = \sum_{n=0}^3 a(n) e^{-j \frac{2\pi}{4} n}$$

$$= 1 + 1 \cdot j\sqrt{2} - j/\sqrt{2} =$$

$$w_4^0 = e^{-j\frac{2\pi}{4} \cdot 0} = 1$$

$$w_4^1 = e^{-j\frac{2\pi}{4} \cdot 1} = -j$$

$$w_4^2 = e^{-j\frac{2\pi}{4} \cdot 2} = -1$$

$$w_4^3 = e^{-j\frac{2\pi}{4} \cdot 3} = e^{-j\frac{3\pi}{2}} = j$$

$n=4$

$$\begin{bmatrix} w_4^0 & w_4^0 & w_4^0 & w_4^0 \\ w_4^0 & w_4^1 & w_4^2 & w_4^3 \\ w_4^0 & w_4^2 & w_4^4 & w_4^6 \\ w_4^0 & w_4^3 & w_4^6 & w_4^9 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

$$= 1+1 = 2$$

$$\begin{bmatrix} 2 \\ 1-j \\ 0 \\ 1+j \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix}$$

$$a + b + c + d = 1 \quad 2a + 2b = 1$$

$$a - b - c + d = 0 \quad a + b = 1$$

$$(a - c) - j(b - d) = 0 \quad a + b = 0.5$$

$$a = c, \quad b = d$$

$$a - b + c - d = 1$$

$$a - b = 0.5$$

$$2a = 1$$

$$a = 0.5 \quad b = 0$$

*find the DFT of a sequence $x(n) = 1 \quad 0 \leq n \leq 2$
 $= 0 \quad \text{otherwise}$

$\Rightarrow N=4, \quad \text{i)} \quad N=8$

Plot $|X(k)|$ & $\angle X(k)$ & comment on result

$$X(k) = \sum_{n=0}^{N-1} x(n) e^{-j\frac{2\pi}{N}kn}$$

$$= \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 4 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

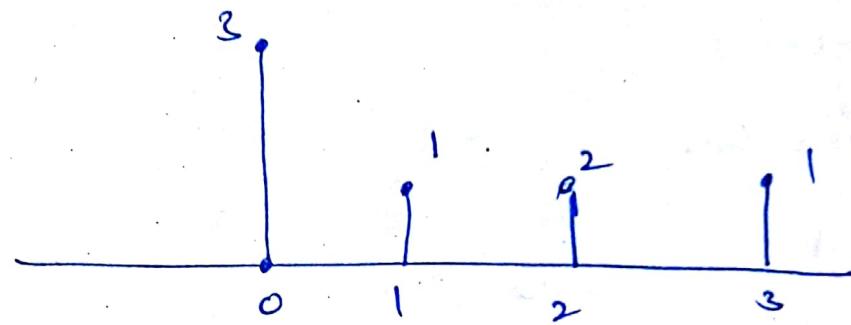
$$= \begin{pmatrix} 3 \\ j \\ 1 \\ j \end{pmatrix}$$

$$x(0) = 3, \quad x(1) = j, \quad x(2) = 1, \quad x(3) = j$$

$$|x(0)| = 3, \quad |x(1)| = 1, \quad |x(2)| = 1, \quad |x(3)| = 1$$

$$\angle x(0) = 0, \quad \angle x(1) = -\pi/2, \quad \angle x(2) = 0, \quad \angle x(3) = \pi$$

X_1



$\pi/4$

0

$-\pi/2$

0	w_8^0	w_8^0	w_8^0	w_8^0
1	w_8^1	w_8^1	w_8^1	w_8^1
2	w_8^2	w_8^2	w_8^2	w_8^2
3	w_8^3	w_8^3	w_8^3	w_8^3
4	w_8^4	w_8^4	w_8^4	w_8^4
5	w_8^5	w_8^5	w_8^5	w_8^5

$$\begin{bmatrix} w_6^0 & w_6^0 & w_6^0 & w_6^0 & w_6^0 & w_6^0 & w_6^0 \\ w_6^0 & w_6^1 & w_6^2 & w_6^3 & w_6^4 & w_6^5 & w_6^6 \\ w_6^1 & w_6^2 & w_6^4 & w_6^6 & w_6^{10} & w_6^{12} & w_6^8 \\ w_6^2 & w_6^3 & w_6^6 & w_6^9 & w_6^{12} & w_6^{15} & w_6^{11} \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & Y_{L2} + Y_L & -j & & & & & \\ 1 & & & & & & & \\ 1 & & & & & & & \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$1 + Y_{L2} - Y_L - j$$

06/01/17. find the D.F.T of

$$a(n) = \cos \frac{2\pi r n}{N} \quad 0 \leq r \leq N-1.$$

Sol: $x(k) = \sum_{n=0}^{N-1} a(n) e^{-j \frac{2\pi}{N} nk}$

$$x(k) = \sum_{n=0}^{N-1} \cos \frac{2\pi r n}{N} \cdot \left(e^{j \frac{2\pi r n}{N}} + e^{-j \frac{2\pi r n}{N}} \right) \cdot e^{-j \frac{2\pi k n}{N}}$$

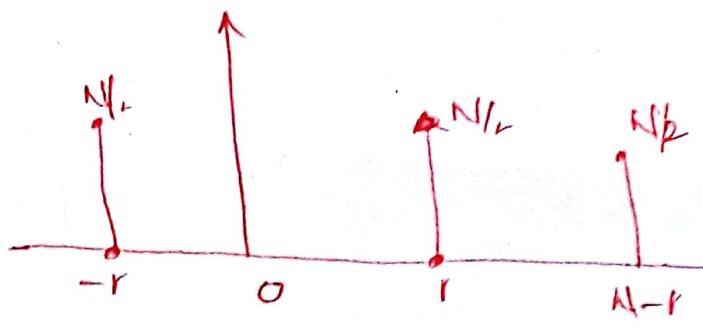
$$x(k) = \sum_{n=0}^{N-1} e^{-j \frac{2\pi}{N} (k-r)n} + e^{-j \frac{2\pi}{N} (r+k)n}$$

$$x(k) = \sum_{n=0}^{N-1} \frac{1}{2} [w_N^{rn} + w_N^{rn}] w_N^{nk}$$

$$= \sum_{n=0}^{N-1} \frac{1}{2} [w_N^{(k-r)n} + w_N^{(r+k)n}]$$

$$\begin{array}{lll} N & \text{if } k=r & N \text{ if } k=-r \\ 0 & \text{ow} & 0 \text{ ow} \end{array} \quad (-r \text{ mean } N-r)$$

$$x(k) = \begin{cases} N/2 & \text{if } k=r \\ N/2 & \text{if } k=-r \\ 0 & \text{ow} \end{cases}$$



Relationship of DFT to Other Transforms:-

$$\text{D} \quad X(k) = x(e^{j\omega}) \Big|_{\omega = \frac{2\pi}{N} k}$$

(i) Relation b/w DFT & Z transform

$$\begin{aligned}
 X(z) &= \sum_{n=-\infty}^{\infty} x(n) z^{-n} \\
 &= \sum_{n=-\infty}^{\infty} \frac{1}{N} \sum_{k=0}^{N-1} X(k) e^{\frac{j2\pi}{N} nk} z^{-n} \\
 &= \frac{1}{N} \sum_{k=0}^{N-1} X(k) \sum_{n=-\infty}^{\infty} \left[e^{\frac{j2\pi}{N} nk} \cdot z^{-n} \right] \\
 &= \frac{1}{N} \sum_{k=0}^{N-1} X(k) \cdot \frac{1 - z^{-N}}{1 - e^{\frac{j2\pi}{N} k} z^{-1}} \\
 &= \left(\frac{1 - z^{-N}}{1 - e^{\frac{j2\pi}{N} k} z^{-1}} \right) \cdot \frac{1}{N} \cdot \sum_{k=0}^{N-1} X(k) \\
 X(z) &= \frac{1 - z^{-N}}{N} \sum_{k=0}^{N-1} \frac{X(k)}{1 - e^{\frac{j2\pi}{N} k} z^{-1}}
 \end{aligned}$$

