RUTUJA GURAV

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EDUCATION M.S. Computer Science, University of California, Riverside USA

2025

B.E. Computer Engineering, University of Mumbai, India

2013 - 2017

RESEARCH University of California, Riverside EXPERIENCE Graduate Student Researcher

LIGO Scientific Collaboration, Caltech

Visiting Student Researcher

Focus: Machine Learning for noise hunting in Advanced LIGO detectors.

WORK Frontier Development Lab (FDL), a public-private partnership between NASA, Google and NVIDIA

EXPERIENCE Researcher June – August 2024

Project: Forecasting radiation exposure for human spaceflight with multi-modal deep learning

Lawrence Livermore National Lab (LLNL)

Graduate Summer Research Intern (Team: Data Science & Analytics Group)

June - September 2022

Project: Modeled multi-scale, multi-physics simulations using Graph Neural Networks (GNNs).

Team Lead: Data Science Challenge

Task: Led a group of undergraduate students to build machine learning models for - 1. classifying stars and galaxies using HSC

images from the Subaru Telescope in Hawaii, 2. detecting asteroids in images from ZTF astronomical survey.

Oak Ridge National Lab (ORNL)

Graduate Summer Research Intern (Team: Geoinformatics Engineering)

June - August 2021

September 2021

Project: Conflation of Geospatial POI Data and Ground-level Imagery via Link Prediction on Joint Semantic Graphs.

Esri Inc.

Data Science Intern (Team: GeoAl)

June - August 2018

Project: Water mains breaks prediction using historic pipe records to forecast future breaks in water supply pipelines to aid risk

assessment and maintenance.

TECHNICAL

Programming Languages & Software - Python (proficient); C/C++, Java, MATLAB (intermediate)

SKILLS

Machine Learning - Numpy, Scipy, Pandas, Scikit-Learn Deep Learning - PyTorch / Lightning, Tensorflow / Keras Tensor Analysis - Tensorly (Python); Tensor Toolbox (MATLAB)

Collaboration & Experiments Tracking - Git / Google Colab, Weight & Biases / Tensorboard

Cloud Computing Platforms - Google Cloud Platform (GCP)

SELECTED PUBLICATIONS

Gurav, R., et al. (2023). Can SAM recognize crops? Quantifying the zero-shot performance of a semantic segmentation foundation model on generating crop-type maps using satellite imagery for precision agriculture. In NeurIPS 2023 AI for

Touridation model on generating crop-type maps using satellite imagery for precision agriculture

Scientific Discovery: From Theory to Practice. (AI for Precision Agriculture)

Gurav, R., De, D., Thakur, G., & Fan, J. (2021, November). Conflation of geospatial POI data and ground-level imagery via link prediction on joint semantic graph. In Proceedings of the 4th ACM SIGSPATIAL International Workshop on AI for Geographic

Knowledge Discovery (pp. 5-8). (Al for Multi-modal Geospatial Analysis)

PATENT Conflation of geospatial points of interest and ground-level imagery, US12008800, 2024/6/11