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#include <stdio.h>

#include <stdlib.h>

int SSTF();

int SCAN();

int CLOOK();

int main(){

int ch, YN = 1, i, l, f;

char F[10], s[25];

for (i = 0; i < f; i++){

F[i] = -1;

}

do{

printf("\n\n\t***** MENU *****");

printf("\n\n\t1:SSTF\n\n\t2:SCAN\n\n\t3:CLOOK\n\n\t4:EXIT");

printf("\n\n\tEnter your choice: ");

scanf("%d", &ch);

switch (ch){

case 1:

for (i = 0; i < f; i++){

F[i] = -1;

}

SSTF();

break;

case 2:

for (i = 0; i < f; i++){

F[i] = -1;

}

SCAN();

break;

case 3:

for (i = 0; i < f; i++){

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F[i] = -1;
}
CLOOK();
break;
case 4:exit(0);
}
printf("\n\n\tDo u want to continue IF YES PRESS 1\n\n\tIF NO PRESS 0: ");
scanf("%d", &YN);
}
while (YN == 1);
return (0);
}
int SSTF(){
int RQ[100], i, n, TotalHeadMoment = 0, initial, count = 0;
printf("Enter the number of Requests\n");
scanf("%d", &n);
printf("Enter the Requests sequence\n");
for (i = 0; i < n; i++){
scanf("%d", &RQ[i]);
}
printf("Enter initial head position\n");
scanf("%d", &initial);
while (count != n){
int min = 1000, d, index;
for (i = 0; i < n; i++){
d = abs(RQ[i] - initial);
if (min > d){
min = d;
index = i;
}
}
}
}

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TotalHeadMoment = TotalHeadMoment + min;

initial = RQ[index];

RQ[index] = 1000;

count++;

}

printf("Total head movement is %d", TotalHeadMoment);

return 0;

}

int SCAN(){int RQ[100], i, j, n, TotalHeadMoment = 0, initial, size, move;

printf("Enter the number of Requests\n");

scanf("%d", &n);

printf("Enter the Requests sequence\n");

for (i = 0; i < n; i++) {

scanf("%d", &RQ[i]);

}

printf("Enter initial head position\n");

scanf("%d", &initial);

printf("Enter total disk size\n");

scanf("%d", &size);

printf("Enter the head movement direction for high 1 and for low 0\n");

scanf("%d", &move);

for (i = 0; i < n; i++){

for (j = 0; j < n - i - 1; j++){

if (RQ[j] > RQ[j + 1]){

int temp;

temp = RQ[j];

RQ[j] = RQ[j + 1];

RQ[j + 1] = temp;

}

}

}

}

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int index;

for (i = 0; i < n; i++){
    if (initial < RQ[i]){
        index = i;
        break;
    }
}

if (move == 1){
    for (i = index; i < n; i++){
        TotalHeadMoment = TotalHeadMoment + abs(RQ[i] - initial);
        initial = RQ[i];
    }

    TotalHeadMoment = TotalHeadMoment + abs(size - RQ[i - 1] - 1); initial = size - 1;
    for (i = index - 1; i >= 0; i--){
        TotalHeadMoment = TotalHeadMoment + abs(RQ[i] - initial);
        initial = RQ[i];
    }
}

else{
    for (i = index - 1; i >= 0; i--) {
        TotalHeadMoment = TotalHeadMoment + abs(RQ[i] - initial);
        initial = RQ[i];
    }

    TotalHeadMoment = TotalHeadMoment + abs(RQ[i + 1] - 0);
    initial = 0;

    for (i = index; i < n; i++){
        TotalHeadMoment = TotalHeadMoment + abs(RQ[i] - initial);
        initial = RQ[i];
    }
}

printf("Total head movement is %d", TotalHeadMoment);

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return 0;

}

int CLOOK(){
int RQ[100], i, j, n, TotalHeadMoment = 0, initial, size, move;

printf("Enter the number of Requests\n");

scanf("%d", &n);

printf("Enter the Requests sequence\n");

for (i = 0; i < n; i++){
scanf("%d", &RQ[i]);
}

printf("Enter initial head position\n");

scanf("%d", &initial);

printf("Enter total disk size\n");

scanf("%d", &size);

printf("Enter the head movement direction for high 1 and for low 0\n");

scanf("%d", &move);

for (i = 0; i < n; i++){for (j = 0; j < n - i - 1; j++){
if (RQ[j] > RQ[j + 1]){

int temp;

temp = RQ[j];

RQ[j] = RQ[j + 1]; RQ[j + 1] = temp;

}

}

}

int index;

for (i = 0; i < n; i++){

if (initial < RQ[i]){

index = i;

break;

}

}

}

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if (move == 1){
    for (i = index; i < n; i++){
        TotalHeadMoment = TotalHeadMoment + abs(RQ[i] - initial);
        initial = RQ[i];
    }
    for (i = 0; i < index; i++){
        TotalHeadMoment = TotalHeadMoment + abs(RQ[i] - initial);
        initial = RQ[i];
    }
}
else{
    for (i = index - 1; i >= 0; i--){
        TotalHeadMoment = TotalHeadMoment + abs(RQ[i] - initial);
        initial = RQ[i];
    }
    for (i = n - 1; i >= index; i--){
        TotalHeadMoment = TotalHeadMoment + abs(RQ[i] - initial);
        initial = RQ[i];
    }
}
printf("Total head movement is %d", TotalHeadMoment);return 0;
}

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