$$x(k) = 2$$

* Find the Z transform of the sequence

$a(n) = u(n) - u(n-8)$ of sampling at 6 points

On the unit circle using the relation

$$X(k) = X(z) \Big|_{z=e^{j\frac{2\pi k}{3}}}$$

$$a(n) = \{1, 1, 1, 1, 1, 1, 1\}$$

$$X(z) = \frac{1}{1-z} - \cancel{\frac{1}{1-z} \cdot \frac{1}{z^8}}$$

$$X(k) = \frac{1}{1-e^{-j\frac{\pi k}{3}}} - \cancel{\frac{1}{1-e^{-j\frac{\pi k}{3}}} \cdot e^{-j\frac{\pi k}{3}}}$$

$$X(z) = \sum_{n=-\infty}^{\infty} a(n) \cdot z^n$$

$$= 1 + z^1 + z^2 + \dots + z^7$$

$$X(k) = X(z) \Big|_{z=e^{j\frac{2\pi k}{3}}} \quad \text{where } k \rightarrow 0 \text{ to } 5.$$

$$\begin{aligned} X(k) &= 1 + e^{-j\frac{\pi k}{3}} + e^{-j\frac{2\pi k}{3}} + e^{-j\frac{3\pi k}{3}} + e^{-j\frac{4\pi k}{3}} + e^{-j\frac{5\pi k}{3}} + e^{-j\frac{6\pi k}{3}} \\ &\quad + e^{-j\frac{7\pi k}{3}} + e^{-j\frac{8\pi k}{3}} \end{aligned}$$

↓ ↓
 (1) $e^{-j\frac{2\pi k}{3}}$

$$a(n) = ?$$

Properties

Periodicity

If DF

$$a(1)$$

$$X(1)$$

Linearity

If $D\{a_1(n)\}$

$$D\{a_2(n)\}$$

then F

$$N_3$$

for fin

length.

If N

to $a_2(n)$

$$x(k) = 2 + 2 e^{-j\pi k/3} + e^{-j2\pi k/3} + e^{-j\pi k} + e^{-j4\pi k/3} + e^{-j5\pi k/3}$$

$$a(n) = \{2, 2, 1, 1, 1, 1\}$$

Properties of DFT:-

Periodicity :-

If $DFT[a(n)] = X(k)$

$$a(n+N) = a(n)$$

$$X(k+N) = X(k)$$

Linearity :-

If $D\left[\frac{a_1(n)}{N_1}\right] = X_1(k)$

$$\frac{a_1(n)}{N_1} \quad N_1$$

$D\left[\frac{a_2(n)}{N_2}\right] = X_2(k)$

$$\frac{a_2(n)}{N_2} \quad N_2$$

then $D[a_1(n) + b a_2(n)] = a_1 X_1(k) + b X_2(k)$

$$N_3 = \max(N_1, N_2)$$

for linear combination both should have same length.

If $N_2 < N_1$, then $(N_1 - N_2)$ no. of zeros are added to $a_2(n)$ & vice versa

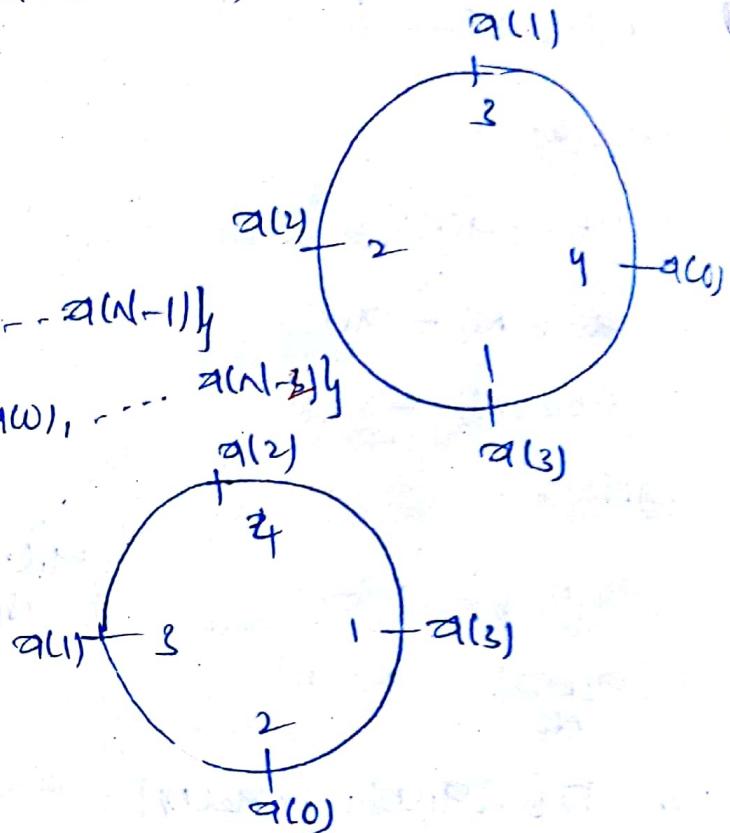
Circular shift of a sequence

$$a_p(n) = \sum_{k=0}^{p-1} a(n-k)$$

$$a((n))_N = a(n \text{ modulo } N)$$

$$a(n) = \{a(0), a(1), \dots, a(N-1)\}$$

$$a((n-1))_N = \{a(N-1), a(0), \dots, a(N-2)\}$$



$$a((n-2))_N = \{a(N-2), a(N-1), \dots, a(N-3)\}$$

$$a((n-k))_N = \{a(n-k), a(n-k+1), \dots, a(n-1)\}$$

$$a((n-N))_N = \{a(0), a(1), \dots, a(N-1)\}$$

$$= a(n)$$

Circular time shift property:

$$a((n-m))_N = a(n-m+N)$$

$$\text{if } \text{DFT}[x(n)] = x(k)$$

$$x((n-m))_N \rightarrow e^{-j\frac{2\pi}{N}mk} x(k),$$

$$\text{DFT}[\alpha((n-m))_N] = \sum_{n=0}^{N-1} \alpha((n-m))_N \cdot e^{-j\frac{2\pi}{N} nk}$$

0 3 u z

$$= \sum_{n=0}^{m-1} d((n-m))_N \cdot e^{-j \frac{2\pi}{N} nk} + \sum_{n=m}^{N-1} d((n-m))_N \cdot e^{-j \frac{2\pi}{N} nk}$$

$$\sum_{n=0}^{m-1} z^{\frac{1}{n}} (n-m)! \cdot e^{-\frac{i 2 \pi n k}{N}}$$

$$= \sum_{n=0}^{m-1} a(n-m+N) \cdot e^{-j \frac{2\pi}{N} nk} + \sum_{n=m}^{N-1} a(n-m+N) \cdot e^{-j \frac{2\pi n k}{N}}$$

$$h-m+n=l$$

$$l = n - m$$

$$m-1-m+n=1 \Rightarrow l=n-1$$

$$= \sum_{l=N-m}^N a(l) e^{-j\frac{2\pi}{N}(l+m-N)k} + \sum_{l=1}^{2N-m-1} a(l) e^{-j\frac{2\pi}{N}(l+mN)k}$$

$$= \sum_{l=m}^{n-1} a_{ll} e^{-j \frac{2\pi}{N} (l+m)k} + \sum_{l=0}^{n-m-1} a_{ll} e^{-j \frac{2\pi}{N} (l+m)k}$$

$$\begin{aligned}
 &= \sum_{l=0}^{N-1} a(l) \cdot e^{-j\frac{2\pi}{N}(l+m)k} \\
 &= e^{-j\frac{2\pi}{N}mk} \cdot \sum_{l=0}^{N-1} a(l) \cdot e^{-j\frac{2\pi}{N}lk} \\
 &= e^{-j\frac{2\pi}{N}mk} \cdot X(k)
 \end{aligned}$$

