

QUESTION

Unit-4 - IC Application and OP-Amp application

- chip size and dat complexity
- Ideal & practical op-amp, op-amp characteristics (dc, ac, slew rate, freq resp) #41 op-amp modes of operation; Inverting, non inverting and differential, op-amp application
- Basic app of op-amp - Instrumentation Amp ac amp, v to i & i to v converters, Sample and hold circuits, differentiator and integrator comparators, schmitt trigger, multivibrators and 723 voltage regulator.
- Amp & linear integrated data by Ramakant M. Graykav.
- linear circuits by Roy Chockary.

* Integrated circuit: If all the components of a circuit are fabricated on the silicon chip it is called integrated circuit (IC). They are used in computer industry, automobile, home appliances, communication and control system.

IC's offer a no. of advantages over the discrete data they are.

- The size is reduced and hence increased component density
- Cost reduction
- Increased system reliability due to elimination of soldering

→ Increased operating speeds
→ Reduction in power consumption

* Pin diagram: The function of an IC can be explained using the pin diagram

2. Classification of IC's:
- (i) Based on the no. of components & gates or the IC the IC's are classified as.
 - (ii)

Type of IC	No. of Components	Example
Small scale IC's (SSI)	< 10	Logic gates, flipflops
Medium scale IC's (MSI)	~ 100	Max, demux, decoder, encoder etc.
Large scale IC's (LSI)	100 to 1000	RAM, ROM, PLA etc.
Very large scale IC's (VLSI)	> 1000	8 bit microprocessor, 8 bit micro controller
Aint scale IC's (ASII)	> 10 ⁸	Special processor like DSP, APR, AUR, visual reality machine, SOC (System on chip)
Linear & Analog IC's		
Linear IC's are equivalent of discrete transistor networks such as amplifiers, filters, oscillators etc which requires additional components.		
Ex:- 50341, 555 timer, 723 voltage regulator.		
(iii) Based on the active devices used IC's can be classified as -		
1) Unipolar IC		
2) Bipolar IC.		
(iv) Based on the active device to design any logic chip is a transistor & BJT then it is known as		
The active device to design any logic chip is a transistor & BJT then it is known as		
Bipolar IC.		
Bipolar IC's are further classified as		
→ Dielectric isolation		
→ PN junction isolation		
If the active device in an IC is a MOSFET then the IC is known as unipolar IC		
If the active device in an IC is a JFET then the IC is known as unipolar IC		
(v) Based on the fabrication method IC's are classified as → Monolithic IC		
→ Hybrid IC		
In the monolithic IC's, all the components are formed simultaneously		
active and passive are formed simultaneously		
by a diffusion process.		
The monolithic IC's exhibit good thermal stability.		
In the hybrid IC's passive components are resistor and capacitor and the interconnects		
are made of metal wires.		
Digital IC's are complete functioning units, they are used to form ckt's as gate, inverter, mux, demux etc.		
Digital IC's have only 2 levels of voltages i.e.,		

even they are formed on an isolating sub.

Active components such as transistors, diodes or monolithic IC's are then connected to form a complete circuit.

Based on application, IC's are classified as general purpose & special purpose.

Ex:- For general purpose are OP-Amps, logic gate, special purpose are voltage regulator, audio power IC's etc.

Temperature ranges of IC's

All the IC's manufactured are classified

one of the 3 basic ranges.

Military temp range (-55°C to +125°C) (1)

Industrial temp range (-20°C to +85°C) (2)

Commercial temp range (0°C to 70°C) (3)

Q. IC Package types: - There are 3 types of

packages

Dual inline package (DIP)

Flat pack

Metal can (or) Transistor pack

Manufacturer designation for IC's

Each manufacturer has a specific code and signs a specific no. to the IC's it produces

Some of the well-known manufacturers for IC's are

Pain child : 741, 741F
National Semiconductor : LM, LHI, LF, TBA
Motorola : MC, NEC

Texas Instruments : SN
signals : L, NS, NE, SE, SU

Ex:- 741 P 0° to 70°C
MC 3400 P 0° to 70°C
L 741 P 0° to 70°C

Note:- The national semiconductor manufacturer represents nos like 1, 2, 3 for the temp. range. Here 1 - military, 2 - industrial, 3 - commercial range.

* Amplifier :-

An amplifier is an electronic device which accepts an input signal and produce an output signal proportional to the input signal i.e., $V_o \propto V_{in}$

$$V_o = A V_{in} - V_{in} \frac{V_{cc}}{R_C} \cdot V_{out}$$

* Differential amplifier:-

V_{in1}

-

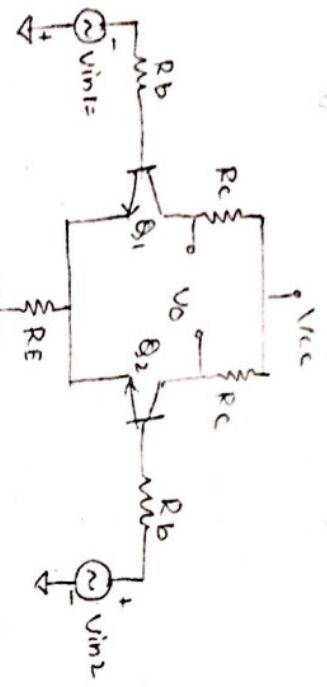
Differential v_o

V_{in2}

+

Differential v_o

Circuit diagram -



$$\text{Let } V_{in2} = 0$$

$$V_{o1} \propto -V_{in1} - \textcircled{1}$$

$$V_{o1} = -A V_{in1}$$

$$V_{in1} = 0 \Rightarrow V_{o2} \propto V_{in2}$$

$$V_{o2} = A V_{in2} - \textcircled{2}$$

By using superposition theorem.

* Common mode gain:- (AC)

So we apply 2 'op' voltages which are equal in amp to diff amplifiers i.e., $V_{in1} = V_{in2}$ then we get

$$V_{o2} = 0$$

~~so if~~ → The o/p voltage of practical differential amp.

depends not only diff voltage but also on avg common level of the 2 o/p voltages which is called common mode signal voltage (V_c) where

$$V_c = \frac{V_{in1} + V_{in2}}{2}$$

so the o/p voltage of the diff amp due to common mode signal V_c is $V_o \propto V_c$.

$$\therefore V_o = A c V_c$$

When A_c is called common mode gain

so the total o/p of any diff amp is expressed as $V_o = A_d \cdot V_d + A_c \cdot V_c$

* Differential gain:-

We define diff amp as $V_o \propto V_{in2} - V_{in1}$ i.e., $V_o \propto V_d$.

$$\therefore V_o = A_d \cdot V_d$$

↓ diff gain

$$\therefore A_d = \frac{V_o}{V_d} - \textcircled{1}$$

An amplifier which amplifies the diff b/w two signals is called differential amp. It is the basic building block of OP-AMP.

The diff amp has certain adv like excellent stability.

Summing to interface signal etc
If $V_{in2} > V_{in1} \Rightarrow V_d$ is +ve \Rightarrow non inverting amp.
 $V_{in2} < V_{in1} \Rightarrow V_d$ is -ve \Rightarrow inverting amp.

Soln:- For an ideal diff amp the diff gain A_d must be zero and common mode gain A_c must be zero.

Common mode rejection ratio:- (CMRR)

It is defined as ratio of diff voltage gain to common mode voltage gain.

$$\rho = CMRR = \left| \frac{A_d}{A_c} \right|$$

For ideal case $\rho = \infty$

$$\therefore A_c = 0$$

The o/p voltage of the diff amp V_o can be expressed in terms of CMRR as

$$V_o = A_d V_d \left[1 + \frac{A_c V_c}{A_d V_d} \right]$$

$$= A_d V_d \left[1 + \frac{1}{CMRR} \times \frac{V_c}{V_d} \right]$$

If $CMRR = 10^5$ and $A_d = 5000$ calculate A_c

$$CMRR = \left| \frac{A_d}{A_c} \right|$$

$$10^5 = \frac{5000}{A_c}$$

$$A_c = \frac{5000}{10^5 \times 10^2}$$

$$A_c = 0.05$$

$$A_c(dB) = 20 \log_{10} 0.05$$

$$A_c = -26.02 \text{ dB}$$

$$(2) \quad \text{If } V_1 = 300\mu V \text{ & } V_2 = 240\mu V \text{ } A_d = 5000, CMRR = \infty$$

Find the o/p voltage of the diff amp.

$$V_o = A_d V_d \left[1 + \frac{1}{CMRR} \times \frac{V_c}{V_d} \right]$$

$$= 5000(60) \left[1 + \frac{1}{100} \times \frac{240}{60} \right]$$

$$= 5000(60) \left[1 + \frac{1}{100} \times \frac{4}{60} \right]$$

$$= 2401$$

$$V_o = 0.313 \text{ V}$$

$$(3) \quad \text{The o/p voltage } V_o = 500 \text{ mV, } V_d = 200 \text{ mV}$$

$$V_c = 180 \text{ mV, } A_d = 4500 \text{ Find CMRR.}$$

$$A_c = \frac{V_o}{V_c} = \frac{500}{180} = 2.77$$

$$CMRR = \frac{A_d}{A_c} = \frac{4500}{2.77} = 1624.5 \text{ Sub.}$$

$$V_o = A_d V_d \left[1 + \frac{1}{CMRR} \times \frac{V_c}{V_d} \right]$$

$$500 = 4500(200) \left[1 + \frac{1}{CMRR} + \frac{180}{200} \right]$$

$$CMRR = 0.9$$

* Features of diff Amplifier-

- High diff voltage gain.
- Low common mode gain.
- High CMRR.

- High o/p impedance
- Low o/p impedance

- Large B.W. → Low offset voltages & currents

Differential Amp Configuration

Depending upon how ip signals are applied and o/p taken the diff amp are classified into 4 types

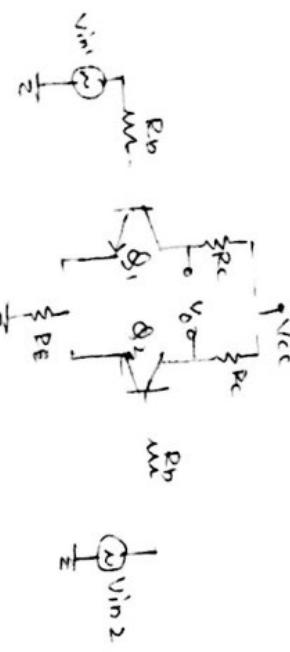
Dual ip balanced o/p

Dual ip unbalanced o/p

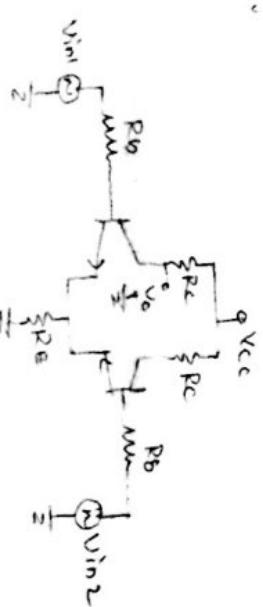
Single ip balanced o/p

Single ip unbalanced o/p

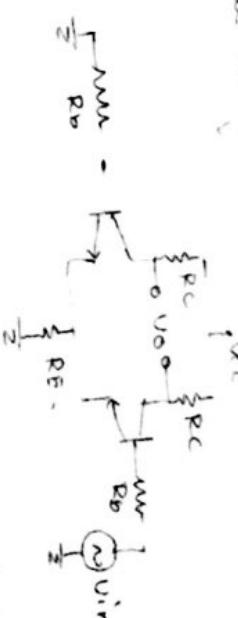
If the ip is given to two terminals it is called dual ip balanced o/p



In this configuration signal is given to both the ip terminals and the o/p is taken between collector and ground hence the name dual ip unbalance o/p



(iv) In this configuration the o/p is taken between collector and ground and the ip is given to only one terminal other terminal is grounded.



* Modes of operation of differential amplifier -

There are 2 modes of operation for diff ampl

(i) Differential mode

(ii) Common mode

In the diff mode 2 unequal ip signals are applied and their diff is amplified

In the common mode of operation either 2 equal signals are supplied or a common signal applied to ip terminals

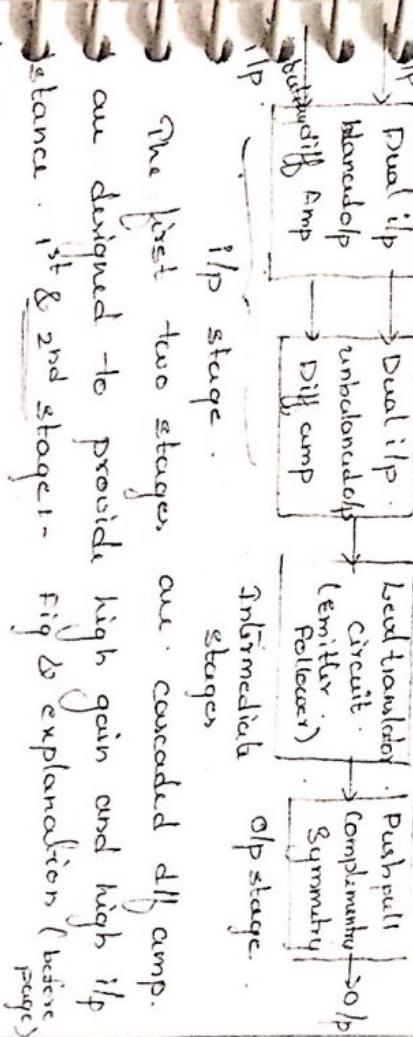
Operational Amplifier

The operational amp is a direct coupled high gain amp consisting of one or more diff amp followed by a level translator and an o/p stage.

The operational amp is also called as OP-Amp is a versatile device that can be used to amplify as well as AC i/p signals.

i) The op-amp is designed for computing mathematical operations like addition, sub, integration, differentiation and for designing log op-amp and anti-log op-amp.

Block diagram of OP-Amp :-



The first two stages are cascaded diff. amp.

are designed to provide high gain and high i/p impedance.

3rd & 2nd stages:- Fig & explanation (before page)

stage:- It acts as a buffer as well as level

buffer. It is an emitter follower circuit whose

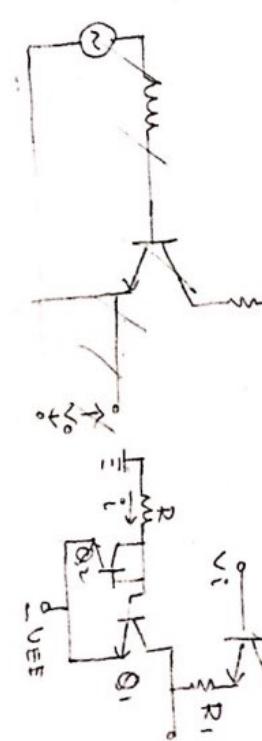
impedance is very high so that it prevents

bassing of high gain stages the level after adjustment

The dc voltages are ground as the first two stages are direct coupled.

∴ the capacitors occupy large space during its fabrication we avoid coupling capacitors.

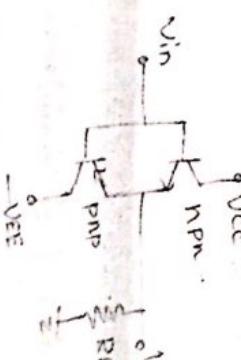
a)



b)



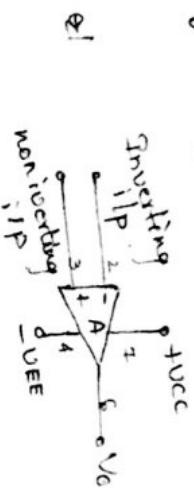
c)



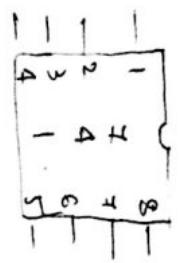
4th stage:- Finally stage is usually a push pull symmetry or push-pull comp symmetry amp.