Time Reversal property:-

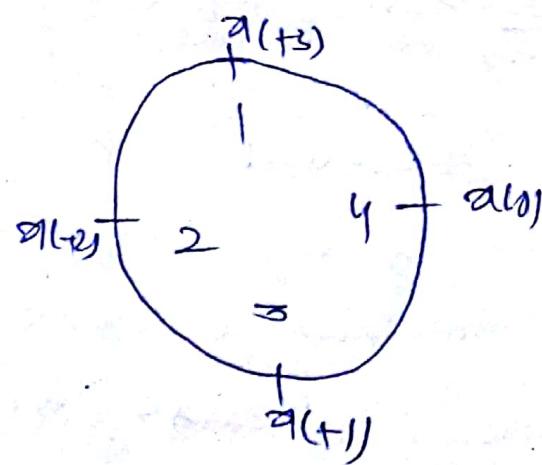
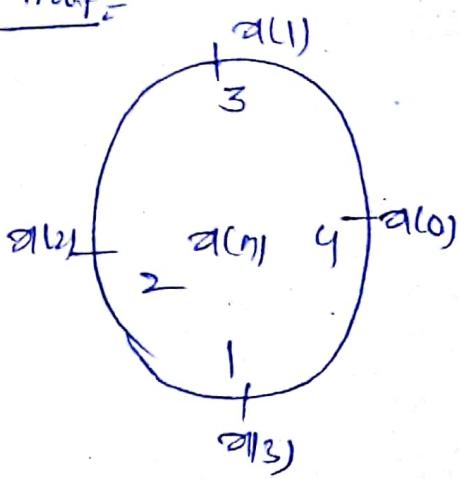
The time reversal of an end point sequence $a(n)$ is obtained by wrapping the sequence $a(n)$ around a circle in clockwise direction.

$$DFT[a((-n))]_N = X((-k))_N$$

$a(N-n)$

~~$a(N-k)$~~

Proof:-



$$\begin{aligned}
 \text{DFT}[\mathbf{a}(n)] &= \sum_{n=0}^{N-1} (\mathbf{a}(n))_N e^{-j \frac{2\pi}{N} kn} \\
 &= \sum_{n=0}^{N-1} \mathbf{a}(N-n) e^{-j \frac{2\pi}{N} nk} \\
 \Rightarrow N-n &= m \\
 &= \sum_{m=0}^{N-1} \mathbf{a}(m) e^{-j \frac{2\pi}{N} (N-m)k} \\
 &= \sum_{m=0}^{N-1} \mathbf{a}(m) e^{j \frac{2\pi}{N} mk} \\
 &= \sum_{m=0}^{N-1} \mathbf{a}(m) e^{-j \frac{2\pi}{N} (N-k)m} \\
 &= \mathbf{a} X(N-k) \\
 &= X(-k)_N
 \end{aligned}$$

Circular frequency shifting.

if $\text{DFT}[\mathbf{a}(n)] = X(k)$ then

$$\text{DFT}\left[e^{j \frac{2\pi}{N} ln} \cdot \mathbf{a}(n)\right] = X((k+l))_N$$

$$\begin{aligned}
 \text{DFT}[\mathbf{a}(n)] &= \sum_{n=0}^{N-1} \mathbf{a}(n) e^{-j \frac{2\pi}{N} kn} \\
 \text{DFT}\left[e^{j \frac{2\pi}{N} ln} \mathbf{a}(n)\right] &= \sum_{n=0}^{N-1} \mathbf{a}(n) e^{j \frac{2\pi}{N} ln} \cdot e^{j \frac{2\pi}{N} kn} \\
 &= \sum_{n=0}^{N-1} \mathbf{a}(n) e^{-j \frac{2\pi}{N} (k-l)n} \\
 &= \mathbf{a}((k-l))_N
 \end{aligned}$$

Complex Conjugate Property:

$$\text{If } \text{DFT}[\alpha(n)] = X(k)$$

$$\text{DFT}[\alpha^*(n)] = X^*(N-k) = X^*(-k)_N$$

$$\text{DFT}[\alpha(n)] = \sum_{n=0}^{N-1} \alpha(n) e^{-j \frac{2\pi}{N} nk}$$

$$\text{DFT}[\alpha^*(n)] = \sum_{n=0}^{N-1} \alpha^*(n) e^{-j \frac{2\pi}{N} nk}$$

$$= \left[\sum_{n=0}^{N-1} \alpha(n) e^{j \frac{2\pi}{N} nk} \right]^*$$

$$= \left[\sum_{n=0}^{N-1} \alpha(n) e^{-j \frac{2\pi}{N} (-kn)} \right]^*$$

$$= [X^*(-k)_N]$$

$$= X^*(N-k)$$

Circular Convolution:

$$\text{DFT}[\alpha_1(n) \circledast \alpha_2(n)] = X_1(k), X_2(k)$$

$$X_1(k) = \sum_{n=0}^{N-1} \alpha_1(n) e^{-j \frac{2\pi}{N} kn}$$

$$X_2(k) = \sum_{n=0}^{N-1} \alpha_2(n) e^{-j \frac{2\pi}{N} kn}$$

$$a_3(n) = \sum_{m=0}^{N-1} a_1(m) \cdot a_2(n-m)$$

$$x_N((n))_N = \sum_{m=0}^{N-1} a_1((m))_N \cdot a_2((n-m))_N$$

$$a_3(n) = \sum_{m=0}^{N-1} a_1(n) \cdot a_2(n-m)_N$$

$$a_3(n) = a_1(n) \cdot a_2(n)$$

$$a_3(n) = \frac{1}{N} \sum_{k=0}^{N-1} x(k) \cdot e^{j \frac{2\pi}{N} kn}$$

$$= \frac{1}{N} \sum_{k=0}^{N-1} x_1(k) \cdot x_2(k) \cdot e^{j \frac{2\pi}{N} kn}$$

$$= \frac{1}{N} \sum_{k=0}^{N-1} \left[\sum_{m=0}^{N-1} a_1(m) e^{-j \frac{2\pi}{N} mn} \sum_{l=0}^{N-1} a_2(l) \cdot e^{-j \frac{2\pi}{N} lk} \right] e^{j \frac{2\pi}{N} kn}$$

$$= \frac{1}{N} \sum_{k=0}^{N-1} \cancel{\sum_{m=0}^{N-1} a_1(m)} \sum_{l=0}^{N-1} a_2(l) \cdot e^{-j \frac{2\pi}{N} (l+m-k)k}$$

$$N = \text{if } l = n-m$$

$$0 \quad \text{otherwise}$$

$$= \frac{1}{N} \sum_{k=0}^{N-1}$$

$$= \frac{1}{N} \sum_{m=0}^{N-1} a_1(m) \sum_{l=0}^{N-1} a_2(l) \sum_{k=0}^{N-1} e^{-j \frac{2\pi}{N} (l+m-n)k}$$

$$N \quad l = n-m$$

$$0 \quad l \neq n-m$$

$$= \frac{1}{N} \sum_{m=0}^{N-1} a_1(m) \cdot a_2((n-m))_N$$

$$a_3(n) = \sum_{m=0}^{N-1} a_1(m) \cdot a_2((n-m))_N$$

* The 5 point DFT of a sequence $a(n)$ denoted by $x(k)$, plot sequence whose DFT is $y(k) = e^{-j\frac{2\pi}{5}nk} \cdot x(k)$

Sol:- Where $a(n) = \{1, 2, 2, 1, 4\}$

$$\text{DFT}[a(n-m)] = e^{-j\frac{2\pi}{5}mk} \cdot x(k).$$

$$y(n) = |a(n-2)|_5$$

$$a(n) = \{1, 2, 2, 1, 0\}$$

$$n=0, y(0) = |a(-2)|_5 = a(3) = 1$$

$$n=1, y(1) = |a((-1))|_5 = a(4) = 0$$

$$n=2, y(2) = |a((0))|_5 = -1$$

$$n=3, y(3) = |a((1))|_5 = 2$$

$$n=4, y(4) = |a((2))|_5 = 2$$

$$y(n) = \{1, 0, 4, 2, 2\}$$

*

$$y(k) = e^{-j\frac{2\pi}{5}nk} \cdot x(k)$$

$$x(n) = \underbrace{\{1, 3, 1, 2, -1\}}_6$$

$$= e^{-j\frac{2\pi}{5}(2)k} \cdot x(k)$$

$$= |a(n-2)|_6$$

$$= \{1, 2, -1, 1, 2, 1\}$$

* Consider the length $N=8$, & sequence

$a(n) = \{1, 2, -3, 0, 1, -1, 4, 2\}$. Evaluate the following functions of $X(k)$ without computing the DFT

$$A) X(0) \quad B) X(4) \quad \Leftrightarrow \sum_{k=0}^7 X(k)$$

$$D) \sum_{k=0}^7 e^{-j \frac{3\pi k}{4}} \cdot X(k) \quad \Leftrightarrow \sum_{k=0}^7 |X(k)|^2$$

$$\text{Sol: } X(0) = \sum_{n=0}^7 a(n) \cdot e^{-j \frac{2\pi}{N} nk + j k \omega_0}$$

$$X(0) = \sum_{n=0}^7 a(n)$$

$$= 6$$

$$X(4) = \sum_{n=0}^7 a(n) \cdot e^{-j \frac{\pi}{2} \cdot 4n}$$

$$= \sum_{n=0}^7 (-1)^n a(n)$$

$$= 1 + 2 - 3 + 0 -$$

$$= 1 + (-1) + (-1) + (-1) + 0 = -2$$

$$= + (1) - (2) + (-3) - (0) + (1) - (-1) + (4) - 2.$$

$$= 7 - 7 = 0$$

$$\sum_{k=0}^7 X(k) = N a(0) \quad a(0) = \frac{1}{N} \sum_{k=0}^{N-1} X(k) \cdot e^{j \frac{2\pi}{N} nk}$$

$$= 8(1)$$

$$= 8,$$

$$a(0) \cdot N = \sum_{k=0}^{N-1} X(k)$$

$$d) \sum_{k=0}^7 e^{-j\frac{3\pi}{4}k} x(k) = \sum_{k=0}^7 e^{-j\frac{2\pi}{8}(3)k} x(k)$$

$$= N \cdot \sum_{k=0}^7 x(k)$$

$$= N \cdot \sum_{k=0}^7 (-1)^k$$

$$= -8$$

* Methods + sequences:

- > Concentric
- > Matrix

Concentric

$$\frac{1}{N} \sum_{k=0}^7 |x(k)|^r = \frac{1}{8} \left(\sum_{n=0}^{N-1} (\alpha(n))^r \right)^r$$

$$= 8 \left(\sum_{n=0}^{N-1} (\alpha(n))^r \right)$$

$$= 8 [1 + 4 + 9 + 0 + 1 + 1 + 16 + 4]$$

$$= 8 \times 36$$

$$= 288$$

Circular Convolution

If $\alpha_1(n)$ length is N_1 , & $\alpha_2(n)$ length is N_2 .

$$\alpha_3(n) = \alpha_1(n) \odot \alpha_2(n), L_3 = \max(N_1, N_2)$$

To perform circular convolution, the sequence length must be same

so, if $N_1 < N_2$ then append $(N_2 - N_1)$ no. of zeros to $\alpha_1(n)$

if $N_2 < N_1$ then append $(N_1 - N_2)$ no. of zeros to $\alpha_2(n)$

$\alpha_1(r)$

$\alpha_2(r)$

Procedure:

- > Take clockwise
- > Graph r around a
- > Start

of $\alpha_2(n)$

in clock wise

⇒ Multiplication

sum of it

⇒ Rotate

wise di

next va

⇒ Repeat

first samp

If $x(n) \rightarrow$ of length L
 $h(n) \rightarrow$ length M

$$\left. \begin{array}{l} \\ \end{array} \right\} \text{Max}(L, M) = A$$

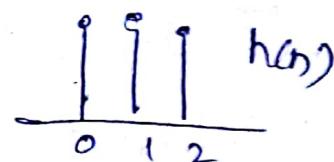
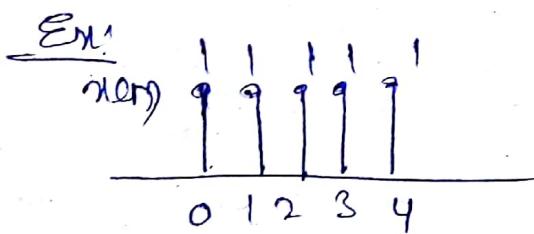
$x(n) * h(n) \rightarrow$ length $\rightarrow L+M-1 = B$

If $A=L$; then $M-1$ points are extra in B (Circular)

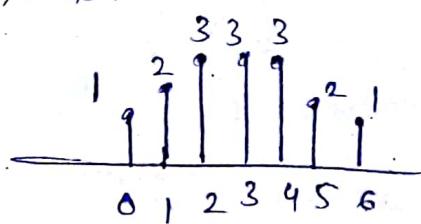
If $A=M$ then $L-1$ pts are extra in B .

→ To perform linear convolution from circular convolution add $(M-1)$ ' zeros to $x(n)$ & $(L-1)$ ' zeros to $h(n)$

→ There is a time aliasing effect that occurs in circular convolution as 'Gray' points overlap first samples in circular convolution.



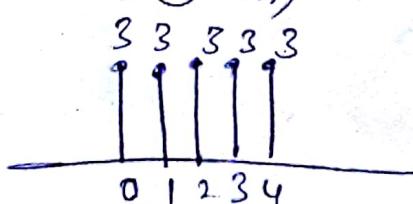
$x(n) * h(n)$



$$y(6) - y(5)$$

$$y(4) - y(3)$$

$x(n) \oplus h(n)$



* Determine the output response $y(n)$ if $h(n) = \{1, 1, 1\}$

$$x(n) = \{1, 2, 3, 4\}, \text{ using } \boxed{V^n}$$

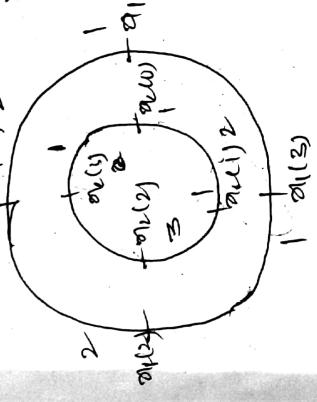
\Rightarrow linear convolution \Rightarrow circular convolution

\Leftrightarrow circular convolution with zero padding
linear conv from circular.

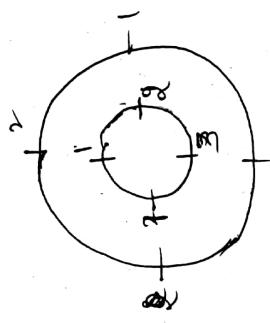
$$\star h(n) = \{1, 2, 2, 1, 1, -1\}.$$

$$\star x_1(n) = \{1, 2, 2, 1, 1\} \quad x_2(n) = \{1, 2, 3, 1\}$$

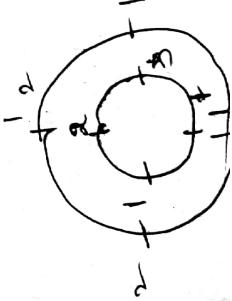
$$N_1 = 4, \quad N_2 = 4 \quad \star x_3(n) = \star x_1(n) \otimes x_2(n)$$

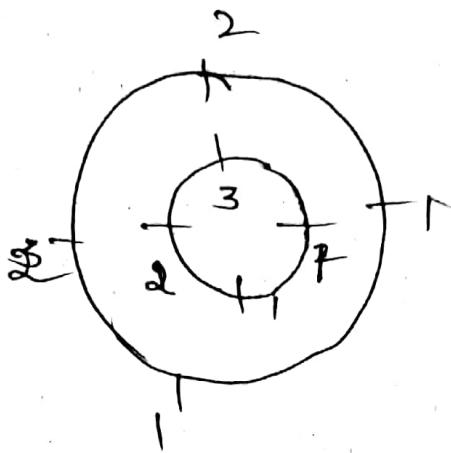


$$\Rightarrow x_3(0) = 1 + \cancel{2} + 6 + \cancel{1} \\ = \cancel{2} 11$$



$$\Rightarrow x_3(1) = 2 + 2 + \cancel{2} + 3 \\ = \cancel{2} 9$$





$$\Rightarrow \alpha_3(n) = 1 + 6 + 8 + 1 \\ = 16$$

$$\alpha_k(n) = \{11, 09, 10, 12\}$$

$$\Rightarrow \alpha_1(n) = \{1, 2, 3, 1\}, \quad \alpha_2(n) = \{4, 3, 2, 2\}$$

$$X_1(1) = \sum_{n=0}^3 \alpha_1(n) e^{-j \frac{2\pi}{N} nk}$$

$$k=0,$$

$$X_1(0) = \sum_{n=0}^3 \alpha_1(n) e^{-j \frac{2\pi}{N} n(0)}$$

$$= \sum_{n=0}^3 \alpha_1(n) = 1 + 2 + 3 + 1 = 7$$

$$k=1$$

$$X_1(1) = \sum_{n=0}^3 \alpha_1(n) e^{-j \frac{2\pi}{N} n(1)}$$

$$= \sum_{n=0}^3 \alpha_1(n) e^{-j n \pi/2}$$

$$= \alpha_1(0) + \alpha_1(1), e^{-j \pi/2} + \alpha_1(2), e^{-j \pi} + \alpha_1(3), e^{-j 3\pi/2}$$