The o/p stage increases the o/p voltage swing and raises the current supplying capability of op-amp. It also provides load o/p impedance

* Symbol of OP-Amp



* Pin diagram of OP-Amp using IC 411



It is an 8 pin DIP

5 → offset null

6 → o/p

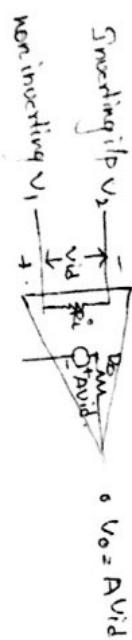
7 → +V_{CC}

8 → no connecting

- 1 → offset null
- 2 → inverting i/p
- 3 → non inverting i/p
- 4 → -V_{EE}

The power supply for op-amp 411 are $\pm 15V$

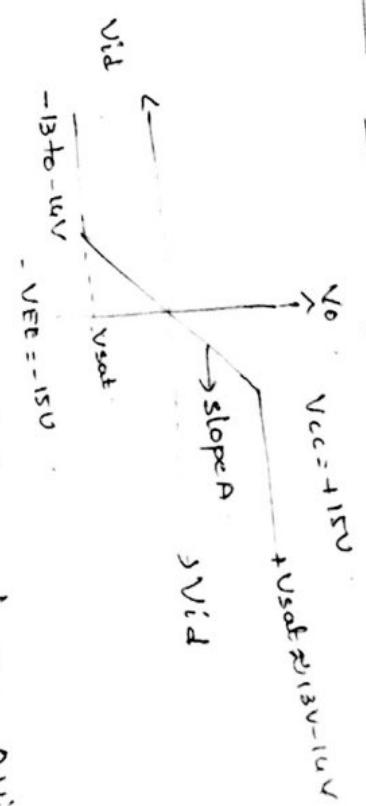
Op-Amp Equivalent circuit:



The o/p voltage for op-amp is $V_o = A(V_1 - V_2)$

where A - law of signal voltage gain

* Op-Amp ideal model



The graphical representation of $V_o = A V_{id}$ called voltage transfer curve. Here the op voltage V_o is plotted against the op diff voltage V_{id} .

keeping gain A constant

The op voltage cannot exceed $+V_{CC}$ and

sat voltages

The saturation voltages are specified by V_{id}

soing for the given supply voltages are proportional to V_{id} the op voltage is directly proportional to V_{id} until it reaches the saturation voltage and then after the op voltage remains constant the curve is called ideal voltage transfer curve because the op offset voltage of op-amp is assumed to be zero.

DC & AC characteristics of op-Amp:-

The DC characteristics of op-Amp are i/p offset voltage

and o/p offset voltage.

The input offset voltage is the voltage that must be applied b/w two i/p terminals of an op-Amp to null the o/p



$R_1 = 10k\Omega$

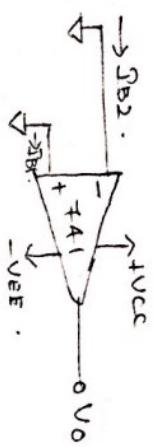
The input offset voltage is represented as V_{IO}

$$V_{IO} = V_{DC1} - V_{DC2}$$

For 741 IC the max. value of V_{IO} is 6mV.

Input offset current:-

The diff. b/w currents into the inverting and inverting terminals is referred to as.



$$I_{IO} = |I_{B1} - I_{B2}|$$

For 741 IC the I_{IO} value is 20nA.

slew rate:-

It is defined as max. rate of change of o/p

Input bias current (I_B)

The input bias current is the sum of the currents that flows into the inverting and non inverting terminals of op-Amp

$$I_B = \frac{I_{B1} + I_{B2}}{2}$$

Thermal Drift:-

Bias current, offset current and offset voltage changes with the temp. This is called thermal drift and the offset current drift is expressed as $\text{mA}/^\circ\text{C}$ and offset voltage drift is expressed as $\text{mV}/^\circ\text{C}$.

* AC characteristics:-

Gain band width product:-

It is the BW of op-Amp when voltage gain is 1. For 741 IC it is 1MHz

Large signal voltage gain:-

The voltage gain of op-Amp is given by

$$A = \frac{V_o}{V_i} \quad \text{If } R_L > 2k\Omega \text{ and } V_o = \pm 10V \text{ then}$$

A = 2 lakhs

voltage per unit of time .

$\frac{dV}{dt}$ is expressed in volts/sec.

$$SR = \frac{dV_o}{dt} \text{ v/μs}$$

For $\frac{dV_o}{dt}$ is 0.5 V/μs .

Supply voltage rejection ratio-

The change in OP-Amp's IP offset voltage by the variation in supply voltage is called supply voltage rejection ratio (SURR).

$$SURR = \frac{\Delta V_o}{\Delta V}$$

Where ΔV - change in supply voltage .

For $\frac{dV_o}{dt}$ $SR = 150 \text{ μv/V}$

Differential input resistance (R_i) :-

It is the equivalent resistance that can be measured at either the inverting or non-inverting IP terminal with the other terminal grounded .

For $\frac{dV_o}{dt}$ R_i is 2 MΩ .

Input capacitance (C_{in})

Can be measured either at inverting or non-inverting terminal with other terminal grounded .

For $\frac{dV_o}{dt}$ C_{in} is 1.4 pF

Transient Response

The transient response is based on rise time and overshoot
For $\frac{dV_o}{dt}$ the rise time is $0.3 \mu\text{s}$ and overshoot is 5% .

Output Resistance (R_o) :-

It is the equivalent resistance that can be measured between op-amp output and ground .

For $\frac{dV_o}{dt}$ it is 45 Ω

Supply current - current drawn by the OP-AMP

from power supply (I_S) .

For $\frac{dV_o}{dt}$ it is 2.8 mA

Power Consumption - (P_c) It is the dissident power ($V_{DD} \cdot I_S$) that must be consumed by OP-AMP to operate properly

For $\frac{dV_o}{dt}$ it is 0.6 mW

char	value for $\frac{dV_o}{dt}$	char	value for $\frac{dV_o}{dt}$
Input offset voltage (V_{io})	6mV	Gain	$SR = 0.5 \text{ V/μs}$
Input offset current (I_{io})	200nA	Supply voltage rejection ratio	$SURR = 150 \text{ μv/V}$
Input bias current $I_B = \frac{I_{io}}{2}$	100nA	Differential resistance $R_i = 2 \text{ MΩ}$	
Thermal Drift in $\text{mV/}^\circ\text{C}$	$0.3 \text{ mV/}^\circ\text{C}$	IP capacitance $C_{in} = 1.4 \text{ pF}$	
Gain error product $A = 2 \text{ MΩ}$	10^{-13}	Transient resp. $0.3 \mu\text{s}$, 5%	
Intrinsic noise u-v gain	0.1 nV/Hz	Supply current $I_S = 2.8 \text{ mA}$	

Ideal Op-Amp Characteristics 1.

The ideal op-amp has the following characteristics

Infinite gain

Infinite input resistance (R_i) so that any signal source can drive it and thus is no loading of preceding stage.

Zero output resistance.

Zero output voltage when input voltage is zero.

Infinite B.W.

Infinite current.

Infinite slew rate.

A non inverting Amp with a gain of 100 is null at $25^\circ C$. What will happen to the output voltage if temp rises to $50^\circ C$ for an offset voltage drift of $0.15 \mu V/C$.

$$A = 100 \text{ at } 25^\circ C \quad \text{Op-P} = 0$$

$$\text{Voltage drift} = 0.15 \mu V/C \text{ at } 25^\circ C$$

For $-25^\circ C$ case

$$25^\circ C \text{ Per } 1^\circ C - V_{IO} = 0.15 \mu V/C$$

$$50^\circ C - V_{IO} = (50 - 25) \times 0.15 \mu V/C$$

$$= 3.75 \mu V$$

$$V_{OS} = A \cdot V_{IO}$$

$$= 100 \times 3.75 \mu V$$

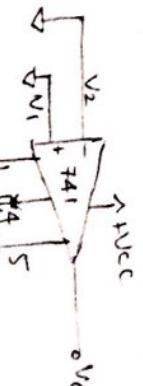
$$= 375 \mu V$$

For 741 IC the pins 1&5 are used to null the offset voltage a potentiometer is placed b/w 1&5 and wiper of potentiometer is connected to V_{REF} As the wiper of potentiometer is charged the op-amp

(2) The op-p of an op-amp voltage follower is a sine wave form with P-P amp of $6V$ and $T = 0.5 \mu s$. For an op-p of square wave with BULP-Pamp and $2MHz$ freq. what is the slew rate of the op-amp.

$$SR = \frac{dV_O}{dt} = \frac{6}{0.5 \times 10^{-6}} = 12V/\mu s$$

$$SR = \frac{60}{25} = 2.4V/\mu s$$



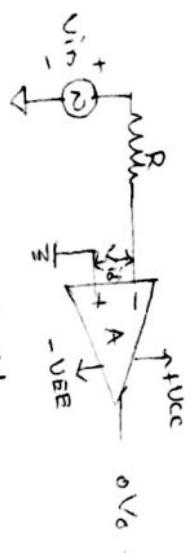
voltage can be reduced to 0V

~~Open loop OP-Amp Configuration~~

The OP-Amp is having 3 open loop config.

- i) Inverting Amp
- ii) Non-inverting amp
- iii) Differential Amp

* Inverting Amp:-



$$\begin{aligned} V_o &= A_{vid} \\ &= A(V_1 - V_2) \end{aligned}$$

From above eqn. $V_1 = 0$, $V_2 = V_{in}$

$$\Rightarrow \boxed{V_o = -AV_{in}}$$

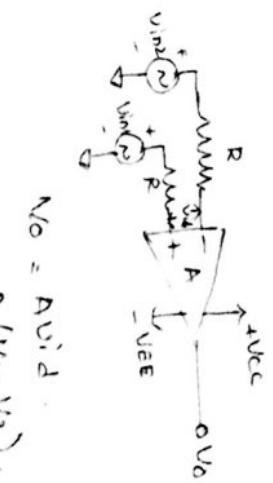
Assume $A = 1$.

$$V_o = -V_{in}$$

In inverting amps. the o/p voltage is 180° out of phase with the i/p voltage.

i. Open loop gain $A = -\frac{V_o}{V_{in}}$

* Non-inverting Amp:-



$$\begin{aligned} V_o &= A_{vid} \\ &= A(V_{in1} - V_{in2}) \\ V_o &= A \cdot V_d \\ A &= \frac{V_o}{V_d} \end{aligned}$$

* Cloud loop Configuration:-

In the cloud loop configuration a load is used along with the OP-Amp. For Amplifying out put is used along with the OP-Amp. For Amplifying output is used. There are 3 types

- (i) Inverting amp with feedback
- (ii) Non-inverting amp with feedback
- (iii) Differential amp with feedback

$$V_o = A_{vid} = A(V_1 - V_2)$$

$$\text{Here } V_1 = V_{in}, V_2 = 0 \therefore V_o = A V_{in}$$

$$A = \frac{V_o}{V_{in}}$$

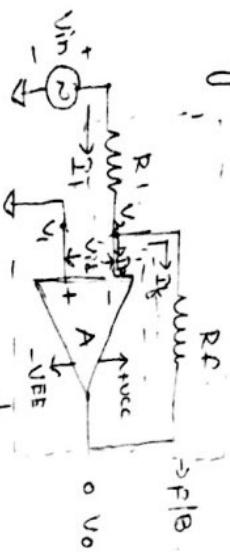
For non inverting amps the o/p voltage is in phase with i/p voltage.

* Differential Amplifier:-

- i) Inverting Amp
- ii) Non-inverting amp
- iii) Differential Amp

- i) Inverting Amp
- ii) Non-inverting amp
- iii) Differential Amp

Inverting Amp:-



$$A = \frac{V_o}{V_i}$$

$$A_F = \frac{V_o}{V_{in}}$$

By using KCL at node $\Sigma_1 = \Sigma_B + \Sigma_f \rightarrow (1)$

"OP-AMP is having very high input resistance $\Sigma_{B>0}$ "

$$\therefore \Sigma_1 = \Sigma_f \rightarrow (2)$$

$$\frac{V_{in} - V_2}{R_1} = \frac{V_2 - V_o}{R_F} \rightarrow (3)$$

Virtual ground:-

$$A = \frac{V_o}{V_{id}}$$

$A = \infty$ for ideal OP-AMP

$$\Rightarrow V_{id} = 0$$

$$\Rightarrow \boxed{V_1 = V_2}$$

But $V_1 = 0$

$\therefore V_2 = 0$ (virtual ground)

By using virtual ground sub $V_2 = 0$ in (3)

$$(3) \Rightarrow \boxed{A_F = \frac{V_o}{V_{in}} = -\frac{R_F}{R_1}}$$

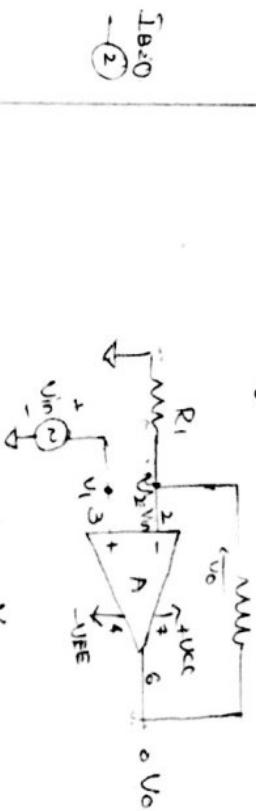
$$\boxed{A_F = -\frac{V_o}{V_{in}} = -\frac{R_F}{R_1}}$$

Virtual ground:-

For an ideal OP-AMP gain in as given mean the diff of two voltages $V_{id} = 0 \Rightarrow V_1 = V_2$

In inverting amp since $V_1 = 0$ then the node V_2 will also be equal to zero which makes V_2 to act as a ground even though it is not ground. Hence can we call it as virtual ground.

* Non inverting Amp:-



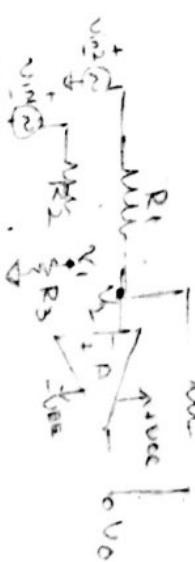
$$A_F = \frac{V_o}{V_{in}}$$

By using voltage divider rule

$$V_{in} = \frac{R_1}{R_1 + R_2} \times V_{o}$$

$$A_F = \frac{V_o}{V_{in}} = \frac{R_1 + R_2}{R_1}$$

* Differential Amp:-



$$R_1 = R_2 = R_3 = R_F = R$$

By using superposition theorem

$$V_o = V_{o1} + V_{o2}$$

If. $V_{in2} = 0V$ then

$$V_1 = V_{in1} \times \frac{R_F}{R_2 + R_3} - \textcircled{1} \quad (\text{Voltage division})$$

But AF-for non inverting amp is

$$1 + \frac{R_F}{R_1}$$

$$V_{o1} = AF V_1$$

$$\therefore V_{o1} = \left(1 + \frac{R_F}{R_1}\right) \times \frac{R_3}{R_2 + R_3} \times V_{in1} - \textcircled{2}$$

$$\left\{ \begin{array}{l} V_{in1} = 0 \\ V_{in2} = 0 \end{array} \right.$$

$$V_{o2} = -\frac{R_F}{R_1} \times V_{in2} - \textcircled{3}$$

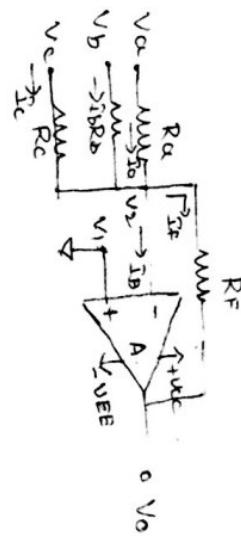
$\sim \frac{R_F}{R_1}$ for inverting amp

$$V_o = (1 + \frac{R_F}{R_1}) \times V_{in1} - 1 \times V_{in2}$$

$$\boxed{V_o = V_{in1} - V_{in2}}$$

Note:- If all the resistor values $R_1 = R_2 = R_3 = R_F = R$ we same then the diff amp with feed back config. works as a subtractor.