$$= 1 + 2(-j) + 3(-1) + 1(j), \\ = 1 - 2j - 3 + j = -2 - j$$

$K=2$

$$x_p(2) = \sum_{n=0}^3 a_1(n) \cdot e^{-j\frac{2\pi}{4}n} \cdot n(2)$$

$$= \sum_{n=0}^3 a_1(n) \cdot e^{-j n \pi}$$

$$= a_1(0) + a_1(1)(-1) + a_1(2) + a_1(3)(-1)$$

$$= 1 - 2 + 3 - 1 = 1$$

$K=3$

$$x_1(3) = \sum_{n=0}^3 a_1(n) \cdot e^{-j\frac{3\pi}{4}n} = \sum_{n=0}^3 a_1(n) \cdot e^{-j\frac{3\pi n}{2}}$$

$$= a_1(0) + a_1(1) \cdot e^{-j 3\pi} + a_1(2) \cdot e^{-j 3\pi} + a_1(3) \cdot e^{-j \frac{9\pi}{2}}$$

$$= 1 + 2 \cdot (-j) + 3(-1) + 1(-j)$$

$$= 1 + 2j - 3 - j = -2 + j$$

$$x_2(0) = \sum_{n=0}^3 a_2(n) = 4 + 3 + 2 + 2 = 11$$

$$x_2(1) = \sum_{n=0}^3 a_2(n) \cdot e^{-j\frac{3\pi}{4}n}$$

$$= 4 + 3(-j) + 2(-1) + 2(j)$$

$$= 4 - 3j - 2 + 2j = 2 + j$$

$$x_2(2) = \sum_{n=0}^3 a_2(n) \cdot e^{-j\frac{2\pi}{4}n}$$

$$= 4 + 3(-1) + 2(1) + 2(-1)$$

$$= 4 - 3 + 2 - 2 = 1$$

$a_3(1), e^{-j 3\pi/2}$

$$x_{2(3)} = 4 + 3(j) + 2(-1) + 2(-j)$$

$$= 4 + 3j - 2 - 2j = 2 + j$$

$$x_{3(k)} = \{x_1(k), x_2(k)\}$$

$$-4 + 2j - 2j - 1$$

$$= \{7, -2-j, 1, -2+j\} \quad \{1, 2-j, 1, 2+j\}$$

$$= \{7, (-4+3j-2j-1), 1, (-1)-4j\}$$

$$= \{7, -5, 1, -5\}$$

IDFT

$$a_3(n) = \frac{1}{N} \sum_{k=0}^3 x_{3(k)} e^{j \frac{2\pi}{N} nk}$$

$$a_3(0) = \frac{1}{4} \sum_{k=0}^3 x_{3(k)} = \frac{1}{4} (7 + 5 + 1 - 5) = 2.17$$

$$a_3(1) = \frac{1}{4} \sum_{k=0}^3 x_{3(k)} e^{j \frac{2\pi}{4} (1)(k)}$$

$$= \frac{1}{4} [x_2(0) + x_2(1) e^{j \frac{\pi}{2}} + x_2(2) e^{j \pi} + x_2(3) e^{j \frac{3\pi}{2}}]$$

$$= \frac{1}{4} [7 - 5(j) + 1(-1) + (-5)(-j)]$$

$$= \frac{1}{4} [(1-5j) - 1 + 5j] = 10,$$

$$= |y_u(77-5j-1+5j)| = |y_u(76)| = 19$$

$$x_2(2) = \frac{1}{4} \sum_{k=0}^5 x_k(1), e^{j\frac{2\pi}{4} k \cdot 2}$$

$$= \frac{1}{4} [x_2(0) + x_2(1), e^{j\pi} + x_2(2), e^{j2\pi} + x_2(3), e^{j3\pi}]$$

$$= \frac{1}{4} [77 - 5(-1) + 1(1) - 5(-1)]$$

$$= \frac{1}{4} [77 + 5 + 1 + 5] = \cancel{22} \quad 22$$

$$x_3(2) = \sum_{k=0}^3 x_k(1), e^{j\frac{3\pi}{4} k \cdot 2}$$

$$= \frac{1}{4} [x_3(0) + x_3(1), e^{j\pi} + x_3(2), e^{j\frac{3\pi}{2}} + x_3(3), e^{j2\pi}]$$

$$= \frac{1}{4} [77 - 5(-1) + i(-1) - 5(1)]$$

$$= 1/4 [77 + 5] - 1 + 5i = \frac{76}{4} = 19$$

$$= \{17, 19, 22, 19\}$$

$$\rightarrow x_1(n) = \{1, 1, -1, 2\}, \quad x_2(n) = \{2, 0, 1, 1\}$$

$$\left[\begin{array}{cccc} 2 & 1 & 1 & 0 \\ 0 & 2 & 1 & 1 \\ 1 & 0 & 2 & 1 \\ 1 & 1 & 0 & 2 \end{array} \right] \left[\begin{array}{c} 1 \\ 1 \\ -1 \\ 2 \end{array} \right]$$

$$= \left[\begin{array}{c} 2+1-1 \\ 2-1+2 \\ 1-1+2 \\ 1+1+4 \end{array} \right] = \left[\begin{array}{c} 2 \\ 3 \\ 1 \\ 6 \end{array} \right]$$

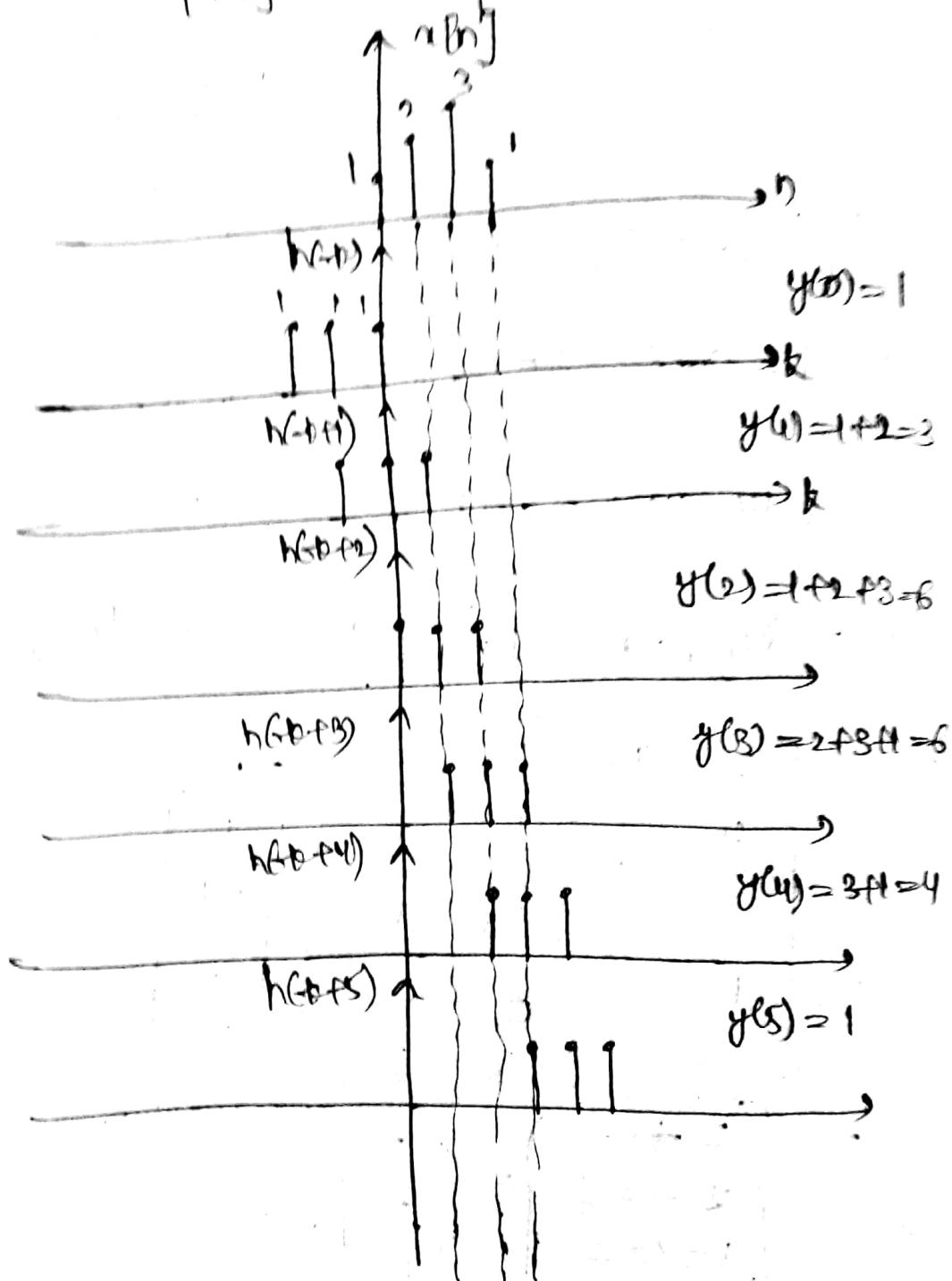
Q) Ans:

① Determining $y(0)$, $h(0) = \{1, 1, 1\}$, $x(0) = \{1, 2, 3, 1\}$

using ② linear convolution ③ circular convolution

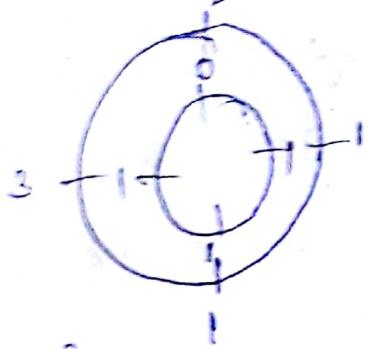
④ circular convolution with zero padding.

Ans. $h(0) = \{1, 1, 1\}$, $x(0) = \{1, 2, 3, 1\}$

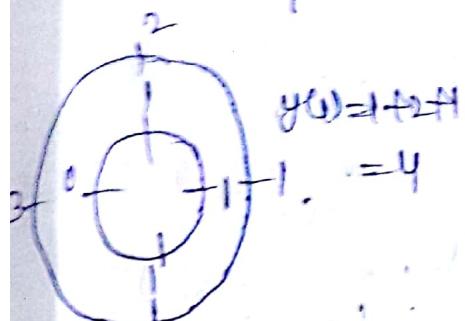


$$y(n) = \{1, 3, 6, 6, 4, 1\}$$

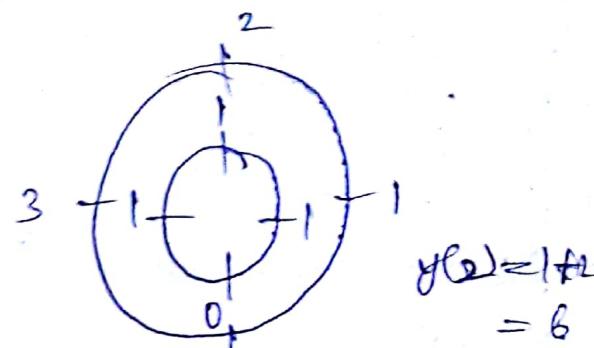
$$\textcircled{b} \quad x(n) = \{1, 2, 3, 0\}, \quad h(n) = \{1, 1, 1, 0\}$$