Summing, scaling and averaging amp in inverting configuration:-



From virtual ground concept $\therefore V_{in1} = 0$

$$\Rightarrow V_2 = 0$$

$$\textcircled{3} \Rightarrow \frac{V_a}{R_a} + \frac{V_b}{R_b} + \frac{V_c}{R_c} = -\frac{V_o}{R_F}$$

$$V_o = -R_F \left(\frac{V_a}{R_a} + \frac{V_b}{R_b} + \frac{V_c}{R_c} \right) - \textcircled{4}$$

$$\text{Case(i)}:- \quad \text{If } R_a = R_b = R_c = R_F = R$$

$$\textcircled{4} \Rightarrow V_o = -(V_a + V_b + V_c) \rightarrow \text{Summing amp}$$

Added

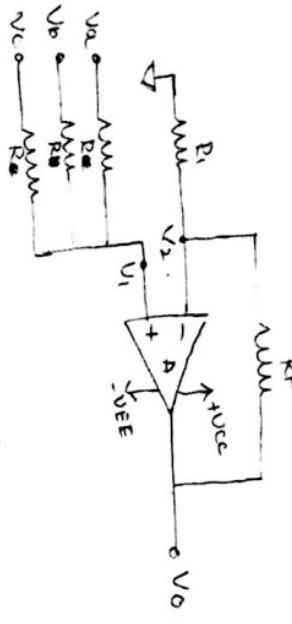
$$\text{Case(ii)}:- \quad \text{If all resistances are diff. Weighing amp}$$

$$\textcircled{4} \Rightarrow V_o = -\left(\frac{R_F}{R_a} V_a + \frac{R_F}{R_b} V_b + \frac{R_F}{R_c} V_c\right) \rightarrow \text{Scaling}$$

$$\text{cond(iii)} : \quad \text{if } R_A = R_B = R_C = \frac{R_F}{3} \rightarrow n = 3$$

$$\textcircled{2} \Rightarrow V_o = -\left(\frac{V_a + V_b + V_c}{3}\right) - \text{averaging amp}$$

Summing, scaling and averaging amp using non-inverting amp.



$$\Rightarrow V_o = \left(1 + \frac{R_F}{R_1}\right)V_a$$

$$V_{out} = V_a \times \frac{R_1/2}{R + R_1/2}$$

by for V_b & V_c .

By using superposition theorem

$$V_i = V_a \times \frac{R_1/2}{R_1 + R_1/2} + V_o \times \frac{R_1/2}{R_1 + R_1/2} + V_c \times \frac{R_1/2}{R_1 + R_1/2} \quad \textcircled{1}$$

For non-inverting configuration $V_o = \left(1 + \frac{R_F}{R_1}\right)V_i$

$$\Rightarrow V_o = \left(1 + \frac{R_F}{R_1}\right) \left(\frac{R_1/2}{R_1 + R_1/2} (V_a + V_b + V_c) \right) + \textcircled{2}$$

$$V_o = \frac{1}{3} \left(1 + \frac{R_F}{R_1}\right) (V_a + V_b + V_c) \quad \textcircled{2}$$

$$\text{cond(i)-} \quad \text{if } R_F = 2R_1 \text{ then}$$

$$V_o = V_a + V_b + V_c \rightarrow \text{Adder}$$

$$\int R_F = R_1 \text{ then}$$

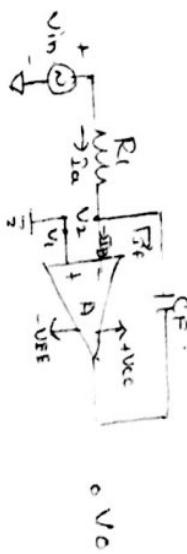
$$V_o = \frac{2}{3} (V_a + V_b + V_c) \rightarrow \text{scaling}$$

cond(ii)- if gain is unity of non-inverting amp

$$V_o = \frac{V_a + V_b + V_c}{3}$$

→ Averaging amp.

* Integrator:



Apply KCL at node V_2 .

$$\text{I}_A = \text{I}_F + \text{I}_B$$

$$\Rightarrow \text{I}_A = \text{I}_F + \frac{V_o}{R_1}$$

$$\Rightarrow \frac{V_{in} - V_2}{R_1} = \frac{d(V_2 - V_o)}{dt} C_F$$

From virtual ground $V_2 = 0$

$$\frac{V_{in}}{R_1} = -C_F \frac{dV_o}{dt}$$

$$V_o = -\frac{1}{R_1 C_F} \int V_{in} dt \quad \textcircled{1}$$

It is used as a wave shaping device, measure form

generator and in A.D.C

$$f = \frac{1}{2\pi R_C C_F}$$

$$V_o = -1000 \text{ mV} = -1.8 \text{ V}$$

$$\int_{0}^{0.2} 1 dt = -2000 \text{ mV} = -2 \text{ V}$$

$$V_o = \frac{-1}{100 \times 10^{-9}} \int_{0}^{0.3} 1 dt = -3000 \text{ mV}$$

$$= -3 \text{ V}$$

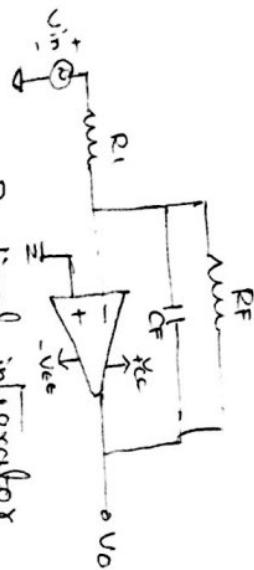
Q3.11 For Q) Apply L.T

$$V_o(s) = \frac{-1}{R_C C_F} \cdot \frac{V_{in}(s)}{s}$$

$$\text{gain} = \frac{V_o(s)}{V_{in}(s)} = \frac{-1}{R_C C_F j \omega} = \frac{-2\pi R_C F}{R_C C_F j 2\pi f}$$

$$A = \frac{-1}{2\pi f R_C C_F}$$

At low frequencies the integrator circuit acts as a open loop circuit hence gain becomes \propto which decreases the stability. Hence in practical a resistor R_F is placed capacitor C_F .



Practical integrator

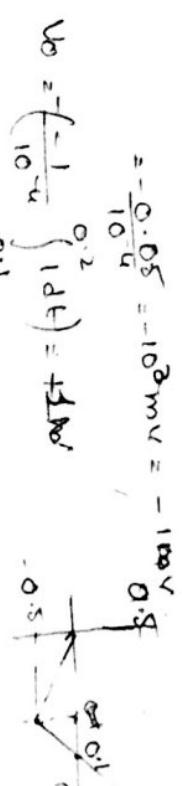
Q3) For a non inverting amp. The gain should be unity design a circuit for this consideration.

$$A_F = 1 + \frac{R_F}{R_1}$$

R_F - shorted, R_1 - open.



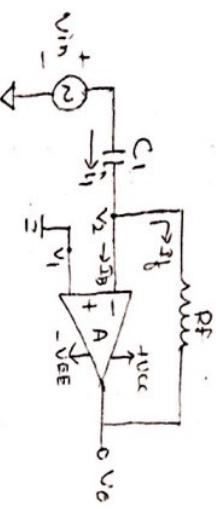
$A_F = 1$



thus is called as voltage follower.

$$V_o = \frac{-1}{10 \times 10^3 \times 10^{-9}} \int_{0}^{0.3} 1 dt$$

Differentiator

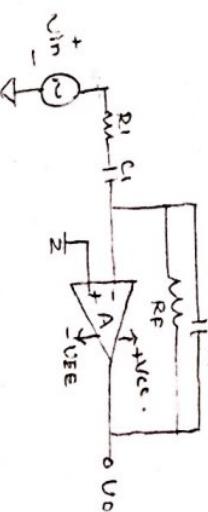


Applying KCL at node v_2 .

$$i_1 = \text{I}_B + \text{I}_F \quad \text{I}_B = 0$$

$$C_1 \frac{d(v_{in} - v_2)}{dt} = \frac{v_2 - v_o}{R_F}$$

From virtual ground concept $v_2 = 0$



$$C_1 \frac{d(v_{in})}{dt} = -\frac{v_o}{R_F}$$

$$\boxed{v_o = -C_1 R_F \frac{d(v_{in})}{dt}} \quad \textcircled{1}$$

Applying L.T for $\textcircled{1}$

$$V_o(s) = -C_1 R_F [V_{in}(s)] s$$

$$= -C_1 R_F j\omega [V_{in}(s)]$$

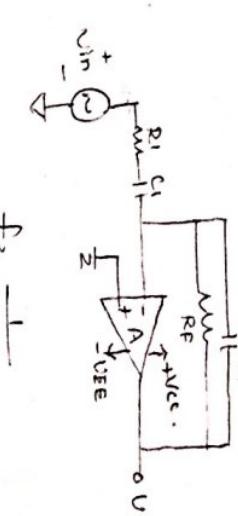
$$V_o(s) = -C_1 R_F j\omega f \cdot V_{in}(s)$$

$$A = \frac{V_o(s)}{V_{in}(s)} = -C_1 R_F 2\pi f$$

As freq \uparrow gain \uparrow so it is called as high pass

As the frequency increases the gain increases over 20 dB/decade which causes instability of the circuit and also the impedance of the capacitor decreases with increase in frequency hence for a practical diff a resistor R_i is added across ip and capacitor C_F is placed in the feed back ckt

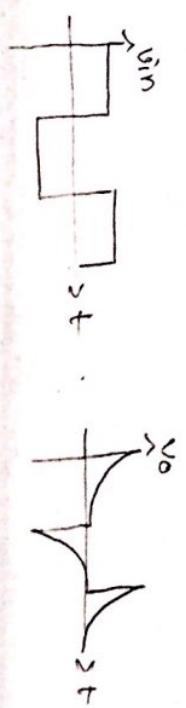
Practical differentiator



If the ip for diff is sine wave the op is cosine



If ip for diff is a square waveform then at $R_C \neq t$ we get spikes as an op.



① Find the o/p for a differentiator with $f_2 = 100\text{Hz}$

$C_1 = 0.1\mu\text{F}$ for a sine wave of 10 peak

$$f_2 = \frac{1}{2\pi C_1 R_F}$$

$$R_F = \frac{1}{2\pi \times 0.1 \times 10^{-6} \times 100} = 15.9 \text{ k}\Omega$$

$$\text{Apply L.T}$$

$$C_1 \text{ s } V_{in(s)} \rightarrow V_{in(s)} = -\frac{V_o(s)}{R_F}$$

$$(C_1 s + \frac{1}{R_F}) V_{in(s)} = -\frac{V_o(s)}{R_F}$$

$$\frac{V_o(s)}{V_{in(s)}} = -\left(\frac{C_1 s + \frac{1}{R_F}}{R_F}\right)$$

$$= -\frac{R_F}{R_F} \left[1 + \frac{1}{s C_1 R_F} \right]$$

$$V_o = -C_1 R_F \frac{dV_{in}}{dt}$$

$$= -0.1 \times 10^{-6} \times 15.9 \times 10^3 \frac{dV_{in}}{dt} \sin 2\pi f t$$

$$= -0.0016 \times 200 \pi \cos 2\pi f t$$

$$= -0.99 \cos 2\pi f t$$

$$\approx -1 \cos 2\pi f t$$

$$(R + \frac{1}{sC_1}) \Sigma_1 = \Sigma_F \Rightarrow \frac{V_{in} - V_2}{R + \frac{1}{sC_1}} = \frac{V_2 - V_o}{R_F}$$

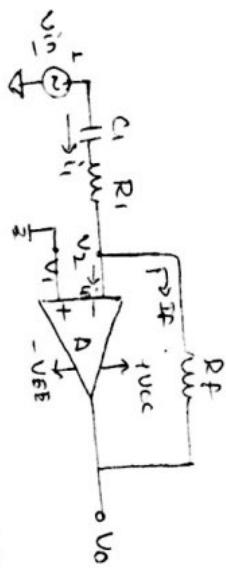
$$\frac{V_{in}}{R + \frac{1}{sC_1}} = -\frac{V_o}{R_F}$$

$$\Rightarrow V_o = -R_F V_{in} / (R + \frac{1}{sC_1})$$

$$A = -R_F / (R + \frac{1}{sC_1})$$

$$\boxed{A = -\frac{R_F}{R} \times \frac{1}{1 + \frac{1}{sC_1 R}}}$$

* AC Amplifier:-



Inverting AC amplifier

In a no. of industrial and consumer applications there is need to measure and control physical quantities, such as control of temp., measuring of intensity, water flow etc. These physical quantities are measured with the help of transducers.

transducer is a device which converts one form of energy into another. The output has transducer

$$C_1 \text{ s } V_{in} + \frac{V_{in}}{R_F} = -\frac{V_o}{R_F}$$

$$V_2 = 0$$

as to be simplified so that it can drive the indicator or display system. This function is performed by an instrumentation amp. The features of instr.

The * Instrumentation Amp using transducer bridge -
performed

卷之三

high gain accuracy

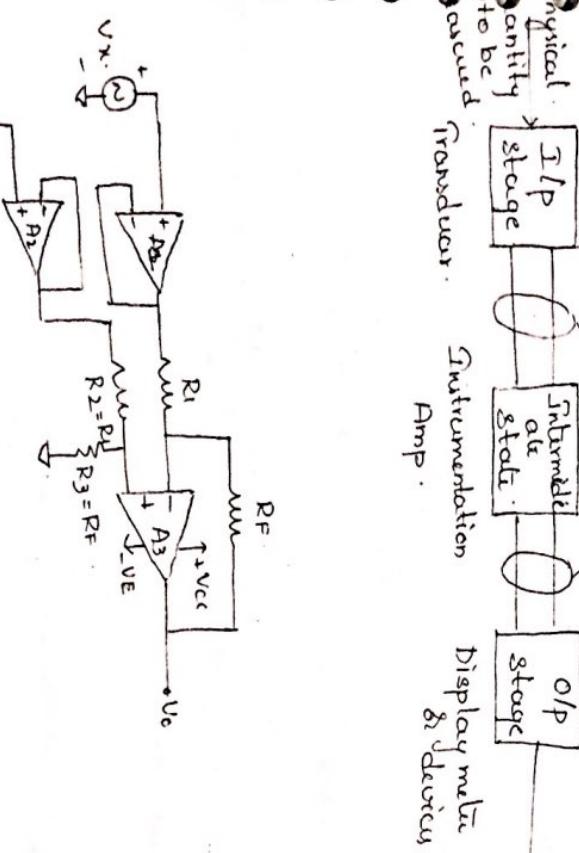
~~high~~ CHRR.

high gain stability with low lump cost

卷之三

卷之三

transmision
linea



```

graph TD
    A[Physical quantity] --> B[Input stage]
    B --> C[Intermediate stage]
    C --> D[Output stage]
    D --> E[Display device]
    F[Amp.] --- B
    G[Instrumentation Amp.] --- C
    H[Output device] --- D
  
```

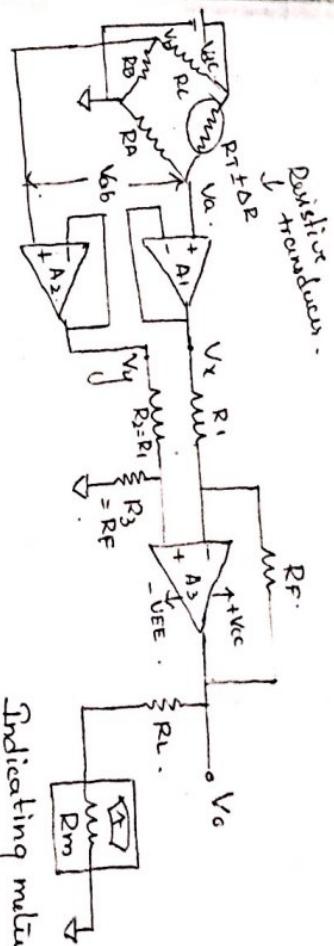
In the above circuit a resistive transducer i.e., the resistance changes as a function changes if some physical energy is connected in one arm of the bridge with a small circle around it.

$$\Rightarrow \frac{V_{AC} \cdot \frac{R_A}{R_A + R_f}}{R_B + R_f} = \frac{V_{AC} \cdot \frac{R_B}{R_B + R_C}}{R_A + R_C}$$

二

Instrumentation Amplifier

∴ V_a & V_b voltages are given to op-amp
 $A_3 \cdot V_o = -\frac{R_F}{R_1} V_{ab}$ —①



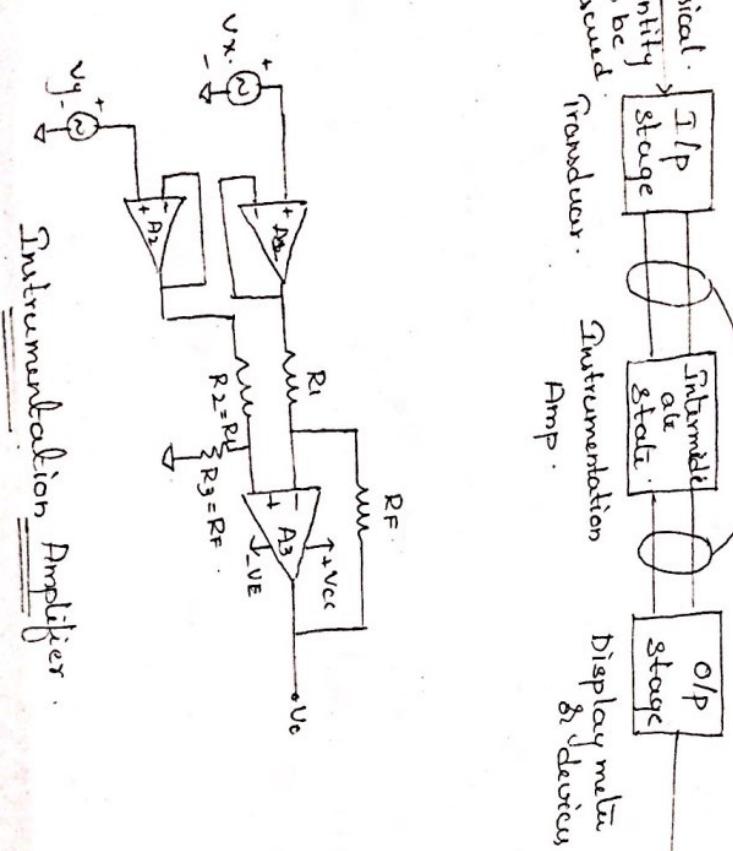
has to be amplified so that it can drive the indicator & display system. This function is performed by an instrumentation amp. The features of instr.

- umplementation and - use

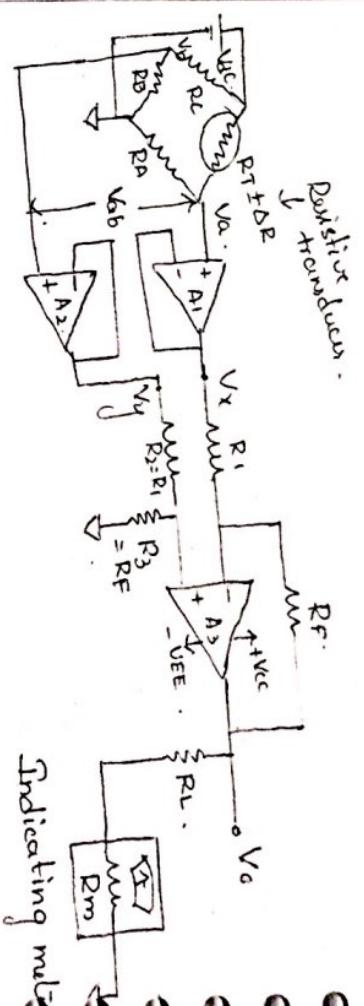
→ high gain accuracy

- high curr.
- high gain stability
- low dc offset voltage
- low op impedance.

Transmission
linus



In the above case a resistive transducer i.e., the resistance changes as a function changes if some physical energy is connected in one arm of the bridge with a small circle around it.



$$\Rightarrow \frac{V_{AC} \cdot R_A}{R_A + R_I} = \frac{V_{AC} \cdot R_B}{R_B + R_C}$$

If V_a & V_b voltages are given to OP-AMP

$$A_3 \text{ then } V_o = -\frac{R_F}{R_1} V_{ab} - ①$$

∴ thus is a change in resistance due to some
then $V_{ab} = V_a - V_b$.

$$V_a = \frac{R_A}{R_A + R_1 \pm \Delta R} V_{dc} \quad V_b = \frac{R_B}{R_B + R_C} \times V_{dc}$$

$$V_{ab} = \left(\frac{R_A}{R_A + R_1 \pm \Delta R} - \frac{R_B}{R_B + R_C} \right) V_{dc}$$

$R_A = R_B = R_C = R_1 = R$. thus.

$$V_{ab} = \left(\frac{R}{2R \pm \Delta R} - \frac{R}{2R} \right) V_{dc}$$

$$= \frac{2R^2 - (2R^2 \pm \Delta R \cdot R)}{2R(2R \pm \Delta R)} V_{dc}$$

$$= \frac{\mp \Delta R \cdot R}{4R^2 \pm \Delta R} V_{dc}$$

$$V_{ab} = \frac{\mp \Delta R}{2(2R \pm \Delta R)} \times V_{dc}$$

$$V_o = -\frac{R_F}{R_1} \times V_{ab}$$

$$V_o = -\frac{R_F}{R_1} \times \frac{\mp \Delta R}{2(2R \pm \Delta R)} V_{dc}$$

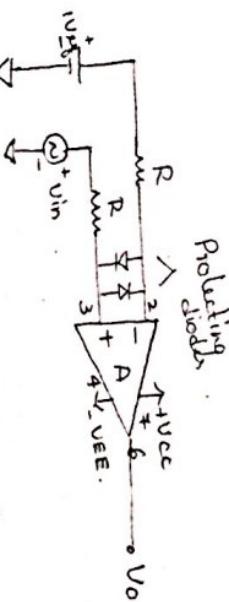
Change in resistance value of transducer is very small i.e., $2R \pm \Delta R \approx 2R$.

$$\therefore V_o = \frac{R_F}{R_1} \frac{\mp \Delta R}{2(2R)} V_{dc}$$

This eq indicates & ΔR of the transducer if ΔR is caused by a change in physical energy the meter connected at the o/p can be calibrated

SOL || COMPARTOR

Comparitor

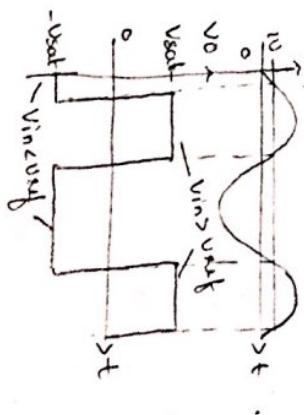


non-inverting Comparitor:

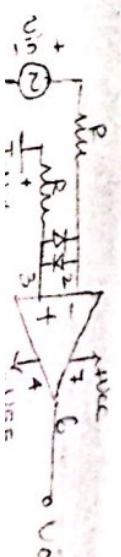
A comparitor as its name implies compares a signal voltage on one ip of an op-amp with any known voltage V_{ref} on another ip.

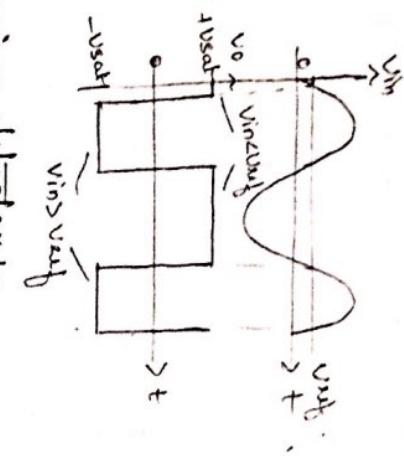
It operates in open loop configuration. Hence the o/p will be $+V_{sat}$ & $-V_{sat}$.
Comparitor also can used in digital interfacing, schmitt trigger, voltage level detector etc..

$V_o = \frac{R_F}{R_1} \times V_{ab}$



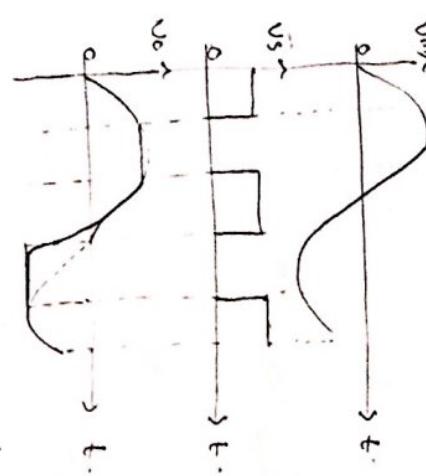
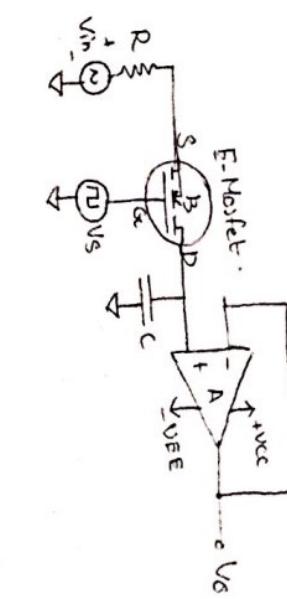
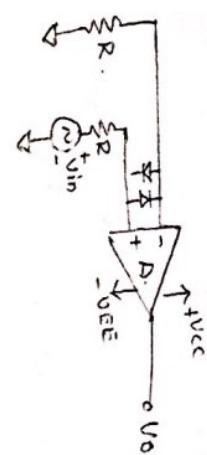
Inverting Comparitor





* Zero crossing detector

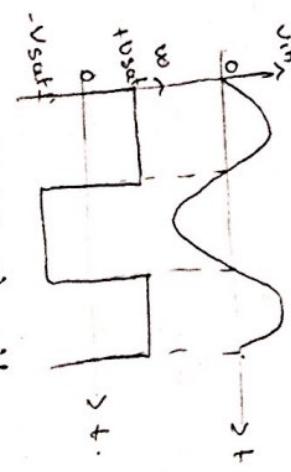
An application of comparator is. Zero crossing detector or sine wave to square wave converter.



And the capacitor C as a storage element. The input voltage V_{in} is applied to source and V_s is applied to gate of the MOSFET. During the $+ve$ part of V_s the F-MOSFET conducts and acts as a switch which allows ' c ' to be charged and the op-amp goes to the $-ve$ since the OP-AMP is in voltage follower mode. When $V_s = 0$ MOSFET is off and acts as an open switch the only discharge path for C is open but the imp resistance of the OP-AMP is very high hence voltage across ' c ' is retained. When $V_s < 0$

* Sample and Hold circuit

The sample & hold ckt as its name implies samples an inp signal and holds on its last sampled value until the inp is sampled again. In this ckt the E-MOSFET works as a switch controlled by V_s .



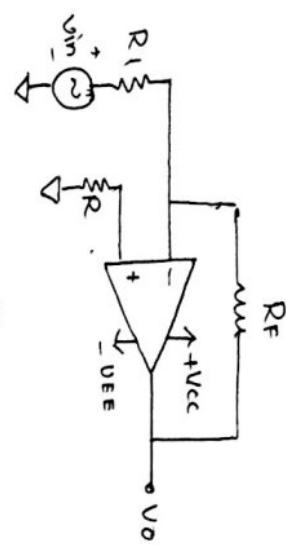
The sample & hold ckt as its name implies samples an inp signal and holds on its last sampled value until the inp is sampled again. In this ckt the E-MOSFET works as a switch controlled by V_s .

then MOSFET is on. Output voltage can be obtained. The time period T_S during which the voltage across 'C' is equal to 'ip' voltage, are called sample period. The period T_S during which current source 'i' is connected is called hold period.

* V to I Converter:-

When MOSFET is on, output voltage can be obtained. The period T_S during which the voltage across 'C' is equal to 'ip' voltage, are called sample period. The period T_S during which current source 'i' is connected is called hold period.

I to V Converter:-

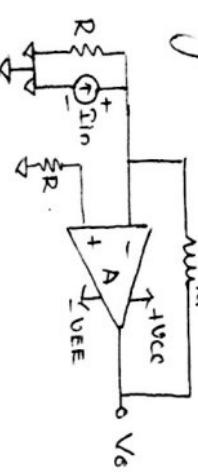


$$V_o = -\frac{R_f}{R_l} \times V_{in}$$

$$\begin{aligned} &\text{Apply KCL at node 1} \\ &\Rightarrow \Omega_1 + \Omega_2 = \Omega_L \\ &\Rightarrow \frac{V_{in} - V_1}{R} + \frac{V_o - V_1}{R} = \frac{\Phi + X_f - \Phi}{R} \Omega_L \\ &\boxed{V_o = 1 + \frac{R_f}{R_l} \times V_1} \\ &\Rightarrow V_{in} + V_o - 2V_1 = \Omega_L R \\ &\Rightarrow V_1 = -\frac{\Omega_L R + V_{in} + V_o}{2} \end{aligned}$$

$$V_o = \left(1 + \frac{R_f}{R_l}\right) \times \frac{V_{in} + V_o - \Omega_L R}{2}$$

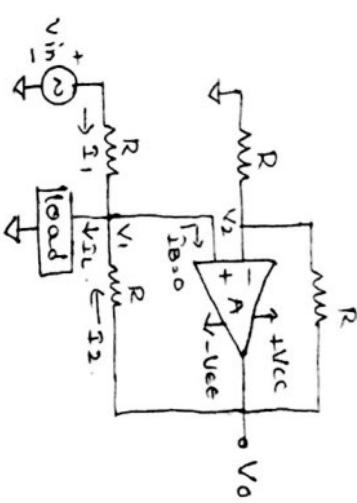
$$V_o = \left(1 + \frac{R_f}{R_l}\right) \left(\frac{V_{in} + V_o - \Omega_L R}{2}\right)$$



Hence, for inverting amp. If the voltage $\frac{V_{in}}{R_l}$ is replaced by current source, then $V_o \propto I_{in}$.

$$V_o = \left(1 + \frac{R_f}{R_l}\right) \left(\frac{V_{in} + V_o - \Omega_L R}{2}\right)$$

$$\boxed{\Omega_L = \frac{V_{in}}{R}}$$

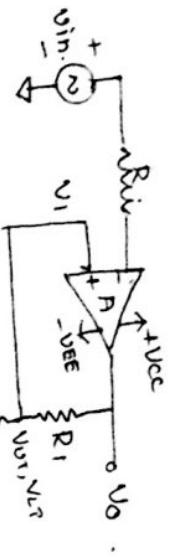


$V_{in} - V_1 - V_o = 0$

$$V_1 = -\frac{\Omega_L R + V_{in} + V_o}{2}$$

$$V_o = \left(1 + \frac{R_f}{R_l}\right) \left(\frac{V_{in} + V_o - \Omega_L R}{2}\right)$$

Schmitt trigger:-



A schmitt trigger is also known as regenerative comparator. And it converts any irregular shape wave form into square wave. For the schmitt trigger the loop gain A_P is considered > 1 .
The op-amp voltage V_{in} triggers (changes the state) the op-amp every time it exceeds certain voltage called upper threshold & lower threshold. These threshold voltages are obtained by voltage divider circuit R_1 & R_2 . If $V_o = +V_{sat}$ the voltage across R_1 is called upper threshold voltage.