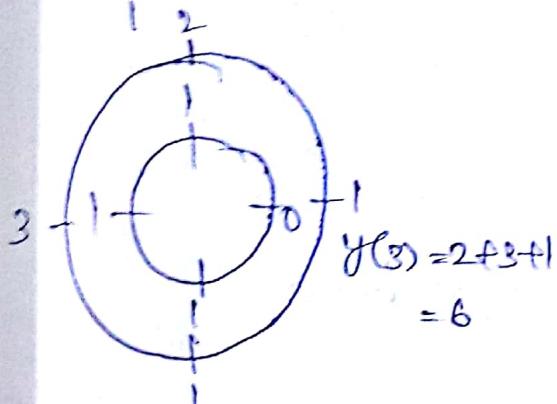
$$y(0) = 1+3+1 = 5$$



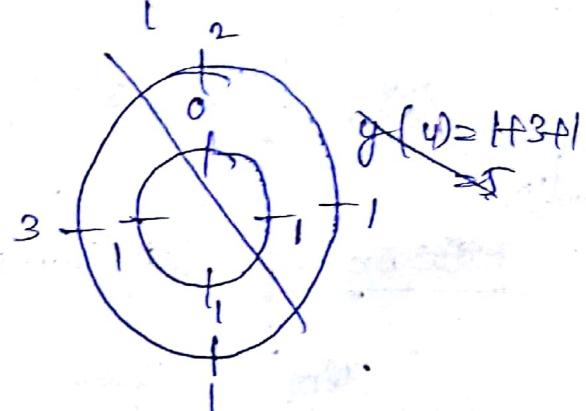
$$y(1) = 1+2+1 = 4$$



$$y(2) = 1+2+3 = 6$$



$$y(3) = 2+3+1 = 6$$



$$\cancel{y(4) = 1+3+1}$$

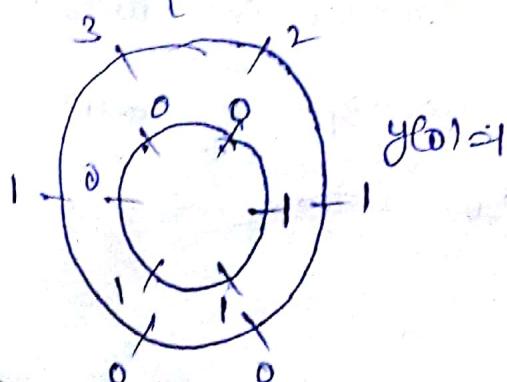
$$y(n) = \{5, 4, 6, 6\}$$

$$\textcircled{c} \quad x(n) = \{1, 2, 3, 1\}, \quad h(n) = \{1, 1, 1\}$$

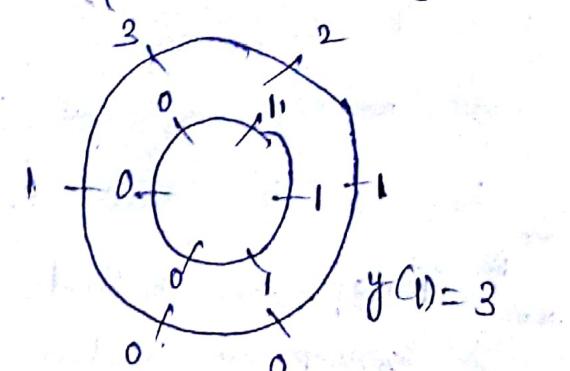
$$N=4, \quad L=3$$

$$N+L-1 = 4+3-1 = 6$$

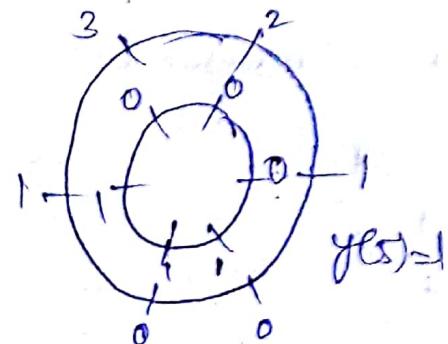
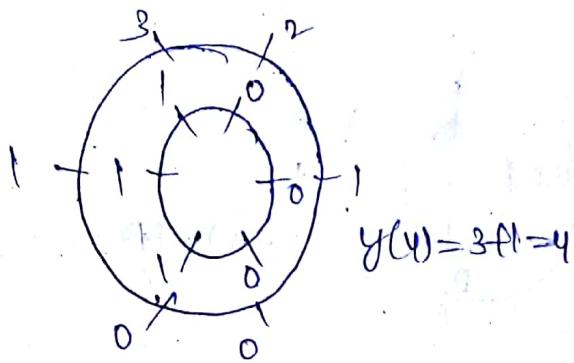
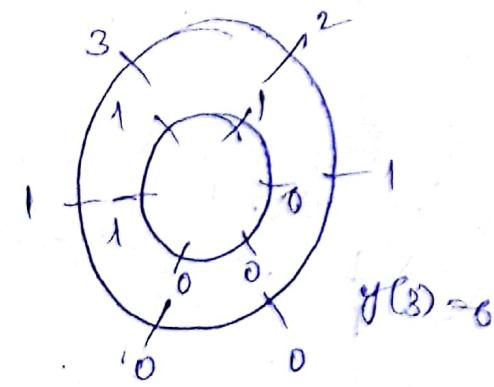
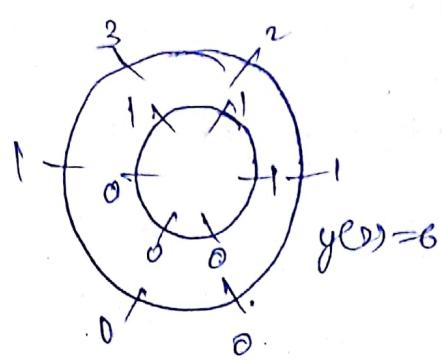
$$x(n) = \{1, 2, 3, 1, 0, 0\}, \quad h(n) = \{1, 1, 1, 0, 0, 0\}$$



$$y(0) = 1$$



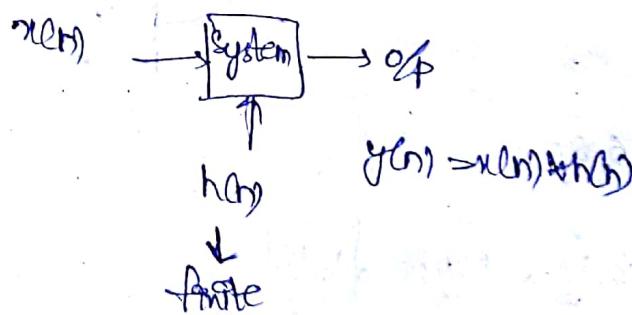
$$y(1) = 3$$



$$y(n) = \{1, 3, 6, 5, 4, 1\}$$

16/11/18

Folding of long duration sequences:



We cannot store long duration signal $x(n)$ before convolution (Circular convolution)

∴ If sequence $x(n)$ is divided into blocks and it is processed and the y 's are combined. It can be done in two methods.

- ~~Method 1~~
 - 1) Overlap save method
 - 2) Overlap-add method.

Overlap save method:

$x(n) \rightarrow$ length = l_s

$h(n) \rightarrow$ length = M

length of each block = $N = l_s + M - 1$

l_s data points

$M-1$ data points from previous data

$$x_1(n) = \{0, 0, x(0), x(1), \dots, x(l_s-1)\}$$

$$x_2(n) = \{x(l_s-M+1), \dots, x(l_s-1), x(l_s), x(l_s+1), \dots, x(l_s+M-1)\}$$

$$x_3(n) = \{x(l_s+M+1), \dots, x(l_s+L-1), x(l_s+L), x(l_s+L+1), \dots, x(l_s+L+M-1)\}$$

$h(n) \rightarrow$ length = M , $L-1$ zeros are appended i.e. $L+M-1$

$$y_1(n) = x_1(n) \textcircled{\#} h(n) = \{y_1(0), y_1(1), \dots\}$$

$$y_2(n) = x_2(n) \textcircled{\#} h(n)$$

$$\vdots$$

$$y_5(n) = x_5(n) \textcircled{\#} h(n)$$

Eg: $l_s = 15$

$$M = 3 \quad M-1 = 2$$

$$N = 5 \quad L = 3$$

$$x_1(n) = \{0, 0, x(0), x(1), x(2), \dots\}$$

$$x_2(n) = \{x(4), x(5), x(6), x(7), x(8)\}$$

$$x_3(n) = \{x(10), x(11), x(12), x(13), x(14)\}$$

$$x_4(n) = \{x(17), x(18), x(19), x(20), x(21)\}$$

$$x_5(n) = \{x(20), x(21), x(22), x(23), x(24)\}$$

$$y(n) = y_1(0), y_1(1), y_1(2), \dots, y_1(L-1)$$

$$y_1(n) = y_2(0), y_2(1), y_2(2), \dots, y_2(M-1)$$

$$\{y_2(0), y_2(1), \dots, y_2(M-1)\}$$

First M-1 points are discarded, as the first point is repeated.

$$y(n) = \{y_1(2), y_1(3), y_1(4), y_2(2), y_2(3), y_2(4), y_3(2), y_3(3), y_3(4)\}$$

$$\{y_1(2), y_1(4), y_2(2), y_2(3), y_3(4)\}$$

Overlap add method:

$$x(n) \rightarrow L_s, h(n) \rightarrow M, N = L_s + M$$

Have 'L' data points and M-1 zeros are taken at

$$N \Rightarrow S, S = L + M - 1, M \Rightarrow B \Rightarrow L \Rightarrow S$$

$$x_1(n) = \{x(0), x(1), \dots, x(L-1), 0, 0, \dots\}$$

$$x_2(n) = \{x(0), x(1), \dots, x(B-1), 0, 0, \dots\}$$

$$x_3(n) = \dots$$

$$\begin{aligned} x_4(n) &= \{x(0), x(1), x(2), 0, 0\} \\ x_5(n) &= \{x(0), x(1), x(2), 0, 0\} \end{aligned}$$

$$y(n) = \{y_1(2), y_1(3), y_1(4), 0, 0\}$$

For h(n), L-1 zeros are appended and convolution is performed

$$y_1(n) = \{y_1(0), y_1(1), \dots, y_1(M)\}$$

$$y_2(n) = \{y_2(0), y_2(1), \dots, y_2(M)\}$$

$$y_3(n) = \{y_3(0), y_3(1), \dots, y_3(M)\}$$

$$\begin{aligned} y(n) &= \{y_1(0), y_1(1), y_1(2), y_1(3) + y_2(0), y_1(4) + y_2(1), y_1(5) + y_2(2), y_1(6) + y_2(3) + y_3(0), \\ &\quad y_2(4) + y_3(1), y_2(5) + y_3(2), y_2(6) + y_3(3), y_3(4) + y_3(5), y_3(6)\} \end{aligned}$$

$$a(n) = \{ -3, -1, 0, 1, 3, 2, 0, 1, 2, 1 \}$$

$$h(n) = \{1, 1, 1\}^T$$

overlap save method

$$N = L_s + M - 1$$

$$L=10, M=3$$

$$N = L + M - 1$$

2 = 42

$$N=5, \quad L=3$$

$\mathbf{g}_1(\mathbf{u}_1) = \{ \mathbf{M}_{-1} \text{ padded zeros, } -h \text{ datapoints} \}$

$\sigma_k(n) = \underbrace{\{M-1\} \text{ previous data points}}_{\text{Points}}, + \text{ new data point},$

$$a(n) = \{ 0, 0, 3, -1, 0 \}$$

$$a_2(n) = \{-1, 0, 1, 3, 2\}$$

$$z_3(n) = \{3, 2, 0, 1, 2\}$$

$$q_4(\eta) = \{12, 1, 0, 0\}$$

$$y_1(n) = a_1(n) h(n)$$

$h(n) = \{1, 1, 1, 0, 0\}$

1

$\{g(1), g_1(2)\}$

$$y_1(n) = \begin{bmatrix} 1 & 0 & 0 & 1 & 1 \\ 1 & 1 & 0 & 0 & 1 \\ 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 3 \\ -1 \\ 0 \end{bmatrix}$$

$$y_1(n) = \{-1, 0, 3, 2, 2\}$$

$$y_2(n) = \begin{bmatrix} 1 & 0 & 0 & 1 & 1 \\ 1 & 1 & 0 & 0 & 1 \\ 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} -1 \\ 0 \\ 1 \\ 3 \\ 2 \end{bmatrix}$$