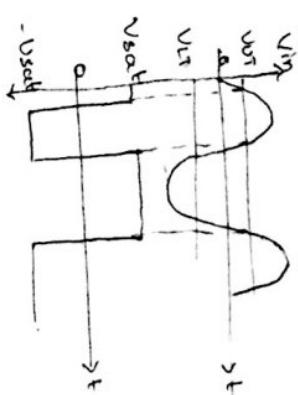
$$V_{out} = V_{sat} \cdot \frac{R_2}{R_1+R_2} - \frac{V_{sat}}{\frac{R_1}{R_1+R_2}} \quad (1)$$

When the op-amp voltage V_{in} becomes more than the op-amp triggers from $+V_{sat}$ to $-V_{sat}$ then the voltage across R_1 is called lower threshold voltage when V_{in} becomes more $-ve$ than V_{LT} then the op-amp triggers from $-V_{sat}$ to $+V_{sat}$

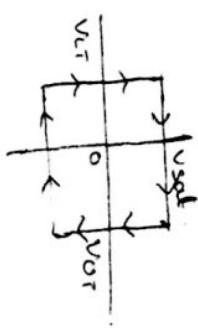
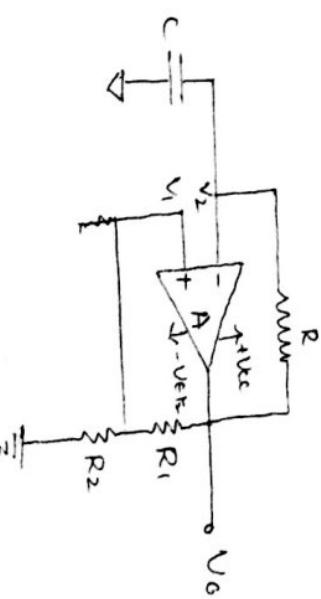
$$V_{LT} = V_{sat} \cdot \frac{R_1}{R_1+R_2}, \quad V_{sat} \cdot \frac{R_2}{R_1+R_2} \quad (2)$$

Because of the +ve feedback the op-amp switches from $+V_{sat}$ to $-V_{sat}$ and vice versa.
The hysteresis voltage is diff b/w V_{LT} & V_{HT} .

$$\text{From } (1) \& (2) \quad V_H = \frac{2 V_{sat} R_2}{R_1+R_2}$$



* Astable Multivibrator:-



The astable multivibrator is also known as free running (or) square wave generator. The square wave (op-amp generated when the op-amp is forced to operate in saturation region).

The o/p of op-amp in this ckt will be $+V_{sat}$ or $-V_{sat}$ depending on diff voltage V_{id} .

Initially because of offset voltage at non inverting terminal let $V_o = +V_{sat}$ then voltage at $V_1 = \frac{R_2}{R_1+R_2} V_o$

$$\text{At } \frac{R_2}{R_1+R_2} = \beta, V_o = V_{sat}$$

\downarrow

$$V_1 = \beta V_o$$

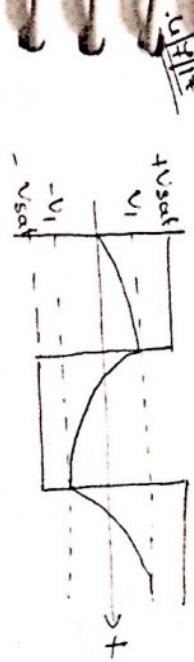
then through the resistor R the capacitor starts charging the voltage across the C appears at V_2 .

Then the capacitor charges more than V_1 i.e.,

$V_2 > V_1$, then the o/p changes from $+V_{sat}$ to $-V_{sat}$

then the voltage at $V_1 = V_{op}$. then the voltage across C starts discharging when the voltage becomes more than V_1 then the o/p changes from $-V_{sat}$ to $+V_{sat}$.

The time period of wave form that is generated from the o/p is obtained by using voltage across the capacitor over time period.



The voltage across capacitor

$$V_C = V_b + (V_i - V_b) e^{-t/RC} \quad \textcircled{1}$$

$$V_p = +V_{sat}, V_{in} = -\beta V_{sat} \quad \textcircled{2}$$

Sub ② in ①

$$V_C = V_{sat} + (-\beta V_{sat} - V_{sat}) e^{-t/RC}$$

$$= V_{sat} - (1+\beta) V_{sat} e^{-t/RC}$$

$$|Y_C = \frac{V_{sat}}{R C e^{-t/RC}}|. \quad \textcircled{3}$$

$$\text{At } t = T_1 \quad V_C(t) = +\beta V_{sat} - V_{sat}$$

Sub ⑤ in ③

$$\Rightarrow \beta V_{sat} e^{(1+\beta)T_1} = -V_{sat} e^{-T_1/RC} + V_{sat}$$

$$\Rightarrow -\beta = e^{\frac{T_1}{RC}}$$

$$\Rightarrow -\beta \approx 4 \quad T_1 = RC \ln \left(\frac{1+\beta}{1-\beta} \right)$$

$$\Rightarrow T = 2T_1$$

$$\Rightarrow T = 2RC \ln \left(\frac{1+\beta}{1-\beta} \right) \quad \textcircled{5}$$

$$\text{Wkt } \beta = \frac{R_2}{R_1+R_2} \quad \textcircled{6}$$

Sub ⑥ in ⑤

$$\Rightarrow T = 2RC \ln \left(\frac{1+2R_2}{R_1} \right)$$

$$\frac{R_2+2R_2}{R_1} = \frac{1+2\frac{R_2}{R_1}}{1+\frac{R_2}{R_1}}$$

$$\Rightarrow R_2 = R_1$$

$$\Rightarrow T = 2RC \ln(3)$$

$$\boxed{T = 2.197 RC}$$

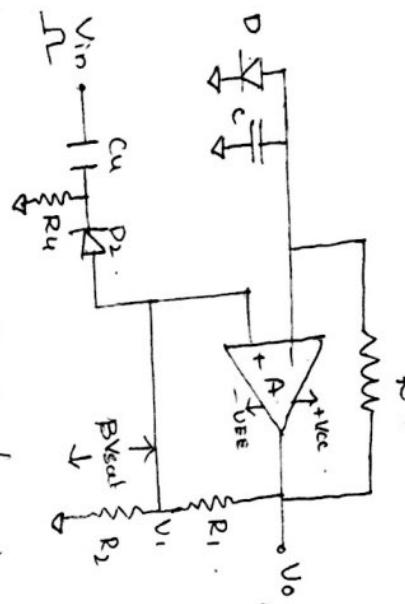


$$\text{If } R_1 = 1.16 R_2 \text{, then}$$

$$T = 2RC$$

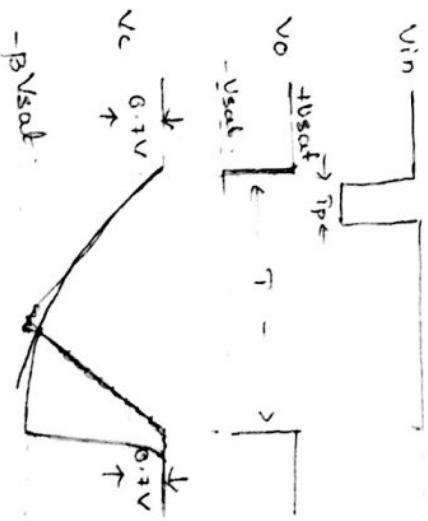
$$f = \frac{1}{2RC}$$

* Monostable Multivibrator.



~~Monostable~~ Multivibrator has 1 stable state and the other is quasi stable state. The ckt is useful for generating single op pulse for adjustable time duration in response to a triggering signal. The width of the op pulse depends only on the external components connected to op-Amp. The ckt of M.S.M. is a modified form of ASR. So this ckt consists of a diode D1 clamped across the capacitor and for triggering the differentiator the diode D2 produces a triggering impulse. Initially assume that ckt is at stable state i.e., $V_0 = +V_{sat}$ then voltage

at $V_1 = -B V_{sat}$ where $B = R_2 / (R_1 + R_2)$. The capacitor starts charging to $+0.7V$ till the diode is in D.B or till the voltage is less than the voltage of V_1 the ckt will be in the same state. A triggering pulse is applied such that the voltage at this time is less than $0.7V$ then the op switcher from + to $-V_{sat}$ and D1 gets R.B. Hence the capacitor starts changing exponentially upto $-B V_{sat}$ till the capacitor voltage becomes more negative than $-B V_{sat}$ then D1 is on hence the op switcher back to $+V_{sat}$. Now the capacitor voltage is clamped at $0.7V$ and stays in the state until trigger pulse applied again.



The voltage across the capacitor

$$V_c(t) = V_0 + (V_i - V_0) e^{-t/RC} \quad (1)$$

$$V_{C(t)} = -\beta V_{sat} + (V_D + \beta V_{sat}) e^{-t/RC}$$

$$\Rightarrow \beta V_{sat} (e^{-t/RC} - 1) + V_D e^{-t/RC} \quad \text{--- (3)}$$

$$\text{at } t = 0, V_{C(t)} = -\beta V_{sat} \quad \text{--- (4)}$$

Sub (4) in (3)

$$\Rightarrow -\beta V_{sat} = \beta V_{sat} (e^{-t/RC} - 1) + V_D e^{-t/RC}$$

$$\Rightarrow \beta = \beta e^{-t/RC} \cdot V_D e^{t/RC}$$

$$\Rightarrow \frac{V_{sat}}{V_{sat} - V_D} = e^{-t/RC}$$

$$\Rightarrow -\beta V_{sat} = V_{sat} (e^{-t/RC} - 1) + V_D e^{-t/RC}$$

$$\Rightarrow -\beta V_{sat} + V_{sat} = V_{sat} e^{-t/RC} + V_D e^{-t/RC}$$

$$\Rightarrow V_{sat}(1-\beta) = e^{-t/RC} (V_{sat} + V_D)$$

$$\Rightarrow \frac{V_{sat}(1-\beta)}{V_{sat} + V_D} = e^{-t/RC}$$

$$\Rightarrow \frac{1-\beta}{1+\frac{V_D}{V_{sat}}} = e^{-t/RC}$$

$$\Rightarrow \frac{1+\frac{V_D}{V_{sat}}}{1-\beta} = e^{+t/RC}$$

$$\Rightarrow \frac{t}{RC} = \ln \left(\frac{1+\frac{V_D}{V_{sat}}}{1-\beta} \right)$$

$$\Rightarrow \boxed{t = RC \ln \left(\frac{1+\frac{V_D}{V_{sat}}}{1-\beta} \right)} \quad \text{--- (5)}$$

$$k_{th} \quad \beta_3 = \frac{R_2}{R_1 + R_2}$$

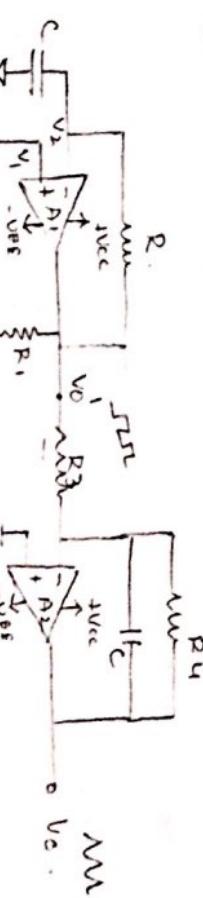
$$Q_1 \quad R_1 = R_2 \quad \& \quad V_D \ll V_{sat}$$

$$\Rightarrow t = RC \ln \left(\frac{1+\frac{V_D}{V_{sat}}}{1-\frac{1}{2}} \right)$$

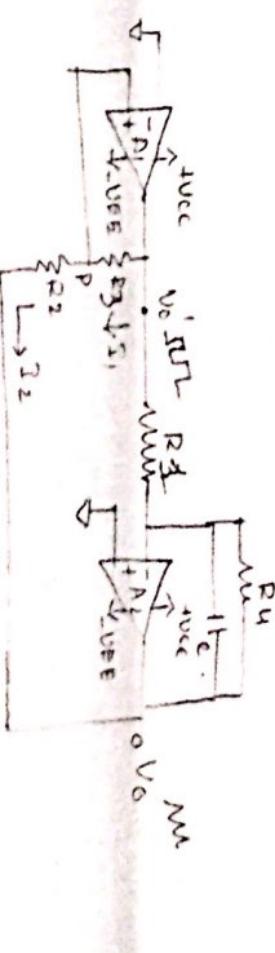
$$\boxed{t = 0.69 RC}$$

* Triangular wave generator :-

The triangular wave can be obtained by using suitable multivibrator & integrator.



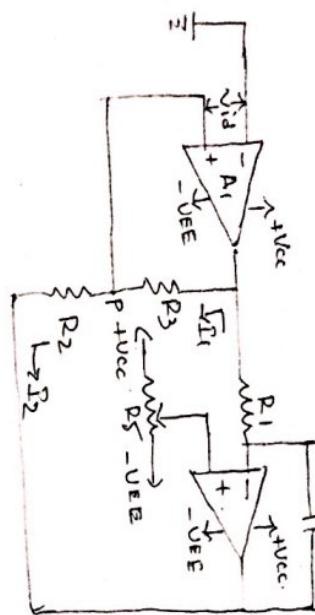
A triangular wave generator can also be designed using comparator and an integrator. Comparator is used as it is simple and less no. of components compared to suitable multivibrator.



$$T = \frac{4R_1 R_2 C_1}{R_3}$$

$$f = -\frac{1}{T} = \frac{R_3}{4R_1 R_2 C_1}$$

Sawtooth wave generator:-



For a triangular wave the rise-time and fall-time are equal i.e., the time taken to going from ramp to ramp is equal to that of +ve ramp-to-zero ramp to zero. Sawtooth wave has unequal rise & fall times.

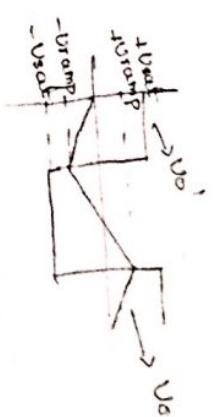
A saw wave generator can be converted to

Sawtooth wave generator by injecting a dc value of sawtooth wave generator by injecting a dc value of inverting terminal of A2. A potentiometer is connected inverting terminal of A2. Hence duty cycle of sawtooth wave depends on this dc value if the copper is moved towards - VEE - the rise time of sawtooth wave form becomes longer than fall time and vice versa.

~~Voltage Regulators~~

A voltage regulator is a circuit that supplies constant voltage. They can be designed using OP-AMPS but it is easier and quick to use IC voltage regulators. IC voltage regulators are versatile, inexpensive and available with features as programmable op-amp, current voltage limiting, internal short circuit current limiting etc.

- 4 types of voltage regulators. +ve, -ve.
- Fixed voltage regulators — adjustable linear
- Variable " "
- Switching " "
- Special purpose " "



For the fixed op-amp voltage regulators, variable and special purpose regulators are called series voltage regul. : a transistor is placed in series with error amp. Thus voltage sag can also called linear error amp. In switching sag, a power amp is used as a switch which is turned on/off at a rate such that the regulator delivers desired output current.

a. pulse to the load.

voltage reg. are used for power supplies for laboratory in pulse width modulation, push pull bridge etc -

Parameter of voltage regulators.

line lfp regulation - It is defined as change in o/p voltage for a change in ifp voltage

load regulation - change in o/p current for a change in load current.

temperature stability / Avg. temp. coeff - It is change in o/p voltage per unit change in temp.

Ripple rejection - It is a measure of regulator's ability to reject ripple voltages. It is measured in decibels

The 78xx IC are used as fixed o/p voltage regulators where xx represents max o/p voltages

Ex:- 7805, 7809, 7812

IC 79xx series are used as fixed -ve voltage regulators

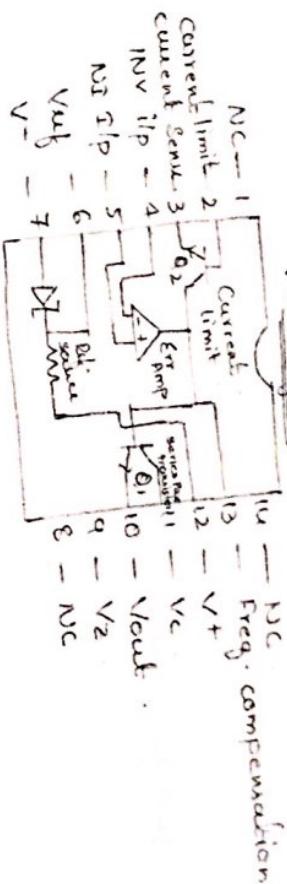
Ex:- 79012, 7915

IC 7423 IC23 & 7840 are used as switching voltage regulators

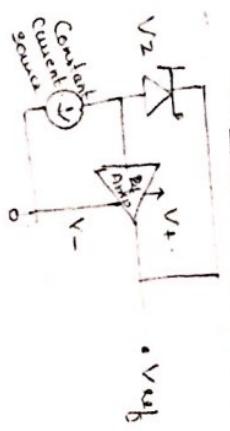
78xx	79xx
1	2
3	4
5	6
6	7
7	8
8	9
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97	98
98	99
99	100

IC 723 is general purpose voltage regulator

Pin diagram



Internal blocks of 723



Connection diagram

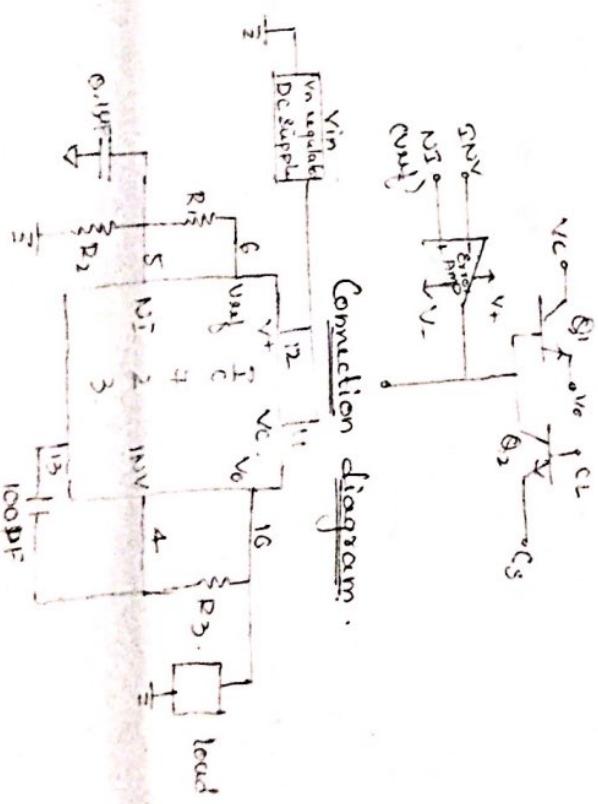


Fig 23 is a general purpose regulator which can be adjusted over wide range of the δ . -ve regulated voltage has \Rightarrow separate section. 1st section consists of zener diode with const current source and self-amp to produce V_{ref} .

The const. current source forces the zener to operate at fixed pt. The other section consists of error amp. via pnp transistor δ_1 , current limiting amp δ_2 . Error amp compares sample of op voltage applied in ip terminal to the ref. applied at ip terminal. The error signal controls conduction of δ_1 in 2 sections and not internally connected.

The opf of the error amp. drives δ_1 so as to minimise the diff b/w V_{ref} & ip of error amp.

If V_{ref} is low then ip is low. Hence error amp. opf V_{ref} is low. Thus by driving δ_1 into saturation this decreases voltage across δ_1 and drives more current into the load which causes voltage across the load to increase. If the current is condition (i.e., error amp. drive the transistor δ_1 is cutoff so the current V_{ref} load decreases and hence reduce V_{ref}) process continues until error amp opf is zero.

Unit-2 - Active filters, oscillators, timers and phase locked loops

\rightarrow Circles order & 2nd order LP, HP, BP, BR and RD

\rightarrow

Principle of operation & types of oscillators: RC, Wein bridge

\rightarrow Sawtooth generators, Dc, sawtooth, and square wave

\rightarrow 555 timer; functional diag., Monostable and Astable operation & app., Schmidt trigger, VCO

\rightarrow PLL: Block diag., principle & description of individual blocks of 565

* Filters :-

Filters are the elts that allow a particular range of freq. and all the remaining freq are attenuated depending on type of signals filters are classified into 2 types (i) Analogue filter (ii) Digital filter
Ex:- LP, HP, BP, BR, FIR, IIR

Depending on type of materials used filters are classified as passive filters and active filters.

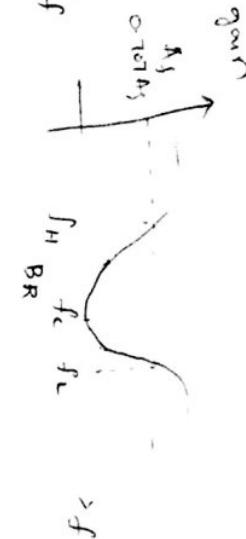
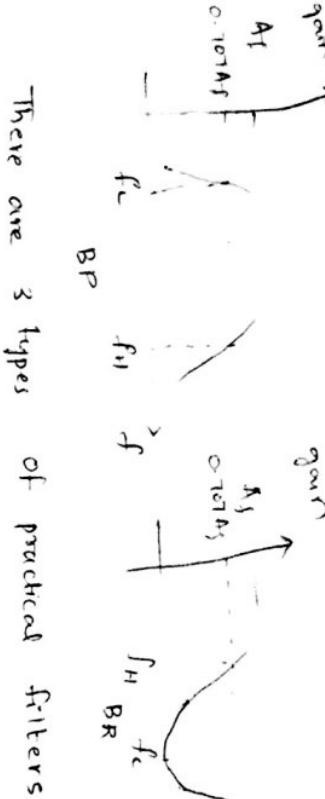
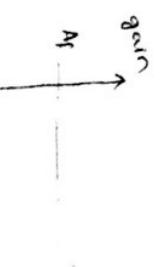
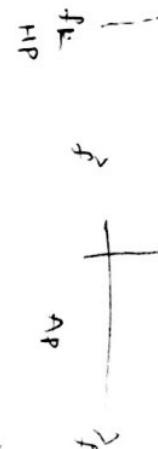
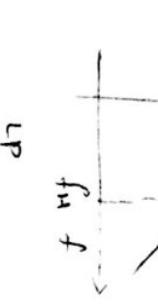
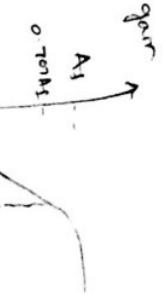
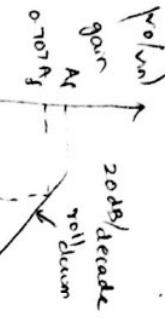
Depending on material filters are classified as audio frequency High freq. filters Radio freq.

The advantages of active filters over passive filters are -
1. High S. Frequency.
2. Adjustment flexibility.

→ No loading problem

→ Active filters are cheaper than passive filter

The commonly used filters are LP, HP, BP, BR and AP



There are 3 types of practical filters

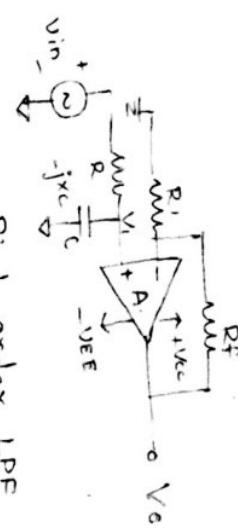
→ Butterworth → Chebyshev → Cauer

→ Butterworth filter has flat pass band flat stop band.

→ Chebyshev filter has ripple pass band flat stop band. Hence, it is sometimes called flat-flat filter

Chebyshev filter has ripple pass band flat stop band. Cauer filter has ripple pass band flat stop band. The Cauer filter gives best S.B. response.

First order low-pass Butterworth filter



$$V_1 = \frac{-j\omega C}{R + j\omega C} \times V_{in} \Rightarrow -j\omega C = \frac{1}{R + j\omega C} \quad (1)$$

$$V_1 = \frac{-j\omega C}{R + j\omega C} \times V_{in} = \frac{V_{in}}{\sqrt{2\pi f RC + 1}} \quad (2)$$

$$V_o = \left(1 + \frac{R_f}{R_1}\right)V_1 = \left(\omega\right)$$

Sub (2) in (1)

$$\omega = \omega \frac{R_f}{R_1} = A_f$$

$$V_o = V_{in} A_f \frac{V_{in}}{1 + j\omega RC} \quad (3)$$

$$\text{For a LP filter - the cutoff freq } f_c = \frac{1}{2\pi RC} \quad (4)$$

Sub (4) in (3)

$$\frac{V_o}{V_{in}} = \frac{A_f}{1 + j\omega f_c}$$

$$\left| \frac{V_o}{V_{in}} \right|^2 = \frac{A_f^2}{1 + (\omega/f_c)^2} \quad (5)$$

$$f < c f_H$$

$$|\frac{V_o}{V_{in}}| = A_F$$

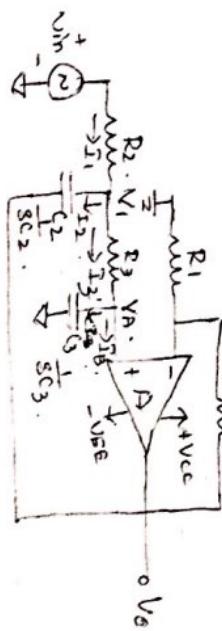
$$f_2 f_H$$

$$G_{\text{gain}} = \frac{A_F}{\sqrt{2}} = 0.707 A_F$$

$$f >> f_H$$

$$G_{\text{gain}} < A_F$$

2nd Order lowpass filter



Apply KCL at node V_1

$$\frac{V_{in} - V_1}{R_2} = \frac{1}{C_2} \frac{d(V_1 - V_o)}{dt} + \frac{V_1 - V_A}{R_3}$$

$$\frac{V_{in} - V_1}{R_2} = \frac{V_1 - V_o}{\frac{1}{C_2}} + \frac{V_1 - V_A}{R_3} \quad (1)$$

By voltage dividing rule.

$$V_A = \frac{V_1 \times 1}{\frac{1}{C_2} + R_3}$$

$$V_A = \frac{V_1 \times 1}{\frac{1}{C_2} + R_3}$$

$$V_A = \frac{V_1}{1 + R_3 C_2}$$

$$V_A = V_D (1 + s R_3 C_2) \quad (2)$$

$$\Rightarrow \frac{V_o}{V_{in}} = \frac{1 - R_2 C_2 R_3}{1 + R_3 C_2} = \frac{A_F R_3 V_{in}}{1 + s R_3 C_2}$$

$$V_o = \frac{V_o [1 - R_2 C_2 R_3]}{\left((1 + s R_3 C_2) (s C_2 R_3 R_2 + R_2 R_3) - R_2 \right) \left((1 + s R_3 C_2) (s C_2 R_3 R_2 + R_2 R_3) + R_2 \right)} = A_F R_3 V_{in}$$

$$\Rightarrow \frac{V_o}{V_{in}} = \frac{A_F R_3}{(1 + s R_3 C_2) (s C_2 R_3 R_2 + R_2 R_3) - R_2 - R_2 C_2 R_3}$$

Sub ② in ①

$$\frac{V_o}{V_{in}} = \frac{A_F R_3}{S C_2 R_3 R_2 + R_2 + S^2 C_2 C_3 R_3^2 R_2 + S R_3 C_2 + S R_3^2 C_3 - R_2 - S C_2 R_2 R_3}$$

$$= \frac{A_F}{S^2 + S \left[\frac{C_3 R_2 + C_2 R_2 - A_F R_3 C_2 + R_3}{C_2 C_3 R_2 R_3} \right] + \frac{1}{R_2 R_3 C_2 C_3}} \quad (1)$$

The standard form of transfer function of any 2nd order system is $\frac{V_o(s)}{V_{in}(s)} = \frac{A}{S^2 + 2\zeta\omega_n s + \omega_n^2} \quad (2)$

Where A is overall gain

ζ is damping of system
 ω_n is freq of oscillation

$$\text{By comparing } (1) \text{ & } (2) \quad \omega_n^2 = \frac{1}{R_2 R_3 C_2 C_3}$$

so For 2nd order low pass filter $\omega_n = \omega_{crossover}$

$$\text{But } \omega_{crossover} = \frac{1}{2\pi f_H}$$

$$f_H = \frac{1}{2\pi \sqrt{R_2 R_3 C_2 C_3}}$$

$$\text{Let } R_2 = R_3 = R \quad C_2 = C_3 = C.$$

$$\text{then } f_H = \frac{1}{2\pi RC}$$

$$\text{For 2nd order } \frac{V_o}{V_{in}} = \frac{A_F}{S^2 + S \left(\frac{2}{RC} + \frac{A_F}{f_H} \right) + 1} \quad (3)$$

$$V_o = A_F V_i = A_F \cdot \frac{R}{R+RC} \times V_{in} \Rightarrow V_o = A_F \cdot \frac{R}{R+RC} \times V_{in}$$

$$\text{For the high pass filter, value of } R \text{ is } \frac{1}{j\omega} \text{ and substituted in } (3) \text{ we get}$$

Filter designing:-

→ choose a value of high cut off freq f_H .

→ select a value of C ($\leq 1\mu F$)

→ calculate the value of R using $R = \frac{1}{2\pi f_H C}$

→ select values of R & R_P calculate the gain A

Note:- For the 2nd order low pass filter $A_F = 1.586$

First order high pass filter:-

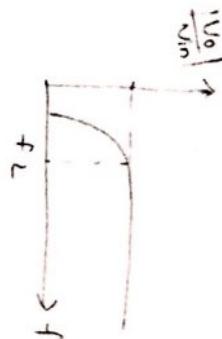
$$\begin{aligned} V_i &= \frac{R}{R+RC} \times V_{in} \\ &= \frac{R}{R + \frac{1}{j\omega C}} \times V_{in} \quad \boxed{\frac{R}{R + \frac{1}{j\omega C}} \times V_{in} = V_o} \\ &= \frac{j\omega RC}{R+j\omega RC} \times V_{in} \end{aligned}$$

Frequency Scaling: The procedure to convert original cut off freq f_H to a new cutoff freq f_H' is called frequency scaling. The scaling factor = $\frac{f_H'}{f_H}$ then multiply the scaling factor to resistors to obtain new resistor value then the filter is designed with new resistor values.

$$\frac{V_o}{V_{in}} = \frac{A_f}{1 + (f/f_p)^2}$$

$\theta = \tan^{-1} \left(\frac{f}{f_p} \right)$

$$| \frac{V_o}{V_{in}} | = \frac{A_f}{\sqrt{1 + (f/f_p)^2}}$$

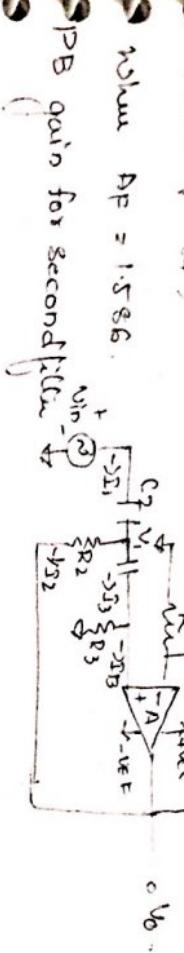


* Second order high pass filter:-

The voltage gain mag of 2nd order HPF is,

$$| \frac{V_o}{V_{in}} | = \sqrt{1 + \left(\frac{f}{f_p} \right)^2}$$

where $A_f = 1.586$.