~~$$y_2(n) = \{4, 1, 0, 4, 6\}$$~~

~~$$y_3(n) = \{6, 7, 5, 3, 3\}$$~~

~~$$y_4(n) = \{1, 3, 4, 3, 1\}$$~~

~~$$y(n) = \{3, 2, 2, 0, 4, 6, 5, 3, 3, 4, 3, 1\}$$~~

Overlap add method

1. $x(n) = \{x \text{ datapoints } (M-1) \text{ zeros padded}\}$

$$x_1(n) = \{3, -1, 0, 0, 0\}$$

$$x_2(n) = \{1, 3, 2, 0, 0\}$$

$$x_3(n) = \{0, 1, 2, 0, 0\}$$

$$x_4(n) = \{1, 0, 0, 0, 0\}$$

$$y_1(n) = \begin{bmatrix} 1 & 0 & 0 & 1 & 1 \\ 1 & 9 & 0 & 0 & 1 \\ 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 & 1 \end{bmatrix} \begin{pmatrix} 3 \\ -1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$y_1(n) = \{3, -1, 0, 0\}$$

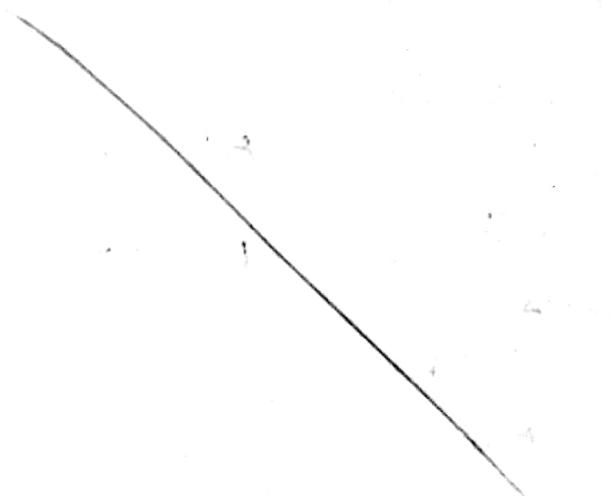
$$y_2(n) = \{1, 4, 6, 5, 2\}$$

$$y_3(n) = \{0, 1, 3, 3, 2\}$$

$$y_4(n) = \{1, 1, 1, 0, 0\}$$

$$\begin{array}{ccccccc} 3 & 2 & 2 & -1 & 0 & & \\ & 1 & 4 & 6 & 5 & 2 & \\ & & 0 & 1 & 3 & 3 & 2 \\ & & & & & 1 & 1 \end{array} \begin{array}{c} 100 \\ \\ \\ \\ \\ \end{array}$$

$$g(n) = \{3, 2, 2, 0, 4, 6, 5, 3, 3, 4, 3, 1\}$$



DIT FFT

Radix 2-pt DITFFT

We perform FFT only for 2-power numbers.

1. Of points. If the sequence length is power 2.

Append zeros.

$$N = 2^M \rightarrow M \rightarrow \text{Integer}$$

$a(n)$ is even

$$a_e(n) = a(2n)$$

$$a_o(n) = a(2n+1)$$

$$\omega_N^{nk} = \omega_N^{nk}$$

$$\omega_N^{nk+n/2} = \omega_N^{nk}$$

$$X(k) = \sum_{n=0}^{N-1} a(n) \omega_N^{nk}$$

$$= \sum_{n=0}^{N-1} a_e(n) \omega_N^{nk} + \sum_{n=0}^{N-1} a_o(n) \omega_N^{nk}$$

even

odd

$$= \sum_{n=0}^{\frac{N}{2}-1} a_e(n) \omega_N^{2nk} + \sum_{n=0}^{\frac{N}{2}-1} a_o(2n+1) \omega_N^{(2n+1)k}$$

$$= \sum_{n=0}^{\frac{N}{2}-1} a(2n) \omega_N^{2nk} + \omega_N^k \sum_{n=0}^{\frac{N}{2}-1} a(2n+1) \omega_N^{2nk}$$

$$w_N^r = \left(e^{-j \frac{2\pi}{N}} \right)^r = w_{N/2}^r$$

$$\sum_{n=0}^{N-1} a_e(n) \cdot w_{N/2}^{nk} + w_N^k \sum_{n=0}^{N-1} a_o(n) \cdot w_{N/2}^{nk}$$

$$x(k) = x_e(k) + w_N^k \cdot x_o(k) \quad k=0 \text{ to } \frac{N}{2}-1$$

$$x(k) = x_e(k-N/2) + w_N^{(k-N/2)} x_o(k-N/2)$$

$N=8$

$$a_e(n) = a(2n)$$

$$a_o(n) = a(2n+1)$$

$$a_e(0) = a(0)$$

$$a_o(0) = a(1)$$

$$a_e(1) = a(2)$$

$$a_o(1) = a(3)$$

$$a_e(2) = a(4)$$

$$a_o(2) = a(5)$$

$$a_e(3) = a(6)$$

$$a_o(3) = a(7)$$

$$x(0) = x_e(0) + w_8^0 x_o(0)$$

$$x(4) = x_e(0) - w_8^0 x_o(0)$$

$$x(1) = x_e(1) + w_8^1 x_o(1)$$

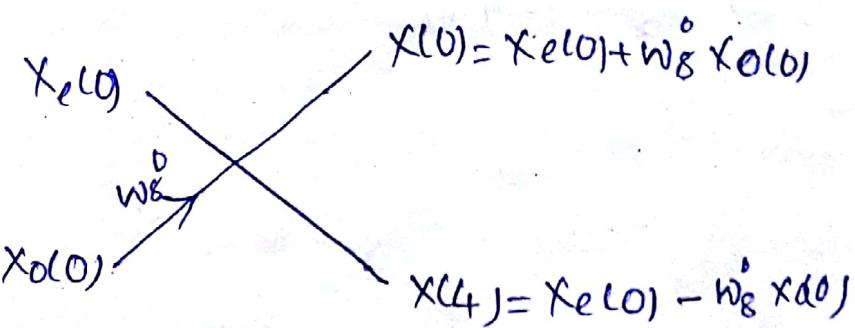
$$x(5) = x_e(0) - w_8^1 x_o(1)$$

$$x(2) = x_e(2) + w_8^2 x_o(2)$$

$$x(6) = x_e(2) - w_8^2 x_o(2)$$

$$x(3) = x_e(3) + w_8^3 x_o(3)$$

$$x(7) = x_e(3) - w_8^3 x_o(3)$$



Steps to perform radix to DIT Algorithm

- * → The no. of I/P samples $N = 2^M$ where M is ~~a~~ integer
- The I/P sequence is shuffled through bit reversal
- The no. of stages in the flow graph $m = \log_2 N$
- Each stage consists of $\frac{N}{2}$ butterflies
- I/P's or O/P's for each butterfly are separated by 2^{m-1} samples. Where m represents stage index.
for example, for 1st stage $m=1$, 2nd stage $m=2$, etc.
- The no. of complex multiplications & Additions
 $\frac{N}{2} \log_2 N$ & $N \log_2 N$ respectively.
- The twiddle factor exponents are function of stage index m , and is given by $K = \frac{NT}{2^m}$
 $t \rightarrow 0, 1, 2, 3, \dots, \frac{(n-1)q}{2^m} - 1$

$m=1$

$$K = \frac{Nt}{2^m}, \quad t=0$$

$$K = \frac{8 \cdot 0}{2^1} = 0 \quad (W_8^0)$$

$m=2$

$$K = \frac{Nt}{2^m}, \quad t=0,1$$

~~$$K=0, \quad K = \frac{8 \cdot 1}{2^2} = 2$$~~

$$W_8^0, W_8^2$$

→ The no. of sets or sections of butler files in each stage is given by the formula 2^{M-m} .

→ The exponent repeat factor which the no. of times the exponent sequence associated with m is repeated is given by 2^{M-m} .

$$2^{M-m}$$