PB gain for second filter \downarrow

$$| \frac{V_o}{V_{in}} | = \sqrt{1 + \left(\frac{f}{f_p} \right)^2} \times \sqrt{1 + \left(\frac{f}{f_p} \right)^2} = \sqrt{1 + \left(\frac{f}{f_p} \right)^2} \times \sqrt{1 + \left(\frac{f}{f_p} \right)^2}$$

* Bandpass filter:-

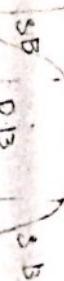
① Wide band pass filter ② Narrow band pass filter

Note:- There is no dividing line b/w the two types of filters i.e.

$Q < 10$ it is considered as wide BPF.
 $Q \geq 10$ then narrow BPF.

* Frequency response of a BPF:-

$$| \frac{V_o}{V_{in}} |$$



$$f_p$$

$$f_L$$

$$f_H$$

$$f_U$$

$$f_C$$

$$f_R$$

$$f_B$$

$$f_M$$

$$f_{M1}$$

$$f_{M2}$$

$$f_{M3}$$

$$f_{M4}$$

$$f_{M5}$$

$$f_{M6}$$

$$f_{M7}$$

$$f_{M8}$$

$$f_{M9}$$

$$f_{M10}$$

$$f_{M11}$$

$$f_{M12}$$

$$f_{M13}$$

$$f_{M14}$$

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$$f_{M99}$$

$$f_{M100}$$

$$f_{M101}$$

$$f_{M102}$$

$$f_{M103}$$

$$f_{M104}$$

$$f_{M105}$$

$$f_{M106}$$

$$f_{M107}$$

$$f_{M108}$$

$$f_{M109}$$

$$f_{M110}$$

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$$f_{M196}$$

$$f_{M197}$$

$$f_{M198}$$

$$f_{M199}$$

$$f_{M200}$$

$$f_{M201}$$

$$f_{M202}$$

$$f_{M203}$$

$$f_{M204}$$

$$f_{M205}$$

feed back filter

\rightarrow The resistor which is connected to non inverting terminal is called offset compensating resistor

\rightarrow For simplifications consider $R_1 = R_2 = C$ then

$$R_1 = \frac{S}{2\pi f_c C A_F}, R_2 = \frac{S}{2\pi f_c C (2S^2 A_F)}, R_3 = -\frac{S}{\pi f_c C}$$

$$A_F = \frac{R_3}{2R_1} \text{, gain at } f_c.$$

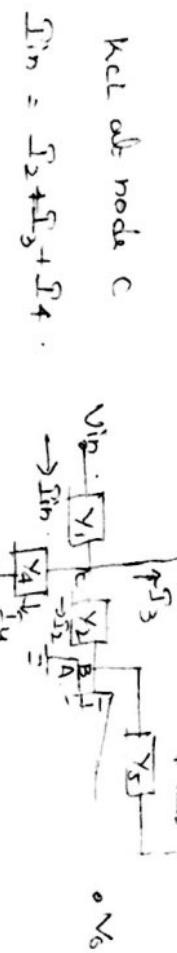
Another adv. of multiple feedback filter is that center freq. can be changed to new center freq. f_c' without changing gain & BW by changing resistance R_2 .

$$\text{The new resistance } R_2' = R_2 \times \left(\frac{f_c'}{f_c}\right)^2$$

Note:- The above ckt is called SGMF ckt
Infinite gain multiple feedback config.

Sub (5) in (1),

at node C



$$\Sigma_{in} = \Sigma_2 + \Sigma_3 + \Sigma_4$$

$$\Rightarrow (\text{Vin} - V_C)Y_1 = (V_C - V_B)V_2 + (V_C - V_O)V_3 + V_C V_4 - (1)$$

$$\text{Vin}Y_1 - V_OY_3 = V_C [V_1 + V_2 + V_3 + V_4]$$

OP - opp current = 0

$$\Rightarrow V_C V_2 = -V_O V_5$$

$$V_C = -V_O \begin{bmatrix} -V_5 \\ V_2 \end{bmatrix} - (2)$$

$$\text{Sub (5) in (1), } \text{Vin} Y_1 + V_O V_3 = -V_O \frac{V_5}{V_2} [V_1 + V_2 + V_3 + V_4] \\ \therefore \text{Vin} Y_1 = -V_O \left[\frac{V_5 V_1}{V_2} + V_5 + \frac{V_5 V_3}{V_2} + \frac{V_5 V_4}{V_2} \right]$$

$$\therefore \frac{\text{Vin}}{V_O} = \frac{-V_1 V_2}{V_5 V_1 + V_5 V_2 + V_3 V_5 + V_5 V_4 + V_2 V_3}$$

\therefore This is the general exp of voltage gain

TAPM config.

For this ckt, to be a band pass ckt substitute $V_1 = V_{R_1}$, $V_2 = S C_2$, $V_3 = S C_3$, $V_4 = 1/R_4$, $V_5 = 1/R_S$

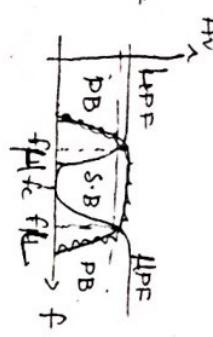
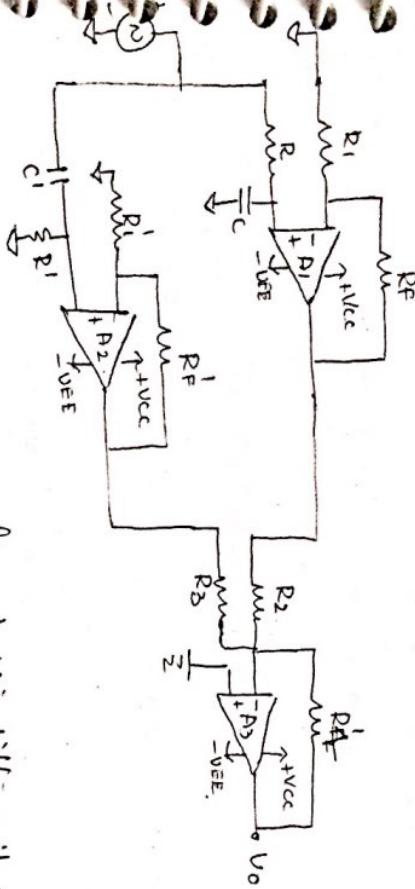
~~Wide Band Reject Filter :-~~

Q18] Band Reject Filter - It is also known as Band elimination / Band attenuation filter. Based on & value BRF is classified into 2 types.

- Wide BRF
- Narrow BRF

* Wide Band Reject Filter :-

The wide band reject filter is a combination of LPF & HPF and an adder.



$$f_H = \frac{1}{2\pi RC} \Rightarrow$$

$$f_L = \sqrt{f_H f_C} = \sqrt{2 \times 10^3 \times 400} =$$

Diag

* Narrow BRF :-

The narrow BRF is used to eliminate a single freq of 60Hz. It is also known as notch filter.

The most commonly used notch filter is twin-T network which is composed of 2 T shaped networks. One T network consists of $2R$ and $1C$ while the other consists

of $2C$ & $1R$. The freq above the attenuation occurs is $f_n = \frac{1}{2\pi RC}$. The twin T network has less gain & less Q value to increase the Q value of circuit it is

used with voltage follower circuit.

For designing notch filter for a specified

cutoff freq of C_{PF} the PB gain of HP & LP must be equal.

→ The gain of summing amp. must be set to 1 i.e., $R_2 = R_3 = R_4 = R$.

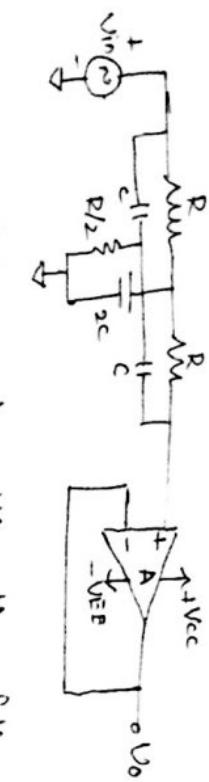
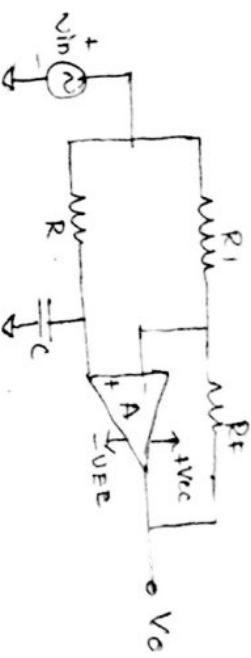
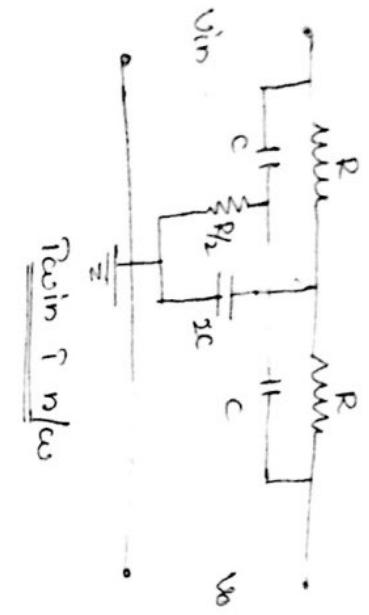
→ The center freq $f_c = \sqrt{f_H f_C}$.

- Design a wide BRF having $f_H = 400 \text{ Hz}$, $f_L = 240 \text{ Hz}$ with a PB gain of 2. And calculate f_c . Assume $C = 0.1 \mu F$.

$$f_H = \frac{1}{2\pi RC} \Rightarrow$$

$$f_L = \sqrt{f_H f_C} = \sqrt{2 \times 10^3 \times 400} =$$

* All pass filter



$V_{in} \uparrow n/\omega$ with voltage follower ckt.

- ① Design a notch filter to eliminate 120Hz hum noise.

$$\text{Let } C_2 = 0.1\mu\text{F}$$

$$f_n = 120\text{Hz}$$

$$f_n = \frac{1}{2\pi RC}$$

$$120 = \frac{1}{2\pi R \times 0.1 \times 10^{-6}}$$

Diag.

Initially consider non inverting terminal is to compensate change in phase.

$$\text{Then } V_{o1} = -\frac{R_F}{R_1} V_{in} \quad (\because \text{ckt is inv amp})$$

$$\text{Let } R_F = +R_1$$

$$\therefore \boxed{V_{o1} = -V_{in}} \quad \text{--- (1)}$$

Consider ckt in non inverting config.

$$V_{o2} = \left(1 + \frac{R_F}{R_1}\right) V_{in}$$

$$R_F = R_1$$

$$= (2) \frac{V_{in} \cdot (-j\omega C)}{R - j\omega C}$$

$$V_{o2} = \frac{2V_{in}}{1 + j\omega R C} \quad \text{--- (2)}$$

$$V_o = V_{o1} + V_{o2} \quad (\text{superposition theorem})$$

$$= -V_{in} + \frac{2 V_{in}}{1+j2\pi f_{RC}}$$

$$= V_{in} \left[-1 - j2\pi f_{RC} + 2 \right]$$

$$\frac{V_o}{V_{in}} = \frac{1 - j2\pi f_{RC}}{1 + j2\pi f_{RC}}$$

$$\frac{V_o}{V_{in}} = \frac{1}{1 + j2\pi f_{RC}}$$

$$\left| \frac{V_o}{V_{in}} \right| = 1$$

$$\therefore |V_o = V_{in}|$$

$$\begin{aligned}\phi &= \tan^{-1}(2\pi f_{RC}) \\ &= -2\tan^{-1}(2\pi f_{RC})\end{aligned}$$

An oscillator is a circuit that generates a repetitive waveform & kind amp & freq without any external (IP b) sional. An ac phase shifter oscillator consists of an op-amp as amplifying stage and \Rightarrow RC cascaded ring as bfo chlt. The op-Amp is used in inverting mode as a phase shift of 180° is obtained at op-amp and an additional 180° phase shift required for oscillation is provided by cascaded RC filters. To find freq of oscillations and gain of the chlt apply KVL for the given chlt.

$$V_b = \frac{1}{j\omega C} + R_2(\Sigma_1 \Sigma_2) = \Sigma_1(R + \frac{1}{j\omega C}) - \Sigma_2 R - 0$$

$$\begin{aligned}\Sigma_2 \frac{1}{j\omega C} + R(\Sigma_2 - \Sigma_3) + R(\Sigma_2 - \Sigma_1) &= 0 \\ \Rightarrow -\Sigma_1 R + \Sigma_2(-\frac{1}{j\omega C} + 2R) - \Sigma_3 R &= 0\end{aligned}$$

$$\Sigma_3 \frac{1}{j\omega C} - R(\Sigma_3 - \Sigma_2) + V_o = 0$$

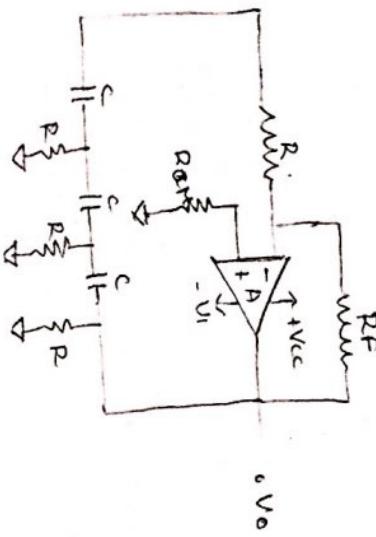
$$\Rightarrow -\Sigma_2 R + \Sigma_3(2R + \frac{1}{j\omega C}) = 0$$

Replace $j\omega C = s$ and write the eq in matrix form

$$\begin{bmatrix} \Sigma_1 \\ \Sigma_2 \\ \Sigma_3 \end{bmatrix} \begin{bmatrix} (R + \frac{1}{sC}) & -R & 0 \\ -R & (\frac{1}{sC} + 2R) & -R \\ 0 & -R & (2R + \frac{1}{sC}) \end{bmatrix} = \begin{bmatrix} V_o \\ 0 \\ 0 \end{bmatrix}$$

using cramer's rule for above matrix ($\Sigma_3 = \frac{D_3}{D}$)

$$\begin{aligned}D &= \begin{vmatrix} (R + \frac{1}{sC}) & -R & 0 \\ -R & (\frac{1}{sC} + 2R) & -R \\ 0 & -R & (2R + \frac{1}{sC}) \end{vmatrix} \\ &\downarrow \\ &= \frac{1}{sC} D_3\end{aligned}$$



The -ve phase shift indicates that V_o lags V_{in} by angle ϕ .
RC phase shift oscillator

The -ve phase shift indicates that V_o lags V_{in} by angle ϕ .

Replace $\frac{1}{wCR} = \alpha$

$$= R + \frac{1}{SC} \left(4R^2 + 4R \frac{1}{SC} \right)^2 + R \left[-2R^2 - \frac{R}{SC} \right]$$

$$= 4R^3 + \frac{4R^2}{SC} \frac{R^2}{SC} + \frac{4R^2}{SC} + \frac{4R}{(SC)^2} + \frac{1}{(SC)^2} R^3 - 2R^3 - \frac{R^2}{SC}$$

$$= \frac{8R^3 + 4R^2}{SC} + \frac{4R}{(SC)^2} + \frac{R^3}{(SC)^3} - 2R^3$$

$$= \frac{2R^3S^3C^3 + 7R^2S^2C^2 + 4RSC + SC^2}{S^3C^3} + 1$$

$$D = 1 + \frac{5SRC + 6S^2C^2R^2 + S^3C^3R^3}{S^3C^3} - \textcircled{2}$$

$$D_3 = \frac{V_f R^2}{S^3C^3} \quad T_3 = \frac{D_3}{D}$$

$$\text{whence } D_3 = S_3 R$$

$$B = \frac{V_o}{V_f} = \frac{\frac{1}{2} S_3 R}{\frac{D}{D_3}} = \frac{\frac{1}{2} S_3 R^2}{D} = \frac{R^3}{D}$$

$$\therefore \boxed{B = \frac{R^3S^3C^3}{1 + 5SRC + 6S^2C^2R^2 + S^3C^3R^3}} - \textcircled{3}$$

$$\therefore \text{order by } R^3S^3C^3$$

$$B = \frac{1}{S^3R^3C^3 + 5S^2R^2C^2 + SRC + 1}$$

$$S = j\omega s$$

$$= \frac{1}{4C^3R^3C^3} + \frac{5}{4C^2R^2C^2} + \frac{6}{j\omega RC} + 1$$

Re

$$B = \frac{1}{j\alpha^3 - \alpha^2 - 6j\alpha + 1}$$

To have the phase shift of 180° the imaginary part denominator must be zero

$$\alpha^3 - 6\alpha = 0$$

$$\alpha(\alpha^2 - 6) = 0$$

$$\therefore \alpha^2 = 6$$

$$\frac{1}{\omega^2 C^2 R^2} = 6$$

$$\omega^2 C^2 R^2 = \frac{1}{6}$$

$$4\pi^2 R^2 C^2 R^2 \cdot \cos R = \frac{1}{\sqrt{6}}$$

$$\boxed{f = \frac{1}{2\pi R C \sqrt{6}}} - \textcircled{4}$$

$$\text{Sub eq } \textcircled{4} \text{ in } \textcircled{3}$$

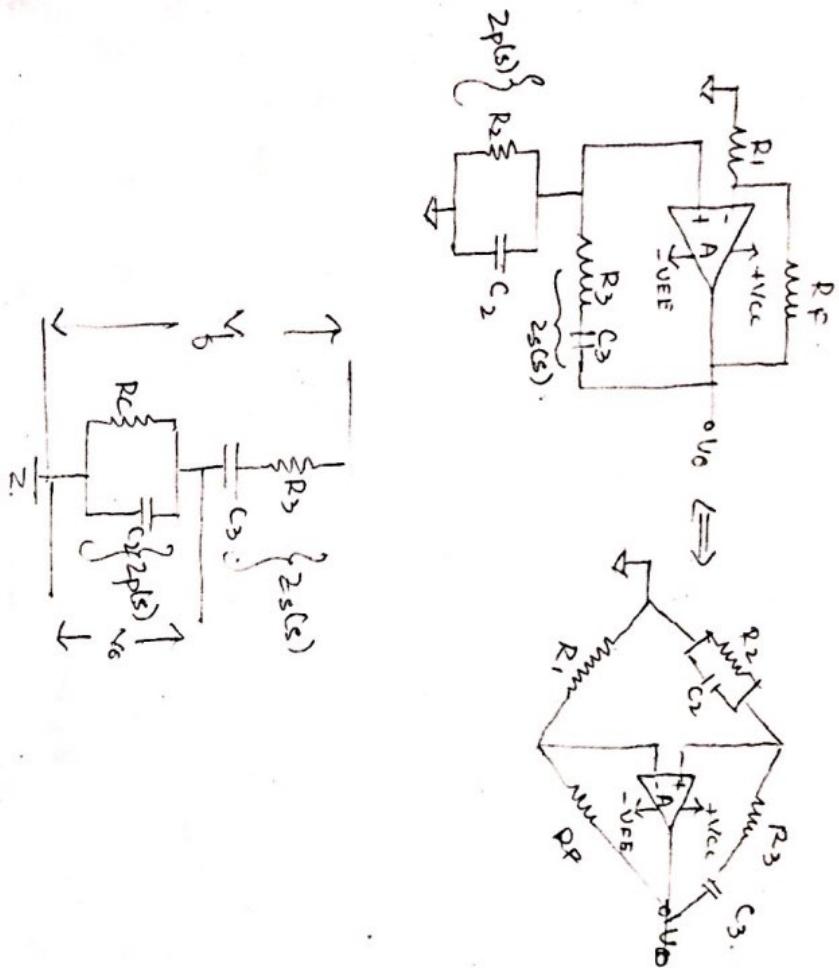
$$\boxed{B = \frac{R^3}{2\alpha^3}}$$

$$\text{whence } AB = 1 \Rightarrow |AB| = 2\alpha$$

Wien Bridge Oscillator

one of the most commonly used audio freq oscillator is Wien bridge osc. because of its stability and simplicity. It consists of a series RC nos and a parallel RC nos. The phase shift around Wien bridge osc is 0° as this condition occurs only when bridge is balanced i.e., at resonance.

$$V_t = \frac{Z_p(s)}{Z_p(s) + Z_s(s)} V_o$$



By using voltage dividing rule above eq.
where $Z_s = R_3 + \frac{1}{j\omega C_3}$
 $\Rightarrow C_2, C_3 = C$. Consider $R_2, R_3 = C$.

$$Z_p = \frac{R_2 \times \frac{1}{j\omega C_2}}{R_2 + \frac{1}{j\omega C_2}} = \frac{R_2}{j R_2 C_2 \omega + 1}$$

$$\beta = \frac{V_t}{V_o} = \frac{Z_p(s)}{Z_p(s) + Z_s(s)} = \frac{\frac{R_2}{j R_2 C_2 + 1}}{\frac{R_2}{j R_2 C_2 + 1} + \frac{s R_3 C_3 + j\omega C_3 + 1}{s R_3 C_3 + s^2 R_3 C_3 R_2 C_2 + s R_2 C_2 + s R_3 C_3 + 1}}$$

$$= \frac{(s R_2 C_2 + 1) s C_3 R_2}{(s R_2 C_2 + 1) (s C_3)}$$

$$= \frac{s^2 R_2^2 C_2^2 + s^2 R_2 C_2 R_2 C_2 + s R_2 C_2 + s R_3 C_3 + 1}{s R_2 C_2 + s^2 R_2 C_2 C_3 + j\omega C_3 R_2}$$

$$= \frac{-s^2 R_2^2 C_2 C_3 + j\omega C_3 R_2}{s R_2 C_2 + s^2 R_2 C_2 C_3 + s R_2 C_2 + s R_3 C_3 + 1}$$

$$= \frac{-s^2 R_2^2 C_2 C_3 + j\omega C_3 R_2}{j\omega R_2 C_2 + s^2 R_2 C_2 C_3 + s R_2 C_2 + s R_3 C_3 + 1}$$

$$\beta = \frac{R_{SC}}{R_{SC} + s^2 R_2^2 C_2 C_3 + s R_2 C_2 + s R_3 C_3 + 1} = \frac{R_{SC}}{s^2 R_2^2 C_2 C_3 + s R_2 C_2 + s R_3 C_3 + 1} \quad (1)$$

The voltage gain of op-amp is $D_{Vt} = \frac{V_o}{V_t}$ and ities

$$1 + \frac{R_F}{R_1} = 2$$

$$\therefore A_B = 1$$

$$\left(1 + \frac{R_F}{R_1}\right) \frac{sCR}{s^2 C^2 R^2 + 3sCR + 1} = 1.$$

$$\Rightarrow \left(1 + \frac{R_F}{R_1}\right) sCR = s^2 C^2 R^2 + 3sCR + 1$$

put $s = j\omega$

$$\Rightarrow \left(1 + \frac{R_F}{R_1}\right) j\omega CR = -s^2 C^2 R^2 + 3sCR + 1$$

$$\Rightarrow -s^2 C^2 R^2 + 1 = -j\omega sRC + j\omega R_F C R$$

$$\Rightarrow -s^2 C^2 R^2 + 1 = -2j\omega sRC + j\omega R_F C R$$

equate real parts on L.H.S

$$\Rightarrow +s^2 C^2 R^2 = 1$$

$$\Rightarrow j\omega R_F \omega = \frac{1}{CR}$$

$$\Rightarrow f = \frac{1}{2\pi RC}$$

To obtain gain equal imaginary parts of both sides

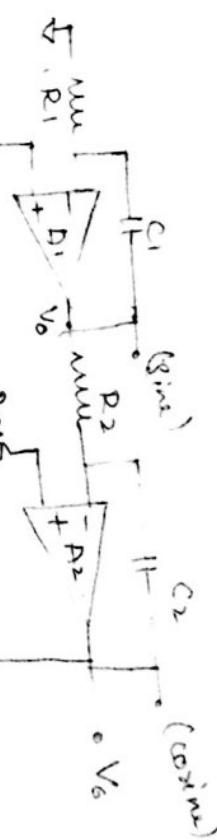
$$\text{Let } \frac{1 + R_F}{R_1} = A.$$

$$\Rightarrow \left(1 + \frac{R_F}{R_1}\right) sCR = 3sCR$$

$$\therefore \boxed{A = 3}$$

$$\therefore \Delta = 3 \Rightarrow R_F = 2R_1$$

* Quadrature Oscillator



$$\frac{1}{2\pi RC} \rightarrow \text{P/B ckt}$$

Op-Amp A₂ is phase inverter and inverter it provides $90^\circ / -270^\circ$ phase shift. The remaining $\Delta = 270^\circ$ of phase shift is obtained from Op-Amp A₁. Feed back ckt R_3, C_3

To calculate freq of oscillations consider feed back ckt

By voltage dividing rule

$$\text{Gain of op-amp } A_2 = \frac{V_{o2}}{V_{i2}} = \frac{-R_3 \times \frac{1}{2\pi RC}}{R_1 + \frac{1}{2\pi RC}} = -\frac{R_3}{2\pi RC}$$

$$= -\frac{R_3}{2\pi RC} \quad \text{or} \quad \frac{1}{2\pi RC}$$

$$B = \frac{V_1}{V_{i2}} = -\frac{1}{4\pi R_3 C_3} \quad \text{--- (1)}$$

$$\text{Gain of op-amp } A_1 = \frac{V_{o1}}{V_{i1}} = -\frac{1}{4\pi R_1 C_1} \quad \text{--- (2)}$$

$$\Delta_2 = \frac{V_{o2}(s)}{V_{i2}(s)} = -\frac{V_{o2}(s)}{V_{i2}(s)} = -\frac{1}{4\pi R_3 C_3}$$

$$\Delta = \Delta_1 \cdot \Delta_2$$

$$\Rightarrow A_B = 1$$

$$R_1 = R_2 = R_3 = R \quad \& \quad C_1 = C_2 = C_3 = C$$

then substitute

$$\left(\frac{1+SCR}{2CR}\right) \left(\frac{1}{1+SCR}\right) = 1$$

$$-1 = S^2 C^2 R^2$$

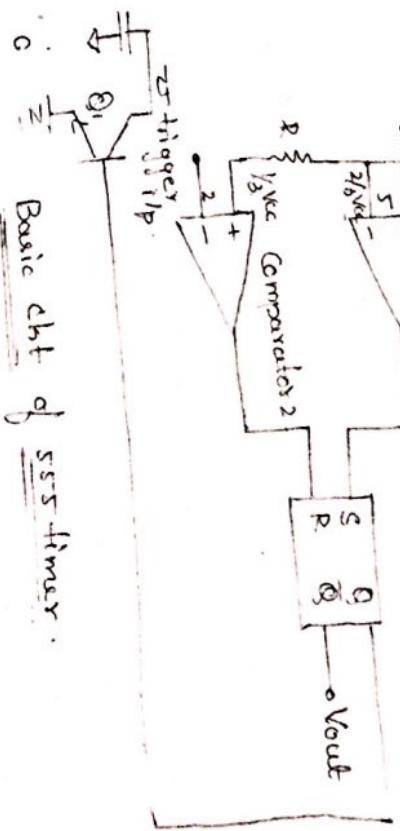
$$\frac{C^2 C^2 R^2}{2} = 1$$

$$B = \frac{1}{1+j2\pi fRC} = \frac{1}{1+j\frac{2\pi f}{2CR}}$$

$$|B| = \frac{1}{\sqrt{2}}$$

$$|A| = \sqrt{2}$$

555 Timer:



Basic ckt of 555 timer.

One of the most versatile linear integrator ckt:

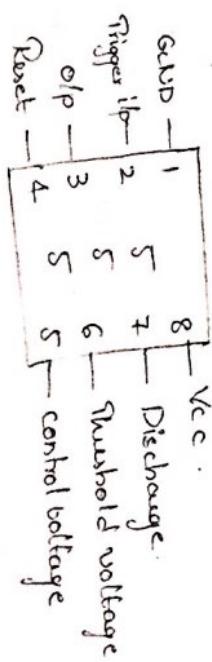
555 timer. It can be used as DC to DC converter, square-wave generator, pulse stretcher, RS flip flop etc. It is manufactured by Signetics SE/NEC with 8 pin DIP. The 14 pin DIP consists of 2-555 timers fabricated on same chip and named as 55556. It can be used in 2 mode monostable multivibrator & astable multivibrator.

→ The supply voltages ranges from 4.5V to 18V.

→ The SE version operates at -55°C to +125°C and NE version operates from 0°C to +70°C.

→ The op-amp of 555 timer is compatible with TTL and CMOS ckt.

Pin diagram



NCC
B C E R
2CR
Comparator 1.

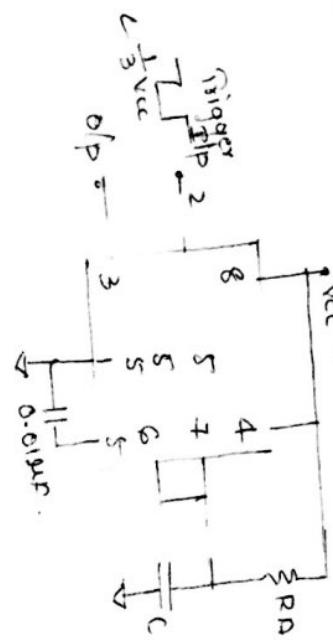
Q1 Q2 (Previous IP)

(Reset)

1 0 0 1 (Set)

X (not used)

555 Timer as Monostable :-



Initially o/p of the monostable multivibrator is low i.e., dot is in stable state then transistor Q_1 is off and capacitor C is shorted to ground. When a -ve trigger pulse is applied to pin 2 the comparator 2 o/p goes high and triggers the o/p of Q_2 . The o/p of Q_2 is high which makes transistor Q_1 on. The voltage across capacitor C starts charging towards V_{cc} through resistor R_A . When the voltage across capacitor $\frac{2}{3}V_{cc}$ the comp. 1 o/p switches from low to high which in turn triggers the Q_1 . The o/p of timer changes to low state and the transistor Q_1 is off and hence capacitor C discharges rapidly the o/p of monostable remains low until a trigger pulse is applied again.



The voltage across capacitor $V_C = V_{CC}e^{-\frac{t}{RC}}$

at $t = T$.

$$V_C = \frac{2}{3} V_{CC} \quad \text{--- (2)}$$

From (1) & (2)

$$V_{CC} [1 - e^{-\frac{T}{RC}}] = \frac{2}{3} V_{CC}$$

$$-e^{-\frac{T}{RC}} = \frac{2}{3} - 1 = -\frac{1}{3}$$

$$e^{\frac{T}{RC}} = 3$$

$$\frac{T}{RC} = \log_e 3$$

$$T = RC \ln 3$$

$$\sqrt{T} = 1.1 R C$$

For a monostable mult. $R_A = 100k\Omega$, $C = 0.9\mu F$

Find time period of pulse.

$$T = 1.1 \times 100 \times 10^3 \times 0.9 \times 10^{-6}$$

$$T = 99 \text{ msec}$$